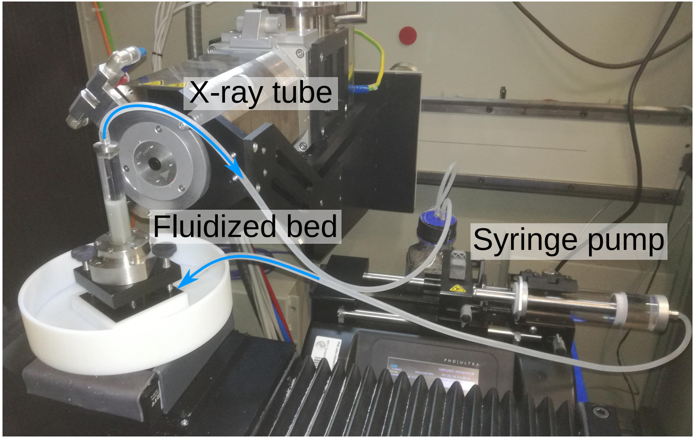
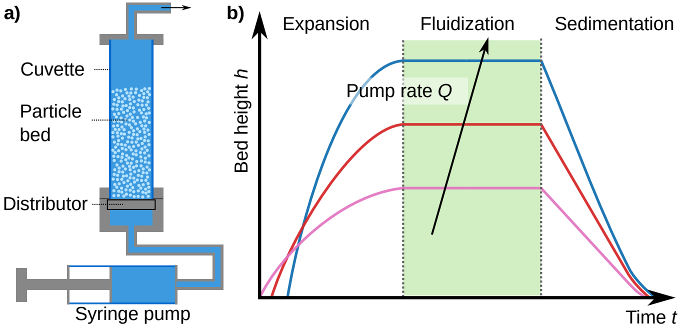
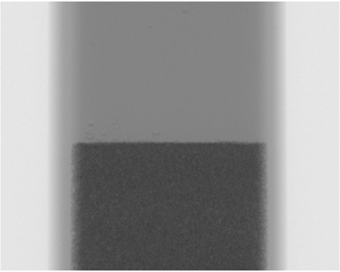
Experimental validation of X-DFA: A suspension of sedimenting particles

