University of Wrocław: Algorithms for Big Data (Fall'19) 07/10/2019

Lecturer: Przemysław Uznański Lecture 1: Approximate Counting, Distinct Elements

# 1 Approximate counting

The problem is to maintain a counter that supports following operations:

reset(), 
$$[n \leftarrow 0]$$
  
inc(),  $[n \leftarrow n + 1]$   
query(), [output n]

Simple lower bound of log(n) bits for exact (information-theoretic lower bound).

**Goal:** algorithm that queried outputs n' such that  $\mathbf{Pr}(|n-n'| > \varepsilon n) < \delta$ .

# 1.1 Morris' algorithm [Sr.78]

**Local state:** X [int], represents  $n \sim 2^X$ . The crucial part of algorithm is to design how we increase X.

**Inc:**  $X \leftarrow X + 1$  with some small probability  $(\sim 2^{-X})$ , with intuition being that the ppb of n being exactly  $2^{X+1} - 1$  is  $2^{-X}$ .

Let us analyze increment probability =  $2^{-X}$ . Let  $X_n$  be random variable denoting state of algorithm after n increases.

Theorem 1.

$$\mathbf{E}[2^{X_0}] = 2^{X_0} = 1 \tag{1}$$

$$\mathbf{E}[2^{X_n}] = n + 1 \ by \ induction \tag{2}$$

Proof.

$$\mathbf{E}2^{X_{n+1}} = \sum_{j=0}^{\infty} \mathbf{Pr} \left( X_n = j \right) \cdot \mathbf{E} \left( 2^{X_{n+1}} | X_n = j \right)$$

$$= \sum_{j=0}^{\infty} \mathbf{Pr} \left( X_n = j \right) \cdot \left( 2^j \left( 1 - \frac{1}{2^j} \right) + \frac{1}{2^j} \cdot 2^{j+1} \right)$$

$$= \sum_{j=0}^{\infty} \mathbf{Pr} \left( X_n = j \right) 2^j + \sum_j \mathbf{Pr} \left( X_n = j \right)$$

$$= \mathbf{E}2^{X_n} + 1$$

$$= (n+1) + 1$$

Morris algorithm output:  $Z = 2^{X_n} - 1 \leftarrow$ , which is an unbiased estimator of n (that is  $\mathbf{E}[Z] = n$ ).

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### 1.1.1 Analysis of variance to extract guarantees:

**Theorem 2.** We show inductively that  $\mathbf{E}[2^{2X_n}] = 3/2n^2 + 3/2n + 1$ .

Proof. see exercise  $\Box$ 

Since

$$\begin{aligned} \mathbf{Var}[Z] &= \mathbf{Var}[2^{X_n}] \\ &= \mathbf{E}[2^{2X_n}] - (\mathbf{E}[2^{X_n}])^2 \\ &= \frac{3}{2}n^2 + 3/2n + 1 - (n+1)^2 \\ &= \frac{1}{2}n^2 - \frac{1}{2}n, \end{aligned}$$

by Chebyshev's inequality  $\Pr(|Z - n| > \varepsilon n) \le 1/(2\varepsilon^2)$ .

This only gives failure probability  $\delta < \frac{1}{2}$  for  $\varepsilon > 1$ , which is not very informative: (large) constant approximation with constant probability. But that was to be expected: our algorithm only outputs powers of two, so it cannot do much better job.

#### 1.2 Morris+

Repeat k times independently, take average of estimations. Since variance is additive:  $\mathbf{Var}(Z') = \frac{1}{k^2}(\mathbf{Var}(Z_1) + \mathbf{Var}(Z_2) + \cdots + \mathbf{Var}(Z_k)) = 1/k\mathbf{Var}(Z)$  so number of iterations necessary becomes:  $k = \mathcal{O}(\frac{1}{\varepsilon^2 \delta})$  (ok for 9/10 ppb of correctness, bad for whp correctness).

