

Filling radius and reach of isometrically embedded metric spaces

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- Definition of the Filling Radius
- Most significant results
- Submersions and submetries
- Lower bound
- Reach of the Kuratowski embedding
- Wasserstein Space: basic definitions
- Reach of the Wasserstein embedding

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Given $r > 0$, we will denote by $U_r(M)$ the r -neighbourhood of M in $L^\infty(M)$, and by $\iota_r: M \hookrightarrow U_r(M)$ the inclusion.

For a given coefficient ring \mathbb{F} , consider the homomorphism induced in n -homology by the inclusion

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Definition (Filling Radius)

The filling radius of M , denoted by $\text{FillRad}(M)$, is the infimum of those $r > 0$ for which $\iota_{r,*}([M]) = 0$, where $[M]$ is the fundamental class of M .

Most significant results

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Theorem 2 (Katz, 1983)

Let M be a closed connected manifold, then

$$\text{FillRad}(M) \leq \frac{1}{3} \text{diam}(M).$$

Theorem 3 (Wilhelm, 1992)

Let \mathbb{S}^n denote the unit sphere in \mathbb{R}^{n+1} , and let \mathcal{M} denote the class of closed, Riemannian n -manifolds with sectional curvature ≥ 1 . For all $M \in \mathcal{M}$,

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Theorem 4 (Yokota, 2013)

For any n -dimensional Alexandrov space X of curvature ≥ 1 with $\partial X = \emptyset$, either $\text{FillRad}(X) < \text{FillRad}(\mathbb{S}^n)$ or X is isometric to the round sphere \mathbb{S}^n .

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- $\text{FillRad}(CaP^2) \geq \frac{1}{2} \arccos\left(-\frac{1}{9}\right).$
- $\text{FillRad}(\mathbb{H}P^n) \geq \frac{1}{2} \arccos\left(-\frac{1}{5}\right).$

Submersions

Definition (Riemannian submersion)

A differentiable map $\pi: M^{m+n} \rightarrow B^n$ is called **submersion** if π is surjective, and for all $p \in M$, $d\pi_p: T_p M \rightarrow T_{\pi(p)} B$ has rank n . If M and B have Riemannian metrics, the submersion π is said to be Riemannian if, for all $p \in M$, $d\pi_p: T_p M \rightarrow T_{\pi(p)} B$ preserves the lengths of vectors orthogonal to F_p , where $F_p := \pi^{-1}(p)$.

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Theorem 5 (C. & Guijarro, 2022)

Let $\pi: M \rightarrow B$ be a Riemannian submersion with $\dim M > \dim B$. Then

$$\text{FillRad}(M) \leq \frac{1}{2} \max_{b \in B} \{\text{diam } \pi^{-1}(b)\}, \quad (1)$$

where the diameter of each fiber is considered in the extrinsic metric.

Submetries

Recall that a submetry between metric spaces is a map $\pi: X \rightarrow B$ such that for every $p \in X$, any closed ball $B(p, r)$ of radius $r > 0$ centred at p maps onto the ball $B(\pi(p), r)$. It is a *purely metric version* of Riemannian submersions.

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Corolary 5.1 (C. & Guijarro, 2022)

Let (X, \hat{d}_X) be a metric manifold (i.e, a closed manifold with a distance), (Y, d_Y) a metric space and $\pi: X \rightarrow Y$ a submetry between them. Thus

$$\text{FillRad}(X) \leq \frac{1}{2} \max_{y \in Y} \{\text{diam } \pi^{-1}(y)\}.$$

More corolaries

Corolary 5.2 (C. & Guijarro, 2022)

For B, F closed Riemannian manifolds, let $f: B \rightarrow (0, \infty)$ be a smooth function, and $M = B \times_f F$ the warped product over B with fiber F . Then

$$\text{FillRad}(M) \leq \min\{\text{FillRad}(B), \frac{1}{2} \max f \cdot \text{diam } F\}.$$

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Corolary 5.3 (C. & Guijarro, 2022)

Suppose M is a Riemannian manifold admitting a singular Riemannian foliation \mathcal{F} with closed leaves. Then

$$\text{FillRad}(M) \leq \frac{1}{2} \max_{N \in \mathcal{F}} \{\text{diam } N\}.$$

Lower bound

Definition (Injectivity radius)

