The Sparse Grids Matlab Kit

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Outline

- Example
- Basic data structure
- Main features
- 4 Example reprise
- Conclusions

• main contributors: Lorenzo Tamellini, Chiara Piazzola

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 - 22-2 ("California")
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- BSD2 license

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- Similar to:
 - Dakota, PyApprox, MUQ, ChaosPy, UQTk (not Matlab);
 - ▶ SG++, Tasmanian (Matlab wrappers);
 - UQLab, Spinterp (Matlab).

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Aim of these slides: give rough idea of sparse grids and of the structure of the code, show features by examples

Outline

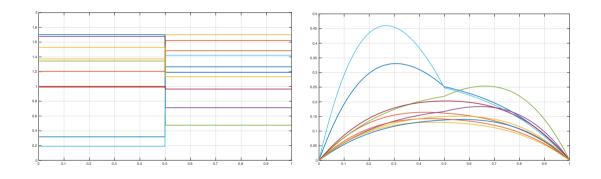
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Forward Uncertainty Quantification

$$\begin{cases} -\frac{d}{dx} \left[a(x, \mathbf{y}) \frac{d}{dx} u(x, \mathbf{y}) \right] = 1, & \text{for } x \in (0, 1) \\ u(0, \cdot) = u(1, \cdot) = 0 \\ a(x, \mathbf{y}) = 1 + \sigma_1 y_1 \mathbb{I}_{[0, 0.5]}(x) + \sigma_2 y_2 \mathbb{I}_{[0.5, 1]}(x) \\ y_1, y_2 \sim \mathcal{U}(-\sqrt{3}, \sqrt{3}) \\ I(\mathbf{y}) = \int_0^1 u(x, \mathbf{y}) dx \end{cases}$$

- often, more than N=2 parameters
- ODE and algebraic models are also of interest

Forward Uncertainty Quantification



Forward Uncertainty Quantification

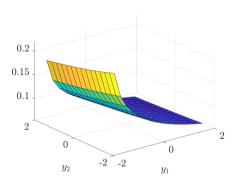
Goals:

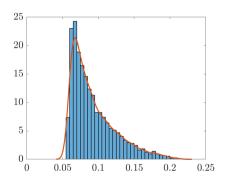
- statistics of I (mean, variance,pdf)
- sensitivity analysis for I
- ullet meta-model for $I(y_1,y_2)$ (aka response surface aka surrogate model)

Need

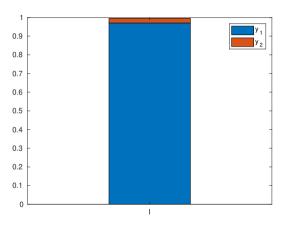
- High-dimensional quadrature (mean, variance)
- High-dimensional interpolation/approximation (pdf, metamodel)

Results

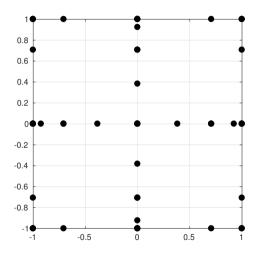




Results



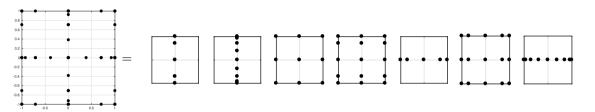
Where do we sample? Sparse grids



Our matlab library handles:

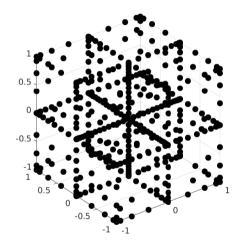
- generation of these schemes
- integration and interpolation on them

Sparse grids in a nutshell



- Linear combination of tensor grids
- ullet Reasonably slows down "curse of dimensionality" up to N=a few tens
- ullet Works well under regularity assumptions on $I({m y})$
- Anisotropic and adaptive versions available

Sparse grids in a nutshell



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```
N=2;
knots=@(n) knots_CC(n,-1,1);
w = 3;
m = @lev2knots_doubling;
Ifun = @(i) sum(i-1);
S = smolyak_grid(N,w,knots,m,Ifun);
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$$S = \sum_{i \in \mathcal{I}} c_i \otimes_{n=1}^N \mathcal{U}^{m(i_n)}$$

