

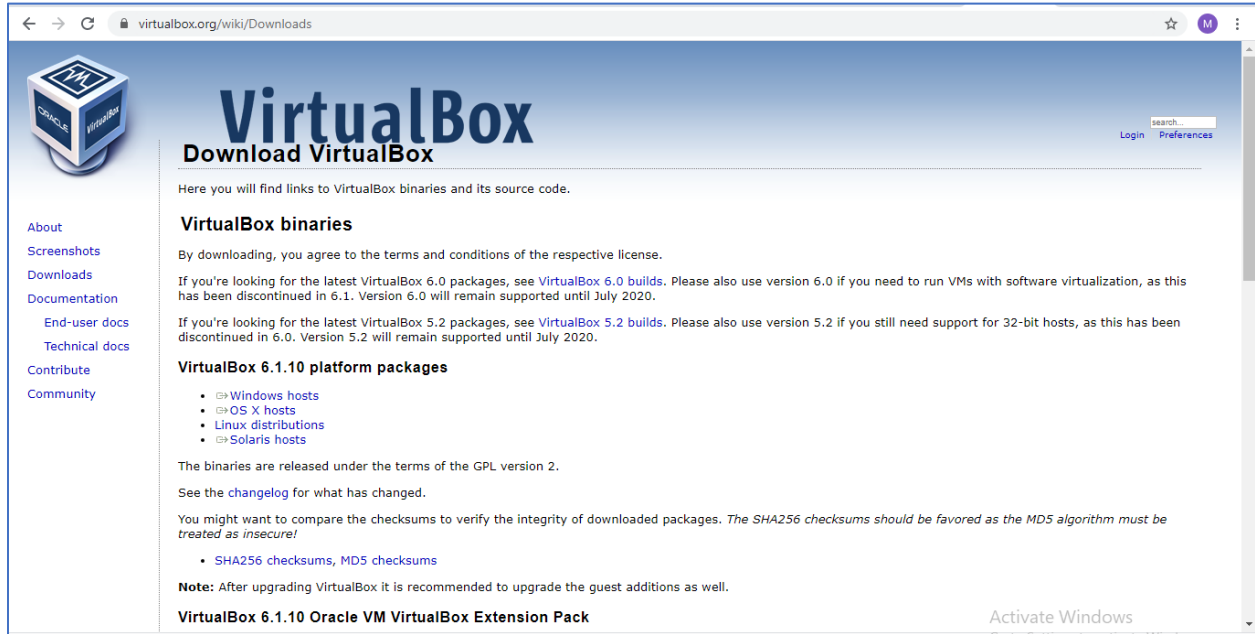
كيفية تحميل نظام Ubuntu

How to install Ubuntu OS

1. نبدأ بتحميل Virtual Box ثم تثبيته.

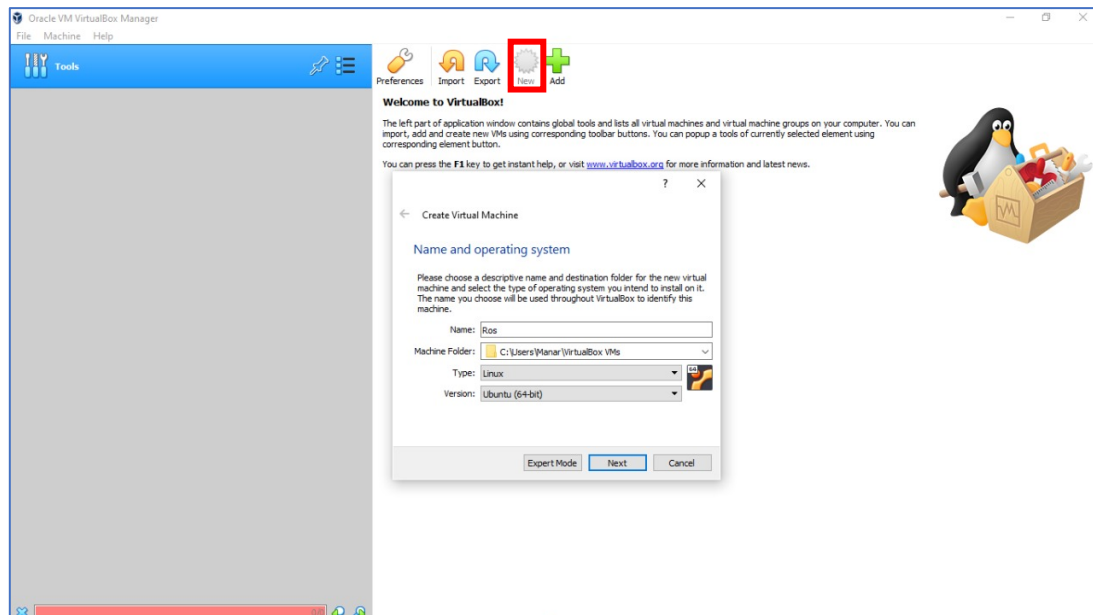
1. Download Virtual Box then install it.

رابط التحميل / Download link: <https://www.virtualbox.org/wiki/Downloads>



2. انقر على New ثم قم بكتابة Name واختر Type: Linux و Version: ubuntu في الاخير انقر على Next.

2. Click on New then write the Name and choose Type: Linux and Version: ubuntu after that click on Next.



← Create Virtual Machine

Memory size

Select the amount of memory (RAM) in megabytes to be allocated to the virtual machine.

The recommended memory size is **1024 MB**.

4 MB 8192 MB

Σ 0 . 0 1 2 MB

Next Cancel

?

X

← Create Virtual Machine

Hard disk

If you wish you can add a virtual hard disk to the new machine. You can either create a new hard disk file or select one from the list or from another location using the folder icon.

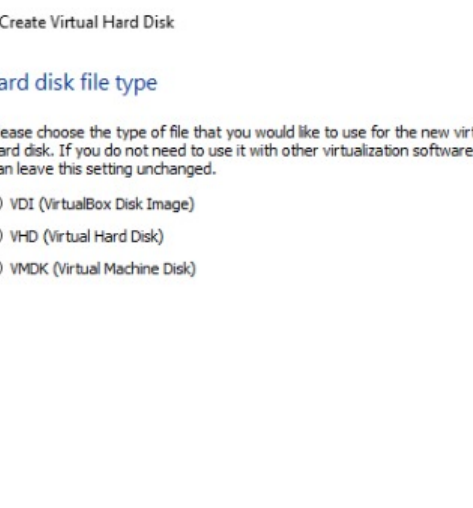
If you need a more complex storage set-up you can skip this step and make the changes to the machine settings once the machine is created.

The recommended size of the hard disk is **10.00 GB**.

☐ Do not add a virtual hard disk
☒ Create a virtual hard disk now
☐ Use an existing virtual hard disk file

Empty

Create Cancel



?

