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Computer Graphics
Assignment 1

Question 1

Changes in Code

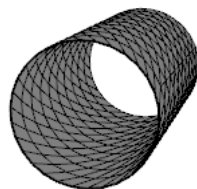
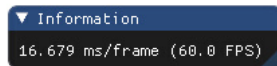
Note:- All changes are done in the main.py file. The changes are wrapped by “*Start*” and “*End*” comments to denote changes. Search “*Start*” for the changes.

1. Change the number of triangles drawn in *glDrawArrays*. Increased the number of triangles to support the newly drawn surface.
2. Create a function to supply the coordinate points of the surface using its parametric equation (hardcoded) and parameters.
3. Added a nested loop in *createParametricObject*. Specify the number of horizontal lines and vertical lines into which the surface is divided. Using the number of lines, divide the range of parameters and create a constant step size to create rectangles. Divide the rectangles into two triangles.

Output

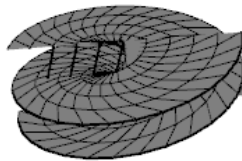
Note:- The code has the equation for cylinder hard coded, but it was changed to create multiple surfaces given below.

1. Cylinder. (Code in main.cpp)
Equation. $x = R \cdot \cos(u)$; $y = R \cdot \sin(u)$; $z = v$ in (u, v)
Parameter Range: $0 \leq u \leq 2\pi$; $0 \leq v \leq 20$.



2. Helicoid
Equation. $x = v \cdot \cos(u)$; $y = v \cdot \sin(u)$; $z = u$;
Parameter Range: $-10 \leq v \leq 10$; $-\pi \leq u \leq \pi$.

▼ Information
16.668 ms/frame (60.0 FPS)

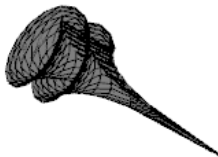


3. Deni's Surface

Parametric Equation: $(5\cos(u)\sin(v), 5\sin(u)\cos(v), 5(\cos(v) + \ln(\tan(v/2))) + 0.5u)$;

Parameter Range: $0 \leq u \leq 4\pi$; $0.01 \leq v \leq 1$.

▼ Information
16.668 ms/frame (60.0 FPS)



4. Klien Bottle

▼ Information
16.666 ms/frame (60.0 FPS)

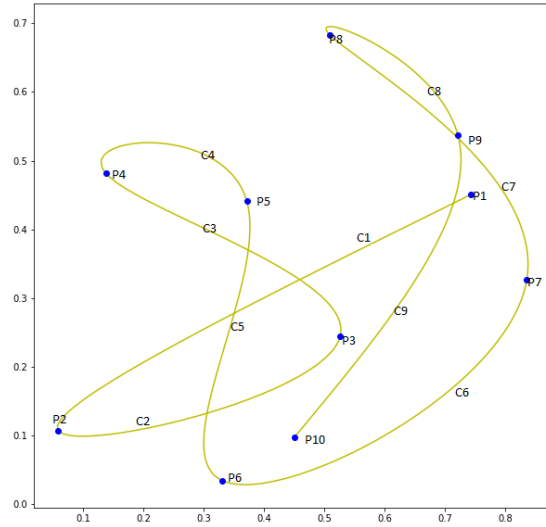


Question 2

Algorithm and Explanation

We aim to interpolate n given points using cubic Bezier curves.

To connect 2 consecutive points P_i and P_{i+1} we will create a cubic Bezier curve with P_i and P_{i+1} as the initial and final control points, respectively. Apart from the two points, we need 2 more points to create a cubic Bezier curve that requires 4 control points.



Like in the given image with points P_1 to P_{10} has 9 cubic Bezier curves, including C_1 to C_9 . Each curve C_i is a cubic Bezier curve starting from P_i and ending at P_{i+1} . For example, C_1 starts from P_1 and ends at P_2 .

We know to create a cubic Bezier curve, we need 4 control points with the equation

$$P(t) = K_0 * (1 - t)^3 + K_1 * 3t(1 - t)^2 + K_2 * 3t^2(1 - t) + K_3 * t^3$$

where K_0 , K_1 , K_2 , and K_3 are the 4 control points. Here, $K_0 = P_i$ and $K_3 = P_{i+1}$.

We need to select points K_1 and K_2 such the C_i is continuous, and the curve between C_i and C_{i+1} is C_i^1 .

