Appendices to the Book: Time Molecules

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These appendices are related to the book, <u>Time Molecules</u>. They live "outside" the book itself to give you the best of both worlds: a clearer, uninterrupted narrative in the core chapters, and a set of "living" resources you can revisit whenever you need greater depth or the very latest guidance. In this LLM-driven era of AI where streaming platforms evolve, best practices shift, and new algorithms emerge overnight, locking every detail into a printed page would risk obsolescence. By decoupling these technical deep dives, we can update them continuously—refreshing code snippets, adding new patterns, or linking to the newest vendor documentation—without disturbing the flow or structure of the book itself.

Each appendix drills into a specialized topic—whether it's the inner workings of Kafka versus Event Hubs, strategies for reordering late-arriving events, or the math behind one-pass variance estimation—that would otherwise interrupt the narrative momentum. Think of this section as your personal workshop: if you want only the high-level overview, stay with the main chapters; but when you need to roll up your sleeves and explore edge cases, configuration knobs, or code examples, the appendices are your go-to reference. They're indexed, versioned, and web-linked so you can always find the most current advice. Welcome to the living engine room of *Time Molecules*.

Appendix A - The Enterprise Intelligence Prompt

<u>Time Molecules</u> is a follow-up to my previous book, <u>Enterprise Intelligence</u> (available at <u>Technics</u> <u>Publications</u> and <u>Amazon</u>), so it helps to have a basic understanding of what that latter book is about. The following is a prompt I used during the writing of <u>Enterprise Intelligence</u> to prime ChatGPT for assistance—fact check, what is a better word, draw a picture, ttl to cql, etc. I found this serves as a good TL;DR, so here it is:

A.1 TL;DR of Enterprise Intelligence

The subject of my book, <u>Enterprise Intelligence</u>, is in the context of Business Intelligence (BI) structures added to an enterprise knowledge graph (EKG). The EKG consists of three major parts: A knowledge graph (KG) authored by subject matter experts (SME) to Semantic Web standards, a data catalog (DC) that holds metadata for all data sources in the enterprise, and two BI-derived structures – Insight Space Graph (ISG) and Tuple Correlation Web (TCW) – passively built from the normal BI query activity of BI analysts across the enterprise. It's for a book I'm writing where I claim businesses are like organisms, departments like organs, and the EKG is like the brain.

I chose to have BI as the spearhead for this EKG since BI data is highly-curated. Whatever data makes it into a BI database must be readily understood, of high analytical value, cleansed, and trustworthy. It is the data used for most business decisions.

The KG is like "System 1" (Kahneman), fast response time, more direct, more deterministic. It's a collection of domain-level ontologies, analogous to domain-level data products of data mesh, authored by SMEs. Authorship of this KG is now feasible thanks to the emergence of readily available and high-quality large-language models (ChatGPT 3.5 in Nov 2022). The LLMs have a symbiotic relationship with KGs (LLMs help to build KGs and KGs ground the LLMs in reality). Incorporating retrieval augmented generation (RAG) into this ecosystem further strengthens its capabilities. RAG allows for more sophisticated query scenarios by combining the generative abilities of LLMs with the structured, fact-based data from the EKG. This mirrors advanced cognitive functions, such as problem-solving and creative thinking.

The nexus of this EKG is the DC, an ontology of the data sources, databases/cubes, tables/views/dimensions, columns/attributes, and even column members (as necessary—since there could be billions of members). It sits between the KG and ISG/TCW. All items of the ISG and TCW are traceable to DC elements. Further, DC tables, columns, and members could be linked to entities and individuals in the KG, expanding the semantics of those DC elements.

The main idea of the ISG/TCW is to passively capture what dozens to thousands of BI analysts have seen (or could have seen) in visualizations rendered from their BI activity. Those salient points are captured

across what could be thousands to billions of queries consuming hundreds to tens of thousands of compute hours across dozens to hundreds of data sources. It charts the points of interest across what is an unbelievably expansive space of insights. The ISG/TCW is more like System 2.