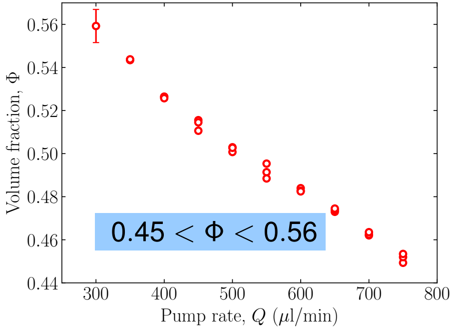


Experimental validation of X-DFA: A suspension of sedimenting particles

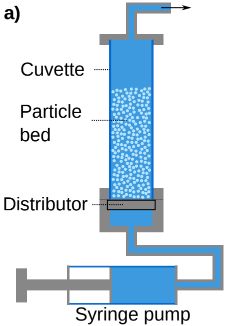


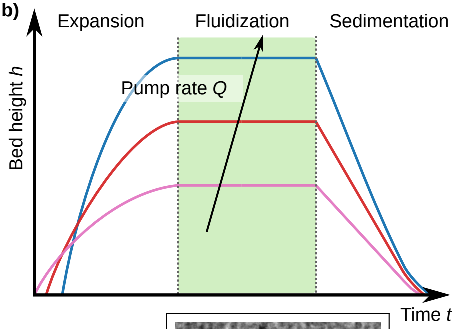
X-ray radiography



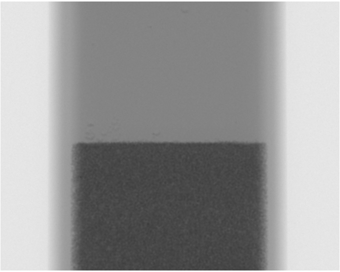


Experimental validation of X-DFA: A suspension of sedimenting particles

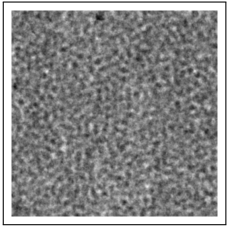


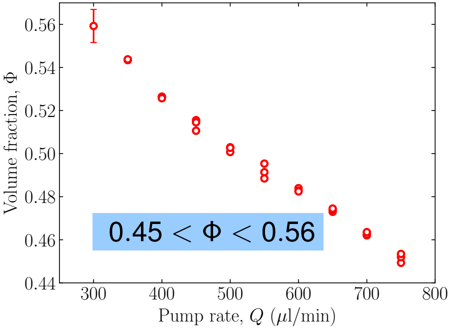


X-ray radiography

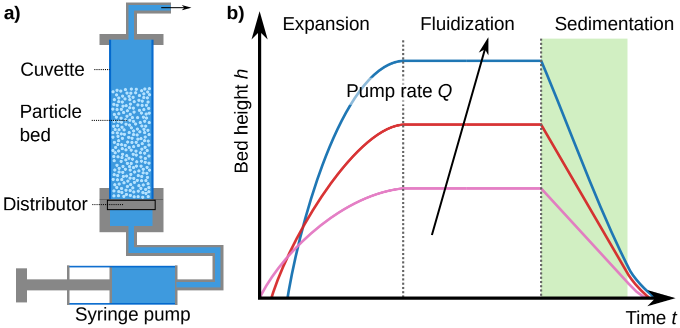


No reliable reference velocity!

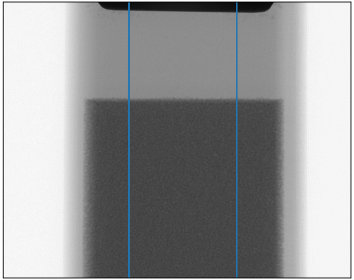




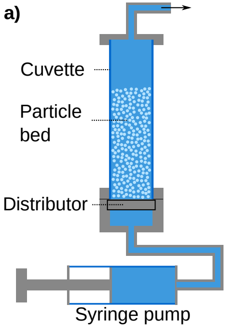
Experimental validation of X-DFA: A suspension of sedimenting particles

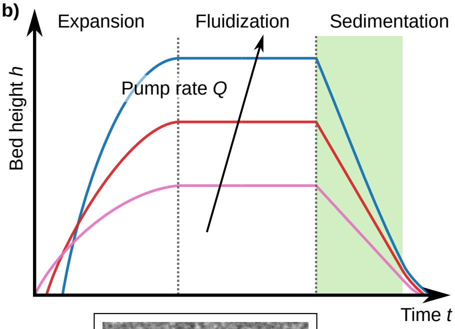


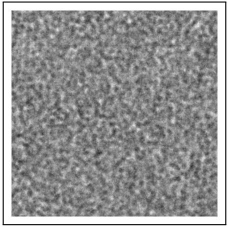
X-ray radiography



Experimental validation of X-DFA: A suspension of sedimenting particles

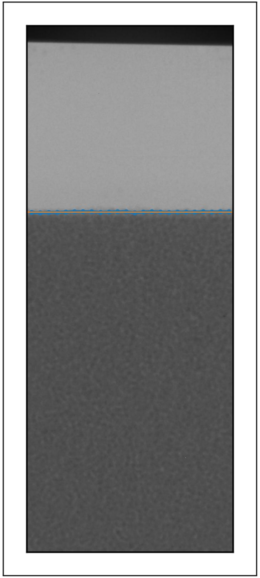






Comparison of $\langle v \rangle_{\mathrm{xdfa}}$ and $\langle v \rangle_{\mathrm{front}}$

