

$$\begin{aligned}
 p(z|x) &= \frac{p(x|z)p(z)}{p(x)} \\
 &= \frac{p(x, z)}{p(x)} \\
 &= \frac{p(x, z)}{\int p(x, z') dz'} \quad \xrightarrow{\text{const}} \text{const}
 \end{aligned}$$

$\xrightarrow{\text{const}} \text{const} \because$

I. Variational inference

Approximate $p(z|x)$ with some variational distribution $q_\phi(z)$.

$$\begin{aligned}
 &KL(q_\phi(z) \parallel p(z|x)) \quad \xrightarrow{\text{Review KL}} \\
 &= \mathbb{E}_{q_\phi(z)} \left[\log \frac{q_\phi(z)}{p(z|x)} \right] \quad \begin{array}{l} \nearrow \text{see end of file} \\ \text{Can't evaluate} \\ \text{since we don't} \\ \text{know } p(z|x)! \end{array} \\
 &= \mathbb{E}_{q_\phi(z)} [\log q_\phi(z)] - \mathbb{E}_{q_\phi(z)} [\log p(z|x)]
 \end{aligned}$$

$$\begin{aligned}
&= \mathbb{E}_{q_\phi(z)} [\log q_\phi(z)] - \mathbb{E}_{q_\phi(z)} [\log p(x, z) - \log p(x)] \\
&= \mathbb{E}_{q_\phi(z)} [\log q_\phi(z) - \log p(x, z)] + \log p(x) \\
&= - \underbrace{\mathbb{E}_{q_\phi(z)} \left[\log \frac{p(x, z)}{q_\phi(z)} \right]}_{\text{ELBO}(\phi)} + \log p(x)
\end{aligned}$$

$$\begin{aligned}
&\Rightarrow \min_{\phi} \text{KL}(q_\phi(z) \| p(z|x)) \\
&\quad \text{is equivalent to } \max_{\phi} \text{ELBO}(\phi)
\end{aligned}$$

$$\begin{aligned}
\text{ELBO}(\phi) &= \mathbb{E}_{q_\phi(z)} \left[\log \frac{p(x, z)}{q_\phi(z)} \right] \\
&= \mathbb{E}_{q_\phi(z)} [\log p(x, z)] + H[q_\phi(z)]
\end{aligned}$$

→ automatic differentiation variational inf.

II. ADVI

How to choose q ?

- 1) Transform the support of the latent variable z such that they live in \mathbb{R}^k .

