

## KY-012 Active Piezo-Buzzer module

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### Pictures



### Technical data / Short description

This Buzzer creates a sound with a frequency of 2,5kHz.

The active Buzzer-module doesn't need a square wave, unlike the passiv module (KY-006), to create a sound. If it gets a minimum Voltage of 3.3V at its signal pin, the buzzer will create the square wave by itself.

## Pinout



## Code example Arduino

In this example, you will see how the buzzer will be ON for 4 seconds and then will be OFF for 2 seconds.

```
int Buzzer = 13;

void setup ()
{
  pinMode (Buzzer, OUTPUT); // Output pin initialization for the buzzer
}

void loop () //Main program loop
{
  digitalWrite (Buzzer, HIGH); // Buzzer will be on
  delay (4000); // Waitmode for 4 seconds
  digitalWrite (Buzzer, LOW); // Buzzer will be off
  delay (2000); // Waitmode for another 2 seconds in which the buzzer will be off
}
```

### Connections Arduino:

Sensor Signal = [Pin 13]  
 Sensor [N.C] =  
 Sensor GND = [Pin GND]

### Example program download:

[KY-006-RPI\\_PWM](#)

## Code example Raspberry Pi

In this example, you will see how, with a defined output pin, the buzzer will be ON for 4 seconds and then will be OFF for 2 seconds.

## KY-012 Active Piezo-Buzzer module

```
import RPi.GPIO as GPIO
import time

GPIO.setmode(GPIO.BCM)

# Output pin declaration for the Buzzer.
Buzzer_PIN = 24
GPIO.setup(Buzzer_PIN, GPIO.OUT, initial= GPIO.LOW)

print ("Buzzer-test [press ctrl+c to end the test]")

# Main program loop
try:
    while True:
        print("Buzzer will be on for 4 seconds")
        GPIO.output(Buzzer_PIN,GPIO.HIGH) #Buzzer will be switched on
        time.sleep(4) #Waitmode for 4 seconds
        print("Buzzer wil be off for 4 seconds")
        GPIO.output(Buzzer_PIN,GPIO.LOW) #Buzzer will be switched off
        time.sleep(2) #Waitmode for another 2 seconds in which the buzzer will be off

# Scavenging work after the end of the program
except KeyboardInterrupt:
    GPIO.cleanup()
```

### Connections Raspberry Pi:

Sensor Signal	=	GPIO24	[Pin 18]
Sensor [+V]	=	3.3V	[Pin 1]
Sensor GND	=	GND	[Pin 6]

### Example program download

[KY-012\\_Buzzer\\_RPi](#)

To start, enter the command:

```
sudo python KY-012_Buzzer_RPi.py
```