

Lecture Notes: Econometrics II

Based on lectures by [Marko Mlikota](#) in Spring semester, 2025

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These lecture notes were taken in the course *Econometrics II* taught by [Marko Mlikota](#) at Graduate of International and Development Studies, Geneva as part of the International Economics program (Semester II, 2024).

Currently, these are just drafts of the lecture notes. There can be typos and mistakes anywhere. So, if you find anything that needs to be corrected or improved, please inform at jingle.fu@graduateinstitute.ch.

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Lecture 1.

Review of Econometrics I

1.1 Basic assumptions

As we know,

$$\hat{\beta} = (X'X)^{-1}X'y \xrightarrow{P} \beta$$

if

1. Model is correctly specified: $y_i = x_i'\beta + u_i$
2. X is full rank
3. $\mathbb{E}[x_i u_i] = 0$: x_i is exogenous.
4. Unbiased CIA: $\mathbb{E}[u_i | x_i] = 0$

Theorem 1.1.1 (Frisch-Waugh-Lovell (FWL) theorem).

Recall: $\hat{Y} = X\hat{\beta} = X(X'X)^{-1}X'Y = P_X Y$, $Y = \hat{Y} + \hat{U} \rightarrow \hat{U} = (I - P_X)Y = M_X Y$.

Take $Y = X_1\beta_1 + X_2\beta_2 + U = X\beta' + U$, let $P_1 = X_1(X_1'X_1)^{-1}X_1'$, $M_1 = I - P_1$.

And write $M_1 Y = M_1 X_2 \beta_2 + M_1 U$, then

$$\hat{\beta}_{2,OLS} = \hat{b}.$$

1.2 Endogeneity

Three reasons for endogeneity:

1. Measurement error: x_i is measured with error.

Assume the true Regression is: $y_i = x_i^{*'}\beta + \varepsilon_i$, $\mathbb{E}[x_i^* \varepsilon_i] = 0$, we run: $y_i = x_i'\beta + u_i$, $x_i = x_i^* + v_i$, $u_i = \varepsilon_i - v_i'\beta$.

$$\begin{aligned} \mathbb{E}[x_i u_i] &= \underbrace{\mathbb{E}[x_i \varepsilon_i]}_0 - \mathbb{E}[x_i v_i']\beta \\ &= -\mathbb{E}[(x_i^* + v_i)v_i']\beta \\ &= \underbrace{-\mathbb{E}[x_i^* v_i']}_0 \beta - \mathbb{E}[v_i v_i']\beta \\ &= -\mathbb{E}[v_i v_i']\beta \end{aligned}$$

2. Simultaneity (Reverse causality): x_i is endogenous.

$$y_i = x_i'\beta + u_i = x_{i1}^*\beta_1 + x_{i2}\beta_2 + u_i, \quad x_i = z_i'\gamma + y_i\delta + v_i.$$

3. Omitted variables: x_i is correlated with u_i .

The true regression is: $y_i = x_i'\beta + w_i'\delta + \varepsilon_i$, $\mathbb{E}[x_i \varepsilon_i] \neq 0$, $\mathbb{E}[w_i \varepsilon_i] = 0$.

We run: $y_i = x_i' \beta + u_i$, then

$$\begin{aligned}\mathbb{E}[x_i u_i] &= \mathbb{E}[x_i (w_i' \delta + \varepsilon_i)] \\ &= \mathbb{E}[x_i w_i'] \delta + \underbrace{\mathbb{E}[x_i \varepsilon_i]}_0\end{aligned}$$

For our general regression model $y_i = x_i' \beta + u_i$, we have $\mathbb{E}[x_i u_i] \neq 0$, thus $\hat{\beta}_{OLS} \xrightarrow{P} \beta$ doesn't hold.

We take $z_i \in \mathbb{R}^r$, which is a good IV if:

1. Relevance: $\mathbb{E}[z_i x_i] \neq 0$;
2. Exogeneity: $\mathbb{E}[z_i u_i] = 0$.

Then, we have the 2SLS method:

Definition 1.2.1 (2SLS Method).

1. Estimate: $x_i = z_i' \gamma + e_i \Rightarrow \hat{\gamma} = (Z'Z)^{-1} Z'X \Rightarrow \hat{X} = Z' \hat{\gamma} = P_Z X$;
2. Estimate: $y_i = \hat{x}_i' \beta + u_i^*$.

$$\begin{aligned}\hat{\beta}_{2SLS} &= (\hat{X}' \hat{X})^{-1} \hat{X}' Y \\ &= ((P_Z X)' P_Z X)^{-1} (P_Z X)' Y \\ &= (X' P_Z X)^{-1} X' P_Z Y \\ &= (X' Z (Z' Z)^{-1} Z' X)^{-1} X' Z (Z' Z)^{-1} Z' Y \\ &= \beta + (X' Z (Z' Z)^{-1} Z' X)^{-1} X' Z (Z' Z)^{-1} Z' u \\ &\xrightarrow{P} \beta + Q_{xz}^{-1} \mathbb{E}[x_i z_i'] \mathbb{E}[z_i z_i'] \mathbb{E}[z_i u_i] \\ &= \beta.\end{aligned}$$

$$\begin{aligned}\mathbb{V}[\hat{\beta}_{2SLS} | X, Z] &= \mathbb{V}[(X' P_Z X)^{-1} X' P_Z U | X, Z] \\ &= (X' P_Z X)^{-1} \mathbb{V}[X' P_Z U | X, Z] (X' P_Z X)^{-1} \\ &= (X' P_Z X)^{-1} X' P_Z \mathbb{V}[U] P_Z X (X' P_Z X)^{-1} \\ &= (X' P_Z X)^{-1} \sigma^2\end{aligned}$$

