

DIGITAL SIGNAL PROCESSING

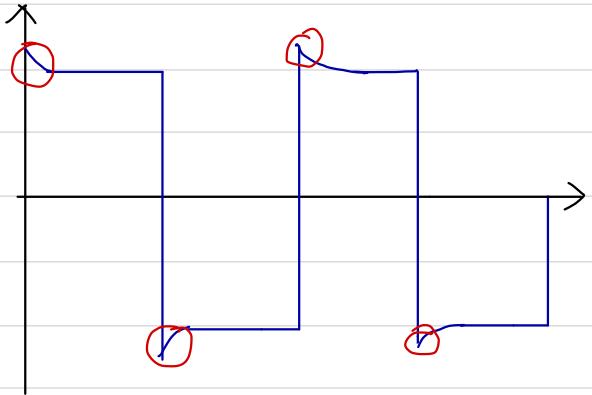
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DIGITAL SIGNAL PROCESSING

→ Digital source interact with digital system to create digital signal.

Gibb's phenomenon:

These distortion occur due to Gibb's phenomenon.



Because of limitation of bandwidth in oscilloscope, all the harmonics of fourier series are not added, which create these distortion.

- Let $x(t) = \sum_{k=-\infty}^{\infty} c_k e^{j k \omega_0 t}$, here $|c_k|$ is continuously decreasing. Also continuous series, $|c_i| \neq |c_j|$

- In discrete domain, $x(n) = x(n + KN)$
But $|c_k| = |c_{k+N}|$

Cosine waveform: $x_1(t) = A \cos(\omega t + \phi)$

Switch cosine waveform: $x_2(t) = x_1(t)(u(t) - u(t-t_0))$

Mathematical models used in DSP -

- 1> Difference equations
- 2> Impulse response $\rightarrow h[n]$
- 3> state variable model.
- 4> DTFS, DTFT, DFT, FFT
- 5> Z transform

$$S(n) = \begin{cases} u(n) - u(n-1) = 1 & , \text{ for only } n=0 \\ 0 & \text{otherwise} \end{cases}$$

Also $s(t) = \frac{d}{dt}(u(t))$

Signal classification:

Energy v/s Power

$$\text{Power} = \frac{V^2}{R} \text{ or } I^2 R$$

$$\text{if } R=1, \text{ Power} = V^2 \text{ or } I^2$$

$$\text{Let } x = V \text{ or } I$$

If x was complex, $x = |x| e^{j\phi}$

$$E \triangleq \lim_{N \rightarrow \infty} \sum_{n=-N}^N |x(n)|^2$$

For finite length signal, $P_{avg} = \frac{1}{2N+1} \sum_{n=-N}^N |x(n)|^2$

For infinite signal,

$$P_{av} = \lim_{N \rightarrow \infty} \frac{1}{2N+1} \sum_{n=-N}^N |x(n)|^2$$

- If E is finite then the signal with $P_{avg} = 0$.
- If E is infinite then it is power signal

DSD lab had Energy signal.

Periodic $\vee \wedge$ Aperiodic signal

Periodic: $x(n) = x(n+N)$
 $N \rightarrow$ fundamental period

If $x_1(n)$ has period N_1 ,
 $x_2(n)$ has period N_2
 $x(n) = x_1(n) + x_2(n)$

then $x(n)$ is periodic with period
 N if $N = pN_1 = qN_2$ where p, q are
 integers
 Also $N = \text{LCM}(N_1, N_2)$

eg 1: $x(n) = \cos\left(\frac{\pi}{9}n\right) + \frac{1}{2}\sin\left(\frac{n\pi}{7} + 30^\circ\right)$. Find period

$$\cos\left(\frac{\pi}{9}(n+N_1)\right) = \cos\left(\frac{\pi}{9}n\right)$$

$$\Rightarrow \frac{\pi N_1}{9} = 2\pi \Rightarrow N_1 = 18$$

$$\sin\left(30^\circ + \frac{\pi(n+N_2)}{7}\right) = \sin\left(30^\circ + \frac{\pi n}{7}\right)$$

$$\Rightarrow \frac{\pi N_2}{7} = 2\pi \quad \therefore N_2 = 14$$

$$\therefore N = \text{LCM}(18, 14) = 126$$

\therefore Fundamental period of $x(n) = 126$

NOTE: $y(n) = \alpha x_1(n) \pm \beta x_2(n)$ is periodic
 $z(n) = x_1^2(n) + \alpha x_2^2(n) \rightarrow$ not periodic

Even $\&$ odd signals:

$$\text{Even} \Rightarrow x(n) = x(-n)$$

$$\text{odd} \Rightarrow x(n) = -x(-n)$$

$$x(n) = x_e(n) + x_o(n) \rightarrow ①$$

$$x(-n) = x_e(n) - x_o(n) \rightarrow ②$$

$$x_e(n) = \frac{1}{2} [x(n) + x(-n)] \rightarrow ③$$

$$x_o(n) = \frac{1}{2} [x(n) - x(-n)] \rightarrow ④$$

$$x_o = [x(n) + (-1)x(-n)] \times y_2$$

$$x_{e/o}(n) = \frac{1}{2} [x(n) + e^{\pm j\pi} x(-n)]$$

$$\text{Ex. } \Rightarrow x(n) = e^{-n/2} u(n)$$

$$y(n) = 2x\left(\frac{5n}{3}\right)$$

$$z(n) = x(2n)$$

$$\Rightarrow x(n) = \begin{cases} 1, & n \text{ is even} \\ -1, & n \text{ is odd} \end{cases}$$

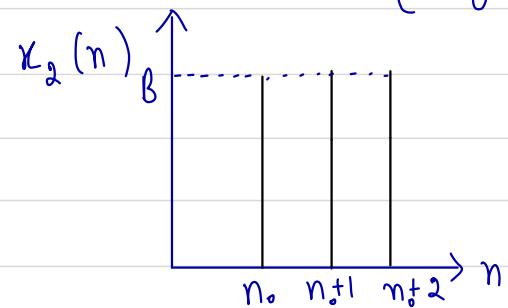
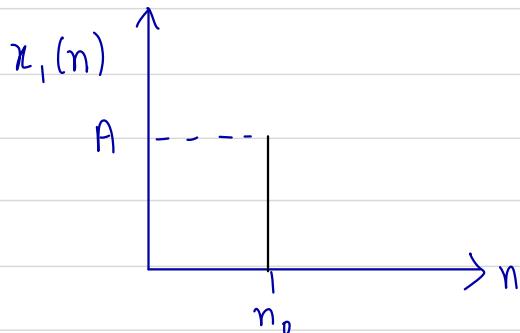
Delayed impulse & step sequence

Assume impulse of amplitude A, happens at $n=n_0$, instead of $n=0$,
 $\Rightarrow x_1(n) = A\delta(n-n_0)$

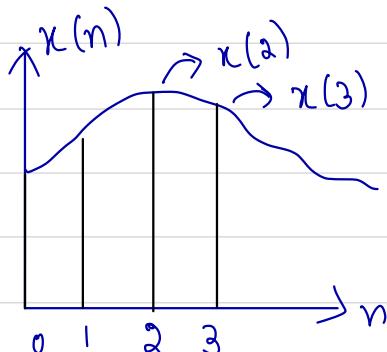
Let the step sequence happen from n_0 with amplitude B

$$\Rightarrow x_2(n) = Bu(n-n_0)$$

$$\Rightarrow x_2(n) = \begin{cases} B, & n \geq n_0 \\ 0, & n < n_0 \end{cases}$$



NOTE : Usually Periodic signals are power signal



$$x(n) = x(0)\delta(n-0) + x(1)\delta(n-1) + x(2)\delta(n-2) + \dots$$

$$= \sum_{k=-\infty}^{\infty} x(k)\delta(n-k)$$

Causal signals: Practical signals which can be generated in lab

Non-causal signals: Non practical signals which cannot be generated in lab.
(Usually starting from $-\infty$ and/or going upto $+\infty$)



$h \rightarrow$ impulse response

Convolution sum:

$$y(n) = \sum_{k=-\infty}^{\infty} x(k) h(n-k) = x(n) * h(n) \rightarrow ①$$

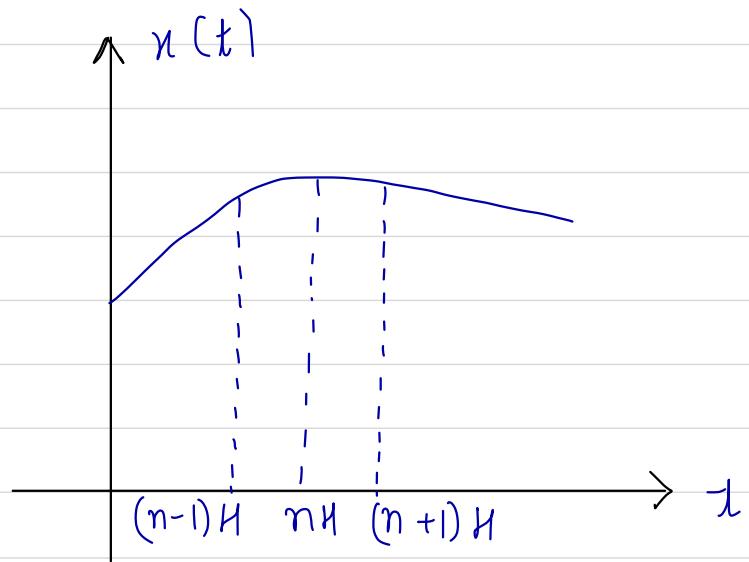
It is response of a LTI system excited by scaled and delayed arbitrary signal.

$$\text{Let } n-k = m \Rightarrow k \in (-\infty, \infty) \Rightarrow m \in (-\infty, \infty)$$

$$\Rightarrow k = n-m$$

$$y(n) = \sum_{m=-\infty}^{\infty} x(n-m) h(m) \rightarrow ②$$

$$= \sum_{m=-\infty}^{\infty} x(m) \cdot h(n-m)$$



$$y(t) = \int_0^t x(\tau) d\tau$$

$$\begin{aligned} y(nH) &= \int_0^{nH} x(\tau) d\tau \\ &= \int_0^{(n-1)H} x(\tau) d\tau + \int_{(n-1)H}^{nH} x(\tau) d\tau \end{aligned}$$

$$y(nH) = y[(n-1)H] + x[(n-1)H] H$$

$\Rightarrow y(n) = y(n-1) + H x(n-1)$,
 This is first order difference equation.

\Rightarrow This is also known as Euler's rule of integration.

Note: • $x(t) = \sum_{n=-\infty}^{\infty} c_n e^{jn\omega_0 T}$ in

continuous time domain.

• But in discrete time domain,

$$\omega_0 T = \Omega_0$$

If $x_1(n)$ has period N ,

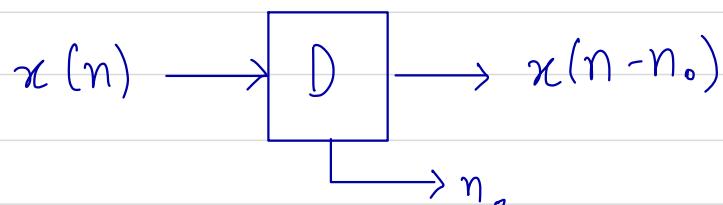
$$e^{j\Omega_0 n} = e^{j\Omega_0 (n+N)} = e^{j\Omega_0 n} \cdot e^{j\Omega_0 N}$$

$$\Rightarrow \Omega_0 N = 2\pi m$$

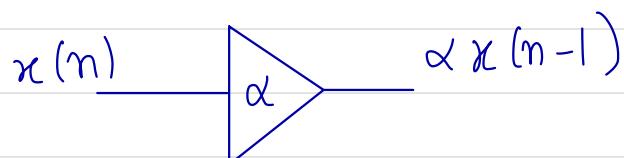
$$\therefore N = \frac{2\pi m}{\Omega_0}$$

Hardwares used in DSP

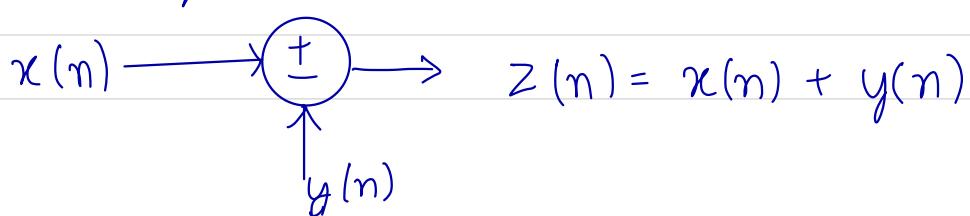
1) Delay unit:



2) Scaler or multiplier



3) Adder / Subtractor



LTI - DTS (Linear time invariant - Discrete time system) of order N .

$$y(n) = y(n-1) + x(n-1) \rightarrow ①$$

$$\begin{aligned} y(n) &= a_1 y(n-1) + a_2 y(n-2) + \dots + a_N y(n-N) + b_0 x(n) \\ &\quad + b_1 x(n-1) + \dots + b_N x(n-N) \rightarrow ② \end{aligned}$$

$$y(n) = \sum_{i=1}^{\infty} a_i y(n-i) + \sum_{k=0}^{\infty} b_k x(n-k)$$

Properties of even and odd symmetric sequences

Given: $x_1(n) = \cos \omega_1 n$ $x_2(n) = \cos \omega_2 n$
 $x_3(n) = \sin \omega_3 n$ $x_4(n) = \sin \omega_4 n$

- Delaying a signal by integer multiple of period, it does not change symmetry of signal.
- Let $y_1(n) = x_1(n) + x_2(n)$.

Here both are of even symmetry so $y_1(n)$ is even.

$$y_2(n) = x_3(n) + x_4(n).$$

$y_2(n)$ is neither odd nor even.

$$y_3(n) = x_3(n) + x_4(n). \quad y_3(n) \rightarrow \text{odd}$$

$$\begin{aligned} \text{Let } y_4(n) &= x_1(n) \cdot x_2(n) \Rightarrow y_4(n) = \text{even} \\ y_5(n) &= x_1(n) \cdot x_3(n) \Rightarrow y_5(n) = \text{odd} \\ y_6(n) &= x_3(n) \cdot x_4(n) \Rightarrow y_6(n) = \text{even} \end{aligned}$$

NOTE:
 odd x even = odd
 odd x odd = even
 even x even = even

$$x_o(t) = e^{j\omega_o t} \xrightarrow[t=nT]{} e^{j\omega_o nT} = e^{jn\Omega_o}$$

$$\Omega_o = \omega_o T \quad x(n) = e^{jn\omega_o}$$

$$T \stackrel{\Delta}{=} \frac{\Omega_o}{\omega_o}$$

$$\underset{k\text{th harmonic}}{x_k(t)} = e^{jk\omega_o t} \quad \& \quad x_k(n) = e^{jk\Omega_o n} \quad \text{are}$$

$$\begin{aligned} x_k(t+T) &= e^{jk\omega_o(t+T)} \\ &= e^{jk\omega_o T} \cdot e^{jk\omega_o t} \\ &= e^{jk\omega_o \frac{2\pi}{\omega_o}} \cdot e^{jk\omega_o t} \\ &= e^{jk\omega_o t} \\ &= x_k(t), \end{aligned}$$

$$\begin{aligned} x_{(k+N)}(n) &= e^{j(k+N)\Omega_o n} \\ &= e^{jk\Omega_o n} \cdot e^{jN\Omega_o n} \\ &= e^{jk\Omega_o n} \cdot e^{jN \times \frac{2\pi m}{N} n} \\ &= x_k(n), \end{aligned}$$

$$\therefore x_k(n) = x_{k+mN}(n),$$

Discrete time signals

$$x_1(t) = e^{j\omega_0 t} = \cos \omega_0 t + j \sin \omega_0 t$$

$$x_k(t) = e^{jk\omega_0 t}$$

$$x_k(n) = e^{jk\omega_0 T_s n} = e^{jk\Omega_0 n}$$

$$\Rightarrow x(n) = e^{j\Omega_0 n}$$

$$x_{k+N}(n) = x_k(n) \quad N \text{ is period of } x_k$$

$$\text{i.e. } N = \frac{2m\pi}{\Omega_0}$$

Ex: Given $x(t) = \sum_{k=-2}^2 c_k e^{jk \frac{2\pi}{3} t}$ with $T_s = 4s$

Find appropriate values of m & N .

$$\begin{aligned} x(n) &= \sum_k d_k e^{jk \left(\frac{2\pi}{3}\right) n} \\ &= \sum_k d_k e^{jk \left(\frac{8\pi}{3}\right) n} \end{aligned}$$

$$N = \frac{2\pi m}{\Omega_0}$$

$$N = \frac{2\pi m}{8\pi} \times 3 = \frac{3}{4} m$$

$$\text{For } m = 4, \quad N = 3$$

Discrete time systems

$$y(n) = x(n) * h(n) = \sum_{k=0}^n x(k) \cdot h(n-k)$$



When $h(n) = \delta(n)$

$$Y(n) = x(n) * h(n) = x(n) * \delta(n)$$

$$Y(n) = \sum_{k=0}^{\infty} x(k) \delta(n-k)$$

$$Y(n) = \sum_{k=0}^{n-1} x(k) \delta(n-k) + x(0) \delta(0) + \sum_{k=n+1}^{\infty} x(k) \delta(n-k)$$

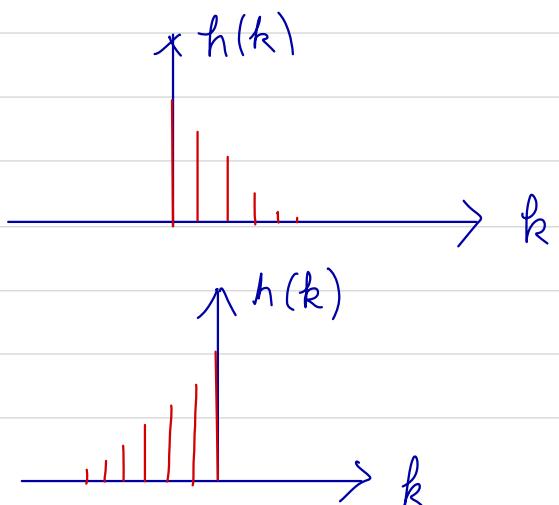
$$= x(n)$$

Eg: Given: $x(n) = \{1, -1, 1, 2, 0.5, -0.5, 1\}$

$$h(n) = \alpha^n u(n) \quad \alpha = 0.9 \quad \text{Find } y(n)$$

$$h(k) = \alpha^k u(k)$$

$$h(-k) = \alpha^{-k} u(-k)$$



NOTE • If x is non zero for $[N_1, N_2]$ and h is non zero for $[N_3, N_4]$. Then to get non-zero convolution:

$$N_1 + N_3 \leq n \leq N_2 + N_4$$

\therefore If x has m samples & h has l samples then number of samples in $y = m + l - 1$
 i.e. $m = N_2 - N_1 + 1$
 $l = N_4 - N_3 + 1$

Ex: If $h(n) = \{1, 2, 0, -1, 1\}$ and
 $x(n) = \{1, 3, -1, -2\}$. Find $y(n)$

$$y(n) = \sum_k h(k) x(n-k)$$

$$y(0) = 1$$

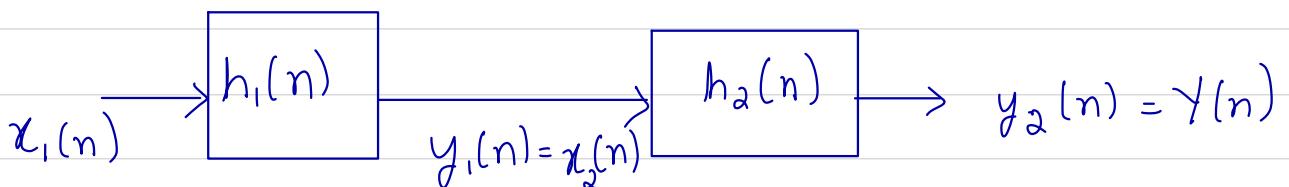
$$y(1) = -1 + 6 = 5$$

⋮

$$y(7) = \text{norm value}$$

$$y(8) \rightarrow y(\infty) = 0$$

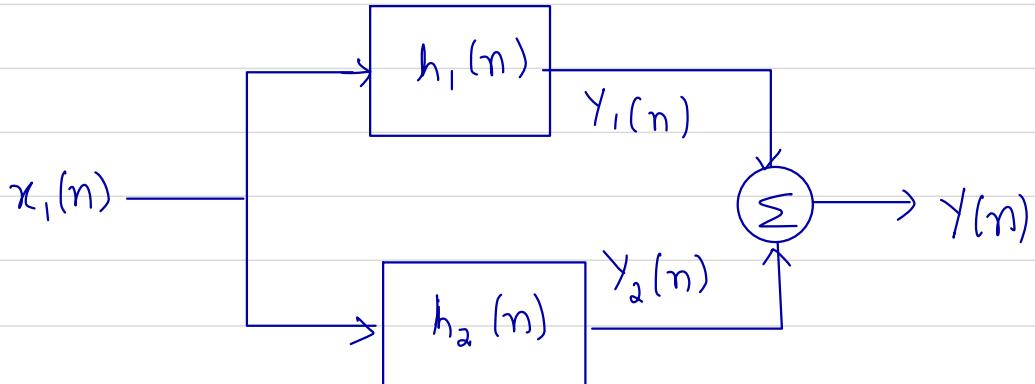
Cascade systems of parallel arrangements of DT-LTI



$$y_1(n) = h_1(n) * x_1(n)$$

$$y(n) = x_1(n) * h_1(n) * h_2(n)$$

$$\therefore h_{eq}(n) = h_1(n) * h_2(n) * h_3(n) * \dots * h_m(n)$$



$$h_{eq}(n) = h_1(n) + h_2(n)$$

Periodic
Convolution:

$$x_1(n) \quad \left. \begin{matrix} \\ x_2(n) \end{matrix} \right\} \text{Period} = N \quad \text{but} \quad x_1(n) \neq x_2(n)$$

$$Y(n) = \sum_{k=-\infty}^{\infty} x_1(k) * x_2(n-k)$$

For periodic function, k can be written as $k = rN + l$
 $l \rightarrow \text{Sample value}$
 $N \rightarrow \text{Period}$

$$l = 0, 1, \dots, N-1$$

$$\therefore Y(n) = \sum_{r=-\infty}^{\infty} \left[\sum_{l=0}^{N-1} x_1(rN+l) x_2(n-rN-l) \right]$$

If $\boxed{\quad}$ block is positive then $y(n)$ diverges. So this convolution can't be applied on periodic signals.

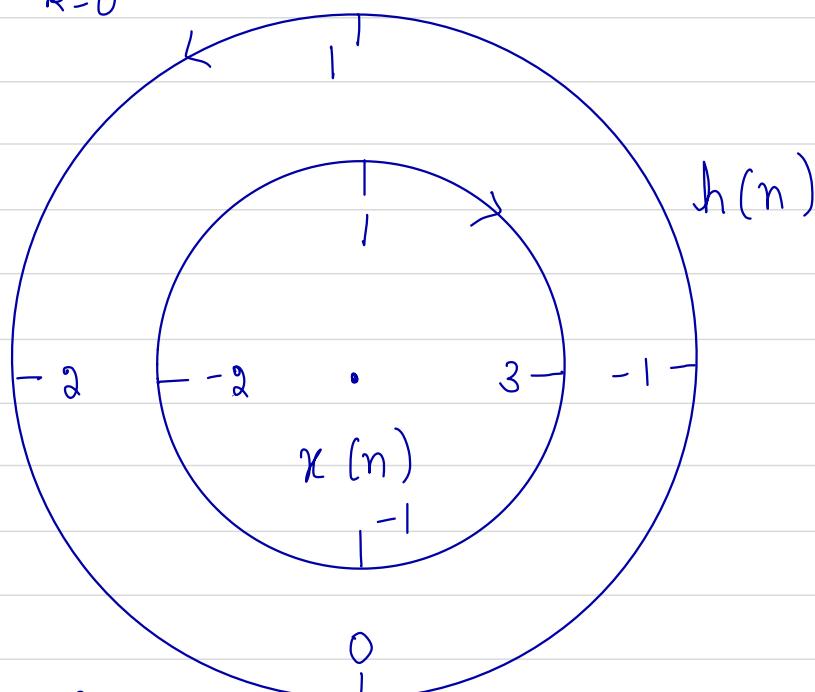
So

$y_h(n) = \sum_{k=0}^{N-1} x_1(k) \cdot x_2(n-k)$ is called
circular or periodic convolution.

Eg 3: $x(n) = [1 \ 3 \ -1 \ -2]$ \uparrow $h(n) = [1 \ 2 \ 0 \ -1]$ \uparrow

Both $x(n)$ & $h(n)$ are periodic with period 4. Find $y_p(n)$

Ans $y_p(n) = \sum_{k=0}^3 x(k) \cdot h(n-k)$



$$y(0) = \sum_{k=0}^3 x(k) h(-k)$$

$$= 1 - 4 + 0 - 3 = -6,$$

For $y(1)$ rotate outercycle by 1 unit in clockwise direction:

$$y(1) = \sum_{k=0}^3 x(k) h(1-k)$$

$$y(1) = 2 + 3 + 1 = 6,$$

$$Y(2) = -1 + 2 + 0 + 6 = 7,$$

$$Y(3) = -2 - 1 + 0 - 2 = -5$$

$$Y(n) = \begin{bmatrix} -6 & 6 & 7 & -5 \end{bmatrix}$$

\uparrow

Zero padding

Repeating $\left\{ \begin{array}{l} x(n) \rightarrow \{ \}_{4 \times 1} \\ h(n) \rightarrow \{ \}_{5} \end{array} \right\} \rightarrow \begin{array}{l} LCM = 2 \\ N \rightarrow 2 \end{array}$

$$x(n) = \{ 1, 3, -1, -2, 0 \}_{5 \times 1}, N=5$$

$$h(n) = \{ 1, 2, 0, -1, 1 \}_{5 \times 1}.$$

NOTE: By adding any number of zeros the energy wont change.

$$Y_p(n) = \sum_{k=0}^4 x(k) h(n-k)$$

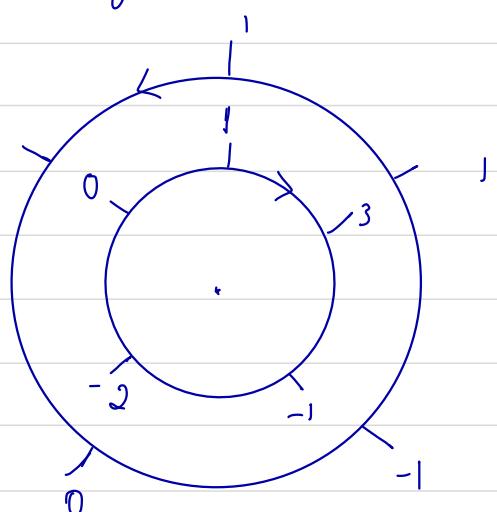
$$Y_p(0) = 5,$$

$$Y_p(1) = 2 + 0 + 2 - 1 + 3 = 6$$

$$Y_p(2) = 0 + 0 - 2 - 1 + 6 = 3$$

$$Y_p(3) = -1 + 0 - 2 - 2 + 0 = -5,$$

$$Y_p(4) = 1 + 0 + -4 + 0 - 3 = -6$$



In linear

convolution

$$y(0) = 1, \quad y(5) = 4 \Rightarrow (y(5) = 5 \text{ in circular})$$
$$y(1) = 5, \quad y(6) = 1 \Rightarrow (y(7) = 6 \text{ in circular})$$

$$\rightarrow x(n) = \{1, 3, -1, -2, 0, 0, 0, 0\}_{8x1}$$
$$h(n) = \{1, 2, 0, -1, 1, 0, 0, 0\}_{8x1}$$

For above sequences $y_p(n) \rightarrow 0-7 = y_e(n)$

NOTE: Adding zeros towards the end, also preserves spectral behaviour of sequence as well as the energy.

