

Bayesian Decision Theory

- Introduction
- Bayesian Decision Theory—Continuous Features
- Minimum-Error-Rate Classification
- Classifiers, Discriminant Functions and Decision Surfaces
- The Normal Density
- Discriminant Functions for the Normal Density
- Bayes Decision Theory – Discrete Features

Introduction

- The sea bass/salmon example
 - State of nature, prior
 - State of nature is a random variable
 - The catch of salmon and sea bass is equiprobable
 - $P(\omega_1) = P(\omega_2)$ (uniform priors)
 - $P(\omega_1) + P(\omega_2) = 1$ (exclusivity and exhaustivity)

- Decision rule with only the prior information
 - Decide ω_1 if $P(\omega_1) > P(\omega_2)$ otherwise decide ω_2
- Use of the class –conditional information
- $P(x | \omega_1)$ and $P(x | \omega_2)$ describe the difference in lightness between populations of sea and salmon

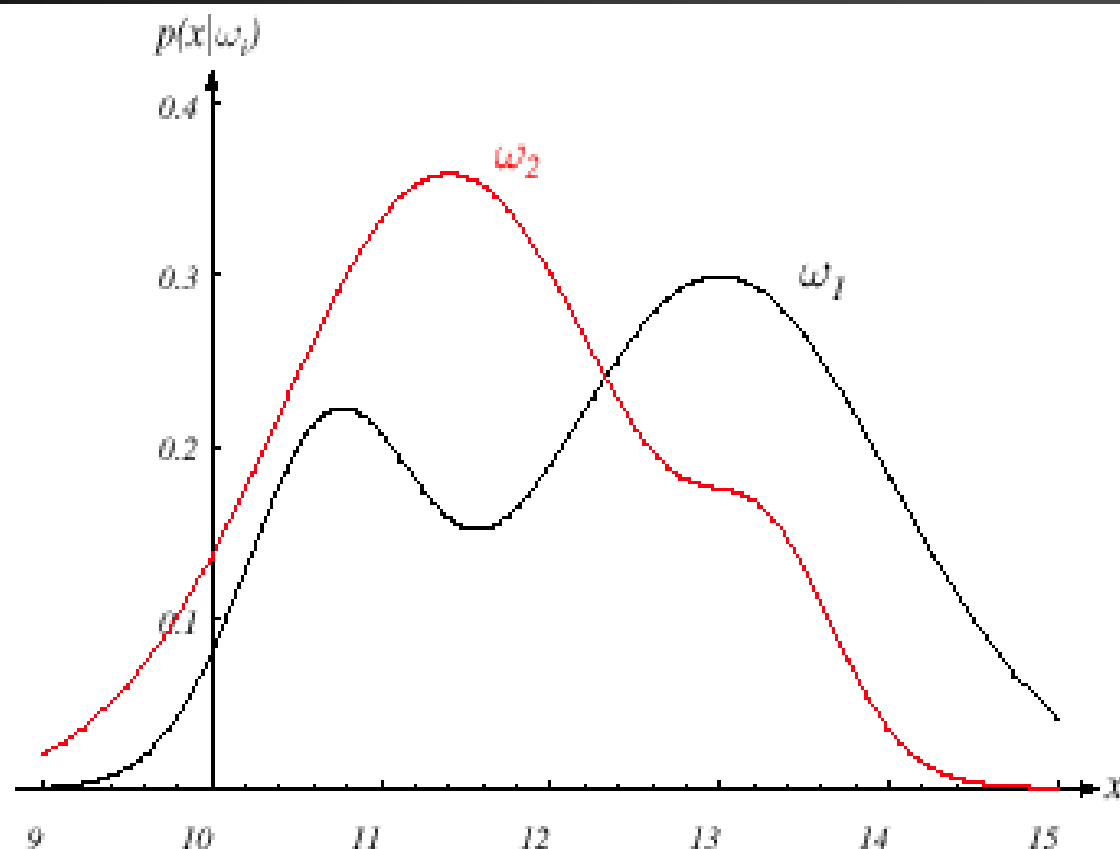


FIGURE 2.1. Hypothetical class-conditional probability density functions show the probability density of measuring a particular feature value x given the pattern is in category ω_i . If x represents the lightness of a fish, the two curves might describe the difference in lightness of populations of two types of fish. Density functions are normalized, and thus the area under each curve is 1.0. From: Richard O. Duda, Peter E. Hart, and David G. Stork, *Pattern Classification*. Copyright © 2001 by John Wiley & Sons, Inc.