×

← Create Virtual Hard Disk

Hard disk file type

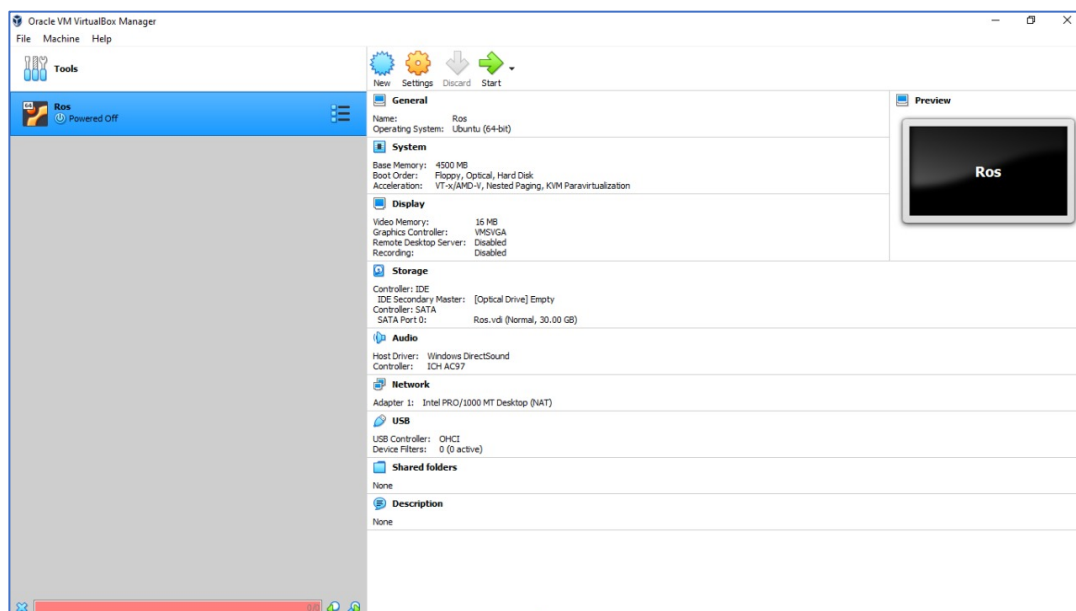
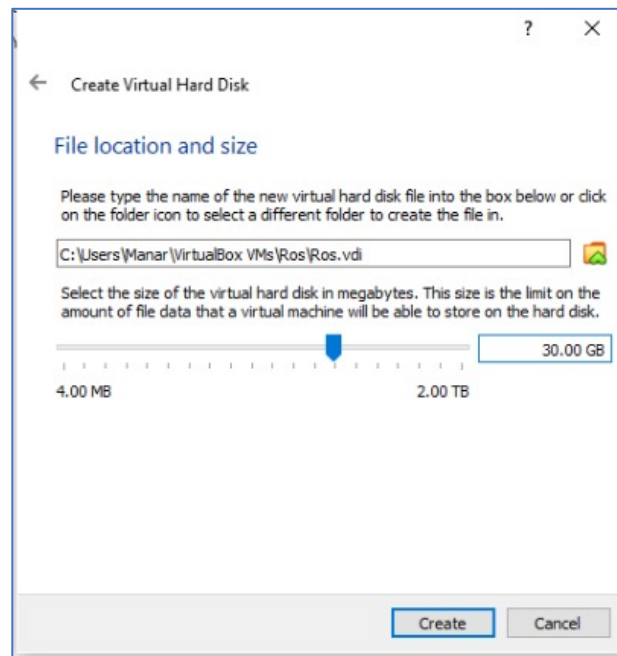
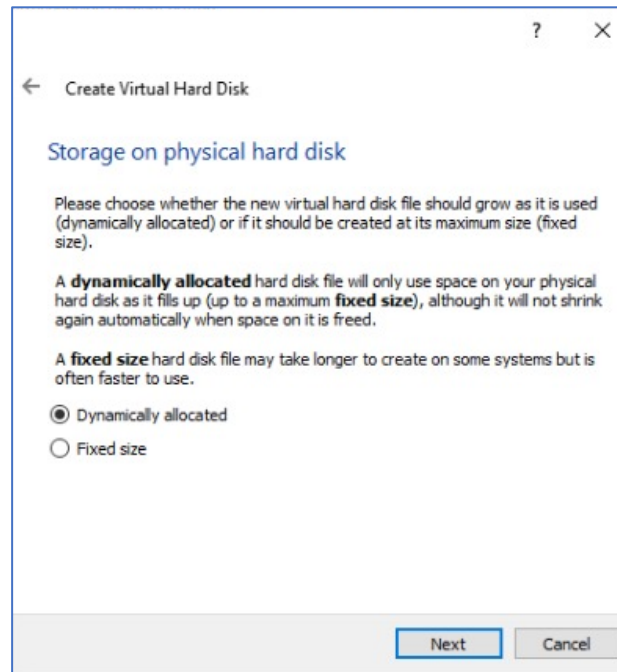
Please choose the type of file that you would like to use for the new virtual hard disk. If you do not need to use it with other virtualization software you can leave this setting unchanged.

☒ VDI (VirtualBox Disk Image)

☐ VHD (Virtual Hard Disk)

☐ VMDK (Virtual Machine Disk)