Difference equations

$$\sum_{k=0}^N a_k y(n-k) = \sum_{k=0}^M b_k x(n-k)$$

Linear constant differential equation of order N

$$\Rightarrow y(n) = \frac{1}{a_0} \left[-\sum_{k=1}^N a_k y(n-k) + \sum_{k=0}^M b_k x(n-k) \right]$$

$$y(0) = \frac{1}{a_0} \left[-\sum_{k=1}^N a_k y(-k) + \sum_{k=0}^M b_k x(-k) \right]$$

For solving above equation we require $y(-1), y(-2), y(-3), \dots, y(-N)$, so the given equation is N^{th} order difference equation.

$$y(n) = y_h(n) + y_p(n)$$

where $y_h(n)$ i.e when $x(n)=0$
 $y_p(n)$ i.e for particular $x(n)$

Ex 1) Given $y(n) = x(n) - 3y(n-1)$ with $y(-1) = 0$
& $x(n) = 5n+3 \in 2n^3+n$

Ans Consider $x(n) = 0$

$$\Rightarrow y(n) + 3y(n-1) = 0$$

$$\left| \begin{array}{l} \alpha dy \\ dt \end{array} \right. + \beta y = 0 \Rightarrow y = A e^{\alpha t}$$

Similarly let $y(n) = A \alpha^n$

$$\therefore A \alpha^n + 3A \alpha^{n-1} = 0$$

$$\Rightarrow A \alpha^{n-1} [\alpha + 3] = 0$$

$$A \alpha^{n-1} \neq 0 \quad \therefore \quad \alpha + 3 = 0 \Rightarrow \alpha = -3$$

$$\therefore y_h(n) = A(-3)^n$$

Now let $x(n) = 2n^3+n$

$$\Rightarrow y(n) + 3y(n-1) = 2n^3+n+0$$

$\because y(n)$ is linear transform, output should be quadratic as input is quadratic

$$\therefore y_p(n) = B n^2 + C n + D$$

$$\therefore B n^2 + C(n-1) + D + 3[B(n-1)^2 + C(n-1) + D]$$

$$= 2n^3+n$$

$$\Rightarrow n^2[B + 3B] + n[C + 3(-2B) + 3C] + D - 3C$$

$$+ 3D + 3B = 2n^3+n$$

$$4B = 2 \Rightarrow B = \frac{1}{2}$$

$$4C - 6B = 1$$

$$\Rightarrow C = \frac{1+6B}{4} = \frac{1}{4}$$

$$D = \frac{3(C-B)}{4} = \frac{3}{8}$$

$$\therefore y_p(n) = \frac{n^3}{2} + n + \frac{3}{8}$$

$$\therefore y(n) = y_h(n) + y_p(n)$$

$$\text{But } Y(-1) = 0$$

$$\Rightarrow \frac{n^3}{2} + n + 8 + A(-3)^n = 0 \quad \text{At } n = -1,$$

$$\frac{1}{2} - 1 + 8 + A(-3)^{-1} = 0$$

$$\Rightarrow \frac{A}{3} = \frac{15}{2} \Rightarrow A = \frac{45}{2}$$

$$\therefore y(n) = \left(\frac{45}{2}\right)(-3)^n + \frac{n^3}{2} + n + 8,$$

NOTE:

General form of the particular solution for several types of input signals:
Particular solution:

A

AM^n

An^m

$A \cos \omega_0 n$

$A \sin \omega_0 n$

K

KM^n

$K_M n^M + K_{M-1} n^{M-1} + \dots + K_0$

$K_1 \cos \omega_0 n + K_2 \sin \omega_0 n$

$K_1 \cos \omega_0 n + K_2 \sin \omega_0 n$

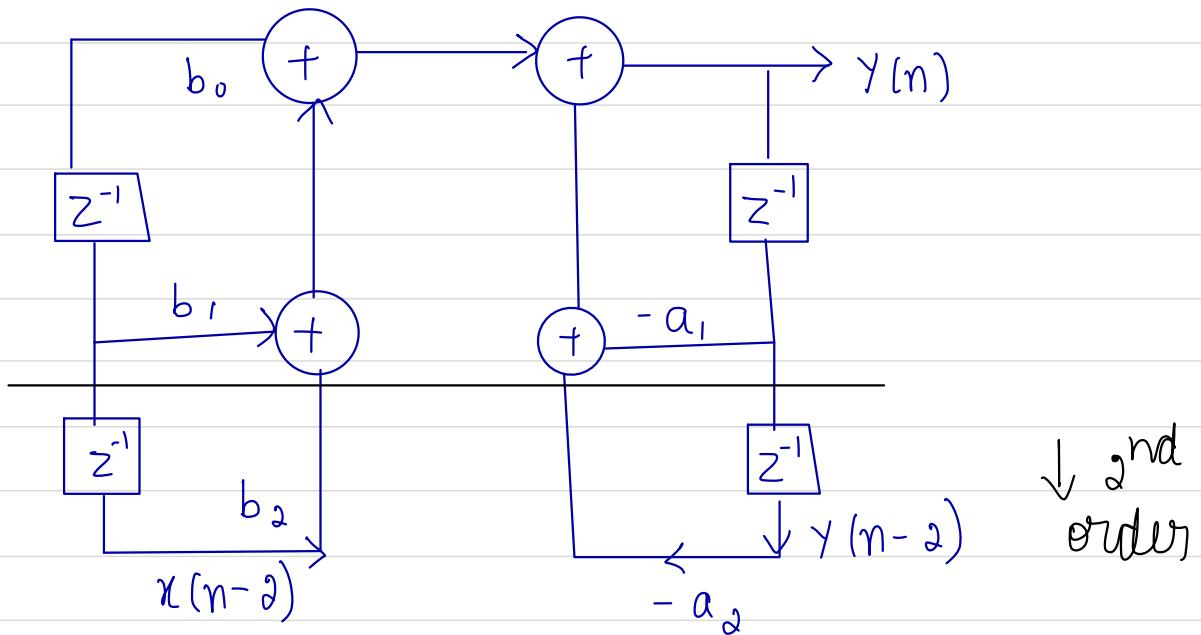
Direct form I

Consider a 1st order system:

$$y(n) = \sum_{i=0}^{M-1} b_i x(n-i) - \sum_{i=1}^{M-1} a_i y(n-i)$$

i.e. $M=1$

$$\therefore y(n) = b_0 x(n) + b_1 x(n-1) - a_1 y(n-1) - a_2 y(n-2)$$



Stability of LTI-DTS

$$y(n) = \sum_{k=-\infty}^{\infty} x(k) \cdot h(n-k)$$

for any n , $|x(n)| \leq p < \infty$

$$|Y(n)| = \left| \sum_{k=-\infty}^{\infty} x(k) \cdot h(n-k) \right| \leq \sum_{k=-\infty}^{\infty} |x(k)| |h(n-k)|$$

$$\leq p \sum_{k=-\infty}^{\infty} |h(n-k)| \leq p \sum_{k=-\infty}^{\infty} |h(k)| \leq M$$

\therefore The system is stable if

$$\sum_{k=-\infty}^{\infty} |h(k)| \leq M < \infty$$

Discrete time fourier series

$$x(t) = \sum_{k=-\infty}^{\infty} c_k e^{j k \omega_0 t}$$

$\omega_0 = \frac{2\pi}{T}$

↓
(continuous fourier series)

DTFT. $x(n) = \sum_k a_k e^{j k \Omega_0 n}$

$$\Omega_0 = \frac{2m\pi}{N}$$

$$\begin{aligned}\therefore x(n) &= \sum_k a_k e^{j \Omega_0 k N} \\ &= \sum_k a_k x_k\end{aligned}$$

$$\begin{aligned}\therefore x_{k+N}(n) &= e^{j (k+N) \cdot \frac{2\pi m}{N} n} \\ &= e^{j k \frac{2\pi m}{N}} \\ &= x_k(n)\end{aligned}$$

We have,

$$x(n) = \sum_{m=\langle N \rangle} a_m e^{j m \Omega_0 n}$$

$$x(n) e^{-j k \Omega_0 n} = \sum_{m=\langle N \rangle} a_m e^{j(m-k) \Omega_0 n}$$

$$\Rightarrow \sum_{n=0}^{N-1} x(n) e^{-j k \Omega_0 n} = \sum_{n=0}^{N-1} \sum_{m=\langle N \rangle} a_m e^{j(m-k) \Omega_0 n}$$

$$= \sum_{m=\langle N \rangle} a_m \left[\sum_{n=0}^{N-1} e^{j(m-k)\frac{2\pi}{N}} \right]^n$$

Now if $m - k \neq \pm N$

then $\sum_{n=0}^{N-1} \left[e^{j(m-k)\frac{2\pi}{N}} \right]^n = \frac{1 - e^{j(m-k)\frac{2\pi N}{N}}}{1 - e^{j(m-k)\frac{2\pi}{N}}} = 0$

Now if $m - k = \pm N$

then $\sum_{n=0}^{N-1} \left[e^{j(m-k)\frac{2\pi}{N}} \right]^n = \sum_{n=0}^{N-1} 1 = N$,

$\therefore \boxed{\quad}$ term can be written as
 $N \cdot \delta(m - k - \pm N)$ i.e. $\begin{cases} N & \text{if } m - k = \pm N \\ 0 & \text{if } m - k \neq \pm N \end{cases}$

$$\therefore \sum_{n=0}^{N-1} x(n) e^{-j k \Omega_0 n} = \sum_{m=\langle N \rangle} N a_m \delta(m - k - \pm N)$$

But to remain within fundamental block, $n = 0$

$$\therefore \sum_{n=0}^{N-1} x(n) e^{-jk\Omega_0 n} = N \sum_{m=0}^{N-1} a_m \delta(m-k)$$

But $\delta(m-k) = 1$ only when $m=k$

$$\therefore N a_k = \sum_{n=0}^{N-1} x(n) e^{-jk\Omega_0 n}$$

$$\therefore a_k = \frac{1}{N} \sum_{n=0}^{N-1} x(n) e^{-jk\Omega_0 n}$$

NOTE: • Fourier transform coefficients are either real valued or they are complex conjugate pairs.

$$\bullet C_k = \frac{1}{T} \int_{-T/2}^{T/2} x(t) e^{-jk\omega_0 t} dt$$

Eg1) Given $x(n) = \{2, -1, 1, 2\}$, $N=4$. Find a_k

$$a_k = \frac{1}{4} \sum_{n=0}^3 x(n) \left(e^{-jk\frac{2\pi}{4}}\right)^{kn}$$

$$= \frac{1}{4} \sum_{n=0}^3 x(n) (-j)^{kn}$$

$$a_0 = \frac{1}{4} \sum_{n=0}^3 x(n) = \frac{2+2-1+1}{4} = 1,$$

$$a_1 = \frac{1}{4} \sum_{n=0}^3 x(n) (-j)^n = \frac{2+j-1+2j}{4} = \frac{1+3j}{4}$$

$$a_2 = \frac{1}{4} \sum_{n=0}^3 x(n) (-j)^{2k}$$

$$= \frac{1}{4} [2 + 1 + 1 - 2] = \frac{1}{2},$$

$a_3 = \frac{1-3j}{4}$ ($\because a_2 \in \mathbb{R}$, a_3 should be conjugate of a_1)

$$\therefore a_k = \left\{ 1, \frac{1+3j}{4}, \frac{1}{2}, \frac{1-3j}{4} \right\}$$

NOTE $a_k = a_{N-k}^*$ where N is period

DTFS properties:

1) Linearity: $x(n) \leftrightarrow a_k$
 $h(n) \leftrightarrow b_k$
 $y(n) \leftrightarrow c_k$

} period N

$$y(n) = \alpha x(n) + \beta h(n) \Rightarrow c_k = \alpha a_k + \beta b_k$$

2) Time shift: $x(n) \xrightarrow{\text{delay } (m)} y(n) = x(n-m)$,

$x(n)$ is periodic with period N , $x_n \leftrightarrow a_k$
then $y(n)$ is also periodic with period N
and $y(n) \leftrightarrow b_k$

$$b_k = \frac{1}{N} \sum_{n=0}^{N-1} y(n) e^{-j k \Omega_0 n}$$

$$= \frac{1}{N} \sum_{n=0}^{N-1} x(n-m) e^{-j k \Omega_0 n}$$

let $n-m = l$, $n=0 \Rightarrow l=-m$
 $n=N-1 \Rightarrow l=N-1-m$

$$b_k = \frac{1}{N} \sum_{l=-m}^{-m+N-1} x(l) e^{-jk\omega_0(l+m)}$$

$$= \left(\frac{e^{-jk\omega_0 m}}{N} \right) \sum_{l=0}^{N-1} x(l) e^{-jk\omega_0 l}$$

$b_k = e^{-jk\omega_0 m} a_k //$

Also $|b_k| = |a_k|$

3) Modulation: Consider $x(n)$ & $h(n)$ with period N , and $x(n) \neq h(n)$

$$x(n) \leftrightarrow a_k, \quad h(n) \leftrightarrow b_k, \quad y(n) \leftrightarrow c_k$$

$$y(n) = x(n) \cdot h(n) \Rightarrow c_k = a_k \circledast b_k$$

$$c_k = \frac{1}{N} \sum_{n=0}^{N-1} x(n) \cdot h(n) \cdot e^{-jk\omega_0 n}$$

$$= \frac{1}{N} \sum_{n=0}^{N-1} \left[\sum_{m=0}^{N-1} a_m e^{jm\omega_0 n} \right] h(n) e^{-jk\omega_0 n}$$

$$= \sum_{m=0}^{N-1} a_m \cdot \left[\frac{1}{N} \sum_{n=0}^{N-1} h(n) e^{-j(k-m)\omega_0 n} \right]$$

But, $\frac{1}{N} \sum_{n=0}^{N-1} h(n) e^{-j(k-m)\omega_0 n} = b_{k-m}$

$$\therefore c_k = \sum_{m=0}^{N-1} a_m \cdot b_{k-m}$$

$$\therefore c_k = a_k \circledast b_k //$$

(Periodic convolution)

NOTE $\circledast \rightarrow$ Circular

$*$ - linear

Sampling; Consider impulse train;

$$s_T(t) = \sum_{n=-\infty}^{\infty} \delta(t-nT) = \int_{-\infty}^{\infty} c_k e^{j k \omega_0 t}$$

$$c_k = \frac{1}{T} \int_{-T/2}^{T/2} s_T(t) e^{-jk\omega_0 t} dt$$

$$= \frac{1}{T} \int_{-T/2}^{T/2} \left(\sum_{n=-\infty}^{\infty} \delta(t-nT) \right) e^{jk\omega_0 t} dt$$

$$= \frac{1}{T} \int_{-T/2}^{T/2} 1 \cdot e^{jk\omega_0 t} dt = \frac{1}{T}$$

$$\therefore s_T(t) = \int_{-\infty}^{\infty} \frac{1}{T} e^{jk\omega_0 t} = 2\pi \delta(\omega - k\omega_0)$$

Discrete time Fourier Transform (DTFT)

$$x(t) \xrightarrow{\text{CTFT}} X(\omega)$$

$$X(\omega) = \int_{-\infty}^{\infty} x(t) e^{-j\omega t} dt$$

$$x(t) \xrightarrow{\text{sampling}} x_s(t)$$

$$x(t) \xrightarrow{\times} x_s(t)$$

$$P(t) = \sum_{n=-\infty}^{\infty} \delta(t - nT_s)$$

$$x_s(t) \xrightarrow{\text{CTFT}} X_s(\omega)$$

$$X_s(\omega) = \int_{-\infty}^{\infty} x_s(t) e^{-j\omega t} dt$$

$$x_s(t) = x(t) \sum_{n=-\infty}^{\infty} \delta(t - nT_s)$$

$$x_s(t) = \sum_{n=-\infty}^{\infty} x(nT_s) \delta(t - nT_s)$$

$$\therefore X_s(\omega) = \int_{-\infty}^{\infty} \sum_{n=-\infty}^{\infty} x(nT_s) \cdot \delta(t - nT_s) e^{-j\omega t} dt$$

We can represent $x(nT_s)$ as $x(n)$

$$X_s(\omega) = \sum_{n=-\infty}^{\infty} x(n) \int_{-\infty}^{\infty} \delta(t - nT_s) e^{-j\omega t} dt$$

$$= \sum_{n=-\infty}^{\infty} x(n) e^{-j\omega n T_s}$$

$$\omega T_1 = \underline{\Omega} \quad \therefore X_s(\underline{\Omega}) = \sum_{n=-\infty}^{\infty} x(n) e^{-j\omega T_1 n}$$

$\rightarrow \underline{\Omega}$ is continuous frequency variable defined for sequence.

$$X(\underline{\Omega}) = \sum_{n=-\infty}^{\infty} x(n) e^{-j\underline{\Omega} n}$$

Now replace $\underline{\Omega} \pm 2m\pi$ with $\underline{\Omega} \pm 2m\pi$

$$X(\underline{\Omega} \pm 2m\pi) = \sum_{n=-\infty}^{\infty} x(n) e^{-j(\underline{\Omega} \pm 2m\pi)n}$$

$$= X(\underline{\Omega})$$

Inverse DTFT

$$X(\underline{\Omega}) = g_1(n)$$

$$x(n) = g_2(\underline{\Omega})$$

$$X(\underline{\Omega}) = \sum_{p=-\infty}^{\infty} x(p) e^{-j\underline{\Omega} p}$$

$$\int_{-2\pi}^{2\pi} X(\underline{\Omega}) e^{j\underline{\Omega} n} d\underline{\Omega} = \int_{-2\pi}^{2\pi} \left[\sum_{p=-\infty}^{\infty} x(p) e^{-j\underline{\Omega} p} \right] e^{j\underline{\Omega} n} d\underline{\Omega}$$

$$\Rightarrow \int_0^{2\pi} X(\underline{\Omega}) e^{j\underline{\Omega} n} d\underline{\Omega} = \sum_{p=-\infty}^{\infty} x(p) \int_0^{2\pi} e^{(n-p)\underline{\Omega}} d\underline{\Omega}$$

$$\text{if } n = p, \int_0^{2\pi} e^{j(n-p)\omega} = 2\pi$$

$$\text{else } \int_0^{2\pi} e^{j(n-p)\omega} = 0$$

$$\therefore \int_0^{2\pi} e^{j(n-p)\omega} = 2\pi \delta(n-p)$$

$$\therefore \int_0^{2\pi} X(\omega) e^{j\omega n} d\omega = \sum_{p=-\infty}^{\infty} x(p) \cdot 2\pi \delta(n-p)$$

$$= x(n) \cdot 2\pi$$

$$\therefore x(n) = \frac{1}{2\pi} \int_0^{2\pi} X(\omega) e^{-j\omega n} d\omega$$

Eg: Given: $x(n) = a^n u(n)$ with $|a| < 1$.
 Find $X(\omega)$ and sketch it.

$$x(n) = \begin{cases} a^n, & n \geq 0 \\ 0, & n < 0 \end{cases}$$

$$X(\omega) = \sum_{n=-\infty}^{\infty} x(n) e^{-j\omega n}$$

$$X(\omega) = \sum_{n=0}^{\infty} a^n e^{-j\omega n} = \sum_{n=0}^{\infty} (ae^{-j\omega})^n$$

$$\text{Here } |ae^{-j\omega}| < 1$$

$$\therefore X(\omega) = \frac{1}{1 - ae^{-j\omega}}$$

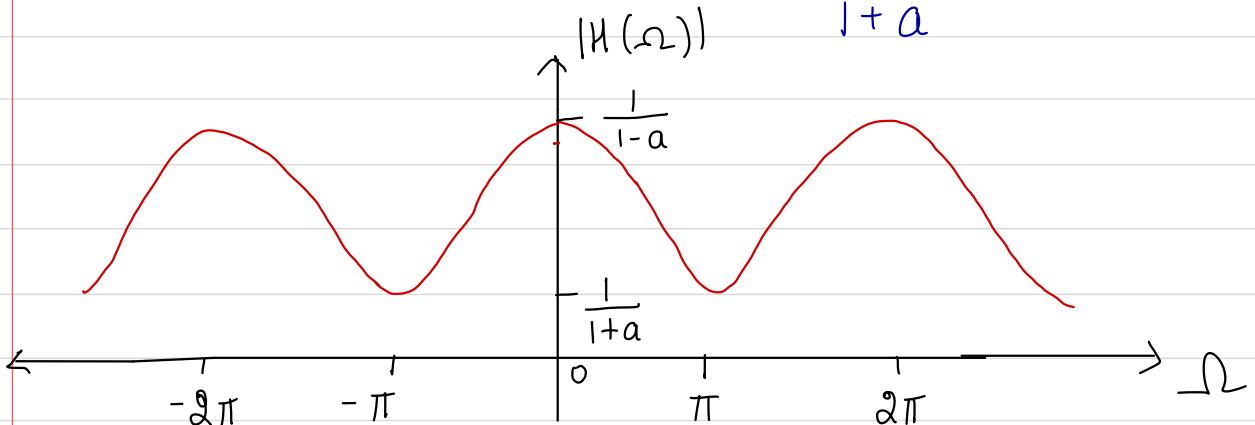
$$\therefore X(\omega) = \frac{1}{1 - a\cos\omega + ja\sin\omega}$$

$$|X(\omega)| = \frac{1}{\sqrt{(1-a\cos\omega)^2 + (a\sin\omega)^2}}$$

$$= \frac{1}{\sqrt{1+a^2 - 2a\cos\omega}}$$

at $\omega = 0$, $|X(0)| = \frac{1}{1-a}$

at $\omega = \pm\pi$, $|X(\pm\pi)| = \frac{1}{1+a}$



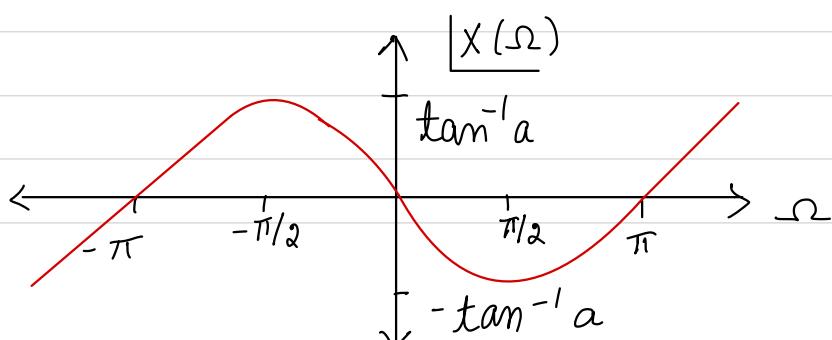
$$X(\omega) = -\tan^{-1} \left(\frac{a\sin\omega}{1 - a\cos\omega} \right)$$

at $\omega = 0$, $X(0) = 0$

at $\omega = \pm\pi$, $X(\pm\pi) = 0$

at $\omega = +\pi/2$, $|X(\pi/2)| = -\tan^{-1} a$

at $\omega = -\pi/2$, $|X(-\pi/2)| = \tan^{-1} a$



NOTE: If $x(n) = e^{j\omega_0 n} \Rightarrow X(\omega) = 2\pi \delta(\omega - \omega_0)$

If $x(n)$ is periodic,
 $X_p(\omega) = 2\pi \sum_{m=-\infty}^{\infty} \delta(\omega - \omega_0 - 2m\pi)$

Consider $x_p(\omega)$,

$$x(n) = \frac{1}{2\pi} \int_{[-\pi]}^{\pi} x_p(\omega) e^{j\omega n} d\omega$$

$$= \frac{1}{2\pi} \sum_{m=-\infty}^{\infty} \int_{-\pi}^{\pi} \delta(\omega - \omega_0 - 2m\pi) \times 2\pi e^{j\omega n} d\omega$$

But $m=0$ for range $(-\pi, \pi)$

$$\text{So } x(n) = \frac{1}{2\pi} \times 2\pi \int_{-\pi}^{\pi} \delta(\omega - \omega_0) e^{j\omega n} d\omega$$

$$x(n) = e^{j\omega_0 n} //$$

DTFT properties

1) Periodicity: $X(\omega) = X(\omega \pm 2m\pi)$

2) Linearity: $x_1(n) \leftrightarrow X_1(\omega)$

$x_2(n) \leftrightarrow X_2(\omega)$

$$y(n) = \alpha x_1(n) + \beta x_2(n)$$

$$\Rightarrow Y(\omega) = \alpha X_1(\omega) + \beta X_2(\omega)$$

3) Time shift: If $y(n) = x(n-m)$

$$\Rightarrow Y(\Omega) = \sum_{n=-\infty}^{\infty} x(n-m) e^{-j\Omega n}$$

$$\text{let } n-m = l \Rightarrow Y(\Omega) = \sum_{l=-\infty}^{\infty} x(l) e^{-j\Omega(l+m)}$$

$$= e^{-j\Omega m} \sum_{l=-\infty}^{\infty} x(l) e^{-j\Omega l}$$

$$\therefore Y(\Omega) = e^{-j\Omega m} X(\Omega) //$$

$$\Rightarrow \text{Ang } Y = \text{Ang } X - (m\Omega),$$

4) Frequency shift: $y(n) = x(n) e^{j\Omega_0 n}$

$$\begin{aligned} Y(\Omega) &= \sum_{n=-\infty}^{\infty} x(n) e^{j\Omega_0 n} e^{-j\Omega n} \\ &= \sum_{n=-\infty}^{\infty} x(n) e^{-j(\Omega - \Omega_0)n} \end{aligned}$$

$$\therefore Y(\Omega) = X(\Omega - \Omega_0) //$$

5) Gradient in frequency domain:

$$X(\Omega) = \sum_{n=-\infty}^{\infty} x(n) e^{-j\Omega n}$$

$$\frac{dX(\Omega)}{d\Omega} = \sum_{n=-\infty}^{\infty} x(n) \frac{d}{d\Omega} (e^{-j\Omega n})$$

$$= \sum_{n=-\infty}^{\infty} x(n) e^{-j\Omega n} (-jn)$$

$$\Rightarrow j \frac{dx}{d\Omega} = \sum_{n=-\infty}^{\infty} n x(n) e^{-j\Omega n}$$

$$\therefore j \frac{dx}{d\Omega} = DTFT[nx(n)],$$

Eg: Given: $x(n) = na^n u(n)$

Ans We have $DTFT[nx(n)] = j \frac{dx}{d\Omega}$

$$X(\Omega) = \frac{1}{1 - a \cos \Omega + ja \sin \Omega}$$

$$\frac{dx}{d\Omega} = \frac{-1 (a \sin \Omega + ja \cos \Omega)}{(1 - a \cos \Omega + ja \sin \Omega)^2}$$

$$\therefore DTFT[nx(n)] = \frac{-j (a \sin \Omega + ja \cos \Omega)}{(1 - a \cos \Omega + ja \sin \Omega)^2},$$

NOTE: $DTFT[n^k x(n)] = (j)^k \frac{d^k}{d\Omega^k} (X(\Omega))$

b) Convolution in time domain:

$$x(n) \longleftrightarrow X(\Omega)$$

$$h(n) \longleftrightarrow H(\Omega)$$

CS: (Convolution sum) $y(n) = x(n) * h(n)$

$$= \sum_{k=-\infty}^{\infty} x(k) h(n-k)$$

$$Y(\Omega) = \sum_{n=-\infty}^{\infty} y(n) e^{-jn\Omega} \rightarrow \textcircled{2}$$

$$Y(\Omega) = \sum_{n=-\infty}^{\infty} \sum_{k=-\infty}^{\infty} x(k) \cdot h(n-k) e^{-jn\Omega}$$

$$= \sum_{n=-\infty}^{\infty} x(k) \sum_{n=-\infty}^{\infty} h(n-k) e^{-jn\Omega}$$

let $n-k=l \Rightarrow n=k+l$

$$Y(\Omega) = \sum_{k=-\infty}^{\infty} x(k) \sum_{l=-\infty}^{\infty} h(l) e^{-j(k+l)\Omega}$$

$$= \left[\sum_{k=-\infty}^{\infty} x(k) e^{-jk\Omega} \right] \sum_{l=-\infty}^{\infty} h(l) e^{-jl\Omega}$$

