

Richardson Extrapolation (Extrapolation to the Limit)  
Romberg Integration and Adaptive Quadrature

### I. Richardson Extrapolation

If we have a composite rule with degree of accuracy  $p - 1$ , we can write

$$I(f) = I_n(f) + Ch^p + \mathcal{O}(h^{p+1}),$$

where  $h$  is proportional to  $1/n$  and  $C$  is a constant which depends on  $f$ . Taking two different values for  $n$  (leading to two different values for  $h$ ), and combining them in the following way, we have

$$h_2^p I(f) - h_1^p I(f) = h_2^p I_{n_1}(f) - h_1^p I_{n_2}(f) + Ch_2^p h_1^p - Ch_1^p h_2^p + \mathcal{O}(h_1^p h_2^{p+1}, h_2^p h_1^{p+1})$$

which simplifies to

$$I(f) = \frac{h_2^p I_{n_1}(f) - h_1^p I_{n_2}(f)}{h_2^p - h_1^p} + \mathcal{O}(h_i^{p+1}).$$

We have just derived a new approximation of  $I(f)$  which is more accurate than the previous approximations. If  $h_1 = mh_2$  for some integer  $m$ , then we have a new rule:

$$I(f) = \frac{m^p I_{mn}(f) - I_n(f)}{m^p - 1} + \mathcal{O}(h^{p+1}).$$

We can also use this technique to estimate the error by taking a different combination of the formulas with  $I_{n_1}$  and  $I_{n_2}$  to eliminate  $I(f)$  and solve for  $C$ . We get the following estimate:

$$C \approx \frac{I_{n_1}(f) - I_{n_2}(f)}{h_2^p - h_1^p}.$$

### II. Romberg Integration

When written out carefully, the error for the Composite Trapezoid Rule, looks like:

$$E_n(f) = D_1 h^2 + D_2 h^4 + D_3 h^6 + \sum_{k=4}^{\infty} D_k h^{2k}.$$

Applying Richardson Extrapolation to two Trapezoid approximations ‘knocks-out’ the first term of the error expansion. Let

$$R_{k,1} = I_{2^k}(f), \quad \text{i.e. Trapezoid rule on } 2^k \text{ intervals.}$$

Let  $h_k = (b - a)/2^k$ , then one can show

$$\begin{aligned} R_{0,1} &= \frac{b-a}{2} (f(a) + f(b)) \\ R_{k+1,1} &= \frac{1}{2} \left( R_{k,1} + h_k \sum_{i=1}^{2^k} f(a + (2i-1)h_{k+1}) \right). \end{aligned}$$

Next, apply Richardson Extrapolation to the estimates  $R_{k,1}$  and  $R_{k+1,1}$  (note that  $h_k = 2h_{k+1}$ ). So we get a new approximation (call it  $R_{k+1,2}$ ):

$$R_{k+1,2} = \frac{4R_{k+1,1} - R_{k,1}}{3}.$$

Now all these  $R_{k,2}$  have degree of accuracy 3 and we can again apply Richardson Extrapolation to  $R_{k,2}$  and  $R_{k+1,2}$ , etc.. So, in general, we get:

$$R_{k+1,j+1} = \frac{4^j R_{k+1,j} - R_{k,j}}{4^j - 1}.$$

Note  $R_{k,j}$  has degree of accuracy  $2j - 1$ . Also, the number of function evaluations to just compute  $R_{N,1}$  is the same as the cost of computing  $R_{N,N+1}$  using Romberg Integration. Also, the computations can be ordered in such a way that this becomes an adaptive-type scheme. The usual stopping criterion is when  $R_{N,N+1} - R_{N-1,N}$  and  $R_{N-1,N} - R_{N-2,N-1}$  are both within tolerance (each row is computed as needed).

### III. Adaptive Quadrature

This version of adaptive quadrature is based on Simpson's rule and uses the error estimate from Richardson Extrapolation to estimate the error. We write

$$I(a, b) = \int_a^b f(x) dx,$$

$$S(a, b) = \frac{b-a}{6}(f(a) + 4f(m) + f(b)), \quad m = (a+b)/2,$$

and

$$S_2(a, b) = S(a, m) + S(m, b).$$

So we have for all  $a$  and  $b$ , with  $h = (b-a)/2$ :

$$I(a, b) = S(a, b) - \frac{h^5}{90}f^{(4)}(\zeta),$$

and

$$I(a, b) = S_2(a, b) - \frac{1}{16} \frac{h^5}{90}f^{(4)}(\tilde{\zeta}).$$

So we have the estimate

$$I(a, b) - S_2(a, b) \approx \frac{1}{15}(S(a, b) - S_2(a, b)).$$

Let  $E(a, b) = S(a, b) - S_2(a, b)$ .