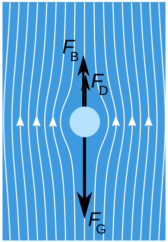
X-ray radiography

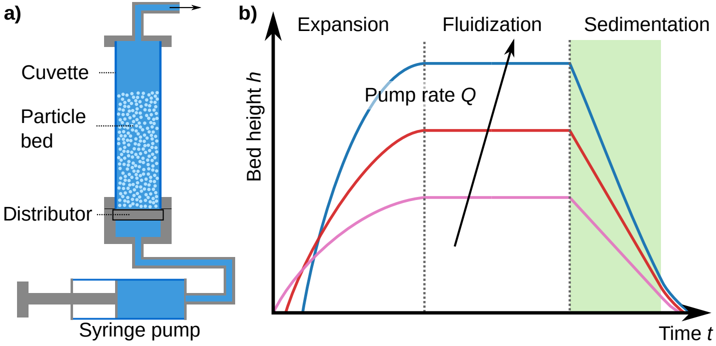


Liquid fluidized bed: Richardson-Zaki law

Gravitation Buoyancy Drag

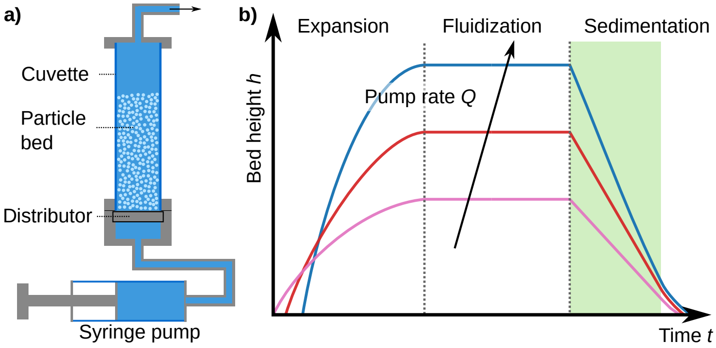
$$F_G = F_B + F_D$$





$$\frac{\langle v \rangle_{\text{fluid}}}{v_{\text{Stokes}}} = (1 - \Phi)^n$$

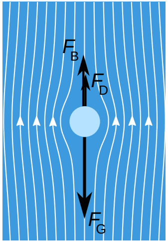
Liquid fluidized bed: Richardson-Zaki law