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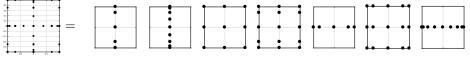
- $S = \sum_{i \in \mathcal{I}} c_i \otimes_{n=1}^N \mathcal{U}^{m(i_n)}$
- ullet $m(i)="2^{i-1}+1"$, $\ \mathcal{U}^{m(i_n)}=$ interpolant on $m(i_n)$ Clenshaw–Cts pts
- $\mathcal{I} = \left\{ i \in \mathbb{N}_+^N : \sum_{n=1}^N (i_n 1) \le w \right\}$

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>>> S
    S =
    1 x 7 struct array with fields:
    knots
    weights
    size
    knots_per_dim
    m
    coeff
    idx
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15 / 25

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```

```
>> S(1)
ans =
struct with fields:

    knots: [2x5 double] % points are always column vectors
    weights: [-0.1333 -1.0667 -1.6000 -1.0667 -0.1333]
    size: 5
knots_per_dim: {[0] [1 0.7071 6.1232e-17 -0.7071 -1]}
    m: [1 5]
    coeff: -1
    idx: [1 3] %multiidx are always row vectors
```

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Sparse grids "ingredients": nodes, m, \mathcal{I}

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```

	knots	function	nestedness
uniform	Gauss–Legendre	knots_uniform	No
	Clenshaw-Curtis	knots_CC	Yes
	Leja (standard, symmetric, p-disk)	knots_leja	Yes
	midpoints	knots_midpoint	Yes
	equispaced	knots_trap	Yes
normal	Gauss–Hermite	knots_normal	No
	Genz–Keister	knots_GK	Yes
	weighted Leja (standard, symmetric)	knots_normal_leja	Yes
exponential	Gauss-Laguerre	knots_exponential	No
	weighted Leja	knots_exponential_leja	Yes
gamma	Gauss-generalized Laguerre	knots_gamma	No
-	weighted Leja	knots_gamma_leja	Yes
beta	Gauss–Jacobi	knots_beta	No
	weighted Leja (standard, symmetric)	knots_beta_leja	Yes

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```
• m = lev2knots_lin(i)
m(i) = i
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```
m = lev2knots_lin(i)
```

• m = lev2knots_2step(i)

$$m(i) = 2(i-1) + 1$$

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- m = lev2knots_lin(i)
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$$m(1) = 1, m(i) = 2^{i-1} + 1$$

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```
m = lev2knots_lin(i)
m = lev2knots_2step(i)
m = lev2knots_doubling(i)
m = lev2knots_tripling(i)
m(i) = 3<sup>i-1</sup>
```

it is possible to specify different m and knots in each direction

m = lev2knots_tripling(i)

m = lev2knots_GK(i)

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presets for m, Ifun are available:

```
[m,Ifun]=define_functions_for_rule(<'TP','TD','HC','SM'>,<N,g>)
```

where for $g \in \mathbb{R}^{N}_{+}$, $w \in \mathbb{N}$

```
ullet 'TP' = tensor prod., \mathcal{I}=\left\{ oldsymbol{\mathsf{i}}\in\mathbb{N}_+^{oldsymbol{N}}: \max_n g_n(i_n-1)\leq w 
ight\}, m(i)=i
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presets for m, Ifun are available:

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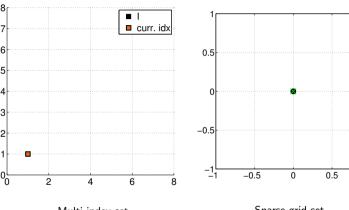
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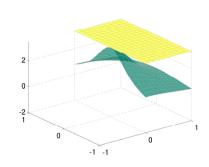
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- 'TD' = total deg., $\mathcal{I} = \left\{ \mathsf{i} \in \mathbb{N}_+^N : \sum_{n=1}^N g_n(i_n-1) \leq w \right\}$, m(i) = i
- 'HC' = hyperbolic cross, $\mathcal{I} = \left\{ \mathsf{i} \in \mathbb{N}_+^N : \prod_{n=1}^N i_n^{g_n} \leq w \right\}$, m(i) = i
- 'SM' = Smolyak, $\mathcal{I} = \left\{\mathsf{i} \in \mathbb{N}_+^N : \sum_{n=1}^N g_n(i_n-1) \leq w \right\}, m(i) = 2^{i-1}+1$

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```

It is also possible to define sparse grids directly by a multi-idx set

