Spatio-temporal Anomaly Detection

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Definition of Anomaly

• Earth Science definition: deviation from past behavior

$$Y(s,t) = X(s,t) - \mu(s,t)$$

Data Science definition: deviation from other values

- Spatio-temporal Anomaly: deviation of values from spatio-temporal neighbors
- Easy problem: isolated anomalies
- Hard problem: bulk anomalies (anomaly events)

	T1	T2	Т3	T4	T5	Т6
S1	24	26	22	30	31	23
S2	28	27	29	26	32	33
S3	25	29	20	26	25	22
S4	35	33	29	33	34	31
S5	33	31	28	31	24	26
S6	32	37	29	34	33	29

• Spatial neighbors: (S1,S2,S3) and (S4,S5,S6)

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• |X(S3,T3) - X(S3,T2) | > thres, |X(S3,T3) - X(S2,T3) | > thres

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• |X(S6,T2) - X(S6,T1) | > thres, |X(S6,T2) - X(S5,T2) | > thres

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• |X(S1,T5) - X(S3,T5) | > thres, |X(S2,T6) - X(S3,T6) | > thres

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S1	24	26	22	30	31	23
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S3	25	29	20	26	25	22
S4	35	33	29	33	34	31
S5	33	31	28	31	24	26
S6	32	37	29	34	33	29

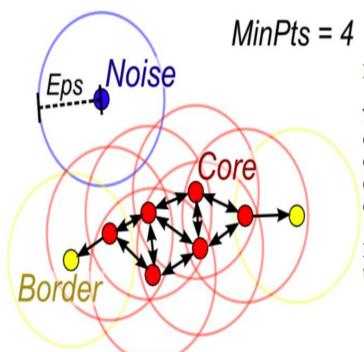
• |X(S1,T5) - X(S3,T5) | > thres, |X(S2,T6) - X(S3,T6) | > thres

Anomaly Detection

- Simplest approach: compare with spatio-temporal neighbors or climatology using threshold
- Problems: i) Results totally sensitive on threshold
 - ii) Comparison with neighbors can't catch "bulk anomalies"
 - iii) Climatology may not be available
- Alternatives: i) Clustering
 - ii) Latent variable models

Clustering: DB-SCAN

- Density-based Spatial Clustering of Applications with Noise
- Idea: for each point, identify "neighbors" in feature space, and add them in cluster.
- Those points which could not be added to any cluster outlier!
- Need to specify distance threshold



Red: Core Points

Yellow: Border points. Still part of the cluster because it's within epsilon of a core point, but not does not meet the min_points criteria

Blue: Noise point. Not assigned to a cluster

Spatio-temporal clustering: DBSCAN

- Each data-point has spatial and temporal neighbors
- Each data-point can join only the clusters of its spatial or temporal neighbors
- Joining cluster on the basis of values
- If it cannot join any such cluster, then it is an outlier/anomaly!

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Can't handle extended/bulk anomalies!

Alternative-1: Multiple scales

- Difficult to identify bulk anomalies at a single spatial/temporal scale
- Smoothen/coarsen the data at several levels
- Merge locations and consider their mean values
- Merge time-points and consider their mean values
- Repeat same process on coarsened dataset

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S5	33	31	28	31	24	26
S6	32	37	29	34	33	29

	T1	T2	T3	T4	T5	Т6
S1-S2	26	27	26	28	32	28
S2-S3	26	28	25	26	29	28
S4-S5	34	32	29	32	29	29
S5-S6	33	34	29	33	29	28

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	T1	T2	T3	T4	T5	T6
S1-S2	26	27	26	28	32	28
S2-S3	26	28	25	26	29	28
S4-S5	34	32	29	32	29	29
S5-S6	33	34	29	33	29	28

Anomalies may get smoothed out!

Alternative-2: latent variable models

- At each (s,t) define discrete latent variable Z(s,t)
- Z(s,t) can take two values (anomaly/ no anomaly) or three values (no anomaly/positive anomaly/negative anomaly)
- X(s,t) is a random variable with value known
- $X(s,t) \sim f(p_{s,t,k})$ where k = Z(s,t)
- Z(s,t) may also depend on Z(s,t-1) or Z(s',t) where (s,s') are neighbors
- Values of Z estimated by Gibbs Sampling

Alternative-2: latent variable models

Example:

```
Observation of X(s,t) = 34.3
 f: Gaussian distribution
 Ps,t,1 = [30,10], ps,t,2 = [8, 20]
 prob(X(s,t)=34.3 \mid Z(s,t)=1) = N(34.3; [30,10])
 prob(X(s,t)=34.3 \mid Z(s,t)=2) = N(34.3; [8,20])
 prob(Z(s,t) = 1 \mid X(s,t)=34.3) = ???? (Bayes Theorem)
Z(s,t) should also depend on Z(s,t-1), Z(s',t) etc for bulk anomalies
```

Alternative-2: latent variable models

- Can handle bulk anomalies
- Used to identify "anomaly events" like heat waves or droughts

	T1	T2	Т3	T4	T5	Т6	Z	T1	T2	Т3	T4	T5	Т6
S1	24	26	22	30	31	23	S1	1	1	1	2	2	1
S2	28	27	29	26	32	33	S2	1	1	1	1	2	2
S3	25	29	20	26	25	22	S3	1	1	3	1	1	1
S4	35	33	29	33	34	31	S4	1	1	1	1	1	1
S 5	33	31	28	31	24	26	S 5	1	1	1	1	2	2
S6	32	37	29	34	33	29	S6	1	2	1	1	1	1