The ISG consists of nodes representing queries that were rendered in a visualization (line graph, bar chart, scatter plot, pie chart, etc.) using a visualization tool, such as Tableau or PowerBI, requested by the actions of BI analysts using those tools. For each of those dataframes resulting from those queries, an array of simple functions wrings out things a human would notice from hose visualizations. For example, in a line graph, the user might recognize trend up, trend down, periodicity, steps, and spikes. Each of those insights is linked as properties of those query nodes. The columns and metrics of the query are linked to the appropriate DC nodes. Note that the data of the dataframe isn't stored in the EKG, just the metadata of the query and any insights. These insights are like the things we notice as we go about our day.

The TCW consists of nodes, each representing a tuple. For example, the price of oil in Beijing or the water consumption in San Diego. A tuple could be thought of as one row in a dataframe. The members represented in the tuples are associated to member nodes in the data catalog (the member nodes are, in turn, linked to the column node in the DC). The tuple nodes can also be connected to each other through Pearson Correlations or Conditional probabilities. These are calculated by comparing the tuples sliced by time series. These correlations are what we notice as patterns to what is related to what. We can construct chains of strong correlations.

With salient points captured in the ISG and strong correlations captured in the TCW from across dozens to thousands of diverse analysts across dozens of domains, we have a single integrated source of insights.

Appendix B - Comparing LLMs and Markov Models

LLMs and Markov models are two sides of the same sequential-modeling coin—one masters the art of language and context, the other masters the science of process and predictability. In modern AI systems, you'll often use Markov models to ground your predictions and LLMs to enrich them with human-readable insights.

B.1 Overview

Large Language Models (LLMs) and Markov models both handle sequences, but they answer different questions:

- **LLMs** learn a high-dimensional, fuzzy mapping from context to next token. They excel at making sense of unstructured text drawn from vast, contradictory sources.
- Markov models capture exact transition probabilities between defined states or events, computed deterministically from historical data. They excel at forecasting "what happens next" in well-structured processes.

This appendix explains why both have their place—and how they can feed into each other when you build AI applications around process data.

B.2 Foundational Differences

Dimension	LLMs	Markov Models
Training data	Unbounded text corpora, web crawl, books	Structured event logs or state sequences
Model form	Neural network with hundreds of billions of parameters	Transition matrix or higher-order chain
Inference style	Probabilistic sampling with temperature, beam search	Exact probability lookup and normalization
Determinism	Stochastic in sampling; outputs can vary	Fully deterministic given the transition matrix
Explainability	Low: "black box" attention patterns	High: explicit counts and probabilities
Fuzziness	Embraces ambiguity to mirror human language	Requires precise event definitions

B.3 Strengths & Limitations

LLMs

Strengths:

- Understand nuance, idioms, and rare contexts.
- Compose coherent prose, summarize, translate.
- Adapt via prompts, chain-of-thought, or RAG pipelines.

Compare the com

- Hallucinations: may assert false facts.
- Non-deterministic: hard to reproduce exact outputs.
- Opaque internals: explanations rely on probing attention or gradient methods.

Markov Models

o Strengths:

- Provide precise next-step probabilities based on observed frequencies.
- Deterministic and reproducible.
- Extremely lightweight to compute and update.

Limitations:

- Memoryless beyond defined order; can't capture long-range context without exploding state space.
- Require structured, well-labeled events.
- No notion of semantics or world knowledge—only what has been seen.

B.4 Complementary Roles in Al Workflows

1. Data Source for RAG and Reasoning

- Time Molecules Markov outputs (transition probabilities, sojourn times) can seed a vector store or knowledge graph.
- An LLM in a RAG loop retrieves the most relevant process fragments (e.g., "order→fulfill" statistics) to ground its reasoning in real data rather than hallucinated flows.

2. Predictive Hypotheses vs. Generative Exploration

- o Use Markov models to forecast the most likely next step quantitatively.
- Use LLMs to generate plausible narratives around why that step happens, suggest alternative scenarios, or propose actions when the data is sparse.