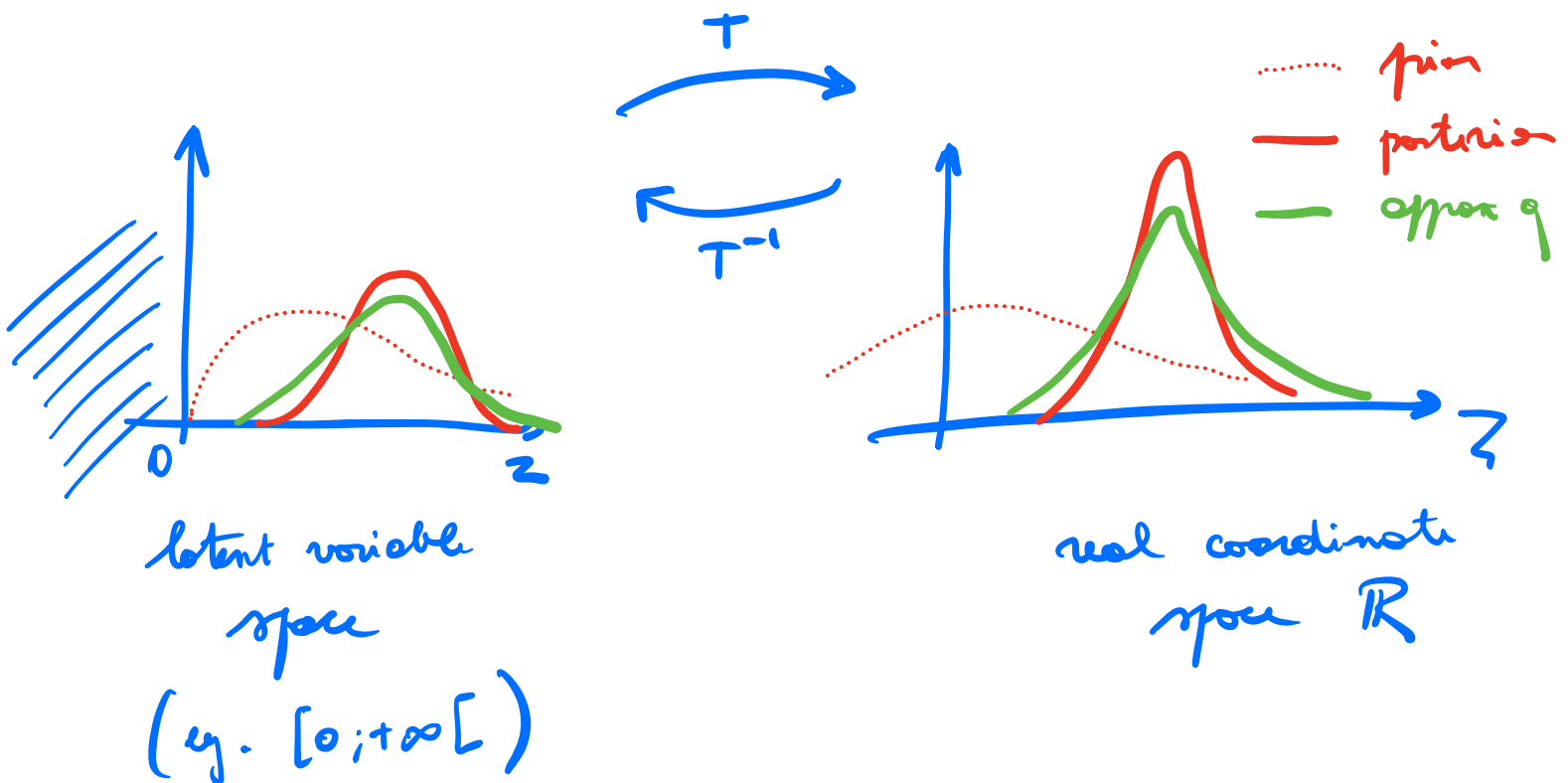
$$T: \text{support}(p(z)) \mapsto \mathbb{R}^k$$