#### 1.3 Morris++

Run t copies of Morris+ algorithm, each with  $\delta = \frac{1}{3}$  and take median of estimations as a final estimation. Each estimation is ok with probability  $\geq \frac{2}{3}$ , so for the median to fail at least  $\frac{1}{6}$  fraction of estimations need to fail (all too large or all too small) Chernoff bound gives us:

$$\mathbf{Pr}\left(\sum_{i=1}^{t} Y_i \le \frac{t}{2}\right) \le \mathbf{Pr}\left(\left|\sum_{i=1}^{t} Y_i - \mathbf{E}\sum_{i=1}^{t} Y_i\right| \ge \frac{t}{6}\right) \le 2e^{-t/3} < \delta \tag{3}$$

for  $t = \Theta(\lg(1/\delta))$ . Final **bit** complexity  $\mathcal{O}(\log\log(n/(\varepsilon\delta))\frac{1}{\varepsilon^2}\log(\frac{1}{\delta}))$ .

**Lower bound:**  $\Omega(\log \log_{1+\varepsilon} n) = \Omega(\log(1/\varepsilon) + \log \log n)$  (for  $\delta = 0$ , its trickier to prove lowerbound involving  $\delta$ )

## 2 Distinct elements

**Input:** Stream of values  $i_1, i_2, \ldots, i_m$  from [n] query()  $\leftarrow$  number of distinct elements

**Trivial solution:** remember the stream, bitvector

# 2.1 Flajolet Martin [FM85]

Pick a hash function  $h:[n] \to [0,1]$  (for a moment let us assume ideal real numbers, and perfectly random hash function).

- 1. initially Z=1
- 2. input  $X: Z = \min(Z, h(X))$
- 3. estimator: Y = 1/Z 1

## Observation 3. Repeats do not affect Z.

If t is the number of distinct elements, then  $Z = \min(r_1, r_2, \dots, r_t)$  where  $r_i$  are all independent and from [0, 1].

#### Lemma 4.

$$\mathbf{E}[Z] = \frac{1}{t+1} \tag{4}$$

*Proof.* Pick fresh A at random from [0,1]. By symmetry,

$$\mathbf{E}[Z] = \mathbf{Pr}[A < Z] = \mathbf{Pr}[A \text{ is minimal among } A, r_1, \dots, r_t] = \frac{1}{(t+1)}.$$

#### Lemma 5.

$$\mathbf{E}[Z^2] \le \frac{2}{(t+1)(t+2)} \tag{5}$$

*Proof.* Pick fresh A, B at random from [0, 1]. By symmetry,  $\mathbf{E}[Z^2] = \mathbf{Pr}[A < Z \land B < Z] = \frac{2}{(t+1)(t+2)}$   $\Box$  Alternative proof.

$$\mathbf{E}\left[Z^{2}\right] = \int_{0}^{\infty} \mathbf{Pr}\left(Z^{2} > \lambda\right) d\lambda$$

$$= \int_{0}^{\infty} \mathbf{Pr}(Z > \sqrt{\lambda}) d\lambda$$

$$= \int_{0}^{1} (1 - \sqrt{\lambda})^{t} d\lambda$$

$$= 2 \int_{0}^{1} u^{t} (1 - u) du \quad [u = 1 - \sqrt{\lambda}] \quad = \frac{2}{(t+1)(t+2)}$$

$$\mathbf{Var}[Z] = \frac{2}{(t+1)(t+2)} - \frac{1}{(t+1)^2} = \frac{t}{(t+1)^2(t+2)} < (\mathbf{E}[Z])^2$$
 (6)

**Remark 6.** Applying Chebyshev's inequality  $\rightarrow$  results in a guarantee of a (large) constant approximation with lets say  $\frac{9}{10}$  probability.

**Issue:**  $\mathbf{E}[\frac{1}{Z}] \neq \frac{1}{\mathbf{E}[Z]}$ , but concentrating Z with  $1 + \varepsilon$  multiplicative error will give  $1 + \varepsilon$  multiplicative error for  $\frac{1}{Z}$ .

#### $2.2 \quad \text{FM} +$

To reach better approximation guarantee, we need to concentrate our output around expected value.

**Approach 1** copy approach from Morris' algorithm - "repeat k times and take average" to improve variance, set  $k = \mathcal{O}(\frac{1}{\varepsilon^2})$  for  $\frac{9}{10}$  probability of  $1 + \varepsilon$  approximation.

