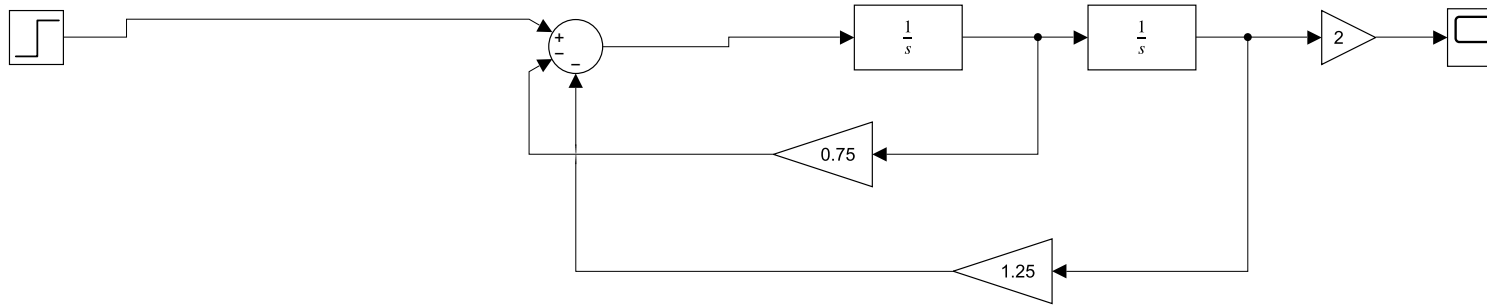


Froma Canónica Controlable



State Space Equations

$$\dot{x}_1(t) = -1.25x_2(t) - 0.75x_1(t)$$

$$\dot{x}_2(t) = x_1(t)$$

$$y(t) = 2x_2(t)$$

Sistema Controlado