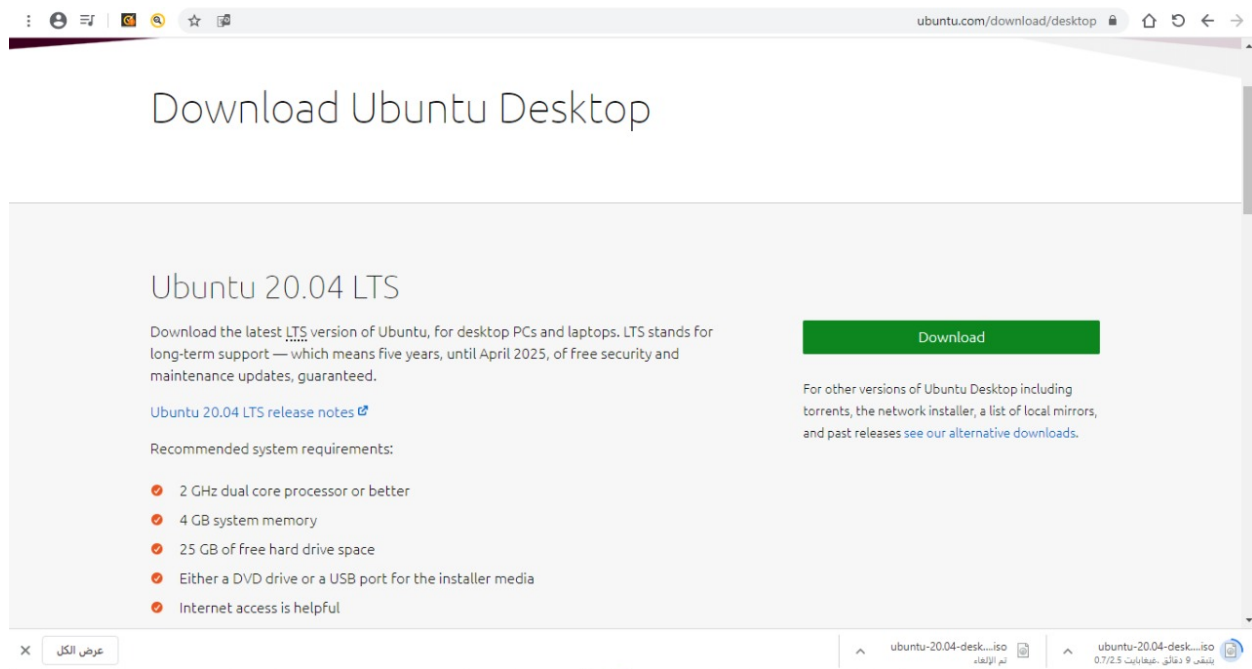
Expert Mode **Next** Cancel



3. الآن نبدأ بتحميل Ubuntu

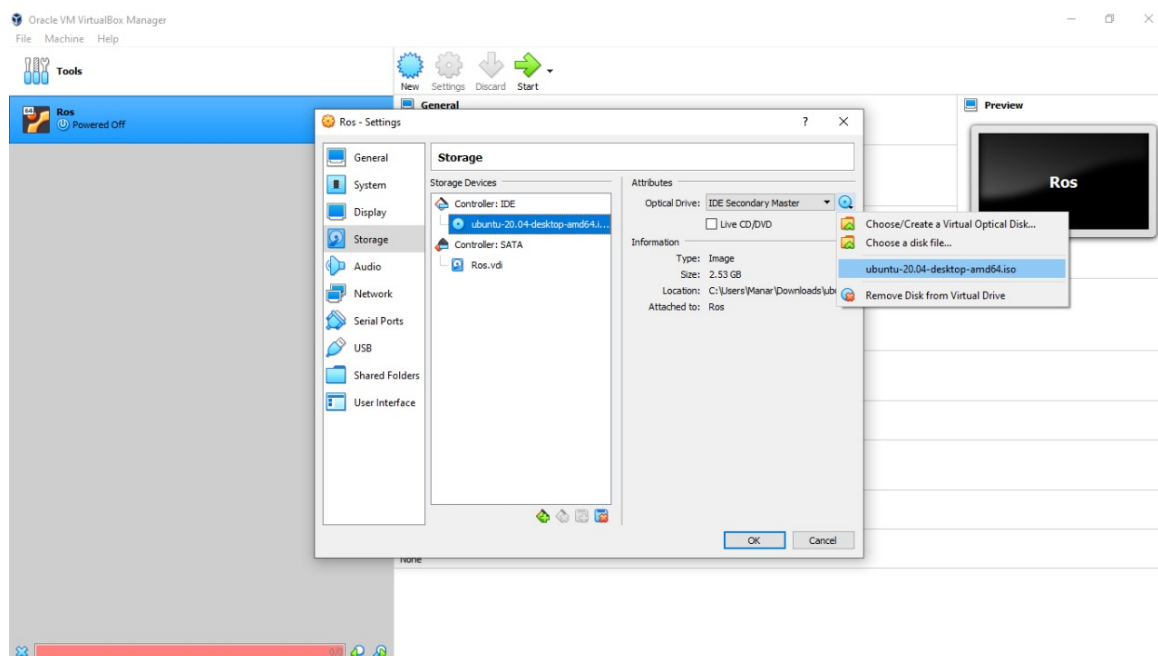
3. Now download Ubuntu

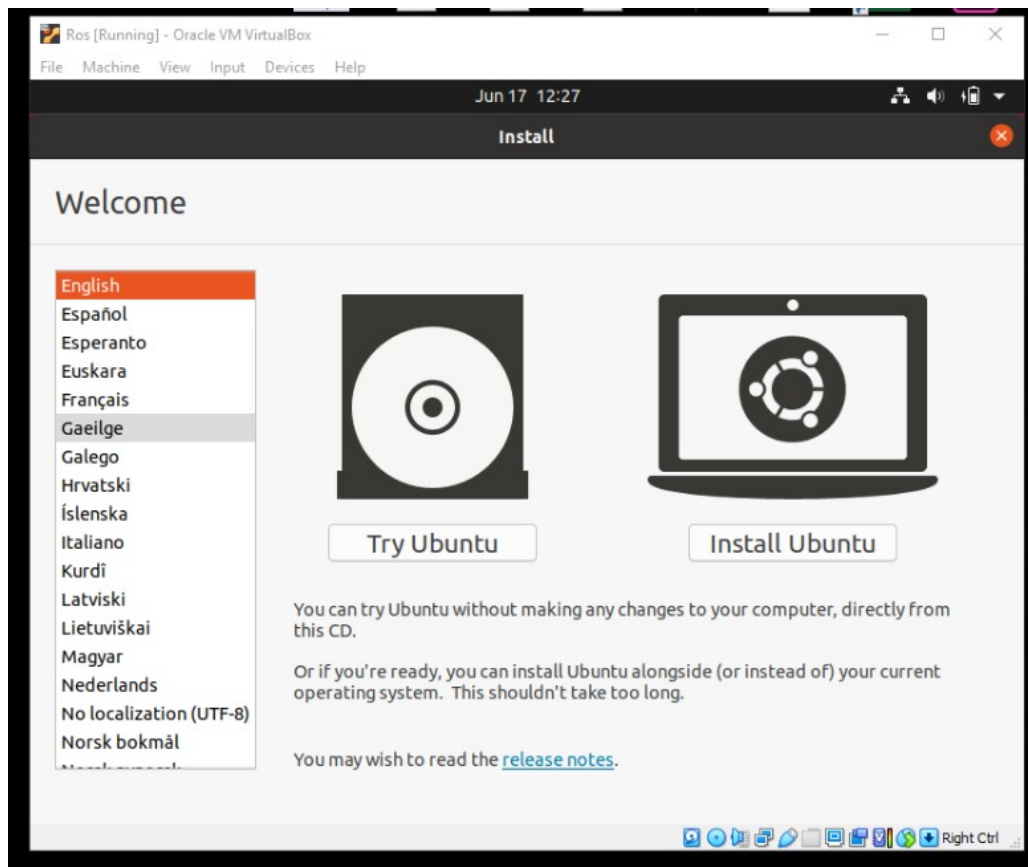
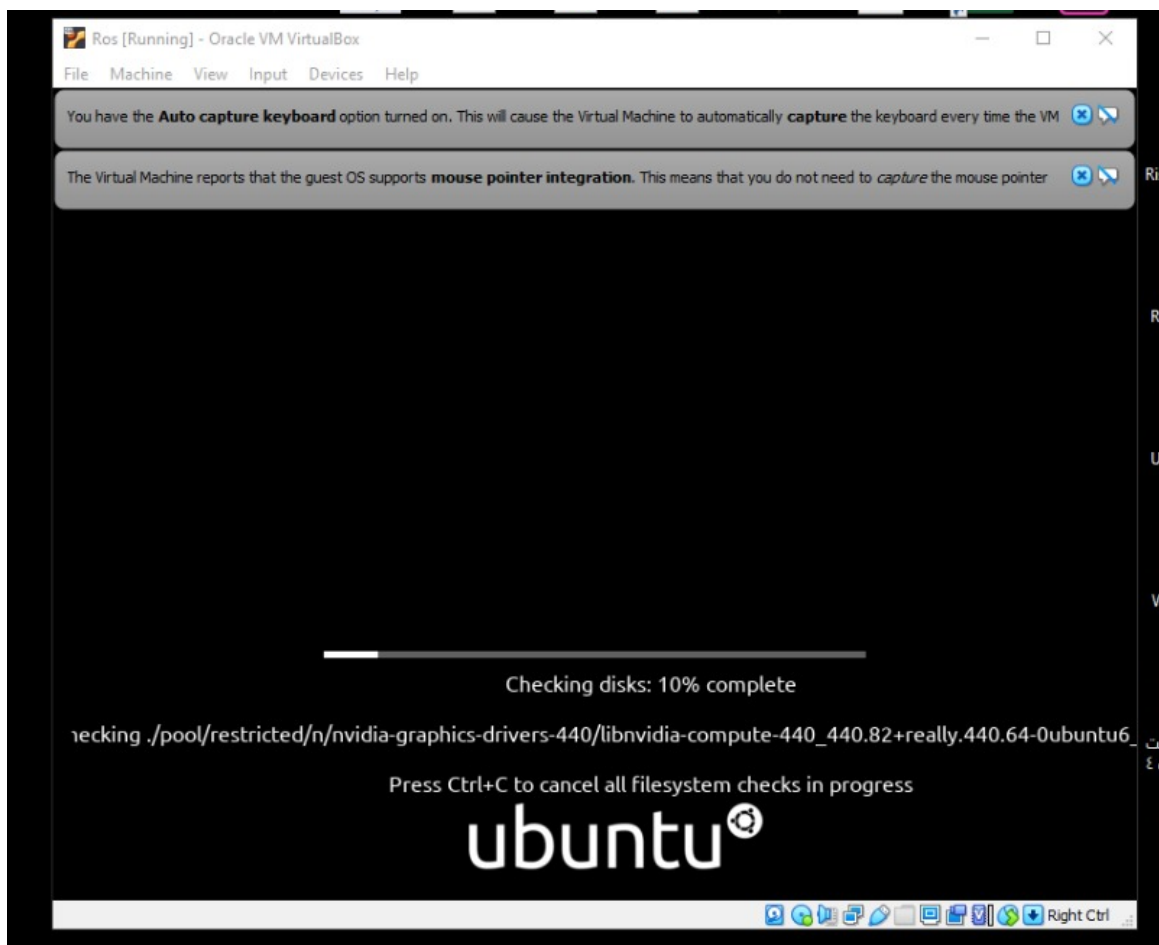
رابط التحميل / Download link : <https://ubuntu.com/download/desktop>