As we know $\mathbb{V}[\hat{\beta}_{OLS}] = (X' X)^{-1} \sigma^2$,

$$\begin{aligned}\mathbb{V}[\hat{\beta}_{OLS}]^{-1} - \mathbb{V}[\hat{\beta}_{2SLS}]^{-1} &= (\sigma^2)^{-1} X' X - (\sigma^2)^{-1} X' P_Z X \\ &= (\sigma^2)^{-1} X' (I - P_Z) X \\ &= (\sigma^2)^{-1} X' M_Z X \\ &= \sigma^{-2} \underbrace{(M_Z X)' M_Z X}_{\hat{E}} \\ &= \sigma^{-2} SSR_{1SLS}.\end{aligned}$$

Theorem 1.2.1 (Anderson-Rubin Method).

$$y_i = x_i' \beta_0 + u_i, \mathbb{E}[z_i u_i] = 0, y_i - x_i' \beta = \delta z_i + v_i. \Rightarrow \hat{\delta}(\beta) = (Z' Z)^{-1} Z' (Y - X \beta) \rightarrow \hat{\delta}(\beta_0) =$$

$(Z'Z)^{-1}Z'U$. For many β s, test: $H_0 : \delta(\beta) = 0$, e.g. using t-test.

$$T_t = \frac{\hat{\delta}(\beta)}{se(\hat{\delta}(\beta))} \sim \mathbf{N}(0, 1)$$

The 90% CI for β is the set of β s at which $\delta(\beta) = 0$ cannot be rejected at 90% confidence level.

Causal Inference

2.1 Potential Outcomes Framework

Definition 2.1.1 (Stable Unit Treatment Value Assumption (SUTVA)).

$$y_i = \begin{cases} y_{0i} & d_i = 0 \\ y_{1i} & d_i = 1 \end{cases}$$

Causal effect of d_i on y_i for individual i : $y_{1i} - y_{0i}$.

$$y_i = d_i y_{1i} + (1 - d_i) y_{0i}$$

SUTVA(2.1.1) ensures that the individual treatment effect is well defined.

For a population, we know that $\mathbb{E}[d_i], \mathbb{E}[y_i], \mathbb{E}[y_{0i}], \mathbb{E}[y_{1i}]$ exist, we can define the treatment conditional expectations:

$$\mathbb{E}[y_i | d_i = 1], \mathbb{E}[y_{0i} | d_i = 1], \mathbb{E}[y_{1i} | d_i = 1] = \mathbb{E}[y_i | d_i = 1]$$

that denote the averages of the outcome y_i .

Analogously, we can define the control conditional expectations:

$$\mathbb{E}[y_i | d_i = 0], \mathbb{E}[y_{0i} | d_i = 0] = \mathbb{E}[y_i | d_i = 0], \mathbb{E}[y_{1i} | d_i = 0]$$

for the non-treated subpopulation.

Then, we can define the Average Treatment Effect (ATE), the Average Treatment Effect for the Treatment-Group (ATT) and the Average Treatment Effect for the Control-Group (ATC) as distinct objects:

$$\text{ATE} = \mathbb{E}[y_{1i} - y_{0i}]$$

$$\text{ATT} = \mathbb{E}[y_{1i} - y_{0i} | d_i = 1]$$

$$\text{ATC} = \mathbb{E}[y_{1i} - y_{0i} | d_i = 0]$$

$$\mathbb{E}[z] = \mathbb{E}[z | d = 1] \mathbb{P}[d = 1] + \mathbb{E}[z | d = 0] \mathbb{P}[d = 0] = \mathbb{E}[\mathbb{E}[z | d]].$$

For sample, $\{d_i, y_i\}_{i=1}^n = \{d_i, y_{d_i, i}\}_{i=1}^n$, because $y_i = y_{1i} d_i + y_{0i} (1 - d_i)$.