- Posterior, likelihood, evidence
 - $P(\omega_j | x) = P(x | \omega_j) \cdot P(\omega_j) / P(x)$
 - Where in case of two categories

$$P(x) = \sum_{j=1}^{j=2} P(x | \omega_j) P(\omega_j)$$

- Posterior = (Likelihood. Prior) / Evidence

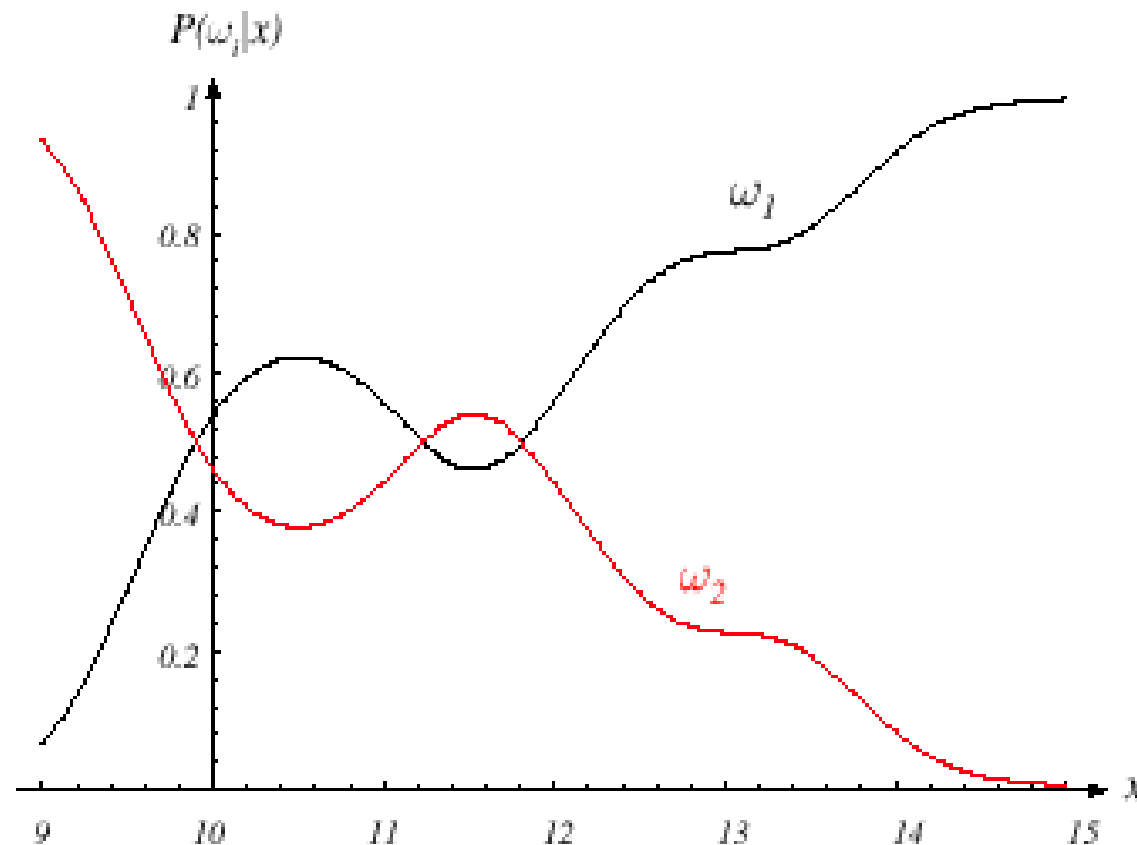


FIGURE 2.2. Posterior probabilities for the particular priors $P(\omega_1) = 2/3$ and $P(\omega_2) = 1/3$ for the class-conditional probability densities shown in Fig. 2.1. Thus in this case, given that a pattern is measured to have feature value $x = 14$, the probability it is in category ω_2 is roughly 0.08, and that it is in ω_1 is 0.92. At every x , the posteriors sum to 1.0. From: Richard O. Duda, Peter E. Hart, and David G. Stork, *Pattern Classification*. Copyright © 2001 by John Wiley & Sons, Inc.