3. Chain-of-Thought with Structured Anchors

 Embed Markov-derived probabilities in your prompt ("Given a 92% chance of A→B within 5±2 minutes...") so the LLM's chain-of-thought remains tethered to ground truth rather than pure linguistic patterns.

B.5 Why Both Matter Today

• Fuzzy Language, Fuzzy World

Humans communicate with ambiguity; LLMs mirror that strength. But when you need operational precision—SLAs, workflows, process mining—you need the explicit trust of exact probabilities.

• Hybrid Agility

Relying solely on neural networks risks hallucination and drift; relying solely on Markov chains misses subtle, contextual signals in unstructured data. Together, they let you blend fuzzy reasoning with hard-number forecasts.

Appendix C - Key Performance Indicator Status

Details the integration of KPI status values into the EKG, showing how they link to data sources, strategy maps, and Markov models to analyze transitions and optimize processes.

Appendix D - Azure Event Hub vs. Apache Kafka

D.1 Introduction

Both Azure Event Hubs and Apache Kafka are high-throughput, distributed event-streaming platforms. They ingest large volumes of timestamped events, making them natural sources for the Time Molecules framework's Markov-model pipelines. This appendix compares the two, focusing on deployment models, scalability, ecosystem integration, and operational trade-offs.

D.2 Architecture & Deployment

Aspect	Azure Event Hubs	Apache Kafka
Deployment	Fully managed PaaS on Azure	Self-managed or managed (Confluent, Aiven, etc.) on any cloud or on-prem
Partitions	User-defined up to hundreds per hub	User-defined per topic; can scale into thousands
Storage	Retention up to 90 days by default; archive to Azure Storage	Retention by time or size; tiering via Kafka Tiered Storage or HDFS
Protocol	AMQP 1.0, HTTPS, Kafka protocol support (Event Hubs for Kafka)	Native TCP protocol; clients in multiple languages
Security	Azure AD integration, SAS tokens, VNet service endpoints	SSL/TLS, SASL, ACLs; integrate with LDAP/Kerberos

D.3 Scalability & Performance

• Azure Event Hubs

- Throughput units (standard or dedicated) automatically scale for ingest and egress.
- o Auto-inflation (preview) can adjust capacity under load.
- o Billing is per throughput unit and ingress/egress volume.

Apache Kafka

- Scale by adding brokers and partitions.
- o Balance of replication factor and partition count affects throughput.
- o Cost varies by self-hosting resources or managed-service fees.

D.4 Ecosystem Integration

• Azure Event Hubs

- Native integration with Azure Stream Analytics, Azure Functions, Azure Data Factory, and Synapse.
- "Event Hubs for Kafka" API compatibility lets existing Kafka clients write to Event Hubs.
- o Built-in capture to Azure Blob or Data Lake Storage for batch processing.

Apache Kafka

- Broad ecosystem: Kafka Streams, KSQL, Connect framework with 200+ connectors (JDBC, Hadoop, Elasticsearch, etc.).
- o Rich client libraries in Java, Python, Go, .NET, etc.
- o Managed services by Confluent, Aiven, Amazon MSK, Google Cloud Pub/Sub (Kafka API).

D.5 Operational Considerations

Factor	Azure Event Hubs	Apache Kafka
Management overhead	Minimal: Azure handles patching, scaling	High if self-managed; expertise needed for cluster tuning, Zookeeper/KRaft
Monitoring & tooling	Azure Monitor, Metrics Advisor, built-in diagnostics	Prometheus, Grafana, Confluent Control Center; on-prem tooling needed
Upgrades & patching	Automatic in PaaS	Manual planning and rollout
High availability	SLA-backed geo-replication options	Multi-cluster replication (MirrorMaker), Confluent Replicator

D.6 Feeding Time Molecules Pipelines

- Event ingestion: Both platforms deliver ordered, partitioned streams keyed by case or entity ID.
- Latency: Event Hubs SLAs target sub-second end-to-end; Kafka clusters can be tuned for low-tens-of-milliseconds.
- **Retention & replay**: Long retention windows allow Time Molecules to rebuild or reprocess historical Markov models.