$N = \{i = 1, 2, \dots, n\}$, $N_1 = \{i \in N : d_i = 1\} \leftarrow n_1 = |N_1|$, $N_0 = \{i : d_i = 0\} \leftarrow n_0 = |N_0|$.

$$\frac{1}{n_1} \sum_{i \in N_1} y_i = \frac{1}{n_1} \sum_{i \in N_1} y_{1i} \xrightarrow{p} \mathbb{E}[y_{1i} | d_i = 1] = \mathbb{E}[y_i | d_i = 1]$$

$$\frac{1}{n_0} \sum_{i \in N_0} y_i = \frac{1}{n_0} \sum_{i \in N_0} y_{0i} \xrightarrow{p} \mathbb{E}[y_{0i} | d_i = 0] = \mathbb{E}[y_i | d_i = 0]$$

$$\frac{1}{n_1} \sum_{i \in N_1} y_i - \frac{1}{n_0} \sum_{i \in N_0} y_i \xrightarrow{p} \mathbb{E}[y_{1i} | d_i = 1] - \mathbb{E}[y_{0i} | d_i = 0] = \text{ATE} = \text{ATT} = \text{ATC}.$$

We define the difference of treated and non-treated as: *Naive Difference*.

$$\begin{aligned} \text{ND} &= \mathbb{E}[y_{1i}|d_i = 1] - \mathbb{E}[y_{0i}|d_i = 0] \\ &= \mathbb{E}[y_{1i}|d_i = 1] - \mathbb{E}[y_{0i}|d_i = 1] + \mathbb{E}[y_{0i}|d_i = 1] - \mathbb{E}[y_{0i}|d_i = 0] \\ &= \text{ATT} + \mathbb{E}[y_{0i}|d_i = 1] - \mathbb{E}[y_{0i}|d_i = 0] \end{aligned}$$

For LRM, $y_i = \beta_0 + \beta_1 d_i + u_i$,

$$\begin{aligned} \text{ND} &= \mathbb{E}[y_i|d_i = 1] - \mathbb{E}[y_i|d_i = 0] \\ &= \mathbb{E}[\beta_0 + \beta_1 + u_i|d_i = 1] - \mathbb{E}[\beta_0 + u_i|d_i = 0] \\ &= \beta_1 + \mathbb{E}[u_i|d_i = 1] - \mathbb{E}[u_i|d_i = 0] \end{aligned}$$

$$\{Y_d\} \perp\!\!\!\perp D \mid X \Rightarrow \{Y_d\} \perp\!\!\!\perp D \mid \pi(X), \quad D \perp\!\!\!\perp X \mid \pi(X)$$

Lecture 3.

Panel Data Analysis

3.1 Incidental Parameters Problem

3.1.1 Consistency

 $i = 1 : n, t = 1 : T, z_{it}$

$$\begin{aligned} y_{it} &= \alpha + x'_{it}\beta + u_{it} \\ &= \tilde{x}'_{it}\tilde{\beta} + u_{it} \\ \tilde{x}_{it} &= \begin{bmatrix} 1 \\ x_{it} \end{bmatrix} \\ \tilde{\beta} &= \begin{bmatrix} \alpha \\ \beta \end{bmatrix} \end{aligned}$$

Then,

$$\begin{aligned} y_i &= \tilde{x}_i \tilde{\beta} + u_i \\ T \times 1 & \quad T \times K \quad K \times 1 \quad T \times 1 \\ \min_{\tilde{\beta}} \sum_i \sum_t u_{it}^2 &= \min_{\tilde{\beta}} \sum_i u'_i u_i = \min_{\tilde{\beta}} (y_i - \tilde{x}_i \tilde{\beta})' (y_i - \tilde{x}_i \tilde{\beta}) \end{aligned}$$

The FOC of this equation is:

$$\begin{aligned} \sum_i -\tilde{x}'_i (y_i - \tilde{x}_i \tilde{\beta}) &= 0 \\ \left(\sum_i \tilde{x}'_i \tilde{x}_i \right) \tilde{\beta} &= \sum_i \tilde{x}'_i y_i \\ \hat{\tilde{\beta}} &= \left(\sum_i \tilde{x}'_i \tilde{x}_i \right)^{-1} \sum_i \tilde{x}'_i y_i \\ &= \left(\sum_i \sum_t \tilde{x}_{it} \tilde{x}'_{it} \right)^{-1} \left(\sum_i \sum_t \tilde{x}_{it} y_{it} \right) \\ &= \tilde{\beta} + \left(\frac{1}{n} \sum_i \sum_t \tilde{x}_{it} \tilde{x}'_{it} \right)^{-1} \left(\sum_i \sum_t \tilde{x}_{it} u_{it} \right) \\ &\xrightarrow{p} \tilde{\beta} + \mathbb{E} \left[\sum_t \tilde{x}_{it} \tilde{x}'_{it} \right]^{-1} \mathbb{E} \left[\sum_t \tilde{x}_{it} u_{it} \right] \\ &= \tilde{\beta} \end{aligned}$$

3.1.2 Asymptotic Normality

From the analysis of consistency, we know that:

$$\hat{\beta} = \left(\sum_i \tilde{x}'_i \tilde{x}_i \right)^{-1} \sum_i \tilde{x}'_i y_i$$

