# Sri Chaitanya IIT Academy.,India.

A right Choice for the Real Aspirant

Date: 03-09-2023

ICON Central Office - Madhapur - Hyderabad

Sec: Sr.Super60\_NUCLEUS & STERLING\_BT Paper -1 (Adv-2021-P1-Model

Time: 09.00Am to 12.00Pm RPTA-05 Max. Marks: 180

## **KEY SHEET**

### **PHYSICS**

1	С	2	С	3	A	4	A	5	2	6	1.1 to 1.2
7	3.6 to 3.7	8	78 to 79	9	2.2 to 2.3	10	2.7 to 2.8	11	ABCD	12	ABD
13	ABCD	14	CD	15	ВС	16	BD	17	7	18	4
19	9										

### **CHEMISTRY**

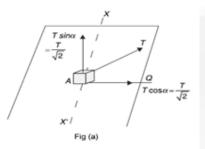
20	C	21	В	22	В	23	D	24	98	25	15
26	22	27	0	28	5	29	4	30	ABD	31	AB
32	ACD	33	BD	34	BD	35	A	36	4	37	1
38	4	a cons									

### **MATHEMATICS**

39	С	40	A	41	A	42	В	43	1.77	44	0.88 to 0.89
45	0.48	46	0	47	0.82	48	1.45 to 1.46	49	BCD	50	ABD
51	ACD	52	BCD	53	ABCD	54	ABCD	55	9	56	1
57	4										

# SOLUTIONS PHYSICS

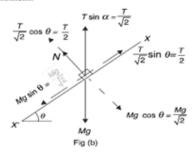
1. Fig (a) shows component of tension (acting A) along horizontal and vertical. Fig. (b) Shows forces along the line of greatest slope (XX') and perpendicular to the incline. In equilibrium T = mg [considering block B] ----- (1)



$$N = \frac{mg}{\sqrt{2}} - \frac{T}{2} = Mg \left\lceil \frac{\sqrt{2} - 1}{2} \right\rceil$$

.....(2)

Forgot about the friction for a moment

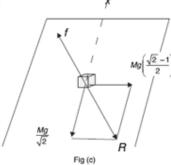


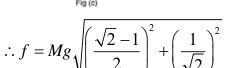
Unbalanced force along XX'=

$$N = \frac{mg}{\sqrt{2}} - \frac{T}{2} = Mg \left[ \frac{\sqrt{2} - 1}{2} \right] \qquad \dots (3)$$

And there is a force along  $AQ = \frac{T}{\sqrt{2}} = \frac{mg}{\sqrt{2}}$  ---- (4)

The friction will balance the resultant of the force given by (3) and (4) The resultant has been shown in fig. (C)

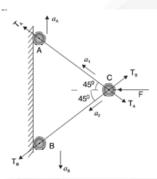




$$= \frac{\sqrt{5 - 2\sqrt{2}}}{2} Mg \ f \le \mu N$$

$$= \frac{\sqrt{5 - 2\sqrt{2}}}{2} Mg \le \mu \left(\frac{\sqrt{2} - 1}{2}\right) mg$$

$$\Rightarrow \frac{\sqrt{5 - 2\sqrt{2}}}{\sqrt{2} - 1} \le \mu$$



Component of acceleration of C can be assumed along the two roads (the rods are.....)as  $a_1$  and  $a_2$  since rods are rigid and  $a_1 = \frac{a_A}{\sqrt{2}}$   $a_2 = \frac{a_B}{\sqrt{2}}$ 

For 
$$A \frac{T_A}{\sqrt{2}} = ma_A$$
....(1)

For 
$$B \frac{T_B}{\sqrt{2}} = ma_B \dots (2)$$

For 
$$C \frac{F}{\sqrt{2}} - T_A = ma_1 \dots (3)$$

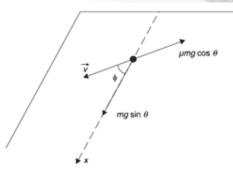
And 
$$\frac{F}{\sqrt{2}} - T_B = ma_2 \dots (4)$$

Using (2) and (4)

$$\frac{F}{\sqrt{2}} - 2\sqrt{2}ma_B = ma_2 \frac{F}{\sqrt{2}} - 2\sqrt{2}ma_B = m = \frac{a_B}{\sqrt{2}} \left( \because a_2 = \frac{a_B}{\sqrt{2}} \right)$$

$$\therefore \frac{F}{\sqrt{2}} = ma_B \left( \frac{1}{\sqrt{2}} + 2\sqrt{2} \right) \qquad \frac{F}{5m} = a_B$$

3. Normal reaction on the particle is always  $N = mg \cos \theta$ 



Friction force on the particle is  $f = \mu mg \cos \theta$  and is always opposite of instantaneous velocity. Another force on the particle in the plane of the incline is  $mg \sin \theta$  which is always directed along x direction. Force on the particle in tangential direction (i.e., in direction of its velocity) is

$$F_{t} = mg\sin\theta.\cos\phi - \mu mg\cos\theta$$

Acceleration in tangential direction is

$$a_t = g \sin \theta (\cos \phi - 1) [\because \mu = \tan \theta] \dots (a)$$

Similarly, acceleration of disc along x-direction is

$$a_x = g\sin\theta - (\mu g\cos\theta)\cos\phi$$

$$= g\sin\theta (1-\cos\phi).....(b)$$

$$\therefore a_t + a_x = 0$$
 [Adding (a) and (b)]

Integrating, we get

$$v + v_r = c$$
 [c is constant]

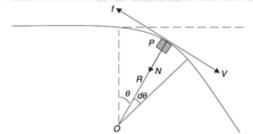
But 
$$v_x = v \cos \phi$$
  $\therefore v + v \cos \phi = c$ 

Initially 
$$\phi = \frac{\pi}{2}$$
;  $v = v_0$ 

$$\therefore c = v_0$$

$$\therefore v = \frac{v_0}{1 + \cos \phi}$$

4. Consider the object at point P on the curve. Let its velocity at this point be V making an angle  $\theta$  with the original direction. Let the centre curvature of the path at this point be O and the radius of curvature be R.