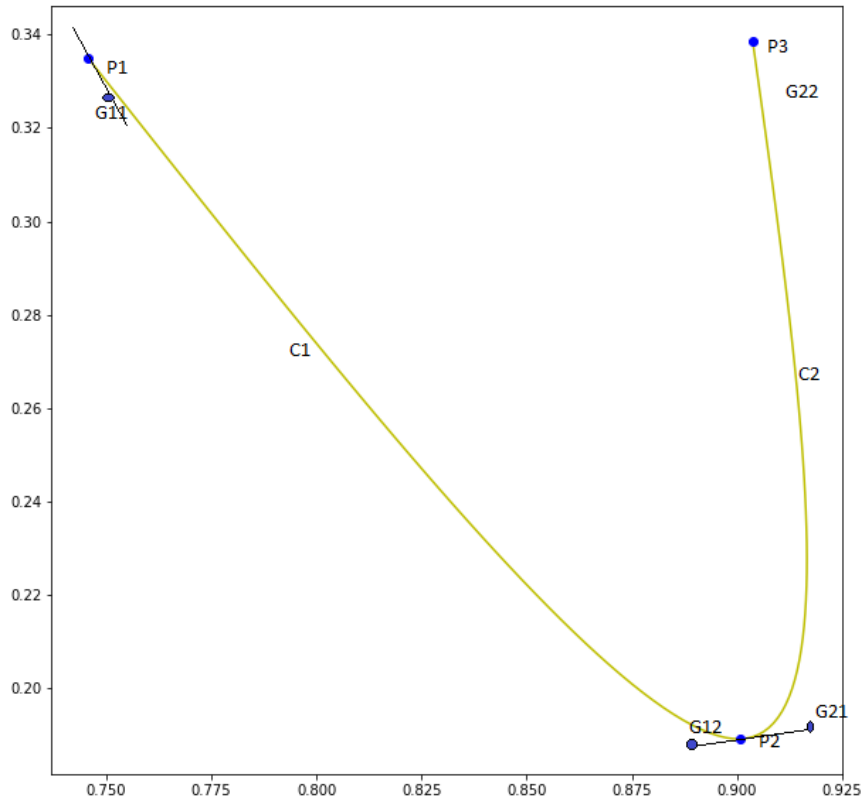
To ensure that C_i and C_{i+1} are continuous and differentiable at P_{i+1} , we need to ensure that the 3rd control point for C_i and 2nd control point for C_{i+1} and P_{i+1} are collinear.

In other words,

If we create 2 ghost control points for each curve C_i namely, G_{i1} and G_{i2} then,

G_{i2} , P_{i+1} , and $G_{(i+1)1}$ should be collinear.

This will ensure that C_i and C_{i+1} are differentiable as $G_{i2}P_{i+1}$ is a tangent to C_i (property of Bezier curve) and $P_{i+1}G_{(i+1)1}$ is a tangent to C_{i+1} (property of Bezier curve) and if the three points are collinear then the line $G_{i2}G_{(i+1)1}$ is a tangent to both C_i and C_{i+1} at P_{i+1} . Hence, the final curve will be differentiable at P_{i+1} .



Thus, we can create G_{11} and G_{12} randomly, G_{21} will be found using G_{12} and P_2 , and G_{22} can be chosen again randomly.

We can continue with the process until we create a complete curve.

Pseudocode

Function PieceWiseCubicBezierCurve(Points):

For P_k where $k = 1$ to $n-1$

If k is 1

Initialize G_{k1} randomly.

// RandomInitialization(P_k)

Initialize G_{k2} randomly.

// RandomInitialization(P_{k+1})

Else

Initialize G_{k1} as a point on $G_{(k-1)2}P_k$.

// CoPointInitialization($G_{(k-1)2}$, P_k)

Initialize G_{k2} randomly.

// RandomInitialization(P_{k+1})

Calculate $C_k = \text{CubicBezierCurve}(P_k, G_{k1}, G_{k2}, P_{k+1})$

Return $\{C_k \text{ where } k = 1 \text{ to } n-1\}$

Function RandomInitialization(P_k):

Initialize ε

{Small value to keep G near P}

$G_k = P_k + (-) \varepsilon$

Return G_k

Function CoPointInitialization($G_{(k-1)2}$, P_k)

{Using vector equations}

Initialize ε

$v = P_k - G_{(k-1)2}$

$u = v / ||v||$

$G_{k1} = P_k + \varepsilon * u$

Return G_{k1}

Function CubicBezierCurve(P_k , G_{k1} , G_{k2} , P_{k+1})

$C_k = P_k * (1-t)^3 + G_{k1} * t * (1-t)^2 + G_{k2} * t^2 * (1-t) + P_{k+1} * t^3$

Return C_k