Hence:

$$\begin{aligned} \sqrt{n}(\hat{\beta} - \tilde{\beta}) &= \left(\frac{1}{n} \sum_i \tilde{x}'_i \tilde{x}_i \right)^{-1} \left(\frac{1}{\sqrt{n}} \sum_i \tilde{x}'_i u_i \right) \\ &\xrightarrow{p} \mathbb{E}[\tilde{x}'_i \tilde{x}_i]^{-1} \xrightarrow{d} \mathcal{N} \left(0, \mathbb{E} \left[(\tilde{x}'_i u_i) (\tilde{x}'_i u_i)' \right] \right) \\ &\xrightarrow{d} \mathcal{N} \left(0, \mathbb{E} [\tilde{x}'_i \tilde{x}_i]^{-1} \mathbb{E} [\tilde{x}'_i u_i u'_i \tilde{x}_i] \mathbb{E} [\tilde{x}'_i \tilde{x}_i] \right) \end{aligned}$$

For $y_{it} = \alpha_i + x'_{it}\beta + u_{it}$,

Under $T = 1$, we run $y_i = \beta_0 + x'_i\beta + v_i$, where $v_u = u_i + \underbrace{\alpha_i - \beta_0}_{\tilde{\alpha}_i}$ and $\mathbb{E}[v_i] = 0$.

Under $T > 1$, we run:

$$\begin{aligned} y_i &= x'_i\beta + \sum_{j=1}^n \alpha_j \mathbf{1}\{i = j\} + u_{it} \\ &= \tilde{x}'_{it}\tilde{\beta} + u_{it} \\ \tilde{x}_{it} &= \begin{bmatrix} x_{it} \\ \mathbf{1}\{i = 1\} \\ \mathbf{1}\{i = 2\} \\ \vdots \\ \mathbf{1}\{i = n\} \end{bmatrix}, \quad \tilde{\beta} = \begin{bmatrix} \beta \\ \alpha_1 \\ \alpha_2 \\ \vdots \\ \alpha_n \end{bmatrix} \end{aligned}$$

3.2 Random Effects

We put α_i in error terms:

$$\begin{aligned} y_{it} &= \alpha_1 + x'_{it}\beta + u_{it} \\ &= \underbrace{\beta_0 + x'_{it}\beta}_{\tilde{x}'_{it}\tilde{\beta}} + \underbrace{u_{it} + \alpha_i - \beta_0}_{\equiv v_{it}} \\ \rightarrow y_{it} &= \tilde{x}'_{it}\tilde{\beta} + v_{it} \\ \Leftrightarrow y_i &= \tilde{x}'_i\tilde{\beta} + v_i \\ \rightarrow \hat{\beta} &= \left(\sum_i \tilde{x}'_i \tilde{x}_i \right)^{-1} \sum_i \tilde{x}'_i y_i \end{aligned}$$

Note (POLS).

Homogenous spec: $y_{it} = \alpha + x'_{it}\beta + u_{it} = \tilde{x}'_{it}\tilde{\beta} + u_{it}$. $\hat{\beta}$ is consistent if $\mathbb{E}[v_{it}x_{it}] = 0, \forall t$.

$$\begin{aligned}
\hat{\beta} &= \left(\frac{1}{n} \sum_i \tilde{x}'_i \tilde{x}_i \right)^{-1} \frac{1}{n} \sum_i \tilde{x}'_i y_i \\
&= \tilde{\beta} + \left(\frac{1}{n} \sum_i \tilde{x}'_i \tilde{x}_i \right)^{-1} \frac{1}{n} \sum_i \tilde{x}'_i v_i \\
&\xrightarrow{p} \tilde{\beta} + \mathbb{E}[\tilde{x}'_i \tilde{x}_i]^{-1} \mathbb{E}[\tilde{x}'_i v_i] \\
\text{where } \mathbb{E}[\tilde{x}'_i v_i] &= \mathbb{E} \left[\sum_t \tilde{x}'_{it} v_{it} \right] \\
&= \sum_t \mathbb{E}[\tilde{x}'_{it} v_{it}] \\
&= \sum_t \mathbb{E}[\tilde{x}_{it}(u_{it} + \alpha_i - \beta_0)]
\end{aligned}$$

Note.

Under the random effect, you have to use the heteroskedasticity-robust methods. Because even if we assume u_{it} to be homoskedastic, v_{it} is not, as it includes also the unit-specific heterogeneity α_i .

Denoted by $\hat{\beta}_{RE-GLS}$, the random effect GLS estimator is consistent and asymptotically normal.

