# Problem Set-1

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## Part (a)

From the question we have:

$$\begin{split} E[r_i] &= 0.5, E[g_i] = 1; \\ E[x_i^*|r_i = 1] &= 3 \text{ and } E[x_i^*|r_i = 0] = 7, \text{which induces a negative correlation between } x_i^* \text{ and } r_i; \\ E[x_i^*] &= 0.5 \times E[x_i^*|r_i = 1] + 0.5 \times E[x_i^*|r_i = 0] = 5; \\ E[x_i^*r_i] &= E[E[x_i^*r_i \mid r_i]] = 0.5 \times E[x_i^* \cdot 1 \mid r_i = 1] + 0.5 \times E[x_i^* \cdot 0 \mid r_i = 0] = 0.5 \times 3 + 0.5 \times 0 = 1.5; \\ Cov(x_i^*, r_i) &= E[x_i^*r_i] - E[x_i^*]E[r_i] = 1.5 - 5 \times 0.5 = -1; \\ y_i &= 400 + 5x_i^* + 200r_i + 10g_i + u_i \end{split}$$

### Part (b)

```
formulas <- list(</pre>
  "Model 1" = y \sim x,
  "Model 2" = y \sim x + r,
  "Model 3" = y \sim x + r + g,
  "Model 4" = y \sim x + r + n1,
  "Model 5" = y \sim x + r + b
)
results <- data.frame(Model = character(),
                       Formula = character(),
                       Beta1 Estimate = numeric(),
                       Std Error = numeric(),
                       stringsAsFactors = FALSE)
for (model_name in names(formulas)) {
  model fit <- lm(formulas[[model name]], data = data)</pre>
  model_summary <- summary(model_fit)</pre>
  beta1 <- model_summary$coefficients["x", "Estimate"]</pre>
  se <- model_summary$coefficients["x", "Std. Error"]</pre>
  results <- rbind(results, data.frame(Model = model name,
                                          Formula = deparse(formulas[[model_name]]),
                                          Beta1_Estimate = beta1,
                                          Std Error = se,
                                          stringsAsFactors = FALSE))
}
print(results)
##
       Model
                     Formula Beta1 Estimate Std Error
                       y ~ x -16.937697 2.2749488
## 1 Model 1
```

• Regression Model 1 only includes fertilizer amount  $x_i^*$ , which is:

$$y_i = \beta_0 + \beta_1 x_i^* + \text{ error } i$$

The probability limit of  $\beta_1$  should be:

$$plim(\hat{\beta}_1) = \beta_1 + \beta_2 \frac{Cov(x_i^*, r_i)}{Var(x_i^*)} + \beta_3 \frac{Cov(x_i^*, g_i)}{Var(x_i^*)}$$

Since  $Cov(x_i^*, r_i) = -1$ ,  $Cov(x_i^*, g_i) = 0$ ,  $Var(x_i^*) = 9$  and  $\beta_2 = 200$ , we have:

$$plim(\hat{\beta}_1) = 5 + 200 \times \frac{-1}{9} \approx -17.22$$

The simulated  $\beta_1$  estimate is approximately -16.94, which is close to the theoretical result. However, both of them deviates from the true value 5 significantly. This happens because  $x_i^*$  is negatively related with  $r_i$ , i.e. farmers apply more fertilizer to lower-quality land, creating a spurious negative correlation between fertilizer and yield when land quality is not controlled for. The model suffers from severe omitted variable bias. The se is approximately 2.27, which is quite large.

• Regression Model 2 includes fertilizer amount  $x_i^*$  and land quality  $r_i$ , which is:

$$y_i = \beta_0 + \beta_1 x_i^* + \beta_2 r_i + \text{error}_i$$

The probability limit of  $\hat{\beta}_1$  should be:

$$plim(\hat{\beta}_1) = \beta_1 + \beta_3 \frac{Cov(x_i^*, g_i | r_i)}{Var(x_i^* | r_i)}$$

Since precipitation  $g_i$  is independent of both  $x_i^*$  and  $r_i$ , we have  $Cov(x_i^*, g_i|r_i) = 0$ . Therefore:

$$plim(\hat{\beta}_1) = \beta_1 = 5$$

This is unbiased despite omitting precipitation because precipitation is uncorrelated with fertilizer application. In this case, the simulated  $\beta_1$  improves significantly to 5.49, which is close to the true values. The *se* also significantly reduced to approximately 0.30.