• Integration:

 Use Azure Stream Analytics or Functions to window and watermark before writing to an intermediate store (e.g. Azure Blob, Cosmos DB). Use Kafka Connect to sink cleansed, time-ordered events into a data lake, SQL warehouse, or directly into a stream-processing engine (Flink, Spark).

D.7 When to Choose Which

- Azure Event Hubs if your organization is already on Azure, prefers fully managed services, and needs
 deep integration with the Azure analytics stack without the operational burden of broker
 management.
- Apache Kafka if you require cloud-agnostic deployment, rich connector ecosystem, custom streamprocessing frameworks, or want fine-grained control over cluster behavior and cost optimization across multiple environments.

D.8 Summary

Azure Event Hubs and Apache Kafka both serve as reliable sources of high-volume event data for the Time Molecules framework. Event Hubs excels in managed simplicity and Azure integration; Kafka shines when you need flexibility, a broad connector ecosystem, and cross-platform deployment. Your choice should align with existing infrastructure, operational expertise, and integration needs.

Appendix E - Markov Models vs. Markov Decision Processes

Markov Models (MMs) and Markov Decision Processes (MDPs) are both mathematical frameworks utilized for modeling stochastic systems, yet they serve distinct purposes.

- Markov Models primarily focus on probabilistic transitions within a sequence of states. They
 are widely used for process analysis and prediction, emphasizing the likelihood of
 transitioning from one state to another based on past occurrences. These models are
 effective in applications such as natural language processing and process optimization,
 where understanding sequential dependencies is key.
- Markov Decision Processes extend the concept of Markov Models by introducing the
 element of decision-making under uncertainty. MDPs are designed to optimize actions
 taken within a stochastic system to achieve the best possible outcome over time. They are
 instrumental in applications like reinforcement learning, where the aim is to determine
 optimal strategies based on rewards and penalties associated with different actions and
 states.

E.1 Key Differences

- Focus: Markov Models analyze and predict transitions, while Markov Decision Processes optimize decisions within those transitions.
- Inclusion of Actions: MDPs incorporate actions and rewards, making them more dynamic compared to the static probabilistic framework of Markov Models.
- Application: MMs are often used in sequence modeling, whereas MDPs find applications in dynamic systems requiring decision-making strategies.

E.2 Complementary Roles

Despite their differences, Markov Models and Markov Decision Processes are complementary. Markov Models can provide foundational insights into the behavior of sequential systems, which can then be leveraged by MDPs to optimize decision-making strategies for long-term objectives.

Consider a scenario where a farmer must decide whether to cover their crops based on the weather conditions. The states are "Rain" and "Sunny," and the farmer's decision revolves around their Markov Decision Process (MDP). If the forecast predicts rain, the farmer must evaluate the cost of covering the crops versus the potential loss if left uncovered, factoring in historical weather patterns modeled by Markov insights. On sunny days, the cost of unnecessary coverage must also be weighed against the less likely risk of unexpected rain.

Using a probabilistic Markov Model, the farmer could estimate the likelihood of transitioning from "Rain" today to "Sunny" tomorrow or vice versa, helping them understand weather trends. The MDP builds on this by assigning actions ("Cover" or "Do Not Cover") and rewards (avoiding crop damage) or penalties (incurring costs for unnecessary coverage). By simulating various outcomes and optimizing decisions over time, the farmer can minimize costs while maximizing crop health, effectively blending sequential predictions with dynamic decision-making strategies.

Appendix F - NFA as the Time Crystal Complement to Time Molecules

F.1 Introduction

Markov models and Non-Deterministic Finite Automata (NFAs) tackle sequence data from opposite angles. A Markov model is like a first draft of your process—an inductive hypothesis built from observed transitions and their probabilities. An NFA, by contrast, embodies the precise rules you ultimately uncover: it recognizes exact patterns in real-time, even when you allow multiple possible "next steps."

