# Bayesian Compromise Estimators

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2023-10-24

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### Introduction

- The common form of a statistical analysis is given by the following two steps:
  - Select the best model
  - Apply the model as if it was the truth/the best overall
- The first step usually relies on either
  - model selection criteria (WAIC/\*IC/CV), often data driven, or
  - scientific theory.
- However, it is quite easy to criticize the model selection step. For example:
  - Model selection can be unstable. Small changes of input data may yield radically different model choice.
  - Very different models can have similar performance overall. Then, discriminating between them is often difficult.
- What are the possible consequences? Poor generalizability and inference.
  - Unstable selection means the model may perform badly with out-of-sample data.
  - Ad-hoc choices between similar models may yield sub-optimal selection.
  - Model selection uncertainty not properly represented in final analysis
- Compromise modeling is one way of dealing with the issue. Particularly good at countering poor generalizability.

### Compromise Modeling - General Idea

Suppose that  $\varphi$  is some quantity of interest, and that

- ullet There are K candidate models under consideration, and
- ullet Each candidate model produces  $arphi_k$  as and approximation of arphi.

Then, compromise modeling entails us a weighted average of the candidates,

$$\bar{\varphi} = \sum_{k=1}^{K} w_k \varphi_k,$$

as the final approximation of  $\varphi$ . Here  $w_k$  are model specific weights that can be estimated to suit the purpose of the analysis.

### Example: Variable Selection in Linear Regression

Let  $\mathbf{y}=(y_1,\dots,y_n)^T$  be a vector of (continuous) outcomes and  $\mathbf{X}$  be a matrix of covariates to use in linear regression.

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**Alternative solution:** Consider several different subsets, and combine their information by a weighted average. For example,

- If  $\varphi$  is the posterior predictive distribution,  $\bar{\varphi} = \sum_k w_k \cdot p(\tilde{\mathbf{y}}|\mathbf{y}, \mathbf{X}_k)$ ,
- If  $\varphi$  is the posterior predictive mean,  $\bar{\varphi} = \sum_k w_k \cdot E[\tilde{\mathbf{y}}|\mathbf{y}, \mathbf{X}_k]$ .

Note that both  $p(\tilde{\mathbf{y}}|\mathbf{y},\mathbf{X}_k)$  and  $E[\tilde{\mathbf{y}}|\mathbf{y},\mathbf{X}_k]$  are derived as usual. The new step in this procedure is finding suitable weights  $w_1,\dots,w_K$ . In Bayesian theory, Bayesian model averaging and Bayesian stacking are the prominent ways of doing so.

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## Bayesian Model Averaging

Bayesian model averaging (BMA) is concerned with  $\varphi=p(\Delta|D)$ , where

- $\bullet$   $\Delta$  could be a new observation,  $\tilde{\mathbf{y}},$  or a vector of regression coefficients,  $\ ,$  and
- D is the data.

# Bayesian Model Averaging

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The BMA posterior probability for  $\Delta$  is given as

$$p(\Delta|D) = \sum_{k=1}^{K} p(\Delta|M_k, D) \cdot p(M_k|D).$$

Here,  $M_k$  denotes the k:th candidate model, and

- $p(\Delta|M_k, D)$  is the posterior probability for  $\Delta$  given model k.
- ullet  $p(M_k|D)$  is the posterior probability of the model  $M_k$ .

Compare to the compromise posterior predictive on last slide, and note that  $w_k=p(M_k|D)$  shows how to weight each model.

### Problems in Practice

- Posterior distributions of advanced models can be hard (impossible) to find.
   For BMA, this amounts to
  - ullet The usual difficulty of finding  $p(\Delta|M_k,D)$ , and
  - $\bullet$  The additional step of finding the model posterior,  $p(M_k|D).$  In particular, computing the integrated likelihood.
- Some simple problems have analytical solutions (see e.g. Raftery, Madigan, and Hoeting 1997 for a linear regression example).
- MCMC Model Composition (MCMCMC) simplifies things by generating a Markov chain that moves through the model space (I think it can be applied using the BMA package).
- Another issue of BMA has to do with the behavior of the weights in large samples. To discuss this, some further notation has to be introduced.

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### ${\mathcal M}$ -open and ${\mathcal M}$ -closed

To formalize the last drawback of BMA, and to motivate the use of Bayesian stacking, the properties of the candidate models employed need to be considered. Thus, let  $\mathcal{M} = \{M_1, \dots, M_K\}$  be the set of candidate models. Then

- $\mathcal{M}$ -closed means the true data generating model is included in  $\mathcal{M}$ , although it is not known which of the candidates it is, while
- $\mathcal{M}$ -complete means that the true model is *not* in  $\mathcal{M}$ , but we still use  $\mathcal{M}$  since the true model may be too complicated in terms of computations, interpretations, etc.
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It is known that, as  $n\to\infty$ , the BMA weight of the candidate closest to the true model (in terms of KL divergence) tends to 1. That is,

- ullet For  $\mathcal{M}$ -closed, this is great since BMA will chose the true model.
- ullet For  ${\mathcal M}$ -complete/open, BMA clearly selects the wrong model.