**Approach 2** replace "take minimum" with "take k-th smallest value" (to be analyzed  $\rightarrow$  exercise).

#### 2.3 FM++

To improve probability of success, repeat FM+ algorithm  $t = \mathcal{O}(\log \delta^{-1})$  times, and take median of answers. This boosts probability of success to  $1 - \delta$ .

Total memory complexity is

 $\mathcal{O}(\log n \frac{1}{\varepsilon^2} \log \delta^{-1})$  of words (each word is  $\log n$  bits).

#### 2.4 Issues

**Recall** "for a moment let us assume ideal real numbers".

We only care about relative order of hashes, and use actual value as an estimator. Using hash-functions of form  $h:[n] \to \{\frac{0}{M},\frac{1}{M},\dots,\frac{M-1}{M},\frac{M}{M}\}$  for some  $M=n^3$ , as it only introduces small relative error (whp each hash is  $\geq \frac{1}{n}$  thus relative error introduced is at most  $(1+\frac{1}{n})$ , and wlog  $\varepsilon > \frac{1}{n}$ ), and whp there are no collisions of hashes.

**Recall** "and perfectly random hash function".

Randomness vs. pseudorandomness  $\rightarrow$  c.f. exercises

# 3 Further reading

- hyperloglog algorithm, which very efficient in theory and practice, but has extremely nontrivial analysis [DF03] [HNH13]
- [Bla18] optimal  $\Theta(\log n + \frac{\log \delta^{-1}}{\varepsilon^2})$  bits.

## References

- [Bla18] Jaroslaw Blasiok. Optimal streaming and tracking distinct elements with high probability. In Proceedings of the Twenty-Ninth Annual ACM-SIAM Symposium on Discrete Algorithms, SODA 2018, New Orleans, LA, USA, January 7-10, 2018, pages 2432–2448, 2018.
- [DF03] Marianne Durand and Philippe Flajolet. Loglog counting of large cardinalities (extended abstract). In Algorithms ESA 2003, 11th Annual European Symposium, Budapest, Hungary, September 16-19, 2003, Proceedings, pages 605-617, 2003.

- [FM85] Philippe Flajolet and G. Nigel Martin. Probabilistic counting algorithms for data base applications. J. Comput. Syst. Sci., 31(2):182–209, 1985.
- [HNH13] Stefan Heule, Marc Nunkesser, and Alexander Hall. Hyperloglog in practice: algorithmic engineering of a state of the art cardinality estimation algorithm. In *Joint 2013 EDBT/ICDT Conferences*, EDBT '13 Proceedings, Genoa, Italy, March 18-22, 2013, pages 683-692, 2013.
- [Sr.78] Robert H. Morris Sr. Counting large numbers of events in small registers. Commun. ACM, 21(10):840–842, 1978.

# A Probability recap

**Definition 7.** 1. The empty set is an event,  $\emptyset \in \mathcal{F}$ 

- 2. Given a countable set of events  $A_1, A_2, \ldots$ , its union is also an event,  $\bigcup_{i \in \mathbf{N}} A_i \in \mathcal{F}$
- 3. if A is an event, then so is the complementary set  $A^c$

**Definition 8.** 1.  $\mathbf{Pr}(\emptyset) = 0, \mathbf{Pr}(\Omega) = 1$ 

2. if  $A_1, A_2, \ldots$  are mutually excluding events, then  $\mathbf{Pr}(\bigcup_{i=1}^{\infty} A_i) = \sum_{i=1}^{\infty} \mathbf{Pr}(A_i)$   $A \mathbf{Pr} : \mathcal{F} \mapsto [0, 1]$  satisfying these is called a probability. The triple  $(\Omega, \mathcal{F}, \mathbf{Pr})$  is called a probability space.

