

# Report COVID19 Model

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## Summary / Take Away

- Using the increased number of covariates seem to be better, model-wise compared to baseline. I think in many istuations our models now perform better than Imperial College Londons baseline.
- Mobility on transit station seem to be a good covariate to use.
- The regression coefficients are really sensitive. They need to be bounded for the model not to explode.

## Current flaws to be fixed:

- IFR for Finland now set to IFR for Sweden

## Potential ways forward:

- Use hospitalizations instead of deaths. I think this has better quality and is more data.
- Focus on Finland (and Sweden) at county level, although data may be missing.
- Include serological studies to estimate cumulative infections, weekly.
- Partial pooling of mobility variables.

## Model descriptions

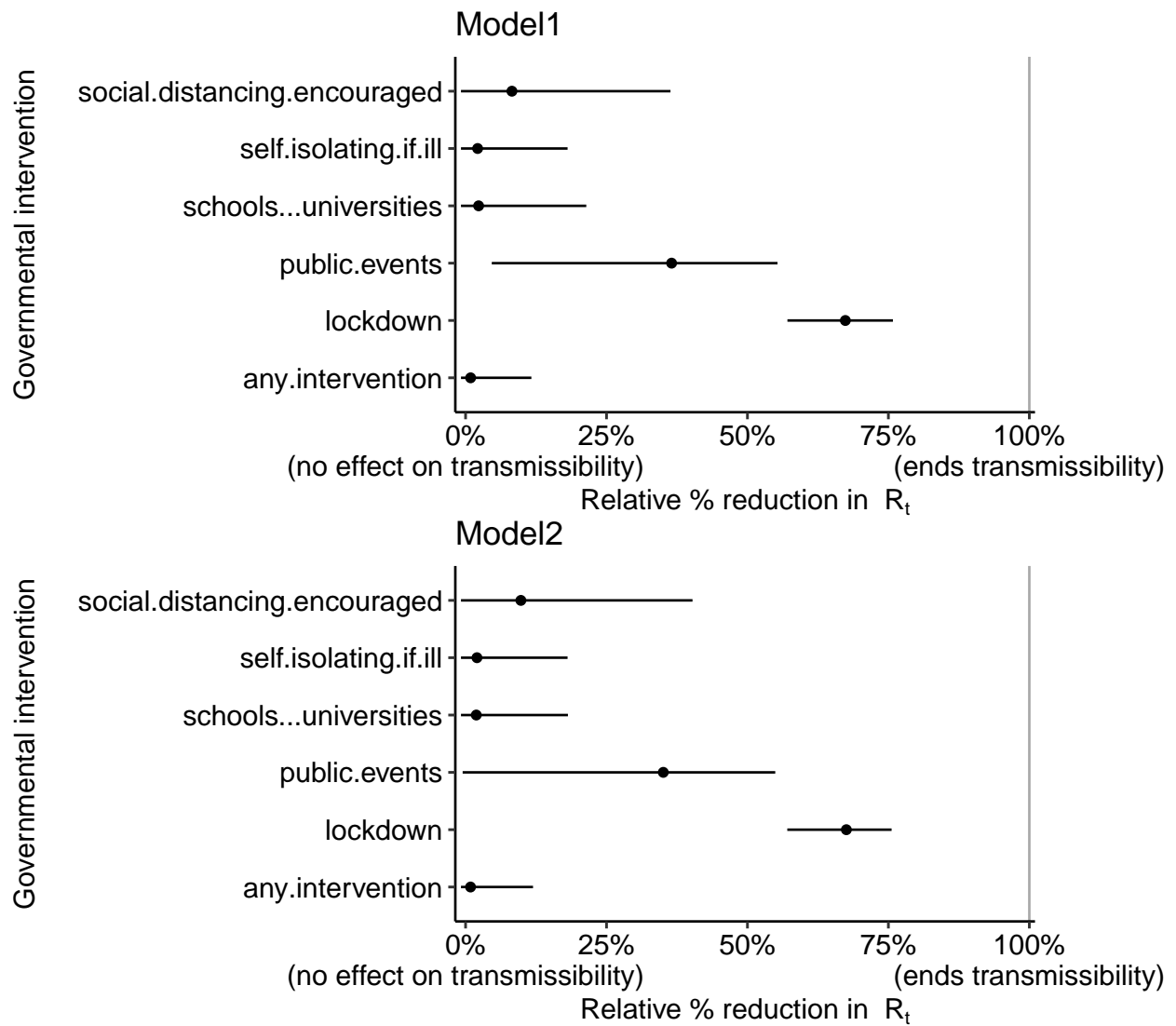
- Model 1: The baseline model, without partial pooling of lockdown
- Model 2: The baseline model, with partial pooling of lockdown variable
- Model 3: Using Oxford Response data as indicator variables
- Model 4: Google Mobility in transit stations
- Model 5: Google Mobility in transit stations and SeverityIndex
- Model 6: Google Mobility in transit stations and Oxford Binary data

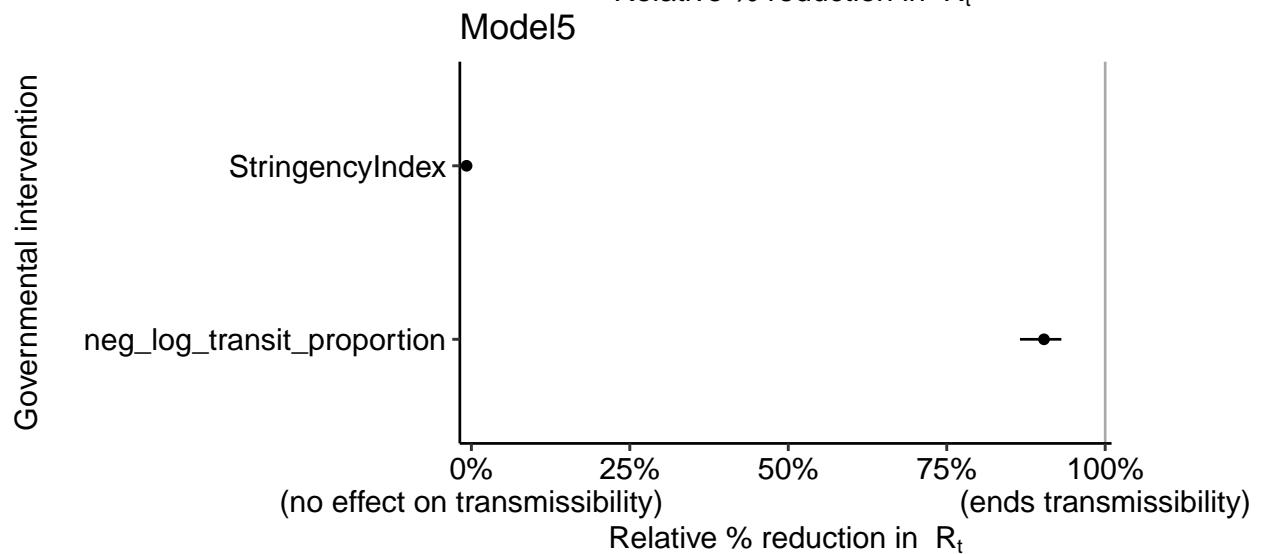
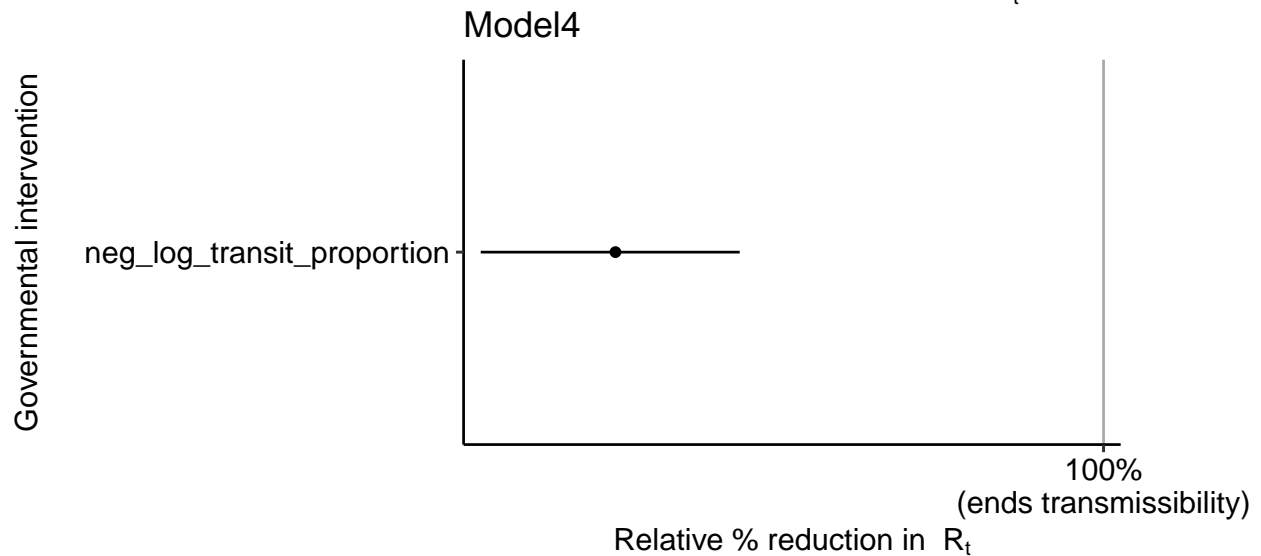
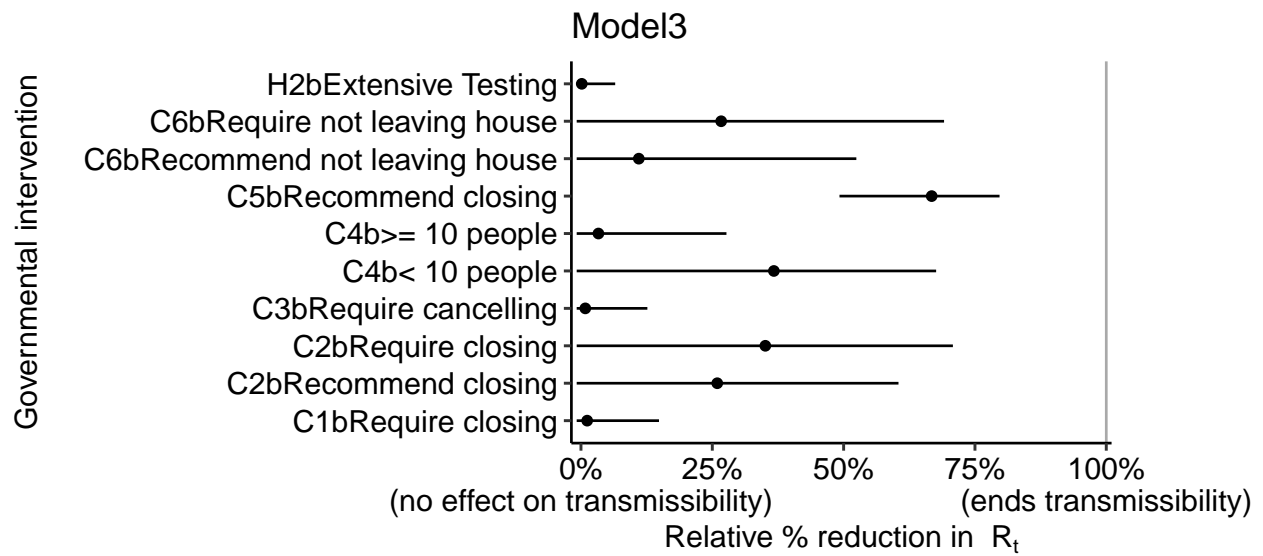
## Oxford covariate descriptions

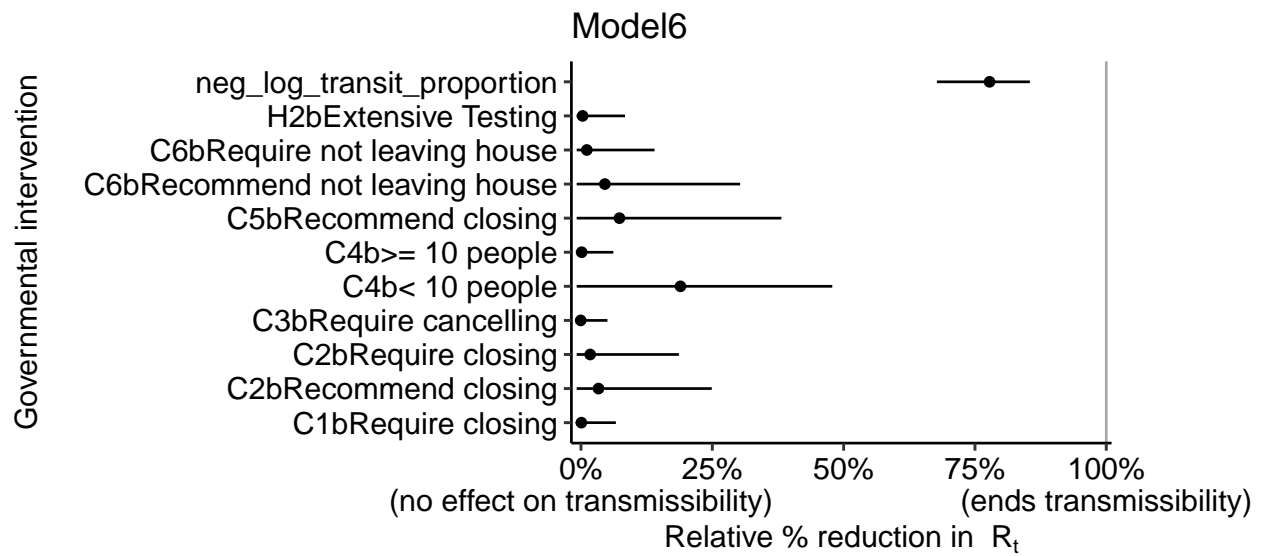
- C1: School closing
- C2: Workplace closing
- C3: Cancel public events
- C4: Restrictions on Gatherings
- C5: Close public transport
- C6: Stay at home requirements