Let (M^n, g) a Riemannian manifold, then

- 1 for $p \in M$, the **injectivity radius at p** , $\text{inj}_M(p)$, is defined as follows

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- 2 the **injectivity radius of M** is defined as follows

$$\text{inj}_M = \inf_{p \in M} \text{inj}_M(p).$$

Theorem 6 (Greene & Petersen, 1992 // C. & Guijarro, 2022)

Let M be a closed Riemannian manifold with injectivity radius $\text{inj } M$ and such that $\text{sec} \leq \Delta$, where $\Delta \geq 0$. Then

$$\text{FillRad}(M) \geq \frac{1}{4} \min \left\{ \text{inj } M, \frac{\pi}{\sqrt{\Delta}} \right\}, \quad (2)$$

where $\pi/\sqrt{\Delta}$ is understood as ∞ whenever $\Delta = 0$.

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Corolary 6.1

Let $\pi : M \rightarrow B$ a Riemannian submersion between closed manifolds. Then

$$\frac{1}{2} \min \left\{ \text{inj } M, \frac{\pi}{\sqrt{\Delta}} \right\} \leq \max_{b \in B} \{\text{diam } \pi^{-1}(b)\},$$

where Δ is an upper positive curvature bound for sec_M .

Reach of the Kuratowski embedding

Definition

Let (X, d) be a metric space and $A \subset X$ a subset. Then, we define the set of points having a unique metric projection in A as

$$\text{Unp}(A) = \{x \in X : \text{there exists a unique } a \in A \text{ such that } d(x, A) = d(x, a)\}.$$

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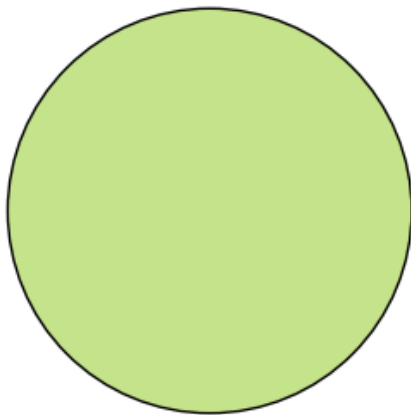
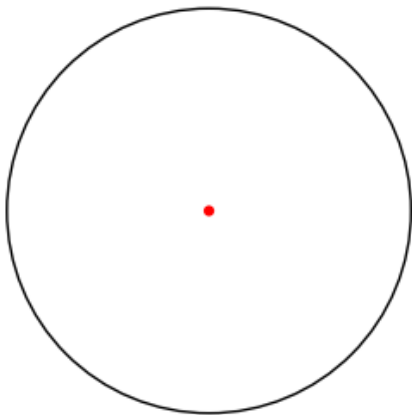
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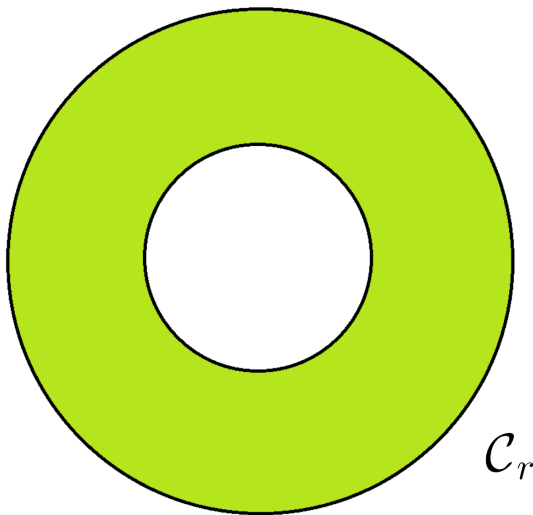
Finally, we define the global reach by

$$\text{reach}(A \subset X) = \inf_{a \in A} \text{reach}(a, A).$$



Example

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$$\text{reach}(\mathcal{C}_r \subset \mathbb{R}^2) = r, \text{ but } \text{reach}(\mathbb{D}^2 \subset \mathbb{R}^2) = \infty.$$

Remark

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Let M^n be a compact n -Riemannian manifold. For every $p \in M$,

$$\text{reach}(p, M \subset L^\infty(M)) = 0.$$

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- $\text{Unp}(M \subset L^\infty(M)) = M$?
- No!! $f(x) = d_p(x) + \delta \in \text{Unp}(M)$.
- Is $\text{Unp}(M \subset L^\infty(M))$ dense?

