Coding Example: Blue Noise Sampling using DART method

In this lesson, we will try to do the blue noise sampling using the DART method discussed in the previous lesson. We will look at both solutions, i.e., Pythonic and NumPy approach and see which one is more efficient.

We'll cover the following

- Python Implementation
- NumPy Implementation

Let's consider the unit surface and a minimum radius r to be enforced between each point.

Knowing that the densest packing of circles in the plane is the hexagonal lattice of the bee's honeycomb, we know this density is $d=\frac{1}{6}\pi\sqrt{3}$ (in fact I learned it while writing this course). Considering circles with radius \mathbf{r} , we can pack at most $\frac{d}{\pi r^2}=\frac{\sqrt{3}}{6r^2}=\frac{1}{2r^2\sqrt{3}}$.

We know the theoretical upper limit for the number of discs we can pack onto the surface, but we'll likely not reach this upper limit because of random placements.

Furthermore, because a lot of points will be rejected after a few have been accepted, we need to set a limit on the number of successive failed trials before we stop the whole process.

()

Python Implementation

```
# Copyright (2017) Nicolas P. Rougier - BSD license
   # More information at https://github.com/rougier/numpy-book
    import math
    import random
    import matplotlib.pyplot as plt
10
    def DART_sampling_python(width=1.0, height=1.0, radius=0.025, k=100):
11
        def squared_distance(p0, p1):
12
            dx, dy = p0[0]-p1[0], p0[1]-p1[1]
13
            return dx*dx+dy*dy
        points = []
17
        i = 0
        last_success = 0
        while True:
19
            x = random.uniform(0, width)
            y = random.uniform(0, height)
21
            accept = True
22
            for p in points:
                 if squared_distance(p, (x, y)) < radius*radius:</pre>
25
                     accept = False
                     break
            if accept is True:
27
28
                 points.append((x, y))
                 if i-last success > k:
30
                     break
                 last success
\triangleright
```

NumPy Implementation

Now we will do the vectorization of the DART method. The idea is to precompute enough uniform random samples as well as paired distances and to test for their sequential inclusion.

```
P = np.zeros((n, 2))
    P[:, 0] = np.random.uniform(0, width, n)
    P[:, 1] = np.random.uniform(0, height, n)
    # Computes respective distances at once
    D = cdist(P, P)
    # Cancel null distances on the diagonal
    D[range(n), range(n)] = 1e10
    points, indices = [P[0]], [0]
    i = 1
    last_success = 0
    while i < n and i - last_success < k:</pre>
        if D[i, indices].min() > radius:
             indices.append(i)
             points.append(P[i])
            last_success = i
        i += 1
    return points
if __name__ == '__main__':
    plt.figure()
    plt.subplot(1, 1, 1, aspect=1)
    points = DART_sampling_numpy()
    X = [x \text{ for } (x, y) \text{ in points}]
    Y = [y \text{ for } (x, y) \text{ in points}]
    plt.scatter(X, Y, s=10)
    plt.xlim(0, 1)
    plt.ylim(0, 1)
    plt.savefig("output/output2.png")
    plt.show()
                                                                                 \leftarrow
```

In the next lesson, we will use another Bridson method to do the sampling!