

class Base {

int b;

public:

void f1() {..}

};

int main() {
Base objB;

objB

Base :: b

objB.f1(); ✓

b is private. → objB.b = 10; ✗

class Derived : Base {

int d;

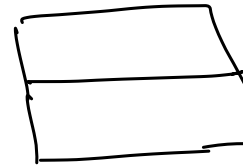
public:

void f2() {..}

};

Derived objD;

objD



Base :: b

Derived :: d

d is private

→ objD.d = 10; ✗
objD.f2(); ✓

b is private

→ Obj D. b = 100; ✗

→ Obj D. f1(); ✗

f1 is private in derived class due to private inheritance.

Class Derived : Public Base {
 int d;
public:
 void f2() { ... }
};

public inheritance

int main() {
 Derived Obj D;

Obj D. f1(); ✓

↑
Derived is inherited publicly so Base class members will retain their access specifiers in Derived class

```
class Base {
```

```
    int b1;
```

```
protected:
```

```
    int b2;
```

```
public:
```

```
    void f1() {
```

```
        b1 = 10; ✓
```

```
        b2 = 20; ✓
```

```
    }
```

```
};
```

```
class Derived : public Base {
```

```
    int d1;
```

```
protected:
```

```
    int d2;
```

```
public:
```

```
    void f2() {
```

```
        d1 = 10; ✓
```

```
        d2 = 20; ✓
```

```
        b1 = 100; ✗
```

```
        b2 = 200; ✓
```

```
        f1(); ✓
```

b1 is
private in
Base and hence
not accessible
in Derived class

this → f1()

f1 is public
in Base

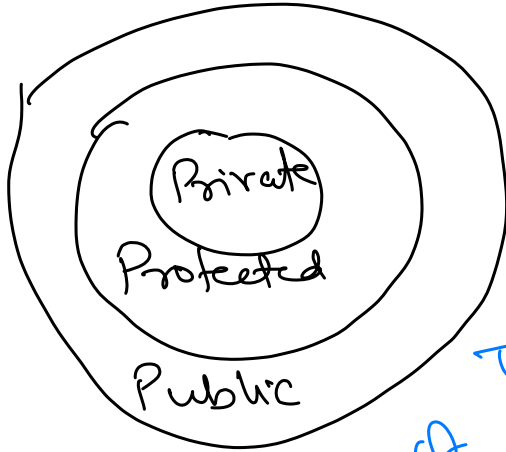
```
int main() {
```

```
Base Obj B;
```

```
Obj B. b1 = 10; ❌ → b1 is private
```

```
Obj B. b2 = 20; ❌ → b2 is protected.
```

Base class
members



Type
of
inheritance

	public	protected	private
public	public	protected	Not accessible
protected	protected	protected	Not accessible
private	private	private	Not accessible

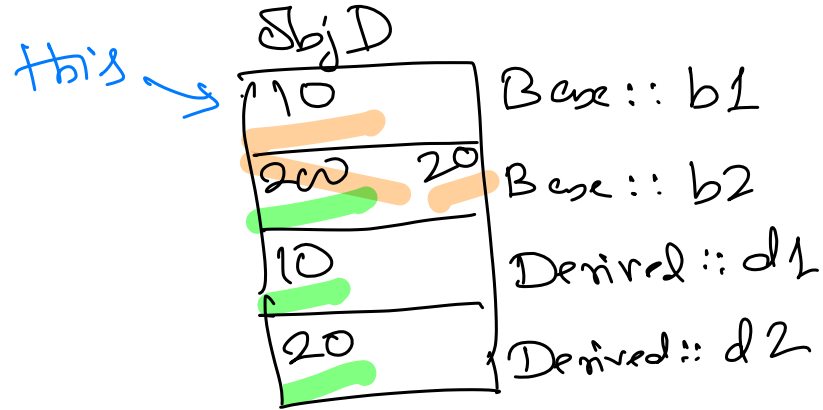
access specifier of Base
class members in Derived class

```
int main() {
```

```
    Derived objD;
```

```
    objD.f2();
```

```
    Base objB;
```



```
class Base {
    int b;
public:
    Base() : b(0) {
        std::cout << "Base default constructor\n";
    }
    ~Base() {
        std::cout << "Base destructor\n";
    }
    void setB(int b) {
        this->b = b;
    }
    int getB() {
        return b;
    }
};
```

```
class Derived : public Base {
    int d;
public:
    Derived() : d(0) {
        std::cout << "Derived default constructor\n";
    }
    ~Derived() {
        std::cout << "Derived destructor\n";
    }
};
```