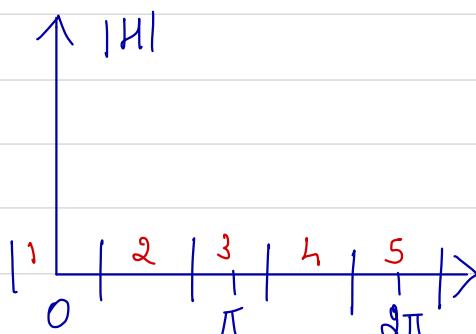
$$= X(\Omega) \cdot H(\Omega)$$

$$\Rightarrow H(\Omega) = \frac{Y(\Omega)}{X(\Omega)}$$

$$\Rightarrow H(\Omega) = \frac{|Y(\Omega)|}{|X(\Omega)|} e^{j \angle Y(\Omega)}$$

$$= \frac{|Y(\Omega)|}{|X(\Omega)|} e^{j \Delta \theta} \quad \text{where } \Delta \theta = \angle Y(\Omega) - \angle X(\Omega)$$

NOTE:



1, 5 → low frequency region

2, 4 → Medium frequency region

3 → High frequency region

Eg: Given: $H(\Omega) = \begin{cases} 1 & 0 \leq |\Omega| \leq \Omega_c \\ 0 & \Omega_c < |\Omega| < \pi \end{cases}$. Find $h(n)$

$$\begin{aligned}
 h(n) &= \frac{1}{2\pi} \int_{-\pi}^{\pi} H(\Omega) e^{j\Omega n} d\Omega \\
 &= \frac{1}{2\pi} \int_{-\pi}^{\pi} H(\Omega) e^{j\Omega n} d\Omega \\
 &= \frac{1}{2\pi} \int_{-\Omega_c}^{\Omega_c} e^{j\Omega n} d\Omega = \frac{1}{2\pi} \left[\frac{e^{j\Omega n}}{n} \right]_{-\Omega_c}^{\Omega_c} \\
 &= \frac{1}{2\pi n} \left[e^{j\Omega_c n} - e^{-j\Omega_c n} \right] = \frac{\sin \Omega_c n}{\pi n}
 \end{aligned}$$

$$= \frac{\Omega_c}{\pi} \operatorname{sinc}(\Omega_c n)$$

$h(n) \rightarrow$ IIR filter

7) Modulation:

$$\begin{array}{ccc}
 x(n) & \xrightarrow{\text{message}} & x(\lambda) \\
 c(n) & \xrightarrow{\text{carrier}} & c(\Omega)
 \end{array}$$

$$\begin{aligned}
 Y(n) &= x(n) \cdot c(n) \\
 Y(\Omega) &= \sum_{n=-\infty}^{\infty} y(n) e^{-jn\Omega n}
 \end{aligned}$$

$$\begin{aligned}
 &= \sum_{n=-\infty}^{\infty} x(n) \cdot c(n) e^{-jn\Omega n} \\
 &= \sum_{n=-\infty}^{\infty} \left[\frac{1}{2\pi} \int_{-\pi}^{\pi} x(\lambda) e^{j\lambda n} d\lambda \right] \cdot c(n) e^{-jn\Omega n}
 \end{aligned}$$

$$= \frac{1}{2\pi} \int_{-\infty}^{\infty} X(\lambda) \left[\sum_{n=-\infty}^{\infty} c(n) e^{-jn(\Omega-\lambda)} \right] d\lambda$$

$$Y(\Omega) = \frac{1}{2\pi} \int_{-\infty}^{\infty} X(\lambda) \cdot C(\Omega - \lambda) d\lambda$$

$$Y(\Omega) = X(\Omega) * C(\Omega)$$

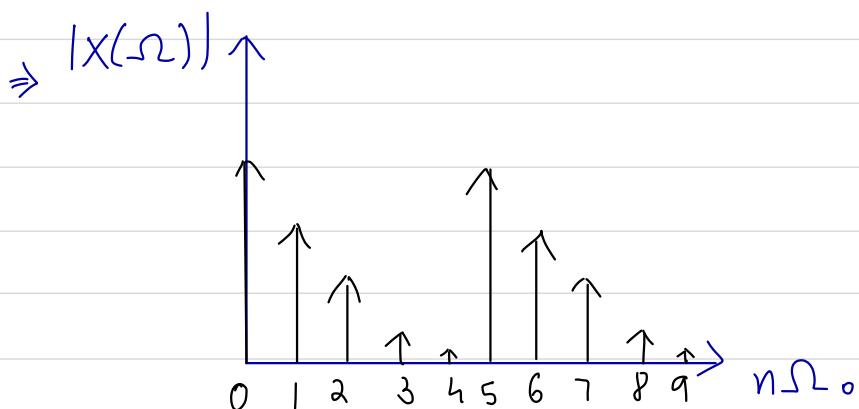
8) FT of a periodic sequence :

$$\text{If } x(n) \Big|_N = \sum_{k=0}^{N-1} a_k e^{jk\Omega_0 n}$$

$$\text{But } e^{jk\Omega_0 n} \longleftrightarrow 2\pi \delta(\Omega - k\Omega_0)$$

$$\therefore X(\Omega) = \sum_{k=0}^{N-1} a_k 2\pi \delta(\Omega - k\Omega_0)$$

NOTE : Suppose $N = 5$, $|a_0| > |a_1| > |a_2| > |a_3| > |a_4|$



Bandwidth of AM = 10 kHz
 " FM = 200 kHz
 " TV channels = 6 MHz

Sampled data or hybrid system

Considered sampled signal: $x_s(t)$, sampled on $x_a(t)$ at nT .

$$\Rightarrow X_a(\omega) = \int_{-\infty}^{\infty} x_a(t) e^{-j\omega t} dt.$$

$$\begin{aligned} \text{Also } X_s(\omega) &= \int_{-\infty}^{\infty} x_s(t) e^{-j\omega t} dt \\ &= \int_{-\infty}^{\infty} x_a(nT) e^{-j\omega nT} dt \end{aligned}$$

$$\text{But } X(\Omega) = \sum_{n=-\infty}^{\infty} x(n) e^{-jn\Omega} d\Omega$$

$$\text{and } x(n) = \frac{1}{2\pi} \int_{-\pi}^{\pi} X(\Omega) e^{jn\Omega} d\Omega \rightarrow ①$$

$$x_s(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} X_s(\omega) e^{j\omega t} d\omega \rightarrow ②$$

$$x_s(t) = \frac{1}{2\pi} \sum_{m=-\infty}^{\infty} \int_{\frac{(2m-1)\pi}{T}}^{\frac{(2m+1)\pi}{T}} X_s(\omega) e^{j\omega t} d\omega \rightarrow ③$$

$$\text{let } \omega = \omega + \frac{2m\pi}{T} \quad \text{and} \quad t = nT$$

$$X_s(\omega) = \frac{1}{2\pi} \sum_{m=-\infty}^{\infty} \int_{-\pi/T}^{\pi/T} X_s\left(\omega + \frac{2m\pi}{T}\right) e^{j\left[\omega + \frac{2m\pi}{T}\right]nT} dw$$

$$= \sum_{m=-\infty}^{\infty} \frac{1}{2\pi} \int_{-\pi/T}^{\pi/T} X_s\left(\omega + \frac{2m\pi}{T}\right) e^{j\omega Tn} dw \rightarrow ④$$

Sampled data systems

$$x_a(t) \xrightarrow{\text{sampling}} @ t = nT \Rightarrow x_a(nT) = x(n)$$

\downarrow

$$x_a(\omega) \quad x_s(t) \leftrightarrow x_s(t)$$

$$\Rightarrow x_a(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} X_a(\omega) e^{j\omega t} dt - (1)$$

$$x_a(nT) = x(n) = \frac{1}{2\pi} \int_{-\infty}^{\infty} X_a(\omega) e^{jn\omega T} d\omega \rightarrow (2)$$

$$x(n) = \frac{1}{2\pi} \int_{-\pi}^{\pi} X(\Omega) e^{jn\Omega} d\Omega \rightarrow (3) \quad (\Omega = \omega T)$$

$$(2) \Rightarrow x(n) = \frac{1}{2\pi} \sum_{m=-\infty}^{\infty} \int_{\frac{(2m-1)\pi}{T}}^{\frac{(2m+1)\pi}{T}} X_a(\omega + \frac{2m\pi}{T}) e^{jnT(\omega + \frac{2m\pi}{T})} d\omega \rightarrow (4)$$

$$\omega = \omega + \frac{2m\pi}{T}$$

$$x(n) = \frac{1}{2\pi} \sum_{m=-\infty}^{\infty} \int_{-\frac{\pi}{T}}^{\frac{\pi}{T}} X_a\left(\omega + \frac{2m\pi}{T}\right) \cdot e^{jnT\left(\omega + \frac{2m\pi}{T}\right)} d\omega \rightarrow (5)$$

$$= \frac{1}{2\pi} \sum_{m=-\infty}^{\infty} \int_{-\frac{\pi}{T}}^{\frac{\pi}{T}} X_a\left(\omega + \frac{2m\pi}{T}\right) e^{jnT\omega} d\omega$$

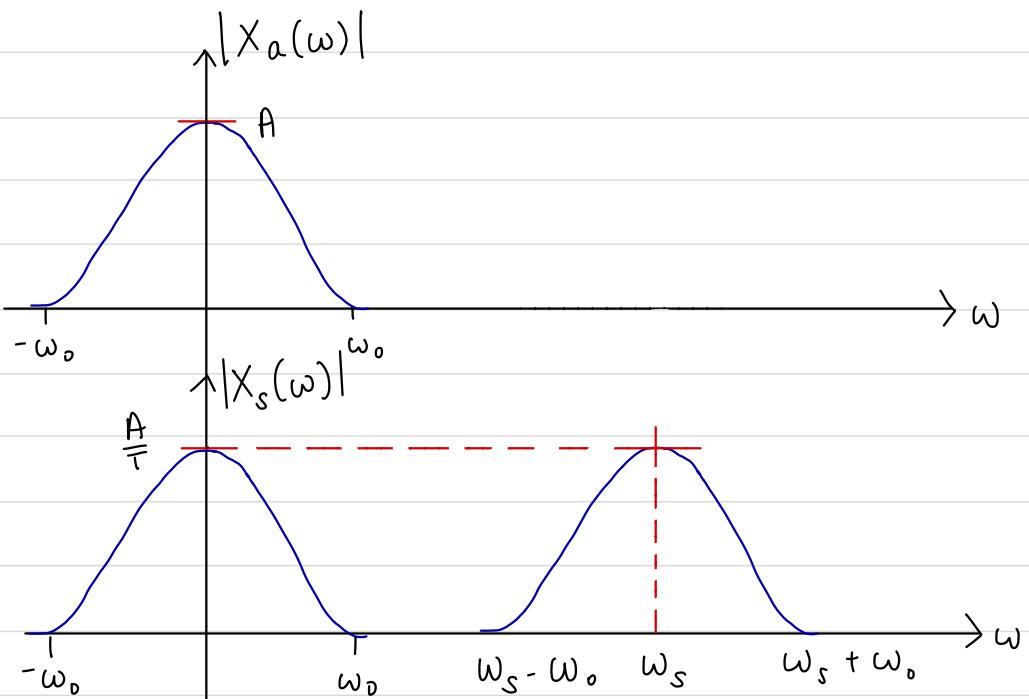
$$= \frac{1}{2\pi} \sum_{m=-\infty}^{\infty} \int_{-\pi}^{\pi} X_a\left(\frac{\Omega}{T} + \frac{2m\pi}{T}\right) e^{jn\Omega} \frac{d\Omega}{T}$$

$$= \frac{1}{2\pi} \int_{-\pi}^{\pi} \left[\frac{1}{T} \sum_{m=-\infty}^{\infty} X_a\left(\frac{\Omega}{T} + \frac{2m\pi}{T}\right) \right] e^{jn\Omega} d\Omega$$

from equation ③,

$$X(\omega) = \frac{1}{T} \sum_{m=-\infty}^{\infty} X_a \left(\frac{\omega}{T} + \frac{2m\pi}{T} \right) \rightarrow ⑦$$

$$X_s(\omega) = \frac{1}{T} \sum_{m=-\infty}^{\infty} X_a \left(\omega + m\omega_s \right) \quad \text{where } \omega_s = \frac{2\pi}{T}$$



Discrete Fourier transform (DFT)

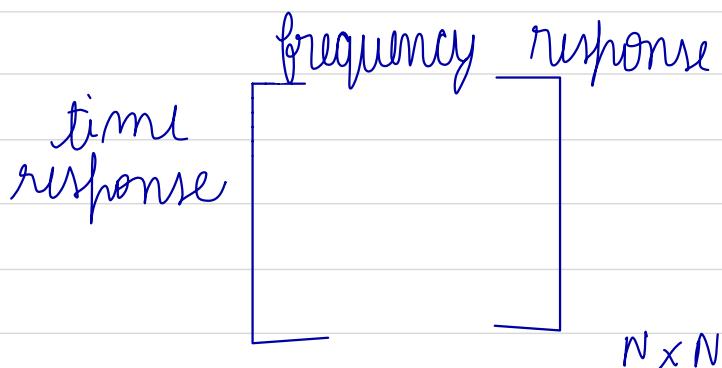
Truncation: $x_a(t) = \alpha^t u(t)$ where $\alpha < 1$

$$x_a(t) \xrightarrow{\text{Sampling}} x_a(nT) = x_a(n)$$

$$x_a(n) \times w(n) = x(n)$$

$$\text{where } w(n) = \begin{cases} 1 & 0 \leq n \leq N-1 \\ 0 & n > N-1 \end{cases}$$

DFT matrix:



The elements of this matrix are complex numbers

$$X(\underline{\Omega}) = \sum_{n=0}^{N-1} x(n) e^{-j n \underline{\Omega}} \rightarrow \textcircled{1}$$

$$X(\underline{\Omega}_k) = \sum_{n=0}^{N-1} x(n) e^{-j \underline{\Omega}_k n}$$

$$X(k) = \sum_{n=0}^{N-1} x(n) e^{-j n \frac{2\pi \cdot k}{N}} \quad \text{for } k = 0, 1, \dots, N-1$$

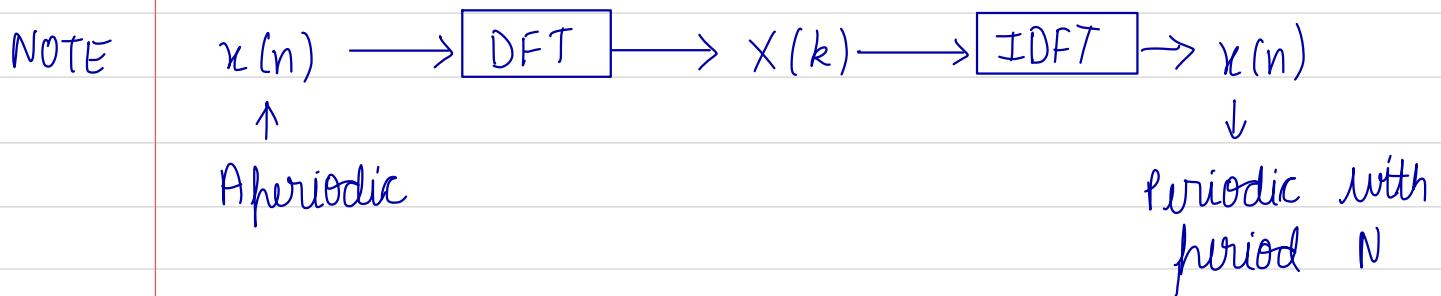
$$\text{NOTE: } x_a(nT) \rightarrow X(n)$$

$$X(\underline{\Omega}_k) \rightarrow X(k)$$

$$X(k) = \sum_{n=0}^{N-1} x(n) e^{-j \frac{2\pi n k}{N}} \rightarrow \textcircled{2}$$

Also $X(k+N) = \sum_{n=0}^{N-1} x(n) e^{-j \frac{2\pi n (k+N)}{N}}$

$$= X(k)$$



Inverse DFT (IDFT)

From DFT we have

$$X(k) = \sum_{l=0}^{N-1} x(l) e^{-j \frac{2\pi l k}{N}}$$

Multiply both sides $e^{j \frac{2\pi k n}{N}}$

$$\Rightarrow X(k) e^{j \frac{2\pi k n}{N}} = \sum_{l=0}^{N-1} x(l) e^{-j \frac{2\pi l k}{N}} \cdot e^{j \frac{2\pi l n}{N}}$$

$$\sum_{k=0}^{N-1} X(k) e^{j \frac{2\pi l k}{N}} = \sum_{k=0}^{N-1} \sum_{l=0}^{N-1} x(l) e^{-j \frac{2\pi l k}{N}} e^{j \frac{2\pi l (l-n)}{N}}$$

$$= \sum_{l=0}^{N-1} x(l) \sum_{k=0}^{N-1} \alpha^k$$

where $\alpha = e^{-j \frac{2\pi}{N} (l-n)}$

$$\Rightarrow \sum_{k=0}^{N-1} x(k) e^{j\frac{2\pi}{N}kn} = \sum_{l=0}^{N-1} x(l) \cdot \left(\frac{1-\alpha^N}{1-\alpha} \right)$$

But $\frac{1-\alpha^N}{1-\alpha} = \frac{1 - e^{-j\frac{2\pi}{N}(l-n) \cdot N}}{1 - e^{-j\frac{2\pi}{N}(l-n)k}}$

$$\Rightarrow \text{sum} = \begin{cases} N & , l=n \\ 0 & , l \neq n \end{cases} = N \delta(l-n)$$

$$\therefore \sum_{k=0}^{N-1} x(k) e^{j\frac{2\pi}{N}kn} = \sum_{l=0}^{N-1} x(l) N \delta(l-n)$$

$$= N \sum_{l=0}^{N-1} x(l) \cdot \delta(l-n)$$

$$= N x(n)$$

$$\therefore x(n) = \frac{1}{N} \sum_{k=0}^{N-1} x(k) e^{j\frac{2\pi}{N}kn}$$

$$\text{Also } x(n+mN) = x(n)$$

Properties of DFT

1) Linearity: $x_1(n) \leftrightarrow X_1(k)$
 $x_2(n) \leftrightarrow X_2(k)$

$$\text{If } y(n) = a_1 x_1(n) + a_2 x_2(n)$$

$$\Rightarrow Y(n) = \sum_{n=0}^{N-1} [a_1 x_1(n) + a_2 x_2(n)] e^{-j \frac{2\pi n}{N} k}$$

$$Y(n) = a_1 X_1(n) + a_2 X_2(n), //$$

2) Time shift: If $y(n) = x(n-m)$

$$Y(k) = \sum_{n=0}^{N-1} x(n-m) e^{-j \frac{2\pi n}{N} k}$$

$$\text{Let } n-m = l$$

$$\Rightarrow Y(k) = \sum_{l=m}^{m+N-1} x(l) e^{-j \frac{2\pi(m+l)}{N} k}$$

$$\Rightarrow Y(k) = \left[\sum_{l=0}^{N-1} x(l) e^{-j \frac{2\pi lk}{N}} \right] e^{-j \frac{2\pi mk}{N}}$$

$$\therefore Y(k) = e^{-j \frac{2\pi mk}{N}} X(k), //$$

$$\text{Also } |Y(k)| = |X(k)|$$

3) Convolution in time:

$$Y(k) = H(k) \cdot X(k)$$

$$\begin{aligned}
 y(n) &= \frac{1}{N} \sum_{k=0}^{N-1} H(k) \cdot X(k) e^{j \frac{2\pi n k}{N}} \\
 &= \frac{1}{N} \sum_{k=0}^{N-1} \left[\sum_{m=0}^{N-1} h(m) e^{-j \frac{2\pi m k}{N}} \right] X(k) e^{j \frac{2\pi n k}{N}} \\
 &= \sum_{m=0}^{N-1} \left[\frac{1}{N} \sum_{k=0}^{N-1} X(k) e^{j \frac{2\pi (n-m) k}{N}} \right] h(m)
 \end{aligned}$$

$$y(n) = \sum_{m=0}^{N-1} h(m) \cdot x(n-m)$$

$\Rightarrow y(n) = h(n) \circledast x(n) \rightarrow$ circular convolution

Eg: $x(n) = \{1, 2, 0, -1\} \quad N=4, \quad h(n) = \{1, 3, -1, 2\} \quad N=4$
 Estimate $y(n)$ using DFT properties.

Ans

$$\begin{aligned}
 X(k) &= \sum_{n=0}^{N-1} x(n) e^{-j \frac{2\pi n k}{N}} \\
 &= \sum_{n=0}^3 x(n) e^{-j \frac{2\pi n k}{4}} = \sum_{n=0}^3 x(n) (-j)^{nk}
 \end{aligned}$$

$$X(0) = \sum_{n=0}^3 x(n) = 2,$$

$$X(1) = \sum_{n=0}^3 x(n) (-j)^n = 1 - 2j - j = 1 - 3j$$

$$X(2) = \sum_{n=0}^3 x(n) (-1)^n = 1 - 2 + 1 = 0,$$

$$X(3) = \sum_{n=0}^3 x(n) (j)^n = 1 + 2j + j = 1 + 3j,$$

$$H(k) = \sum_{n=0}^3 h(n) (-j)^{nk}$$

$$H(0) = \sum_{n=0}^3 h(n) = 5$$

$$H(1) = \sum_{n=0}^3 h(n) (-j)^n = 1 - 3j + 1 + 2j = 2 - j$$

$$H(2) = \sum_{n=0}^3 h(n) (-1)^n = 1 - 3 - 1 - 2 = -5$$

$$H(3) = 2 + j$$

$$\therefore X(k) = \{2, 1-3j, 0, 1+3j\}$$

$$\therefore H(k) = \{5, 2-j, -5, 2+j\}$$

$$\begin{aligned}\therefore Y(k) &= X(k) \cdot H(k) \\ &= \{10, -1-7j, 0, -1+7j\}\end{aligned}$$

$$\therefore y(n) = \frac{1}{4} \sum_{k=0}^3 Y(k) e^{j \frac{2\pi n k}{4}}$$

$$= \frac{1}{4} \sum_{k=0}^3 Y(k) [j]^{nk}$$

$$y(0) = \frac{1}{4} \sum_{k=0}^3 Y(k) = 2,$$

$$y(1) = \frac{1}{4} \sum_{k=0}^3 Y(k) [j]^n = \frac{10 - j + 7 + j + 7}{4} = 6,$$

$$y(2) = \frac{1}{4} \sum_{k=0}^3 Y(k) (-1)^n = \frac{10 + 1 + 7j + 1 - 7j}{4} = 3,$$

$$y(3) = \frac{1}{4} \sum_{k=0}^3 Y(k) (-j)^n = \frac{10 + 1j - 7 - j - 7}{4} = -1,$$

$$\therefore y(n) = [2, 6, 3, -1],$$

DFT estimate in matrix form

$x(n) \rightarrow$ finite sample : N i.e. $n = 0, 1, \dots, N-1$

$$x(n) \rightarrow \vec{x}_{N \times 1}$$

$$\downarrow$$

$$X(k) \rightarrow \vec{X}_{N \times 1} : k = 0, 1, 2, \dots, N-1$$

$$X(k) = \sum_{n=0}^{N-1} x(n) e^{-j \frac{2\pi k n}{N}} \rightarrow \textcircled{1}$$

$$x(n) = \frac{1}{N} \sum_{k=0}^{N-1} X(k) e^{j \frac{2\pi k n}{N}} \rightarrow \textcircled{2}$$

$$\text{Let } w_N = e^{-j \frac{2\pi}{N}}$$

$$\therefore X(k) = \sum_{n=0}^{N-1} x(n) (w_N)^{kn}$$

$$\begin{bmatrix} x(0) \\ x(1) \\ \vdots \\ x(N-1) \end{bmatrix}_{N \times 1} = \begin{bmatrix} n \rightarrow 0 \\ k \downarrow 0 \\ N-1 \end{bmatrix} \begin{bmatrix} w_N^0 & w_N^0 & \cdots & w_N^0 \\ w_N^0 & w_N^1 & \cdots & w_N^{N-1} \\ \vdots & \vdots & \ddots & \vdots \\ \vdots & \vdots & & \vdots \\ w_N^0 & w_N^{N-1, 1} & \cdots & w_N^{N-1, N-1} \end{bmatrix}_{N \times N} \begin{bmatrix} x(0) \\ x(1) \\ \vdots \\ x(N-1) \end{bmatrix}_{N \times 1}$$

$$\Rightarrow \vec{x} = W \vec{x}$$

$$\therefore \vec{x} = W^{-1} \vec{x}$$

$$\text{Also } W^T = W$$

From equation ②

$$\vec{x} = w^{-1} \vec{X} = \frac{1}{N} w^* \vec{X}$$

$$\vec{x} = \frac{1}{N} w^{T*} \vec{X}$$

$$\text{But } \vec{x} = w^{-1} \vec{X} \\ \Rightarrow \frac{w^{T*}}{N} = w^{-1} \Rightarrow w^{T*} w = N I_N \Rightarrow$$

NOTE: If $A^{*T} A = I$ then A is unitary matrix.

$$\begin{aligned} \text{We have } x(n) &= \frac{1}{N} \sum_{k=0}^{N-1} x(k) e^{j \frac{2\pi n k}{N}} \\ &= \frac{1}{\sqrt{N}} \sum_{k=0}^{N-1} \left[\frac{1}{\sqrt{N}} \sum_{n=0}^{N-1} x(n) e^{-j \frac{2\pi n k}{N}} \right] e^{j \frac{2\pi n k}{N}} \\ &= \sum_{k=0}^{N-1} \left[\sum_{n=0}^{N-1} x(n) \frac{e^{-j \frac{2\pi n k}{N}}}{\sqrt{N}} \right] \frac{e^{j \frac{2\pi n k}{N}}}{\sqrt{N}} \end{aligned}$$

$$\text{Now let } w_N = \frac{e^{-j \frac{2\pi n k}{N}}}{\sqrt{N}}$$

$$\begin{aligned} \text{Now } w^{*T} w &= I_N \\ \text{Also } N &= 2^n \end{aligned}$$

$$\text{NOTE: } x(k) = \sum_{n=0}^{N-1} x(n) w_N^{nk} \Rightarrow \underbrace{\begin{array}{l} N \text{ complex multiplication} \\ N-1 \text{ complex addition} \end{array}}_{\text{for } N \text{ values of } k}$$

DFT E FFT

$$X(k) = \sum_{n=0}^{N-1} x(n) W_N^{nk}$$

requires for 1 loop :

- 1 > N complex multiplication
- 2 > N-1 complex addition.

- If N is very large, $N-1 \approx N$, then for N loops, it requires N^2 complex multiplication and N^2 complex addition
- If N is very large, computation takes lot of time.

Fast Fourier transform (FFT)

- It is a radix 2 algorithm.
- 2^n samples requires n stages of computation.