Now, assume we want to estimate  $I(a, b)$  to an accuracy of  $\delta$ . The procedure is as follows:

1. Compute  $S(a, b)$  and  $S_2(a, b)$  (this can be done with 5 function evaluations)
2. If  $|E(a, b)| \leq 15\delta$  then we are done, take the value as either  $S_2(a, b)$  or  $S_2(a, b) + \frac{1}{15}E(a, b)$ .
3. Otherwise, repeat this procedure on each of  $I(a, m)$  and  $I(m, b)$  to estimate them to an accuracy of  $\delta/2$ .

The only trick to programming this is to make sure you don't evaluate the function any more than you have to.

An example: suppose we want to approximation  $I = \int_0^1 e^x dx = 1.7182818$  with a value  $V$  so that  $|I - V| \leq \delta$ , where  $\delta = 2 \times 10^{-6}$ . Start with  $V = 0$ .  
Level 1, Estimate  $I(0, 1)$

$$S(0, 1) = \frac{1}{6}(e^0 + 4e^{0.5} + e^1) = 1.718861... \quad (1)$$

$$S(0, \frac{1}{2}) = \frac{1}{12}(e^0 + 4e^{0.25} + e^{0.5}) = 0.648735... \quad (2)$$

$$S(\frac{1}{2}, 1) = \frac{1}{12}(e^{0.5} + 4e^{0.75} + e^1) = 1.069583... \quad (3)$$

$$S_2(0, 1) = 1.718318... \quad (4)$$

Now we estimate the error

$$|E(0, 1)| \approx \frac{1}{15}|S_2(0, 1) - S(0, 1)| = 3.6E - 5,$$

This is not within tolerance ( $\delta$ ), so we split the interval.

Level 2 Left, Estimate  $I(0, \frac{1}{2})$

$$S(0, \frac{1}{2}) = 0.648735... \quad (5)$$

$$S(0, \frac{1}{4}) = 0.284025... \quad (6)$$

$$S(\frac{1}{4}, \frac{1}{2}) = 0.364696... \quad (7)$$

$$S_2(0, \frac{1}{2}) = 0.648722... \quad (8)$$

Now we estimate the error

$$|E(0, \frac{1}{2})| \approx 8.73 \times 10^{-7}$$

This is less than  $\delta/2$  we take

$$V = V + S_2(0, \frac{1}{2}) + \frac{1}{15}(S_2(0, \frac{1}{2}) - S(0, \frac{1}{2})) = 0.648721...$$

Note: to increase the accuracy we use the Richardson Extrapolation value for the estimate of  $I(0, \frac{1}{2})$ .

Level 2 Right, Estimate  $I(\frac{1}{2}, 1)$

$$S(\frac{1}{2}, 1) = 1.069583... \quad (9)$$

$$S(\frac{1}{2}, \frac{3}{4}) = 0.468279... \quad (10)$$

$$S(\frac{3}{4}, 1) = 0.601282... \quad (11)$$

$$S_2(\frac{1}{2}, 1) = 1.069562... \quad (12)$$

with an error of

$$|E(\frac{1}{2}, 1)| \approx 1.43 \times 10^{-7}$$

This is not less than  $\delta/2$  so we split again.

Level 3 Left, Estimate  $I(\frac{1}{2}, \frac{3}{4})$

$$S(\frac{1}{2}, \frac{3}{4}) = 0.468279... \quad (13)$$

$$S(\frac{1}{2}, \frac{5}{8}) = 0.219524... \quad (14)$$

$$S(\frac{5}{8}, \frac{3}{4}) = 0.248754... \quad (15)$$

$$S_2(\frac{1}{2}, \frac{3}{4}) = 0.468278... \quad (16)$$

with an error of

$$|E(\frac{1}{2}, \frac{3}{4})| \approx 3.96 \times 10^{-8}$$

which is within the tolerance of  $\delta/4$  so we take

$$V = V + S_2(\frac{1}{2}, \frac{3}{4}) + \frac{1}{15}(S_2(\frac{1}{2}, \frac{3}{4}) - S(\frac{1}{2}, \frac{3}{4})) = 1.117000...$$

