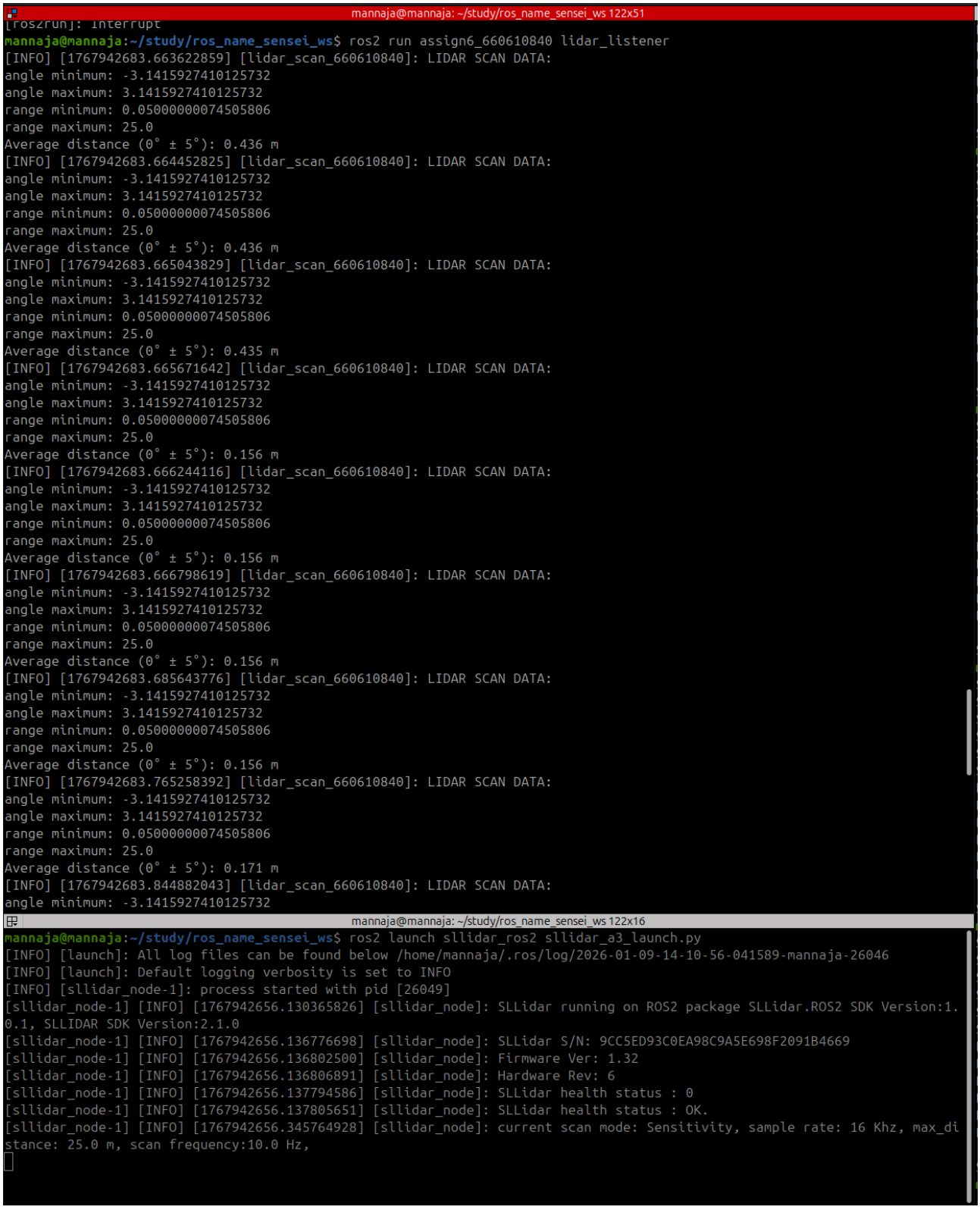
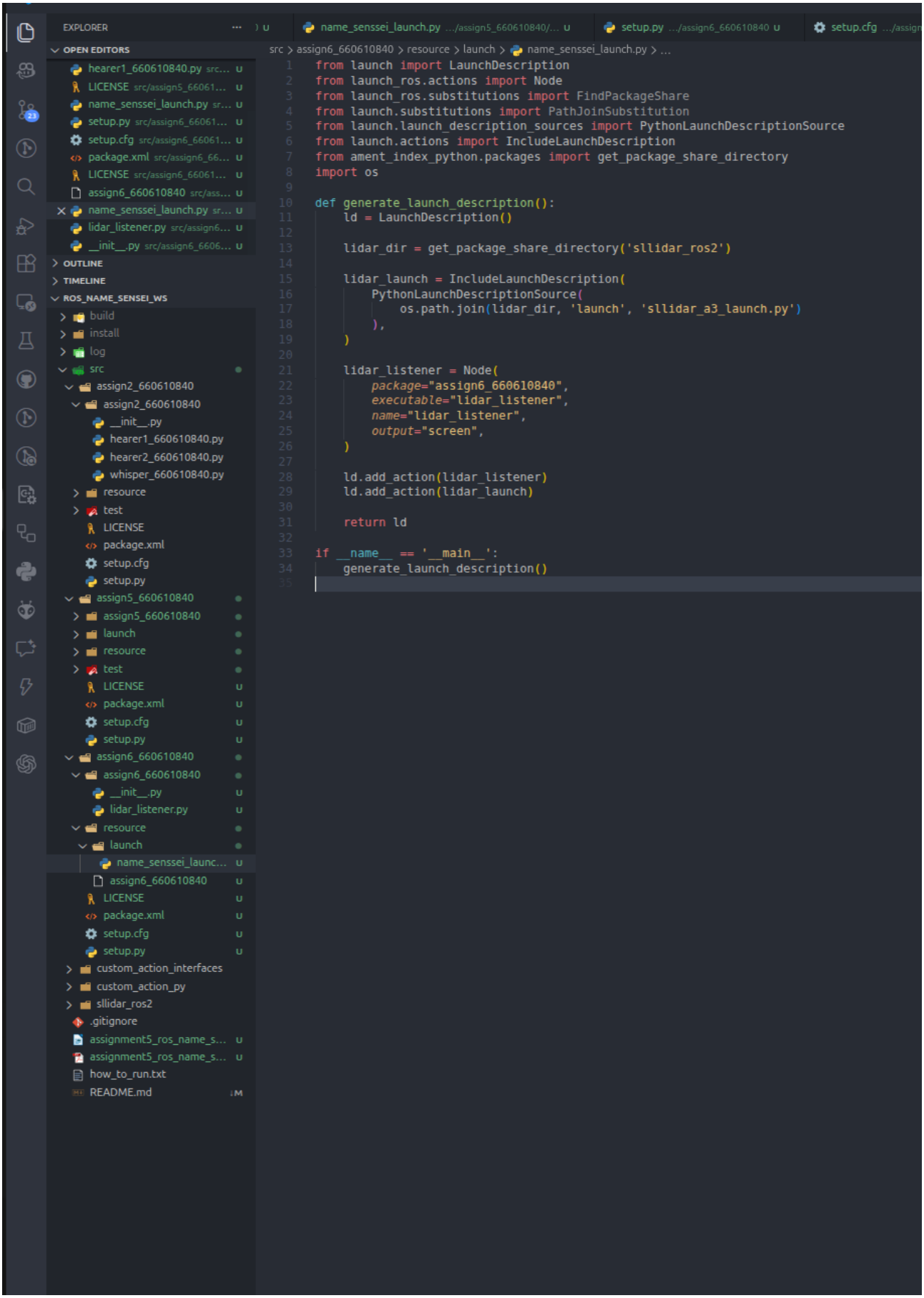
ไฟล์ subscriber node