- H2: Testing policy

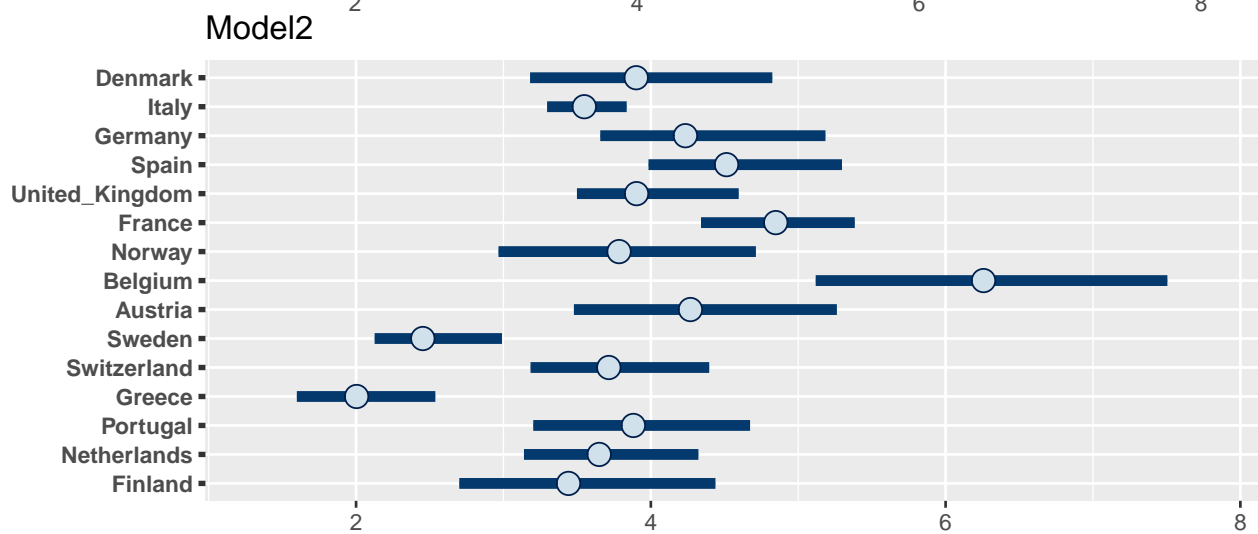
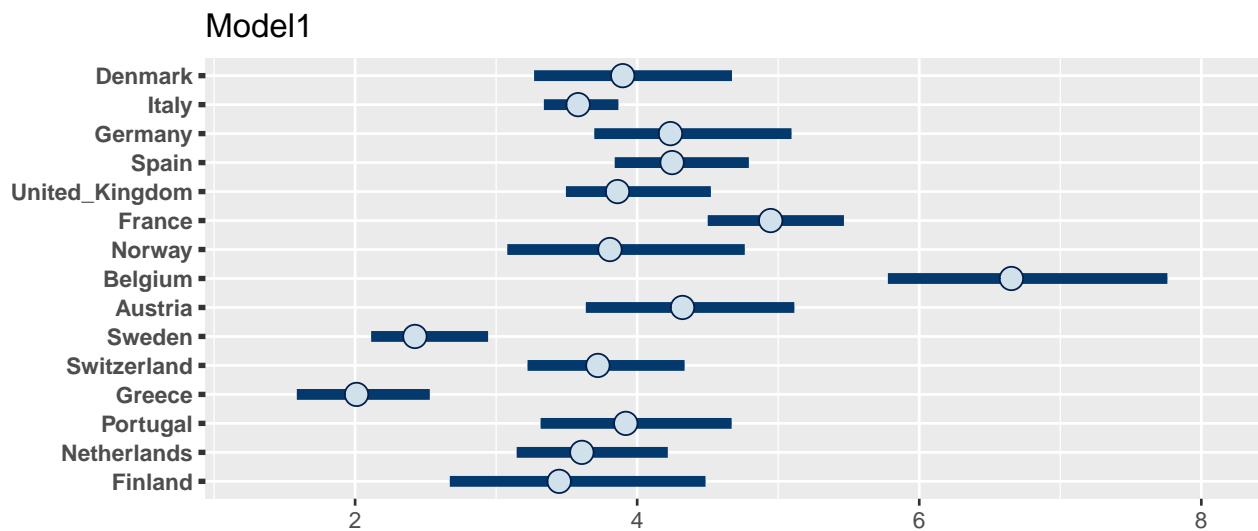
## Covariate effects