$$z = T(z)$$

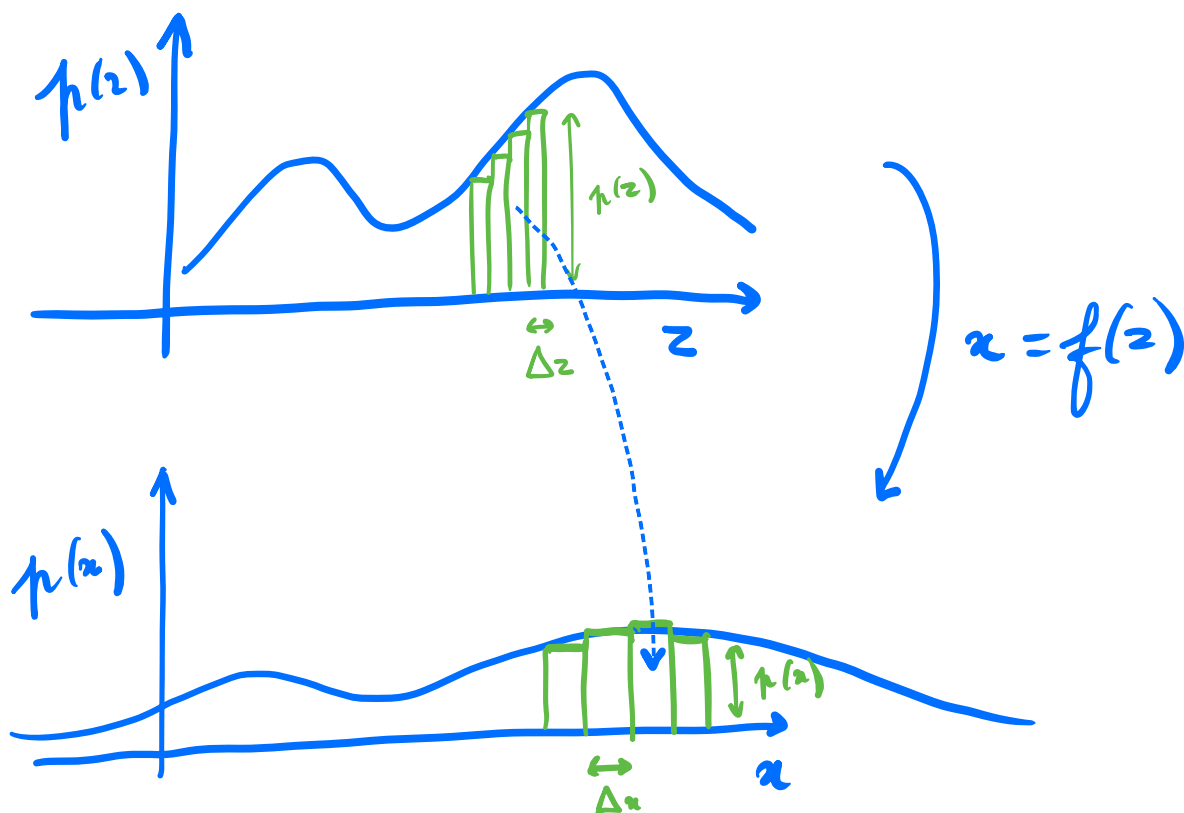
↳ will be easier to define q over \mathbb{R}^k
(eg. $q := \mathcal{N}$)

$$\Rightarrow p(x, z) = p(x, T^{-1}(z)) |\det J_{T^{-1}}(z)|$$

change of variable then



Change of variable theorem:



conservation
de la densité

$$p(z) \Delta z = p(u) \Delta u$$

Change of
measure
→ stretching z to u
must be compensated
by reducing $p(u)$

$$\textcircled{1} \rightarrow p(u) = p(z) \frac{\Delta z}{\Delta u}$$

$$= p(f^{-1}(u)) \frac{\Delta f^{-1}}{\Delta u}$$

$$\Delta u \rightarrow 0 \rightarrow p(f^{-1}(u)) \left| \frac{\partial f^{-1}}{\partial u} \right|$$