```
% ex. 1) ''hand-typed'' set
C=[1 1; 1 3; 4 1]; % non downward-closed set
[adm,C_comp1] = check_set_admissibility(C); % fix C
S_M = smolyak_grid_multiidx_set(C_comp1, knots, m);
%ex. 2) create a box in N^2 with top-right corner at [2 3]
jj=[2 3];
D=multiidx_box_set([2 3],1);
T_M = smolyak_grid_multiidx_set(D, knots, m);
```



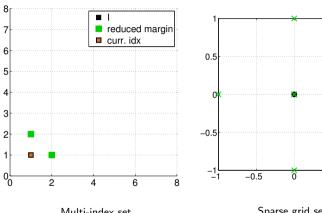


Multi-index set

Sparse grid set

interpolation of
$$f(\mathbf{y}) = \frac{1}{y_1^2 + y_2^2 + 0.3}$$

res = adapt_sparse_grid(f, N, knots, m, res_old, controls)

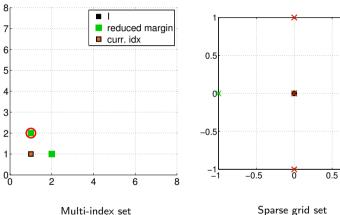


Multi-index set

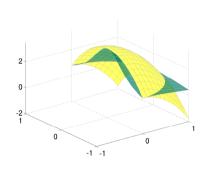
Sparse grid set

0.5

interpolation of $f(\mathbf{y}) = \frac{1}{y_1^2 + y_2^2 + 0.3}$

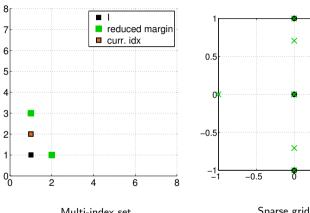


Sparse grid set



interpolation of $f(\mathbf{y}) = \frac{1}{v_1^2 + v_2^2 + 0.3}$

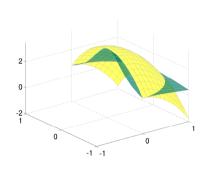
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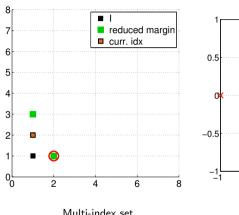
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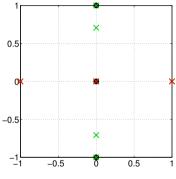
0.5



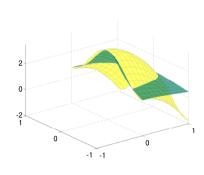
interpolation of
$$f(\mathbf{y}) = \frac{1}{y_1^2 + y_2^2 + 0.3}$$



Multi-index set



Sparse grid set

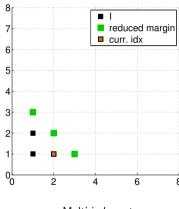


interpolation of $f(\mathbf{y}) = \frac{1}{v_1^2 + v_2^2 + 0.3}$

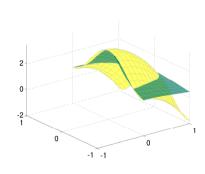
0.5

-0.5

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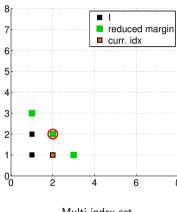


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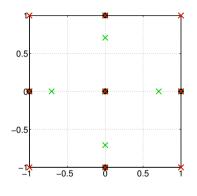
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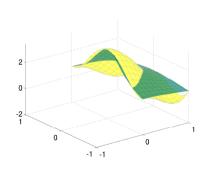
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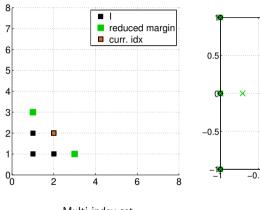
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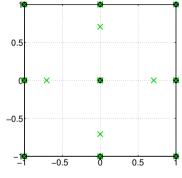
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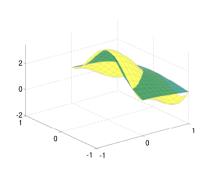
interpolation of $f(\mathbf{y}) = \frac{1}{y_1^2 + y_2^2 + 0.3}$



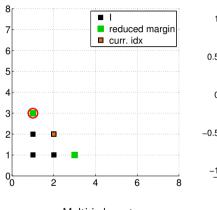
Multi-index set



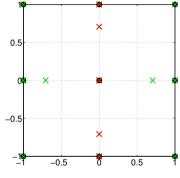
Sparse grid set



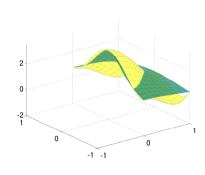
interpolation of $f(\mathbf{y}) = \frac{1}{y_1^2 + y_2^2 + 0.3}$



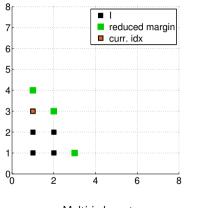
Multi-index set



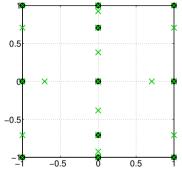
Sparse grid set



