



Preconditioning the time-harmonic elastic wave equation at multiple frequencies

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Problem statement

The discretized **time-harmonic elastic wave equation** yields,

$$(K + i\omega_k C - \omega_k^2 M) \mathbf{x}_k = \mathbf{b}, \quad k = 1, \dots, N, \quad (1)$$

where $\{\omega_1, \dots, \omega_N\}$ are a range of (angular) frequencies.

1. Linearization:

$$\left\{ \begin{bmatrix} iC & K \\ I & 0 \end{bmatrix} - \omega_k \begin{bmatrix} M & 0 \\ 0 & I \end{bmatrix} \right\} \begin{bmatrix} \omega_k \mathbf{x}_k \\ \mathbf{x}_k \end{bmatrix} = \begin{bmatrix} \mathbf{b} \\ 0 \end{bmatrix} \quad (2)$$

2. Matrix equation:

$$K\mathbf{X} - iC\mathbf{X}\Omega + M\mathbf{X}\Omega^2 = B, \quad \Omega := \text{diag}(\omega_1, \dots, \omega_N). \quad (3)$$

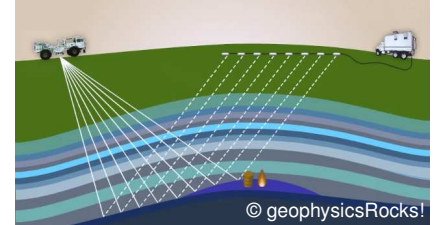


Fig. 1: Full-waveform inversion

Preconditioning multi-shift wave propagation problems

Right-preconditioning of (2) yields,

$$\mathcal{A} := \begin{bmatrix} iC & K \\ I & 0 \end{bmatrix}, \quad \mathcal{B} := \begin{bmatrix} M & 0 \\ 0 & I \end{bmatrix}$$

$$(\mathcal{A} - \omega_k \mathcal{B}) \mathcal{P}_k^{-1} \mathbf{y}_k = \mathbf{b} \Leftrightarrow (\mathcal{A}(\mathcal{A} - \tau \mathcal{B})^{-1} - \eta_k I) \mathbf{y}_k = \mathbf{b},$$

where $\eta_k = \omega_k / (\omega_k - \tau)$ and $\mathcal{P}_k = (1 - \eta_k)(\mathcal{A} - \tau \mathcal{B})$.

- Use MSSS matrix computations to approximately apply $(\mathcal{A} - \tau \mathcal{B})^{-1}$, cf. Figure 2.
- Choose τ optimally in the sense of,

$$\tau^* = \min_{\tau \in \mathbb{C}} \max_{k=1, \dots, N} \left(\frac{R_k(\tau)}{|c_k(\tau)|} \right), \quad \text{cf. Figure 3.}$$

Theorem: GMRES convergence bound [Y. Saad, 2003]

Let the eigenvalues of the preconditioned matrix be enclosed by a circle of radius R and center c . Then the GMRES-residual norm after i iterations $\|r^i\|$ satisfies,

$$\frac{\|r^i\|}{\|r^0\|} \leq c_2(X) \left(\frac{R}{|c|} \right)^i,$$

where X is the matrix of eigenvectors, and $c_2(X)$ its condition number in 2-norm.

MSSS matrix structure

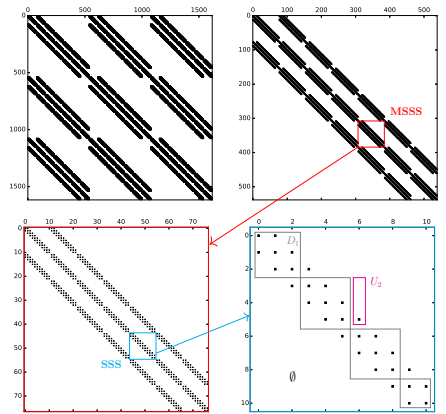


Fig. 2: MSSS structure of the 3D matrix (1)

Simulation results in 2D and 3D

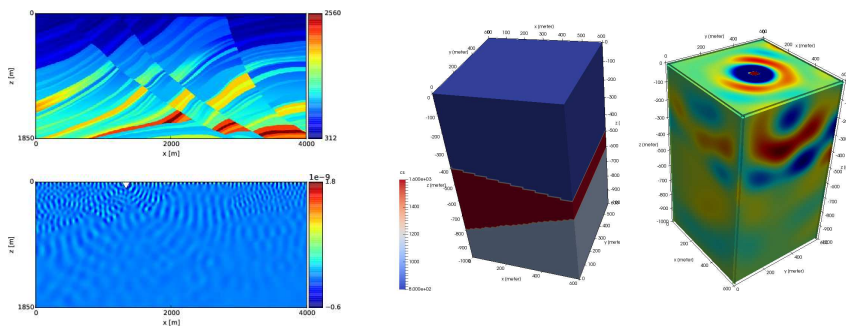


Fig. 4: Simulation results for the 2D Marmousi-II problem, and a 3D wedge problem

Preconditioned spectra

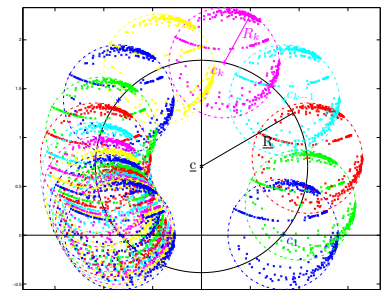


Fig. 3: Spectra after Möbius transformation

References

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