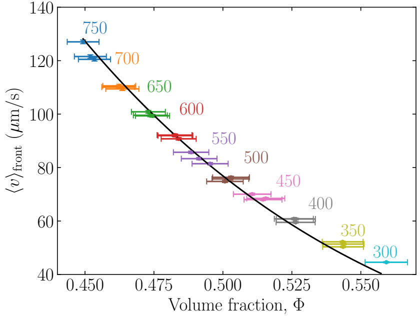


$$\frac{\langle v \rangle_{\text{front}}}{v_{\text{Stokes}}} = (1 - \Phi)^n$$

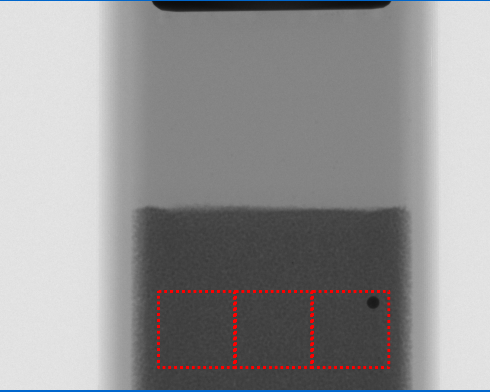
Gravitation Buoyancy Drag

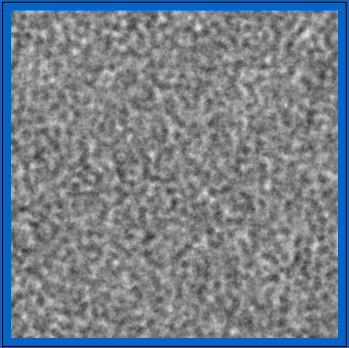
$$F_G = F_B + F_D$$



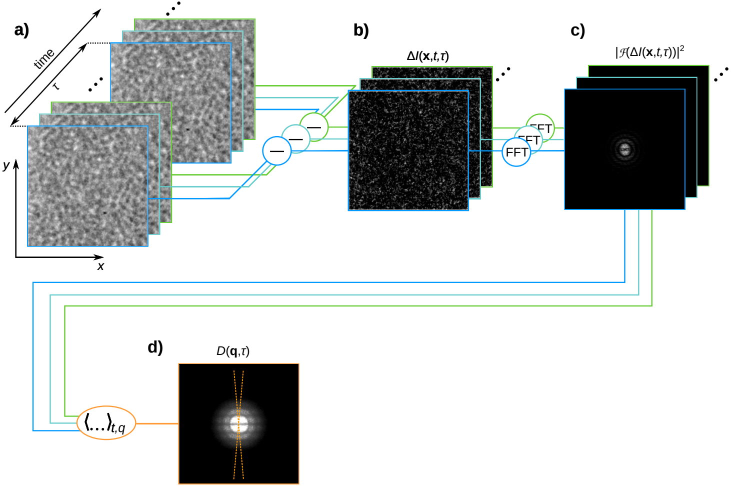


X-ray Digital Fourier Analysis of a suspension of sedimenting particles



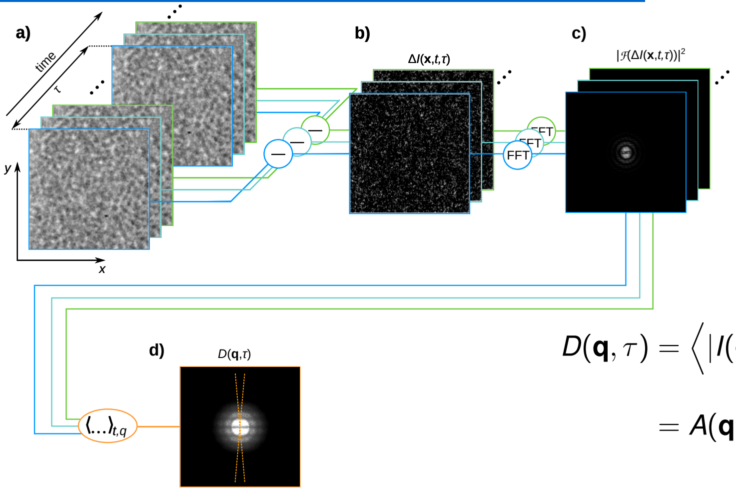


The image structure function $D(\mathbf{q}, \tau)$



In collaboration with Manuel Escobedo, University of Düsseldorf

The image structure function $D(\mathbf{q}, \tau)$



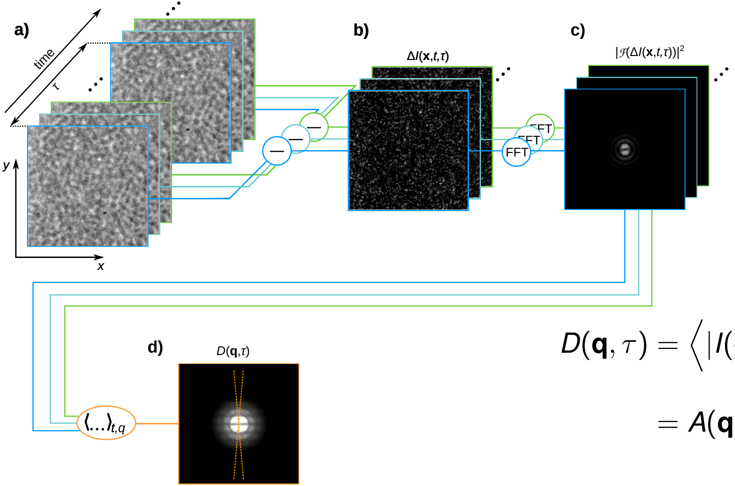
$$D(\mathbf{q}, \tau) = \left\langle |I(\mathbf{q}, t+\tau) - I(\mathbf{q}, t)|^2 \right\rangle_t$$

$$= A(\mathbf{q}) \left[1 - \frac{\langle I^*(\mathbf{q}, t) I(\mathbf{q}, t+\tau) \rangle_t}{\langle |I(\mathbf{q}, t)|^2 \rangle_t} \right] + B(\mathbf{q})$$

- $D(\mathbf{q}, \tau \to 0) = B(\mathbf{q})$
- $D(\mathbf{q}, \tau \to \infty) = A(\mathbf{q}) + B(\mathbf{q})$