$$\begin{aligned}
\sqrt{n} \left(\hat{\beta}_{RE-GLS} - \tilde{\beta} \right) &\xrightarrow{d} \mathcal{N}(0, V) \\
\text{where } V &= \mathbb{E}[\tilde{x}'_i \tilde{x}_i]^{-1} \mathbb{E}[\tilde{x}'_i v_i v'_i \tilde{x}_i] \mathbb{E}[\tilde{x}'_i \tilde{x}_i] \\
&= \mathbb{E} \left[\tilde{x}'_i \tilde{x}_i \underbrace{\mathbb{E}[v_i v'_i | \tilde{x}_i]}_{\equiv \Omega} \right] \\
\rightarrow \hat{\beta}_{RE-GLS} &= \left(\sum_i \tilde{x}'_i \Omega^{-1} \tilde{x}_i \right)^{-1} \sum_i \tilde{x}'_i \Omega^{-1} y_i \\
\Omega^{-\frac{1}{2}} y_i &= \Omega^{-\frac{1}{2}} \tilde{x}'_i \tilde{\beta} + \Omega^{-\frac{1}{2}} v_i \\
\Omega &= \mathbb{E}[v_i v'_i | \tilde{x}_i] = \mathbb{E} \left[\begin{bmatrix} v_{i1} \\ v_{i2} \\ \vdots \\ v_{iT} \end{bmatrix} \begin{bmatrix} v_{i1} & v_{i2} & \cdots & v_{iT} \end{bmatrix} | \tilde{x}_i \right] \\
&= \mathbb{E} \begin{bmatrix} \mathbb{E}[v_{i1}^2 | \tilde{x}_i] & \mathbb{E}[v_{i1} v_{i2} | \tilde{x}_i] & \cdots & \mathbb{E}[v_{i1} v_{iT} | \tilde{x}_i] \\ \mathbb{E}[v_{i2} v_{i1} | \tilde{x}_i] & \mathbb{E}[v_{i2}^2 | \tilde{x}_i] & \cdots & \mathbb{E}[v_{i2} v_{iT} | \tilde{x}_i] \\ \vdots & \vdots & \ddots & \vdots \\ \mathbb{E}[v_{iT} v_{i1} | \tilde{x}_i] & \mathbb{E}[v_{iT} v_{i2} | \tilde{x}_i] & \cdots & \mathbb{E}[v_{iT}^2 | \tilde{x}_i] \end{bmatrix} \\
&= \begin{bmatrix} \mathbb{E}[\alpha_i^2 | \tilde{x}_i] + \mathbb{E}[u_{i1}^2 | \tilde{x}_i] & \mathbb{E}[\alpha_i^2 | \tilde{x}_i] + \mathbb{E}[u_{i1} u_{i2} | \tilde{x}_i] & \cdots & \mathbb{E}[\alpha_i^2 | \tilde{x}_i] + \mathbb{E}[u_{i1} u_{iT} | \tilde{x}_i] \\ \mathbb{E}[\alpha_i^2 | \tilde{x}_i] + \mathbb{E}[u_{i2} u_{i1} | \tilde{x}_i] & \mathbb{E}[\alpha_i^2 | \tilde{x}_i] + \mathbb{E}[u_{i2}^2 | \tilde{x}_i] & \cdots & \mathbb{E}[\alpha_i^2 | \tilde{x}_i] + \mathbb{E}[u_{i2} u_{iT} | \tilde{x}_i] \\ \vdots & \vdots & \ddots & \vdots \\ \mathbb{E}[\alpha_i^2 | \tilde{x}_i] + \mathbb{E}[u_{iT} u_{i1} | \tilde{x}_i] & \mathbb{E}[\alpha_i^2 | \tilde{x}_i] + \mathbb{E}[u_{iT} u_{i2} | \tilde{x}_i] & \cdots & \mathbb{E}[\alpha_i^2 | \tilde{x}_i] + \mathbb{E}[u_{iT}^2 | \tilde{x}_i] \end{bmatrix} \\
&= \mathbb{E} \left[\mathbb{E}[\alpha_i^2 | \tilde{x}_i] \mathbf{1} \right] + \mathbb{E}[u_i u'_i | \tilde{x}_i]
\end{aligned}$$

$$\begin{aligned}
&= \mathbb{E}[\alpha_i^2] \mathbf{1}\mathbf{1}' + \begin{bmatrix} \mathbb{E}[u_{i1}^2|\tilde{x}_i] & 0 & \cdots & 0 \\ 0 & \mathbb{E}[u_{i2}^2|\tilde{x}_i] & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & \mathbb{E}[u_{iT}^2|\tilde{x}_i] \end{bmatrix} \\
&= \sigma_{\alpha_i}^2 \mathbf{1}\mathbf{1}' + \sigma_i^2 I \\
&= \sigma_{\alpha}^2 \mathbf{1}\mathbf{1}' + \sigma^2 I \\
&\text{beacuse } \mathbb{V}[\tilde{\alpha}_i|\tilde{x}_i] = \sigma_{\alpha_i}^2 = \sigma_{\alpha}^2 \\
&\mathbb{V}[u_{it}|\tilde{x}_i] = \sigma_i^2 = \sigma^2, \forall i.
\end{aligned}$$

$$\begin{aligned}
\Omega &= \mathbb{E}[v_i v_i' | \tilde{x}_i] \\
&= \mathbb{E}[(\alpha_i \mathbf{1} + u_i)(\alpha_i \mathbf{1} + u_i)' | \tilde{x}_i] \\
&= \mathbb{E}[\alpha_i^2] \mathbf{1}\mathbf{1}' + \mathbb{E}[u_i u_i' | \tilde{x}_i]
\end{aligned}$$

3.3 Fixed Effects

We transform equation to get rid of α_i : $y_{it} = \alpha_i + x'_{it}\beta + u_{it}$.