- Decision given the posterior probabilities

X is an observation for which:

if $P(\omega_1 | x) > P(\omega_2 | x)$ \longrightarrow True state of nature = ω_1

if $P(\omega_1 | x) < P(\omega_2 | x)$ \longrightarrow True state of nature = ω_2

Therefore:

whenever we observe a particular x , the probability of error is :

$P(\text{error} | x) = P(\omega_1 | x)$ if we decide ω_2

$P(\text{error} | x) = P(\omega_2 | x)$ if we decide ω_1

- Minimizing the probability of error
- Decide ω_1 if $P(\omega_1 | \mathbf{x}) > P(\omega_2 | \mathbf{x})$;
otherwise decide ω_2

Therefore:

$$P(\text{error} | \mathbf{x}) = \min [P(\omega_1 | \mathbf{x}), P(\omega_2 | \mathbf{x})]$$

(Bayes decision)

- Two-category classification

α_1 : deciding ω_1

α_2 : deciding ω_2

$$\lambda_{ij} = \lambda(\alpha_i \mid \omega_j)$$

loss incurred for deciding ω_i when the true state of nature is ω_j

Conditional risk:

$$R(\alpha_1 \mid \mathbf{x}) = \lambda_{11}P(\omega_1 \mid \mathbf{x}) + \lambda_{12}P(\omega_2 \mid \mathbf{x})$$

$$R(\alpha_2 \mid \mathbf{x}) = \lambda_{21}P(\omega_1 \mid \mathbf{x}) + \lambda_{22}P(\omega_2 \mid \mathbf{x})$$

Our rule is the following:

if $R(\alpha_1 | \mathbf{x}) < R(\alpha_2 | \mathbf{x})$
 action α_1 : “decide ω_1 ” is taken

This results in the equivalent rule :
 decide ω_1 if:

$$(\lambda_{21} - \lambda_{11}) P(\mathbf{x} | \omega_1) P(\omega_1) > (\lambda_{12} - \lambda_{22}) P(\mathbf{x} | \omega_2) P(\omega_2)$$

and decide ω_2 otherwise

Likelihood ratio:

The preceding rule is equivalent to the following rule:

$$\text{if } \frac{P(x / \omega_1)}{P(x / \omega_2)} > \frac{\lambda_{12} - \lambda_{22}}{\lambda_{21} - \lambda_{11}} \cdot \frac{P(\omega_2)}{P(\omega_1)}$$

Then take action α_1 (decide ω_1)

Otherwise take action α_2 (decide ω_2)

Exercise

Select the optimal decision where:

$$= \{\omega_1, \omega_2\}$$

$$P(x | \omega_1) \quad \longrightarrow \quad N(2, 0.5) \text{ (Normal distribution)}$$

$$P(x | \omega_2) \quad \longrightarrow \quad N(1.5, 0.2)$$

$$P(\omega_1) = 2/3$$

$$P(\omega_2) = 1/3$$

$$\lambda = \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix}$$

Minimum-Error-Rate Classification

- Actions are decisions on classes
If action α_i is taken and the true state of nature is ω_j then:
the decision is correct if $i = j$ and in error if $i \neq j$
- Seek a decision rule that minimizes the *probability of error* which is the *error rate*

- Introduction of the zero-one loss function:

$$\lambda(\alpha_i, \omega_j) = \begin{cases} 0 & i = j \\ 1 & i \neq j \end{cases} \quad i, j = 1, \dots, c$$

Therefore, the conditional risk is:

$$\begin{aligned} R(\alpha_i | x) &= \sum_{j=1}^{j=c} \lambda(\alpha_i | \omega_j) P(\omega_j | x) \\ &= \sum_{j \neq i} P(\omega_j | x) = 1 - P(\omega_i | x) \end{aligned}$$

- Minimize the risk requires maximize $P(\omega_i | \mathbf{x})$
(since $R(\alpha_i | \mathbf{x}) = 1 - P(\omega_i | \mathbf{x})$)
- For Minimum error rate
 - Decide ω_i if $P(\omega_i | \mathbf{x}) > P(\omega_j | \mathbf{x}) \quad \forall j \neq i$

- Regions of decision and zero-one loss function, therefore:

$$\text{Let } \frac{\lambda_{12} - \lambda_{22}}{\lambda_{21} - \lambda_{11}} \cdot \frac{P(\omega_2)}{P(\omega_1)} = \theta_\lambda \text{ then decide } \omega_1 \text{ if : } \frac{P(x / \omega_1)}{P(x / \omega_2)} > \theta_\lambda$$

