

Policy

This is a takehome midterm. You take it home, do it for a week, and then hand it back. It is due Apr 20th. (So you have a total of 2 weeks.) This exam is hard, so please **START EARLY**.

I encourage collaborations on this midterm. However, you must obey the following rule:

1. You **MUST** each hand in your own work individually in your own words.
2. You **MUST** understand everything you wrote. (Say you copied your friend's **WRONG** answer without thinking, and that will most likely be in violation of this rule.)
3. You need to write down the names of your collaborator, if any.
4. Failure to comply rule 2 and rule 3 will be treated as plagiarism.
5. Collaboration with people not in this class (such as a math grad student) is not forbidden but not recommended. If you choose to, then write down their names as well.

We have a total of six problems and 11 points each, and a total of 66 points. Full credit is 60 points, and if you get more than 60 points, then your score is simply 60 points. (So you have some room for mistakes.)

The Midterm

Problem 1 (Pokémon Battle!). You are in a Pokémon battle, and your rattata is fighting Ash's Pikachu. You will need to attack three times to fully defeat Pikachu. However, your rattata is paralyzed. Each round, you have $\frac{3}{4}$ chance to attack successfully, and $\frac{1}{4}$ chance to be effected by the paralysis status and therefore unable to attack. Let us study this battle with linear algebra.

1. (2pt) Suppose after the battle go on for t rounds, the chance we still need 3, 2 or 1 successful attacks to win is p_3 , p_2 and p_1 . And the chance that you have already won is p_0 . Find a matrix A such that

$$A^t \begin{bmatrix} 1 \\ 0 \\ 0 \\ 0 \end{bmatrix} = \begin{bmatrix} p_3 \\ p_2 \\ p_1 \\ p_0 \end{bmatrix}. \text{ (} A \text{ is called the Markov matrix of this dynamical system. It describes the evolution of the battle.)}$$

2. (2pt) Find the Jordan canonical form of A and the minimal polynomial of A .
3. (2pt) Suppose we want to block diagonalize A into a 3×3 block and a 1×1 block, which Sylvester's equation do I need to solve? Find the equation and solve it.
4. (2pt) Find X such that $X^{-1}AX$ is in Jordan canonical form.
5. (3pt) Note that $\mathbf{e}_4^T(A^t - A^{t-1})\mathbf{e}_1$ is the probability that Pikachu is defeated using exactly t rounds. (You do not need to prove this.) Therefore the expected number of rounds needed to defeat Pikachu is $\mathbf{e}_4^T(\sum_{t=1}^{\infty} tA^{t-1})(A - I)\mathbf{e}_1$. Power series calculation then shows that $\sum_{t=1}^{\infty} tx^{t-1} = -\frac{1}{(1-x)^2}$, which means the expected value should be something like $\mathbf{e}_4^T(A - I)^{-1}\mathbf{e}_1$. However, $A - I$ is not invertible! What should we do? Well, note that $(A^t - A^{t-1})\mathbf{e}_1 = (A^t - A^{t-1})(\mathbf{e}_1 - \mathbf{e}_4)$, and A has an invariant subspace V containing $\mathbf{e}_1 - \mathbf{e}_4$ on which $A - I$ is invertible. For this problem, find this invariant subspace V , and compute $\mathbf{e}_4(A - I)^{-1}(\mathbf{e}_1 - \mathbf{e}_4)$ where $(A - I)^{-1}$ is interpreted as the inverse of $A - I$ restricted to the invariant subspace V . (This is the expected number of rounds we need to defeat pikachu.)

Problem 2 (Matrix Square Root). Given a matrix A , we would like to find all square roots of A , i.e., matrices B such that $B^2 = A$. (Some of the questions here concerns Hermitian matrices. You may use the spectral theorem of Hermitian matrices freely.)

1. (1pt) Suppose A is $n \times n$ and diagonalizable with distinct eigenvalues. How many square roots of A are there?
2. (2pt) Describe all square roots of the 2×2 identity matrix.

3. (2pt) Describe all square roots of $A = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$.