The normal force is  $N = \frac{mv^2}{R}$ 

Kinetic friction force on the object is  $f = \mu N = \frac{\mu m v^2}{R}$  work done by the friction in small angular displacement  $d\theta$  of the block is  $dW_f = -f(Rd\theta) = -\mu m v^2 d\theta$  from work energy theorem, work done by the friction is equal to change in KE of the object

$$K = \frac{1}{2}mv^2 dK = mv dv$$

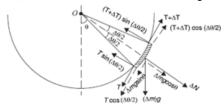
$$\therefore mvdv = -\mu mv^2 d\theta \Rightarrow \frac{dv}{v} = -\mu d\theta \Rightarrow \int_{u}^{v} \frac{dv}{v} = -\mu \int_{0}^{\theta_0} d\theta$$

$$\Rightarrow \ln v - \ln u = -\mu \theta_0 \Rightarrow \ln \left(\frac{v}{u}\right) = -\mu \theta_0 \Rightarrow \frac{v}{u} = e^{-\mu \theta_0} \Rightarrow v = ue^{-\mu \theta_0}$$

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Answer does not shape of the curve.

5. Consider an element of the rope having angular width  $\Delta\theta$ .



Length of the element =  $R\Delta\theta$ 

Mass of element =  $\lambda R \Delta \theta$ 

Tension at lower end of the element =T

For tangential equilibrium of the element

$$(T + \Delta T)\cos\left(\frac{\Delta\theta}{2}\right) - T\cos\left(\frac{\Delta\theta}{2}\right) = \pi R\Delta\theta \cdot g\sin\theta$$

For small angle 
$$\Delta \theta$$
,  $\cos \left( \frac{\Delta \theta}{2} \right) = 1$ .  $T + \Delta T - T = \lambda Rg \Delta \theta \sin \theta$ 

$$\Delta T = \lambda Rg.\Delta\theta.\sin\theta$$
 For  $\Delta\theta \to 0$   $dT = \lambda Rg\sin\theta d\theta$  .....(1)

For equilibrium in radial direction

$$\Delta N + \lambda Rg \Delta \theta \cos \theta = T \sin \left(\frac{\Delta \theta}{2}\right) + \left(T + \Delta T\right) \sin \left(\frac{\Delta \theta}{2}\right)$$

$$\Delta N = T \frac{\Delta \theta}{2} + (T + \Delta T) \frac{\Delta \theta}{2} - \lambda Rg \Delta \theta \cdot \cos \theta$$

$$\left[ \because for \ small \Delta \theta, \sin \left( \frac{\Delta \theta}{2} \right) \rightarrow \frac{\Delta \theta}{2} \right]$$

 $\Delta T \Delta \theta = 0$  [Product very small quantities]

$$\Delta N = T\Delta\theta = -\lambda Rg\Delta\theta \cdot \cos\theta$$

 $\Delta N \ge 0$  At all points  $\Rightarrow T \ge \lambda Rg \cos \theta$  At all points

At bottom (i.e., at  $\theta = 0^{\circ}$ )

$$T_1 \ge \lambda Rg$$

From equation (1)

$$dT = \lambda Rg \sin\theta d\theta$$

$$\therefore \int_{T_1}^{T_0} dT = \lambda Rg \int_{0}^{\pi/2} \sin\theta d\theta$$

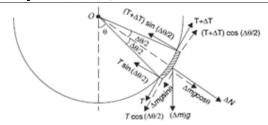
$$T_0 - T_1 = \lambda Rg$$

$$T_0 = T_1 + \lambda Rg$$

$$\therefore T_0 \ge 2\lambda Rg \left[ u \sin g \left( 2 \right) \right]$$

6. Consider an element of the rope having angular width  $\Delta \theta$ .

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For small angle  $\Delta \theta$ ,  $\cos \left( \frac{\Delta \theta}{2} \right) = 1$ 

$$T + \Delta T - T = \lambda Rg \Delta \theta \sin \theta$$

$$\Delta T = \lambda Rg. \Delta \theta. \sin \theta$$

For 
$$\Delta\theta \rightarrow 0$$

$$dT = \lambda Rg \sin \theta d\theta$$

For equilibrium in radial direction

$$\Delta N + \lambda R g \Delta \theta \cos \theta = T \sin \left(\frac{\Delta \theta}{2}\right) + \left(T + \Delta T\right) \sin \left(\frac{\Delta \theta}{2}\right)$$

$$\Delta N = T \frac{\Delta \theta}{2} + (T + \Delta T) \frac{\Delta \theta}{2} - \lambda Rg \Delta \theta . \cos \theta$$