Within $\bar{y}_i = \alpha_i + \bar{x}'_i\beta + \bar{u}_i$, $\bar{y}_i = \frac{1}{T} \sum_t y_{it}$. Then,

$$\begin{aligned}
(y_{it} - \bar{y}_i) &= (x_{it} - \bar{x}_i)' \beta + (u_{it} - \bar{u}_i) \\
\check{y}_{it} &= \check{x}'_{it} \beta + \check{u}_{it}
\end{aligned}$$

The first difference estimation method:

$$\begin{aligned}
y_{it} - y_{i,t-1} &= (x_{it} - x_{i,t-1})' \beta + (u_{it} - u_{i,t-1}) \\
\Delta y_{it} &= \Delta x'_{it} \beta + \Delta u_{it}, i = 1 \cdots n, t = 2 \cdots T.
\end{aligned}$$

Denote the time-averages method by $\hat{\beta}_{FE-W}$, the fixed effect estimator is consistent and asymptotically normal.

$$\begin{aligned}
\hat{\beta}_{FE-W} &= \left(\sum_i \sum_t \check{x}_{it} \check{x}'_{it} \right)^{-1} \sum_i \sum_t \check{x}_{it} \check{y}_{it} \\
&= \beta + \left(\sum_i \sum_t \check{x}_{it} \check{x}'_{it} \right)^{-1} \sum_i \sum_t \check{x}_{it} \check{u}_{it} \\
&\xrightarrow{p} \beta + \mathbb{E} \left[\sum_t \check{x}_{it} \check{x}'_{it} \right]^{-1} \mathbb{E} \left[\sum_t \check{x}_{it} \check{u}_{it} \right]
\end{aligned}$$

where $\mathbb{E} \left[\sum_t \check{x}_{it} \check{u}_{it} \right] = \sum_t \mathbb{E} [\check{x}_{it} \check{u}_{it}]$

$$\begin{aligned}
\mathbb{E} [\check{x}_{it} \check{u}_{it}] &= \mathbb{E} \left[\left(x_{it} - \frac{1}{T} \sum_t x_{it} \right) \left(u_{it} - \frac{1}{T} \sum_t u_{it} \right) \right]' \\
&= 0 \quad \text{if } u_{it} \perp\!\!\!\perp x_{is}, \forall t, s = 1, \dots, T.
\end{aligned}$$

Denote the first difference method by $\hat{\beta}_{FE-FD}$, the fixed effect estimator is consistent and asymptotically normal.

$$\begin{aligned}
\hat{\beta}_{FE-FD} &= \left(\sum_i \sum_t \Delta x_{it} \Delta x'_{it} \right)^{-1} \sum_i \sum_t \Delta x_{it} \Delta y_{it} \\
&= \beta + \left(\frac{1}{n} \sum_i \sum_t \Delta x_{it} \Delta x'_{it} \right)^{-1} \frac{1}{n} \sum_i \sum_t \Delta x_{it} \Delta u_{it} \\
&\xrightarrow{p} \beta + \mathbb{E} \left[\sum_t \Delta x_{it} \Delta x'_{it} \right]^{-1} \mathbb{E} \left[\sum_t \Delta x_{it} \Delta u_{it} \right] \\
\text{where } \mathbb{E} \left[\sum_t \Delta x_{it} \Delta u_{it} \right] &= \sum_t \mathbb{E} [\Delta x_{it} \Delta u_{it}] \\
\mathbb{E} [\Delta x_{it} \Delta u_{it}] &= \mathbb{E} [(x_{it} - x_{i,t-1}) (u_{it} - u_{i,t-1})'] \\
&= 0 \quad \text{if } x_{it} \perp\!\!\!\perp (u_{it}, u_{i,t-1}), \forall t.
\end{aligned}$$

Note.

The FD method is not as strong as the within method, because it only requires that the variable is uncorrelated with the error term in the same period and the previous period.

If there is a correlation between the error term in current period and two periods ago, there is a problem of feedback loop, which we will imply the correlated random effect model.

Take x_{it} for which $\bar{x}_i = x_{it}, \forall i, t$.

Theorem 3.3.1 (Hausman-Test).

$\mathcal{H}_0: \hat{\beta}_{RE, pop} = \hat{\beta}_{FE-W, pop} \Leftrightarrow$ We should use $\hat{\beta}_{RE}$.

We define:

$$T_{Hausman} = n(\hat{\beta}_{FE} - \hat{\beta}_{RE})' \left(A\mathbb{V}[\hat{\beta}_{FE}] - A\mathbb{V}[\hat{\beta}_{RE}] \right)^{-1} (\hat{\beta}_{FE} - \hat{\beta}_{RE}) \rightarrow \chi_k^2$$

Note.

To sum up, the FE estimators work under arbitrary correlation between the unobserved heterogeneity α_i and covariates X_i , but they cannot deal with time-constant regressors and their consistency is paid for by an efficiency loss relative to RE estimators.

Most importantly, their consistency requires strict exogeneity, a much stronger assumption than contemporaneous exogeneity of covariates and error terms.

3.3.1 FE-IV Estimation

1. Contemporaneous exogeneity: $\mathbb{E}[x_{it}u_{it}] = 0, \forall t$.
2. Strict exogeneity: $\mathbb{E}[x_{it}u_{is}] = 0, \forall t, s$.
3. Sequential exogeneity: $\mathbb{E}[x_{it}u_{is}] = 0, \forall t, s \geq t$.