terminal ตอนรัน เฉพาะ node



launch file


EXPLORER
OPEN EDITORS
name_senssei_launch.py .../assign5_660610840/... U
setup.py .../assign6_660610840 U
setup.cfg .../assign
src > assign6_660610840 > resource > launch > name_senssei_launch.py > ...
1 from launch import LaunchDescription
2 from launch_ros.actions import Node
3 from launch_ros.substitutions import FindPackageShare
4 from launch.substitutions import PathJoinSubstitution
5 from launch.launch_description_sources import PythonLaunchDescriptionSource
6 from launch.actions import IncludeLaunchDescription
7 from ament_index_python.packages import get_package_share_directory
8 import os
9
10 def generate_launch_description():
11 ld = LaunchDescription()
12
13 lidar_dir = get_package_share_directory('sllidar_ros2')
14
15 lidar_launch = IncludeLaunchDescription(
16 PythonLaunchDescriptionSource(
17 os.path.join(lidar_dir, 'launch', 'sllidar_a3_launch.py')
18),
19)
20
21 lidar_listener = Node(
22 package="assign6_660610840",
23 executable="lidar_listener",
24 name="lidar_listener",
25 output="screen",
26)
27
28 ld.add_action(lidar_listener)
29 ld.add_action(lidar_launch)
30
31 return ld
32
33 if __name__ == '__main__':
34 generate_launch_description()
35
OUTLINE
TIMELINE
ROS_NAME_SENSEI_WS
build
install
log
src
assign2_660610840
assign2_660610840
__init__.py
hearer1_660610840.py
hearer2_660610840.py
whisper_660610840.py
resource
test
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resource
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package.xml
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assign6_660610840
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package.xml
setup.cfg
setup.py
custom_action_interfaces
custom_action_py
sllidar_ros2
.gitignore
assignment5_ros_name_s...
assignment5_ros_name_s...
how_to_run.txt
README.md

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