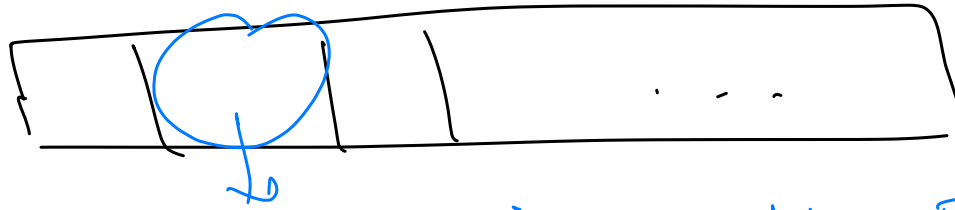
```
void setD(int d) {
    this->d = d;
}
int getD() {
    return d;
}
};

int main() {
    Derived objD;

    objD.setB(10);
    objD.setD(5);

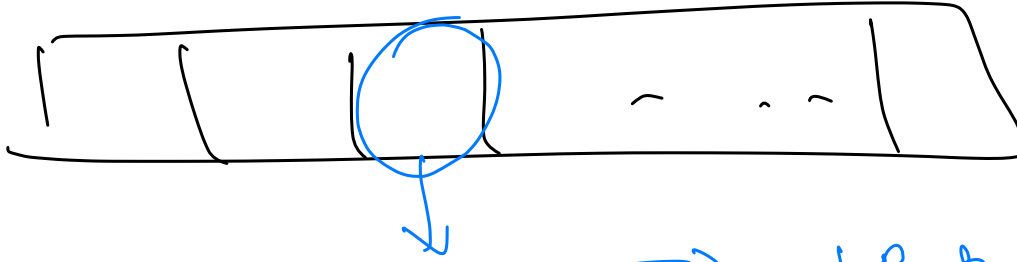
    std::cout << "Size of Base = " << sizeof(Base) << "\n";
    std::cout << "Size of Derived = " << sizeof(Derived) << "\n";
    std::cout << "getB for Derived = " << objD.getB() << "\n";

    return 0;
}
```



$\text{line}^* \Rightarrow \underbrace{\text{line}^*}_{\text{plines}} \text{ plines}[10]$

array whose
each element
will be a
address of
line object



$\text{Rect}^* \Rightarrow \underbrace{\text{Rect}^*}_{\text{pRects}} \text{ pRects}[10]$

array wher
each element
will be a
address of
rect object

Physical size of array \rightarrow How much memory is allocated?