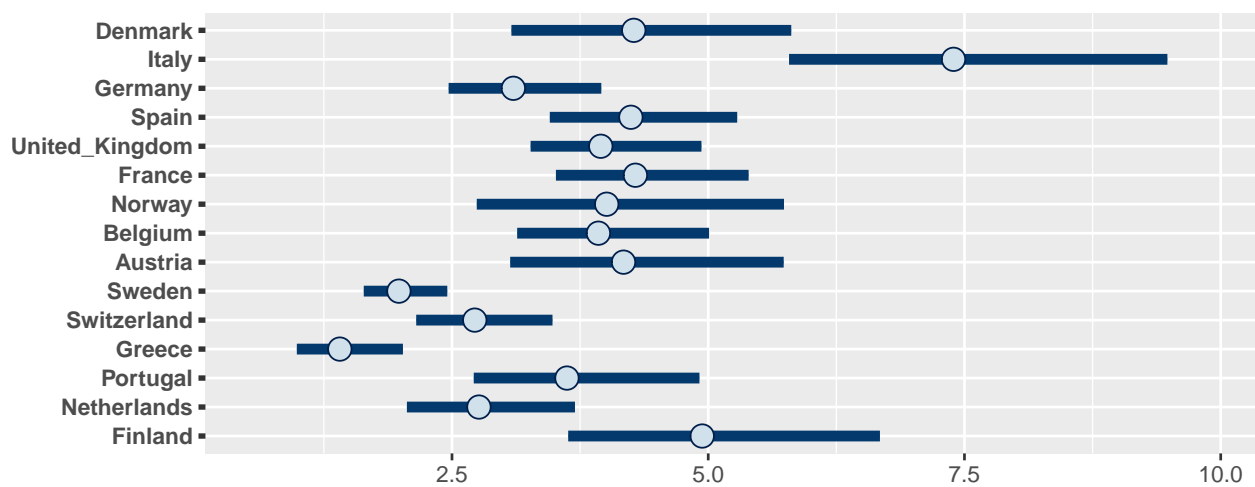




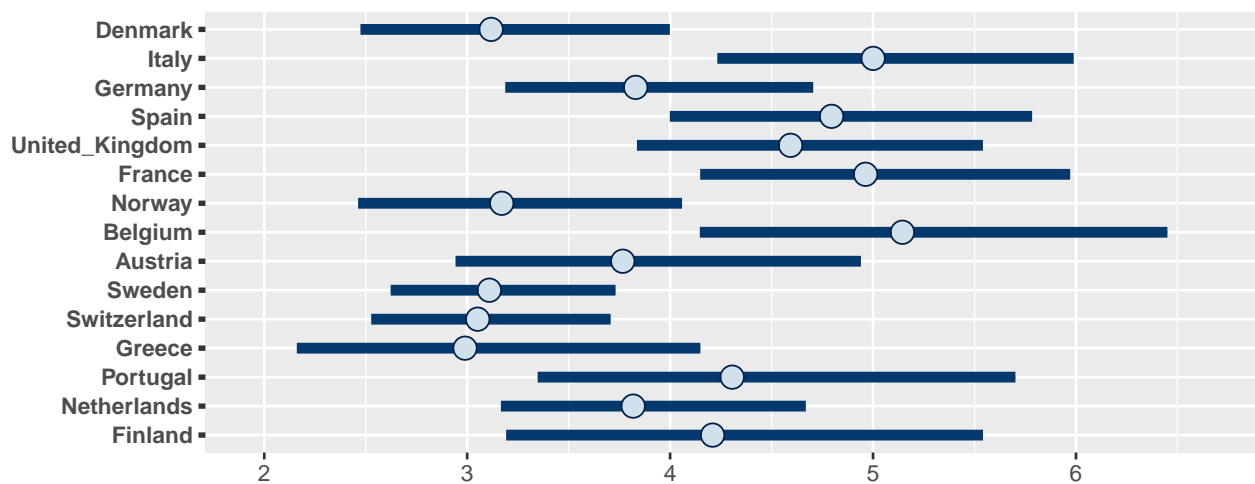
## R0 for different countries



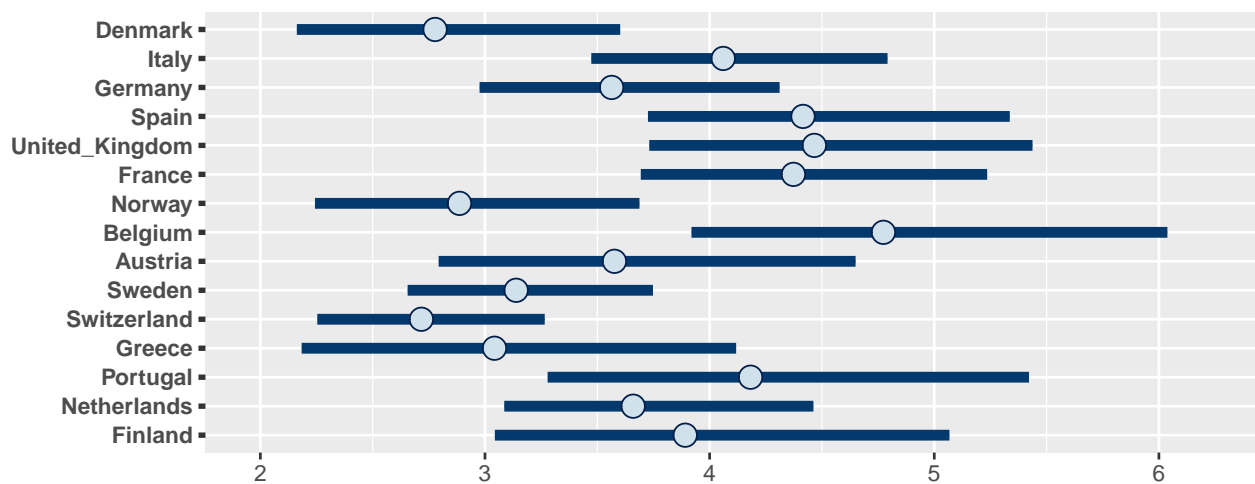
Model3



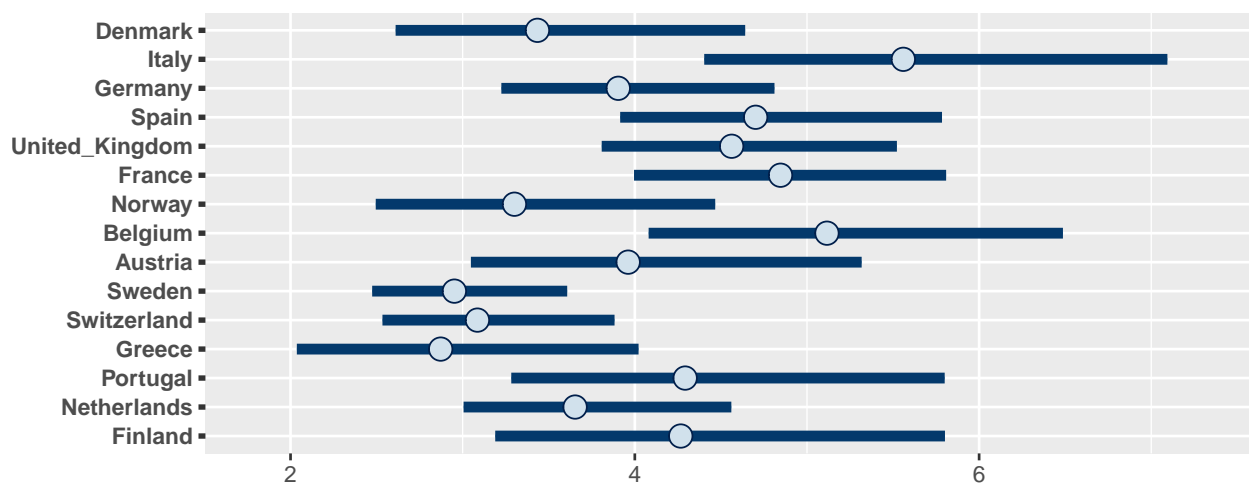
Model4



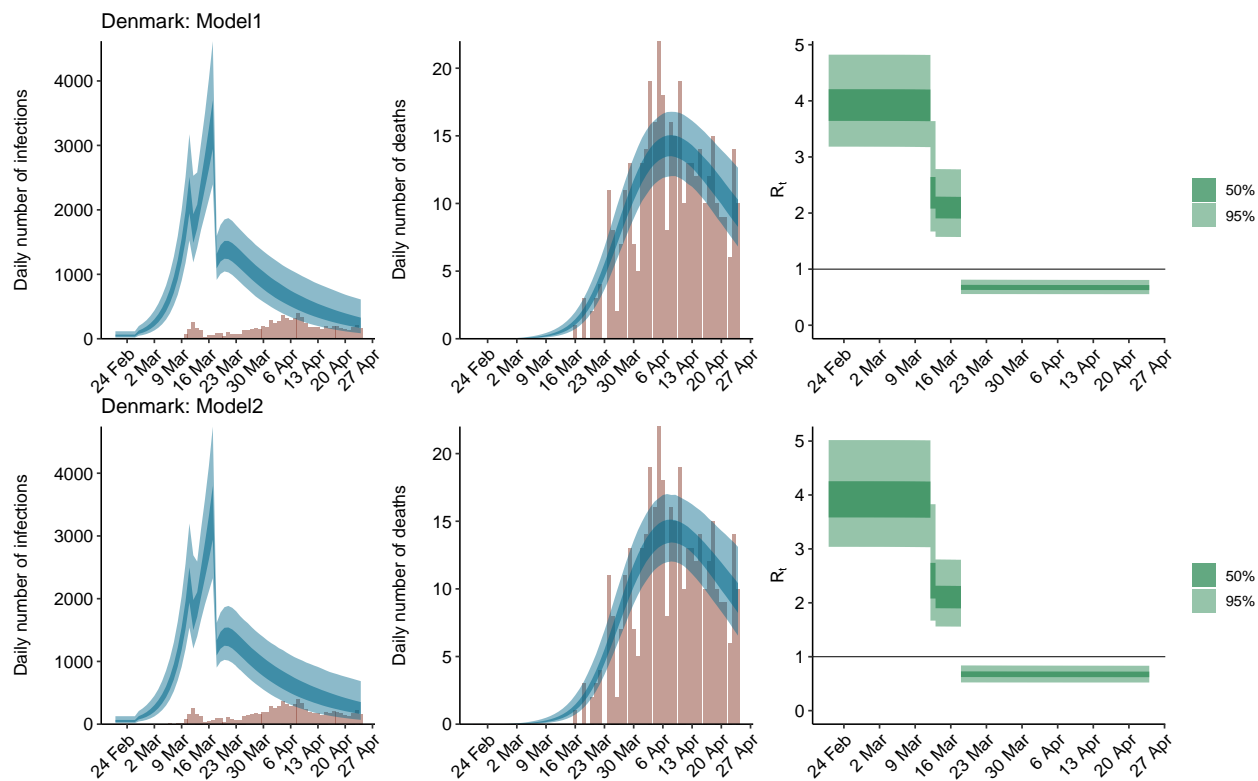
Model5

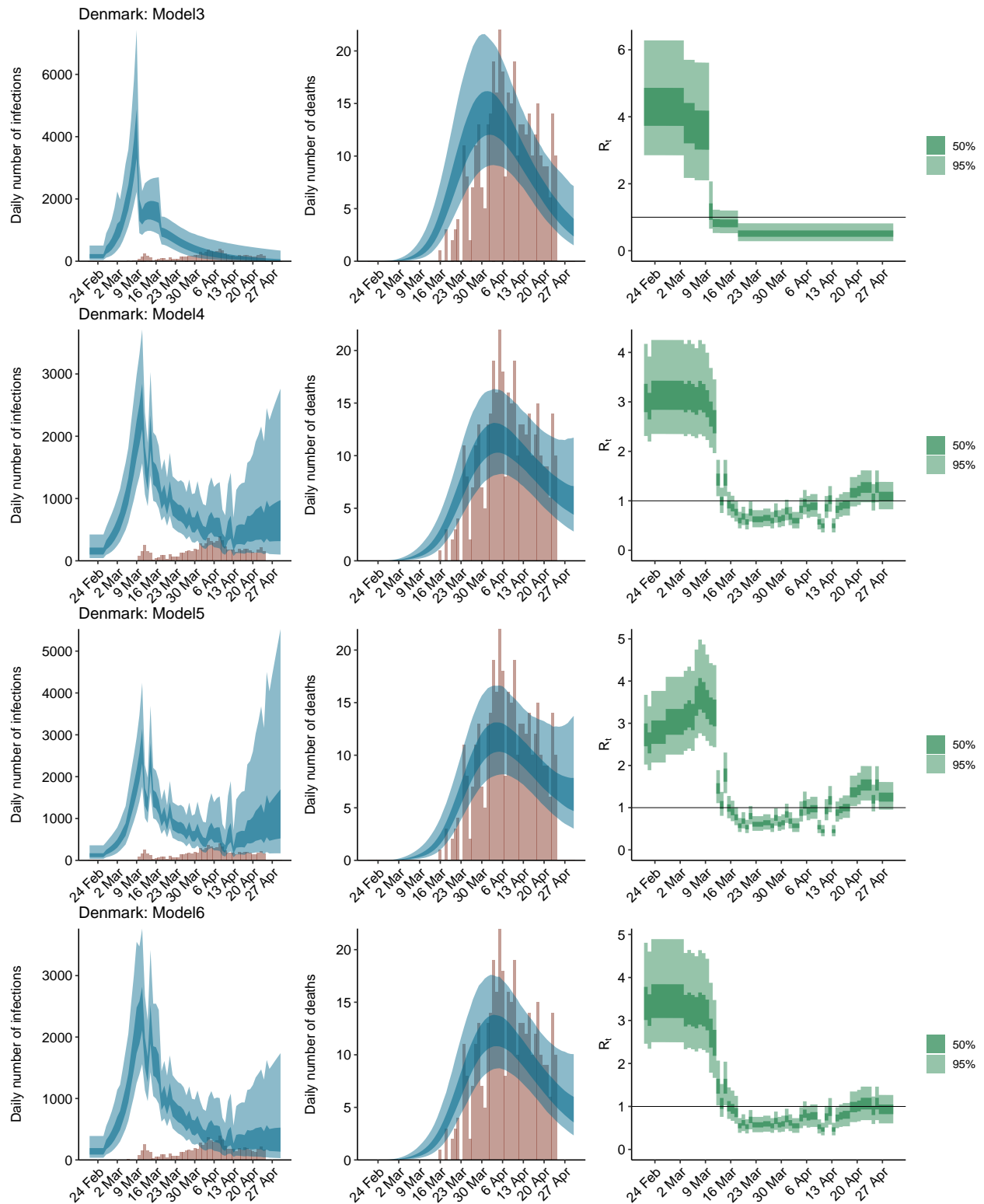


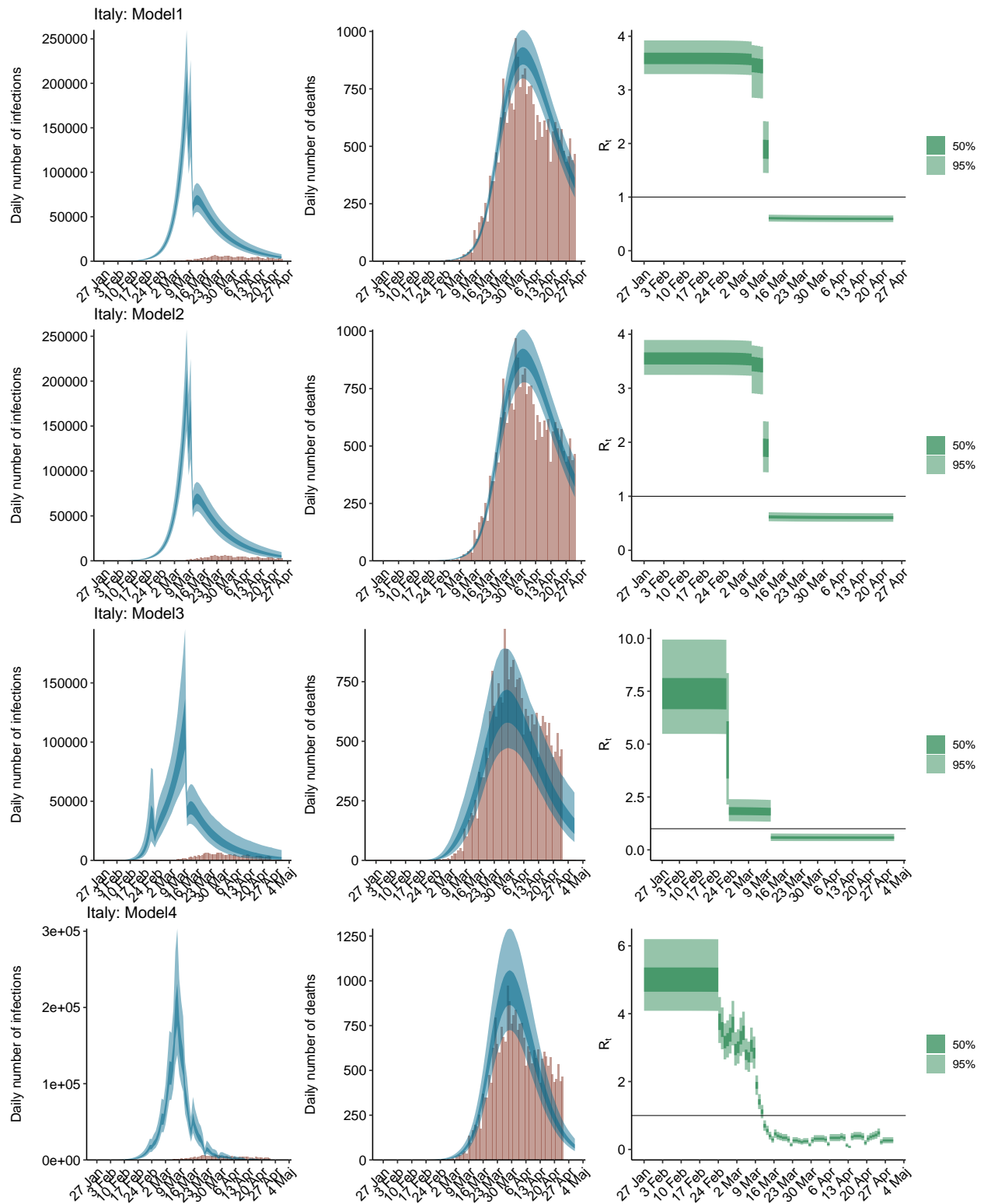
Model6



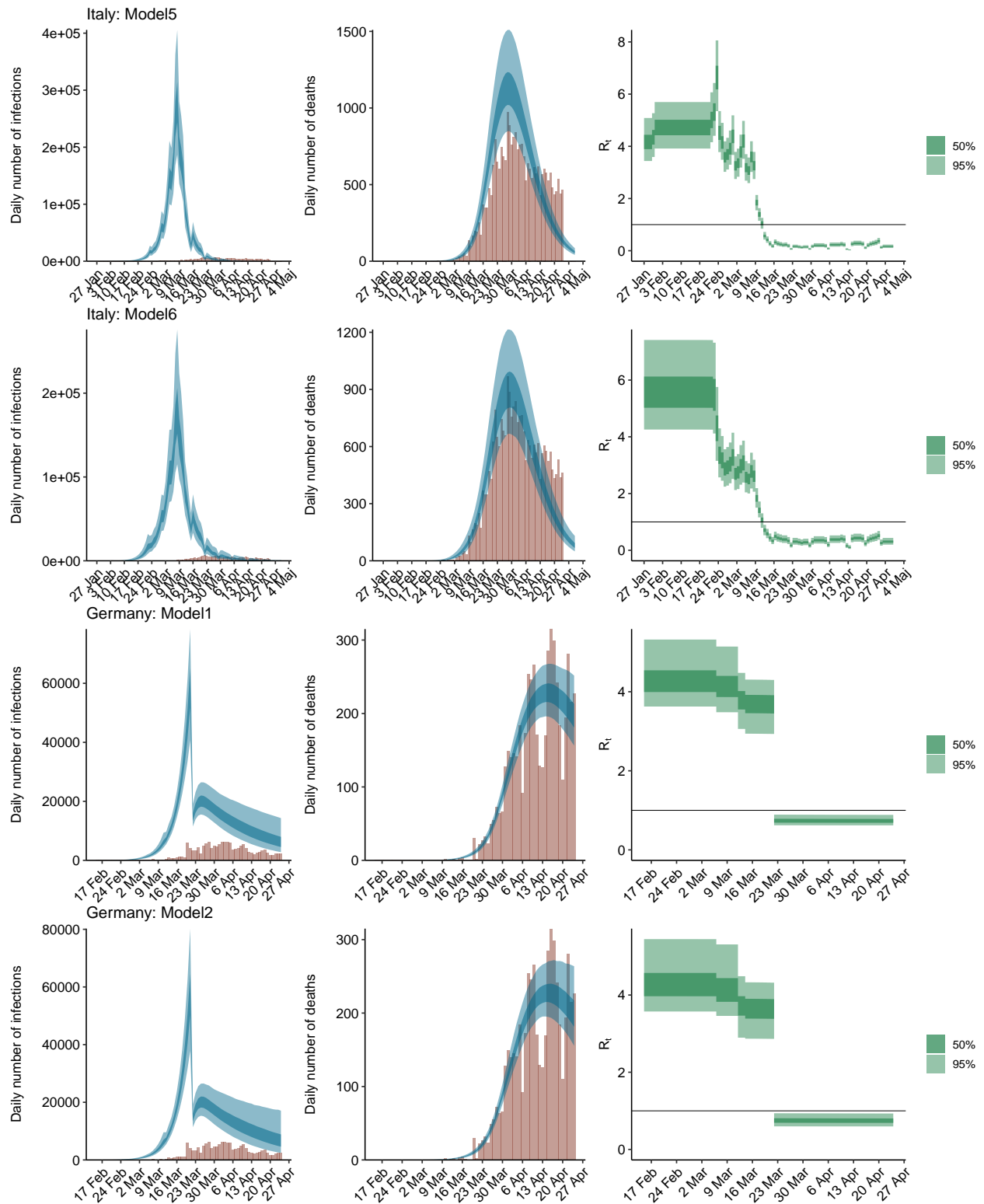
Infections, deaths and Rt by country and model