Proof

We are going to check that for every $d_p \in M$ and all $\epsilon > 0$. There exists a function $f \in B_\epsilon(d_p)$ such that

$$d_\infty(f, M) = \|f - d_p\|_\infty = \|f - d_q\|_\infty.$$

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We consider $\delta > 0$ such that $\delta \ll \epsilon$ and some $q \in M$ with $d_M(p, q) = \delta$. Then, $\|d_p - d_q\|_\infty = \delta$. Now, our candidate is

$$f := \frac{1}{2}(d_p + d_q).$$

1 $f \notin M$.

- ① $f \notin M$. Suppose there exists $r \in M$ such that $f = d_r$. Then, if that is true
- $$0 = d_r(r) = f(r) = \frac{1}{2} (d_p(r) + d_q(r)) \Rightarrow d_p(r) = d_q(r) = 0 \Rightarrow p = q = r \text{ !}.$$

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- ③ $\nexists r \in M$ such that $\|f - d_r\|_\infty < \|f - d_p\|_\infty$. Suppose it does, then evaluating at r , we would obtain

$$|d_r(r) - f(r)| = |f(r)| = \frac{1}{2} (d_p(r) + d_q(r)) < \frac{\delta}{2}. \quad (3)$$

On the other hand, by the triangular inequality,

$$d_p(r) + d_q(r) \geq d_M(p, q) = \delta \text{ !} \quad (4)$$

This part of the talk was based on:

- Manuel Cuerno and Luis Guijarro. “Upper and lower bounds on the filling radius”. In: (2022). arXiv: 2206.08032 Accepted in *Indiana University Mathematics Journal*.

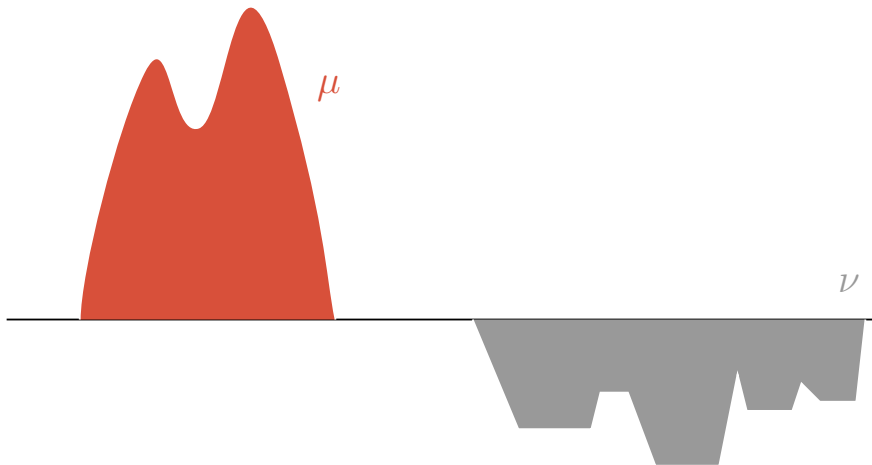
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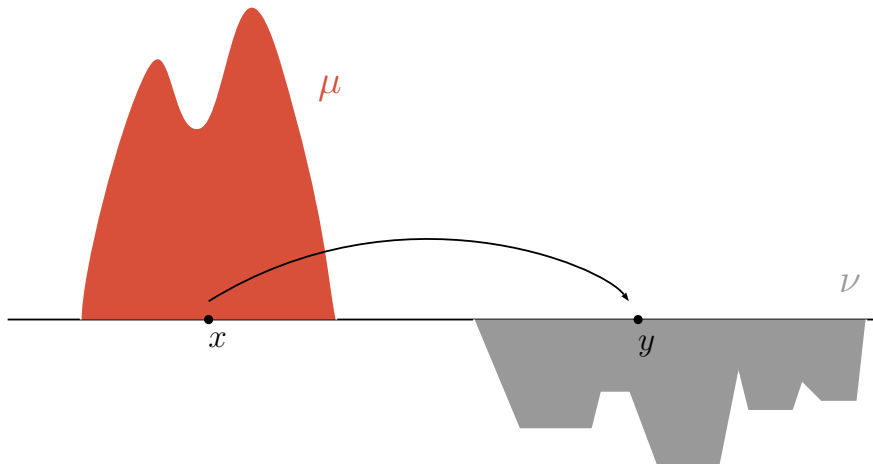
The next part is based on:

- [Javier Casado, Manuel Cuerno, and Jaime Santos-Rodríguez](#). “On the reach of isometric embeddings into Wasserstein type spaces”. In: (2023). [arXiv: 2307.01051](#)

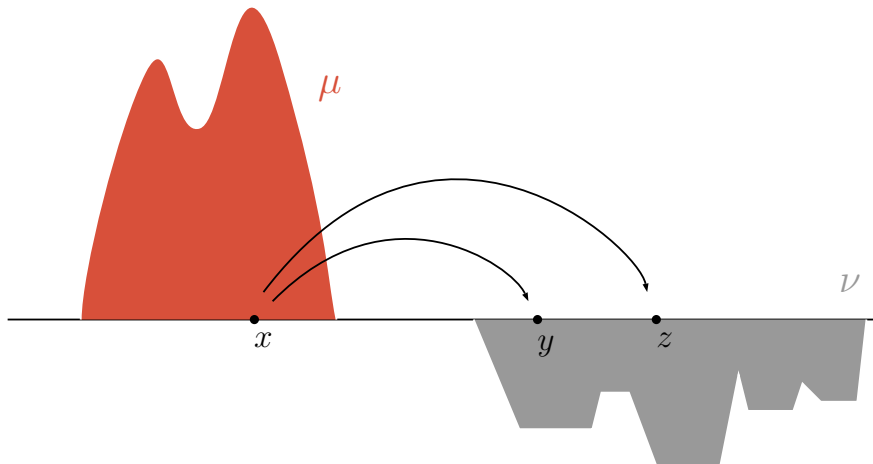
Optimal Transport



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Let (X, d_X) be a complete and separable metric space. We denote by $\mathcal{P}(X)$ the set of probability measures of X and $\mathcal{P}_p(X)$ the ones with finite p -moment, i.e.

$$\mathcal{P}_p(X) := \{\sigma \in \mathcal{P}(X) : \int_X d(x, x_0)^p d\sigma(x) < \infty \text{ for some } x_0 \in X\}.$$

Monge's formulation

Let μ, ν be two probability measures supported on X .

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Let μ, ν be two probability measures supported on X . Monge's optimal transport problem (1781) consists on minimizing:

$$\int d(x, T(x))^2 d\mu(x), \quad (5)$$

among all measurable maps $T: X \rightarrow X$ such that $T_{\#}\mu = \nu$.

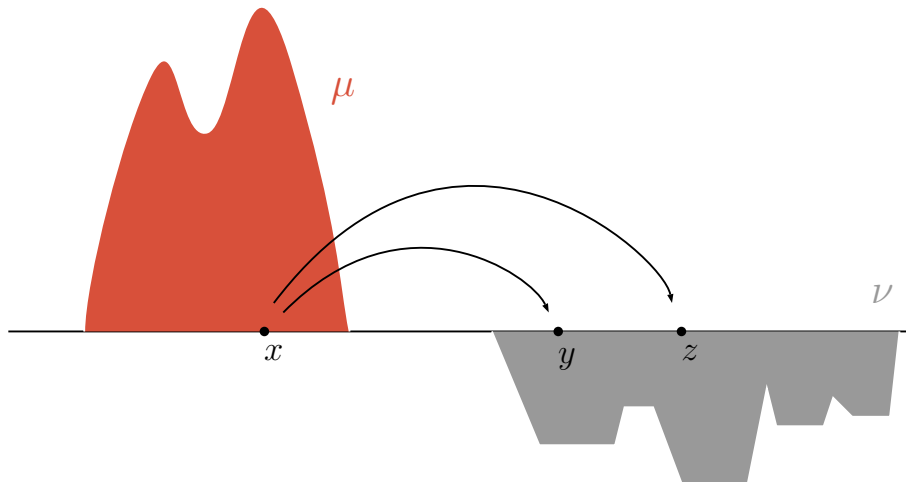
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Kantorovich presented a new formulation (1942) of the optimal transport problem, in some sense, weaker than Monge's one: instead of imposing the existence of some function T that sends one measure μ to another ν , he allows the possibility to split mass, i.e., he proposed to minimize the following functional:

$$\pi \mapsto \int d_X(x, y)^2 d\pi,$$

among all *admissible measures* $\pi \in \Gamma(\mu, \nu)$.