$$z = f^{-1}(u)$$

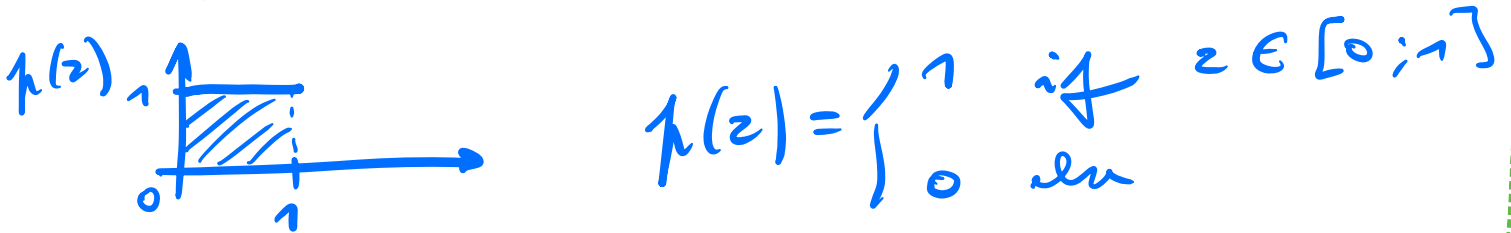
1.1 because
of ratio
of two ones

$$\textcircled{2} \rightarrow p(u) = p(z) \frac{\Delta z}{\Delta u}$$

$$p(f(z)) = p(z) \frac{\Delta z}{\Delta f} \quad \text{with } \Delta z = f(z) \quad \left(\frac{\Delta f}{\Delta z} \right)^{-1}$$

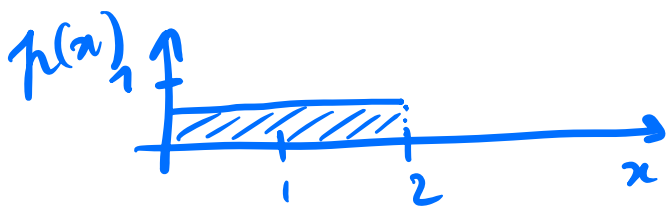
$$\stackrel{\Delta z \rightarrow 0}{=} p(z) \left| \frac{\partial f}{\partial z} \right|^{-1}$$

Example:



$$x = f(z) = 2z \rightarrow z = f^{-1}(x) = \frac{1}{2}x$$

$$p(x) = p(f^{-1}(x)) \left| \frac{\partial f^{-1}}{\partial x} \right| = p(f^{-1}(x)) \frac{1}{2}$$



Multivariate case:

$$p(x) = p(f^{-1}(x)) \left| \det \frac{\partial f^{-1}}{\partial x} \right| \rightarrow \text{Jacobian of } f^{-1}$$

$$p(x=f(z)) = p(z) \left| \det \frac{\partial f}{\partial z} \right|^{-1} \rightarrow \text{Jacobian of } f$$

2) Point a mean-field Gaussian variational approximation:

$$q(\underline{z}) = \mathcal{N}(\underline{z} | \underline{\mu}, \underline{\sigma}^2)$$

$$= \prod_{k=1}^K \mathcal{N}(z_k | \underbrace{\mu_k, \sigma_k^2})$$

⚠ Strong
assumption
 \Rightarrow no posterior
correlation

$$\phi = \{\mu_1, \sigma_1, \dots, \mu_K, \sigma_K\}$$

(1) + (2) :

$$\mathcal{L}(\underline{\mu}, \underline{\sigma}^2) = \mathbb{E}_{q(\underline{z})} \left[\log p(x, T^{-1}(\underline{z})) | \det J_{T^{-1}}(\underline{z}) \right] \\ + \underbrace{\mathbb{H}[q(\underline{z})]}$$

$$= \frac{K}{2} (1 + \log 2\pi) + \sum_{k=1}^K \log \sigma_k^2$$

3) Optimization:

$$\underline{\mu}^*, \underline{\sigma}^* = \arg \max_{\underline{\mu}, \underline{\sigma}} \mathcal{L}(\underline{\mu}, \underline{\sigma})$$

$$\text{s.t. } \underline{\sigma}^2 > 0$$

\Rightarrow Stochastic gradient ascent on \mathcal{L} .



- How to enforce $\underline{\sigma}^2 > 0$?

\Rightarrow Reparametrize $\rightarrow \underline{w} = \log \underline{\sigma}^2 \in \mathbb{R}^k$