↳ Decimation in time (DIT) algorithm:

$$\underbrace{x(n)}_N = \underbrace{x_e(n)}_{\frac{N}{2}} \& \underbrace{x_o(n)}_{\frac{N}{2}}$$

$$X(k) = \sum_{n=0}^{N-1} x(n) W_N^{nk} \rightarrow ①$$

$$= \sum_{n=\text{even}} x(n) W_N^{nk} + \sum_{n=\text{odd}} x(n) W_N^{nk} \rightarrow ②$$

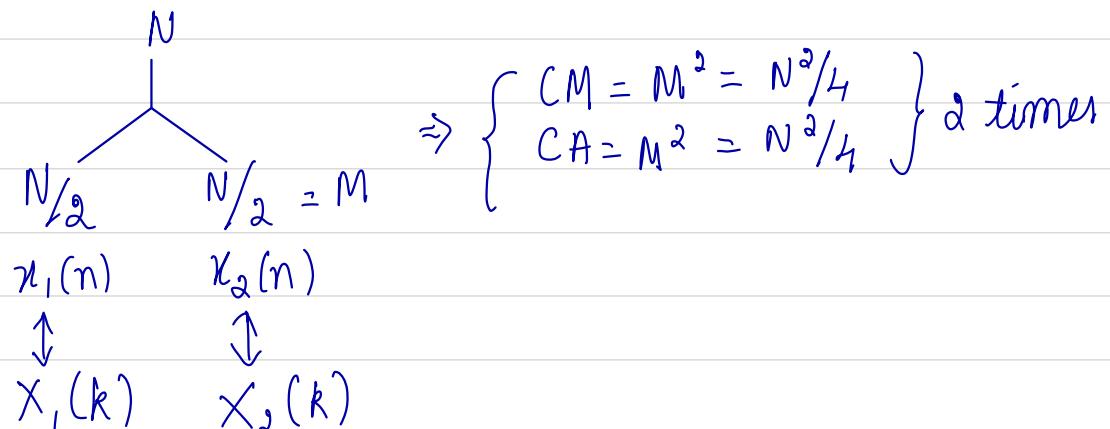
In equation ② let $\begin{cases} n = 2l \\ n = 2l+1 \end{cases} \} l = 0, 1, \dots, \frac{N}{2} - 1$

$$\therefore X(k) = \sum_{l=0}^{\frac{N}{2}-1} x(2l) W_N^{2lk} + \sum_{l=0}^{\frac{N}{2}-1} x(2l+1) W_N^{(2l+1)k} \rightarrow ③$$

NOTE: $x(n) \Big|_N = N$ samples,

Normal DFT $\Rightarrow N^2 - CM \& N^2 CA$

Now



For complex adder:

$$\begin{array}{ll} \text{without decomposition} \rightarrow N^2 \\ \text{with one decomposition} \rightarrow \frac{N^3}{4} \times 2 + N \end{array}$$

Now if $N = 10^5$ without decomposition $= 10^{10}$
 with one decomposition $= \frac{10^{10}}{2} + 10^5 \approx 5 \times 10^9$
 i.e. 50% time saving

equation ③ \Rightarrow

$$X(k) = \sum_{l=0}^{N/2-1} x(2l) w_N^{2lk} + \sum_{l=0}^{N/2-1} x(2l+1) w_N^{(2l+1)k}$$

Let $x(2l) = g(l)$ & $x(2l+1) = h(l)$

Then, $X(k) = \sum_{l=0}^{N/2-1} g(l) w_N^{2lk} + w_N^k \sum_{l=0}^{N/2-1} h(l) w_N^{2lk} \rightarrow ④$

↓

here $w_N^k = e^{-j\frac{2\pi k}{N}}$

If $y(n)$ has $N/2$ samples,

$$Y(k) = \sum_{n=0}^{N/2-1} y(n) w_{N/2}^{nk} = \sum_{n=0}^{N/2-1} y(n) w_N^{2nk}$$

i.e. $w_{N/2}^{nk} = e^{-j\frac{2\pi k}{N/2}} = e^{-j\frac{2\pi k \times 2}{N}} = w_N^{2nk}$

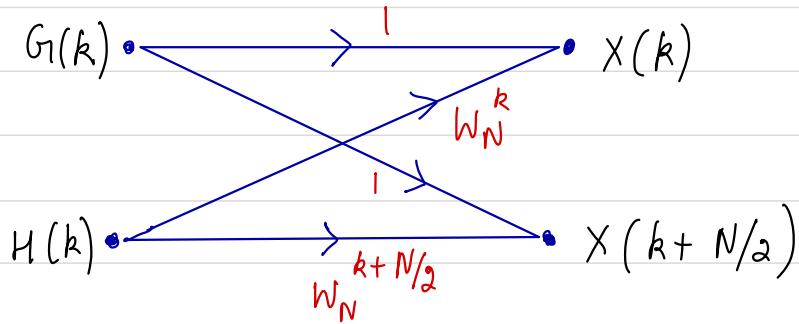
From equation ④
 $X(k) = G(k) + w_N^k H(k) \rightarrow ⑤$

⑤ $\Rightarrow X(k) = G(k) + w_N^k H(k) \rightarrow ⑥a$

$X(k+N/2) = G(k) + w_N^{k+N/2} H(k) \rightarrow ⑥b$

$G_r(k + N/2) = G_r(k)$ & $H(k + N/2) = H(k)$ since both are periodic with period $N/2$

From 6a & 6b, we get following signal flow graph



From equation ⑤, requirement for this decomposition:

$$CM: \frac{N^2}{4} \times 2 + N = \frac{N^2}{2} + N$$

$$CA: \frac{N^2}{4} \times 2 + N = \frac{N^2}{2} + N$$

Now, for an 8 point DFT, DIT can be applied as:

$$x(n) = \{x(0), x(1), \dots, x(7)\}_{8 \times 1}$$

$$g(l) = \{x(0), x(2), x(4), x(6)\}_{4 \times 1}$$

$$h(l) = \{x(1), x(3), x(5), x(7)\}_{4 \times 1}$$

From 6a & 6b :

For $k = 0, 1, 2, 3$

$$X(k) = G_r(k) + w_N^k H(k) \rightarrow \textcircled{*}$$

$$X(k+4) = G_r(k) + w_N^{k+4} H(k) \rightarrow \textcircled{#}$$

This can be visualised as:



If we again decompose:

$$g(l) \rightarrow g_1(l) = \{x(0), x(4)\} \leftrightarrow G_1(k)$$

$$g(l) \rightarrow h_1(l) = \{x(2), x(6)\} \leftrightarrow H_1(k)$$

$$h(l) \rightarrow \tilde{g}(l) = \{x(1), x(5)\} \leftrightarrow \tilde{G}(k)$$

$$h(l) \rightarrow \tilde{h}(l) = \{x(3), x(7)\} \leftrightarrow \tilde{H}(k)$$

For and decomposition $k=0, 1$

$$G(k) = G_1(k) + W_{N/2}^k H_1(k) \rightarrow \textcircled{a}$$

$$G(k+2) = G_1(k) + W_{N/2}^{k+2} H_1(k) \rightarrow \textcircled{b}$$

$$H(k) = \tilde{G}(k) + W_{N/2}^k \tilde{H}(k) \rightarrow \textcircled{c}$$

$$H(k+2) = \tilde{G}(k) + W_{N/2}^{k+2} \tilde{H}(k) \rightarrow \textcircled{d}$$

$$a \Rightarrow G(k) = G_1(k) + W_N^{2k} H_1(k)$$

$$b \Rightarrow G(k+2) = G_1(k) + W_N^{2(k+2)} H_1(k)$$

$$c \Rightarrow H(k) = \tilde{G}(k) + W_N^{2k} \tilde{H}(k)$$

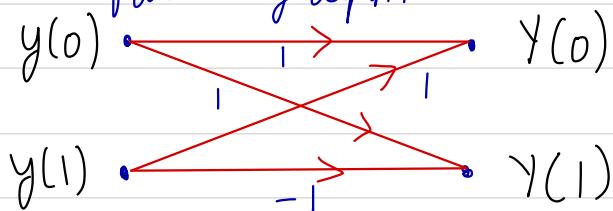
$$d \Rightarrow H(k+2) = \tilde{G}(k) + W_N^{2(k+4)} \tilde{H}(k)$$

NOTE: If $y(n)$ has 2 points, $W_n \triangleq e^{-\frac{2\pi j}{n}} = e^{-2\pi j/2} = e^{-j\pi} = -1$

$$\Rightarrow Y(k) = \sum_{n=0}^1 y(n) (-1)^{nk}$$

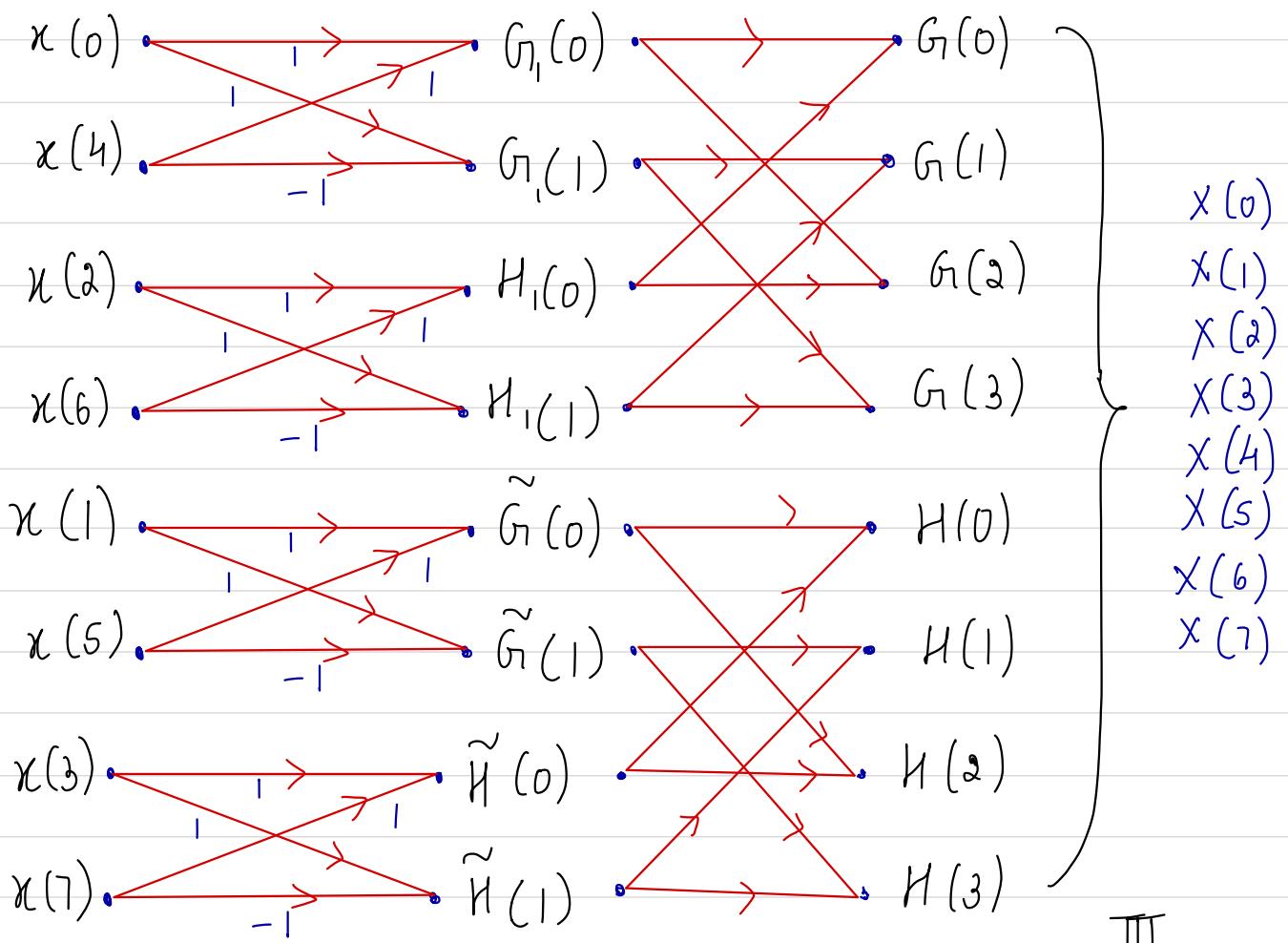
$$\text{for } k = 0, 1 : \quad Y(0) = y(0) + y(1) \\ Y(1) = y(0) - y(1)$$

Signal flow graph:



← Butterfly structure

For 8 point DFT:



I stage

II stage

III stage

$$\text{Number of stages} = \log_2(n)$$

∴ Total time complexity $O(n) = n \log_2 n$

Bit reversal :

Eg: For 8 point sample:

$x \rightarrow$	0	1	2	3	4	5	6	7
	000	, 001	, 010	, 011	, 100	, 101	, 110	, 111

reverse: 000, 100, 010, 110, 001, 101, 011, 111

0 4 2 6 1 5 3 7

DIF Algorithm (Decimation in Frequency)

We have $X(k) = \sum_{n=0}^{N-1} x(n) W_N^{nk}$

$$\begin{aligned}
 X(k) &= \sum_{n=0}^{N/2-1} x(n) W_N^{nk} + \sum_{n=N/2}^{N-1} x(n) W_N^{nk} \\
 &= \sum_{n=0}^{N/2-1} x(n) W_N^{nk} + \sum_{n=0}^{N/2-1} x\left(n + \frac{N}{2}\right) W_N^{nk} W_N^{\frac{N}{2}k} \rightarrow ① \\
 &= \sum_{n=0}^{N/2-1} x(n) W_N^{nk} + (-1)^k \sum_{n=0}^{N/2-1} x\left(n + \frac{N}{2}\right) W_N^{nk} \rightarrow ②
 \end{aligned}$$

Here index = k.

Now put $k = 2r$, $2r+1$

$$\begin{aligned}
 X(2r) &= \sum_{n=0}^{N/2-1} x(n) W_N^{2rn} + \sum_{n=0}^{N/2-1} x\left(n + N/2\right) W_N^{2rk} \\
 &= \sum_{n=0}^{N/2-1} x(n) W_{N/2}^{rn} + \sum_{n=0}^{N/2-1} x\left(n + \frac{N}{2}\right) W_{N/2}^{rn} \\
 \Rightarrow X(2r) &= \sum_{n=0}^{N/2-1} [x(n) + x\left(n + \frac{N}{2}\right)] W_{N/2}^{rn} \rightarrow ③
 \end{aligned}$$

Let $g(n) = x(n) + x\left(n + \frac{N}{2}\right)$

$$\therefore X(2r) = \sum_{n=0}^{N/2-1} g(n) W_{N/2}^{rn} \rightarrow ④$$

Also $X(2r) = G(r)$

Now put $k = 2r+1$ in ②

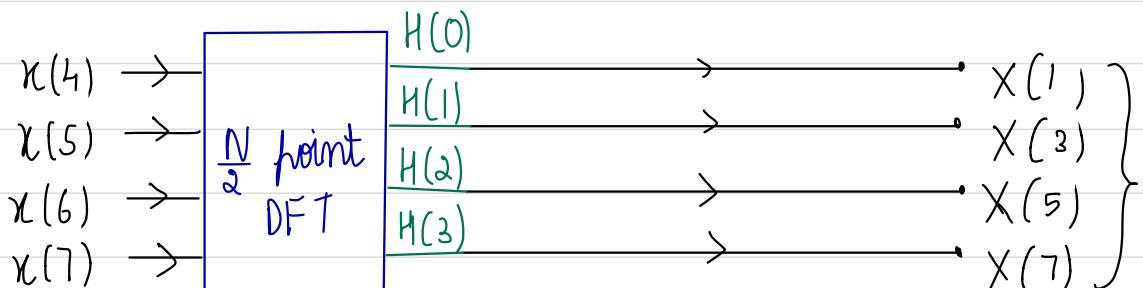
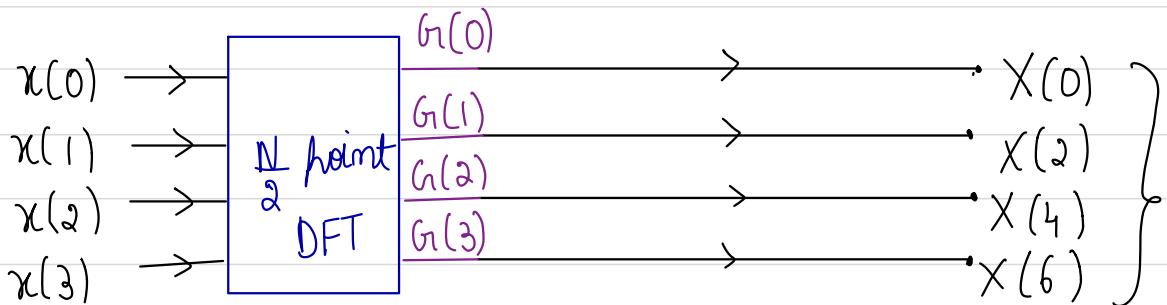
$$x(2n+1) = \sum_{n=0}^{N/2-1} x(n) w_N^{(2n+1)n} - \sum_{n=0}^{N/2-1} x\left(n + \frac{N}{2}\right) w_N^{n(2n+1)}$$

$$= \sum_{n=0}^{N/2-1} w_{N/2}^{nn} \left[[x(n) - x\left(n + \frac{N}{2}\right)] w_N^n \right] \rightarrow ⑤$$

Let $h(n) = (x(n) - x(n + N/2)) w_N^n \Rightarrow x(2n+1) = h(n)$

$$\Rightarrow H(n) = \sum_{n=0}^{N/2-1} h(n) w_{N/2}^{nn}$$

Ex: 8-point DFT using DIF



Splitting $g(n)$ & $h(n)$ again:

$$g_1(n) = g(n) + g\left(n + \frac{N}{4}\right)$$

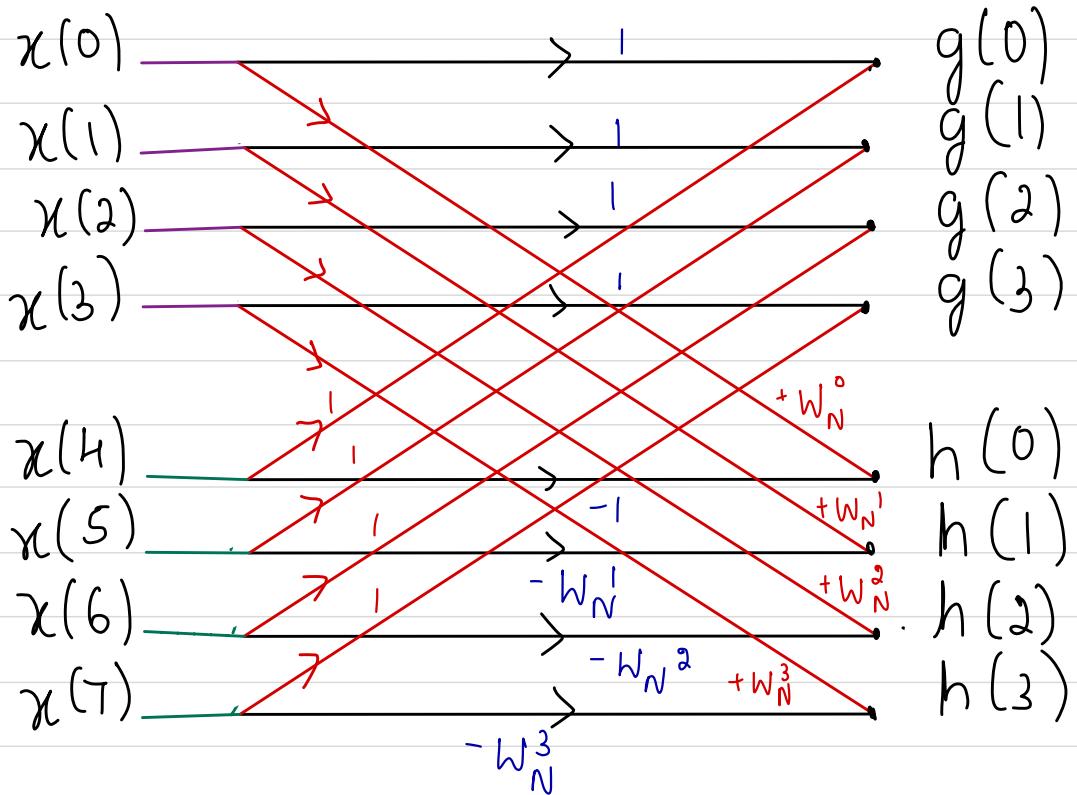
$$g_2(n) = \left[g(n) - g\left(n + \frac{N}{4}\right) \right] w_{N/2}^n$$

$$h_1(n) = h(n) + h\left(n + \frac{N}{4}\right)$$

$$h_2(n) = \left[h(n) - h\left(n + \frac{N}{4}\right) \right] w_{N/2}^n$$

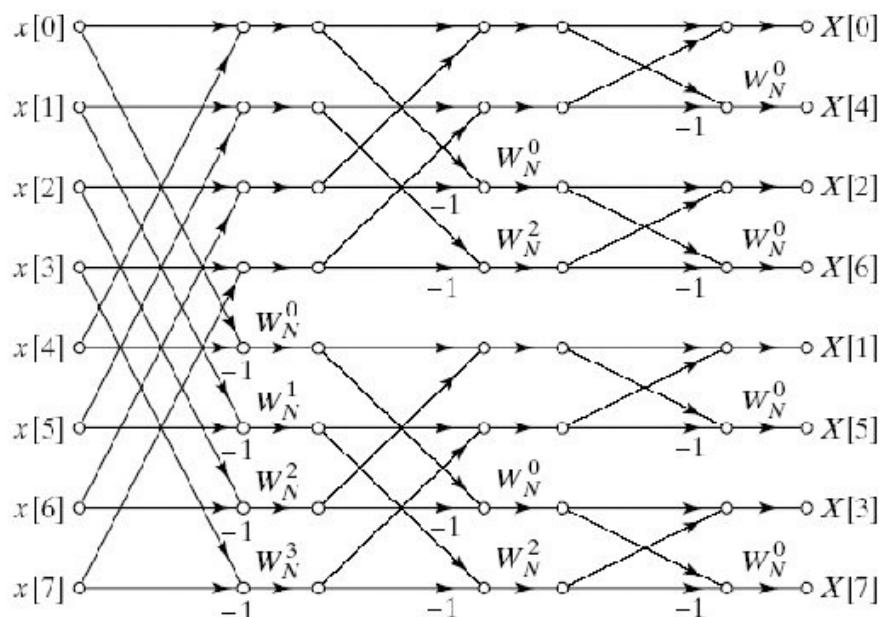
NOTE: In DIT: First stage maps time \rightarrow Frequency
 All other stages: Freq \rightarrow Frequency

In DFT: Last stage maps time \rightarrow Frequency
 All other stages: time \rightarrow time.



Decimation-In-Frequency FFT Algorithm

- Final flow graph for 8-point decimation in frequency



Total number of calculations = $2N \log_2 N$

Linear convolution using DFT

$$h(n) = \{1, 2, 0, -1, 1\}$$

$$x(n) = \{1, 3, -1, -2\}, \Rightarrow x_p(n) = \{1, 3, -1, 2, 0\}$$

$$\begin{aligned}y_p(n) &= h(n) * x_p(n) \\&= \{5, 6, 3, -5, 6\}\end{aligned}$$

$$\text{length of } y_e(n) = 4 + 5 - 1 = 8$$

$$h'(n) = \{1, 2, 0, -1, 1, 0, 0, 0\}$$

$$x'_p(n) = \{1, 3, -1, -2, 0, 0, 0, 0\}$$

$$y_e(n) = h'(n) * x'_p(n)$$

$$y_p(n) = \{1, 5, 5, -5, 6, 4, 1, -2\}$$

$$y_e(n) = \{5, 6, 3, -5, 6\}$$

In $y_e(n)$ 1st $(L-K)$ samples & last $(L-K)$ samples are lost. Addition gives $L-K$ samples of periodic convolution.

Also $L-2(L-K) = 2K-L$ samples have same value in periodic & linear convolution.

If you zeropad $h(n), x(n)$ to 8 point sequence, then linear convolution = periodic convolution.

Z-transform

Let $x_s(t)$ be sampled version of $x_a(t)$, then

$$x_s(t) = \sum_{n=-\infty}^{\infty} x_a(t) \cdot \delta(t - nT_s)$$

$$= \sum_{n=-\infty}^{\infty} x_a(nT_s) \cdot \delta(t - nT_s)$$

$$\mathcal{L}(x_s(t)) = \int_{-\infty}^{\infty} \sum_{n=-\infty}^{\infty} x_a(nT_s) \delta(t - nT_s) e^{-st} dt$$

$$X_s(s) = \sum_{n=-\infty}^{\infty} x(n) \int_{-\infty}^{\infty} \delta(t - nT_s) e^{-st} dt \rightarrow (1)$$

$$X_s(s) = \sum_{n=-\infty}^{\infty} x(n) e^{-nT_s s}$$

$$= \sum_{n=-\infty}^{\infty} x(n) (e^{-sT_s})^{-n}$$

Now let $e^{sT_s} = Z$

$$\therefore X(z) = \sum_{n=-\infty}^{\infty} x(n) z^{-n} \rightarrow \text{bilateral } z \text{ transform.}$$

If $x(n)$ is causal sequence,
 $X(z) = \sum_{n=0}^{\infty} x(n) z^{-n} \rightarrow \text{unilateral } z \text{ transform}$

$$\therefore X(z) = \sum_{n=0}^{\infty} x(n) z^{-n}$$

Eg: $\delta(z) = \sum_{n=0}^{\infty} \delta(n) z^{-n} = 1$

$$U(z) = \sum_{n=-\infty}^{\infty} U(n) z^{-n} = \sum_{n=0}^{\infty} 1 \cdot z^{-n}$$

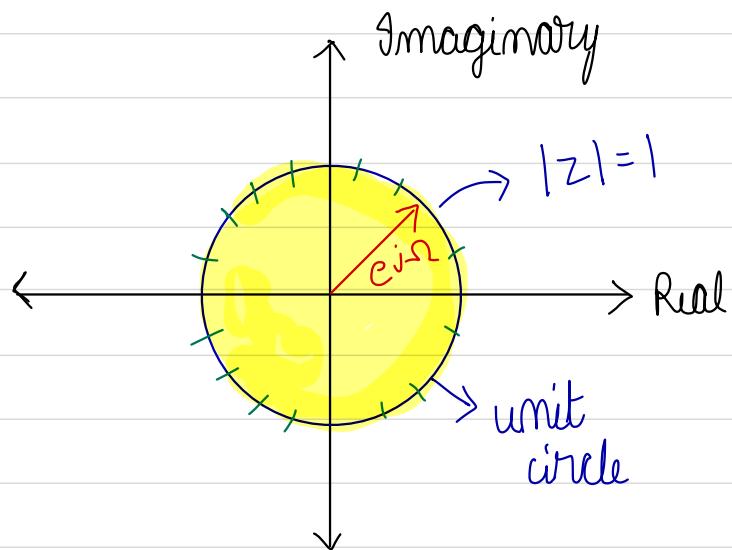
For $|z| < 1$

$$U(z) = \frac{1}{1 - \frac{1}{z}} = \frac{z}{z-1}$$

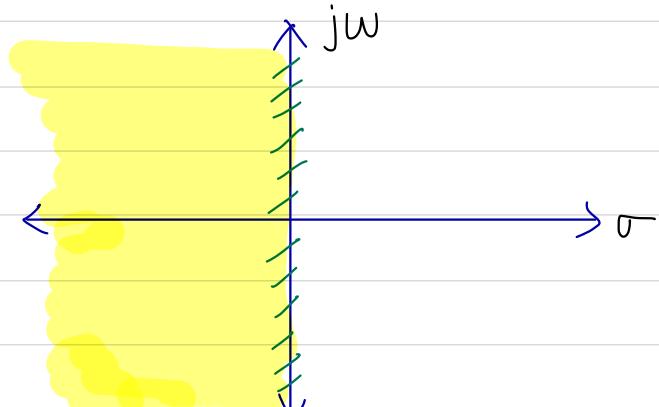
NOTE: z is complex $\Rightarrow z = \alpha + j\beta = r e^{j\phi}$
 if $z = e^{j\omega}$
 i.e. $r = 1$ & $\phi = \omega$

$$\text{So } X(z) \Big|_{z=e^{j\omega}} = X(\omega)$$

Z plane:



S-plane:



\rightarrow stability region

Bounding condition for $X(z)$

$$X(z) = \sum_{n=0}^{\infty} x(n) z^{-n} = \sum_{n=0}^{\infty} x(n) r^{-n} e^{-jn\Omega}$$

For $X(z)$ to be bounded,
 $|x(n) r^{-n}| \leq L < \infty$,

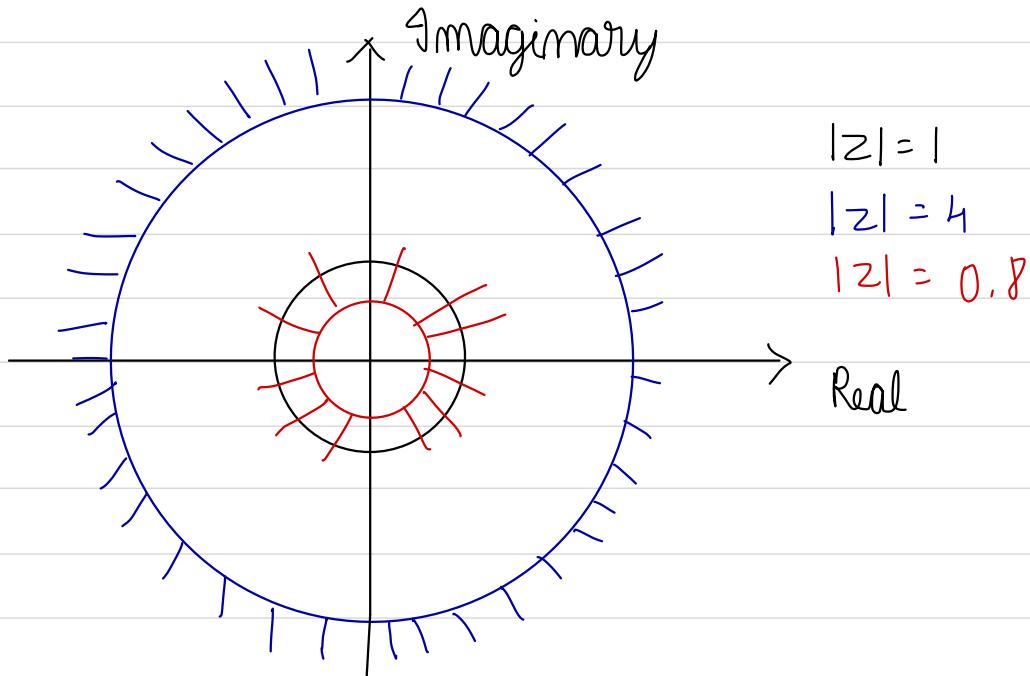
Q) Find \sum transform for DTFT for
 $x(n) = a^n u(n)$, case 1: $|a| < 1$ & case 2: $|a| > 1$

Ans

$$\begin{aligned} Z[x(n)] &= \sum_{n=0}^{\infty} a^n z^{-n} \\ &= \sum_{n=0}^{\infty} (az^{-1})^n = \frac{1}{1 - a/z} = \frac{z}{z - a} \end{aligned}$$

if $|z| > |a|$

When $|a| = 0.8$ & $|a| = 4$



$a = 0.8 \rightarrow$ stable \rightarrow unit circle included
 $a = 4 \rightarrow$ unstable \rightarrow unit circle not included

$$\begin{aligned}
 X(\Omega) &= \sum_{n=0}^{\infty} x(n) e^{-jn\Omega n} \\
 &= \sum_{n=0}^{\infty} a^n e^{-jn\Omega n} = \sum_{n=0}^{\infty} (ae^{-j\Omega})^n \\
 &= \frac{1}{1 - ae^{-j\Omega}}
 \end{aligned}$$

Q> Find 3 transform of $y(n) = a^n u(-n)$
 Ans $y(z) = \sum_{n=-\infty}^{\infty} a^n u(-n) z^{-n}$

$$\begin{aligned}
 \text{let } m &= -n \\
 Y(z) &= \sum_{m=-\infty}^{\infty} a^{-m} u(m) z^m \\
 &= \sum_{m=0}^{\infty} (a^{-1}z)^m = \frac{1}{1 - a^{-1}z} = \frac{a}{a - z}
 \end{aligned}$$

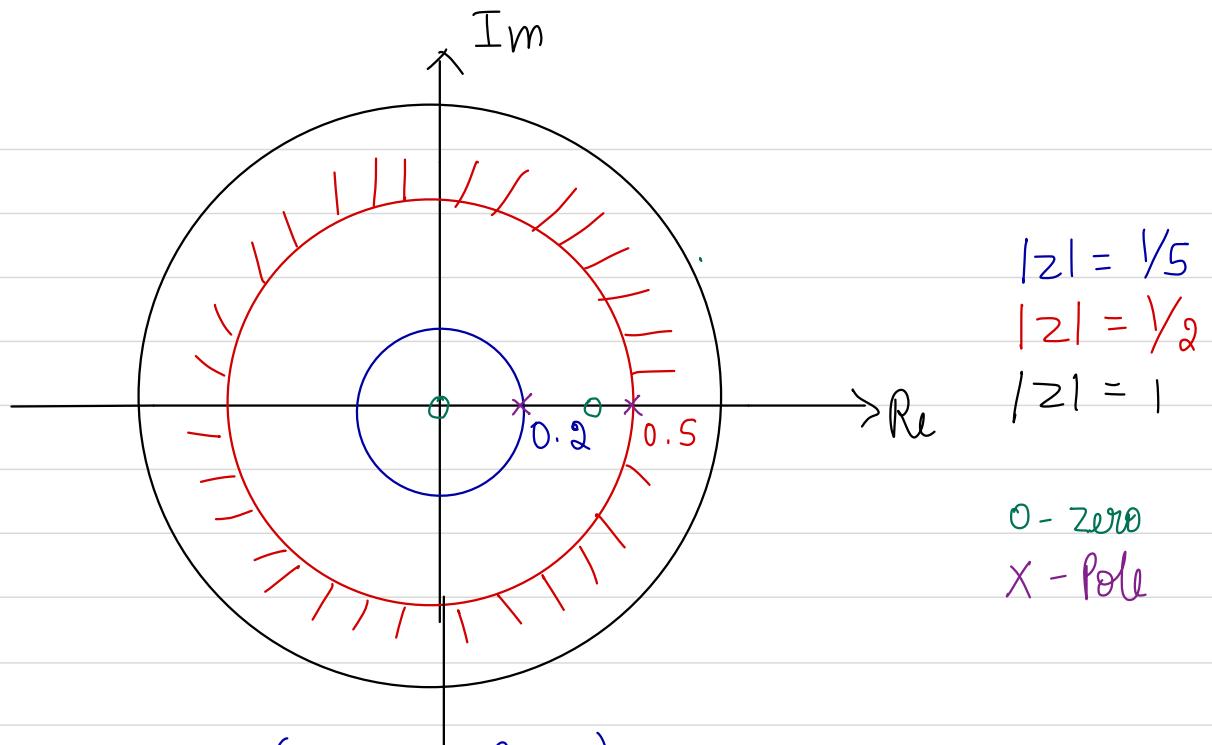
$$\begin{aligned}
 |a^{-1}z| &< 1 \\
 \Rightarrow |z| &< |a|
 \end{aligned}$$

Here $|a| = 0.8 \Rightarrow \text{unstable}$
 $|a| = 4 \Rightarrow \text{stable.}$

Eg: $x(n) = (Y_2)^n u(n) + (Y_5)^n u(n)$
 Ans $x(n) = x_1(n) + x_2(n)$

$$X_1(z) = \frac{z}{z - 1/2} \quad X_2(z) = \frac{z}{z - 1/5}$$

$$\therefore X(z) = \frac{z}{z - 1/2} + \frac{z}{z - 1/5}$$



$$|z| = \frac{1}{5}$$

$$|z| = \frac{1}{2}$$

$$|z| = 1$$

0 - zero

X - Pole

$$\text{ROC} = \text{Max} (\text{ROC}_1, \text{ROC}_2)$$

$$= \text{Max} \left(\frac{1}{2}, \frac{1}{5} \right) \Rightarrow \frac{1}{2}$$

$$\text{Also } X(z) = \frac{z(2z-0.7)}{(z-0.5)(z-0.2)}$$

$$\text{Eq 2: } x(n) = \cos \Omega_0 n u(n)$$

$\Omega_0 = \pi/3$

$$Z[x(n)] = \frac{1}{2} \sum_{n=0}^{\infty} [e^{j\Omega_0 n} + e^{-j\Omega_0 n}] z^{-n}$$

$$X(z) = \frac{1}{2} \left[\sum_{n=0}^{\infty} (e^{j\Omega_0} z^{-1})^n + \sum_{n=0}^{\infty} (e^{-j\Omega_0} z^{-1})^n \right]$$

$$X(z) = \frac{1}{2} \left[\frac{1}{1 - e^{j\Omega_0} z^{-1}} + \frac{1}{1 - e^{-j\Omega_0} z^{-1}} \right]$$

$$= \frac{1}{2} \left[\frac{z}{z - e^{j\Omega_0}} + \frac{z}{z - e^{-j\Omega_0}} \right]$$

$$= \frac{z}{2} \left[\frac{z - e^{-j\Omega_0} + z - e^{-j\Omega_0}}{(z - e^{j\Omega_0})(z - e^{-j\Omega_0})} \right]$$

$$= \frac{z}{2} \left[\frac{2z - (e^{j\Omega_0} + e^{-j\Omega_0})}{z^2 + 1 - z(e^{j\Omega_0} + e^{-j\Omega_0})} \right]$$

$$= z \left[\frac{z - \cos \Omega_0}{z^2 - 2z \cos \Omega_0 + 1} \right]$$

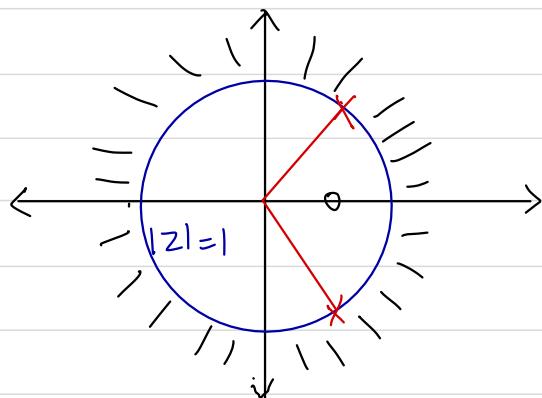
Poles : $z = \frac{2 \cos \Omega_0}{2} \pm \sqrt{\frac{4 \cos^2 \Omega_0 - 4}{4}}$

 $= \cos \Omega_0 \pm j \sin \Omega_0$

$= (\gamma_2) \pm j (\sqrt{3}/2)$

ZEROS : $0, \cos \Omega_0 \Rightarrow 0, 1/2$

To find ROC : $|e^{j\Omega} z^{-1}| < 1$
 $\Rightarrow |z| > |e^{j\Omega_0}| \Rightarrow |z| > 1$



System is unstable
as $|z|=1$ not included

Properties of \tilde{z} transform

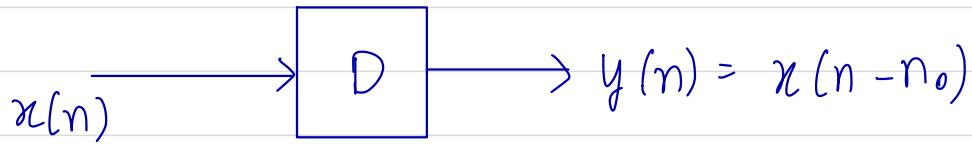
1) Linearity: $x_1(n) \leftrightarrow X_1(z)$
 $x_2(n) \leftrightarrow X_2(z)$

$y(n) = \alpha_1 x_1(n) \pm \alpha_2 x_2(n)$

\downarrow
 $y(z) = \sum_{n=0}^{\infty} [\alpha_1 x_1(n) \pm \alpha_2 x_2(n)] z^{-n}$

$$\therefore Y(z) = \alpha_1 X_1(z) + \alpha_2 X_2(z),$$

2) Time shift: (delay n_0 unit):



$$Y(z) = \sum_{n=0}^{\infty} x(n - n_0) z^{-n}$$

Let $n - n_0 = l$, when $n=0, l=-n_0$
 $n=\infty, l=\infty$

$$\therefore Y(z) = \sum_{l=-n_0}^{\infty} x(l) z^{-(l+n_0)}$$

$$= z^{-n_0} \left[\sum_{l=-n_0}^{-1} x(l) z^{-l} + \sum_{l=0}^{\infty} x(l) z^{-l} \right]$$

$$Y(z) = z^{-n_0} \left[\sum_{l=-n_0}^{-1} x(l) z^{-l} + X(z) \right] \neq$$

Q> Solve a Difference equation using Z transform
 $y(n) - \frac{1}{5}y(n-1) = \delta(n)$ with $y(-1) = 2$

and $x(n) = \delta(n)$

Ans Applying Z transform:

$$Y(z) - \frac{1}{5} \left[\frac{Y(z)}{z} + y(-1) \right] = 1$$

$$Y(z) \left[1 - \frac{1}{5z} \right] = 1 + \frac{2}{5}$$

$$Y(z) \frac{(5z-1)}{z} = 7$$

$$\therefore Y(z) = \frac{7z}{5z-1}$$

$$y(n) = z^{-1} \left[\frac{7z}{5z-1} \right]$$

$$y(n) = \frac{7}{5} \left(\frac{1}{5} \right)^n u(n)$$

3> Frequency scaling: $x(n) \longleftrightarrow X(z)$
 $y(n) = \alpha^n x(n) u(n)$

$$Y(z) = \sum_{n=0}^{\infty} \alpha^n x(n) z^{-n}$$

$$= \sum_{n=0}^{\infty} x(n) (\alpha^{-1} z)^{-n}$$

$$= X(\alpha^{-1} z) = X\left(\frac{z}{\alpha}\right)$$

Eg: $x(n) = u(n)$ find $X_m(z)$ for $(0.3)^n u(n)$
 Ans $X(z) = \frac{z}{z-1}$

$$X_m(z) = \frac{z/0.3}{z - 1} = \frac{z}{z - 0.3}, |z| > 0.3 //$$

Eg: Find $X_m(z)$ for $x_m(n) = \alpha^n \cos \Omega_0 n u(n)$
 For $x(n) = \cos \Omega_0 n u(n)$

$$X(z) = z \left[\frac{z - \cos \Omega_0}{z^2 - 2z \cos \Omega_0 + 1} \right]$$

$$\begin{aligned} \therefore X_m(z) &= \left(\frac{z}{\alpha} \right) \left[\frac{\left(z/\alpha \right) - \cos \Omega_0}{\left(\frac{z^2}{\alpha^2} \right) - 2 \frac{z}{\alpha} \cos \Omega_0 + 1} \right] \\ &= z \left[\frac{z - \alpha \cos \Omega_0}{z^2 - 2z \alpha \cos \Omega_0 + 1} \right] // \end{aligned}$$

4) Gradient in z plane: $x(n) \leftrightarrow X(z)$

$$\begin{aligned} \frac{d}{dz}(X(z)) &= \frac{d}{dz} \left[\sum_{n=0}^{\infty} x(n) z^{-n} \right] \\ &= \sum_{n=0}^{\infty} x(n) (-n) z^{-n-1} \end{aligned}$$

$$\frac{d}{dz}(X(z)) = -\frac{1}{z} \sum_{n=0}^{\infty} n x(n) z^{-n}$$

$$\therefore -z \frac{d}{dz}(X(z)) = \sum_{n=0}^{\infty} n x(n) z^{-n} \Rightarrow z [n x(n)] //$$

In general: $Z[n^k x(n)] = (-z)^k \left[\frac{d^k}{dz^k}(X(z)) \right]$

5> Initial value theorem: $\lim_{n \rightarrow 0} x(n) = x(0)$

$$X(z) = \sum_{n=0}^{\infty} x(n) z^{-n}$$

$$= x(0) + \frac{x(1)}{z} + \frac{x(2)}{z^2} + \dots$$

$$\lim_{z \rightarrow \infty} X(z) = \lim_{z \rightarrow \infty} x(0) + \frac{x(1)}{z} + \frac{x(2)}{z^2} + \dots$$

$$\Rightarrow \lim_{z \rightarrow \infty} X(z) = x(0) //$$

$$\therefore x(0) = \lim_{z \rightarrow \infty} X(z) //$$

Eg: Find $x(0)$ for $x(n) = u(n) \& \cos(\Omega_0 n) u(n)$
using $X(z)$

Atm $X(z) = \frac{z}{z-1}$ for $x(n) = u(n)$

$$x(0) = \lim_{z \rightarrow \infty} X(z) = \lim_{z \rightarrow \infty} \frac{z}{z-1} = \lim_{z \rightarrow \infty} \frac{z}{z(1-1/z)}$$

$$= \lim_{z \rightarrow \infty} \frac{1}{1-1/z} = 1 //$$

$$X(z) = z \left[\frac{z - \cos \Omega_0}{z^2 - 2z \cos \Omega_0 + 1} \right]$$

$$\therefore x(0) = \lim_{z \rightarrow \infty} z \left[\frac{z - \cos \Omega_0}{z^2 - 2z \cos \Omega_0 + 1} \right]$$

$$= \lim_{z \rightarrow \infty} \frac{z^2}{z^2} \left[\frac{1 - (\cos \Omega_0 / z)}{1 - (2 \cos \Omega_0 / z) + 1/z^2} \right] = 1 //$$

$$\text{Eg: If } X(z) = \frac{z}{z-1} + \frac{z}{z-\frac{1}{3}} - \frac{(z-\frac{1}{4})}{z^2 - \frac{z}{2} + 1}$$

Verify IVT

$$\text{Atm } x(0) = \lim_{z \rightarrow \infty} \frac{z}{z-1} + \lim_{z \rightarrow \infty} \frac{z}{z-\frac{1}{3}} - \lim_{z \rightarrow \infty} \frac{(z-\frac{1}{4})}{z^2 - \frac{z}{2} + 1}$$

$$\therefore x(0) = 1 + 1 - 0 = 2 //$$

$$\text{Also } x(n) = u(n) + (\frac{1}{3})^n u(n) - z^{-1} \left[\frac{(z-\frac{1}{4})}{(z-\frac{1}{4})^2 + \frac{15}{16}} \right]$$

$$5) \text{ Final value theorem : } z[x(n) - x(n-1)] = X(z) - \frac{x(z)}{z}$$

$$\lim_{N \rightarrow \infty} \sum_{n=0}^N [x(n) - x(n-1)] z^{-n} = X(z) \left(1 - \frac{1}{z} \right)$$

$$\text{But } \sum_{n=0}^N [x(n) - x(n-1)] z^{-n} = [x(N) - x(N-1)] z^{-N} + [x(N-1) - x(N-2)] z^{-(N-1)} + \dots$$

Now putting $\lim_{z \rightarrow 1}$ on both sides

$$\lim_{N \rightarrow \infty} \lim_{z \rightarrow 1} x(N) = \lim_{z \rightarrow 1} X(z) \left(1 - \frac{1}{z} \right)$$

$$\therefore x(\infty) = \lim_{z \rightarrow 1} X(z) \left(1 - \frac{1}{z} \right) //$$

Eg: Find $x(\infty)$ for i) $x_1(n) = u(n)$ using FVT
 ii) $x_2(n) = \alpha^n u(n)$

Ans i) $X_1(z) = \frac{z}{z-1}$

$$x(\infty) = \lim_{z \rightarrow 1} \left(\frac{z}{z-1} \right) \left(\frac{z-1}{z} \right) = 1 //$$

ii) $X_2(z) = \frac{z}{z-\alpha}$

$$\begin{aligned} x(\infty) &= \lim_{z \rightarrow 1} \left(\frac{z}{z-\alpha} \right) \left(\frac{z-1}{z} \right) \\ &= \lim_{z \rightarrow 1} \frac{z-1}{z-\alpha} = 0 // \end{aligned}$$

6) Convolution: $x_1(n) \longrightarrow X_1(z)$
 $x_2(n) \longrightarrow X_2(z)$

$$x_3(n) = x_1(n) * x_2(n)$$

$$\begin{aligned} X_3(z) &= \sum_{n=0}^{\infty} [x_1(n) * x_2(n)] z^{-n} \\ &= \sum_{n=0}^{\infty} \left[\sum_{k=0}^{\infty} x_1(n) \cdot x_2(n-k) \right] z^{-n} \end{aligned}$$

Put $n-k=l$
 $\Rightarrow X_3(z) = \sum_{l=-k}^{\infty} \left[\sum_{k=0}^{\infty} x_1(k) x_2(l) \right] z^{-(k+l)}$

$$= \left(\sum_{k=0}^{\infty} x_1(k) z^{-k} \right) \left(\sum_{l=0}^{\infty} x_2(l) z^{-l} \right)$$

$$\therefore X_3(z) = X_1(z) \cdot X_2(z)$$

Eg: Given $h(n) = \{1, 2, 0, -1, 1\}$ & $x(n) = \{1, 3, -1, -2\}$

$y_e(n) = \{1, 5, 5, -5, -6, 4, 1, -2\}$. Verify
using \geq transform.

Ans

$$H(z) = \sum_{n=0}^{\infty} h(n) z^{-n}$$

$$= 1 + 2z^{-1} - 1z^{-3} + z^{-4}$$

$$X(z) = \sum_{n=0}^{\infty} x(n) z^{-n} = 1 + 3z^{-1} - z^{-2} - 2z^{-3}$$

$$\begin{aligned} Y(z) &= X(z) \cdot H(z) \\ &= 1 + 3z^{-1} - z^{-2} - 2z^{-3} + 2z^{-1} + 6z^{-2} - 2z^{-3} - 4z^{-4} \\ &\quad - z^{-3} - 3z^{-4} + z^{-5} + 2z^{-6} + z^{-4} + 3z^{-5} - z^{-6} - 2z^{-7} \\ &= 1 + 5z^{-1} + 5z^{-2} - 5z^{-3} - 6z^{-4} + 4z^{-5} + z^{-6} - 2z^{-7} \end{aligned}$$

$$\therefore y(n) = \{1, 5, 5, -5, -6, 4, 1, -2\} // = y_e(n)$$

Verified.

Inverse z -transform

1) Circular integral method: $x(n) \leftrightarrow X(z)$

$$X(z) = \sum_{n=0}^{\infty} x(n) z^{-n}$$

then $x(n) = \frac{1}{2\pi j} \oint_C x(z) z^{n-1} dz \quad \rightarrow ②$

consider $\frac{1}{2\pi j} \oint_C x(z) z^{k-1} dz = \frac{1}{2\pi j} \int_C^{\infty} x(n) z^{k-n-1} dz$

with circle C being in ROC.

$$\text{Let } z = Re^{j\theta} \Rightarrow \frac{dz}{d\theta} = Re^{j\theta} j = jz$$

$$\Rightarrow \frac{dz}{z} = j d\theta$$

$$\therefore \frac{1}{2\pi j} \oint_C \sum_{n=0}^{\infty} x(n) z^{k-n} \frac{dz}{z} = \sum_{n=0}^{\infty} \frac{x(n)}{2\pi j} \oint_C (R, e^{j\theta})^{k-n} j d\theta$$

$$\Rightarrow \sum_{n=0}^{\infty} \frac{x(n) R_1^{k-n}}{2\pi} \int_0^{2\pi} e^{j(k-n)\theta} d\theta$$

$$\text{now if } n=k, \int_0^{2\pi} e^{j(k-k)\theta} d\theta = 2\pi$$

if $n \neq k$, integral = 0

$$\Rightarrow \sum_{n=0}^{\infty} \frac{x(n)}{2\pi} R_1^{(k-k)} \cdot 2\pi = \sum_{n=0}^{\infty} x(n) = x(n) //$$

This integral is known as Cauchy Integral

2) Power series / long division method:

- If ROC $|z| > r_1$, then $H(z) = \frac{N(z)}{D(z)}$ should

be arranged in such a way that both $N(z)$ & $D(z)$ should be in decreasing powers of z .

- If ROC $|z| < r_2$, then $H(z) = \frac{N(z)}{D(z)}$ should

be arranged in such a way that both $N(z)$ & $D(z)$ should be in increasing powers of z .

Eg: Given: $\frac{z}{3z^2 - 4z + 1}$, case 1: $|z| > 1$
case 2: $|z| < \frac{1}{3}$.

Find $x(n)$.

Ans

$$\begin{array}{r} 0z^0 + (\frac{1}{3})z^{-1} + (\frac{4}{9})z^{-2} + (\frac{13}{27})z^{-3} + \dots \\ \hline 3z^2 - 4z + 1) z \\ z - \frac{4}{3} + \frac{1}{3z} \\ \hline + \frac{4}{3} - \frac{1}{3z} \\ \hline + \frac{4}{3} - \frac{16}{9z} + \frac{4}{9z^2} \\ \hline \frac{13}{9z} - \frac{4}{9z^2} \\ \hline \frac{13}{9z} - \frac{52}{27z^2} + \frac{13}{27z^3} \\ \hline \frac{10}{9z^2} - \frac{13}{27z^3} \end{array}$$

$$\therefore x(n) = \left\{ 0, \frac{1}{3}, \frac{4}{9}, \frac{13}{27}, \dots \right\} \quad \text{if ROC : } |z| > 1$$

if ROC : $|z| < \frac{1}{3}$

$$X(z) = \frac{z}{1 - 4z + 3z^2}$$

$$\begin{array}{r} 0z^0 + z + 4z^2 + 13z^3 + 30z^4 \\ \hline 1 - 4z + 3z^2) \quad z \\ \underline{z - 4z^2 + 3z^3} \\ 4z^2 - 3z^3 \\ \underline{4z^3 - 16z^4 + 12z^5} \\ 13z^4 - 12z^5 \\ \underline{13z^4 - 52z^5 + 39z^6} \\ 30z^5 - 39z^6 \\ \vdots \end{array}$$

$$\therefore x(n) = \left\{ \dots, \underset{n=-\infty}{\overset{\uparrow}{30}}, 13, 4, 1, \underset{n=0}{\overset{\uparrow}{0}} \right\}$$

3) Partial fraction expansion:

Taking same example:

$$X(z) = \frac{z}{3z^2 - 4z + 1}$$

$$\frac{X(z)}{z} = \frac{1}{(3z-1)(z-1)} = \frac{a}{3z-1} + \frac{b}{z-1}$$

$$a = -\frac{3}{2} \quad b = \frac{1}{2}$$

$$\Rightarrow \frac{X(z)}{z} = \frac{-3}{2(3z-1)} + \frac{1}{2(z-1)}$$

$$X(z) = -\frac{3}{2} \frac{z}{3(z-1/3)} + \frac{1}{2} \frac{2}{z-1}$$

$$\therefore X(z) = \frac{1}{2} \left[1 - \left(\frac{1}{3}\right)^n \right] u(n)$$

• System function for a causal DTS (also LTI)

N^{th} order system:

$$\sum_{k=0}^N a_k y(n-k) = \sum_{k=0}^M b_k x(n-k)$$

→ System is initially relaxed i.e all initial conditions are zero

$$\sum_{k=0}^N a_k z^{-k} Y(z) = \sum_{k=0}^M b_k z^{-k} X(z)$$

$$\begin{aligned} \frac{Y(z)}{X(z)} &= H(z) = \frac{\sum_{k=0}^M b_k z^{-k}}{\sum_{k=0}^N a_k z^{-k}} \\ &= \frac{(z-z_0)(z-z_1)\dots(z-z_n)}{(z-p_0)(z-p_1)\dots(z-p_n)} = \frac{\prod_{i=0}^M (z-z_i)}{\prod_{i=0}^N (z-p_i)} \end{aligned}$$

where z_i = zeros ϵ_i p_i = poles

• If we put $z = e^{j\omega}$ then it becomes DTFT.