Wasserstein space

Let (X, d, μ) a metric measure space. We denote by $\mathcal{P}(X)$ the set of probability measures of X and $\mathcal{P}_p(X)$ the ones with finite p -moment, i.e.

$$\mathcal{P}_p(X) := \{\sigma \in \mathcal{P}(X) : \int_X d(x, x_0)^p d\sigma(x) < \infty \text{ for some } x_0 \in X\}.$$

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Definition

A transference plan, *admissible plan* or *admissible measure* between two positive measures $\mu, \nu \in \mathcal{P}(X)$ is a finite positive measure $\pi \in \mathcal{P}(X \times X)$ which satisfies that, for all A, B Borel subsets of X ,

$$\pi(A \times X) = \mu(A), \quad \text{and} \quad \pi(X \times B) = \nu(B).$$

We denote by $\Gamma(\mu, \nu)$ the set of transference plans between those two measures. Then, we define the p -Wasserstein distance for $p \geq 1$ and two probability measures by

$$W_p(\mu, \nu) := \left(\min_{\pi \in \Gamma(\mu, \nu)} \int_{X \times X} d(x, y)^p d\pi(x, y) \right)^{\frac{1}{p}}.$$

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Thus, we define the **p -Wasserstein space** as the following metric space

$$W_p(X) := (\mathcal{P}_p(X), W_p).$$

The inclusion

$$\Psi : X \rightarrow W_p(X)$$

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Notation: We denote $x \in X$ as barycenter of μ if

$$W_p(\mu, X) = W_p(\mu, \delta_x).$$

Proposition (Casado, C., Santos-Rodríguez, 2023)

Let (X, d) be a non-branching metric space and $W_p(X)$ with $p > 1$ its p -Wasserstein space. Then the set of unique points $\text{Unp}(X \subset W_p(X))$ is dense in $W_p(X)$.

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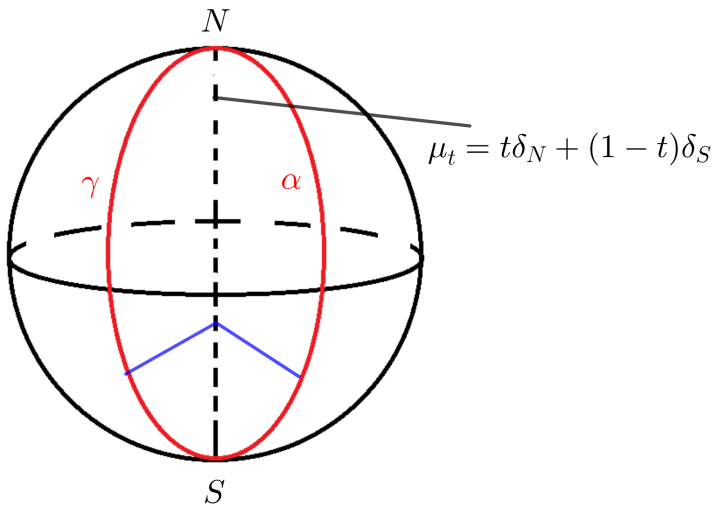
Furthermore we notice that there is a branching geodesic joining μ with δ_z . This gives us the contradiction as $W_p(X)$ is non-branching. Then ν is a measure in $\text{Unp}(X \subset W_p(X))$ which can be taken arbitrarily close to μ .

Proposition (Casado, C., Santos-Rodríguez, 2023)

Let X be a geodesic metric space, and $x, y \in X$ two points with $x \neq y$. Consider the probability measure

$$\mu_\lambda = \lambda\delta_x + (1 - \lambda)\delta_y,$$

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Let $\gamma(t) : [0, 1] \rightarrow X$ be a minimizing geodesic from x to y . Then

$$W_p^p(\delta_{\gamma(t)}, \mu_\lambda) = \lambda d(\gamma(t), x)^p + (1 - \lambda) d(\gamma(t), y)^p = (\lambda t^p + (1 - \lambda)(1 - t)^p) d(x, y)^p.$$