- \mathbb{E}_q depends on ϕ , hence

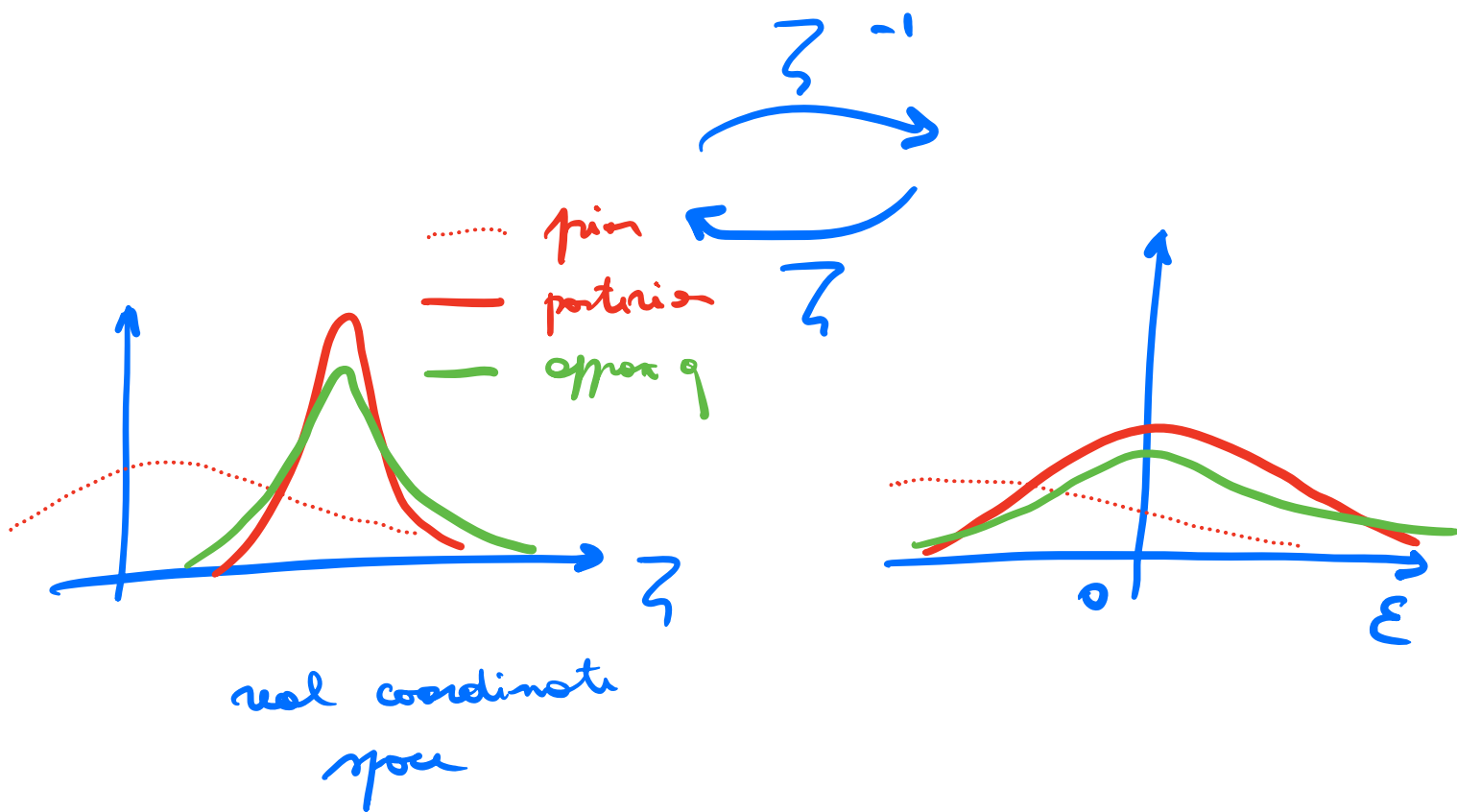
$$\nabla_{\phi} \mathbb{E}_{q_{\phi}} \neq \mathbb{E}_{q_{\phi}} \nabla_{\phi}$$