In collaboration with Manuel Escobedo, University of Düsseldorf

The image structure function $D(\mathbf{q}, \tau)$



Linear space invariant imaging

$$f(\mathbf{q}, \tau) = \frac{\langle \rho^*(\mathbf{q}, t)\rho(\mathbf{q}, t+\tau)\rangle_t}{\langle |\rho(\mathbf{q}, t)|^2\rangle_t}$$

Intermediate scattering function

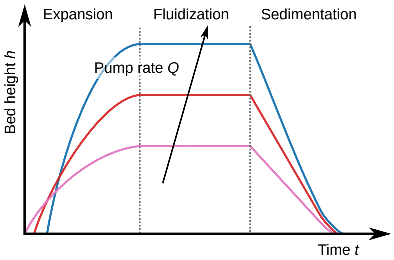
$$D(\mathbf{q}, \tau) = \left\langle |I(\mathbf{q}, t+\tau) - I(\mathbf{q}, t)|^2 \right\rangle_t$$

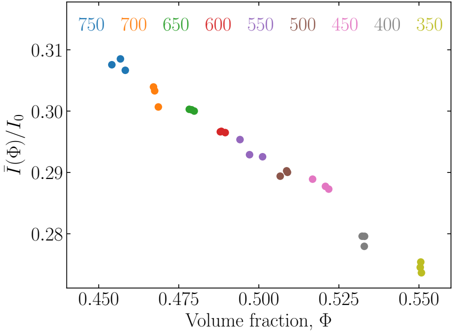
$$= A(\mathbf{q})\left[1 - \frac{\left\langle I^*(\mathbf{q}, t) I(\mathbf{q}, t+\tau)\right\rangle_t}{\left\langle |I(\mathbf{q}, t)|^2\right\rangle_t}\right] + B(\mathbf{q})$$

- $D(\mathbf{q}, \tau \to 0) = B(\mathbf{q})$
- $D(\mathbf{q}, \tau \to \infty) = A(\mathbf{q}) + B(\mathbf{q})$

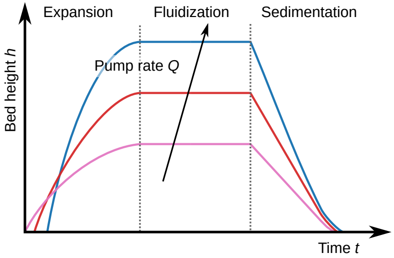
In collaboration with Manuel Escobedo, University of Düsseldorf

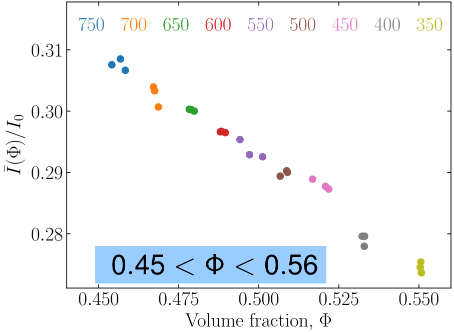
X-ray imaging – Linear space invariant?





X-ray imaging – Linear space invariant?