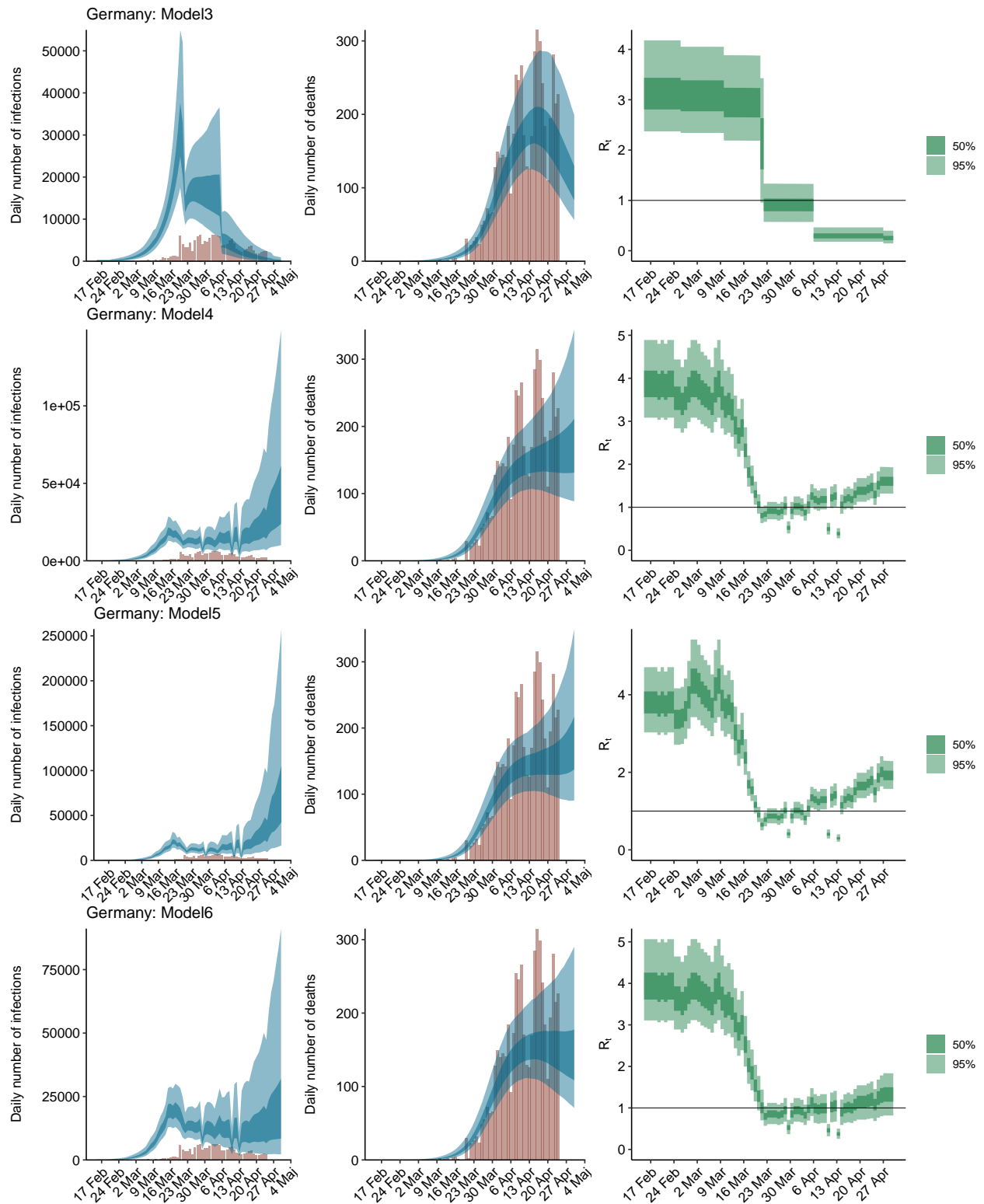


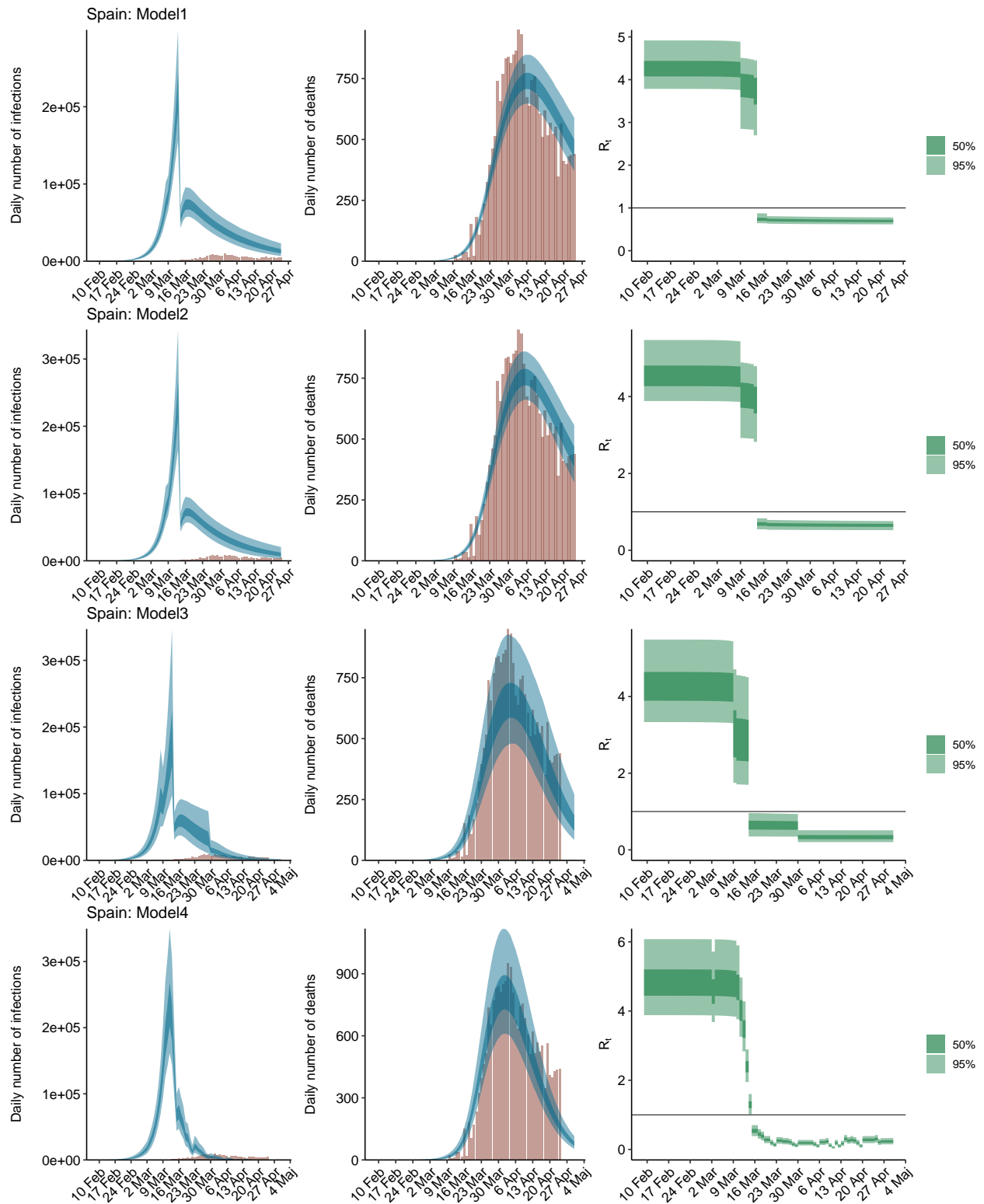


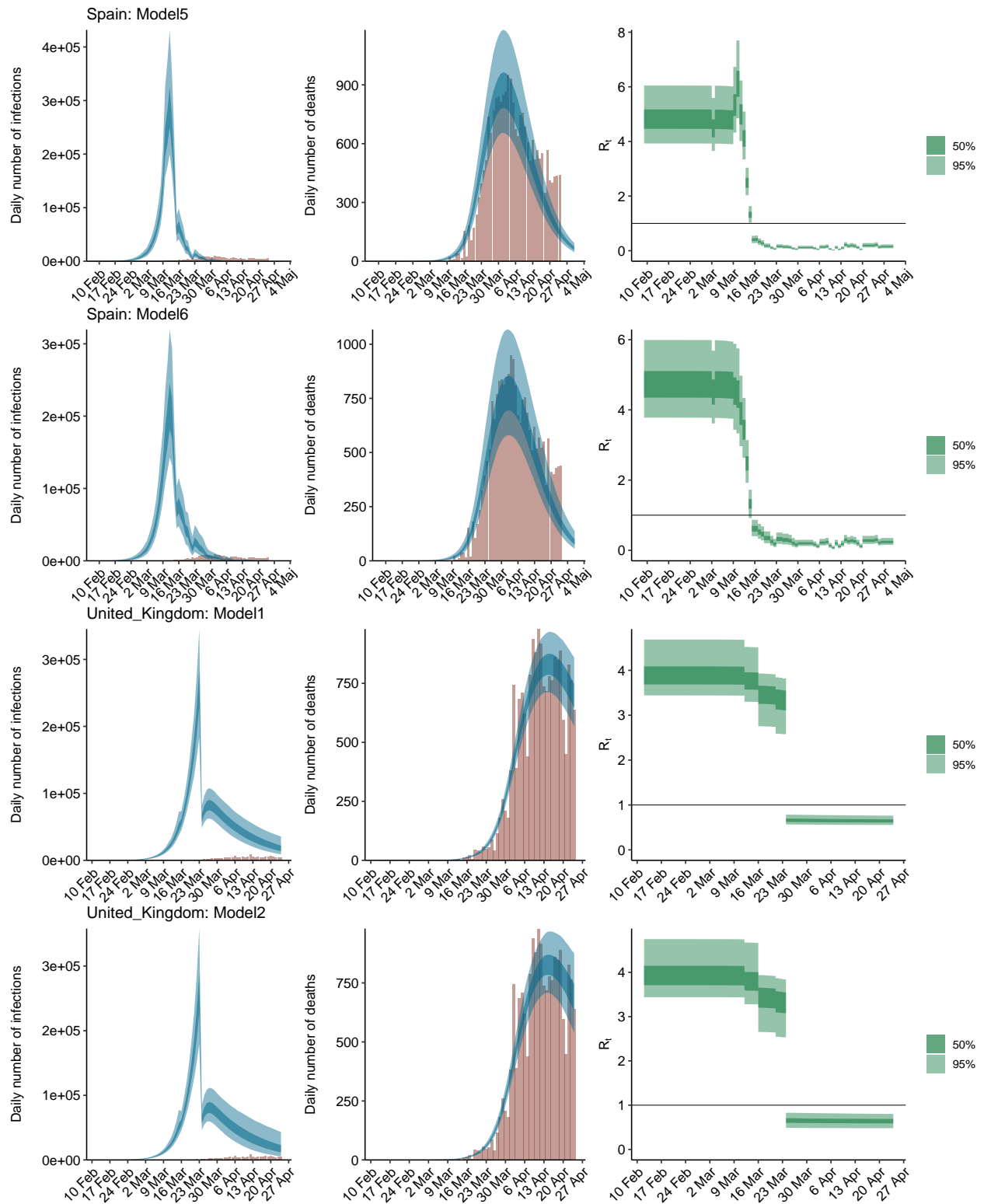


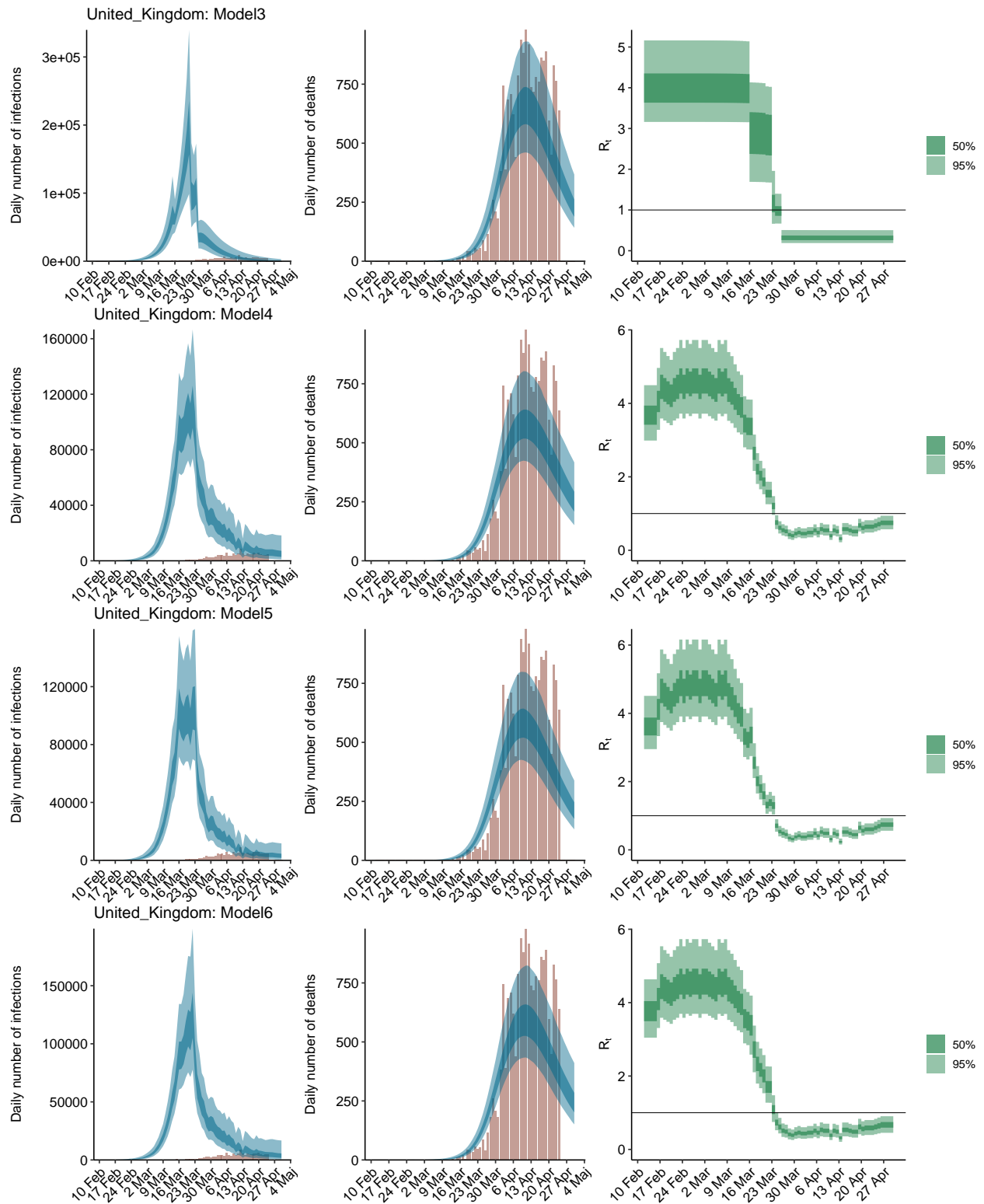


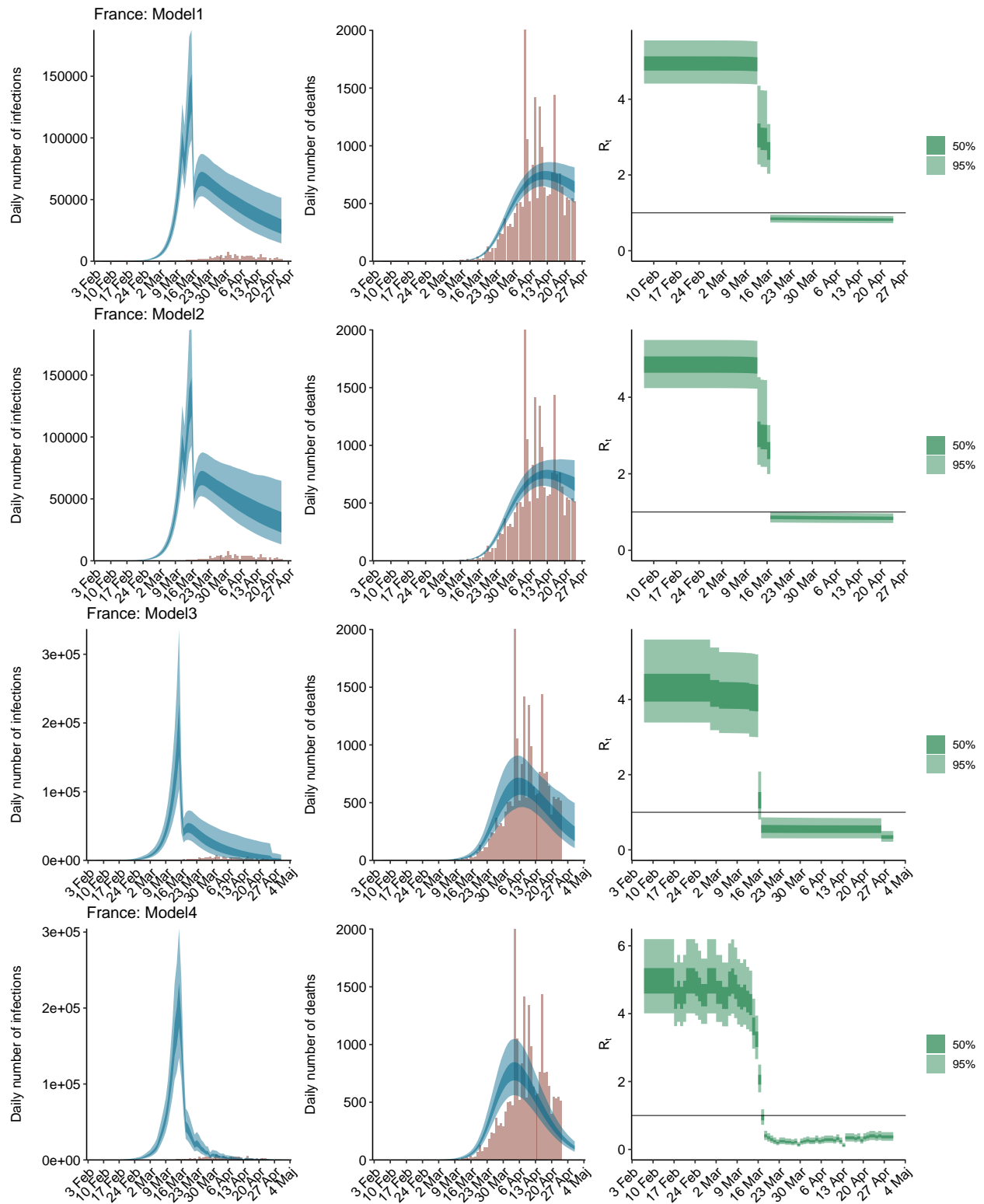


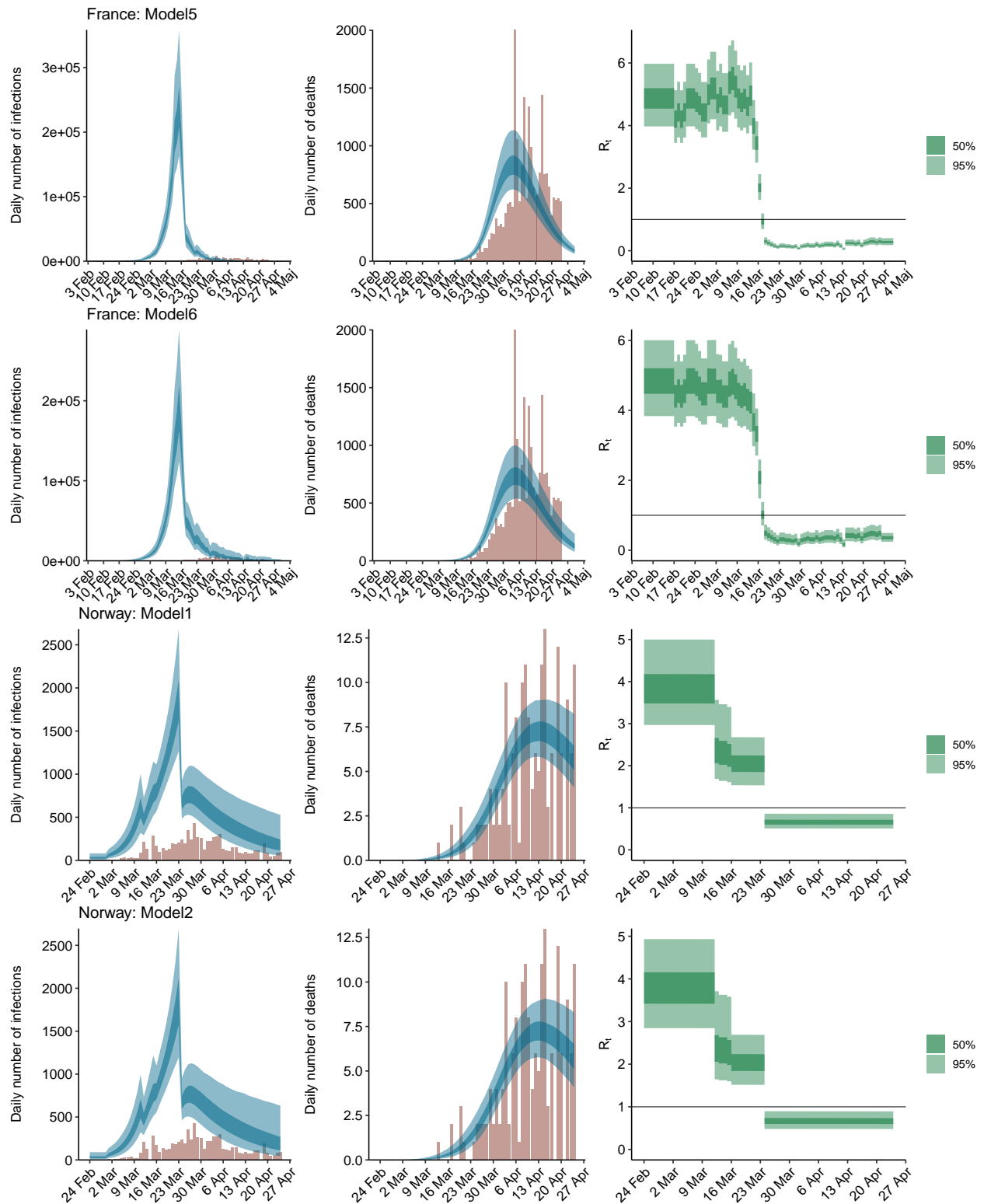


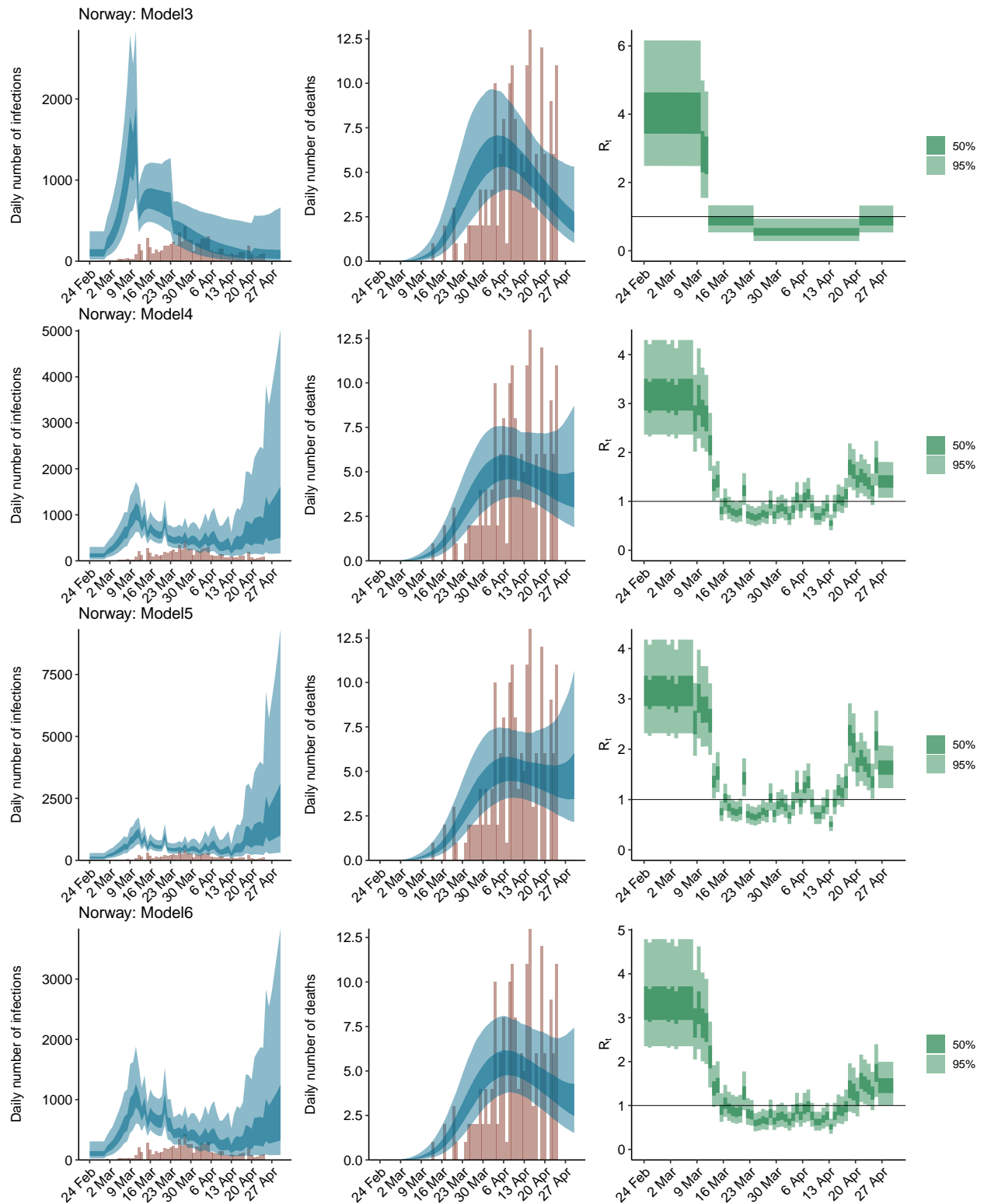






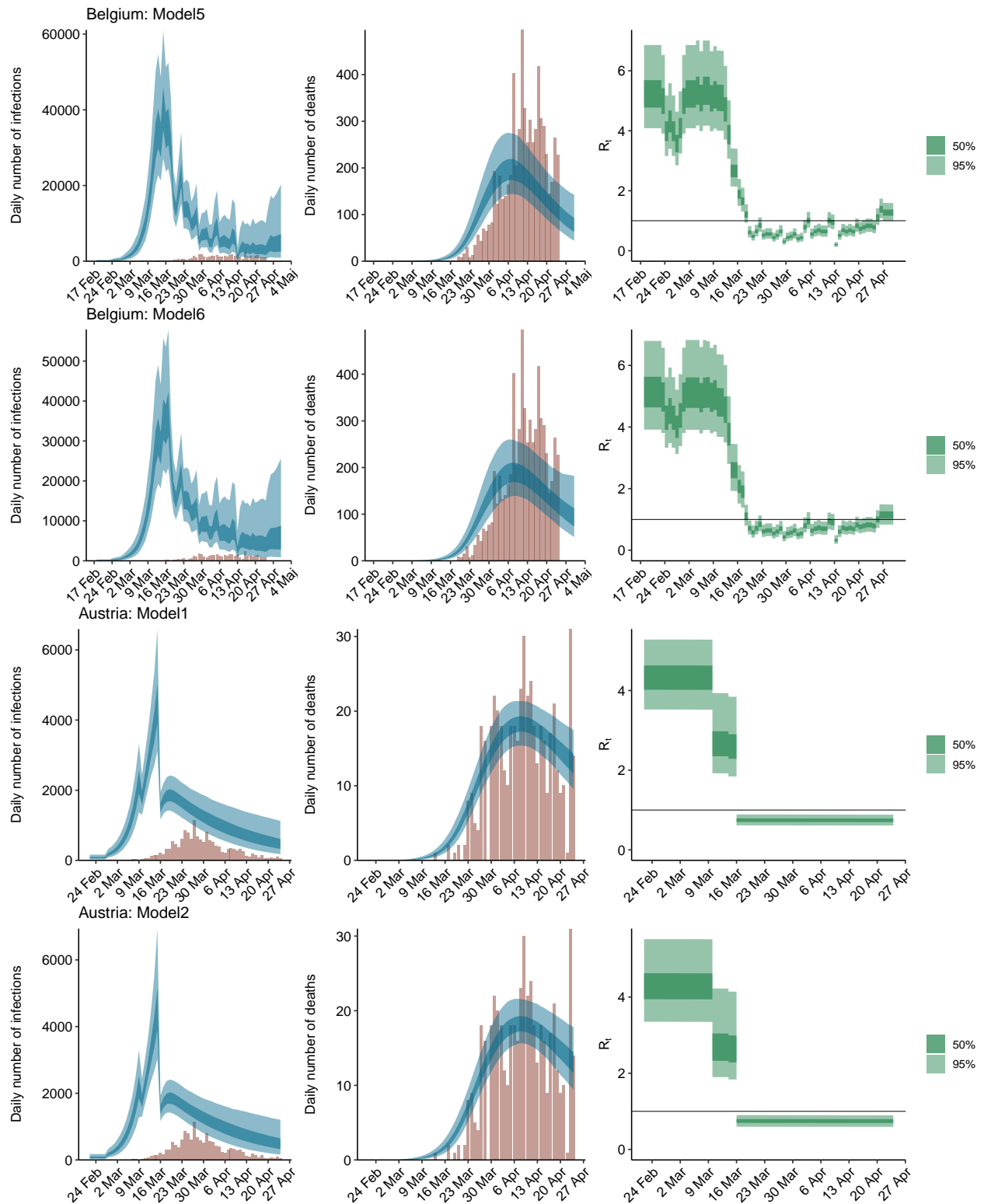


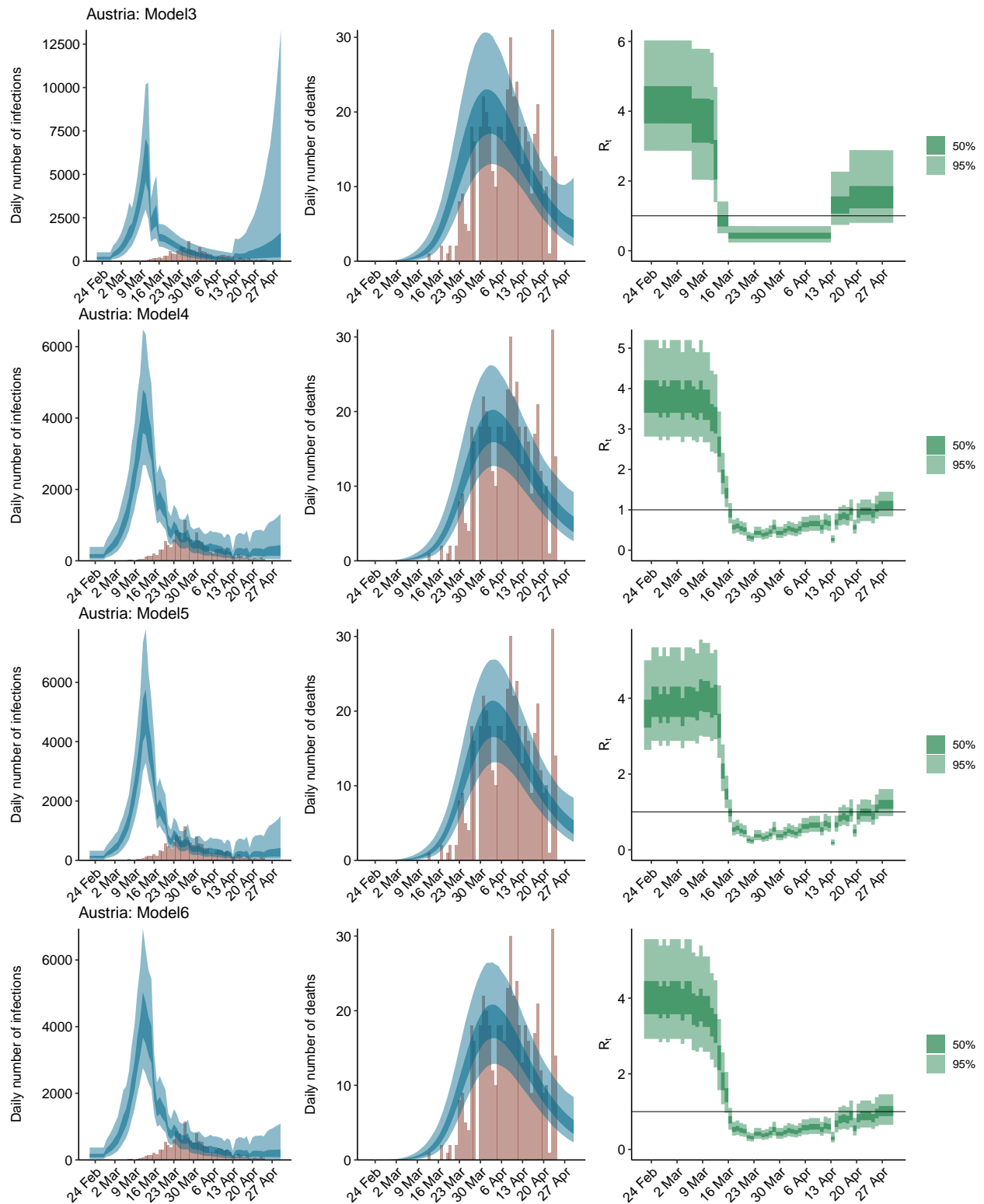


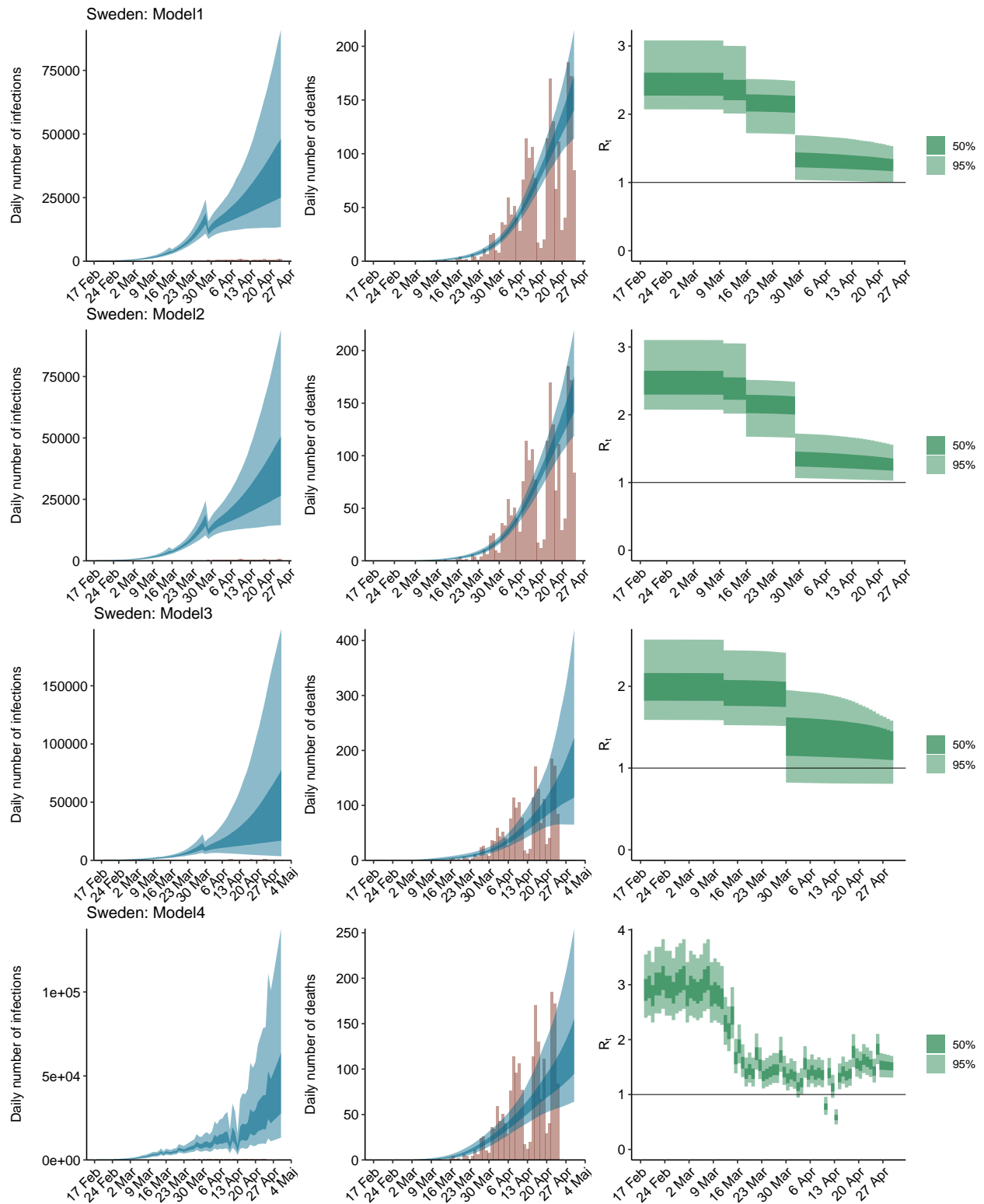


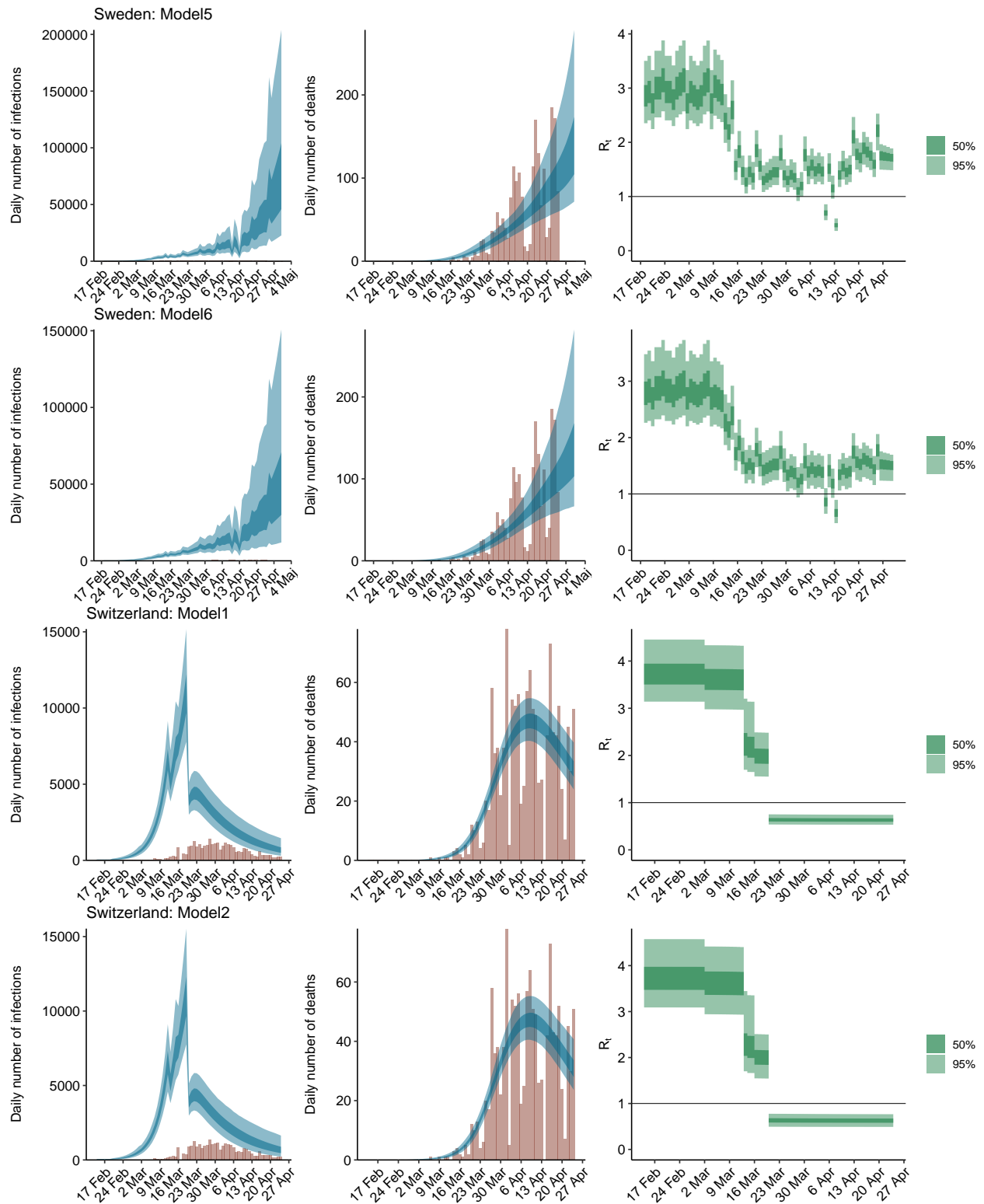


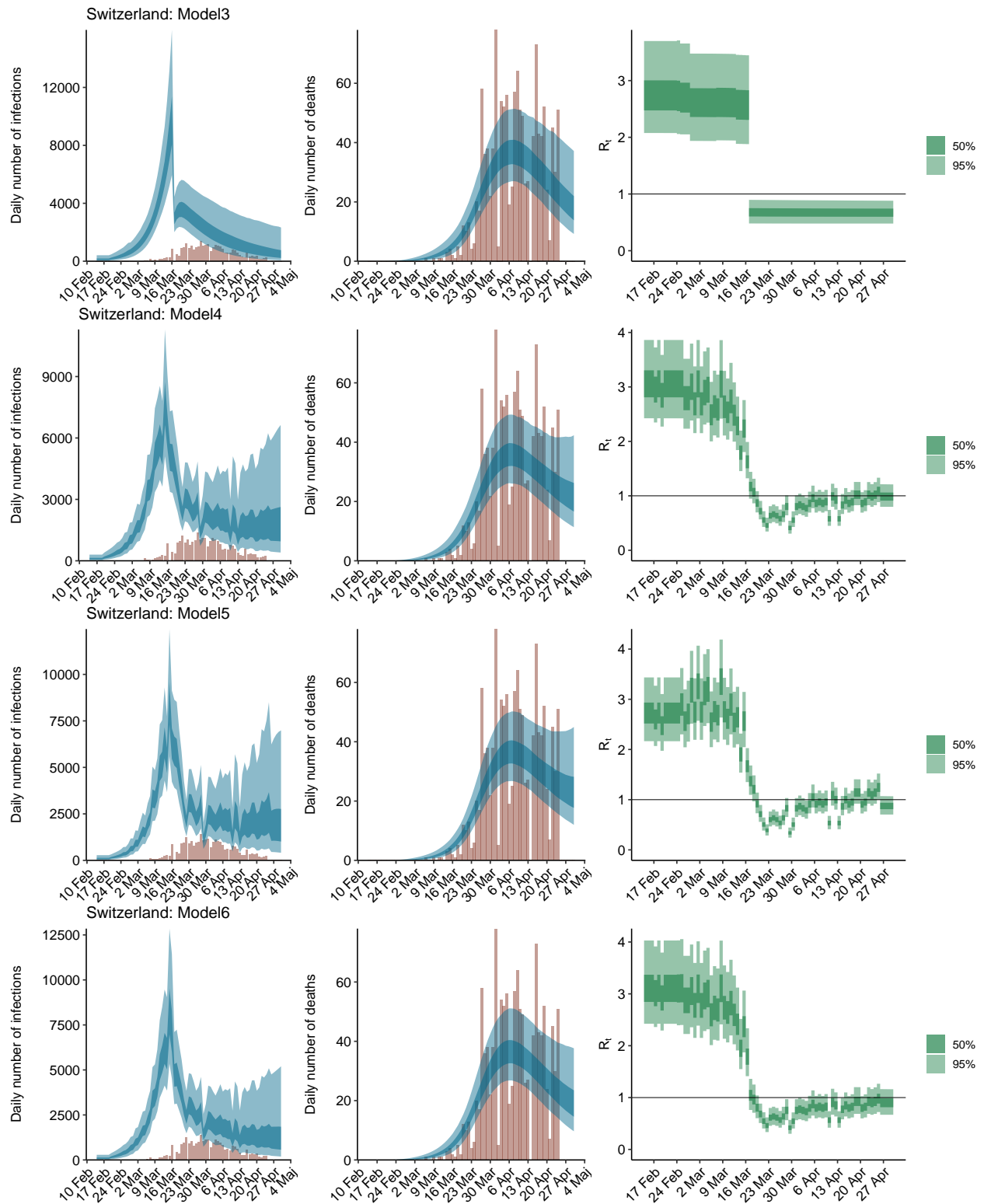


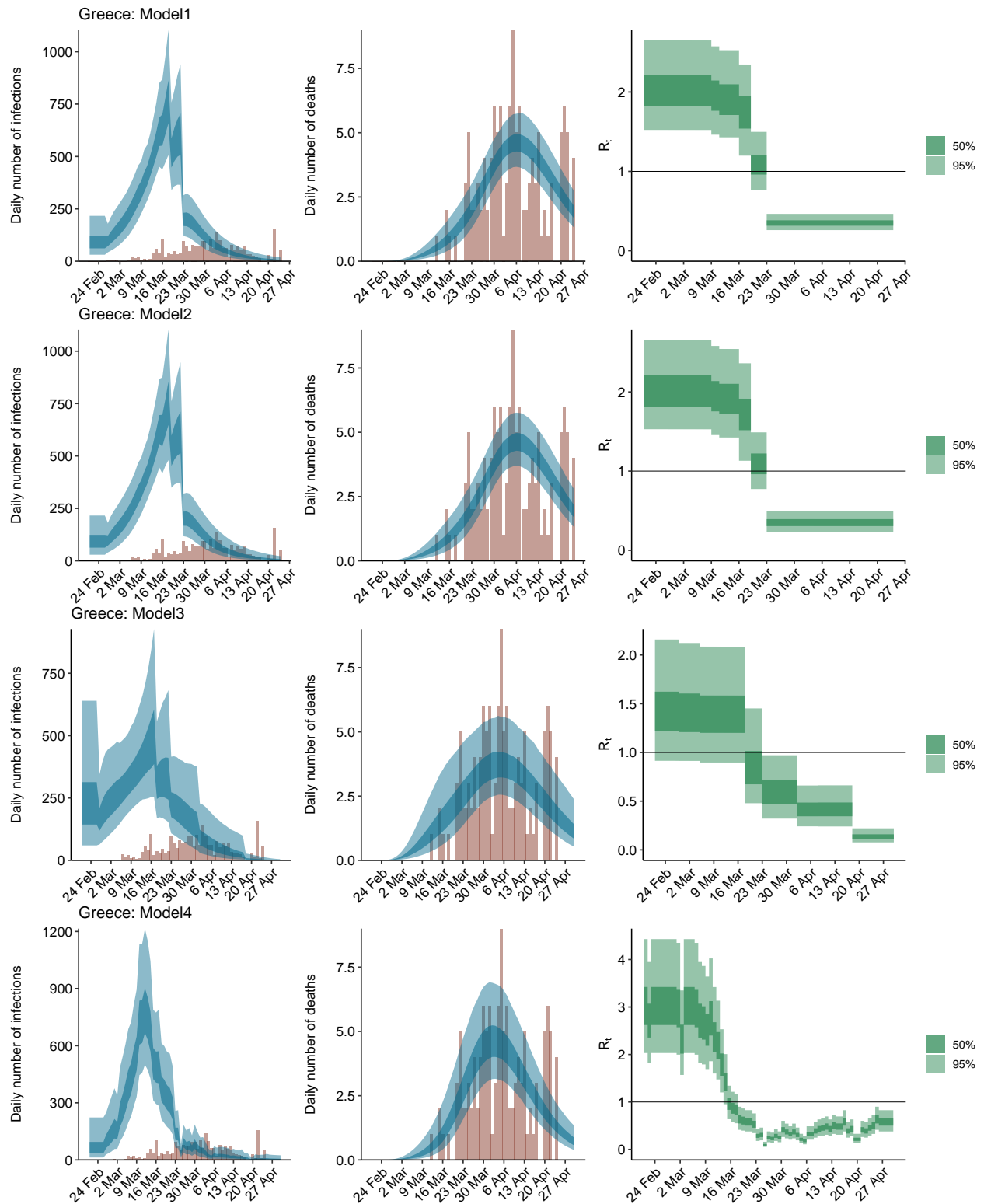


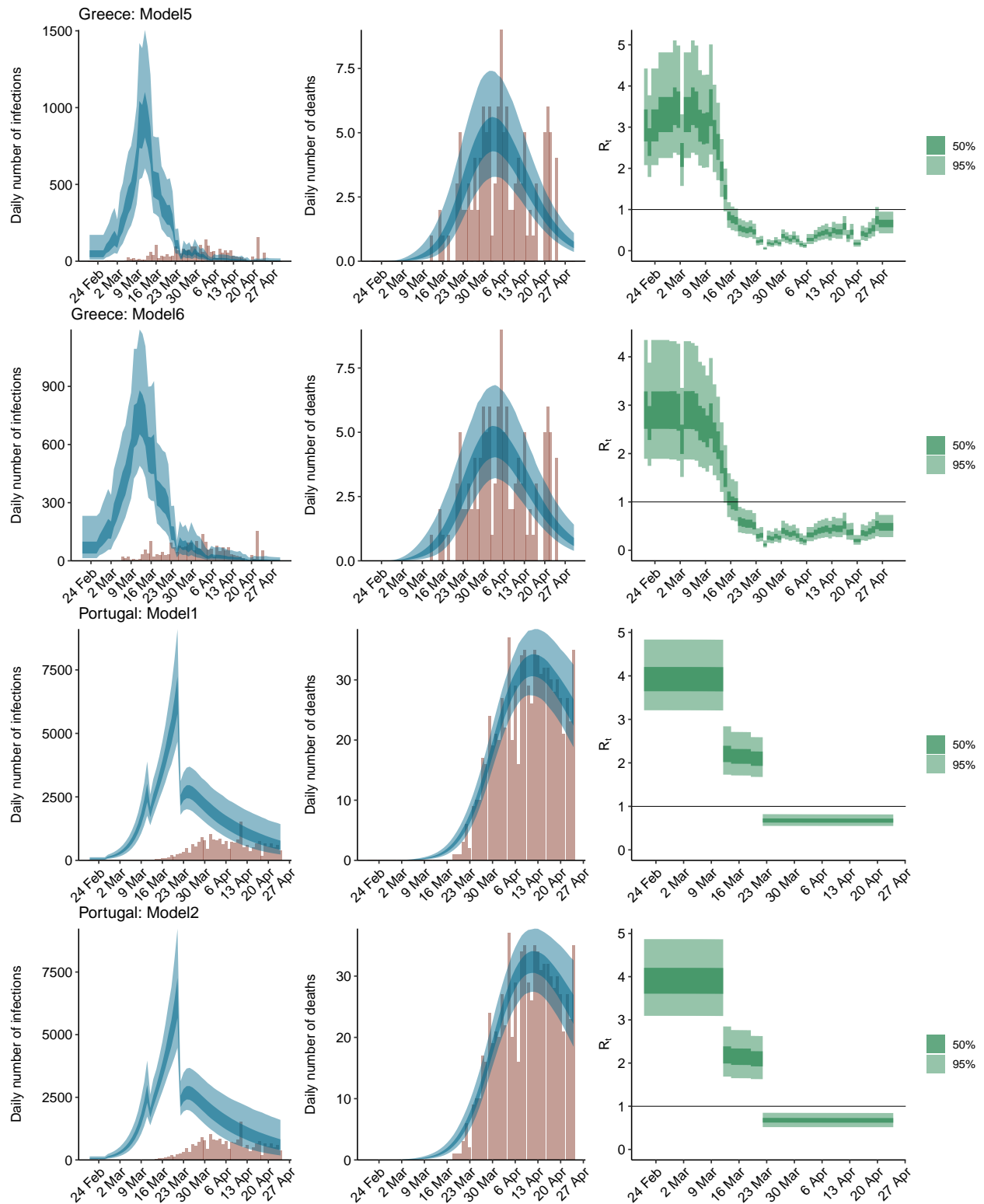




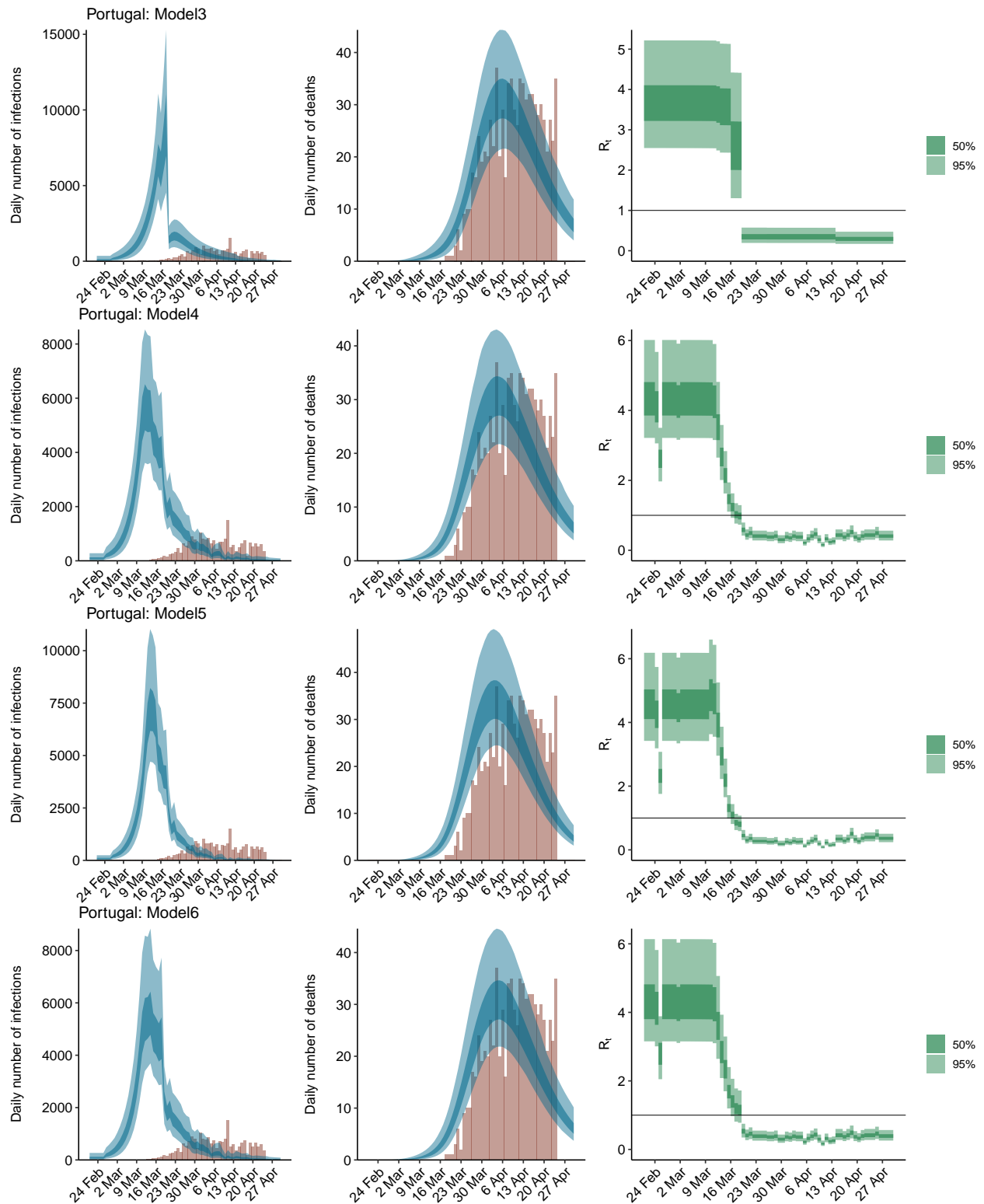


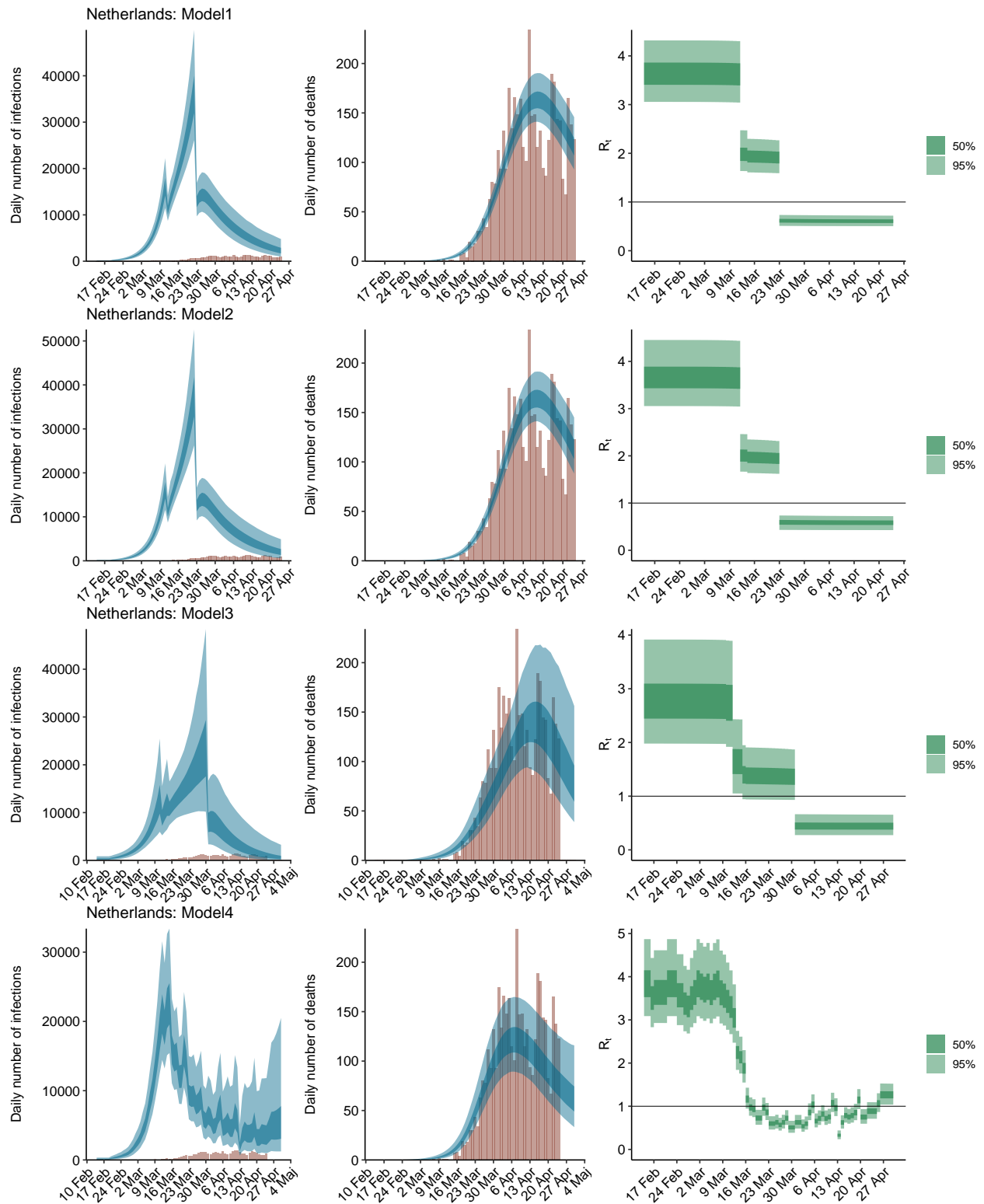


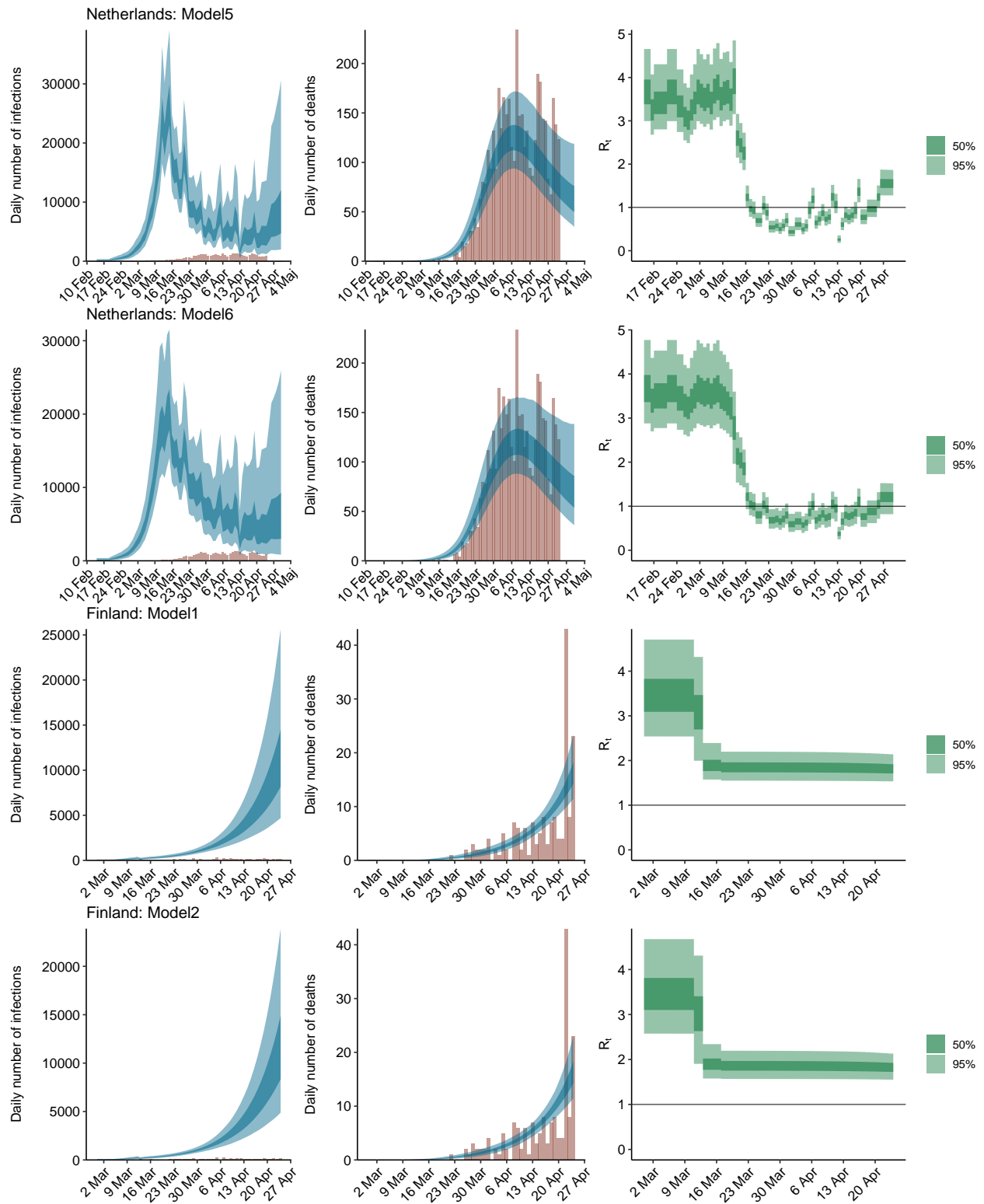


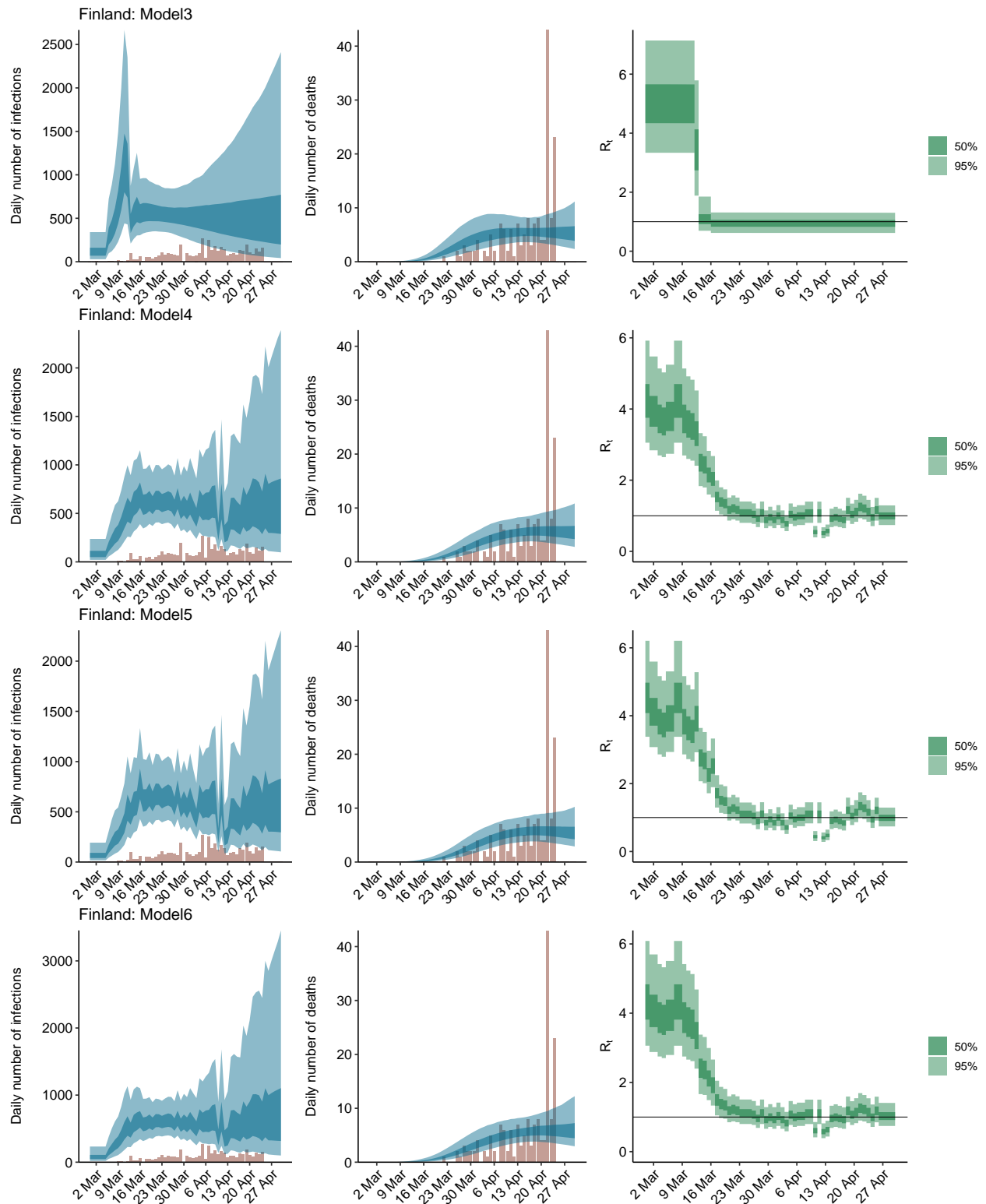












## Stan code

```
## S4 class stanmodel 'base_general_speed' coded as follows:
## data {
```

```