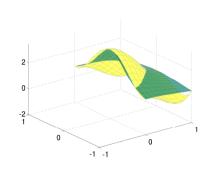
interpolation of
$$f(\mathbf{y}) = \frac{1}{y_1^2 + y_2^2 + 0.3}$$



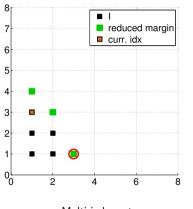
Multi-index set



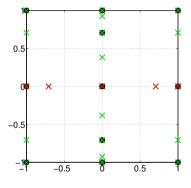
Sparse grid set



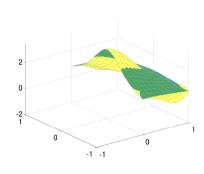
interpolation of
$$f(\mathbf{y}) = \frac{1}{y_1^2 + y_2^2 + 0.3}$$



Multi-index set

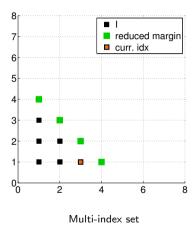


Sparse grid set

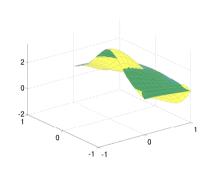


interpolation of $f(\mathbf{y}) = \frac{1}{y_1^2 + y_2^2 + 0.3}$

-0.5



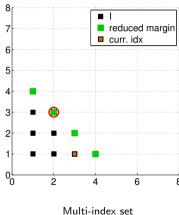
-0.5 0.5



Sparse grid set

interpolation of
$$f(\mathbf{y}) = \frac{1}{y_1^2 + y_2^2 + 0.3}$$

res = adapt_sparse_grid(f, N, knots, m, res_old, controls)

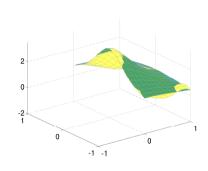


8 Sparse grid set

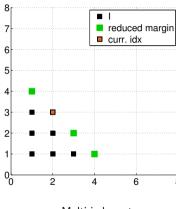
-0.5

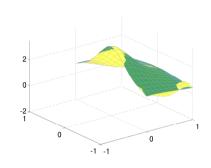
0.5

-0.5



interpolation of
$$f(\mathbf{y}) = \frac{1}{y_1^2 + y_2^2 + 0.3}$$

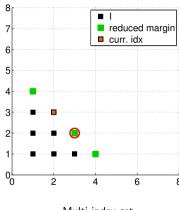




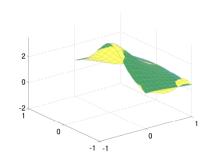
Multi-index set

Sparse grid set

interpolation of
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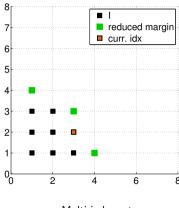
-0.5-0.5 0.5

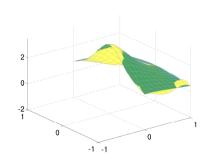


Multi-index set

Sparse grid set

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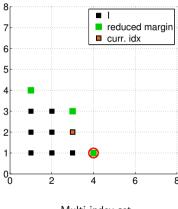




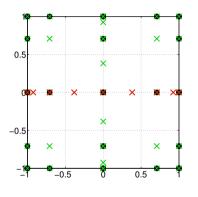
Multi-index set

Sparse grid set

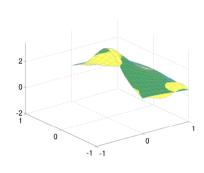
interpolation of
$$f(\mathbf{y}) = \frac{1}{y_1^2 + y_2^2 + 0.3}$$



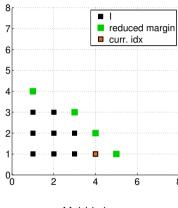
Multi-index set



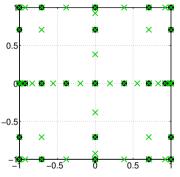
Sparse grid set



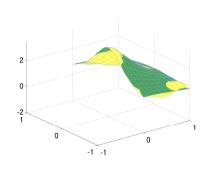
interpolation of
$$f(\mathbf{y}) = \frac{1}{y_1^2 + y_2^2 + 0.3}$$



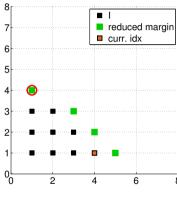
Multi-index set Sparse



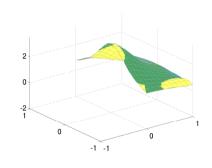
Sparse grid set



interpolation of
$$f(\mathbf{y}) = \frac{1}{y_1^2 + y_2^2 + 0.3}$$



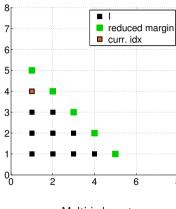
× X -0.5× ×

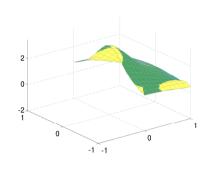


Multi-index set

Sparse grid set

interpolation of
$$f(\mathbf{y}) = \frac{1}{y_1^2 + y_2^2 + 0.3}$$





Multi-index set

Sparse grid set

interpolation of $f(\mathbf{y}) = \frac{1}{y_1^2 + y_2^2 + 0.3}$

Outline

- Example
- Basic data structure
- Main features
- 4 Example reprise
- Conclusions