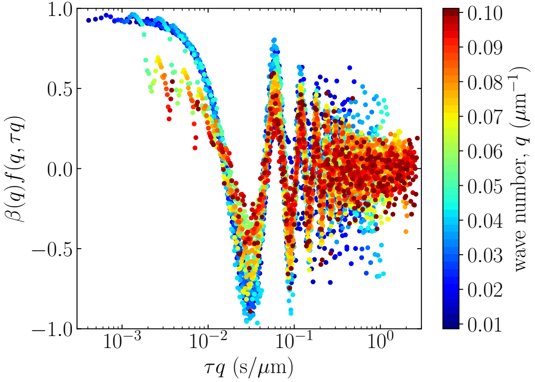


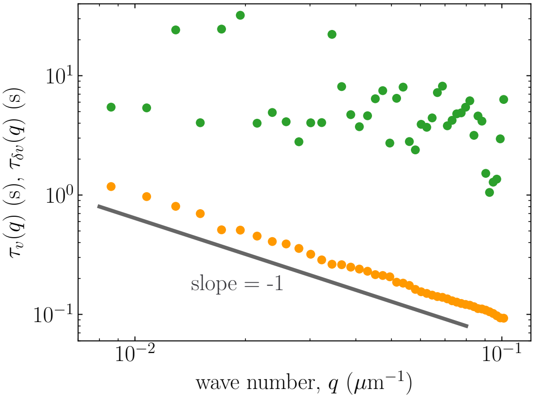


X-DFA for a suspension of sedimenting particles

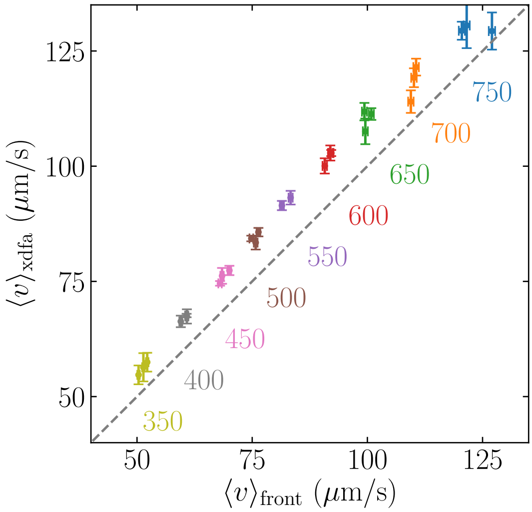
$$f(q,\tau) = \cos(q\langle v_s\rangle\tau)\exp\left(-\frac{1}{2}q^2\delta v^2\tau^2\right)$$

$$\langle v_s\rangle = \langle\Delta r\rangle/\tau_\nu, \langle\delta v\rangle = \langle\delta r\rangle/\tau_{\delta\nu}$$