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$$\Delta N = T\Delta\theta = -\lambda Rg\Delta\theta \cdot \cos\theta$$

$$\Delta N \ge 0$$
 At all points

$$\Rightarrow T \ge \lambda Rg \cos \theta$$
 At all points

At bottom (i.e., at  $\theta = 0^{\circ}$ )

$$T_1 \ge \lambda Rg$$
 ......(2)

From equation (1)

$$dT = \lambda Rg \sin\theta d\theta$$

$$\therefore \int_{T_0}^{T_0} dT = \lambda Rg \int_{0}^{\pi/2} \sin\theta d\theta$$

$$T_0 - T_1 = \lambda Rg$$

$$T_0 = T_1 + \lambda Rg$$

$$\therefore T_0 \ge 2\lambda Rg \left[ u \sin g \left( 2 \right) \right]$$

Maximum chance of loosing contact is at lowest point where Tension is  $\lambda gR$ 

$$dT = \lambda Rg \sin\theta \ d\theta$$
, (:where  $\lambda = \frac{dm}{dx}$ )

$$T - T_{lowest} = \lambda g R \left[ 1 - \cos 30^{\circ} \right]$$
$$= \lambda g R \left[ 1 - \frac{\sqrt{3}}{2} \right]$$

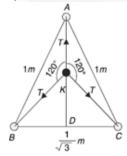
$$T = \lambda gR + 0.1339 \lambda gR$$

 $1.1339 \lambda gR$ 

7. If m is mass of each particle, tension in each string is T = mg.

For equilibrium of the knot it is necessary that the three strings from 120° angle with each other. The situation has been shows in figure.

A, B, and C are holes and K is the knot.



$$KD = \frac{1}{2\sqrt{3}} \tan 30^\circ = \frac{1}{6} m$$

$$AD = \sqrt{1^2 - \left(\frac{1}{2\sqrt{3}}\right)^2} = \sqrt{\frac{11}{12}} = \frac{1}{2}\sqrt{\frac{11}{3}}m$$

$$\therefore AK = \frac{1}{2}\sqrt{\frac{11}{3}} - \frac{1}{6}$$

And 
$$BK = CK = \frac{1}{2\sqrt{3}\sin 60^{\circ}} = \frac{1}{3}m$$

:. Length of string on the table is

∴ Length of string on the table is
$$BK + CK + AK = \frac{1}{3} + \frac{1}{2}\sqrt{\frac{11}{3}} - \frac{1}{6} + \frac{1}{3} = \frac{1}{2}\left[1 + \sqrt{\frac{11}{3}}\right]m$$

$$PE = -mgh$$

$$= 3 \times 10(9 - (AK + BK + CK)_{min})$$

$$= -255\left(1 - \sqrt{\frac{11}{867}}\right)$$

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$$=3\times10(9-(AK+BK+CK)_{\min})$$

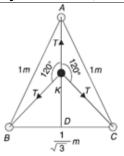
$$= -255 \left( 1 - \sqrt{\frac{11}{867}} \right)$$

$$s / r = 78.8$$

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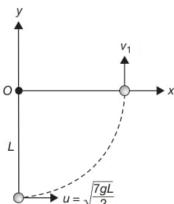
$$s/r = 8.87$$

$$W_{AtoC} = KE_C - KE_A$$

$$(mg)(2L) - \mu mg(8L) - 2\mu mg(4L) = \frac{1}{2}mV_c^2$$

$$2mgL - 16\mu mgL = \frac{1}{2}mv_c^2 V_C = \sqrt{\frac{7}{2}}gL$$
By law of conservation of energy, we get

By law of conservation of energy, we get



$$\frac{1}{2}m\frac{7gL}{2} = mgL + \frac{1}{2}mv_1^2 \Rightarrow 7gL = 4gL + 2v_1^2$$

$$\Rightarrow v_1^2 = \frac{3}{2}gL \stackrel{\Delta\vec{v}}{=} \vec{v_1} - \vec{u}$$

$$\Rightarrow \Delta\vec{v} = \left(\sqrt{\frac{3}{2}gL}\right)\hat{j} - \left(\sqrt{\frac{7}{2}gL}\right)\hat{i}$$

$$\Rightarrow |\Delta\vec{v}| = \sqrt{\frac{3}{2}gL + \frac{2gL}{2}} \Rightarrow |\Delta\vec{v}| = \sqrt{5gL}$$

$$v_1^2 = gL\sin(30^\circ) - \frac{gL}{2}$$

10. 
$$v^{2} = gL\sin(30^{\circ}) = \frac{gL}{2}$$

$$\Rightarrow \vec{v} = -v\sin\theta \hat{i} + v\cos\theta \hat{j} \quad \text{where } \theta = 30^{\circ}$$

$$\Rightarrow \vec{v} = \sqrt{\frac{gL}{8}} \left( -1\hat{i} + \sqrt{3}\hat{j} \right)$$

$$p + q = 1.73 + 1 = 2.73$$

11. Since the balloon is ascending at a constant rate.

So, 
$$v_0 = \frac{dy}{dt} \Rightarrow dy = v_0 dt \Rightarrow y = v_0 t$$

Also, we have

$$v_x = \frac{dx}{dt} = ky$$

$$\Rightarrow dx = kydt = kv_0tdt$$

$${\because y = v_0 t}$$

Integrating, we get

$$x = kv_0 \left(\frac{t^2}{2}\right)$$

$$\Rightarrow x = k \frac{v_0}{2} \left( \frac{y}{v_0} \right)^2$$

$$\Rightarrow x = \frac{1}{2} \frac{ky^2}{v_0}$$

A) For finding the tangential and normal accelerations, we require an expression for the velocity as a function of height y. so we have