• $H(z)$ is known as system function

Eg: Given : $y(n) - 2y(n-1) + 2y(n-2) = x(n) + \frac{x(n-1)}{2}$
 Find $H(z)$.

$$At n \quad y(n) - 2y(n-1) + 2y(n-2) = x(n) + \frac{x(n-1)}{2}$$

$$Y(z) - 2\frac{Y(z)}{z} + 2\frac{Y(z)}{z^2} = X(z) + \frac{X(z)}{2z}$$

$$\Rightarrow Y(z) \left[\frac{z^2 - 2z + 2}{z^2} \right] = X(z) \left[\frac{2z + 1}{2z} \right]$$

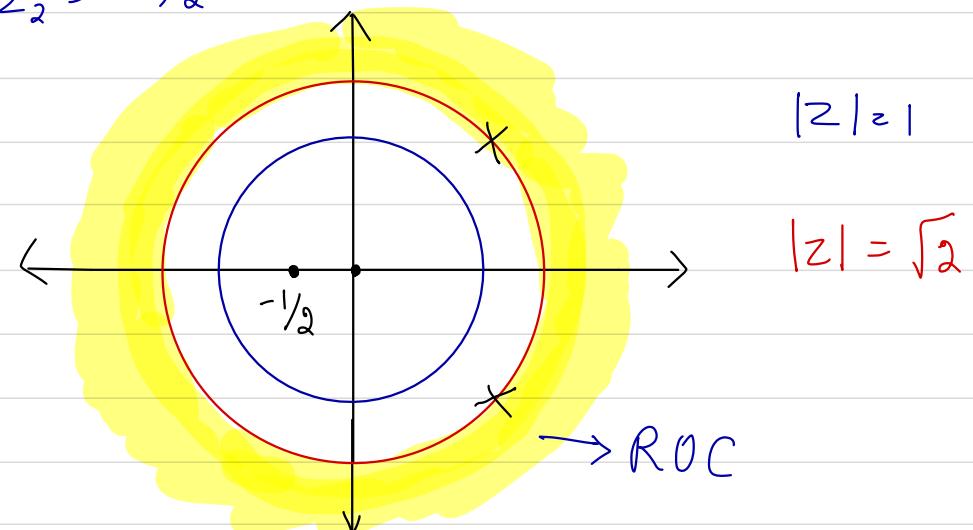
$$H(z) = \frac{Y(z)}{X(z)} = \frac{z(2z+1)}{2(z^2 - 2z + 2)}$$

$$\Rightarrow P_1, P_2 = \frac{2 \pm \sqrt{4-8}}{2} \Rightarrow P_1, P_2 = 1 \pm j$$

$$Z_1 = 0 \quad Z_2 = -\frac{1}{2}$$

X - Poles

• - Zeros



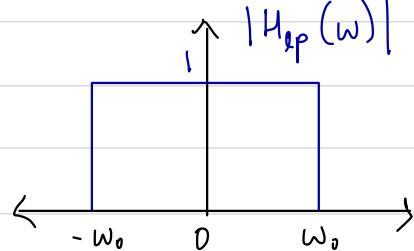
Filters:

Based on required sensitivity, active filters or passive filters can be chosen for a particular operation.

→ Active filters have higher sensitivity.

Ideal v/s Practical filters :

LPF: Ideal : $H(\omega) = \begin{cases} 1 & |\omega| \leq \omega_0 \\ 0 & \text{otherwise} \end{cases}$

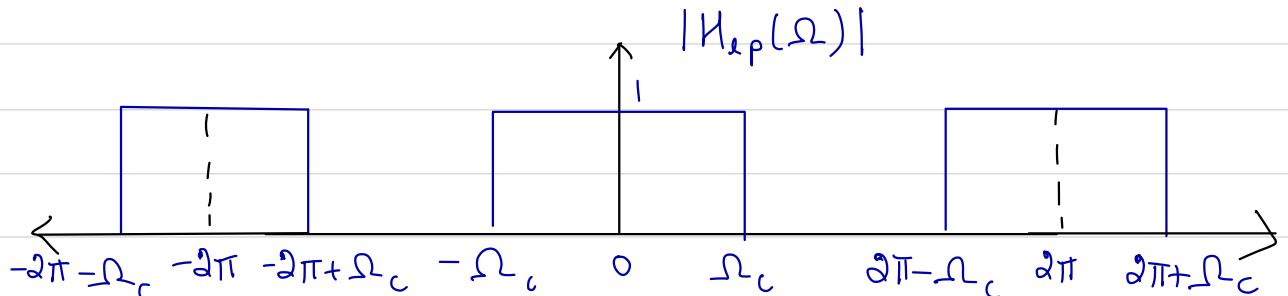


Inverse FT : $h(t) = \frac{1}{2\pi} \int_{-\omega_0}^{\omega_0} e^{j\omega t} d\omega = \frac{1}{2\pi j} \left[\frac{e^{j\omega t}}{t} \right]_{-\omega_0}^{\omega_0}$

$$= \frac{1}{2\pi j t} [e^{j\omega_0 t} - e^{-j\omega_0 t}] = \frac{\sin \omega_0 t}{\pi t}$$

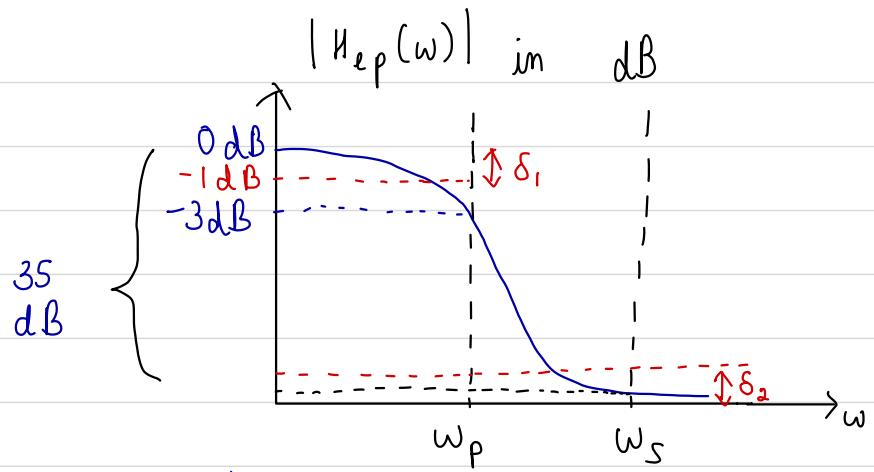
In discrete time domain :

$$H_{lp}(\Omega) = \begin{cases} 1, |\Omega| \leq \Omega_c \\ 0, \Omega_c < |\Omega| \leq \pi \end{cases}$$



Practical LPF:

$$\omega_p = \text{passband}$$
$$\omega_s = \text{stopband}$$



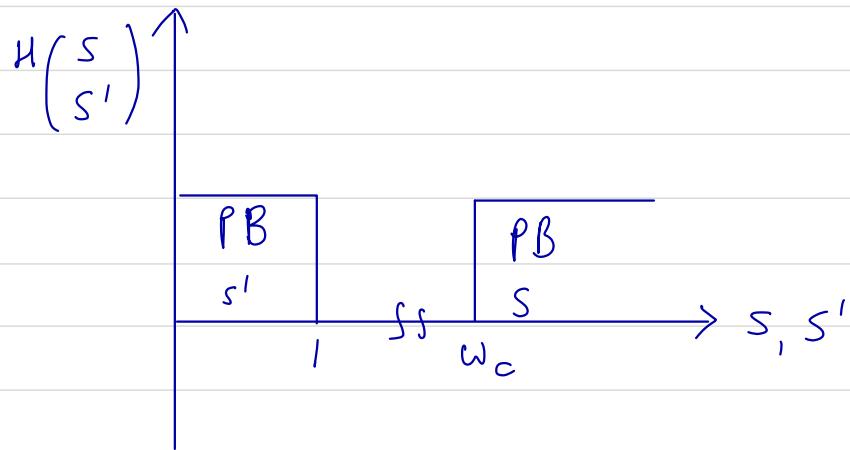
Transfer function: $|H_{ep}(w)| = \begin{cases} 1 \pm \delta_1, & |w| \leq w_p \\ \delta_2, & |w| \geq w_s \end{cases}$

Normalised LPF: Has cutoff frequency = 1 (unity)

Frequency transformation :

$$s' - \text{plane} \rightarrow s - \text{plane}$$

$$s' = \sigma' + j\omega' \rightarrow s = \sigma + j\omega$$



Forward mapping $s' = f(s)$
Inverse mapping $s = g(s')$

i) Normalise LPF \rightarrow LPF with ω_c

$$\omega_c \stackrel{\triangle}{=} \text{unity}$$

$$s' = \sigma' + j\omega'$$

Pass band \rightarrow LPF ω

$$0 \leq \omega' \leq 1 \rightarrow 0 \leq \omega \leq \omega_c$$

$$\Rightarrow \frac{j\omega'}{1} = \frac{j\omega}{\omega_c}$$

$$\Rightarrow \omega = \omega' \omega_c$$

∴

$$\boxed{\frac{s'}{1} = \frac{s}{\omega_c}}$$

Eg: If LPF is made LC

then $X_L = Ls'$
 $= L \frac{s}{\omega_c}$

$$\therefore Lq = \frac{L}{\omega_c}$$

$$X_c = \frac{1}{s' C} = \frac{\omega_c}{s C} \quad \therefore C_{eq} = \frac{C}{\omega_c}$$

2) LPF : ω_c' \rightarrow HPF : ω_c

Pass band: $0 \leq \omega' \leq \omega_c'$ $\rightarrow \omega_c \leq \omega \leq \infty$

$$\Rightarrow \frac{j\omega'}{\omega_c'} = \frac{\omega_c}{j\omega}$$

$$\Rightarrow \omega = \left| -\frac{\omega_c' \omega_c}{\omega'} \right| \quad \therefore \omega = \frac{\omega_c' \omega_c}{\omega'}$$

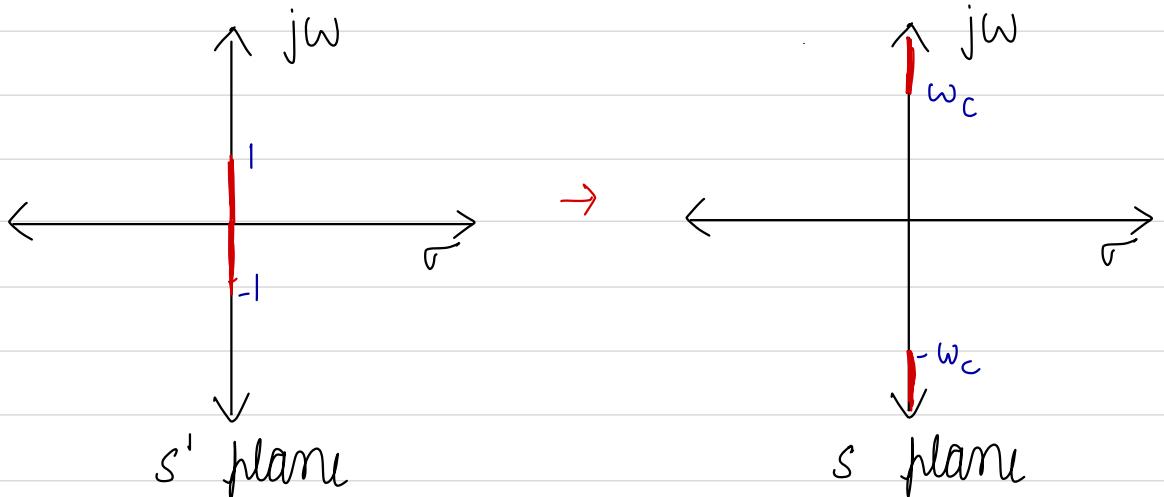
Also

$$\boxed{\frac{s'}{\omega_c'} = \frac{\omega_c}{s}}$$

For normalized LPF: $s' = \frac{\omega_c}{s}$

$$\text{So } X_L = L s' = L \frac{\omega_c}{s} = \frac{1}{C_{eq} s} \quad \therefore C_{eq} = \frac{1}{L \omega_c},$$

$$X_c = \frac{1}{s' C} = \frac{s}{\omega_c C} = L_{eq} s \quad \therefore L_{eq} = \frac{1}{C \omega_c},$$

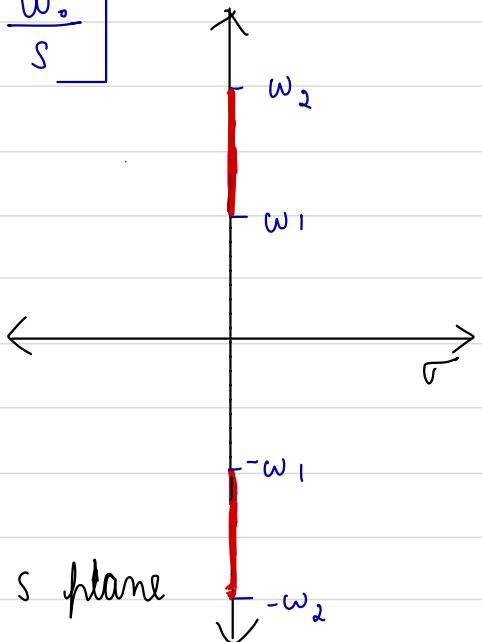
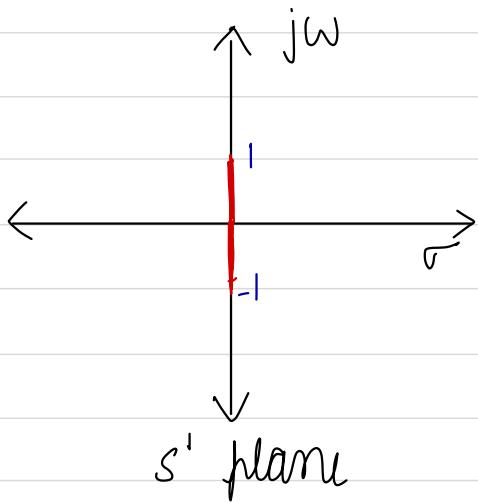


3) LPF \rightarrow Band pass filter:
 $s' \rightarrow s$

For BPF, let bandwidth = $B = \omega_2 - \omega_1$,
 Mid band frequency = $\omega_0 = \sqrt{\omega_1 \omega_2}$

BPF \rightarrow High pass filter cascaded by Low pass filter and not vice versa.

$$s' = \frac{\omega_0}{B} \left[\frac{s}{\omega_0} + \frac{\omega_0}{s} \right]$$



$$s' = j\omega = \frac{\omega_0}{B} \left[\frac{j\omega}{\omega_0} + \frac{\omega_0}{j\omega} \right]$$

$$Bj\omega_0 j\omega = \omega_0 \left[-\omega^2 + \omega_0^2 \right]$$

$$-\beta\omega = \omega_0^2 - \omega^2$$

$$\Rightarrow \omega^2 - \beta\omega - \omega_0^2 = 0$$

$$\therefore \omega = \frac{\beta}{2} \pm \sqrt{\frac{\beta^2}{4} + \omega_0^2}$$

$$= \frac{\omega_2 - \omega_1}{2} \pm \sqrt{\frac{\omega_2^2 + \omega_1^2 - 2\omega_1\omega_2 + 4\omega_1\omega_2}{4}}$$

$$\omega = \frac{\omega_2 - \omega_1}{2} \pm \frac{\omega_2 + \omega_1}{2}$$

$$\omega = \omega_2 \text{ or } -\omega_1$$

Also $\chi_L = S'L = L \left[\frac{S}{B} + \frac{\omega_0^2}{S B} \right] = \frac{LS}{B} + \frac{L\omega_0^2}{BS}$

$$= L_{b_1} S + \frac{1}{SC_{b_1}}$$

$$\therefore L_{b_1} = \frac{L}{B}$$

$$C_{b_1} = \frac{B}{L\omega_0^2}$$

$$\chi_C = \frac{1}{S'C} = \frac{1}{\frac{CS}{B} + \frac{C\omega_0^2}{B} \cdot \frac{1}{S}} = \frac{1}{C_{b_2} S + \frac{1}{L_{b_2} S}}$$

$$\therefore C_{b_2} = \frac{C}{B}$$

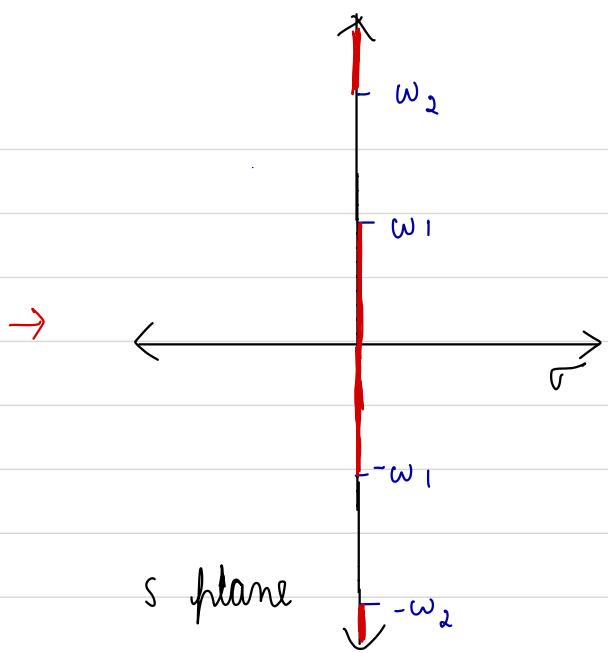
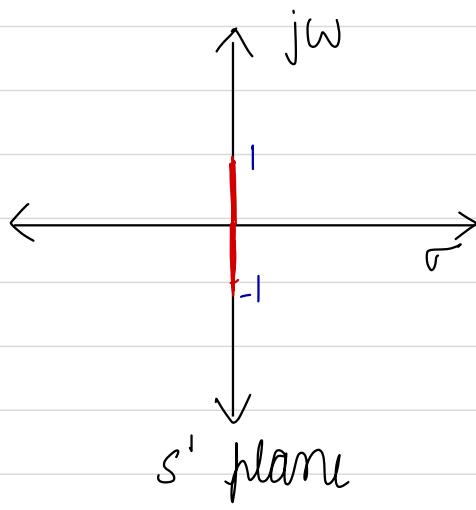
$$L_{b_2} = \frac{B}{C\omega_0^2}$$

i.e. $\frac{m}{L} = \frac{m}{L_{b_1}} \parallel \frac{1}{C_{b_1}}$

$$\frac{1}{C} = \frac{m}{L_{b_1}} \parallel \frac{1}{C_{b_2}}$$

↳ LPF to Bandstop filter:

$$PB : 0 \leq \omega' \leq \omega_c \rightarrow |\omega| \geq \omega_2 \text{ & } |\omega| \leq \omega_1$$



$$s^1 = \frac{1}{\frac{\omega_0}{B} \left[\frac{s}{\omega_0} + \frac{\omega_0}{s} \right]}$$

Chelyshkov Polynomial for n^{th} Order

$$C_n(\omega) \triangleq \cos(n \cos^{-1} \omega) \rightarrow ①$$

$$\cos^{-1} \omega = \theta \Rightarrow \omega = \cos \theta$$

$$C_n(\omega) = \cos(n\theta) \rightarrow ②$$

$$\text{For } ②, \quad n=0 \Rightarrow C_0(\omega) = 1$$

$$n=1 \Rightarrow C_1(\omega) = \cos \theta = \omega$$

$$C_{n+1}(\omega) = \cos((n+1)\theta) = \cos n\theta \cos \theta - \sin n\theta \sin \theta \rightarrow ③$$

$$C_{n-1}(\omega) = \cos((n-1)\theta) = \cos n\theta \cos \theta + \sin n\theta \sin \theta \rightarrow ④$$

$$\begin{aligned} ③ + ④ &\Rightarrow C_{n+1}(\omega) + C_{n-1}(\omega) = 2 \cos n\theta \cos \theta \\ &= 2\omega C_n(\omega) \rightarrow ⑤ \end{aligned}$$

$$C_{n+1}(\omega) = 2\omega C_n(\omega) - C_{n-1}(\omega) \rightarrow ⑥$$

$$\begin{aligned} C_2(\omega) &= 2\omega C_1(\omega) - C_0(\omega) \\ &= 2\omega \cdot \omega - 1 \\ &= 2\omega^2 - 1 \end{aligned}$$

$$\begin{aligned} C_3(\omega) &= 2\omega(2\omega^2 - 1) - \omega \\ &= 4\omega^3 - 2\omega - \omega \\ &= 4\omega^3 - 3\omega \end{aligned}$$

:

$$C_{10}(\omega) = 512\omega^{10} - 1280\omega^8 + 1120\omega^6 - 400\omega^4 + 50\omega^2 - 1$$

$$\text{if } \omega \gg 1, \quad C_n(\omega) \approx 2^{n-1} \omega^n$$

NOTE:

MATLAB: C_{11}

$\gg \text{syms } \omega$

$\gg C_{11} = \cos(11 * \text{acos}(\omega));$

$\gg C_{11} = \text{expand}(C_{11})$

Analyse $C_n(\omega)$ for various ω

1) Passband ($0 \leq \omega \leq 1$):

$$C_n(\omega) = \cos(n \cos^{-1} \omega) \Rightarrow C_n(0) = \cos(n\pi/2)$$

If $n = \text{even}$, $C_n(0) = 1$
 $n = \text{odd}$, $C_n(0) = -1$

$$\begin{aligned} C_n(1) &= \cos(n \cos^{-1}(1)) \\ &= \cos(n \cdot 2m\pi) = 1 \end{aligned}$$

2) If $\omega > 1$: $C_n(\omega) = \cos(n \cos^{-1} \omega)$
 $= \cosh(n \cosh^{-1}(\omega))$

3) If $\omega \gg 1$: $C_n(\omega) \approx 2^{n-1} \omega^n$

Chelyshov LPF characteristic

$$|C_n(\omega)| \leq 1 \quad \text{for} \quad |\omega| \leq 1$$

$$C_n(\omega) = \cos(n \cos^{-1} \omega)$$

$$C_n(-\omega) = \cos(n \cos^{-1}(-\omega))$$

$$= \cos[n(\pi + \cos^{-1}\omega)]$$

$$= \cos[n\pi + n \cos^{-1}\omega]$$

$$= \cos n\pi \cos(n \cos^{-1}\omega) - \sin n\pi \sin(n \cos^{-1}\omega)$$

$$= (-1)^n C_n(\omega)$$

For a small number ξ

$$F^2(\omega) = \xi^2 C_n^2(\omega)$$

$$|H(j\omega)|^2 = \frac{A_0}{1 + F^2(\omega)} = \frac{1}{1 + \xi^2 C_n^2(\omega)}$$

For band (0 ≤ ω ≤ 1) :

$$|H(j\omega)| = \frac{1}{1 + \xi^2}$$

$$|H(j\omega)|_{\max} = 1$$

$$|H(j\omega)|_{\min} = \frac{1}{\sqrt{1 + \xi^2}}$$

$$\text{Attenuation (dB)} = 10 \log_{10} \left(\frac{1}{1 + \xi^2} \right)$$

$$\Rightarrow \alpha_p = -10 \log_{10} (1 + \xi^2)$$

$$\bullet \text{ If } \xi^2 C_n^2(\omega) \gg 1, \quad |H(j\omega)|^2 \approx \frac{1}{\xi^2 C_n^2(\omega)}$$

$$\therefore |H(j\omega)|^2 \approx \frac{1}{\xi^2 2^{2(n-1)} \omega^{2n}}$$

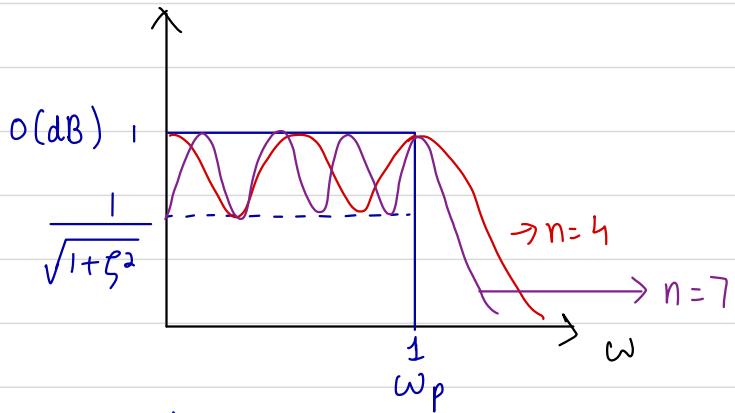
$$|H(j\omega)|^2 \text{ in dB} = -10 \log_{10} (\xi^2 2^{2(n-1)} \omega^{2n})$$

$$\Rightarrow \alpha_s(\omega) = -20 \log (\xi 2^{n-1} \omega^n), \\ = -20 \log_{10} \xi - 20(n-1) \log 2 - 20n \log \omega$$

$$\therefore \alpha_s(\omega) = -20 \log_{10} \xi - 6(n-1) - 20n \log \omega$$

NOTE: α_p = attenuation in band

α_s = attenuation in stopband



Sum of maxima + minima = n

Eg: Estimate n. $\alpha_p = 1 \text{ dB}$ $\alpha_s = 25 \text{ dB}$

$$\frac{\omega_s}{\omega_p} = 1.5 \quad |H(j\omega)|^2 = \frac{1}{1 + \xi^2 C_n^2(\omega)}$$

Atm $\alpha_p = 10 \log(1 + \xi^2) = 1$
 $\log(1 + \xi^2) = 1/10$
 $1 + \xi^2 = 10^{0.1}$
 $\xi^2 = 0.259,$

$$\begin{aligned}\alpha_s &= 10 \log[1 + \xi^2 C_n^2(\omega)] \\ 25 &= 10 \log[1 + 0.259 C_n^2(1.5)] \\ C_n^2(1.5) &= 1217.4 \\ C_n(1.5) &= \sqrt{1217.4} \\ C_n &= 34.9\end{aligned}$$

$$\Rightarrow C_n(\omega) = \cos(n \cosh^{-1} \omega)$$

But $\omega > 1 \Rightarrow C_n(\omega) = \cosh(n \cosh^{-1}(\omega))$

$$\Rightarrow 34.9 = \cosh(n \cosh^{-1}(1.5))$$

$$n = \frac{\cosh^{-1}(34.9)}{\cosh^{-1}(1.5)} = 4.41 \approx 5^{\text{th}} \text{ order}$$

For Butterworth, $|H(j\omega)|^2 = \frac{1}{1 + \omega^{2n}}$

$n = q$, for butterworth filter.