• Regression Model 3 includes the complete set of causal variables, which is:

$$y_i = \beta_0 + \beta_1 x_i^* + \beta_2 r_i + \beta_3 g_i + \text{error}_i$$

It's correctly specified so it yields unbiased estimates like Model 2:

$$plim(\hat{\beta}_1) = \beta_1 = 5$$

However, for Model 2:

$$\begin{split} \varepsilon_i^{M2} &= y_i - (\hat{\beta}_0 + \hat{\beta}_1 x_i + \hat{\beta}_2 r_i) \approx \hat{\beta}_3 g_i + u_i \\ \sigma_\varepsilon^2 &= \mathrm{Var}(\beta_3 g_i + u_i) = \beta_3^2 \mathrm{Var}(g_i) + \mathrm{Var}(u_i) \end{split}$$

For Model 3:

$$\begin{split} \varepsilon_i^{M3} &= y_i - (\hat{\beta}_0 + \hat{\beta}_1 x_i + \hat{\beta}_2 r_i + \hat{\beta}_3 g_i) \approx u_i \\ \sigma_\varepsilon^2 &\approx \mathrm{Var}(u_i) \end{split}$$

Model 2's estimate is less precise because the residual variance is higher. Model 3 will have a  $\beta_1$  closer to true value 5 and a lower se-0.22.

• Model 4 and 5's equations are as follows:

Model 4: 
$$y_i = \beta_0 + \beta_1 x_i^* + \beta_2 r_i + \beta_4 n_i + \text{error}_i$$
  
Model 5:  $y_i = \beta_0 + \beta_1 x_i^* + \beta_2 r_i + \beta_4 b_i + \text{error}_i$ 

The simulated  $\beta_1$  estimates are 5.45 and 5.50 respectively. Similar with Model 2, both the estimation are unbiased. However, they differ in efficiency:

- Model 4 adds  $n_i$ , which is uncorrelated with other variables, causing a slight loss in efficiency. Its se becomes higher compared with Model 2 due to the reduction in model degrees of freedom 0.3084 verse 0.3037;
- Model 5 adds  $b_i$ , which is correlated to  $x_i^*$ , creating multicollinearity and potentially substantial efficiency loss. Therefore, its se is 0.32, higher than Model 2 and 4. The variance inflation due to multicollinearity in Model 5 is given by:

$$\frac{Var(\hat{\beta}_{1}^{M5})}{Var(\hat{\beta}_{1}^{M2})} = \frac{1}{1 - R_{x^{*}|r,b}^{2}}$$

#### Part (c)

```
M < -100
n <- 100
true beta1 <- 5
simulate_beta1 <- matrix(NA, nrow = M, ncol = 5)</pre>
for (m in 1:M) {
  r \leftarrow rbinom(n, size = 1, prob = 0.5)
  x \leftarrow ifelse(r == 1,
                rgamma(sum(r == 1), shape = 3, rate = 1),
                rgamma(sum(r == 0), shape = 7, rate = 1))
  g \leftarrow rgamma(n, shape = 2, rate = 2)
  u \leftarrow rnorm(n, mean = 0, sd = sqrt(5))
  y \leftarrow 400 + 5 * x + 200 * r + 10 * g + u
  n1 \leftarrow rnorm(n, mean = 10, sd = 3)
  b \leftarrow rnorm(n, mean = 5 + sqrt(x), sd = 3)
  df <- data.frame(y, x, r, g, n1, b)</pre>
  simulate beta1[m, 1] \leftarrow coef(lm(y ~ x, data = df))["x"]
  simulate_beta1[m, 2] \leftarrow coef(lm(y \sim x + r, data = df))["x"]
  simulate\_beta1[m, 3] \leftarrow coef(lm(y \sim x + r + g, data = df))["x"]
  simulate_beta1[m, 4] \leftarrow coef(lm(y \sim x + r + n1, data = df))["x"]
  simulate_beta1[m, 5] \leftarrow coef(lm(y \sim x + r + b, data = df))["x"]
}
```

```
par(mfrow = c(2, 3))
model_names <- c("Model 1", "Model 2", "Model 3", "Model 4", "Model 5")

for (i in 1:5) {
   hist(simulate_beta1[, i],
        main = paste("Histogram for", model_names[i]),
        xlab = expression(hat(beta)[1]),
        col = "lightblue")
   abline(v = true_beta1, col = "red", lwd = 2)
}</pre>
```