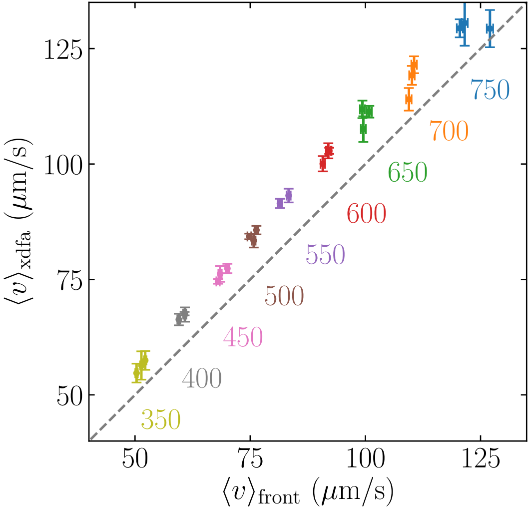


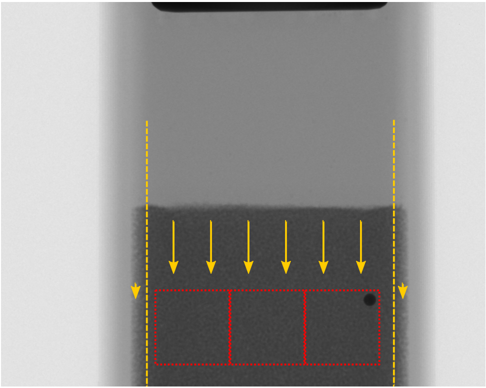
Front tracking vs. X-DFA



$\langle v \rangle_{\mathrm{xdfa}} > \langle v \rangle_{\mathrm{front}}$ by 9.4%

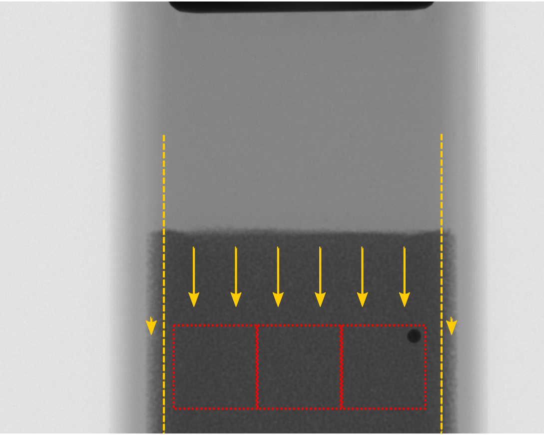
Front tracking vs. X-DFA





$\langle v \rangle_{\mathrm{xdfa}} > \langle v \rangle_{\mathrm{front}}$ by 9.4%

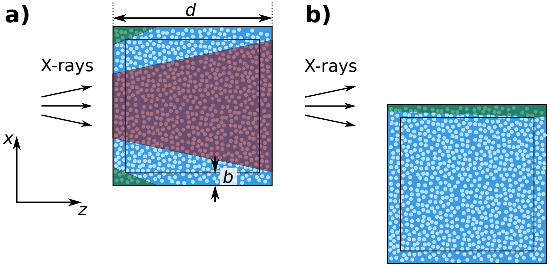
Estimate width of boundary layer



$\langle v \rangle_{\text{xdfa}} > \langle v \rangle_{\text{front}}$ by 9.4%

$\langle v \rangle_{\text{xdfa}}$ takes two layers into account

$\langle v \rangle_{\text{front}}$ takes four layers into account



Estimation:

Boundary velocity = 0

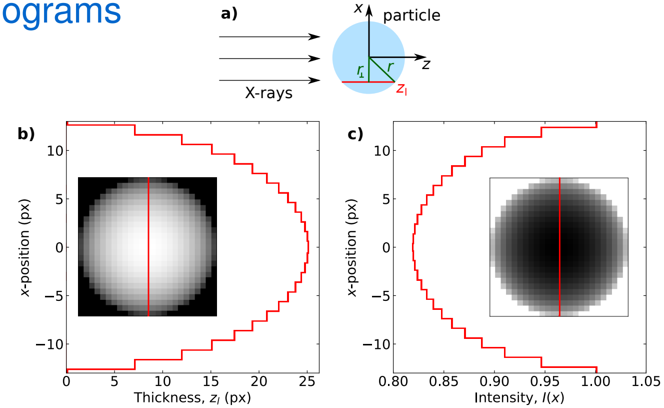
Else = const.

$\rightarrow b \approx 3$ particle diameters

Thank you for your attention!

Backup slides

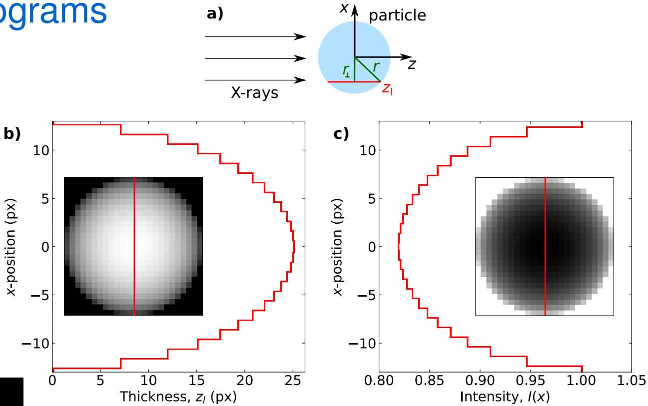
Synthetic radiograms

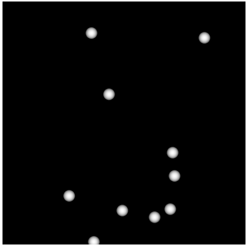


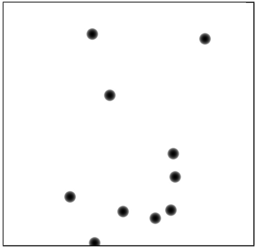
Beer-Lambert

$$I(z_l) = I_0 \exp(-\mu z)$$

Synthetic radiograms







Beer-Lambert

$$I(z_l) = I_0 \exp(-\mu z)$$

Linear space invariant imaging

Image correlation function

$$g(\mathbf{q},\tau) = \frac{\langle I^*(\mathbf{q},t)I(\mathbf{q},t+\tau)\rangle_t}{\langle |I(\mathbf{q},t)|^2\rangle_t}$$