Logical size of array \rightarrow How many elements are stored?


```
struct Point {
    int x;
    int y;
};

class Line {
    Point pts[2];
public:
    Line(int x1, int y1, int x2, int y2);
    ~Line();
    void Move(int cx, int cy);
    void Draw();
};

class Rect {
    Point pts[2];
public:
    Rect(int x1, int y1, int x2, int y2);
    ~Rect();
    void Move(int cx, int cy);
    void Draw();
};
```

```
Line::Line(int x1, int y1, int x2, int y2) {
    std::cout << "Line::Line()\n";
}
Line::~~Line() {
    std::cout << "Line::~~Line()\n";
}
void Line::Move(int cx, int cy) {
    std::cout << "Line::Move()\n";
}
void Line::Draw() {
    std::cout << "Line::Draw()\n";
}

Rect::Rect(int x1, int y1, int x2, int y2) {
    std::cout << "Rect::Rect()\n";
}
Rect::~~Rect() {
    std::cout << "Rect::~~Rect()\n";
}
void Rect::Move(int cx, int cy) {
    std::cout << "Rect::Move()\n";
}
void Rect::Draw() {
    std::cout << "Rect::Draw()\n";
}
```

```
int main() {
    Line* pLines[10];
    int lineCount = 0;

    Rect* pRects[10];
    int rectCount = 0;

    std::cout << "\nCreating objects\n";
    // Create some objects.
    pLines[lineCount] = new Line(0, 0, 1, 1);
    ++lineCount;
    pLines[lineCount] = new Line(2, 2, 3, 3);
    ++lineCount;

    pRects[rectCount] = new Rect(10, 10, 20, 20);
    ++rectCount;

    std::cout << "\nDrawing objects\n";
    // Draw first line and rect
    pLines[0]->Draw();
    pRects[0]->Draw();

    std::cout << "\nDeleting objects\n";
    // Delete the memory for objects created.
    for (int i = 0; i < lineCount; ++i)
        delete pLines[i];
```

```
for (int i = 0; i < rectCount; ++i)  
    delete pRects[i];
```

```
return 0;
```

```
}
```

```
struct Point {
    int x;
    int y;
};

class Object {
protected:
    Point pts[2];
public:
    Object(int x1, int y1, int x2, int y2);
    ~Object();
    void Move(int cx, int cy);
    void Draw();
};

class Line : public Object {
public:
    Line(int x1, int y1, int x2, int y2);
    ~Line();
    void Draw();
};

class Rect : public Object {
public:
    Rect(int x1, int y1, int x2, int y2);
    ~Rect();
    void Draw();
};
```

```
Object::Object(int x1, int y1, int x2, int y2) {
    std::cout << "Object::Object()\n";
}
Object::~~Object() {
    std::cout << "Object::~~Object()\n";
}
void Object::Move(int cx, int cy) {
    std::cout << "Object::Move()\n";
}
void Object::Draw() {
    std::cout << "Object::Draw()\n";
}
```

```
Line::Line(int x1, int y1, int x2, int y2) : Object(x1, y1, x2, y2) {
    std::cout << "Line::Line()\n";
}
Line::~~Line() {
    std::cout << "Line::~~Line()\n";
}
void Line::Draw() {
    std::cout << "Line::Draw()\n";
}
```

```
Rect::Rect(int x1, int y1, int x2, int y2) : Object(x1, y1, x2, y2) {
    std::cout << "Rect::Rect()\n";
}
```

```

Rect::~~Rect() {
    std::cout << "Rect::~~Rect()\n";
}
void Rect::Draw() {
    std::cout << "Rect::Draw()\n";
}

```

```

int main() {
    Object* pObjects[20];
    int objectCount = 0;

```

Due to inheritance each Derived class object has a base class object in it \Rightarrow address of

```

// Create some lines and rectangles in some order
std::cout << "\nCreating Line\n";
pObjects[objectCount++] = new Line(0, 0, 1, 1);
std::cout << "\nCreating Rect\n";
pObjects[objectCount++] = new Rect(1, 1, 2, 2);
std::cout << "\nCreating Rect\n";
pObjects[objectCount++] = new Rect(10, 10, 20, 20);
std::cout << "\nCreating Line\n";
pObjects[objectCount++] = new Line(5, 5, 10, 10);

```

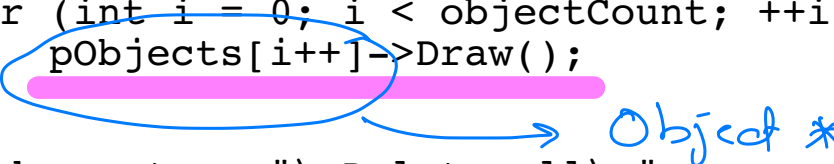
```

std::cout << "\nMove first line\n";
// Move first line
pObjects[0]->Move(10, 10);

```

Derived class object can be stored in Base class pointer/reference

```
std::cout << "\nDraw all\n";  
// Draw all objects in the order of creation.  
for (int i = 0; i < objectCount; ++i) {  
    pObjects[i++] -> Draw();  
}  
  
std::cout << "\nDelete all\n";  
// Delete the memory for objects created.  
for (int i = 0; i < objectCount; ++i) {  
    delete pObjects[i];  
}  
  
return 0;  
}
```