Level 3 Right, Estimate  $I(\frac{3}{4}, 1)$

$$S(\frac{3}{4}, 1) = 0.601282... \quad (17)$$

$$S(\frac{3}{4}, \frac{7}{8}) = 0.281875... \quad (18)$$

$$S(\frac{7}{8}, 1) = 0.319406... \quad (19)$$

$$S_2(\frac{3}{4}, 1) = 0.601281... \quad (20)$$

with an error of

$$|E(\frac{3}{4}, 1)| \approx 5.08 \times 10^{-8}$$

which is within the tolerance of  $\delta/4$ , so we take

$$V = V + S_2(\frac{3}{4}, 1) + \frac{1}{15}(S_2(\frac{3}{4}, 1) - S(\frac{3}{4}, 1)) = 1.718281...$$

For the actual error, we have  $|I - V| = 5.3 \times 10^{-9}$ . It is common for smooth integrands to get a much smaller error than needed.

This is the way a computer program would do this, except that it would be more careful to save and reuse the function evaluations. In pseudo-code, we would have a subfunction like this

```
V = adsimp(a,b,fa,fm,fb,V0,delta)

h = b-a
f1 = f(a + h/4)           % left-half midpoint
f2 = f(b - h/4)           % right-half midpoint
s1 = h*(fa + 4*f1 + fm)/12 % left-half estimate
s2 = h*(fm + 4*f2 + fb)/12 % right-half estimate
s2 = s1+s2
err = (s2-V0)/15
if (abs(err)<delta)         % estimate is within tolerance, so accept it
    V = s2 + err
else                       % split interval into two pieces
    m = a + h/2
    V1 = adsimp(a,m,fa,f1,fm,s1,delta/2)
    V2 = adsimp(m,b,fm,f2,fb,sr,delta/2)
    V = V1 + V2
endif
```

To call this you would use

```
% main program

fa = f(a)
fm = f((a+b)/2)
fb = f(b)
V0 = (fa + 4*fm + fb)*(b-a)/6

V = adsimp(a,b,fa,fm,fb,V0,delta)
```

| Errors for $I = \int_0^1 \sqrt{x} dx$ . |        |         |         |         |         |
|---|--------|---------|---------|---------|---------|
| Function Evals =<br>Method              | 1      | 2       | 3       | 4       | 5       |
| Closed N-C                              | -      | -1.7e-1 | -2.9e-2 | -1.9e-2 | -8.9e-3 |
| Open N-C                                | 4.0e-2 | 3.0e-2  | 8.3e-3  | 6.9e-3  |         |
| Comp. Trap                              | -      | -1.7e-1 | -6.3e-2 | -3.5e-2 | -2.3e-2 |
| Comp. Simp                              | -      | -       | -2.9e-2 | -       | -1.0e-2 |
| Romberg                                 | -      | -       | -2.9e-2 | -       | -8.9e-3 |
| Gauss-Leg                               | 4.0e-2 | 7.2e-3  | 2.5e-3  | 1.2e-3  | 6e-4    |

| Errors for $I = \int_0^1 \sin x dx$ . |        |         |         |          |         |
|---------------------------------------|--------|---------|---------|----------|---------|
| Function Evals =<br>Method            | 1      | 2       | 3       | 4        | 5       |
| Closed N-C                            | -      | -3.9e-2 | 1.6e-4  | 7.3e-5   | -2.5e-7 |
| Open N-C                              | 2.0e-2 | 1.3e-2  | -1.4e-4 | -1.0e-4  |         |
| Comp. Trap                            | -      | -3.9e-2 | -9.6e-3 | -4.3e-3  | -2.4e-3 |
| Comp. Simp                            | -      | -       | 1.6e-4  | -        | 1.0e-5  |
| Romberg                               | -      | -       | 1.6e-4  | -        | -2.5e-7 |
| Gauss-Leg                             | 2.0e-2 | -1.1e-4 | 2.4e-7  | -2.7e-10 | 1.8e-13 |

| Errors for $I = \int_0^{10} \sin x dx$ . |       |       |      |      |        |
|--|-------|-------|------|------|--------|
| Function Evals =<br>Method               | 1     | 2     | 3    | 4    | 5      |
| Closed N-C                               | -     | -4.6  | -9.1 | -1.8 | 1.9    |
| Open N-C                                 | -11.4 | -0.92 | 11.6 | 6.4  |        |
| Comp. Trap                               | -     | -4.6  | -8.0 | -2.1 | -1.1   |
| Comp. Simp                               | -     | -     | -9.1 | -    | 1.2    |
| Romberg                                  | -     | -     | -9.1 | -    | 1.9    |
| Gauss-Leg                                | -11.4 | 7.4   | -2.1 | 0.29 | -0.022 |