```
f=@(x) x.^2; %vector-valued function
N=2; w=3;
S=smolyak_grid(N,w,@(n) knots_uniform(n,-1,1),@lev2knots_lin);
Sr= reduce_sparse_grid(S);
```

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f=@(x) x.^2; %vector-valued function
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ev_f = evaluate_on_sparse_grid(f,Sr)

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Sr= reduce_sparse_grid(S);
```

```
ev_f = evaluate_on_sparse_grid(f, Sr)
can recycle evaluations from previous results if available (regardless of nestedness)
ev_f = evaluate_on_sparse_grid(f, S, Sr, ev_f_old, S_old, Sr_old)
```

```
f=@(x) x.^2; %vector-valued function
N=2; w=3;
S=smolyak_grid(N,w,@(n) knots_uniform(n,-1,1),@lev2knots_lin);
Sr= reduce_sparse_grid(S);
```

ev_f = evaluate_on_sparse_grid(f,Sr)
evaluate f in parallel if more than X evals are required, uses Matlab parallel toolbox
ev_f = evaluate_on_sparse_grid(f,S,Sr,[],[],[],X)

```
f=@(x) x.^2; %vector-valued function
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Sr= reduce_sparse_grid(S);
```

ev_f = evaluate_on_sparse_grid(f,Sr)
 q_f = quadrature_on_sparse_grid(f,Sr)
 same features as evaluate

• int_f = interpolate_on_sparse_grid(S,Sr,ev_f,P)

P is a matrix of eval. points (stored as columns)

```
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ev_f = evaluate_on_sparse_grid(f,Sr)
eq_f = quadrature_on_sparse_grid(f,Sr)
```

q_f = quadrature_on_sparse_grid(f,Sr)

• int_f = interpolate_on_sparse_grid(S,Sr,ev_f,P)
• [coeffs,I] = convert_to_modal(S,Sr,ev_f,'Legendre')

Converts a sparse grid into its equivalent Polynomial Chaos Exp.

```
f=@(x) x.^2; %vector-valued function
N=2; w=3;
S=smolyak_grid(N,w,@(n) knots_uniform(n,-1,1),@lev2knots_lin);
Sr= reduce_sparse_grid(S);

    ev.f = evaluate_on_sparse_grid(f,Sr)
```

```
f=@(x) x.^2; %vector-valued function
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Sr= reduce_sparse_grid(S);
```