## int <lower=1> M; // number of countries
## int <lower=1> P; // number of covariates
## int <lower=1> N0; // number of days for which to impute infections
## int<lower=1> N[M]; // days of observed data for country m. each entry must be <= N2
## int<lower=1> N2; // days of observed data + # of days to forecast
## int cases[N2,M]; // reported cases
## int deaths[N2, M]; // reported deaths -- the rows with i > N contain -1 and should be ignored
## matrix[N2, M] f; // h * s
## matrix[N2, P] X[M];
## int EpidemicStart[M];
## real pop[M];
## real SI[N2]; // fixed pre-calculated SI using emprical data from Neil
## }
##
## transformed data {
##   vector[N2] SI_rev; // SI in reverse order
##   vector[N2] f_rev[M]; // f in reversed order
##
##   for(i in 1:N2)
##     SI_rev[i] = SI[N2-i+1];
##
##   for(m in 1:M){
##     for(i in 1:N2) {
##       f_rev[m, i] = f[N2-i+1,m];
##     }
##   }
## }
##
## parameters {
##   real<lower=0> mu[M]; // intercept for Rt
##   real<lower=0> alpha_hier[P]; // sudo parameter for the hier term for alpha
##   real<lower=0> kappa;
##   real<lower=0> y[M];
##   real<lower=0> phi;
##   