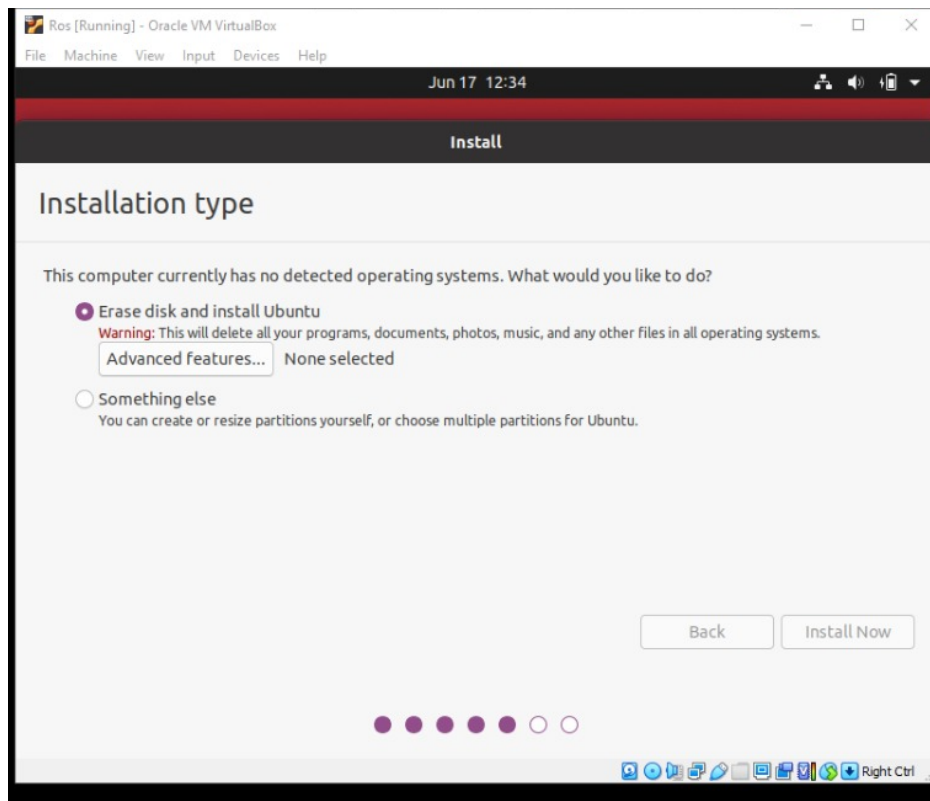
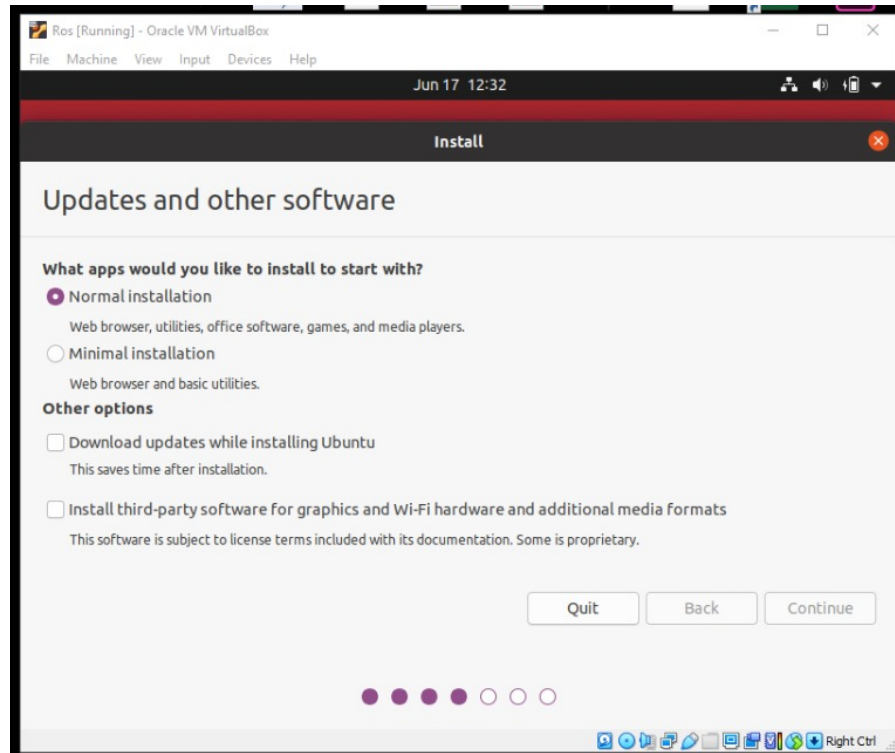


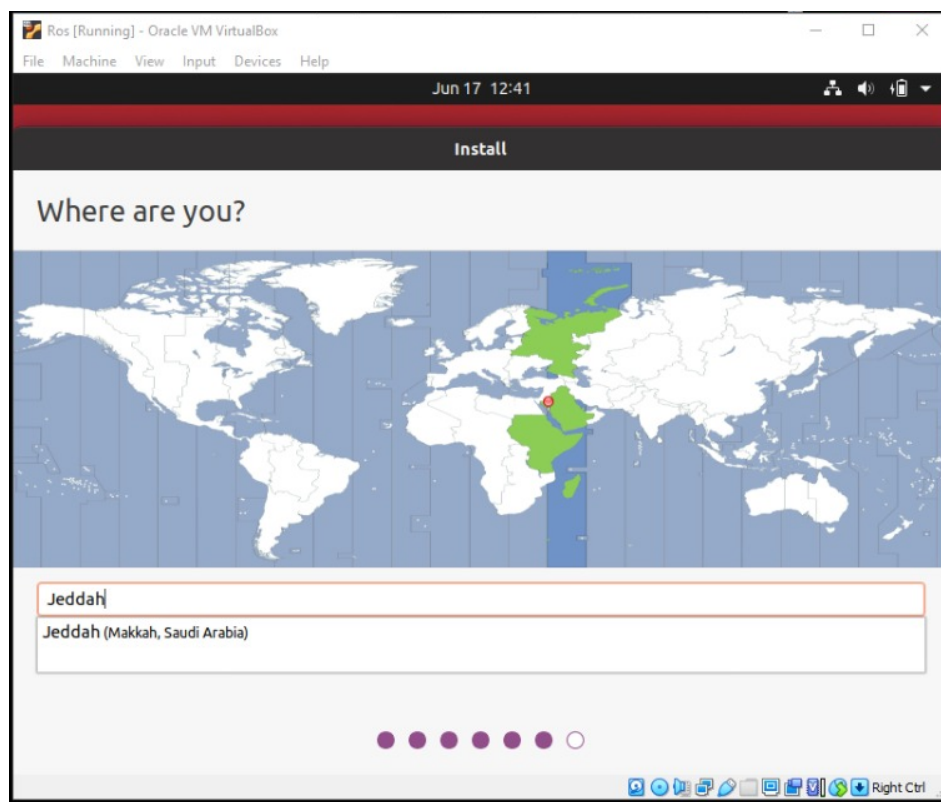
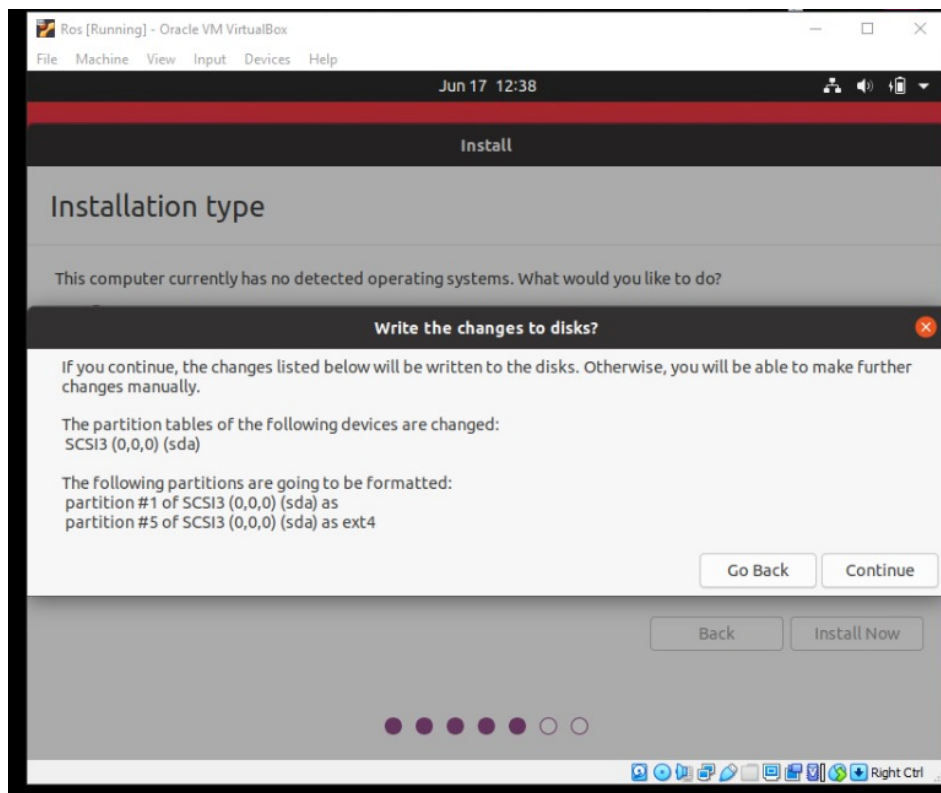
3. بعد الانتهاء من تحميل Ubuntu. انقر على Setting ثم Storage ثم اختر Ubuntu في حال لم يكن ظاهر لك فقم باختياره من Choose a disk file