F.2 Non-Deterministic Finite Automata (NFA) Basics

States & Transitions

An NFA consists of a finite set of states and transitions labeled by events. From any given state, an NFA can follow one or more outgoing transitions when it sees an event, or even make "epsilon" moves without consuming input.

Recognition

At runtime, the NFA maintains all active states in parallel. If any active state reaches an accepting state when the input ends, the sequence is recognized.

Real-Time Matching

NFAs excel at streaming pattern detection—flagging whenever a specific event sequence (or any of several variants) occurs, without needing to observe the entire trace first.

F.3 Markov Models Recap

• Probabilistic First Draft

A Markov chain (or higher-order Markov model) captures how often you've seen one event follow another, estimating transition probabilities and time-between-events statistics.

Prediction & Hypotheses

By projecting those probabilities forward, a Markov model offers a quick way to forecast likely next steps—or to surface surprising deviations from expected behavior.

F.4 Complementary Roles

Role	NFA	Markov Model
Primary Task	Recognize exact or pattern-based sequences	Predict next events and timing
Nature	Rule-based, deterministic or branching rules	Data-driven, probabilistic

Role	NFA	Markov Model
Latency	Immediate: as soon as a pattern completes	Aggregated: after collecting transition counts
Flexibility	Captures specified variants via nondeterminism	Learns variants automatically from data
Updating	Edit rules when you discover new constraints	Recompute probabilities as you ingest new data

F.5 Markov Models as Hypotheses, NFAs as Refined Rules

1. Build the Hypothesis

 Use Markov models on historical event logs to propose which transitions happen most often and with what timing variability.

2. Validate & Refine

 Translate high-probability paths into NFA transitions. For each surprising or low-probability branch, inspect logs and decide whether to include or tighten rules.

3. Operationalize

 Deploy the NFA in your real-time stream processor. It will instantly flag any matching sequence, including the variants you allowed via nondeterminism.

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Over time, your NFA becomes the "time crystal" of the process: a fixed, precise automaton that reflects all the domain rules you've hammered out from your initial Markov-model hypotheses.

F.6 Use Cases

Fraud Detection

- \circ Markov models surface unexpected transition patterns (e.g., login \rightarrow funds transfer \rightarrow new beneficiary).
- NFAs encode the precise sequences that should trigger alerts, including multiple branching paths (e.g., optional OTP failures).

• Manufacturing Workflow

- Markov analysis highlights common failure points or delays.
- NFAs enforce the exact allowed sequence of machine states, flagging deviations immediately.

F.7 Summary

Markov models give you a lightweight, probabilistic "first draft" of how your system behaves. NFAs let you crystallize those insights into concrete, nondeterministic rules that run in real time. Together, they form a powerful one-two punch: hypothesize with data, then validate and enforce with rules.

Appendix G - Handling Events Arriving Out of Order in Streaming Systems

G.1 Introduction

Events in a real-time pipeline can arrive late or out of sequence due to network latency, clock skew, or retries. If you process them strictly in ingestion order, you'll distort transition counts and inter-event timing—poisoning your Markov models. The following patterns ensure you respect **event time** and still meet latency and resource constraints.

G.2 Core Techniques Summary

1. Event-Time Semantics & Watermarks

- Tag each record with its original timestamp (from the source or an ingestion proxy).
- o Define a watermark: "we've seen all events up to (max event time allowed lateness)."
- Emit windowed results when the watermark passes the window end, with optional reemission for stragglers within the lateness bound Milvus BlogZilliz.

2. Windowing with Allowed Lateness

- o Use event-time tumbling or sliding windows.
- o Configure an **allowed lateness** (e.g. 5 min) so late arrivals within that bound still update the window.
- Redirect events later than (window end + lateness) to a "late" side stream MediumDatabricks.

3. Buffer & Reorder Before Aggregation

- Maintain a small per-key buffer sorted by event timestamp.
- Hold events until the buffer spans your lateness bound or reaches a max size, then flush in timestamp order.
- Guarantees correct sequence without unbounded state growth <u>ZillizSoftware Engineering</u>
 <u>Stack Exchange</u>.