#### **Histogram for Model 1 Histogram for Model 2 Histogram for Model 3** 20 20 15 Frequency Frequency Frequency 20 9 0 9 S 4.0 4.5 5.0 5.5 6.0 5.2 -25 -20 -15 4.8 5.0 $\hat{\beta}_1$ $\hat{\beta}_1$ $\hat{\beta}_1$ **Histogram for Model 5 Histogram for Model 4** 20 20 Frequency 9 9 4.0 4.5 5.0 5.5 6.0 4.0 4.5 5.0 5.5 6.0

The results of the Monte Carlo simulations are in general agreement with the analysis in question b). The mean of  $\beta_1$  across simulations all converge to the theoretical probability limits. Specifically:

 $\hat{\beta}_1$ 

• Model 1: centered around -17, with the largest spread;

 $\hat{\beta}_1$ 

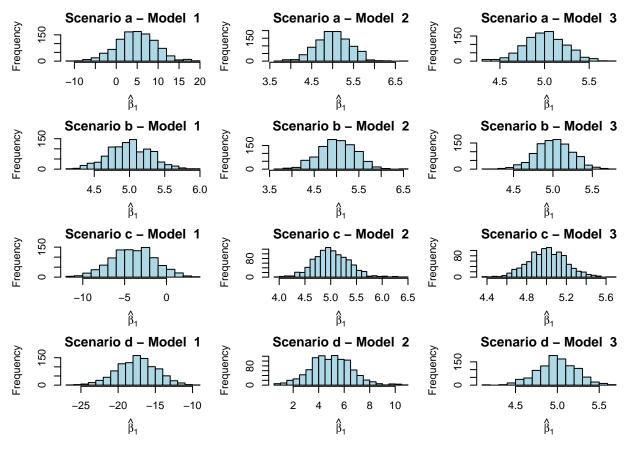
- Models 2-5: all centered around 5, but with different spread. Among them:
  - Model 2 produces the least efficient estimates within the group, showing maximal dispersion;

- Model 3 achieves the minimum variance bound, suggesting the most precise estimation;
- Model 4 is similar with Model 3 but exhibits a slightly wider spread due to the inclusion of an extraneous variable.
- Model 5 presents a broader dispersion than Models 3 and 4, indicating increased variability in the estimates.

# Part (d)

```
M < -1000
n <- 100
# Define modification scenarios in a list
# Each element contains a description and parameters
scenarios <- list(</pre>
  a = list(desc = "x|r identical: Gamma(5,1)", beta2 = 200, beta3 = 10, prob_r = 0.5, gamma(5,1)"
 b = list(desc = "beta2 = 0",
                                                  beta2 = 0, beta3 = 10, prob r = 0.5, ga
 c = list(desc = "P(r=1) = 0.1",
                                                  beta2 = 200, beta3 = 10, prob_r = 0.1, ga
  d = list(desc = "beta3 = 50",
                                                  beta2 = 200, beta3 = 50, prob_r = 0.5, ga
)
simulate_one <- function(scenario_params) {</pre>
  # True model parameters
  beta0 <- 400
  beta1 <- 5
  beta2 <- scenario_params$beta2</pre>
  beta3 <- scenario params$beta3
  prob_r <- scenario_params$prob_r</pre>
  u \leftarrow rnorm(n, mean = 0, sd = 5)
  g \leftarrow rgamma(n, shape = 2, rate = 2)
  r <- rbinom(n, size = 1, prob = prob r)
  if (scenario params$gamma shape == "a") {
    x \leftarrow rgamma(n, shape = 5, scale = 1)
  } else {
    x <- numeric(n)
    x[r == 1] \leftarrow rgamma(sum(r == 1), shape = 3, rate = 1)
    x[r == 0] \leftarrow rgamma(sum(r == 0), shape = 7, rate = 1)
  }
  y <- beta0 + beta1 * x + beta2 * r + beta3 * g + u
```

```
beta1 vals <- c(
    coef(lm(y ~ x))[["x"]],
    coef(lm(y - x + r))[["x"]],
    coef(lm(y ~ x + r + g))[["x"]]
 names(beta1_vals) <- c("Model 1", "Model 2", "Model 3")</pre>
  return(beta1 vals)
}
par(mfrow = c(4, 3), mar = c(4, 4, 2, 1))
results <- list()
for (scenario in names(scenarios)) {
  scenario_params <- scenarios[[scenario]]</pre>
  beta1 mat <- t(replicate(M, simulate_one(scenario params)))</pre>
  results[[scenario]] <- beta1 mat</pre>
  for (i in 1:3) {
    hist(beta1 mat[, i],
         main = paste("Scenario", scenario, "-", "Model ", i),
         xlab = expression(hat(beta)[1]),
         col = "lightblue",
         breaks = 20)
  }
}
```