Definition 3.3.1 (Predetermined variables(Or Sequential Exogeneity)).

Predetermined variables are variables that were determined prior to the current period. In econometric models this implies that the current period error term is uncorrelated with current and lagged values of the predetermined variable but may be correlated with future values. This is a weaker restriction than strict exogeneity, which requires the variable to be uncorrelated

with past, present, and future shocks.

Still assume that we have a standard model:

$$\begin{aligned} y_{it} &= \alpha_i + x'_{it}\beta + u_{it} \\ &= \alpha_i + \beta_1 y_{i,t-1} + \tilde{x}'_{it}\beta_{-1} + u_{it} \\ \Rightarrow \Delta y_{it} &= \Delta\alpha_i + \Delta x'_{it}\beta + \Delta u_{it} \end{aligned}$$

Definition 3.3.2 (Anderson and Hsiao(1981)).

FE-IV: Use $y_{i,t-2}$ as the IV for $\Delta y_{i,t-1}$.

Under sequential exogeneity, instrument-exogeneity is satisfied:

$$\mathbb{E}[y_{is}\Delta u_{it}] = 0, \forall s \leq t-2.$$

17.38 Anderson-Hsiao Estimator

Anderson and Hsiao (1982) made an important breakthrough by showing that a simple instrumental variables estimator is consistent for the parameters of (17.81).

The method first eliminates the individual effect u_i by first-differencing (17.81) for $t \geq p+1$

$$\Delta Y_{it} = \alpha_1 \Delta Y_{i,t-1} + \alpha_2 \Delta Y_{i,t-2} + \dots + \alpha_p \Delta Y_{i,t-p} + \Delta X'_{it}\beta + \Delta \varepsilon_{it}. \quad (17.87)$$

This eliminates the individual effect u_i . The challenge is that first-differencing induces correlation between $\Delta Y_{i,t-1}$ and $\Delta \varepsilon_{it}$:

$$\mathbb{E}[\Delta Y_{i,t-1} \Delta \varepsilon_{it}] = \mathbb{E}[(Y_{i,t-1} - Y_{i,t-2})(\varepsilon_{it} - \varepsilon_{i,t-1})] = -\sigma_\varepsilon^2.$$

The other regressors are not correlated with $\Delta \varepsilon_{it}$. For $s > 1$, $\mathbb{E}[\Delta Y_{i,t-s} \Delta \varepsilon_{it}] = 0$, and when X_{it} is strictly exogenous $\mathbb{E}[\Delta X_{it} \Delta \varepsilon_{it}] = 0$.

The correlation between $\Delta Y_{i,t-1}$ and $\Delta \varepsilon_{it}$ is endogeneity. One solution to endogeneity is to use an instrument. Anderson-Hsiao pointed out that $Y_{i,t-2}$ is a valid instrument because it is correlated with $\Delta Y_{i,t-1}$ yet uncorrelated with $\Delta \varepsilon_{it}$.

$$\mathbb{E}[Y_{i,t-2} \Delta \varepsilon_{it}] = \mathbb{E}[Y_{i,t-2} \varepsilon_{it}] - \mathbb{E}[Y_{i,t-2} \varepsilon_{i,t-1}] = 0. \quad (17.88)$$

Using similar reasoning, other approaches use sequential exogeneity to circumvent FE methods altogether rather than to save their consistency. For example, Blundell and Bond (1998) start from the original specification:

$$y_{it} = x'_{it}\beta + \alpha_i + u_{it},$$

where correlation between α_i and x_{it} is suspected to be due to $y_{i,t-1}$, contained in x_{it} .

Definition 3.3.3 (Blundell and Bond(1998)).

$$\begin{aligned} y_{it} &= \alpha_i + \beta_1 y_{i,t-1} + u_{it} \\ &= \beta_1 y_{i,t-1} + (u_{it} + \alpha_i) \end{aligned}$$

Use $\Delta y_{i,t-1}$ as the IV for $y_{i,t-1}$

The Anderson-Hsiao estimator is IV using $Y_{i,t-2}$ as an instrument for $\Delta Y_{i,t-1}$. Equivalently, this is IV using the instruments $(Y_{i,t-2}, \dots, Y_{i,t-p-1})$ for $(\Delta Y_{i,t-1}, \dots, \Delta Y_{i,t-p})$. The estimator requires $T \geq p + 2$.

To show that this estimator is consistent, for simplicity assume we have a balanced panel with $T = 3$, $p = 1$, and no regressors. In this case the Anderson-Hsiao IV estimator is

$$\hat{\alpha}_{iv} = \left(\sum_{i=1}^N Y_{i1} \Delta Y_{i2} \right)^{-1} \left(\sum_{i=1}^N Y_{i1} \Delta Y_{i3} \right) = \alpha + \left(\sum_{i=1}^N Y_{i1} \Delta Y_{i2} \right)^{-1} \left(\sum_{i=1}^N Y_{i1} \Delta \varepsilon_{i3} \right).$$

Under the assumption that ε_{it} is serially uncorrelated, (17.88) shows that $\mathbb{E}[Y_{i1} \Delta \varepsilon_{i3}] = 0$. In general, $\mathbb{E}[Y_{i1} \Delta Y_{i2}] \neq 0$. As $N \rightarrow \infty$

$$\hat{\alpha}_{iv} \xrightarrow{p} \alpha - \frac{\mathbb{E}[Y_{i1} \Delta \varepsilon_{i3}]}{\mathbb{E}[Y_{i1} \Delta Y_{i2}]} = \alpha.$$

Thus the IV estimator is consistent for α .