- ev_f = evaluate_on_sparse_grid(f,Sr)
- q_f = quadrature_on_sparse_grid(f,Sr)
- int_f = interpolate_on_sparse_grid(S,Sr,ev_f,P)
- [coeffs, I] = convert_to_modal(S, Sr, ev_f, 'Legendre')
 - ► Converts a sparse grid into its equivalent Polynomial Chaos Exp.
 - ▶ Idea: For each tensor grid in the combination technique, compute the equivalent PCE by solving a Vandermonde system

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f=@(x) x.^2; %vector-valued function
N=2; w=3;
S=smolyak_grid(N,w,@(n) knots_uniform(n,-1,1),@lev2knots_lin);
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 - Vandermonde matrix is orthogonal for Gaussian quadrature points

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- [coeffs, I] = convert_to_modal(S, Sr, ev_f, 'Legendre')
 - Converts a sparse grid into its equivalent Polynomial Chaos Exp.
 - Idea: For each tensor grid in the combination technique, compute the equivalent PCE by solving a Vandermonde system
 - ► Vandermonde matrix is orthogonal for Gaussian quadrature points
 - several orthogonal polynomials:

```
'Legendre', 'Hermite', 'Chebyshev', 'Laguerre', 'Jacobi', 'Generalized Laguerre'
```

• int_f = interpolate_on_sparse_grid(S,Sr,ev_f,P)
• [coeffs,I] = convert_to_modal(S,Sr,ev_f,'Legendre')

[Si,Ti]=compute_sobol_indices_from_sparse_grid(S,Sr,ev_f,'Legendre')

```
f=@(x) x.^2; %vector-valued function
N=2; w=3;
S=smolyak_grid(N,w,@(n) knots_uniform(n,-1,1),@lev2knots_lin);
Sr= reduce_sparse_grid(S);

ev_f = evaluate_on_sparse_grid(f,Sr)
eq_f = quadrature_on_sparse_grid(f,Sr)
```

• int_f = interpolate_on_sparse_grid(S,Sr,ev_f,P)
• [coeffs,I] = convert_to_modal(S,Sr,ev_f,'Legendre')

[Si,Ti]=compute_sobol_indices_from_sparse_grid(S,Sr,ev_f,'Legendre')
 Si are the principal Sobol indices of xi (fraction of variability due to xi only)

```
f=@(x) x.^2; %vector-valued function
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Sr= reduce_sparse_grid(S);

    ev_f = evaluate_on_sparse_grid(f,Sr)
     q_f = quadrature_on_sparse_grid(f,Sr)
```

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- q_f = quadrature_on_sparse_grid(f,Sr)
- int_f = interpolate_on_sparse_grid(S,Sr,ev_f,P)
- [coeffs, I] = convert_to_modal(S, Sr, ev_f, 'Legendre')
- [Si,Ti]=compute_sobol_indices_from_sparse_grid(S,Sr,ev_f,'Legendre')
 - **Si** are the principal Sobol indices of x_i (fraction of variability due to x_i only)
 - ▶ **Ti** are the **total** Sobol indices of x_i (fraction of variability due to x_i alone and together with any other variable)

grads = derive_sparse_grid(S,Sr,ev_f,P)

```
f=@(x) x.^2; %vector-valued function
N=2; w=3;
S=smolyak_grid(N,w,@(n) knots_uniform(n,-1,1),@lev2knots_lin);
Sr= reduce_sparse_grid(S);

ev_f = evaluate_on_sparse_grid(f,Sr)
eq_f = quadrature_on_sparse_grid(f,Sr)
eint_f = interpolate_on_sparse_grid(S,Sr,ev_f,P)
e[coeffs,I] = convert_to_modal(S,Sr,ev_f,'Legendre')
e[Si,Ti]=compute_sobol_indices_from_sparse_grid(S,Sr,ev_f,'Legendre')
```

```
f=0(x) x.^2: %vector-valued function
N=2; w=3;
S=smolyak\_grid(N, w, @(n) knots\_uniform(n, -1, 1), @lev2knots\_lin);
Sr= reduce_sparse_grid(S);
  ev_f = evaluate_on_sparse_grid(f,Sr)
  • q_f = quadrature_on_sparse_grid(f,Sr)
  • int_f = interpolate_on_sparse_grid(S,Sr,ev_f,P)
  • [coeffs, I] = convert_to_modal(S, Sr, ev_f, 'Legendre')
  • [Si, Ti] = compute_sobol_indices_from_sparse_grid(S, Sr, ev_f, 'Legendre')
  grads = derive_sparse_grid(S,Sr,ev_f,P)
    uses Finite Differences, increment step can be specified
```