Linear space invariant imaging

Image correlation function

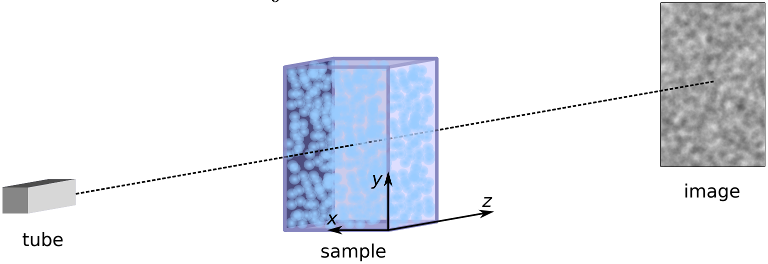
$$g(\mathbf{q}, \tau) = \frac{\langle I^*(\mathbf{q}, t) I(\mathbf{q}, t+\tau)\rangle_t}{\langle |I(\mathbf{q}, t)|^2\rangle_t}$$

Intermediate scattering function

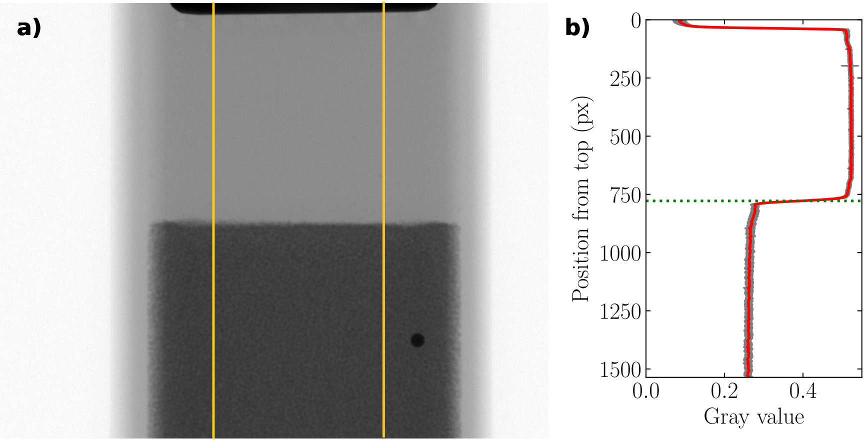
$$f(\mathbf{q}, \tau) = \frac{\langle \rho^*(\mathbf{q}, t) \rho(\mathbf{q}, t+\tau)\rangle_t}{\langle |\rho(\mathbf{q}, t)|^2\rangle_t}$$

Linear space-invariant imaging:

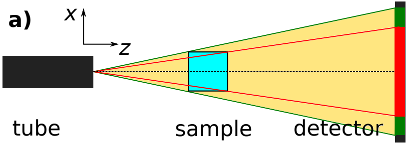
$$I(\mathbf{r}, t) = I_0 + \int \mathrm{d}\mathbf{r}' \, \mathrm{d}z' \, T(\mathbf{r} - \mathbf{r}', -z') c(\mathbf{r}', z', t)$$

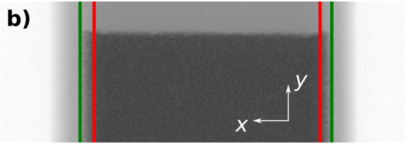


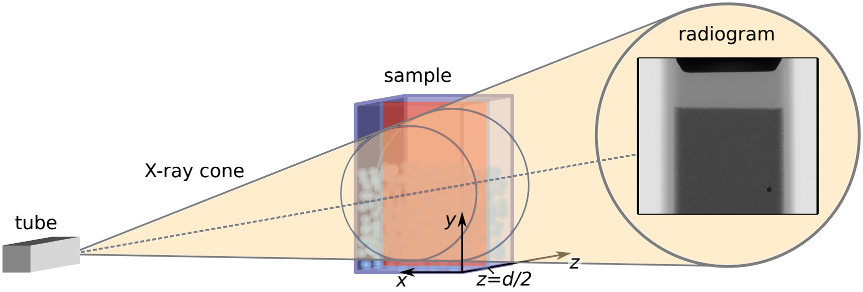
Tracking of particle front



Tracking of particle front







Tracking of particle front