4. Idempotent, Transactional State Updates

- Model transition counts and timing stats as upserts keyed by event ID or window key, not simple increments.
- Use transactional sinks (Kafka transactions, ACID databases) so partial writes don't leave state inconsistent <u>Milvus Blog</u>.

5. State TTL & Checkpointing

- Attach a time-to-live to per-key buffers/window-state so once the lateness window lapses, old state is evicted.
- Regularly checkpoint state; on restart, replay the event log (including late arrivals) to rebuild correct counts Medium.

6. Monitoring & Alerts

o Track metrics for on-time vs. late vs. dropped events.

- Alert when late-event rates spike (signaling clock drift or upstream delays).
- o Log event IDs and timestamps end-to-end for traceability <u>Stack Overflow</u>.

G.3 Best Resources for Further Reading

1. 9 Best Practices For Handling Late-Arriving Data

https://lakefs.io/blog/best-practices-late-arriving-data/

2. How do streaming systems handle out-of-order data?

https://blog.milvus.io/ai-quick-reference/how-do-streaming-systems-handle-outoforder-data Milvus Blog

3. Feature Deep Dive: Watermarking in Apache Spark Structured Streaming

https://www.databricks.com/blog/feature-deep-dive-watermarking-apache-spark-structured-streaming

4. Watermarking Late Data in Spark Structured Streaming (Part 8)

https://medium.com/@kiranvutukuri/watermarking-late-data-in-spark-structured-streaming-part-8-f75e156d7bce

5. Best practices for delayed actions in event-driven architecture

https://softwareengineering.stackexchange.com/questions/445645/best-practices-for-delayed-actions-in-event-driven-architecture Software Engineering Stack Exchange

Appendix H - State/Event, Cause/Effect, and Event Sourcing

H.1 Introduction

At the heart of any process-mining or event-analysis framework lie two complementary lenses: **cause/action**, which captures the deliberate triggers that set things in motion, and **event/state**, which records the manifestations or conditions that follow. Understanding their interplay is essential for building the ISG, the TCW, and any event-driven reasoning system.

H.2 Defining Cause/Action and Event/State

Cause/Action

A cause or action is an intentional or identifiable trigger—"why" something happens. It's a choice or external force that initiates change. In data, actions are typically logged as discrete events (e.g. "place order," "raise bet," "spill lunch").

Event/State

An event is any occurrence or change that can be observed. A state is the condition or snapshot at a particular moment. While we often refer to "event" and "state" interchangeably, it helps to think of an event as the transition and a state as the resulting condition (e.g. "order fulfilled," "chips held," "shirt stained").

H.3 A Simple Example: Spilling Lunch

- 1. Cause/Action: You spill food on your shirt.
- 2. Resulting State: Your shirt is stained.
- 3. **Remedial Actions**: You consider "change clothes" or "spot-clean" as actions that resolve the stained state.

Humans infer the link instinctively, but computers need structured data. We might log:

- Event A: "spill lunch"
- · State B: "shirt stained"
- Action C: "change clothes"

A single action (C) may have many causes (spill, rain, ink leak), and a single cause (spill) may trigger multiple actions (change clothes, use napkin). Correlation measures alone (e.g. Pearson) will dilute this link unless we introduce context or conditioning (e.g. Bayesian likelihoods given spare shirt availability).

H.4 Capturing Patterns in Data

To uncover these relationships without hand-crafting every rule:

1. Event Sequencing

Track timestamps and sequence IDs so you can group "spill \rightarrow stained \rightarrow change clothes" without pre-defined rules.

2. Conditional Probabilities

Use a Bayesian model: given "spill," compute P(change | spill).

3. Outlier Detection

If most "change clothes" occur at 6 pm but a few happen at 1 pm, flag those as "unscheduled changes"—likely driven by spills or other causes.

4. Clustering Causes and Effects

Represent each sequence as a vector of event counts or transition probabilities and cluster similar patterns to surface common cause-effect pathways.