Object *


```
class Base {
```

```
    int b;
```

```
public:
```

```
    void f1() {..}
```

```
    void f2() {..}
```

```
};
```

```
class Derived : public Base {
```

```
    int d;
```

```
public:
```

```
    void g1() {..}
```

```
    void f2() {..}
```

```
};
```


function  overriding

```
int main() {
```

```
    Base obj B;
```

```
    Derived obj D;
```

obj B . f2();
Base


Base :: f2

obj D . f1();
Derived


Base :: f1

obj D . f2()
Derived

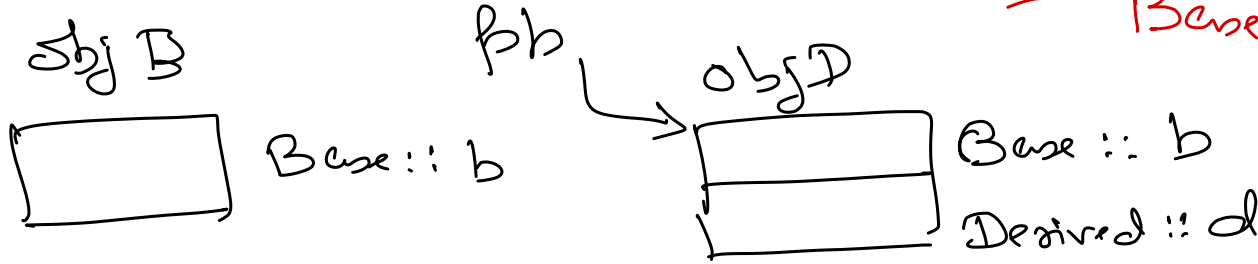

Derived :: f2

Base * pb = &objD;

Object slicing

Obj D. Base::f2C);
Derived

Base::f2



Base class
pointer/
reference
pointing or
referencing to
Derived class
object

pb → d = 10;
Base *

Is d a
member of Base? NO

pb → f2(); ✓ ⇒ Base::f2
Base *

↑
Is f2 a
member A Base? YES

Is it accessible? YES

Base * pb1 = new Derived();
Base::Base()
Derived::Derived()



delete pb1;
Base * ⇒ Base::~~Base()


```
void swap(int& a, int &b) {
    int t;

    t = a; a = b; b = t;
}
void swap(float& a, float &b) {
    float t;

    t = a; a = b; b = t;
}

int main() {
    int x = 10, y = 20;
    std::cout << "Before swap x = " << x << ", y = " << y << "\n";
    swap(x, y);
    std::cout << "After swap  x = " << x << ", y = " << y << "\n";

    float f1 = 1.5, f2 = 2.5;
    std::cout << "Before swap f1 = " << f1 << ", f2 = " << f2 << "\n";
    swap(f1, f2);
    std::cout << "After swap  f1 = " << f1 << ", f2 = " << f2 << "\n";

    return 0;
}
```

```
template<class T>
void swap(T& a, T& b) {
    std::cout << "Calling template function\n";

    T t;

    t = a; a = b; b = t;
}

int main() {
    int x = 10, y = 20;
    std::cout << "\nBefore swap x = " << x << ", y = " << y << "\n";
    swap(x, y);
    std::cout << "After swap  x = " << x << ", y = " << y << "\n";

    float f1 = 1.5, f2 = 2.5;
    std::cout << "\nBefore swap f1 = " << f1 << ", f2 = " << f2 << "\n";
    swap(f1, f2);
    std::cout << "After swap  f1 = " << f1 << ", f2 = " << f2 << "\n";

    return 0;
}
```

```
template<class T>
void swap(T& a, T& b) {
    std::cout << "Calling template function\n";

    T t;

    t = a; a = b; b = t;
}

template<>
void swap(float& a, float& b) {
    std::cout << "Calling template specialization for float\n";

    float t;

    t = a; a = b; b = t;
}

int main() {
    int x = 10, y = 20;
    std::cout << "\nBefore swap x = " << x << ", y = " << y << "\n";
    swap(x, y);
    std::cout << "After swap  x = " << x << ", y = " << y << "\n";

    float f1 = 1.5, f2 = 2.5;
    std::cout << "\nBefore swap f1 = " << f1 << ", f2 = " << f2 << "\n";
```

```
swap(f1, f2);  
std::cout << "After swap  f1 = " << f1 << ", f2 = " << f2 << "\n";  
  
return 0;  
}
```