Digital filter:

FIR filter: Finite impulse response
 IIR filter: Infiniit impulse response

LTI (Linear time invariant) → LSI (linear shift invariant)
 Analog Digital

$$y(n) = \sum_{k=0}^q a_k x(n-k) - \sum_{k=1}^p b_k y(n-k) \rightarrow \textcircled{1}$$

$$y(n) + \sum_{k=0}^p b_k y(n-k) = \sum_{k=0}^q a_k x(n-k)$$

$$Y(z) \left[1 + \sum_{k=1}^p b_k z^{-k} \right] = \sum_{k=0}^q a_k z^{-k} X(z) \rightarrow \textcircled{2}$$

$$H(z) = \frac{Y(z)}{X(z)} = \frac{\sum_{k=0}^q a_k z^{-k}}{1 + \sum_{k=1}^p b_k z^{-k}} \rightarrow \textcircled{3}$$

$$H(z) = A \frac{\prod_{k=1}^q (1 - \alpha_k z^{-1})}{\prod_{k=1}^p (1 - \beta_k z^{-1})}$$

case 1: if $p > q \Rightarrow$ proper system function

case 2: if $p < q \Rightarrow$ improper system function

Impulse response for a rational system function:

$\alpha_i \neq \beta_j \Rightarrow$ No pole zero cancellation (1st order)

if proper rational function, $p > q$

$$PFE \Rightarrow H(z) = \sum_{k=1}^p \frac{a_k}{1 - \beta_k z^{-1}}$$

$IIT \downarrow$

$$h(n) = \sum_{k=1}^p a_k (\beta_k)^n u(n), \quad |\beta_k| < 1 \rightarrow IIR$$

When $q > p$

$$H(z) = \sum_{k=0}^{q-p} \alpha_k z^{-k} + \sum_{k=1}^p \frac{a_k}{1 - \beta_k z^{-1}}$$

$$\therefore h(n) = \sum_{k=0}^{q-p} \alpha_k \delta(n-k) + \sum_{k=1}^p a_k \beta_k^n u(n)$$

$\underbrace{\hspace{10em}}_{FIR} + \underbrace{\hspace{10em}}_{IIR} = IIR$

Suppose $p = 0$, $h(n) = FIR$

$p > 0$, $h(n) = IIR$

Inverse system

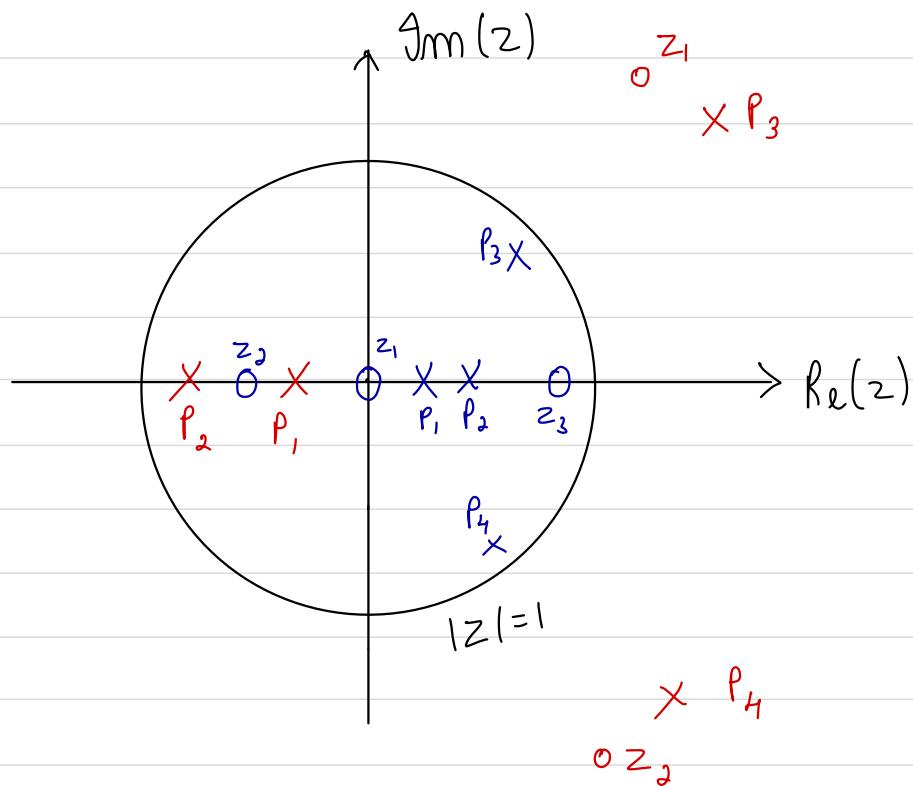
If $h_2(n)$ is inverse of $h_1(n)$ then ,
 $h_1(n) * h_2(n) = \delta(n)$

$$\Rightarrow H_1(z) \cdot H_2(z) = 1$$

$$\therefore H_2(z) = \frac{1}{H_1(z)}$$

Minimum phase system

Given a pole zero plot ;



- For inverse system, zeros become poles and poles become zeros .
- For blue coloured zeros & poles , they remain within $|z|=1$
- For red coloured zeros & poles , they can make inverse unstable .

Minimum phase response $\Rightarrow |z_k| < 1 \quad \sum |p_k| <$

in

$$H(z) = \frac{\prod_{k=1}^q (z - z_k)}{\prod_{k=1}^p (z - p_k)}$$

Eg: $|H(e^{j\omega})|^2 = \frac{17}{16} - \frac{1}{2} \cos \omega$. Check if system

Ans in minimum phase system.

$$|H(e^{j\omega})|^2 = \frac{17}{16} - \frac{1}{2} \frac{(e^{j\omega} + e^{-j\omega})}{2}$$

$$|H(z)|^2 = \frac{17}{16} - \frac{1}{4} \left(z + \frac{1}{z} \right)$$

Frequency response of an LTI FIR & IIR system

$$h(n) = \begin{cases} 1 & , N_1 \leq n \leq N_2 \\ 0 & , \text{otherwise} \end{cases}, \quad N_2 > N_1$$

$$H(e^{j\omega}) = \sum_{n=N_1}^{N_2} h(n) e^{-j\omega n}$$

Here $\omega = \Omega$

Difference equation:

$$\sum_{k=0}^N d_k y(n-k) = \sum_{k=0}^M p_k x(n-k)$$

$$\sum_{k=0}^N d_k e^{-jk\omega} Y(e^{j\omega}) = \sum_{k=0}^M p_k e^{-jk\omega} X(e^{j\omega})$$

$$H(e^{j\omega}) = \frac{Y(e^{j\omega})}{X(e^{j\omega})} = \frac{\sum_{k=0}^M p_k e^{-jk\omega}}{\sum_{k=1}^N d_k e^{-jk\omega}}$$

Eg: Frequency response of moving average filter

$$h(n) = \frac{1}{M} \left\{ \underset{0}{\overset{1}{\uparrow}}, \underset{1}{\overset{1}{\uparrow}}, \underset{2}{\overset{1}{\uparrow}}, \dots, \underset{M-2}{\overset{1}{\uparrow}}, \underset{M-1}{\overset{1}{\uparrow}}, 0, 0 \right\}$$

$$h(n) = \frac{1}{M} \left\{ \underset{0}{\alpha_1}, \underset{1}{\alpha_2}, \underset{2}{\alpha_3}, \dots, \underset{M-1}{\alpha_M}, 0, 0 \right\}$$

DTFT: $H(e^{j\omega}) = \sum_{n=0}^{M-1} \frac{1}{M} e^{-j\omega n}$

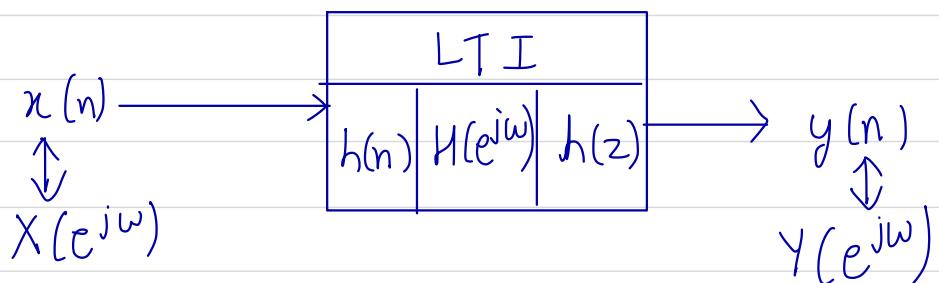
$$\Rightarrow H(e^{j\omega}) = \frac{1}{M} \sum_{n=0}^{M-1} (e^{-j\omega})^n \rightarrow \text{finite GP sum}$$

$$\begin{aligned} &= \frac{1}{M} \frac{1 - e^{-j\omega M}}{1 - e^{-j\omega}} = \\ &= \frac{1}{M} \frac{e^{-j\omega M/2} [e^{+j\omega M/2} - e^{-j\omega M/2}]}{e^{-j\omega/2} [e^{j\omega/2} - e^{-j\omega/2}]} \\ &= \frac{1}{M} e^{j\omega(1-M)/2} \frac{\sin(\omega M/2)}{\sin(\omega/2)} \end{aligned}$$

Magnitude response: $|H(e^{j\omega})| = \frac{1}{M} \frac{\sin(\omega M/2)}{\sin(\omega/2)}$

This behaves like LPF

Phase ξ group delay:



$$\begin{aligned} Y(e^{j\omega}) &= H(e^{j\omega}) X(e^{j\omega}) \\ |Y(e^{j\omega})| &= |H(e^{j\omega})| \cdot |X(e^{j\omega})| \\ \angle Y(e^{j\omega}) &= \angle H(e^{j\omega}) + \angle X(e^{j\omega}) \end{aligned}$$

More spectral:

Let $x(n) = A \cos(\omega_0 n + \phi)$

then

$$y(n) = A |H(e^{j\omega})| \cdot \cos[\omega_0 n + \phi + \theta(\omega)]$$

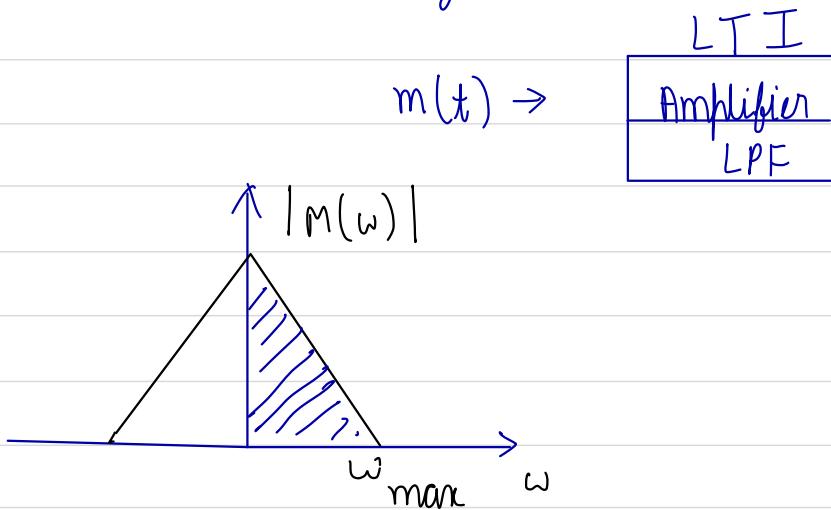
$$y(n) = A |H(e^{j\omega})| \cdot \cos \left[\omega_0 \left(n + \frac{\theta(\omega)}{\omega_0} \right) + \phi \right]$$

$$= A |H(e^{j\omega})| \cdot \cos \left[\omega_0 (n - \tau_p) + \phi \right]$$

where $\tau_p = - \frac{\theta(\omega)}{\omega_0}$

continuous time counterpart of τ_p ,
group delay, $\tau_g = - \frac{d(\theta(\omega))}{d\omega}$

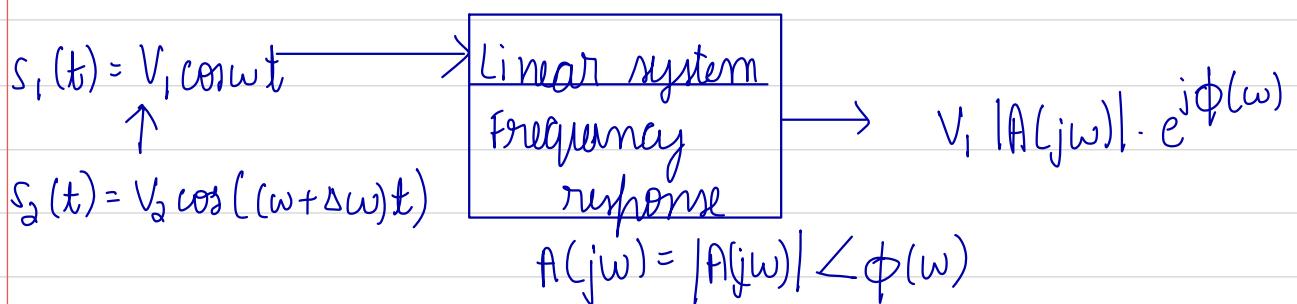
Consider a system:



• Also $\tau_g = - \frac{d(\theta(\omega))}{d\omega}$

If τ_g is fixed quantity, then it is fixed slope.

Amplitude and phase distortion:



$$\begin{aligned}
 \text{for } s_1, \quad V_1 |A(j\omega)| e^{j\phi(\omega)} &= V_1 |A(j\omega)| \cos(\omega t + \phi(\omega)) \\
 &= V_1 |A(j\omega)| \cos\left(\omega(t + \frac{\phi(\omega)}{\omega})\right) \\
 &= V_1 |A(j\omega)| \cos[\omega(t - T_p)] \\
 \text{where } T_p &\stackrel{\triangle}{=} \frac{-\phi(\omega)}{\omega} \rightarrow \textcircled{1}
 \end{aligned}$$

Response: $V_2 |A(j(\omega + \Delta\omega))| e^{j\phi(\omega + \Delta\omega)}$

$$\begin{aligned}
 &= V_2 |A(j(\omega + \Delta\omega))| \cos[(\omega + \Delta\omega)t + \phi(\omega + \Delta\omega)] \\
 &= V_2 |A(j(\omega + \Delta\omega))| \cos[(\omega + \Delta\omega)(t - T_p)] \rightarrow \textcircled{2}
 \end{aligned}$$

$$\text{where } T_{p_2} = \frac{-\phi(\omega + \Delta\omega)}{\omega + \Delta\omega} \rightarrow \textcircled{3}$$

But,

$$\phi(\omega + \Delta\omega) = \phi(\omega) + \frac{d\phi}{d\omega} \Delta\omega$$

$$\begin{aligned}
 \text{consider } \frac{1}{\omega + \Delta\omega} &= (\omega + \Delta\omega)^{-1} \\
 &= \omega^{-1} \left(1 + \frac{\Delta\omega}{\omega}\right)^{-1} \\
 &= \omega^{-1} \left(1 - \frac{\Delta\omega}{\omega} + \left(\frac{\Delta\omega}{\omega}\right)^2 + \dots\right)
 \end{aligned}$$

Ignoring higher order terms,

$$\frac{1}{\omega + \Delta\omega} \approx \frac{1}{\omega} \left(1 - \frac{\Delta\omega}{\omega}\right)$$

From equation $\textcircled{3}$, $\frac{\phi(\omega + \Delta\omega)}{\omega + \Delta\omega} = \left(\frac{\phi(\omega)}{\omega} + \frac{d\phi}{d\omega} \frac{\Delta\omega}{\omega}\right) \left(1 - \frac{\Delta\omega}{\omega}\right)$

$\uparrow \tau_{P_1}$

$$\therefore \tau_{P_2} = -\frac{\phi(w)}{w} + \frac{\phi(w)}{w} \frac{\Delta w}{w} - \frac{\Delta w}{w} \frac{d\phi}{dw}$$

To make $\tau_{P_1} = \tau_{P_2}$

$$\tau_{P_2} = \tau_{P_1} + \frac{\Delta w}{w} \left(\frac{\phi(w)}{w} - \frac{d\phi}{dw} \right)$$

$$\Rightarrow \frac{\Delta w}{w} \left(\frac{\phi(w)}{w} - \frac{d\phi}{dw} \right) = 0$$

$$\Rightarrow \int \frac{dw}{w} = \int \frac{d\phi}{\phi(w)}$$

$$\ln \phi(w) = \ln w + \ln K$$

$$\phi(w) = Kw //$$

$$\boxed{\phi(w) \propto w}$$

→ condition for zero phase distortion

$$\text{Also } d\phi = K dw \Rightarrow \frac{d\phi}{dw} = K = -\tau_g$$

$$\therefore \tau_g = \text{constant} //$$

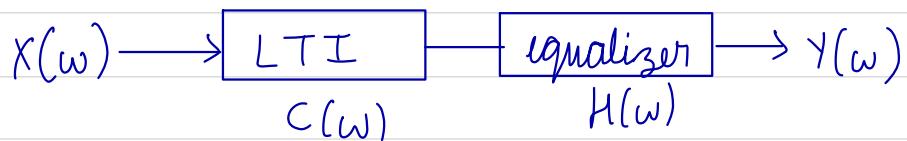
Frequency domain equalization

Consider a practical channel; Frequency response = $C(\omega)$

Ideal situation \Rightarrow Behave like response channel
 FR: $C_{ref}(\omega) = e^{-j\omega D}$

where $D = \text{delay}$

Practical channel to ideal channel is made by cascading an equalizer:



$$\Rightarrow Y(\omega) = C(\omega) \cdot H(\omega) \cdot X(\omega)$$

For ideal channel: $Y(\omega) = C_{ref}(\omega) \cdot X(\omega)$

$$\therefore C_{ref}(\omega) = C(\omega) \cdot H(\omega)$$

$$\Rightarrow H(\omega) = \frac{C_{ref}(\omega)}{C(\omega)} = \frac{e^{-j\omega D}}{C(\omega)}$$

$H(\omega) \rightarrow$ FIR filter
 \downarrow IDTFT

$$\begin{aligned} h(l) &= \text{defined} & \text{for } 0 \leq l \leq n-1 \\ \Rightarrow H(\omega) &= \sum_{l=0}^{L-1} h(l) e^{-j\omega l} \end{aligned}$$

Discretizing ω to M samples,

$$h(m) = \sum_{l=0}^{L-1} h(l) e^{-j\frac{2\pi}{M} ml}$$

where $m = 0, 1, 2, \dots, M-1$

$$\text{Also } H(\omega) = \sum_{l=0}^{L-1} h(l) e^{-j\omega l} = a^T(\omega) \cdot h$$

where $a(\omega) = [e^{-j\omega 0}, e^{-j\omega 1}, e^{-j\omega 2}, \dots]$, $a^T(\omega)$ = Transpose of a

$$h = [h(0), h(1), h(2), \dots, h(L-1)]_{L \times 1}$$

$$\therefore H(m) = a_m^T \cdot h$$

$$a_m = [1, e^{-j\frac{2\pi m}{M}}, e^{-j\frac{2\pi m \times 2}{M}}, e^{-j\frac{2\pi m \times 3}{M}}, \dots, e^{-j\frac{2\pi m (L-1)}{M}}]_{L \times 1}$$

NOTE: FIR filters are preferred over IIR filters because :

- 1> It is easier to maintain Linear phase response in FIR filter.
- 2> FIR filters are always stable. IIR filters may or may not be stable.

Least Square Approximation Algorithm

Strategy: Use of digital filter to approximate the system $H(w)$ or $H(m)$

Use FIR filter of length L , having frequency response $E(w)$

We try to approximate $E(w) \approx H(w)$ from $\textcircled{*}$. So that we can use a FIR filter instead of the previous block diagram system. Since $H(w) / H(m)$ is just a abstract math model we use this approach to realize the model.

$$E(w) = \sum_{n=0}^{L-1} h(n) e^{-jwn} \rightarrow a(w)$$

↓
array of length 'L'

$$\therefore E(w) = a(w) \cdot h$$

$$\text{where } h = \{ h(0), h(1), \dots, h(L-1) \}_{1 \times L}$$

$$a(w) = \{ 1, e^{-jw}, e^{-2jw}, \dots, e^{-j(L-1)w} \}_{1 \times L}$$

$$\text{Taking } T = \text{unity}$$

$$a(w) = \{ 1, e^{-jwT}, e^{-2jwT}, e^{-3jwT}, \dots, e^{-j(L-1)wT} \}_{1 \times L}$$

$h \rightarrow$ weighted coefficient array or filtered coefficient array

$a \rightarrow$ Phase shift array

$$E(\omega) = \vec{a}^T(\omega) \cdot h$$

Discretizing ω to M samples

$$E(m) = \sum_{n=0}^{L-1} h(n) e^{-j\frac{2\pi}{M} m n} \quad m = 0, 1, 2, \dots, M-1$$

$$\text{Error} = e(m) = H(m) - E(m)$$

$$a(m) = \{a(0), a(1), \dots, a(M-1)\}_{1 \times M}$$

$E(m)$ can be written as:

$$E(m) = A^T \cdot h$$

where

$$A^T = \begin{bmatrix} 1 & 1 & 1 & \dots & 1 \\ 1 & \ddots & & & \vdots \\ \vdots & \ddots & \ddots & & \vdots \\ \vdots & & \ddots & \ddots & \vdots \\ 1 & \cdots & \cdots & \cdots & e^{-j\frac{2\pi}{M} (M-1)(L-1)} \end{bmatrix}_{L \times M}$$

$$\text{Error} = \vec{e} = \vec{H} - A \cdot \vec{h}$$

To minimize error we vary \vec{h} .

$$\text{Optimization: } \min |(e_m)^2| = \min_h \|H - Ah\|^2$$

Transfer function (frequency response) classification
 - on band on phase characteristics

TF: $H(z) \rightarrow$ real valued coefficients $h(n)$

$$H(z) = \sum_{n=0}^{\infty} h(n) z^{-n}$$

Define: $F(z) = H(z) H(z^{-1})$, $F(z) = \text{zero}$

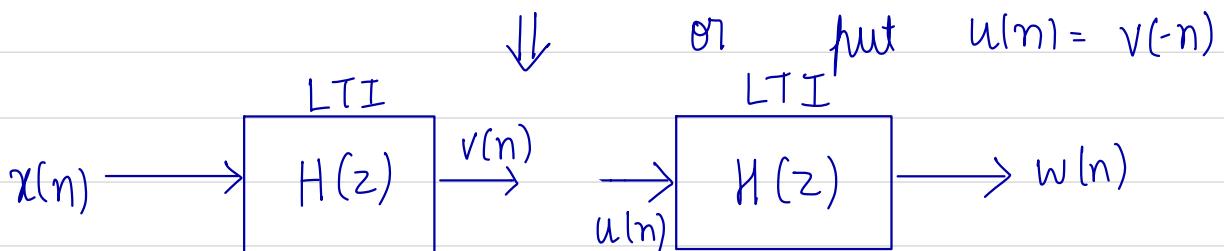
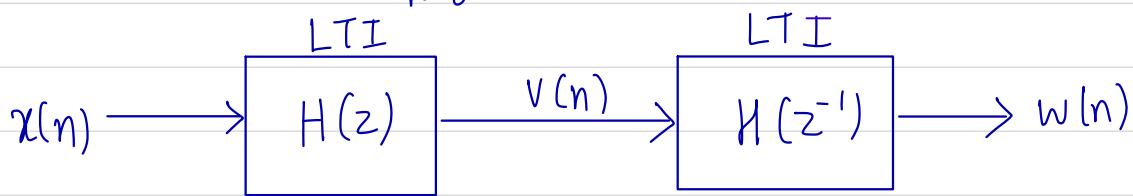
$$F(e^{j\omega}) = |H(e^{j\omega})|^2 e^{j0}$$
, phase TF

At $z = V(P/z)$ (Poly/zero) for $H(z)$
 then for $H(z^{-1})$, $z = \frac{1}{V(P/z)} \Rightarrow z = V^{-1}$

FIR: $A(z) = \sum_{i=0}^N h(i) z^{-i}$

then zero phase transfer function:

$$B(z) = \sum_{i=0}^N h(i) [z^i + z^{-i}]$$



$x(n) \leftrightarrow X(z) \Rightarrow x(-n) \leftrightarrow X(z^{-1})$

Also $U(e^{j\omega}) = V(e^{-j\omega}) = V^*(e^{j\omega})$
 $y(n) = w(-n)$

$$V(e^{j\omega}) = X(e^{j\omega}) \cdot H(e^{j\omega})$$

$$U(e^{j\omega}) = X^*(e^{j\omega}) \cdot H^*(e^{j\omega})$$

$$W(e^{j\omega}) = U(e^{j\omega}) \cdot H(e^{j\omega}) = X^*(e^{j\omega}) \cdot H^*(e^{j\omega}) H(e^{j\omega})$$

$$Y(e^{j\omega}) = W^*(e^{j\omega})$$

NOTE: zero phase response is practically realizable.

Linear phase transfer function

- We try to achieve linear phase only in passband.

$$x(n) \xrightarrow{D} y(n) = x(n-D)$$

$$H(e^{j\omega}) = \frac{Y(e^{j\omega})}{X(e^{j\omega})} = e^{-j\omega D} //$$

$$\Rightarrow |H(e^{j\omega})| = 1 \quad \Rightarrow \angle H(e^{j\omega}) = -\omega D,$$

Eg: If $x(n) = Ae^{j\omega n}$ then for linear phase response

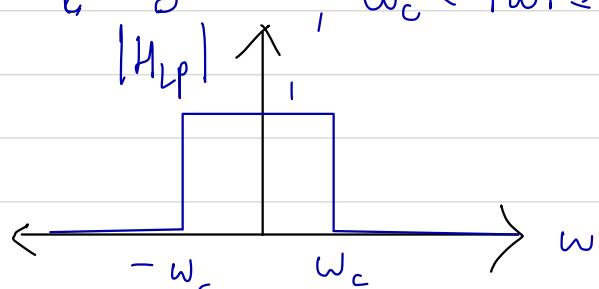
$$y(n) = A e^{j\omega n} \cdot e^{-j\omega D}$$

$$\Rightarrow y(n) = A e^{j\omega(n-D)}$$

Q) Given IR of ideal linear phase LPF (DT)
Find linear phase TF.

Ans

$$H_{LP}(e^{j\omega}) = \begin{cases} e^{-j\omega n_0}, & |\omega| \leq \omega_c \\ 0, & \omega_c \leq |\omega| \leq \pi \end{cases}$$



$$h_{LP}(n) = \frac{1}{2\pi} \int_{-\omega_c}^{\omega_c} e^{-j\omega n_0} e^{j\omega n} d\omega$$

$$= \frac{1}{2\pi} \int_{-\omega_c}^{\omega_c} e^{j\omega(n-n_0)} d\omega$$

$$h_{LP}(n) = \frac{1}{2\pi} \left[\frac{e^{j\omega(n-n_0)}}{j(n-n_0)} \right] \Big|_{-\omega_c}^{\omega_c}$$

$$= \frac{\sin \omega_c(n-n_0)}{\pi(n-n_0)} \quad -\infty < n < \infty \Rightarrow IIR$$

if $n_0 = N/2$

$$h_{LP}(n) = \frac{\sin \omega_c(n-N/2)}{\pi(n-N/2)} \quad 0 \leq n \leq N$$

\Rightarrow FIR filter of length $N+1$

$$H_{LP}(\omega) = \sum_{n=0}^N h_{LP}(n) e^{-j\omega n} = e^{-j\omega N/2} H_{LP}^U(\omega)$$

$H_{LP}^U(\omega) =$ zero phase TF.

Types of linear phase FIR filter

$h(n)$ = real valued.