**Definition 9.** We define conditional probability as

$$\mathbf{Pr}(A|B) = \frac{\mathbf{Pr}(A \cap B)}{\mathbf{Pr}(B)}$$

**Theorem 10.** Let  $B_1, \ldots, B_n$  be a partition of  $\Omega$ , then

$$\mathbf{Pr}(A) = \sum_{i=1}^{n} \mathbf{Pr}(A|B_i) \mathbf{Pr}(B_i)$$
 (7)

**Definition 11.** Events A and B are called independent if

$$\mathbf{Pr}(A \cap B) = \mathbf{Pr}(A)\mathbf{Pr}(B). \tag{8}$$

When  $0 < \mathbf{Pr}(B) < 1$ , this is the same as

$$\mathbf{Pr}(A|B) = \mathbf{Pr}(A) = \mathbf{Pr}(A|B^c) \tag{9}$$

A family  $\{A_i : i \in I\}$  of events is called independent if

$$\mathbf{Pr}\left(\cap_{i\in J} A_i\right) = \prod_{i\in J} \mathbf{Pr}\left(A_i\right) \tag{10}$$

for any finite subset J of I.

**Definition 12.** A random variable is Informally: A quantity which is assigned by a random experiment. Formally: A mapping  $X : \Omega \to \mathbf{R}$ .

**Definition 13.** The cumulated distribution function(cdf) is:

$$F(x) = \mathbf{Pr}(X \le x) \tag{11}$$

If satisfies following properties:

1. 
$$\lim_{x \to -\infty} F(x) = 0$$
,  $\lim_{x \to +\infty} F(x) = 1$ 

2. 
$$x < y \Rightarrow F(x) \le F(y)$$

3. F is right-continuous, ie.  $F(x+h) \rightarrow F(x)$  as  $h \downarrow 0$ 

**Definition 14.** The mean of a stochastic variable is

$$\mathbf{E}X = \sum_{i \in \mathbb{Z}} i \mathbf{Pr}(X = i)$$

in the discrete case, and

$$\mathbf{E}X = \int_{-\infty}^{+\infty} f(x)dx$$

in the continuous case. In both cases we assume that the sum/integral exists absolutely. The variance of X is

$$\mathbf{Var}X = \mathbf{E}(X - \mathbf{E}x)^2 = \mathbf{E}X^2 - (\mathbf{E}X)^2$$

**Definition 15.** The conditional expectation is the mean in the conditional distribution

$$\mathbf{E}(Y|X=x) = \sum_{y} y f_{Y|X}(y|x) \tag{12}$$

It can be seen as a stochastic variable: Let  $\psi(x) = \mathbf{E}(Y|X=x)$ , then  $\psi(X)$  is the conditional expectation of Y given X

$$\psi(X) = \mathbf{E}(Y|X) \tag{13}$$

We have

$$\mathbf{E}(\mathbf{E}(Y|X)) = \mathbf{E}Y\tag{14}$$

**Definition 16.** Conditional variance Var(Y|X) is the variance in the conditional distribution.

$$\mathbf{Var}(Y|X=x) = \sum_{y} (y - \psi(x))^2 f_{Y|X}(y|x)$$
 (15)

This can also be written as

$$\mathbf{Var}(Y|X) = \mathbf{E}(Y^2|X) - (\mathbf{E}(Y|X))^2$$

and can be manipulated into

$$Var = EVar(Y|X) + VarE(Y|X)$$

which partitions the variance of Y.

**Theorem 17** (Markov's inequality). Let  $X \geq 0$  be a random variable. Then for any  $k \geq 1$ :

$$\mathbf{Pr}(X \ge k \cdot \mathbf{E}[X]) \le \frac{1}{k} \tag{16}$$

**Theorem 18** (Chebyshev's inequality). Let X be a random variable. For any k > 0:

$$\mathbf{Pr}(|X - \mathbf{E}[X]| \ge k \cdot \sqrt{\mathbf{Var}[X]}) \le \frac{1}{k^2}$$
(17)

**Theorem 19.** Hoeffding bound] Let  $X_1, X_2, ..., X_n \in \{0,1\}$  be fully independent ran-dom variables. Let  $X = \sum_i X_i$ . Then:

$$\mathbf{Pr}(|X - \mathbf{E}[X]| \ge t) \le 2\exp\left(-\frac{t^2}{n}\right) \tag{18}$$