$$v_{y} = v_{0}$$
 and  $v_{x} = ky$ 

$$\Rightarrow v = \sqrt{v_x^2 + v_y^2} = \sqrt{v_0^2 + k^2 y^2}$$

Therefore tangential acceleration,

$$a_{T} = \frac{dv}{dt} = \frac{k^{2}y}{\sqrt{v_{0}^{2} + k^{2}y^{2}}} \frac{dy}{dt} = \frac{k^{2}yv_{0}}{\sqrt{v_{0}^{2} + k^{2}y^{2}}}$$

$$\Rightarrow a = \frac{dv_x}{dt} = k\frac{dy}{dt} = kv_0$$

$$\left\{ \because \frac{dv_y}{dt} = 0 \right\}$$

B) To find the normal acceleration, since we know that

$$a^2 = a_N^2 + a_T^2$$

$$\Rightarrow a_N = \sqrt{a^2 - a_T^2} = \frac{kv_0}{\sqrt{1 + \left(\frac{ky}{v_0}\right)^2}}$$

C) 
$$R_C = \frac{v^2}{a_c} = \frac{v_0}{k} \left[ 1 + \left( \frac{ky}{v_0} \right)^2 \right]^{3/2}$$

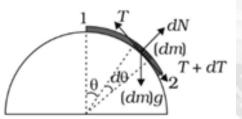
D) Curvature  $\alpha \frac{1}{R_c}$ 

As  $y \uparrow$  increases,  $R_c \uparrow$ , Curvature  $\downarrow$ 

12. I) Initial tangential acceleration of all elements will be same for the element of mass dm:

$$(T+dT)+(dm)g\sin\theta-T=(dm)a_t \Rightarrow dT+\left(\frac{m}{l}rd\theta\right)g\sin\theta=\frac{m}{l}rd\theta a_t$$

Integrating between 1 and 2



$$\Rightarrow \int_{T_1}^{T_2} dT + \frac{m}{l} rg \int_{0}^{l/r} \sin\theta d\theta = \frac{m}{l} ra_t \int_{0}^{l/r} d\theta$$

$$\Rightarrow (T_2 - T_1) + \frac{m}{l} rg \left( 1 - \cos \frac{l}{r} \right) = \frac{m}{l} ra_t \frac{l}{r}$$

But at free ends tension is zero

$$T_1 = T_2 = 0$$

$$\therefore a_t = \frac{rg}{l} \left( 1 - \cos \frac{l}{r} \right)$$

II) Integrating between 1 and  $\theta$ 

$$(T-O) + \frac{m}{l}rg(1-\cos\theta) = \frac{mr}{l}\left[\frac{rg}{l}\left(1-\cos\frac{l}{r}\right)\right]\theta$$

Differentiating w.r.t  $\theta$ :

$$\frac{dT}{d\theta} + O + \frac{mr}{l} \left[ \frac{rg}{l} \left( 1 - \cos \frac{l}{r} \right) \right]$$

For 
$$T_{\text{max'}} \frac{dT}{d\theta} = o$$

$$\Rightarrow \sin \theta = \frac{r}{l} \left( 1 - \cos \frac{l}{r} \right)$$

$$\alpha = 90 - \theta \Rightarrow \alpha \cos^{-1} \left( \frac{r}{\ell} \left( 1 - \frac{\cos \ell}{r} \right) \right)$$

D) To prevent slipping

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$$F_{friction} = F_{weight}$$

$$\mu\left(\frac{m}{l}\right)g(r)\sin\alpha = \left(\frac{m}{l}\right)(r)(1-\cos\alpha)g$$

$$\mu = \frac{1 - \cos \alpha}{\sin \alpha} \qquad \left[\alpha = \frac{l}{r}\right]$$

$$=\tan\left(\frac{\alpha}{2}\right)$$

- 13. Conceptual
- 14. A) Only vertical force present in the system. So vertical momentum does not change.
  - B) Also horizontal velocity will remain same.

Let's work from CM frame, in this frame disk moves in circular path. For circular motion

$$mg\cos\theta - ma_0\sin\theta - N = \frac{mV_1^2}{R}$$
....(i)

 $V_1$  is velocity of disk relative to the hemisphere

According to conservation of linear momentum  $m(V_1 \cos \theta - V_2) - mV_2$ 

$$\Rightarrow V_2 = \frac{V_1 \cos \theta}{2}$$
 .....(ii)

WE theorem (for whole system)

$$mgR(1-\cos\theta) = \frac{1}{2}mV_2^2 + \frac{1}{2}m\{(V_1\cos-V_2)^2 + V_1^2\sin^2\theta\}$$
 .....(iii)

At the time of breakoff  $N \to 0 \Rightarrow a_0 \to 0$  (Because  $N \sin \theta = ma_0$ )

So from (i)

$$V_1^2 = gR\cos\theta$$
.....(iv)