I would argue that  $\mathcal{M} ext{-complete/open}$  is more realistic. So what to do?

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#### Some preliminaries: Let

- $\bullet \ \mathbf{w} = (w_1, \dots, w_k)^T$  , and suppose it belongs to some set  $\mathcal{W}$  , and
- $\bullet$  S(P,Q) be a scoring rule, measuring the similarity of two distributions P and Q.

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Then, Bayesian stacking weights are given by

$$\mathbf{w}^* = \underset{\mathbf{w} \in \mathcal{W}}{\operatorname{argmax}} \ S\left(\sum_{k=1}^K w_k p(\tilde{\mathbf{y}}|\mathbf{y}, M_k), p_{\mathsf{true}}(\tilde{\mathbf{y}}|\mathbf{y})\right).$$

That is,  $\mathbf{w}^*$  is the weight vector that maximizes the similarity between the stacked posterior predictive and the true posterior predictive distribution

Of course,  $p_{\mathsf{true}}(\tilde{\mathbf{y}}|\mathbf{y})$  is not known, and some kind of empirical approximation is required. One way of estimating  $\mathbf{w}^*$  is using leave-one-out cross-validation.

- Clyde and Iversen (2013) introduce it in Bayesian setting,
- Le and Clarke (2017) theoretically motivate use of CV for weight estimation,
- Yao et al. (2018) use general scoring rules.

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Using the weight vector estimated by cross-validation, the stack is given by

$$\sum_{k=1}^{K} w_k^* p(\tilde{\mathbf{y}}|\mathbf{y}, M_k),$$

which is very similar to the frequentist jackknife model averaging.

## Scoring Rules

For Bayesian stacking, it is common to use either

- The  $\log$  score,  $LS(P,y) = \log[p(y)]$ , or
- The energy score,  $ES(P,y)=\frac{1}{2}E_P\|Y-Y'\|^{\beta}-\mathbb{E}_p\|Y-y\|^{\beta}.$  Here, Y and Y' both follow P independently.  $\beta=2$  is common in practice.

The major difference is that stacking using the  $\log$  score gives a stacked posterior distribution, while stacking using the  $\beta=2$  energy score gives a stacked posterior mean.

Depending on the objective of the analysis, either approach may be suitable.

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### Example Using rstanarm and loo

 ${\tt loo::stacking\_weights} \ \ {\rm gives} \ \log {\sf -score} \ \ {\rm weights}. \ \ {\sf See} \ \ {\sf stylized} \ \ {\sf example} \ \ {\sf below}.$ 

```
library("rstanarm"); library("loo")
# Fitting the candidate models
cand1 \leftarrow stan_glm(y \sim X1, data = df)
cand2 \leftarrow stan glm(v \sim X1 + X2, data = df)
cand2 \leftarrow stan_glm(y \sim X1 + X2 + X3, data = df)
# LOO-CV approximation
loo1 <- loo(cand1); loo2 <- loo(cand2); loo3 <- loo(cand3)
# Pointwise LOO ELPD
lpd_point <- cbind(loo1$pointwise[,"elpd_loo"],</pre>
                     loo2$pointwise[,"elpd_loo"],
                     loo3$pointwise[,"elpd_loo"])
stacking_weights(lpd_point) # Estimates the weights
```

An example using real data is given in the enclosed R script.

### Research Example

Ongoing work aims to evaluate Bayesian stacking using frequentist asymptotics. In particular, the focus is to establish the *oracle property* 

$$\frac{\|\mathbf{y} - \sum_k w_k^* E[\mathbf{y}|M_k]\|^2}{\inf_{\mathbf{w} \in \mathcal{W}} \|\mathbf{y} - \sum_k w_k E[\mathbf{y}|M_k]\|^2} \overset{p}{\longrightarrow} 1.$$

This means that no candidate, nor any other average using the same candidates and weights from  $\mathcal{W}$ , provides smaller asymptotic error than Bayesian stacking.

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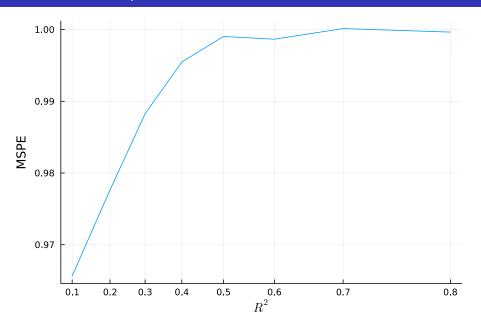
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To date, the oracle has been established for Bayesian stacking of linear regression models using  $\mathcal{N}(\mathbf{0}, \mathbf{S})$ , as the prior for  $\beta$ , where  $\mathbf{S} > 0$  is symmetric.

The results of a simulation are given on the next slide. The curve gives the ratio of the Bayesian stacking squared error to the squared error of the best candidate.

# Research Example



### References

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- Yao, Yuling, Aki Vehtari, Daniel Simpson, and Andrew Gelman. 2018. "Using Stacking to Average Bayesian Predictive Distributions (with Discussion)." Bayesian Analysis 13 (3): 917–1003.