N samples : $n = 0, 1, 2, \dots, N-1$

length of $h(n) = N+1$ for $0 \leq n \leq N$

$$H(z) = \sum_{n=0}^N h(n) z^{-n}$$

$$H(e^{j\omega}) = \sum_{n=0}^N h(n) e^{-j\omega n}$$

Mathematically, $H(e^{j\omega}) = e^{j(c\omega + \beta)} H^u(\omega)$

$$|H^u(e^{j\omega})| = |H^u(\omega)|$$

Zero phase response
(only magnitude)

zero phase TF $H^u(\omega)$ can be even or odd.

$$H^u(-\omega) = H^u(\omega) \rightarrow \text{even}$$

$$H^u(-\omega) = -H^u(\omega) \rightarrow \text{odd}$$

$$\rightarrow H^*(e^{-j\omega}) = \sum_{n=0}^N h(n) e^{-j\omega n} = H(e^{j\omega}) \rightarrow ①$$

$$\rightarrow H(e^{j\omega}) = e^{j(c\omega + \beta)} H^u(\omega) \rightarrow ②a$$

$$H(e^{j\omega}) = e^{jc\omega} \cdot e^{j\omega\beta} H^u(\omega) \rightarrow ②b$$

$$\rightarrow H^u(\omega) = e^{-j(c\omega + \beta)} H(e^{j\omega}) \rightarrow ③$$

if $H^u(\omega)$ is even function

$$H^u(-\omega) = e^{-j(c(-\omega) + \beta)} H(e^{-j\omega}) \rightarrow ④$$

$$H^*(e^{-j\omega}) = e^{-j(c(-\omega) + \beta)} \cdot H^u(-\omega)$$

$$\therefore H^*(e^{-j\omega}) = e^{j\omega c} e^{-j\beta} H^U(-\omega) \rightarrow (5)$$

case study 1: $H^U(\omega)$ is even function
 $H^U(\omega) = H^U(-\omega)$

Compare equation 5 & 2b
 $e^{j\beta} = e^{-j\beta} \rightarrow (6)$

True for $\beta = 0, \pm \pi$

$$H^U(\omega) = e^{j\omega(\pm 1)} H^U(\omega)$$

$$H^U(\omega) = \pm e^{-j\omega c} \sum_{n=0}^N h(n) e^{-j\omega n}$$

$$H^U(\omega) = \pm \sum_{n=0}^N h(n) e^{-j(c+n)\omega} \rightarrow (7)$$

Put $\omega = -\omega$ in equation 7 & put $l = n$
 $H^U(-\omega) = \pm \sum_{l=0}^N h(l) e^{j\omega(c+l)} \rightarrow (8)$

Now put $l = N-n$ & $c = -N/2$

$$H^U(-\omega) = \pm \sum_{n=0}^N h(N-n) e^{j\omega(-N/2 + N-n)}$$

$$= \pm \sum_{n=0}^N h(N-n) e^{-j\omega(n-N/2)} \rightarrow (9)$$

From 7 & 9,

$$H^U(-\omega) = H^U(\omega) \Rightarrow h(n) = h(N-n)$$

case 2: $H^U(\omega)$ is odd function
if $H^U(-\omega) = -H^U(\omega)$

$$H^U(\omega) = e^{-j\omega c} e^{-j\beta} H(e^{j\omega})$$

$$H^U(-\omega) = e^{j\omega c} e^{-j\beta} H(e^{-j\omega})$$

For odd $e^{j\beta} = -e^{-j\beta}$ if $\beta = \pm \pi/2$

$$H(e^{j\omega}) = e^{j\omega c} \sum_j H^U(\omega)$$

$$\begin{aligned} H^U(\omega) &= -j e^{-j\omega c} \sum_{n=0}^N h(n) e^{-j\omega n} \\ &= -j \sum_{n=0}^N h(n) e^{-j\omega(c+n)} \rightarrow \textcircled{10} \end{aligned}$$

$$H^U(-\omega) = -j \sum_{l=0}^N h(l) e^{j\omega(c+l)} \rightarrow \textcircled{11} \quad (\text{Put } l=n)$$

$$\text{Put } l = N-n \quad \epsilon_1 \quad c = -N/2$$

$$\begin{aligned} H^U(-\omega) &= -j \sum_{n=0}^N h(N-n) e^{+j\omega(N-n-N/2)} \\ &= j \sum_{n=0}^N [-h(N-n)] e^{-j\omega(n-N/2)} \rightarrow \textcircled{12} \end{aligned}$$

∴ From $\textcircled{10}$ & $\textcircled{12}$,

$$H^U(-\omega) = -H^U(\omega) \Rightarrow h(n) = -h(N-n)$$

4 types of filter

i) $H^U(\omega)$ & N both are even

ii) $H^U(\omega)$ & N both are odd

iii) $H^U(\omega)$ is even & N is odd

iv) $H^U(\omega)$ is odd & N is even

• If $H^U(\omega)$ is even, $h(n)$ is symmetric
as $h(n) = h(N-n)$

• If $H^U(\omega)$ is odd, $h(n)$ is anti-symmetric
as $h(n) = -h(N-n)$

Digital filter structure

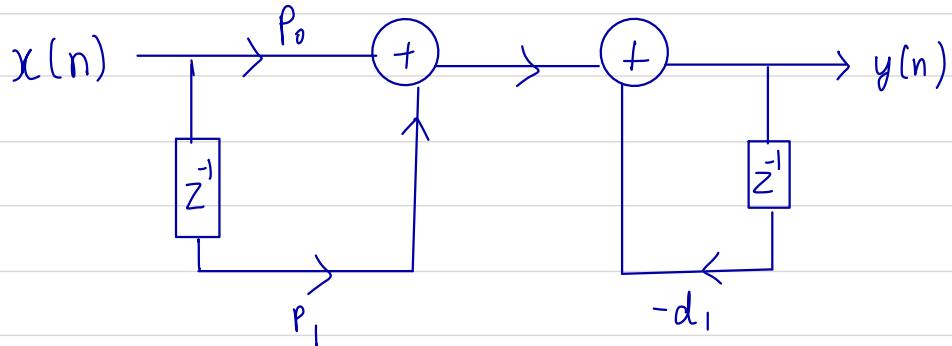
$$y(n) = h(n) * x(n)$$

$$= \sum_{k=-\infty}^{\infty} h(k) \cdot x(n-k)$$

Difference equation:

$$y(n) = - \sum_{k=1}^{N} d_k y(n-k) + \sum_{k=0}^{M} p_k x(n-k)$$

1st order IIR: if $N=1 \quad \& \quad M=1$

$$y(n) = -d_1 y(n-1) + p_0 x(n) + p_1 x(n-1)$$


→ If the number of delay units is greater than the order of system, it is known as Non canonical structure.

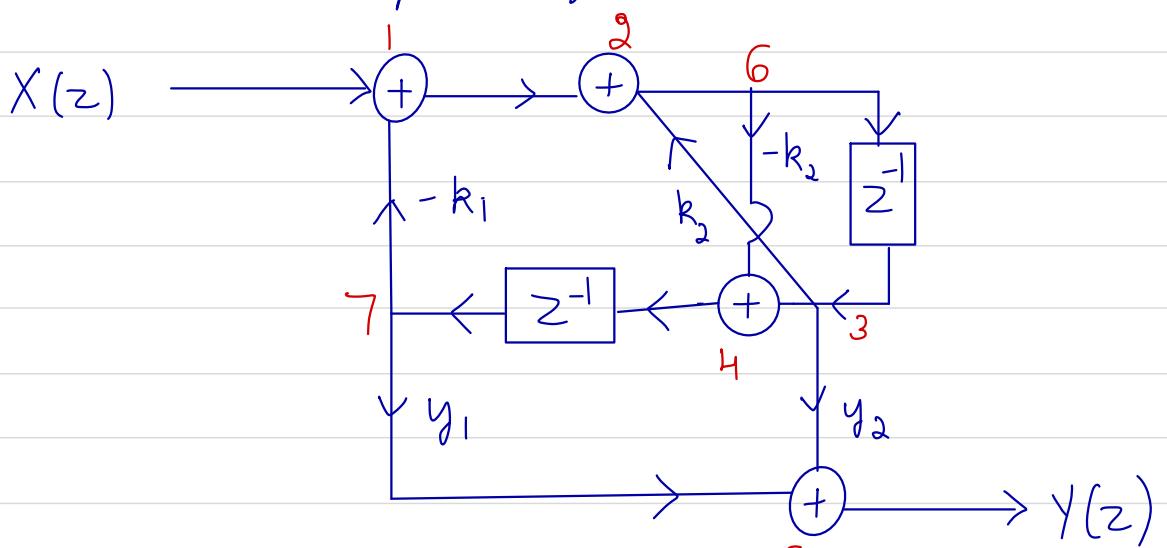
→ If the number of delay units is equal to the order of system, it is known as canonical structure.

Equivalent structure & Transpose operation

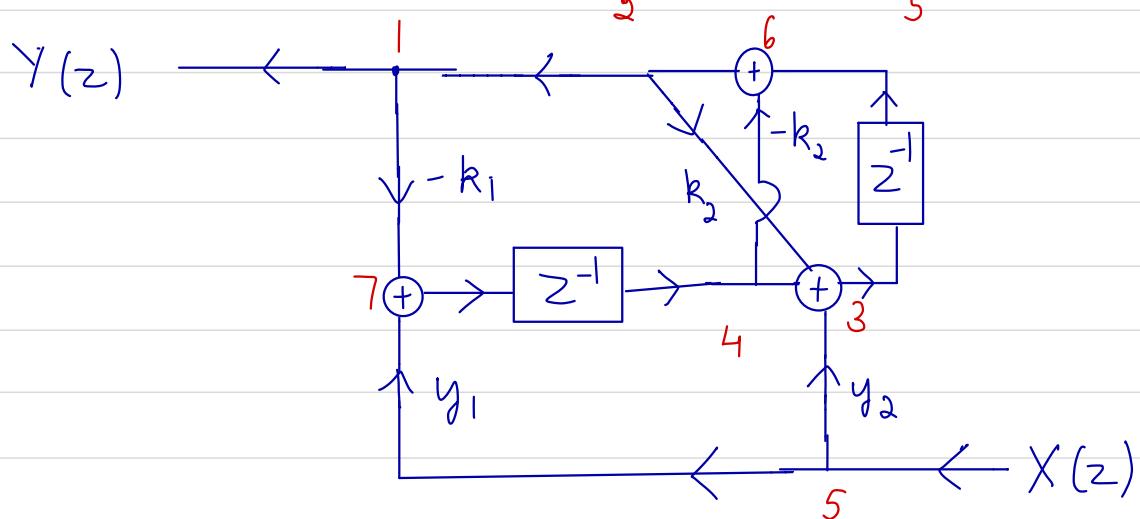
Transpose: is Replace adder by take off point and vice versa

- ii) Reverse the direction of arrows
- iii) change the port: $x(n) \leftrightarrow y(n)$

Eg 1) Find the transpose of:



Ans



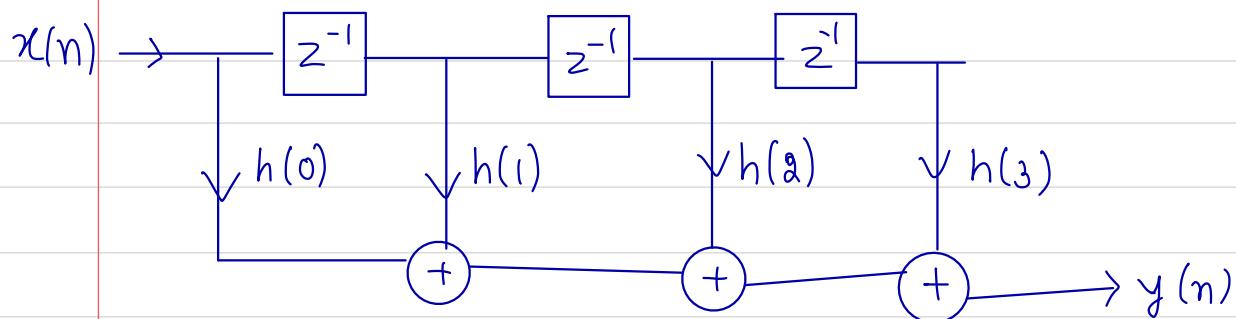
This is the transpose of system

FIR filter structure

i> Direct \rightarrow order N , $(N+1) \rightarrow$ filter coefficient
 $h(0) \dots h(N)$

Eg: $N=3$

$$y(n) = h(0)x(n) + h(1)x(n-1) + h(2)x(n-2) + h(3)x(n-3)$$



Taking transpose and inverting

Adder $\rightarrow N$

Multiplier $\rightarrow N+1$ delay = order

Suppose we had,

$$y(n) = h(0)x(n) + h_1x(n-1) + h_2x(n-2) + h_3x(n-3) + \alpha_1y(n-1) + \alpha_2y(n-2) + \alpha_3y(n-3)$$

if one of $\alpha_i \neq 0$ then feedback exists & it is IIR filter

3> Spiral form; (FIR) \rightarrow order N

Taking a higher N ,

$$N = \text{even} \Rightarrow k = \frac{N}{2}$$

$$N = \text{odd} \Rightarrow k = \frac{N+1}{2} \quad \text{with } \beta_{2i} = 0$$

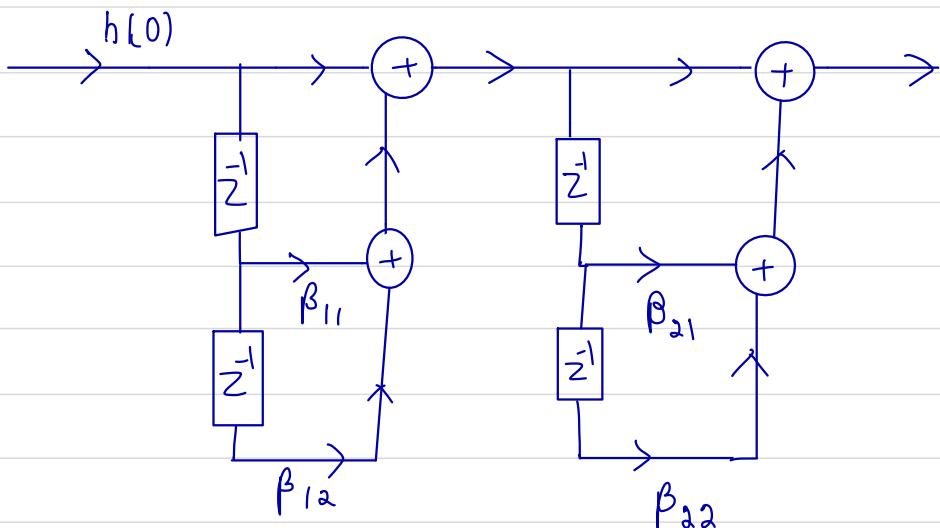
TF: factored

$$H(z) = \sum_{k=0}^N h(k) z^{-k}$$

$$= h(0) \prod_{i=1}^k (1 + \beta_{1i} z^{-1} + \beta_{2i} z^{-2})$$

$$\text{if } N = 4, \quad k = 2$$

$$H(z) = h(0) \prod_{i=1}^2 (1 + \beta_{1i} z^{-1} + \beta_{2i} z^{-2})$$



3> Polyphase realization: FIR of order $N=8$

$$H(z) = \sum_{k=0}^8 h(k) z^{-k}$$

$$= h(0) + h(1)z^{-1} + \dots + h(8)z^{-8}$$

$$= h(0) + h(2)z^{-2} + h(4)z^{-4} + h(6)z^{-6} + h(8)z^{-8}$$

$$+ z^{-1} [h(1) + h(3)z^{-2} + h(5)z^{-4} + h(7)z^{-6}]$$

$\rightarrow \textcircled{1}$

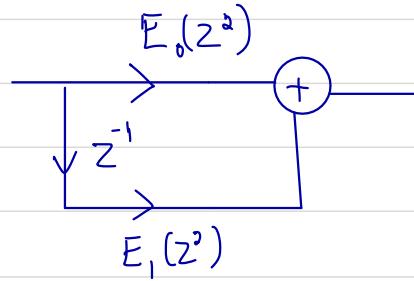
and level decomposition:

$$\text{let } E_0(z) = h(0) + h(2)z^{-1} + h(4)z^{-2} + h(6)z^{-3} + h(8)z^{-4}$$

$$E_1(z) = h(1) + h(3)z^{-1} + h(5)z^{-2} + h(7)z^{-3}$$

$$H(z) = f[E_0(z) \& E_1(z)]$$

$$\therefore H(z) = E_0(z^2) + z^{-1} E_1(z^2)$$



3rd level decomposition:

$$E_0(z) = h(0) + h(3)z^{-1} + h(6)z^{-2}$$

$$E_1(z) = h(1) + h(4)z^{-1} + h(7)z^{-2}$$

$$E_2(z) = h(2) + h(5)z^{-1} + h(8)z^{-2}$$

$$\text{then } H(z) = E_0(z^3) + z^{-1} E_1(z^3) + z^{-2} E_2(z^3)$$

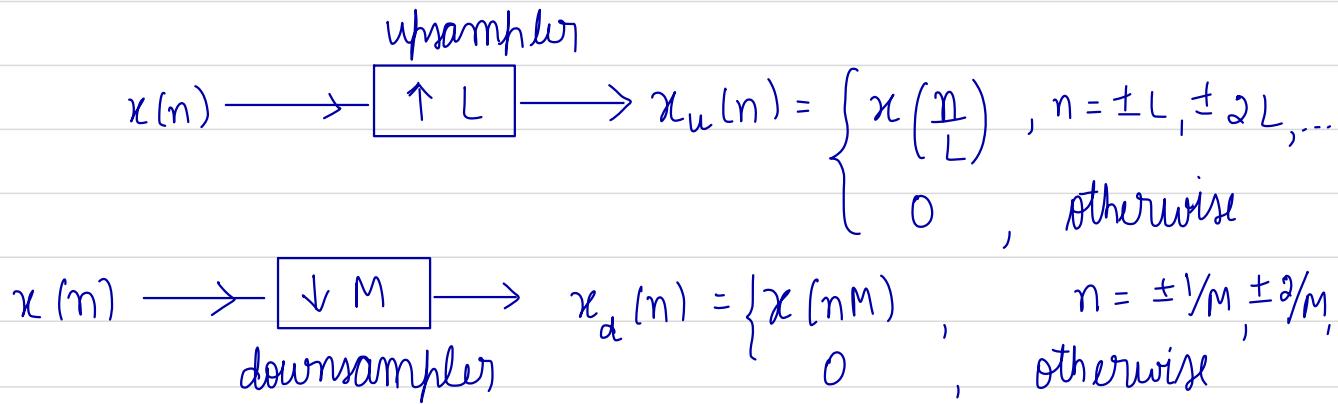
- Now consider a generic FIR filter of order N size $S = N+1$

$$\text{then } H(z) = \sum_{m=0}^{L-1} z^{-m} E_m(z^L)$$

$$\text{and } E_m(z) = \sum_{n=0}^{\lfloor \frac{N+1}{L} \rfloor} h(Ln+m) z^{-n} \quad 0 \leq m \leq L-1$$

where $\lfloor x \rfloor$ is floor function

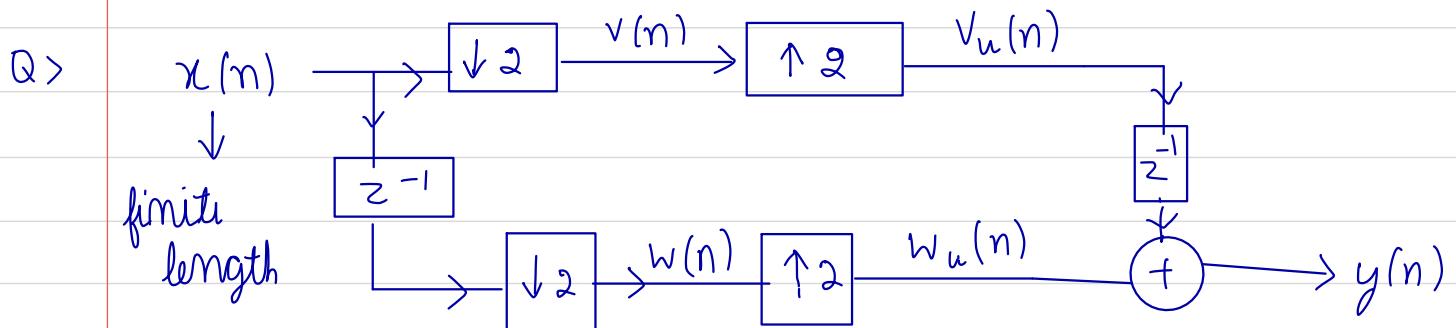
Multirate system



$$f_{s_i} = \frac{1}{T}$$

(sampling frequency)

for upsampler for downsampler	$f_{s_o} = L f_{s_i} = \frac{L}{T}$ $f_{s_o} = \frac{f_{s_i}}{M} = \frac{1}{MT}$
----------------------------------	---



At n	0	1	2	3	4	5	6	7	8
$x(n)$	$x(0)$	$x(1)$	$x(2)$	$x(3)$	$x(4)$	$x(5)$	$x(6)$	$x(7)$	$x(8)$
$v(n)$	$x(0)$	$x(2)$	$x(4)$	- - -	- - -	- - -	- - -	- - -	$x(16)$
$w(n)$	$x(-1)$	$x(1)$	$x(3)$	- - -	- - -	- - -	- - -	- - -	$x(15)$
$v_u(n)$	$x(0)$	0	$x(2)$	0	$x(4)$	- - -	- - -	- - -	$x(8)$
$w_u(n)$	0	$x(1)$	0	$x(3)$	0	$x(7)$	0
$y(n) = w_u(n) + v_u(n-1)$									
$\therefore y(n)$	$x(-1)$	$x(0)$	$x(1)$	- - -	- - -	- - -	- - -	- - -	$x(7)$

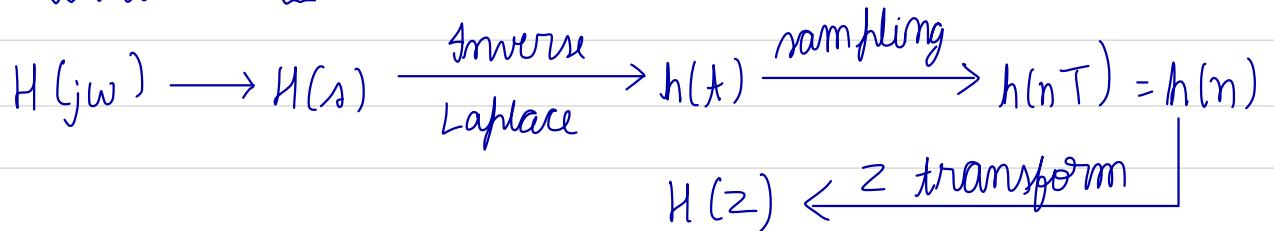
IIR filter

Based on analog filter design techniques:

I: Impulse invariant

II: Bilinear transformation

Digital LPF:



I Impulse invariant: $h(nT) \rightarrow h(n)$

II Bilinear transformation:

S plane \longleftrightarrow Z -plane

$$S = \frac{2}{T} \frac{z-1}{z+1}$$

or

$$Z = \frac{1 + S^T/2}{1 - S^T/2}$$

$$\text{let } z = \pi^{-1} e^{j\Omega}$$

$$\text{then } S = \frac{2}{T} \frac{1 - \pi e^{-j\Omega}}{1 + \pi e^{-j\Omega}} \times \left(\frac{1 + \pi e^{-j\Omega}}{1 + \pi e^{-j\Omega}} \right)$$

$$S = \frac{2}{T} \left[\frac{1 - \pi^2 + j(2\pi \sin \Omega)}{1 + \pi^2 + 2\pi \cos \Omega} \right]$$

$$\Rightarrow S = \frac{2}{T} \left[\frac{1 - \pi^2}{1 + \pi^2 + 2\pi \cos \Omega} + j \frac{2\pi \sin \Omega}{1 + \pi^2 + 2\pi \cos \Omega} \right]$$

$$S = \sigma + j\omega$$

$$\text{if } \pi < 1 \Rightarrow \sigma > 0$$

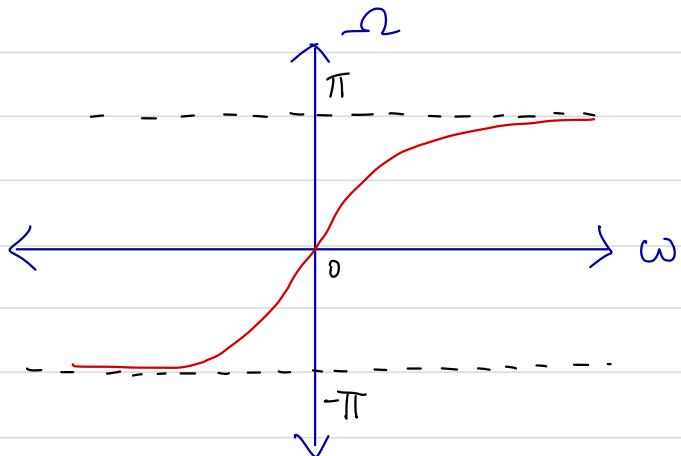
$$\text{if } \eta < 1 \Rightarrow \sigma < 0$$

$$\text{if } \eta = 1 \Rightarrow \sigma = 0$$

$$\text{if } \omega = \frac{\omega_0}{T} \tan \frac{\Omega}{2}$$

$$\therefore \Omega = \frac{1}{2} \tan^{-1} \left(\frac{\omega T}{2} \right) \quad \text{for } \eta = 1$$

For $\eta = 1$



Q) Butterworth digital filter should be designed using bilinear transformation ($T = 2$). Specifications: Pass band (Permissible attenuation 2 dB , 0.2π) Stop band (Attenuation more than 10 dB , frequency : $0.4\pi \leq \Omega \leq \pi$)

Given : $\Omega_p = 0.2\pi$

$$\Rightarrow \omega_p = \frac{1}{2} \tan \left(\frac{0.2\pi}{2} \right) = 0.3249,$$

$$\Omega_s = 0.4\pi \Rightarrow \omega_s = \tan \left(\frac{0.4\pi}{2} \right) = 0.7265$$

$$|H(j\omega)|^2 = \frac{1}{1 + \left(\frac{\omega}{\omega_c} \right)^{2N}} \quad \text{for Butterworth filter}$$

Taking $\omega_c = 1$ (since it is not given)

$$\text{Attenuation : } | -2 \text{ dB} |^2 = \frac{1}{1 + \omega^{2N}} \quad \text{at } \omega = \omega_p$$

$$\Rightarrow N = 1.695 \approx 2$$

$$\text{Now } |z|^2 = \frac{1}{1 + \left(\frac{\omega_p}{\omega_c}\right)^2 z^2}$$

$$\Rightarrow \omega_c = 0.4195$$

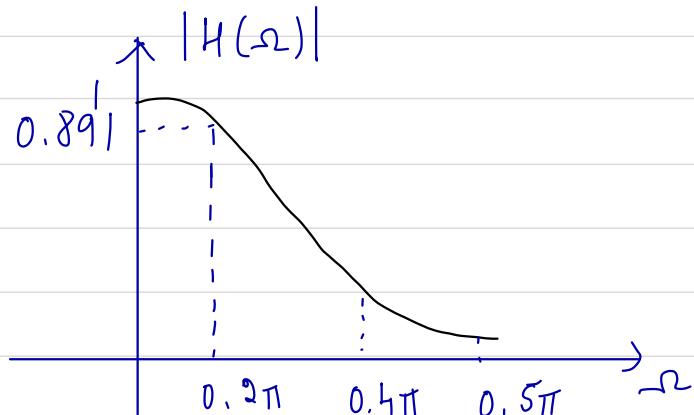
$$H(s) = \frac{1}{\left(\frac{s}{\omega_c}\right)^2 + \sqrt{2} \frac{s}{\omega_c} + 1}$$

$$H(s) = \frac{0.176}{s^2 + 0.5935s + 0.176}$$

$$H(z) = \frac{0.176}{\left(\frac{z-1}{z+1}\right)^2 + 0.5935 \left(\frac{z-1}{z+1}\right) + 0.176}$$

$$\therefore H(z) = \frac{0.135(z+1)^2}{z^2 - 2.174z + 1.716}$$

$$\text{Put } z = e^{j\Omega}$$



FIR filter using window

$$h_{ep}(n) = \frac{\sin[\omega_c(n - N/2)]}{\pi(n - N/2)} \quad -\infty < n < \infty$$

1) Rectangular window

$$\hat{h}_{ep}(n) = h_{ep}(n) \cdot w_R(n)$$

$$\text{where } w_R(n) = \begin{cases} 1 & 0 \leq n \leq N-1 \\ 0 & \text{otherwise} \end{cases}$$

2) Hamming window:

$$w_{\text{hamming}}(n) = \begin{cases} 0.54 - 0.46 \cos\left(\frac{2\pi n}{N-1}\right) & 0 \leq n \leq N-1 \\ 0 & \text{otherwise} \end{cases}$$

3) Blackman window

$$w_{BM}(n) = \begin{cases} 0.42 - 0.5 \cos\left(\frac{2\pi n}{N-1}\right) + 0.08 \cos\left(\frac{4\pi n}{N-1}\right) & \text{for } 0 \leq n \leq N-1 \\ 0 & \text{otherwise} \end{cases}$$