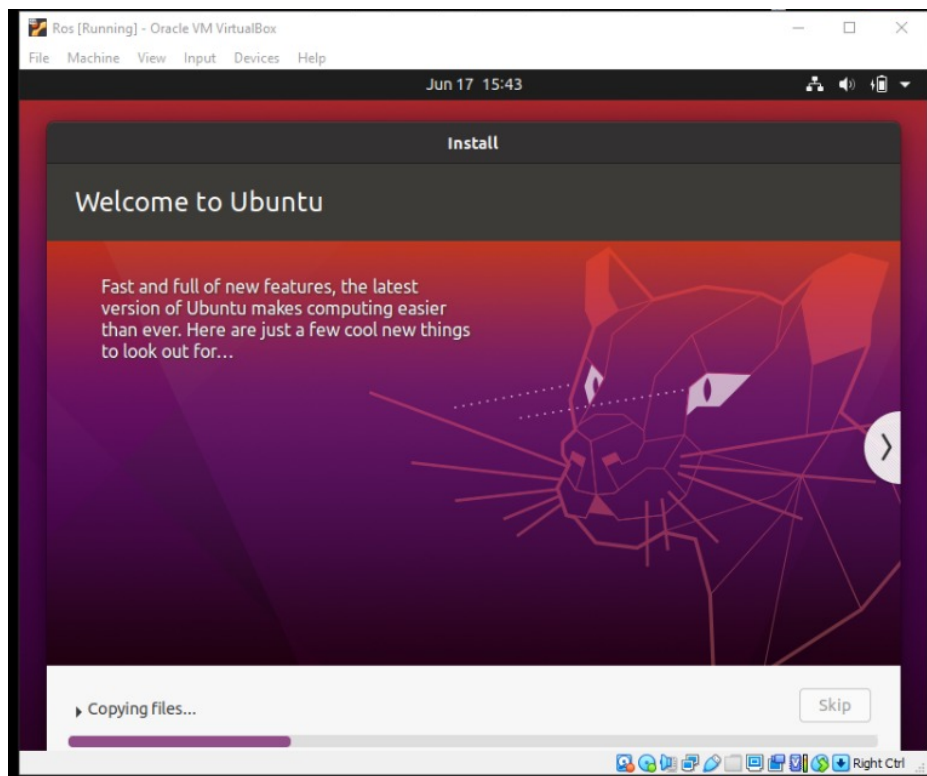
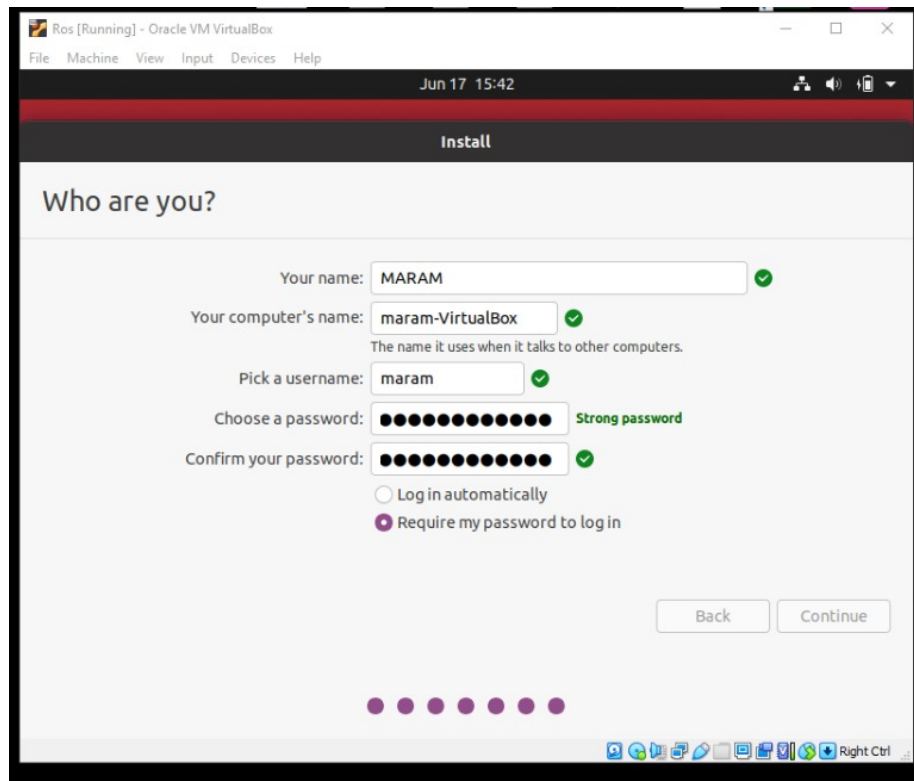
4. After completing the download of Ubuntu. Click on Setting then Storage then choose Ubuntu, if it is not apparent to you click on Choose a disk file

