

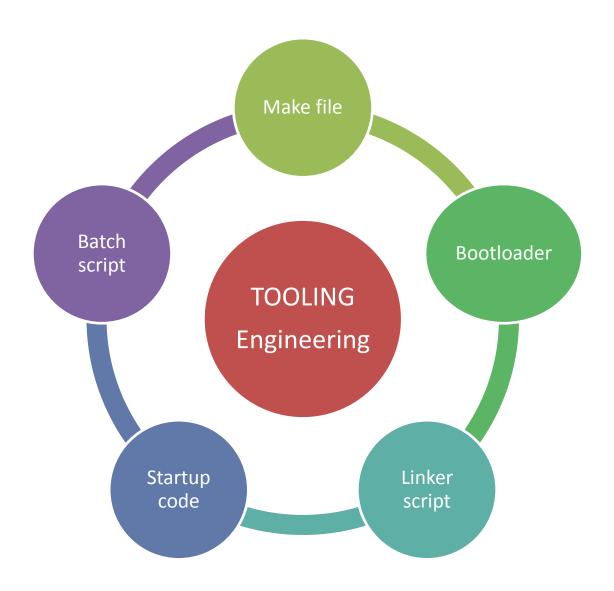
Embedded Systems

TOOLING

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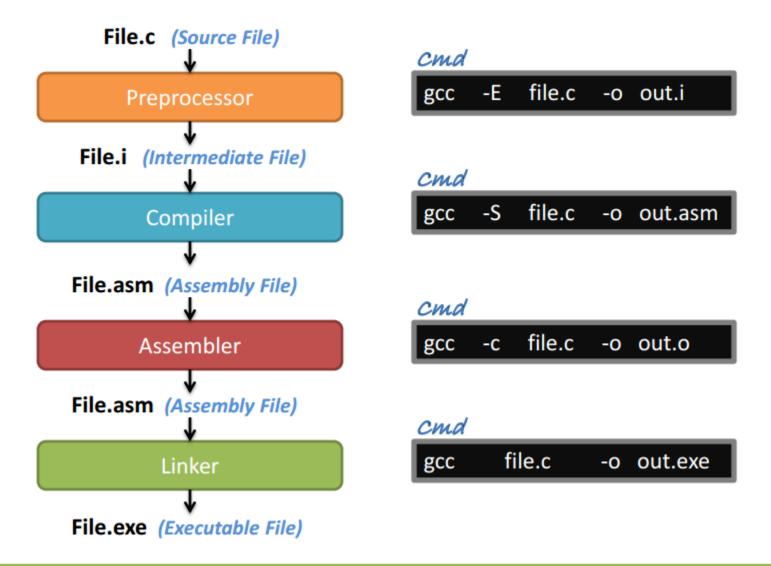


### TOOLING ENGINEERING





# Let's recap C Building Process

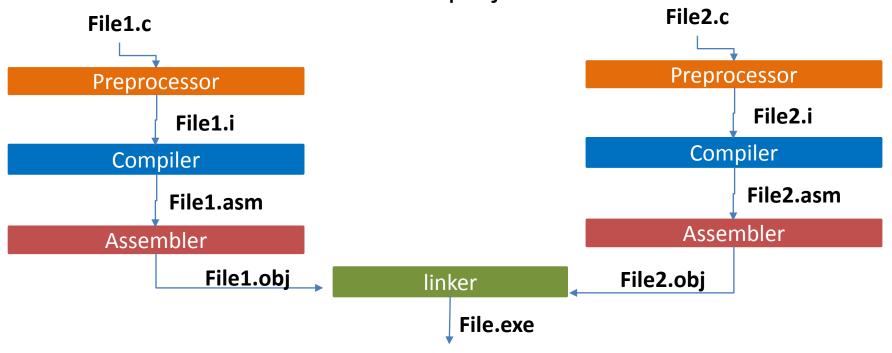




# Let's recap C Building Process

What 's the difference between object file and executable file?

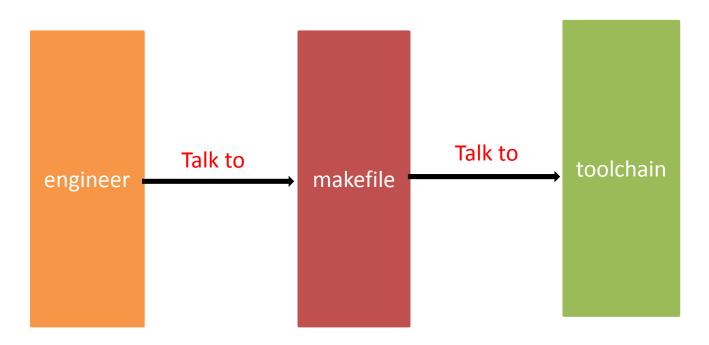
Object file and Executable file are both written in binary (0&1) but the difference is clear when we have more than one file (file1.c,file2.c,....) in this case every c file has its own object file but one executable file for the whole project.