Now from (i) and (iii)

$$2gR(1-\cos\theta) = \frac{(V_1\cos\theta)^2}{4} + \frac{(V_1\cos\theta)^2}{4} + V_1^2\sin^2\theta$$

$$= \frac{V_1^2 \cos^2 \theta}{2} + V_1^2 \left(1 - \cos^2 \theta\right)$$

$$2gR(1-\cos\theta) = V_1^2 - V_1^2 \frac{\cos^2\theta}{2}$$

From (iv),

$$2gR(1-\cos\theta) = gR\cos\theta - \frac{gR\cos\theta.\cos^2\theta}{2}$$

$$2 - 2\cos\theta = \cos\theta - \frac{\cos^3\theta}{2}; 2(2 - 2\cos\theta) = 2\cos\theta - \cos 5\theta$$

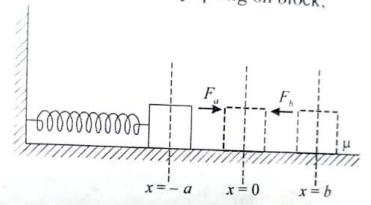
$$\Rightarrow \cos^3 \theta - 6\cos \theta + 4 = 0 \Rightarrow (\cos \theta = \sqrt{3} - 1)$$

$$(\cos\theta - 2)(\cos^2\theta + 2\cos\theta - 2) = 0$$

$$\cos\theta = \frac{-2 \pm \sqrt{4+8}}{2}$$

$$=-1\pm\sqrt{3}$$

- D) Disc will be accelerating only not bowl.
- 15. Work done by spring on block



$$w_s = \frac{1}{2}ka^2 - \frac{1}{2}kb^2 = \frac{1}{2}k(a^2 - b^2)$$

By work energy theorem,

$$K_i + w = K_f$$

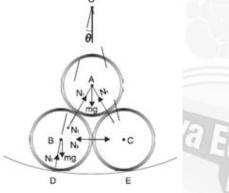
$$0 + \frac{1}{2}ka^2 - \mu mg(a+b) - \frac{1}{2}kb^2 = 0$$

$$\mu mg\left(a+b\right) = \frac{1}{2}k\left(a^2 - b^2\right)$$

$$\mu = \frac{k(a-b)}{2mg}$$

16. Force applied by D is more but velocity of string in his hands is less in the same proportion. Hence the power is same.

17.



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O =Centre of larger cylinder.

DO will pass through centre of lower cylinder (B)

 $N_1$  = Contact force between A and B (and A and C)

 $N_2$  = Contact force between B and the large cylinder

 $N_3$  = Contact force between B and C.

For the vertical equilibrium of A

$$2N_1 \cos 30^\circ = mg \Rightarrow \sqrt{3}N_1 = mg \dots (1)$$

#### For horizontal equilibrium of B

$$N_1 \sin 30^\circ = N_2 \sin \theta$$

$$\frac{mg}{2\sqrt{3}} = N_2 \sin \theta \qquad \dots (2)$$

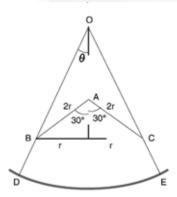
For vertical equilibrium of whole system

$$2N_2 \cos \theta = 3mg$$

$$\therefore N_2 \cos \theta = \frac{3}{2} mg \qquad \dots (3)$$

$$(2) \div (3)$$

$$\tan \theta = \frac{1}{3\sqrt{3}} \Rightarrow \frac{r}{\sqrt{(R-r)^2 - r^2}} = \frac{1}{3\sqrt{3}}$$



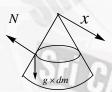
$$\Rightarrow 27r^2 = (R - r)^2 - r^2$$

$$\Rightarrow (R-r)^2 = 28r^2$$

$$R - r = 2\sqrt{7}r$$

$$\therefore R = r\left(1 + 2\sqrt{7}\right)$$

18.



Consider the potential energy of the band as a function of R. To be in equilibrium, the band must be at a position of minimum potential energy. Let the elastic potential energy

be  $U_i = \frac{1}{2}k(2\pi R - 2\pi R)^2$  and the gravitational potential energy measured with respect to

the vertex of the code  $U_i = -mg(R-r)\cot\theta$ 

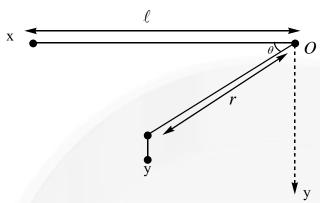
The total potential energy is  $U = 2k\pi^2(R-r)^2 - mg(R-r)\cot\theta$ 

At the minimum position,

$$\frac{dU}{dR} = 4\pi^2 k (R - r) - mg \cot \theta = 0$$

Which has solution

$$R = r + \frac{mg}{4\pi^2 k} \cot \theta$$



Let the second nail be located as a distance r from the first nail and angle  $\theta$  below horizontal as shown. Now speed of the bob at its lowest position can be found using conservation of energy.

$$\frac{1}{2}mv^{2} = mg\left[r\sin\theta + \ell - r\right]$$

$$\Rightarrow v^{2} = 2g\left(r\sin\theta + \ell - r\right) \qquad \dots (i)$$

The particle will complete circle about the second nail if  $v^2 = 5g(\ell - r)$  .....(ii)

From (i) and (ii)

$$2(r\sin\theta + \ell - r) = 5(\ell - r)$$

$$\Rightarrow 3r + 2r \sin \theta = 3\ell$$

.....(iii)

onal Institutions

Now coordinates of the nail are

ri Chaitanya Edu

$$x = r\cos\theta, y = r\sin\theta$$

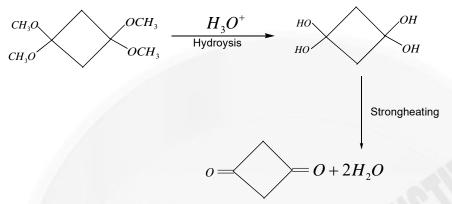
Using these in (iii), we get

$$3\sqrt{x^2 + y^2} + 2y = 3\ell$$

$$Or 9(x^2 + y^2) = (3\ell - 2y)^2$$

### **CHEMISTRY**

- **20. Reason-I:** Intermolecular H-bonding and intramolecular H-bonding **Reason-II:** Molecular weight
- 21.