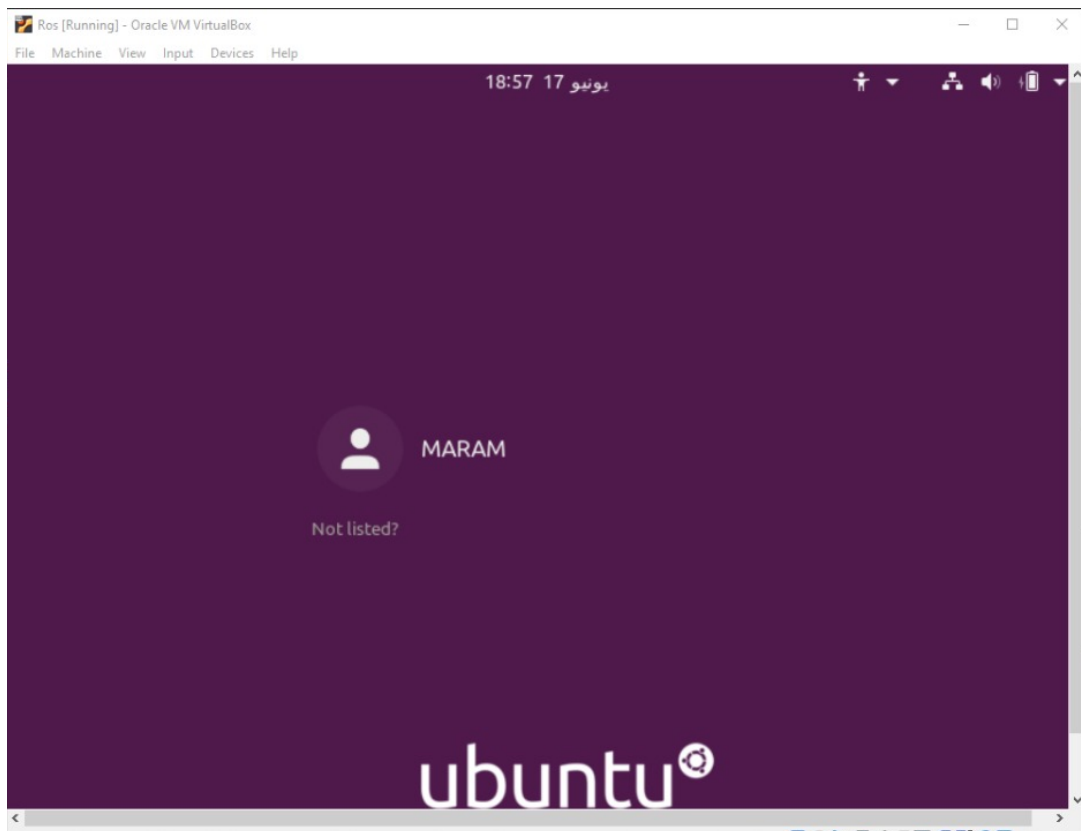
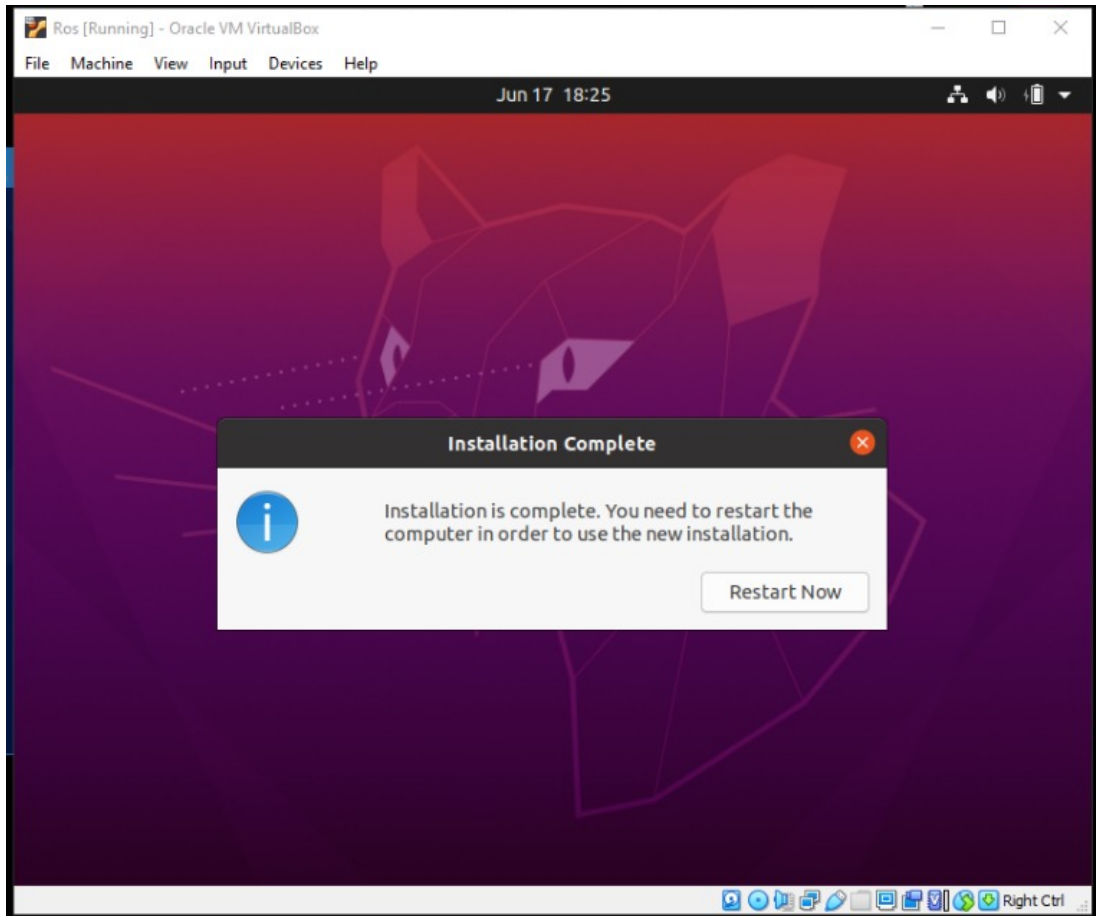












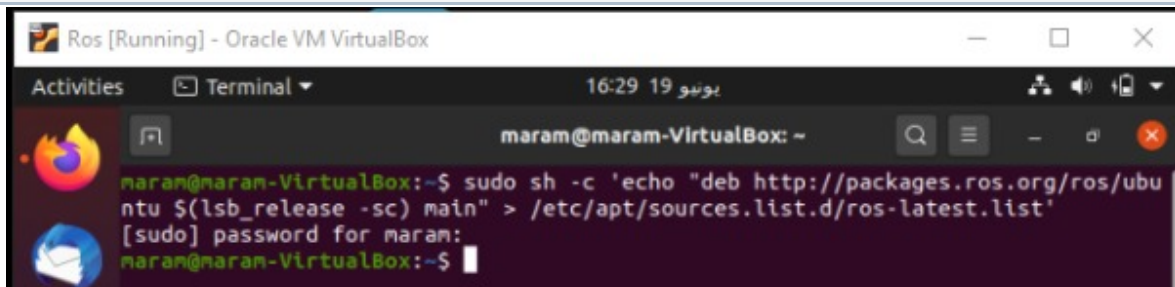
كيفية تحميل نظام ROS على نظام Ubuntu

How to install ROS on Ubuntu OS

- 1- Open Terminal then write the command for Set-up your computer to accept software from packages.ros.org.

١- قم بفتح Terminal ثم قم بكتابة أمر إعداد الكمبيوتر لقبول البرامج.

```
sudo sh -c 'echo "deb http://packages.ros.org/ros/ubuntu $(lsb_release -sc) main" > /etc/apt/sources.list.d/ros-latest.list'
```

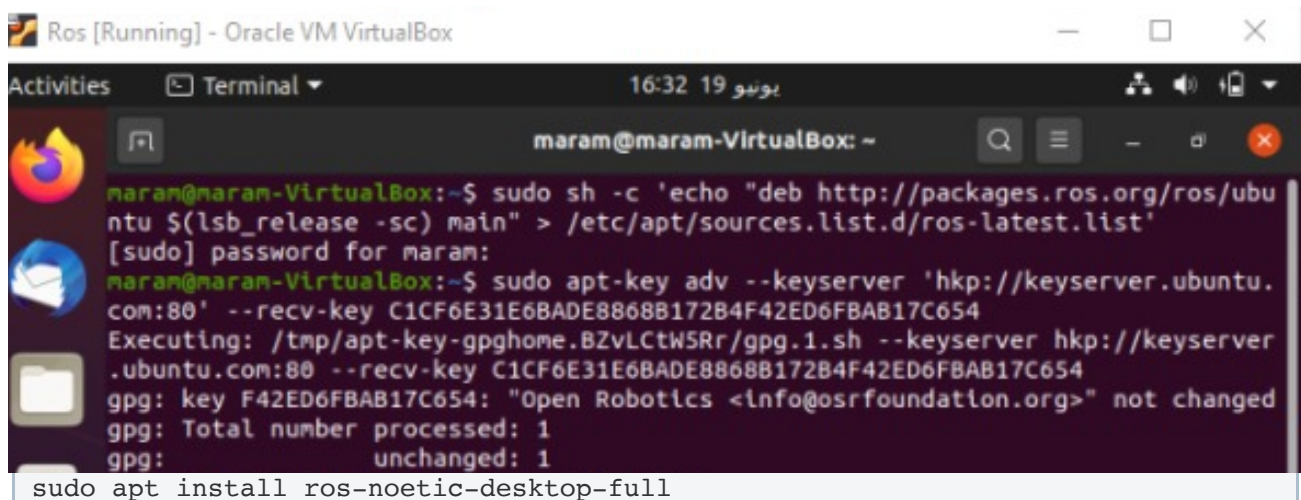


The screenshot shows a terminal window titled 'Ros [Running] - Oracle VM VirtualBox'. The terminal output shows the command being executed: `sudo sh -c 'echo "deb http://packages.ros.org/ros/ubuntu $(lsb_release -sc) main" > /etc/apt/sources.list.d/ros-latest.list'`. The prompt is `maram@maram-VirtualBox: ~`. The user is prompted for a password, and the command is successfully executed.