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f=0(x) x.^2: %vector-valued function
N=2; w=3;
S=smolyak\_grid(N, w, @(n) knots\_uniform(n, -1, 1), @lev2knots\_lin);
Sr= reduce_sparse_grid(S);
  ev_f = evaluate_on_sparse_grid(f,Sr)
  • q_f = quadrature_on_sparse_grid(f,Sr)
  • int_f = interpolate_on_sparse_grid(S,Sr,ev_f,P)
  • [coeffs, I] = convert_to_modal(S, Sr, ev_f, 'Legendre')
  [Si,Ti]=compute_sobol_indices_from_sparse_grid(S,Sr,ev_f,'Legendre')
  grads = derive_sparse_grid(S,Sr,ev_f,P)
  • H = hessian_sparse_grid(S,Sr,ev_f,P)
```

grads = derive_sparse_grid(S,Sr,ev_f,P)
H = hessian_sparse_grid(S,Sr,ev_f,P)

uses Finite Differences, increment step can be specified

```
f=@(x) x.^2; %vector-valued function
N=2; w=3;
S=smolyak_grid(N,w,@(n) knots_uniform(n,-1,1),@lev2knots_lin);
Sr= reduce_sparse_grid(S);

    ev_f = evaluate_on_sparse_grid(f,Sr)
        q_f = quadrature_on_sparse_grid(f,Sr)
        int_f = interpolate_on_sparse_grid(S,Sr,ev_f,P)
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ev_f = evaluate_on_sparse_grid(f,Sr)
eq_f = quadrature_on_sparse_grid(f,Sr)
eint_f = interpolate_on_sparse_grid(S,Sr,ev_f,P)
e[coeffs,I] = convert_to_modal(S,Sr,ev_f,'Legendre')
```

• [Si, Ti] = compute_sobol_indices_from_sparse_grid(S, Sr, ev_f, 'Legendre')

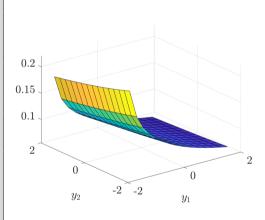
grads = derive_sparse_grid(S,Sr,ev_f,P)
 H = hessian_sparse_grid(S,Sr,ev_f,P)
 plus of course. plotting and exporting on file...

Outline

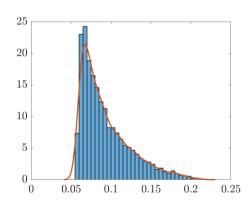
- Example
- Basic data structure
- Main features
- 4 Example reprise
- 6 Conclusions

Results with code

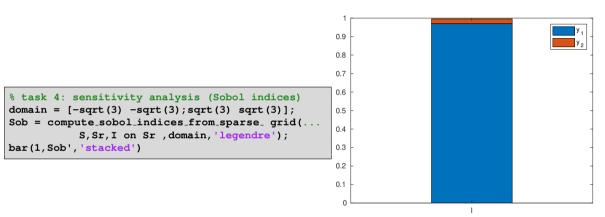
```
N = 2:
knots = @(n) knots_CC(n,-sqrt(3), sqrt(3));
lev2knots = @lev2knots_doubling;
rule = @(ii) sum((ii-1));
w=4:
S = smolyak_grid(N, w, knots, lev2knots, rule);
Sr = reduce_sparse_grid(S);
% solve PDEs on sparse grid (expensive part)
I_on_Sr = evaluate_on_sparse_grid(I,Sr);
% task 1: expected value
exp_I = quadrature_on_sparse_grid(I_on_Sr,Sr);
% task 2: evaluate metamodel
yy = linspace(-sqrt(3), sqrt(3), 15);
[Y1, Y2] = meshgrid(yy, yy);
eval_points = [Y1(:)';Y2(:)'];
I_vals = interpolate_on_sparse_grid(S,Sr,...
                            I_on_Sr.eval_points);
```



Results with code



Results with code



Outline

- Example
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• high-level Matlab software, based on combination technique form of sparse grids;

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- high-dimensional quadrature/interpolation, geared towards UQ

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