The Anderson-Hsiao IV estimator relies on two critical assumptions. First, the validity of the instrument (uncorrelatedness with the equation error) relies on the assumption that the dynamics are correctly specified so that ε_{it} is serially uncorrelated. For example, many applications use an AR(1). If instead the true model is an AR(2) then $Y_{i,t-2}$ is not a valid instrument and the IV estimates will be biased. Second, the relevance of the instrument (correlatedness with the endogenous regressor) requires $\mathbb{E}[Y_{i1} \Delta Y_{i2}] \neq 0$. This turns out to be problematic and is explored further in Section 17.40. These considerations suggest that the validity and accuracy of the estimator are likely to be sensitive to these unknown features.

Figure 3.1: Anderson and Hsiao(1981)

Time Series

4.1 Univariate Time Series

We have a sample $\{w_i\}_{i=1}^n$, with $w_i = (y_i, x_i)'$,

$\{w_{it}\}_{i=1:n, t=1:T}$.

Now, we look at $\{w_t\}_{t=1}^T$, usually written as y_t , is univariate time series data.

In the cross-sectional context, we average over i to get

$$\mathbb{E}[u_i] = \int u_i f_u(u_i) du_i.$$

Under time series data, we also think y_t as a RV. without i.i.d. assumption, we generally have T realizations of different and mutually dependent variables.

$$\begin{aligned}\mathbb{E}[y_t] &= \int y_t f_{y_t}(y_t) dy_t = \mu_t, \\ \mathbb{V}[y_t] &= \mathbb{E}[(y_t - \mu_t)^2] = \gamma_{0,t}, \\ \text{Cov}(y_t, y_{t-h}) &= \mathbb{E}[(y_t - \mu_t)(y_{t-h} - \mu_{t-h})] = \gamma_{h,t}.\end{aligned}$$

Definition 4.1.1 (Weak Stationarity).

y_t is a weakly stationary process if

1. $\mu_t = \mu$ for all t ,
2. $\gamma_{h,t} = \gamma_h$ for all t .

autocovariance function (ACF): $\{\gamma_0, \gamma_1, \dots\}$ autocorrelation function: $\{\rho_0, \rho_1, \dots\}$, where $\rho_h = \frac{\gamma_h}{\gamma_0}$.

Appendix

Recommended Resources

Books

- [1] James H. Stock and Mark W. Watson. *Introduction to Econometrics*. 4th ed. New York: Pearson, 2003
- [2] Jeffrey M. Wooldridge. *Introductory Econometrics: A Modern Approach*. 7th ed. Cengage Learning, 2020
- [3] Bruce E. Hansen. *Econometrics*. Princeton, New Jersey: Princeton University Press, 2022
- [4] Fumio Hayashi. *Econometrics*. Princeton, New Jersey: Princeton University Press, 2000
- [5] Jeffrey M. Wooldridge. *Econometric Analysis of Cross Section and Panel Data*. 2nd ed. Cambridge, Massachusetts: The MIT Press, 2010
- [6] Joshua Chan et al. *Bayesian Econometric Methods*. 2nd ed. Cambridge, United Kingdom: Cambridge University Press, 2019
- [7] Badi H. Baltagi. *Econometric Analysis of Panel Data*. 6th ed. Cham, Switzerland: Springer, 2021
- [8] James D. Hamilton. *Time Series Analysis*. Princeton, New Jersey: Princeton University Press, 1994. ISBN: 9780691042893
- [9] Takeshi Amemiya. *Advanced Econometrics*. Cambridge, MA: Harvard University Press, 1985

Others

- [10] Roger Bowden. “The Theory of Parametric Identification”. In: *Econometrica* 41.6 (1973), pp. 1069–1074. DOI: [10.2307/1914036](https://doi.org/10.2307/1914036)
- [11] Robert I. Jennrich. “Asymptotic Properties of Non-linear Least Squares Estimators”. In: *The Annals of Mathematical Statistics* 40.2 (1969), pp. 633–643. DOI: [10.1214/aoms/1177697731](https://doi.org/10.1214/aoms/1177697731)
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- [15] Abraham Wald. “Note on the Consistency of the Maximum Likelihood Estimate”. In: *The Annals of Mathematical Statistics* 20.4 (1949), pp. 595–601. DOI: [10.1214/aoms/1177729952](https://doi.org/10.1214/aoms/1177729952)
- [16] Halbert White. “Maximum Likelihood Estimation of Misspecified Models”. In: *Econometrica* 50.1 (1982), pp. 1–25. DOI: [10.2307/1912526](https://doi.org/10.2307/1912526)