- 2- Set up your keys

٢- قم بكتابة الأوامر التالية لبداية التحميل

```
url -sSL 'http://keyserver.ubuntu.com/pks/lookup?op=get&search=0xC1CF6E31E6BADE8868B172B4F42ED6FBAB17C654' | sudo apt-key add -  
sudo apt-get update
```



The screenshot shows a terminal window titled 'Ros [Running] - Oracle VM VirtualBox'. The terminal output shows the command being executed: `url -sSL 'http://keyserver.ubuntu.com/pks/lookup?op=get&search=0xC1CF6E31E6BADE8868B172B4F42ED6FBAB17C654' | sudo apt-key add -`. The prompt is `maram@maram-VirtualBox: ~`. The user is prompted for a password, and the command is successfully executed. The output shows the key being added and the package list being updated. The final command shown is `sudo apt install ros-noetic-desktop-full`.

```
562::15). - connect (101: Network is unreachable) [IP: 91.189.91.38 80]
E: Failed to fetch http://sa.archive.ubuntu.com/ubuntu/pool/main/libv/libvdpau/
vdpau-driver-all_1.3-1ubuntu2_amd64.deb Cannot initiate the connection to sa.a
rchive.ubuntu.com:80 (2001:67c:1360:8001::23). - connect (101: Network is unrea
achable) Cannot initiate the connection to sa.archive.ubuntu.com:80 (2001:67c:15
62::18). - connect (101: Network is unreachable) Cannot initiate the connection
to sa.archive.ubuntu.com:80 (2001:67c:1360:8001::24). - connect (101: Network
is unreachable) Cannot initiate the connection to sa.archive.ubuntu.com:80 (200
1:67c:1562::15). - connect (101: Network is unreachable) [IP: 91.189.91.38 80]
E: Failed to fetch http://sa.archive.ubuntu.com/ubuntu/pool/universe/p/proj/pro
j-bin_6.3.1-1_amd64.deb Cannot initiate the connection to sa.archive.ubuntu.co
m:80 (2001:67c:1360:8001::23). - connect (101: Network is unreachable) Cannot i
nitiate the connection to sa.archive.ubuntu.com:80 (2001:67c:1562::18). - conne
ct (101: Network is unreachable) Cannot initiate the connection to sa.archive.u
buntu.com:80 (2001:67c:1360:8001::24). - connect (101: Network is unreachable)
Cannot initiate the connection to sa.archive.ubuntu.com:80 (2001:67c:1562::15).
- connect (101: Network is unreachable) [IP: 91.189.91.38 80]
E: Unable to fetch some archives, maybe run apt-get update or try with --fix-mi
ssing?
naram@naram-VirtualBox:~$ sudo apt-get update
```

```
longer has a Release file.
N: Updating from such a repository can't be done securely, and is therefore dis
abled by default.
N: See apt-secure(8) manpage for repository creation and user configuration det
ails.
naram@naram-VirtualBox:~$ sudo apt install ros-noetic-desktop-full
Reading package lists... Done
Building dependency tree
Reading state information... Done
The following additional packages will be installed:
  autoconf automake autopoint autotools-dev binfmt-support blt bzip2-doc
  cmake cmake-data comerr-dev cpp-8 curl cython3 debhelper
  default-libmysqlclient-dev dh-autoreconf dh-strip-nondeterminism dwz
  glibc-source glibc-source-base glibc-source-dev glibc-source-dev-bin glibc-s
  ...
```

```
ros-noetic-turtle-tf ros-noetic-turtle-tf2 ros-noetic-turtlesim
ros-noetic-urdf ros-noetic-urdf-parser-plugin ros-noetic-urdf-sim-tutorial
ros-noetic-urdf-tutorial ros-noetic-vision-opencv
ros-noetic-visualization-marker-tutorials ros-noetic-visualization-msgs
ros-noetic-visualization-tutorials ros-noetic-viz
ros-noetic-webkit-dependency ros-noetic-xacro ros-noetic-xmllrpcpp ruby
ruby-minitest ruby-net-telnet ruby-power-assert ruby-test-unit ruby-xmllrpc
ruby2.7 rubygems-integration sbcl sdfORMAT9-sdf shiboken2 tango-icon-theme
tcl tcl-dev tcl-vtk7 tcl8.6 tcl8.6-dev tk tk-dev tk8.6 tk8.6-blt2.5
tk8.6-dev ttf-bitstream-vera ttf-dejavu-core unixodbc-dev va-driver-all
vdpau-driver-all vtk7 wayland-protocols x11proto-core-dev x11proto-dev
x11proto-input-dev x11proto-randr-dev x11proto-record-dev
x11proto-scrnsaver-dev x11proto-xext-dev x11proto-xinerama-dev
xorg-sgml-doctools xtrans-dev
0 upgraded, 952 newly installed, 1 to remove and 12 not upgraded.
Need to get 244 MB/511 MB of archives.
After this operation, 2484 MB of additional disk space will be used.
Do you want to continue? [Y/n] y
```

3- After the installation process, now we configure the environment.

٣- بعد عملية التنصيب ، نقوم الآن بعملية التهيئة.

```
source /opt/ros/noetic/setup.bash
```



```
echo "source /opt/ros/noetic/setup.bash" >> ~/.bashrc
source ~/.bashrc
echo "source /opt/ros/noetic/setup.zsh" >> ~/.zshrc
source ~/.zshrc
```

4- The last step: Create ROS packages

٤- الخطوة الأخيرة: إنشاء ملفات ROS

```
cd Documents/
mkdir wallE_ws
cd wallE_ws/
mkdir src
cd src/
catkin_init_workspace
ls
cd ..
ls
catkin_make
ls
ls build/
ls devel/
ls src/
cd src/
catkin_create_pkg rebot_tutorials rospy roscpp std_msgs
ls
ls rebot_tutorials/
cd ..
catkin_make
```



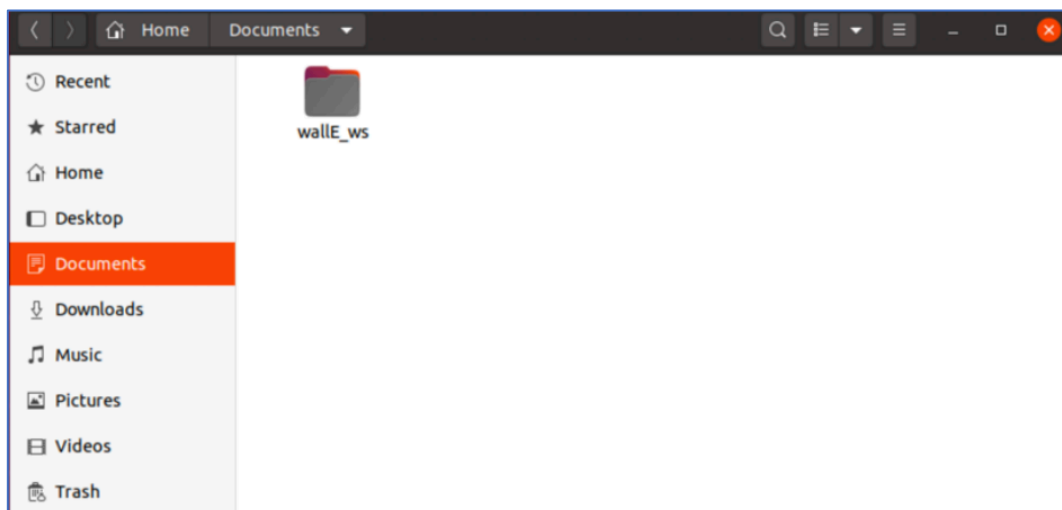
```
maram@maram-VirtualBox:~$ source /opt/ros/noetic/setup.bash
maram@maram-VirtualBox:~$ echo "source /opt/ros/noetic/setup.bash" >> ~/.bashrc
maram@maram-VirtualBox:~$ source ~/.bashrc
maram@maram-VirtualBox:~$ echo "source /opt/ros/noetic/setup.zsh" >> ~/.zshrc
maram@maram-VirtualBox:~$ source ~/.zshrc
bash: cd: -q: invalid option
cd: usage: cd [-L|[-P [-e]] [-@]] [dir]
emulate: command not found
maram@maram-VirtualBox:~$ cd Documents/
maram@maram-VirtualBox:~/Documents$ mkdir wallE_ws
maram@maram-VirtualBox:~/Documents$ cd wallE_ws/
maram@maram-VirtualBox:~/Documents/wallE_ws$ mkdir src
maram@maram-VirtualBox:~/Documents/wallE_ws$ cd src/
maram@maram-VirtualBox:~/Documents/wallE_ws/src$ catkin_init_workspace
Creating symlink "/home/maram/Documents/wallE_ws/src/CMakeLists.txt" pointing to
"/opt/ros/noetic/share/catkin/cmake/toplevel.cmake"
maram@maram-VirtualBox:~/Documents/wallE_ws/src$ ls
CMakeLists.txt
maram@maram-VirtualBox:~/Documents/wallE_ws/src$ cd ..
maram@maram-VirtualBox:~/Documents/wallE_ws$ ls
src
maram@maram-VirtualBox:~/Documents/wallE_ws$ catkin_make
```