real<lower=0> tau;
##   real <lower=0> ifr_noise[M];
## }
##
## transformed parameters {
##   vector[P] alpha;
##   matrix[N2, M] prediction = rep_matrix(0,N2,M);
##   matrix[N2, M] E_deaths = rep_matrix(0,N2,M);
##   matrix[N2, M] Rt = rep_matrix(0,N2,M);
##   matrix[N2, M] Rt_adj = Rt;
##
##   {
##     matrix[N2,M] cumm_sum = rep_matrix(0,N2,M);
##     for(i in 1:P){
##       alpha[i] = alpha_hier[i] - ( log(1.05) / 6.0 );
##     }
##     for (m in 1:M){
##       /*
##       for (i in 2:N0){

```

```

##      cumm_sum[i,m] = cumm_sum[i-1,m] + y[m];
##    }
##    */
##    prediction[1:NO,m] = rep_vector(y[m],NO); // learn the number of cases in the first NO days
##    cumm_sum[2:NO,m] = cumulative_sum(prediction[2:NO,m]);
##
##    Rt[,m] = mu[m] * exp(-X[m] * alpha);
##    Rt_adj[1:NO,m] = Rt[1:NO,m];
##    for (i in (NO+1):N2) {
##      /*
##      real convolution=0;
##      for(j in 1:(i-1)) {
##        convolution += prediction[j, m] * SI[i-j];
##      }
##      */
##      real convolution = dot_product(sub_col(prediction, 1, m, i-1), tail(SI_rev, i-1));
##
##      cumm_sum[i,m] = cumm_sum[i-1,m] + prediction[i-1,m];
##      Rt_adj[i,m] = ((pop[m]-cumm_sum[i,m]) / pop[m]) * Rt[i,m];
##      prediction[i, m] = Rt_adj[i,m] * convolution;
##    }
##
##    E_deaths[1, m]= 1e-15 * prediction[1,m];
##    for (i in 2:N2){
##      // for(j in 1:(i-1)){
##      //   E_deaths[i,m] += prediction[j,m] * f[i-j,m] * ifr_noise[m];
##      // }
##      E_deaths[i,m] = ifr_noise[m] * dot_product(sub_col(prediction, 1, m, i-1), tail(f_rev[m], i-1));
##    }
##  }
## }
## }
## model {
##   tau ~ exponential(0.03);
##   for (m in 1:M){
##     y[m] ~ exponential(1/tau);
##   }
##   phi ~ normal(0,5);
##   kappa ~ normal(0,0.5);
##   mu ~ normal(3.28, kappa); // citation: https://academic.oup.com/jtm/article/27/2/taaa021/5735319
##   alpha_hier ~ gamma(.1667,1);
##   ifr_noise ~ normal(1,0.1);
##   for(m in 1:M){
##     deaths[EpidemicStart[m]:N[m], m] ~ neg_binomial_2(E_deaths[EpidemicStart[m]:N[m], m], phi);
