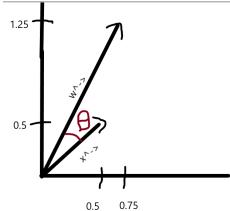
1. 
$$|\vec{w}| = \sqrt{(0.5)^2 + (0.5)^2} = 0.707$$

2. 
$$\vec{x} * \vec{w}^T = x_1 w_1 + x_2 w_2 = (0.5)(0.75) + (0.5)(1.25) = 1$$

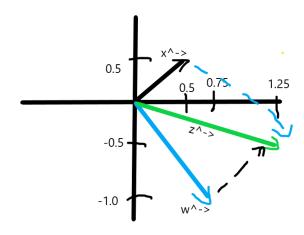
3. 
$$\vec{x} * \vec{w} = x_1 w_1 + x_2 w_2 = (0.5)(0.75) + (0.5)(1.25) = 1$$

4. 
$$\vec{x} \cdot \vec{w} = x_1 w_1 + x_2 w_2 = (0.5)(0.75) + (0.5)(1.25) = 1$$

5. 
$$\vec{x} \cdot \vec{w} = x_1 w_1 + x_2 w_2 = |\vec{x}| * |\vec{w}| * cos(\theta) -> cos(\theta) = (x_1 w_1 + x_2 w_2)/(|\vec{x}| * |\vec{w}|)$$
  
=  $1/(0.707 * \sqrt{0.75^2 + 1.25^2}) = 0.970 -> \theta = cos^{-1}(0.970) = 0.244 \, rad = 14^\circ$ 



6. 
$$\vec{z} = \vec{x} + \vec{w} = [x_1 + w_1, x_2 + w_2] = [0.5 + 0.75, 0.5 - 1] = [1.25, -0.5]$$



- 7. Prediction involves using existing outputs to make an estimate of future outputs. Classification involves identifying existing outputs with a particular category of results.
- 8. Initial weights:  $w_0 = 0$ ,  $w_1 = 0.5$ ,  $w_2 = -0.5$ , Ir = 0.25. Assume  $x_0 = 1$  for all passes. First pass:  $x_1 = 0$ ,  $x_2 = 0$ , OR = 0  $y = g(w_0x_0 + w_1x_1 + w_2x_2) = g[(0)(1) + (0.5)(1) + (-0.5)(1)] = 0 \rightarrow correct$ Due to being correct, no adjustments to weights

```
Second pass: x_1 = 0, x_2 = 1, OR = 1
        y = g(w_0x_0 + w_1x_1 + w_2x_2) = g[(0)(1) + (0.5)(0) + (-0.5)(1)] = -0.5 -> incorrect
        Weight adjustments: w_{ii} \leftarrow w_{ii} - g(y_i - OR_i)x_i
                 w_0 = 0 - g[(-0.5) - (1)](1) = 1.5
                 W_1 = 0.5 - g[(-0.5) - (1)](0) = 0.5
                 w_2 = -0.5 - g[(-0.5) - (1)](1) = 1
Third pass: x_1 = 1, x_2 = 0, OR = 1
        y = g(w_0x_0 + w_1x_1 + w_2x_2) = g[(1.5)(1) + (0.5)(1) + (1)(0)] = 2 -> incorrect
        Weight adjustments: w_{ii} \leftarrow w_{ij} - g(y_i - OR_i)x_i
                 w_0 = 1.5 - g[(0.5) - (1)](1) = 2
                 W_1 = 0.5 - g[(0.5) - (1)](1) = 1
                 w_2 = 1 - g[(0.5) - (1)](0) = 1
Fourth pass: x_1 = 1, x_2 = 1, OR = 1
        y = g(w_0x_0 + w_1x_1 + w_2x_2) = g[(2)(1) + (1)(1) + (1)(1)] = 4 -> incorrect
        Weight adjustments: w_{ii} \leftarrow w_{ii} - g(y_i - OR_i)x_i
                 w_0 = 2 - g[(4) - (1)](1) = -1
                 W_1 = 1 - g[(4) - (1)](1) = -2
                 w_2 = 1 - g[(4) - (1)](1) = -2
```