- 22. Tertiary Carbocation is more stable in option (B)
- 23.



N- atom have Sp<sup>3</sup> hybridization So, %S character is less and Lone Pairs are localized

24.

$$OH \longrightarrow_{H^+} OH \oplus_{CH_2 - NH_3}$$

$$-NH_3$$

$$-NH_3$$

$$OH \oplus_{CH_2 - NH_3}$$

$$O$$

25. 
$$CH_3 - CH_2 - NH_2 \xrightarrow{HNO_2} CH_3 - CH_2 - CH_2 - OH$$

now, 
$$59gm. \xrightarrow{\text{will give}} 60gm$$

So, 
$$14.75 gm. \xrightarrow{\text{will give}} \frac{14.75 \times 60}{59} = 15 gm$$

$$CH_{3} - CH = C - CH_{2} - CH_{3} \xrightarrow{HBr \atop H_{2}O_{2}} (CH_{3} - CH_{2})_{2} - CH - CH_{3}(P)$$

NO.of  $\sigma$  -bonds=22 in product (P)

27.

$$CH_{3} - CH = C - CH_{2}CH_{3} \xrightarrow{Hg(ACO)_{2}/H_{2}0} (C_{2}H_{5})_{3}C - OH$$

$$(Y)$$

Oximercuration demerculation gives Markovnikov's product without any rearrangement.

28.

29.

$$OH$$

$$COOH$$

$$Soda lime$$

$$-CO_{2}$$

$$N_{2}^{*}Cl^{-}$$

$$BDC(Salt)$$

$$(B)$$

There are 4-lone pairs

30. Conceptual

 $\overline{31. \quad CH_3CH_2OH \xrightarrow{(CH_3CO)_2O} CH_3COOH + CH_3COOC_2H_5}$ 

32.

$$CH_{3}CH - CH_{2} \xrightarrow{CH_{3}-C=C^{-}} CH_{3} - CH - CH_{2} - C \equiv C - CH_{3}$$

$$O$$

$$(X)$$

$$CH_{3}I$$

$$CH_{3} - CH - CH_{2} - C \equiv C - CH_{3}$$

$$O - CH_{3}$$

$$O - CH_{3}$$

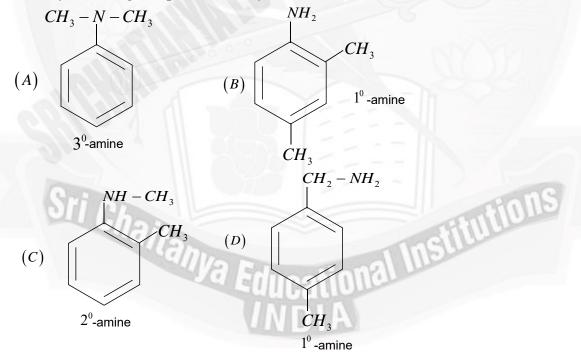
$$CH_{3} - CH - CH_{2} - C \equiv C - CH_{3}$$

$$O - CH_{3}$$

$$O - CH_{3}$$

$$(Z)$$

- 33. Phenol gives violet colored complex with neutral *Fecl*<sub>3</sub> and benzoic acid gives brisk effervescence with *NaHCO*<sub>3</sub>
- 34. Primary amines gives positive carbylamines test



35.

$$H_3C$$

$$\begin{array}{c}
 & \vdots O_1 \\
 & \vdots O_2 \\
 & \vdots O_3 \\
 & \vdots O_4 \\
 & \vdots O_4$$

Br (2)

$$HNO_3$$
 $H_2SO_4$ 
 $OCH_3$ 
 $O$ 

37. More stable carbocation is possible on C-1

38.

$$CH_3 CH_3$$

$$CH_4 CH_3$$

$$CH_5$$

### **MATHEMATICS**

39. 
$$\left(\frac{\{x\}}{1+\{x\}}\right) = \frac{y}{1+y} \le \frac{\pi}{4}$$

Angle of 
$$\tan\left(\frac{\{x\}}{1+\{x\}}\right)$$
 is less than  $\frac{\pi}{4}$ .

$$\left[\tan\left(\frac{\{x\}}{1+\{x\}}\right)\right] = 0$$

$$\left\{\frac{x}{4}\right\} = \frac{x}{4}$$
  $\int_0^4 \frac{x}{4} dx = \left|\frac{x^2}{8}\right|_0^4 = 2$ 