• Scenario 1:  $x_i^*|r=1) = x_i^*|r=0) \sim \Gamma(5,1)$ 

In this case, both distributions have mean 5, i.e.  $E[x_i^*|r=1] = E[x_i^*|r=0] = 5$ . Therefore:

$$Cov(x_i^*, r_i) = 0.$$

Therefore we have:

$$plim(\hat{\beta}_1) = \beta_1 + \beta_2 \frac{Cov(x_i^*, r_i)}{Var(x_i^*)} = \beta_1$$

This means that in Scenario 1, all the  $\beta_1$  estimated will be unbiased. The trend of their variances are also the same as before, gradually decreasing as more variables are added, i.e.  $Var(\hat{\beta}_1^{M3}) < Var(\hat{\beta}_1^{M2}) < Var(\hat{\beta}_1^{M1})$ 

• Scenario 2:  $\beta_2 = 0$ 

In this case, land quality  $r_i$  has no effect on crop yields  $y_i$ . Therefore:

$$plim(\hat{\beta}_1) = \beta_1 + \beta_2 \frac{Cov(x_i^*, r_i)}{Var(x_i^*)} = \beta_1$$

Again, all the  $\beta_1$  estimated are unbiased even though  $x_i^*$  and  $r_i$  are still correlated.

In terms of variance we have:

$$Var(\hat{\beta}_1^{M3}) < Var(\hat{\beta}_1^{M1}) < Var(\hat{\beta}_1^{M2})$$

• Scenario 3:  $r_i = 1$  with probability 0.1

In this case, similar to the calculation in previous questions, we have:

$$Cov(x,r) = E[x_i^*r_i] - E[x_i^*]E[r_i] = 0.3 - (6.6 \times 0.1) = -0.36$$

 $Var(x_i^*) = E[Var(x_i^*|r_i)] + Var(E[x_i^*|r_i]) = 0.1 \times 3 + 0.9 \times 7 + 0.1 \times 0.9 \times (3-7)^2 = 8.04$  Therefore, for Model 1:

$$plim(\hat{\beta}_1) = \beta_1 + \beta_2 \frac{Cov(x_i^*, r_i)}{Var(x_i^*)} + \beta_3 \frac{Cov(x_i^*, g_i)}{Var(x_i^*)} = 5 + 200 \times \frac{-0.36}{8.04} \approx -3.96$$

For Model 2 & 3:

$$plim(\hat{\beta}_1) = \beta_1 + \beta_2 \frac{Cov(x_i^*, r_i)}{Var(x_i^*)} + \beta_3 \frac{Cov(x_i^*, g_i)}{Var(x_i^*)} = 5$$

The distribution of  $\hat{\beta}_1$  of Model 1 will center around -3.96, with the highest variance. We still see some negative bias, but presumably smaller in magnitude than before. The distribution of  $\hat{\beta}_1$  of Model 2 and Model 3 will still both center around 5, with Model 3 having a smaller variance. Therefore:

$$Var(\hat{\beta}_1^{M3}) < Var(\hat{\beta}_1^{M2}) < Var(\hat{\beta}_1^{M1})$$

• Scenario 4:  $\beta_3 = 50$ 

In this case, the true DGP is:

$$y_i = 400 + 5x_i^* + 200r_i + 50g_i + u_i$$

For Model 1, again, its  $\hat{\beta}_1$  will be biased as before. However, the bigger difference is now the residual variance of the regression is much higher because  $g_i$  contributes strongly to  $y_i$ . This means that  $\beta_1$  will have a larger se.

For Model 2 and 3, their  $\hat{\beta}_1$  will also be unbiased as before, and we still have  $Var(\hat{\beta}_1^{M3}) < Var(\hat{\beta}_1^{M2})$ . However, since  $g_i$  has a very large effect on  $y_i$ , Model 2's omission of  $g_i$  will result in a much larger variance than any previous scenario, i.e.  $Var(\hat{\beta}_1^{M2-Scenario4}) > Var(\hat{\beta}_1^{M2-Scenario1/2/3})$ .