4. (2pt) Suppose A is a Hermitian positive-definite matrix. (I.e., $A^* = A$ and all eigenvalues are positive.) Show that there is a UNIQUE Hermitian positive-definite matrix B such that $B^2 = A$. We shall write this B as $A^{\frac{1}{2}}$ from now on. (Note that there might be other non-Hermitian square roots. If you fail to see how, then you might be doing this problem wrong.)

5. (2pt) Suppose A is a Hermitian positive-definite matrix. Show that $(A^{\frac{1}{2}})^{-1} = (A^{-1})^{\frac{1}{2}}$.
6. (2pt) Find an example of Hermitian positive-definite matrices A, B such that $(A^{\frac{1}{2}}B^{\frac{1}{2}})^2 \neq AB$.

Problem 3 (Geometric Mean). Given two positive real numbers a, b , their arithmetic mean is $\frac{a+b}{2}$, while their geometric mean is \sqrt{ab} . A famous inequality is $\sqrt{ab} \leq \frac{a+b}{2}$.

We now attempt to derive a similar idea for matrices. Given two positive definite Hermitian matrices A, B (so that their eigenvalues are positive real numbers), their arithmetic mean is easily $\frac{1}{2}(A+B)$. But what should be their geometric mean? In last problem, you have seen that $A^{\frac{1}{2}}B^{\frac{1}{2}}$ does NOT work, because it might not even be a square root of AB . So we need to do something else.

Given two positive definite Hermitian matrices A, B , let us define the matrix $A\#B$ as a positive definite Hermitian matrix X such that $XB^{-1}X = A$. We shall see that such X is unique.

(BTW, the idea of geometric mean of matrices have some interesting applications. For example, in computational graphics, given two motions described by linear transformations A, B , how to find a “mid-point” between the motion? Then $A\#B$ would be a good candidate.)

1. (2pt) Show that if $XB^{-1}X = A$, then we must have $(B^{-\frac{1}{2}}XB^{-\frac{1}{2}})^2 = B^{-\frac{1}{2}}AB^{-\frac{1}{2}}$, and show that $X = B^{\frac{1}{2}}(B^{-\frac{1}{2}}AB^{-\frac{1}{2}})^{\frac{1}{2}}B^{\frac{1}{2}}$. (Here $B^{-\frac{1}{2}}$ means the inverse of $B^{\frac{1}{2}}$.) In particular, we see that such positive definite Hermitian X is uniquely determined.
2. (2pt) Show that $A\#A = A$ and $(A\#B)^{-1} = A^{-1}\#B^{-1}$.
3. (2pt) Show that $A\#B = B\#A$.
4. (2pt) Given two Hermitian matrices A, B , we say $A \geq B$ if $A - B$ is positive semidefinite (i.e., all eigenvalues are non-negative). Show that $A\#B \leq \frac{1}{2}(A+B)$. So indeed the geometric mean is at most the algebraic mean. (Hint: Note that the square of any Hermitian matrix must be positive semidefinite, so $((B^{-\frac{1}{2}}AB^{-\frac{1}{2}})^{\frac{1}{2}} + I)^2 \geq 0$. Also recall that M and $XM X^*$ have the same definite-ness for invertible X .)
5. (3pt) Show that if $\begin{bmatrix} A & X \\ X & B \end{bmatrix} \geq 0$ for some Hermitian X , then $X \leq A\#B$. (So $A\#B$ is the largest Hermitian matrix with such a property. Hint: Block LDU.)

Problem 4 (Motion under weird force field). Suppose a mass point with mass $m = 1$ is moving inside \mathbb{R}^2 , under the effect of some weird force field. Let $\mathbf{r}(t) = \begin{bmatrix} x(t) \\ y(t) \end{bmatrix}$ be the location of the mass point at time t . Suppose the force field applies a force to the mass point depending on the location of the mass point, say, $\mathbf{F}(t) = \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix} \mathbf{r}(t)$, where $\mathbf{F}(t)$ is the force acting on the mass point at time t . We would like to solve this differential equation.