##   }
## }
##
## generated quantities {
##   matrix[N2, M] prediction0 = rep_matrix(0,N2,M);
##   matrix[N2, M] E_deaths0 = rep_matrix(0,N2,M);
##
##   {
##     matrix[N2,M] cumm_sum0 = rep_matrix(0,N2,M);
##     for (m in 1:M){

```

```

##         for (i in 2:N0){
##             cumm_sum0[i,m] = cumm_sum0[i-1,m] + y[m];
##         }
##         prediction0[1:N0,m] = rep_vector(y[m],N0);
##         for (i in (N0+1):N2) {
##             real convolution0 = 0;
##             for(j in 1:(i-1)) {
##                 convolution0 += prediction0[j, m] * SI[i-j];
##             }
##             cumm_sum0[i,m] = cumm_sum0[i-1,m] + prediction0[i-1,m];
##             prediction0[i, m] = ((pop[m]-cumm_sum0[i,m]) / pop[m]) * mu[m] * convolution0;
##         }
##
##         E_deaths0[1, m] = uniform_rng(1e-16, 1e-15);
##         for (i in 2:N2){
##             for(j in 1:(i-1)){
##                 E_deaths0[i,m] += prediction0[j,m] * f[i-j,m] * ifr_noise[m];
##             }
##         }
##     }
## }
##

```