H.5 Real-Time vs. Batch Context

- The analytics database (EKG) is optimized for large-scale reads (OLAP). Batch updates (hourly, nightly) load new states and events into the DC, ISG, and TCW.
- For near-real-time visibility, a staging area holds recent events (e.g. analyst insights or LLM-augmented annotations). Queries can merge staging and EKG results on the fly, yielding "seconds-old" insights without interrupting heavy analytic workloads.
- Just as RAG augments LLMs beyond their training cutoff, this two-tier approach extends the freshness of your event/state information.

H.6 CAUSE/EVENT vs. ACTION/STATE IN PRACTICE

Role	Cause/Action	Event/State
What it is	Trigger or reason	Outcome or condition
Data representation	Logged as an event type (verb)	Logged as an event node or state snapshot
Example (poker)	"Raise," "Fold"	"Pot size," "Chips held"
TCW usage	Count correlations from causes to states	Measure frequencies and durations of states

H.7 Key Takeaways

- **Distinct but intertwined**: causes/actions ignite transitions; events/states capture the before-and-after.
- **Modeling challenge**: computers need explicit sequencing, probability, and clustering to mirror human intuition about cause and effect.
- **Practical workflow**: log fine-grained actions, group and cluster resulting states, apply Bayesian and correlation analyses, and enable real-time staging to keep insights fresh.

By clearly separating "why" from "what happened," you empower the TCW (and any Aldriven reasoning process) to move from raw counts toward causal understanding and actionable intelligence.

Appendix I - Markov Models vs RNN

RNNs & Time-Series Analysis

RNNs (especially LSTMs and GRUs) were designed to handle sequential data by maintaining a hidden state that evolves over time. In finance or IoT, you feed each new timestep into the network and train it to predict the next value or classify a pattern. Their gating mechanisms help them remember longer contexts than vanilla RNNs, making them a staple in demand forecasting and anomaly detection.

Sequence Clustering Approaches

- *Markov Models:* you can represent each sequence as a vector of transition probabilities or stationary distribution and then cluster those vectors to find common process archetypes.
- *RNNs:* by collecting the hidden-state activations at each timestep (or the final state), you obtain fixed-length representations that you can feed into k-means or hierarchical clustering for grouping similar behaviors.
- Transformers: you typically take the pooled [CLS] embedding (or average all token embeddings) as a sequence fingerprint and then apply standard clustering on those high-dimensional vectors, often revealing semantic or functional clusters in large text/process logs.

Aspect	Markov Models	RNNs (LSTM/GRU)	Transformers (LLMs)
Core Idea	Probabilistic state- to-state transitions	state updates with	Attention over entire sequence
Background & Techniques	Transition matrices; sojourn- time stats; first- or higher-order chains	Backpropagation through time; LSTM/GRU cells; time- series forecasting	lavers, positional encodings,
Strengths	Simple, efficient, highly interpretable	Handles short/medium sequences; models non-linear dynamics	Context-rich long-range dependencies; zero-/few-shot abilities

Aspect	Markov Models	RNNs (LSTM/GRU)	Transformers (LLMs)
Weaknesses	Limited memory— state space explodes with longer context		Computationally heavy; internal representations opaque
Time-Series Analysis	Direct modeling of transition probabilities & timing		Fine-tuned forecasting/classification; accepts numeric/time features
Sequence Clustering	trangition-	Cluster hidden-state trajectories (e.g. k- means on hidden states)	embeddings (e.g. CLS token
Applications	Process mining; queueing theory; predictive maintenance	Speech recognition; anomaly detection; demand forecasting	Text generation; summarization; complex reasoning tasks

Appendix J - Weighted Standard Deviation

In large-scale or distributed environments, computing standard deviation in the naïve two-pass way can become expensive and unwieldy. The classic approach first requires a full pass over every data point (or every weighted record) to calculate the overall mean, and then a second pass to accumulate the squared deviations from that mean. If your fact tables or event streams live on multiple servers, you must gather partial sums and counts from each node, merge them to compute the global mean, and then push that mean back out so that each node can compute its local deviations and contribute to the final variance. That "round trip" inevitably doubles both data movement and I/O, and it complicates your streaming or batch pipelines.