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The minimum will be achieved at the parameter t_0 which verifies

$$\left. \frac{d}{dt} \right|_{t=t_0} W_p^p(\delta_{\gamma(t)}, \mu_\lambda) = 0 \text{ which is } t_0 = \frac{(1-\lambda)^{p-1}}{\lambda^{p-1} + (1-\lambda)^{p-1}}.$$

$$W_p^p(\delta_{\gamma(t_0)}, \mu_\lambda) = \frac{\lambda(1-\lambda)^{(p-1)p} + (1-\lambda)\lambda^{(p-1)p}}{(\lambda^{p-1} + (1-\lambda)^{p-1})^p} \cdot d^p(x, y).$$

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We will choose any $a \in X$, and we will construct another point a' inside a minimizing geodesic γ verifying $W_p^p(\delta_a, \mu_\lambda) \geq W_p^p(\delta_{a'}, \mu_\lambda)$.

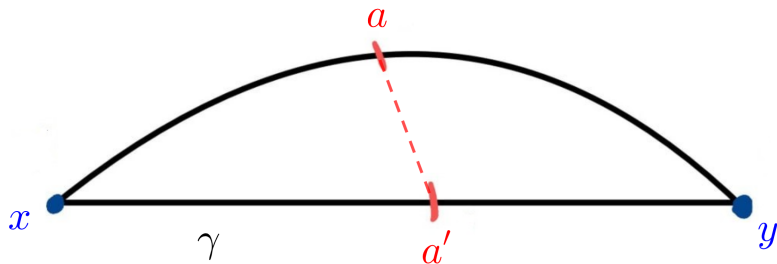
The case $d(a, y) \geq d(x, y)$ is straightforward, as choosing $a' = x$ we have

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Now, if $d(a, y) < d(x, y)$, we can pick a' inside γ at distance $d(a, y)$ to y . Observe that $d(a, x) \geq d(a', x)$ or γ would not be minimizing. Then,

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Theorem 8 (Casado, C. & Santos-Rodríguez, 2023)

Let X be a geodesic metric space, and $x \in X$ a point such that there exists another $y \in X$ with the property that there exist at least two different minimising geodesics from x to y . Then, for every $p > 1$,

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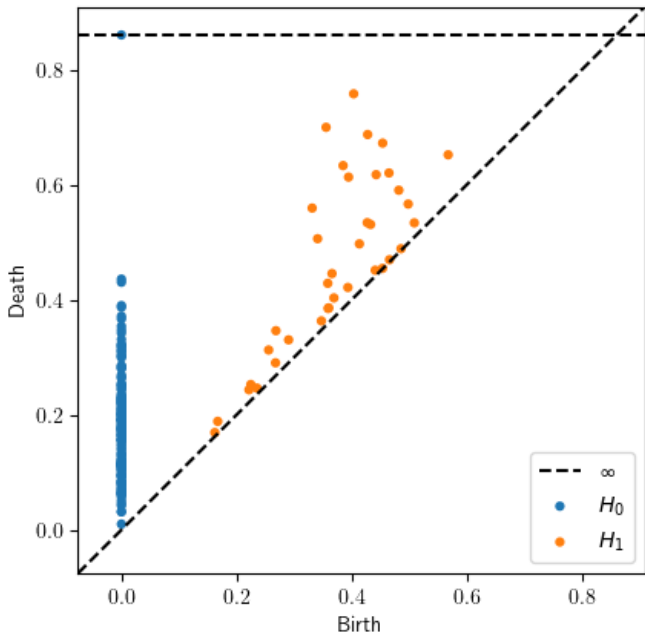
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Definition (Persistence diagram)

A *persistence diagram* D is a multiset of points $(a, b) \in \mathbb{R}_{<}^2 = \{(x, y) \in \mathbb{R}^2 : x < y\}$ and whose points represent the i -persistent homology of certain filtration \mathcal{F} .



Bottleneck Distance

Definition (Partial matching)

Let $D_1: I_1 \rightarrow \mathbb{R}_{\leq}^2$ and $D_2: I_2 \rightarrow \mathbb{R}_{\leq}^2$ be persistence diagrams.