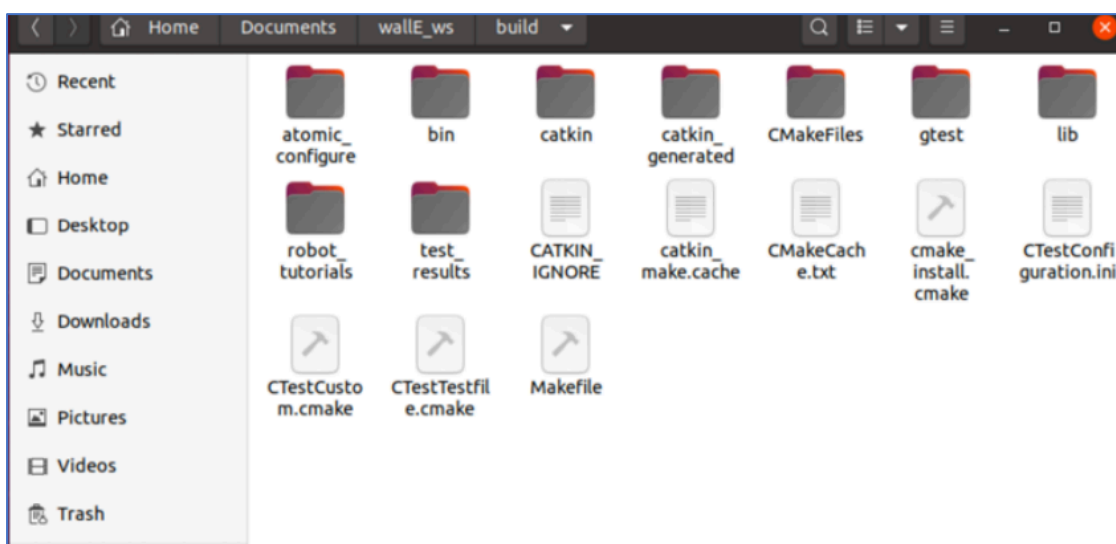
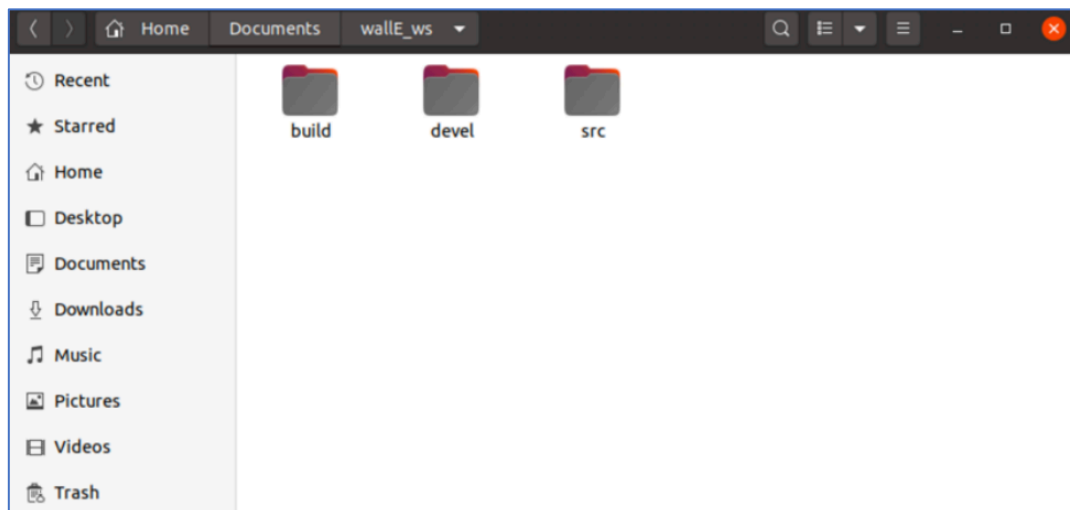
```
#### Running command: "make -j1 -l1" in "/home/maram/Documents/wallE_ws/build"
####
maram@maram-VirtualBox:~/Documents/wallE_ws$ ls
build devel src
maram@maram-VirtualBox:~/Documents/wallE_ws$ ls build/
atomic_configure  CATKIN_IGNORE  cmake_install.cmake  gtest
bin               catkin_make.cache  CTestConfiguration.ini  lib
catkin            CMakeCache.txt   CTestCustom.cmake      Makefile
catkin_generated  CMakeFiles       CTestTestfile.cmake    test_results
maram@maram-VirtualBox:~/Documents/wallE_ws$ ls devel/
cmake.lock  lib          local_setup.sh  setup.bash  _setup_util.py
env.sh      local_setup.bash  local_setup.zsh  setup.sh    setup.zsh
maram@maram-VirtualBox:~/Documents/wallE_ws$ ls src/
CMakeLists.txt
maram@maram-VirtualBox:~/Documents/wallE_ws$ cd src/
maram@maram-VirtualBox:~/Documents/wallE_ws/src$ catkin_create_pkg rebot_tutorial
als rospy roscpp std_msgs
Created file rebot_tutorials/package.xml
Created file rebot_tutorials/CMakeLists.txt
Created folder rebot_tutorials/include/rebot_tutorials
Created folder rebot_tutorials/src
Successfully created files in /home/maram/Documents/wallE_ws/src/rebot_tutorial
s. Please adjust the values in package.xml.
maram@maram-VirtualBox:~/Documents/wallE_ws/src$ ls
CMakeLists.txt  rebot_tutorials
maram@maram-VirtualBox:~/Documents/wallE_ws/src$
maram@maram-VirtualBox:~/Documents/wallE_ws/src$ ls rebot_tutorials/
CMakeLists.txt  include  package.xml  src
maram@maram-VirtualBox:~/Documents/wallE_ws/src$
```

```
als rospy roscpp std_msgs
Created file rebot_tutorials/package.xml
Created file rebot_tutorials/CMakeLists.txt
Created folder rebot_tutorials/include/rebot_tutorials
Created folder rebot_tutorials/src
Successfully created files in /home/maram/Documents/wallE_ws/src/rebot_tutorial
s. Please adjust the values in package.xml.
maram@maram-VirtualBox:~/Documents/wallE_ws/src$ ls
CMakeLists.txt  rebot_tutorials
maram@maram-VirtualBox:~/Documents/wallE_ws/src$
maram@maram-VirtualBox:~/Documents/wallE_ws/src$ ls rebot_tutorials/
CMakeLists.txt  include  package.xml  src
maram@maram-VirtualBox:~/Documents/wallE_ws/src$ cd ..
maram@maram-VirtualBox:~/Documents/wallE_ws$ catkin_make
Base path: /home/maram/Documents/wallE_ws
Source space: /home/maram/Documents/wallE_ws/src
Build space: /home/maram/Documents/wallE_ws/build
Devel space: /home/maram/Documents/wallE_ws/devel
Install space: /home/maram/Documents/wallE_ws/install
####
#### Running command: "cmake /home/maram/Documents/wallE_ws/src -DCATKIN_DEVEL_
PREFIX=/home/maram/Documents/wallE_ws/devel -DCMAKE_INSTALL_PREFIX=/home/maram/
Documents/wallE_ws/install -G Unix Makefiles" in "/home/maram/Documents/wallE_w
s/build"
####
CMake Warning (dev) in CMakeLists.txt:
  No project() command is present.  The top-level CMakeLists.txt file must
  contain a literal, direct call to the project() command.  Add a line of
  code such as
```

هكذا نكون قد انتهينا من انشاء Catkin init workspace

سنجد جميع الملفات الخاصة بالنظام بداخل Documents / wallE_ws





Done by: Maram Alsofiani