40. 
$$(x^4 + 8x^3 + 18x^2 + 16x + 5) = (x+1)^4 + 4(x+1)^3$$

41. 
$$= \int_{-3/2}^{-1/2} ((x+1)^5 - 2x^2 - 4x - 1) dx$$

$$= \int_{-3/2}^{-1/2} ((x+1)^5 - 2(x+1)^2 + 1) dx = \int_{-1/2}^{1/2} (y^5 - 2y^2 + 1) dy$$

$$=0-\frac{4}{3}\times\frac{1}{8}+1=\frac{5}{6}$$

42. 
$$\int_{2}^{12} \frac{1 + \sqrt{1 + 4x}}{2x} dx$$

$$\int_{2}^{12} \frac{1}{2x} dx + \int_{2}^{12} \frac{\sqrt{1+4x}}{2x} dx$$

$$\frac{1}{2} \ln x \Big|_{2}^{12} + \int_{3}^{7} \frac{x^{2}}{x^{2} - 1} dx$$

$$\frac{1}{2}\ln 6 + \int_{3}^{7} \frac{x^2}{x^2 - 1} dx$$

43. 
$$I = 2e^4 \int_0^\infty e^{-x^2 - 4/x^2} dx.$$

$$x \mapsto \frac{2}{x}$$

$$I = 2e^4 \int_0^\infty \frac{2}{x^2} e^{-4/x^2 - x^2} dx. \text{ N}$$

$$I = 2e^{4} \int_{0}^{\infty} \frac{2}{x^{2}} e^{-4/x^{2} - x^{2}} dx. \text{ N}$$
Adding these then gives
$$I = e^{4} \int_{0}^{\infty} \left( 1 + \frac{2}{x^{2}} \right) e^{-x^{2} - 4/x^{2}} dx = e^{4} \frac{1}{e^{4}} \int_{0}^{\infty} \left( 1 + \frac{2}{x^{2}} \right) e^{-(x - 2/x)^{2}} dx.$$

$$u = x - \frac{2}{x} \qquad I = \int_{-\infty}^{\infty} e^{-u^{2}} du = \sqrt{\pi} = 1.77$$
Substitute  $x \leftrightarrow \sqrt{n}x \lim_{n \to \infty} \int_{-\infty}^{\sqrt{n}} \left( 1 - \frac{4x^{2}}{x^{2}} + \frac{x^{4}}{x^{2}} \right)^{n} dx$ 

$$u = x - \frac{2}{x}$$
  $I = \int_{-\infty}^{\infty} e^{-u^2} du = \sqrt{\pi} = 1.77$ 

44. Substitute 
$$x \leftrightarrow \sqrt{n}x \lim_{n \to \infty} \int_{-\frac{\sqrt{n}}{2}}^{\frac{\sqrt{n}}{2}} \left(1 - \frac{4x^2}{n} + \frac{x^4}{n^2}\right)^n dx$$

$$=\int_{-\infty}^{\infty}e^{-4x^2}\ dx$$

$$=\frac{1}{2}\int_{-\infty}^{\infty}e^{-x^2}\ dx$$

$$=\int_0^\infty e^{-x^2} dx = 0.88$$

45. 
$$\int_0^1 {207 \choose 7} x^{200} (1-x)^7 dx = \frac{1}{208}$$

$$46. = \frac{1}{2025!} \int_0^{2024} x(x-1)(x-2)....(x-2024) dx$$

$$= \frac{1}{2025!} \int_{2012}^{2012} (x-2012)(x-2011)....(x-1)x$$

$$(x+1)$$
.... $(x+2011)(x+2012)dx$ 

$$=\frac{1}{2025!}\int_{-2}^{2}x(x^2-1^2)(x^2-2^2)....(x^2-2012^2)dx$$

$$=0$$

47. 
$$\sum_{1}^{\infty} \int_{1/(n+1)}^{1/n} nx dx = \sum_{1}^{\infty} \frac{n}{2} \left( \frac{1}{n^2} - \frac{1}{(n+1)^2} \right) = \frac{1}{2} \sum_{1}^{\infty} \left( \frac{1}{n} - \frac{n+1-1}{(n+1)^2} \right)$$
$$= \frac{1}{2} \sum_{1}^{\infty} \left( \frac{1}{n} - \frac{1}{n+1} + \frac{1}{(n+1)^2} \right) = \frac{1}{2} (1 + \sum_{1}^{\infty} \frac{1}{n^2}) = \frac{\pi^2}{12} = 0.82$$

48. 
$$\int_0^1 \frac{[(x+1) + x^2 - x^2] \log(x)}{x^3 - 1} dx = \int_0^1 \frac{\log x}{x - 1} dx - \int_0^1 \frac{x^2 \log x}{x^3 - 1} dx.$$

$$\int_0^1 \frac{x^2 \log x}{x^3 - 1} dx = \frac{1}{3} \int_0^1 \frac{\log u^{1/3}}{u - 1} du = \frac{1}{9} \int_0^1 \frac{\log x}{x - 1} dx.$$

$$I_0 = \frac{8}{9} \int_0^1 \frac{\log x}{x - 1} dx. \ I_0 = (-1) \frac{8}{9} \int_0^1 \sum_{n=0}^\infty x^n \cdot \log x dx = (-1) \frac{8}{9} \sum_{n=0}^\infty \int_0^1 x^n \cdot \log x dx.$$

$$I_0 = \frac{8}{9} \sum_{n=0}^{\infty} \frac{1}{(1+n)^2} = \frac{4\pi^2}{27} = 1.45$$

$$\int_0^{\frac{\pi}{2}} x \tan 2x \ln(\tan x) dx, \ x \mapsto \frac{\pi}{2} - x$$