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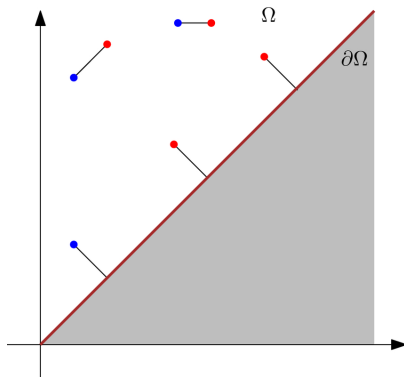
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Bottleneck Distance

Definition (Cost of a partial matching)

Let $D_1: I_1 \rightarrow \mathbb{R}_{\leq}^2$ and $D_2: I_2 \rightarrow \mathbb{R}_{\leq}^2$ be persistence diagrams and (I'_1, I'_2, f) a partial matching between them. We endow \mathbb{R}^2 with the infinity metric $d_\infty(a, b) = \|a - b\|_\infty = \max(|a_x - b_x|, |a_y - b_y|)$. We denote by $\text{cost}_\infty(f)$ the ∞ -cost of f , defined as follows:

$$\text{cost}_\infty(f) = \max \left\{ \sup_{i \in I'_1} d_\infty(D_1(i), D_2(f(i))), \sup_{j \in I_1 \setminus I'_1} d_\infty(D_1(j), \Delta), \sup_{k \in I_2 \setminus I'_2} d_\infty(D_2(k), \Delta) \right\}.$$

If any of the terms in either expression is unbounded, we declare the cost to be infinity.

Definition (Bottleneck distance of persistence diagrams)

Let $p = \infty$ and D_1, D_2 persistence diagrams. Define

$$\tilde{w}_\infty(D_1, D_2) = \inf\{\text{cost}_\infty(f) : f \text{ is a partial matching between } D_1 \text{ and } D_2\}.$$

Let $(\text{Dgm}_\infty, w_\infty)$ denote the metric space of persistence diagrams D such that $\tilde{w}_\infty(D, \emptyset) < \infty$ with the relation $D_1 \sim D_2$ if $\tilde{w}_\infty(D_1, D_2) = 0$. The metric w_∞ is called the *bottleneck distance*.

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Remark

For $p < \infty$, we can use

$$\text{cost}_p(f) = \left(\sum_{i \in I'_1} d_\infty(D_1(i), D_2(f(i)))^p + \sum_{j \in I_1 \setminus I'_1} d_\infty(D_1(j), \Delta)^p + \sum_{k \in I_2 \setminus I'_2} d_\infty(D_2(k), \Delta)^p \right)^{1/p},$$

and then, define the p -Wasserstein distance for persistence diagrams.

Reach of the space of persistence diagrams

Bubenik and Wagner construct an explicit isometric embedding of bounded separable metric spaces into $(\text{Dgm}_\infty, w_\infty)$.

$$\begin{aligned}\varphi : (X, d) &\rightarrow (\text{Dgm}_\infty, w_\infty) \\ x &\mapsto \{(2c(k-1), 2ck + d(x, x_k))\}_{k=1}^\infty,\end{aligned}$$

where $c > \text{diam}(X)$ and $\{x_k\}_{k=1}^\infty$ is a countable, dense subset of (X, d) .

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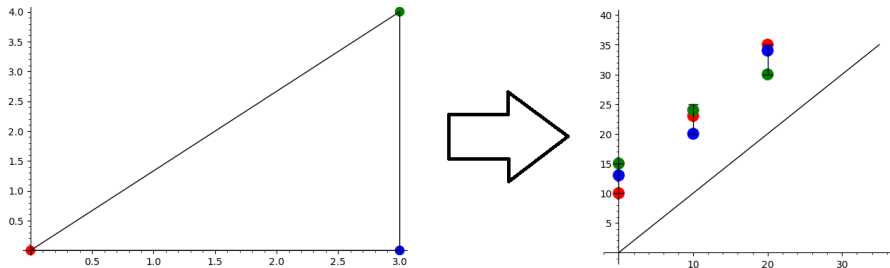


Figure: Bubenik's embedding of a triangle

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Theorem 11 (Casado, C. & Santos-Rodríguez, 2023)

Let (X, d) be a separable, bounded metric space and $(\text{Dgm}_\infty, w_\infty)$ the space of persistence diagrams with the bottleneck distance. If $x \in X$ is an accumulation point, then

$$\text{reach}(x, X \subset \text{Dgm}_\infty) = 0.$$

In particular, if X is not discrete, $\text{reach}(X \subset \text{Dgm}_\infty) = 0$.

Thank you for your attention!

manuel.mellado@cunef.edu