- If λ is the zero-one loss function which means:

$$\lambda = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$$

$$\text{then } \theta_\lambda = \frac{P(\omega_2)}{P(\omega_1)} = \theta_a$$

$$\text{if } \lambda = \begin{pmatrix} 0 & 2 \\ 1 & 0 \end{pmatrix} \text{ then } \theta_\lambda = \frac{2P(\omega_2)}{P(\omega_1)} = \theta_b$$

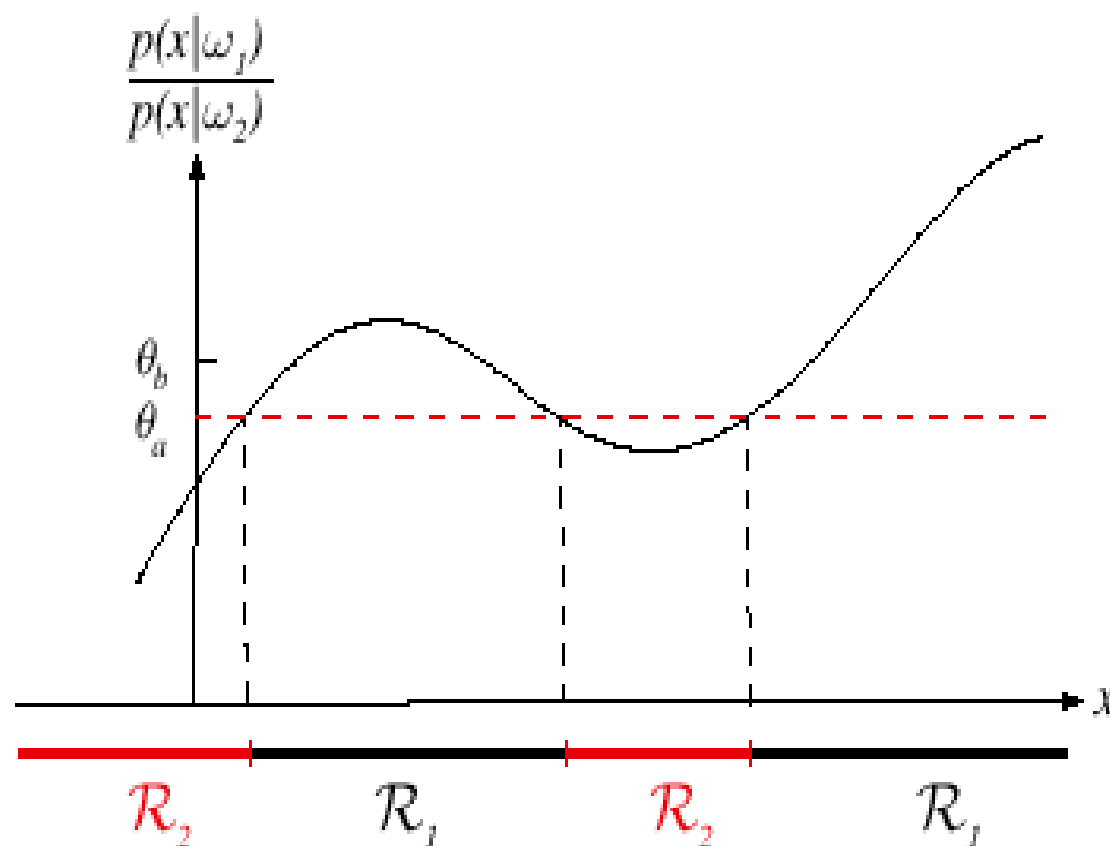


FIGURE 2.3. The likelihood ratio $p(x|\omega_1)/p(x|\omega_2)$ for the distributions shown in Fig. 2.1. If we employ a zero-one or classification loss, our decision boundaries are determined by the threshold θ_a . If our loss function penalizes miscategorizing ω_2 as ω_1 patterns more than the converse, we get the larger threshold θ_b , and hence \mathcal{R}_1 becomes smaller. From: Richard O. Duda, Peter E. Hart, and David G. Stork, *Pattern Classification*. Copyright © 2001 by John Wiley & Sons, Inc.

- 某医院确诊患者中疾病A和疾病B的概率分别为 $P(A)=0.7$ 和 $P(B)=0.3$ ，两种疾病发生都有症状x，其概率分别为 $P(x|A)=0.45$ 和 $P(x|B)=0.5$ ，同时两种疾病的误诊代价 $\lambda_{AB}=1$ 和 $\lambda_{BA}=2$ 。现有患者出现了症状x，请帮助医生做出疾病决策。