$$I = \frac{\pi}{4} \int_{0}^{\frac{\pi}{2}} \tan 2x \ln(\tan x) dx, \quad \tan x = \frac{\sin 2x}{1 + \cos 2x}$$

$$I = \frac{\pi}{4} \int_{0}^{\frac{\pi}{2}} \left[ \frac{\sin 2x}{\cos 2x} \ln(\sin 2x) - \frac{\sin 2x}{\cos 2x} \ln(1 + \cos 2x) \right] dx$$

$$J \stackrel{x \to \pi - x}{=} -J \Longrightarrow J = 0, \qquad I = -\frac{\pi}{8} K.$$

$$K = \int_{-1}^{y=\cos x} \frac{\ln(1+y)}{y} dy$$

$$J = -J \Rightarrow J = 0, \qquad I = -\frac{n}{8}K.$$

$$K = \int_{-1}^{y=\cos x} \frac{\ln(1+y)}{y} dy$$

$$I = \int_{0}^{\infty} \frac{\arctan(1/x)}{\sqrt{x}(1+x)} dx$$

$$= \frac{1}{2} \int_{0}^{\infty} \frac{\arctan(x) + \arctan(1/x)}{\sqrt{x}(1+x)} dx$$

$$= \frac{1}{2} \int_0^\infty \frac{\arctan(x) + \arctan(1/x)}{\sqrt{x}(1+x)} dx$$

$$= \frac{\pi}{4} \int_0^\infty \frac{dx}{\sqrt{x}(1+x)} = \frac{\pi^2}{4}$$

51. 
$$= \int_0^\infty \frac{x}{x^8 - 1} - \int_0^\infty \frac{1}{x^8 - 1} = \int_0^\infty \frac{1/2}{x^4 - 1} - \int_0^\infty \frac{1}{x^8 - 1}$$

$$= \int_0^\infty \frac{1/2(x^4+1)}{x^8-1} - \int_0^\infty \frac{1}{x^8-1} = \int_0^\infty \frac{1/2(x^4-1)}{x^8-1} = \frac{1}{2} \int_0^\infty \frac{1}{x^4+1} = \frac{\pi}{4\sqrt{2}}$$

$$\int_0^\infty \frac{1}{(1+x^{-2023})(1+x^{-2})} \frac{1}{x^2} dx = \int_0^\infty \frac{x^{2023}}{(1+x^{2023})(1+x^2)} dx$$

$$2I = \int_0^\infty \frac{1}{(1+x^{2023})(1+x^2)} dx + \int_0^\infty \frac{x^{2023}}{(1+x^{2023})(1+x^2)} dx$$

$$= \int_0^\infty \frac{1 + x^{2023}}{(1 + x^{2023})(1 + x^2)} dx = \int_0^\infty \frac{1}{1 + x^2} dx = \frac{\pi}{2} \qquad I = \frac{\pi}{4}$$

$$\int_{1/2}^{2} \log \log \left( x + \frac{1}{x} \right) dx$$

$$= \int_0^{3/2} \log \log \sqrt{x^2 + 4} \, dx = \int_{1/2}^2 \log \log \sqrt{x^2 - x + \frac{17}{4}} \, dx$$

$$\int_{\frac{1}{2}}^{2} \log \left( \frac{\log(x + \frac{1}{x})}{\log(x^2 - x + \frac{17}{4})} \right) dx$$

$$= \int_{1/2}^{2} \left( \log \log \left( x + \frac{1}{x} \right) - \log \log \sqrt{x^2 - x + \frac{17}{4}} - \log 2 \right) dx$$

$$= -\int_{1/2}^{2} \log 2 dx = -\frac{3}{2} \log 2$$

54. 
$$= \int_0^{\pi/6} \sqrt{\tan(\theta) + \sec(\theta)} d\tan(\theta) = \int_0^{\pi/6} \sqrt{\tan(\theta) + \sec(\theta)} \sec^2(\theta) d\theta$$

$$= \frac{1}{\sqrt[4]{3}} - \int_0^{\pi/6} \tan(\theta) \frac{\sec^2(\theta) + \tan(\theta) \sec(\theta)}{2\sqrt{\tan(\theta) + \sec(\theta)}} d\theta$$

$$=\frac{1}{\sqrt[4]{3}}-\frac{1}{2}\int_{0}^{\pi/6}\sqrt{\tan(\theta)+\sec(\theta)}\,\mathrm{d}\sec(\theta)=\frac{1}{2}+\frac{1}{2}\int_{0}^{\pi/6}\sec(\theta)\frac{\sec^{2}(\theta)+\tan(\theta)\sec(\theta)}{2\sqrt{\tan(\theta)+\sec(\theta)}}\mathrm{d}\theta$$

$$= \frac{1}{2} + \frac{1}{4} \int_0^{\pi/6} \sqrt{\tan(\theta) + \sec(\theta)} \sec^2(\theta) d\theta \qquad = \frac{2}{3}$$

55. When plotted on graph we can see that these

nal Institutions create triangles of area 1/2 between any two intervals [n, n+1]

The value of this integral is

$$56. \qquad \lim_{n \to \infty} \int_0^\infty \left( 1 + \frac{t}{n} \right)^{-n} \cdot \cos\left(\frac{t}{n}\right) dt = \int_0^\infty e^{-t} dt = 1$$

57. In each interval [1,2],[2,3],[3,4]

The area is  $\frac{1}{2}$  which means that the answer is  $\frac{8}{2} = 4$