1. (3pt) Let $\mathbf{v}(t) = \mathbf{r}'(t)$ be the velocity at time t . Then we can think of the status of the mass point as a vector $\begin{bmatrix} \mathbf{r}(t) \\ \mathbf{v}(t) \end{bmatrix}$. Find a constant matrix A such that $\frac{d}{dt} \begin{bmatrix} \mathbf{r}(t) \\ \mathbf{v}(t) \end{bmatrix} = A \begin{bmatrix} \mathbf{r}(t) \\ \mathbf{v}(t) \end{bmatrix}$.
2. (3pt) Find X, J such that $A = XJX^{-1}$ is the Jordan decomposition for A .
3. (2pt) For fixed t , find a polynomial $p(x)$ of degree 3 such that $p(t) = e^t, p'(t) = e^t, p(-t) = e^{-t}, p'(-t) = e^{-t}$.
4. (3pt) Say $p(x) = a_0 + a_1x + a_2x^2 + a_3x^3$ in the last sub-problem. Calculate the entries of e^{At} involving the constants a_0, a_1, a_2, a_3 . (We use a_0, a_1, a_2, a_3 so that your answer is not absurdly long and complicated. We do not require you to solve this differential equation, but at this stage, you should know how to obtain a formula for the solution to this differential equation.)

Problem 5 (Generalized Cayley-Hamilton). Given any square matrix A , if $p_A(x) = \det(xI - A)$, then we know $p_A(A) = 0$. This is the Cayley-Hamilton theorem. However, in a letter to Sylvester, Cayley claimed that he in fact know a more generalized version of this result. Suppose we have two square matrices A, B such that $AB = BA$. Let us define a function $f(x, y) = \det(xA - yB)$ (so the inputs are two complex numbers, and the output is a complex number). The generalized Cayley-Hamilton claim that $f(B, A) = 0$. As you can see, the original Cayley-Hamilton is the special case when $A = I$.

Alas, Cayley did not really provide any proof in that letter. So let us prove it ourselves.

1. (2pt) An absent-minded student Yilong Yang used the following argument: If we plug in $x = B, y = A$ directly into the definition of f , then we have $f(B, A) = \det(BA - AB)$. And since $AB = BA$, we see that $f(B, A) = 0$. Unfortunately, this argument is wrong. Could you describe what's wrong with it?
2. (2pt) Verify that $f(B, A) = 0$ when $A = \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}$ and $B = \begin{bmatrix} 2 & 3 \\ 0 & 2 \end{bmatrix}$.
3. (3pt) If A is invertible, show that $f(x, y)$ is a multiple of $y^n p_C(y^{-1}x)$, where A, B are $n \times n$ matrices, $C = A^{-1}B$, and p_C is the characteristic polynomial of C .
4. (2pt) If A is invertible, prove that $f(B, A) = 0$.
5. (2pt) Show that there is a sequence of invertible matrices A_t such that $A = \lim A_t$, and $A_t B = B A_t$ for all A_t . (We do not require you to fill out the rest of the proof of the generalized Cayley-Hamilton, but you should be able to imagine what the proof looks like.)

Problem 6 (Newton's Method). As we have seen in class, $\text{sign}(X)$ is useful to solve certain Sylvester's equations. Here we aim to find a way an approximation to $\text{sign}(X)$. Given a matrix A with no purely imaginary eigenvalue, set $X_0 = A$, and set $X_{n+1} = \frac{1}{2}(X_n + X_n^{-1})$. (As a side note, a complex number z is purely imaginary if its real part is zero. In particular, 0 is a purely imaginary number as well. So, if a matrix has no purely imaginary eigenvalue, then it is invertible.)

1. (2pt) Show that if X_n has no purely imaginary eigenvalue, then X_{n+1} has no purely imaginary eigenvalue. (So our inductive definition makes sense.)
2. (3pt) If A is 1×1 , and it is not purely imaginary, show that X_n indeed converge to $\text{sign}(A)$. (This question has little to do with linear algebra....) (Hint: $\frac{f(x)-1}{f(x)+1} = (\frac{x-1}{x+1})^2$ where $f(x) = \frac{1}{2}(x + \frac{1}{x})$.)
3. (3pt) If A is diagonalizable and has no purely imaginary eigenvalue, show that X_n indeed converge to $\text{sign}(A)$. (Not part of this problem. But diagonalizable matrices are dense, so you can imagine that this is true in general.)
4. (3pt) Suppose A is an $n \times n$ Jordan block with eigenvalue 1 . Show that $X_{n-1} = \text{sign}(A)$.