The one-pass, weighted incremental algorithm bypasses this entirely. Instead of separating "mean" and "deviation" into two phases, it maintains three running totals—total weight, running average, and a single accumulated "error" term that implicitly tracks squared deviations as new observations arrive. Each time you see a new datum (with its associated weight), you update those three totals in constant time and constant space, and you never need to revisit old data. When your

pipeline finishes, you can compute the variance or standard deviation directly from those accumulated totals.

J.1 Why this matters

- **Reduced data movement**: You only emit partial aggregates once per record, rather than shuttling windows of raw values or intermediate means across the network.
- **Lower I/O costs**: No need to materialize or re-read large intermediate datasets for a second pass.
- **Streaming friendly**: Perfect for event-time streams where records arrive continuously; you never have to "rewind" or buffer entire windows just to finish a calculation.
- **Numerical stability**: By carefully updating the running mean and error term together, the algorithm avoids catastrophic cancellation that can plague naïve two-pass implementations—especially when weights vary widely or values are large.

In short, this weighted one-pass approach delivers fully accurate, reproducible variance and standard deviation without the complexity and resource overhead of a second sweep through your data.

When you call Python's built-in statistics.stdev(), under the hood it really does two passes:

- 1. **First pass** to compute the mean over your list
- 2. **Second pass** to sum up each (xi-mean)2(x_i \text{mean})^2(xi-mean)2 and then take the square root

That's fine for in-memory lists, but in a distributed or streaming system it means:

- You have to pull all your partial sums and counts together just to get the global mean
- Then you have to push that mean back out so each node can compute its local deviations and contribute to the final variance
- Two full sweeps of your data, doubling I/O and network traffic

J.2 One-Pass, Incremental (Weighted) Approach

The weighted running-stats algorithm we showed (West's variant of Welford's method) only ever *visits* each record once. Each time you see a new (x,w)(x,w) pair, you:

- Update your running total of weights
- Shift your running mean in constant time
- Adjust a single "error" accumulator that implicitly tracks all the squared deviations so far

Because all three quantities get updated together, you never need a second pass. As soon as your stream (or batch) is done, you compute variance or standard deviation directly from those running totals.

J.3 Why You See Two Loops in the Demo

In the example given, there were two loops **only** to show:

- How it works with uniform weights (which replicates the unweighted case)
- How it works with varied weights

Each loop is a separate demonstration, but **neither** requires going back over the data a second time. In practice you'd have one loop over your stream, and that's it.

J.4 Key Takeaways

- statistics.stdev() = two full scans (mean pass + deviation pass)
- Weighted running stats = one scan, constant-space, streaming-friendly
- You still "touch" each record exactly once, but you never have to rewind to recompute anything—so no second pass, no extra I/O, and no extra data-movement.

J.5 One-Pass Standard Deviation in Practice (one_pass_standard_deviation.py)

The file <u>one_pass_standard_deviation.py</u> illustrates the contrast between the standard two-pass method for calculating standard deviation and a one-pass, streaming-friendly alternative.

The **first part** of the script demonstrates the conventional approach:

- 1. Compute the mean in a first pass.
- 2. In a second pass, compute the squared deviations from that mean.

This is how Python's built-in statistics.stdev() works internally. It's fine for small, in-memory lists but becomes inefficient when applied to large-scale ETL or streaming systems that can't afford multiple passes over the data.

The **second part** of the script implements a **one-pass, weighted algorithm**, adapted from Welford's method. It maintains a running total of weights, a streaming mean, and a single accumulator for squared error. Each update is constant-time and numerically stable, even with varied weights or large values. When the data stream ends, it computes the sample or population standard deviation directly.

This is especially relevant for Time Molecules and other distributed systems, where minimizing data movement and computation time is crucial. The approach shown in one_pass_standard_deviation.py enables high-performance statistical analysis without sacrificing accuracy.