3b) \hookrightarrow

Reparametrization trick:

$$\underline{\varepsilon} \sim \mathcal{N}(0, \mathbf{I})$$

$$\underline{z} = \underline{\mu} + \text{diag}(\sqrt{\exp(\underline{w})}) \underline{\varepsilon}$$



$$\begin{aligned}
 \underline{\mu}^*, \underline{w}^* &= \arg \max_{\underline{\mu}, \underline{w}} \mathcal{L}(\underline{\mu}, \underline{w}) \quad \rightarrow = \int p(\alpha|z) p(z) \\
 &= \arg \max_{\underline{\mu}, \underline{w}} \mathbb{E}_{w(\mathcal{E}; \mathbf{0}, \mathbf{I})} \left[\log p(\alpha, T^{-1}(z(\mathcal{E}))) \right. \\
 &\quad \left. + \log |\det J_{T^{-1}}(z(\mathcal{E}))| \right] \\
 &\quad + \sum_{k=1}^K w_k
 \end{aligned}$$

$$\nabla_{\mu} \mathcal{L} = \mathbb{E}_{w(\epsilon)} [\nabla_{\mu} (...)]$$

$$\nabla_{w_k} \mathcal{L} = \mathbb{E}_{w(\epsilon)} [\nabla_{w_k} (...)] + 1$$

with auto-diff

approximate
the expectation
using M samples

Start with the found
KL \rightarrow better choice
if q has high
capacity

II. Neural posterior approximation

emortize over all x

$$\min_{\phi} \mathbb{E}_{p(x)} \left[\text{KL} \left(p(z|x) \parallel q_{\phi}(z|x) \right) \right]$$

found KL neural density estimator

$$= \min_{\phi} \mathbb{E}_{p(x) p(z|x)} \left[\log \frac{p(z|x)}{q_{\phi}(z|x)} \right]$$

$$= \max_{\phi} \mathbb{E}_{p(x, z)} \left[\log q_{\phi}(z|x) \right]$$

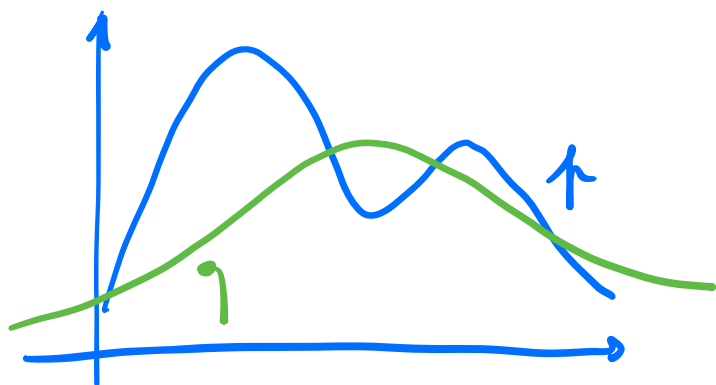
Forward KL

vs.

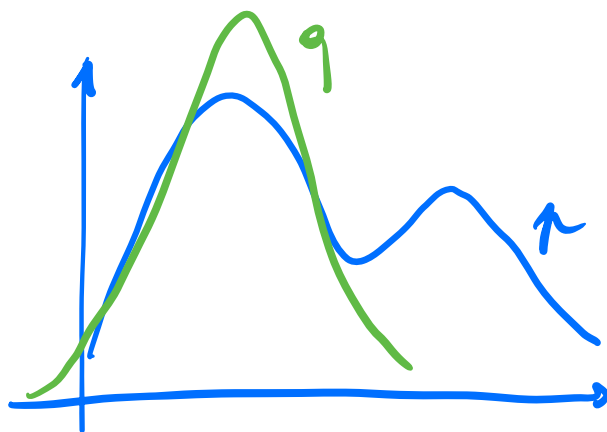
Reverse KL

$$KL(p \parallel q) \\ = \mathbb{E}_p \left[\log \frac{p}{q} \right]$$

$$KL(q \parallel p) \\ = \mathbb{E}_q \left[\log \frac{q}{p} \right]$$



mean-seeking



mode-seeking