# Make file

Now if we want to debug our code we need to write each command by ourselves and this leads us to execute more effort so we can make use of a magic tool between the user and toolchain, at this case the user sends one command only to this magic tool which in turn sends the required commands to the toolchain. This magic tool is called the (makefile).





# Make file

#### Rules:

1-(makefile ) all letters are lower case and without spaces

2- the file has no extensions.

#### makefile

Rule name : dependencies

tap command

Rule name: This is the word that I want to

write to generate makefile

dependencies: This is the used c file

command: This is the command that you

want to be generated.

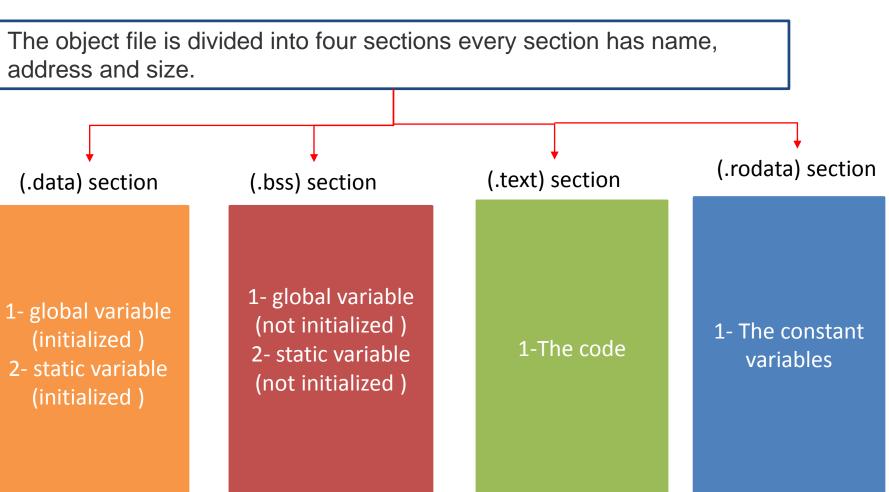


#### **Batch file**

The batch file is similar to makefile but without sending any commands by this method you create (file.bat) and write all the same commands that you write in makefile and then you can double click on this file to execute all commands in this file.



## Object file sections





## Symbol table

This table is generated with each object file. It defines which of the global components(variables, functions,....) is needed or provided.

### Symbol table

Func1	needed
Func2	provided
Х	provided

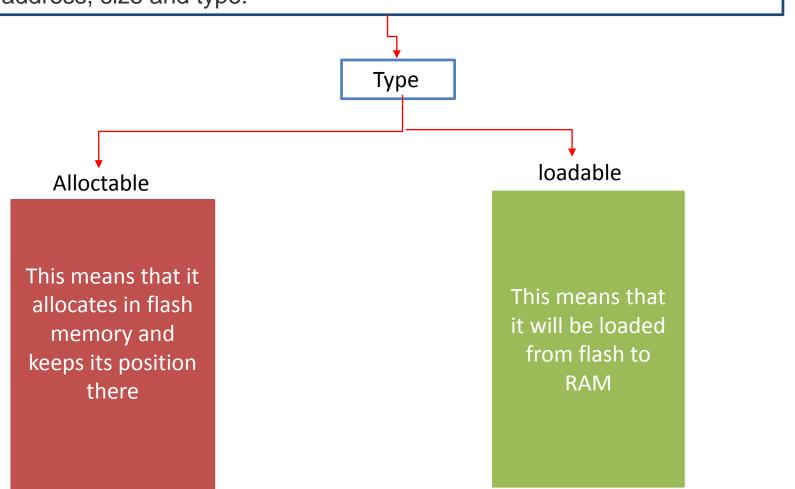
Func1: the owner file has its prototype but it needs the implementation of the function which is located in another file

Func2: the owner file has the implementation of the function



### **Executable file section**

The executable file is divided into five sections every section has name, address, size and type.





## Startup code

- Startup code is located in the fifth section that is called (.init). This section is allocated in the first location in the flash. This location is the first code to be executed.

#### - Functions of startup code:

1-load (.data) section from flash to RAM

2-reserve (.bss) section into RAM and initialize it

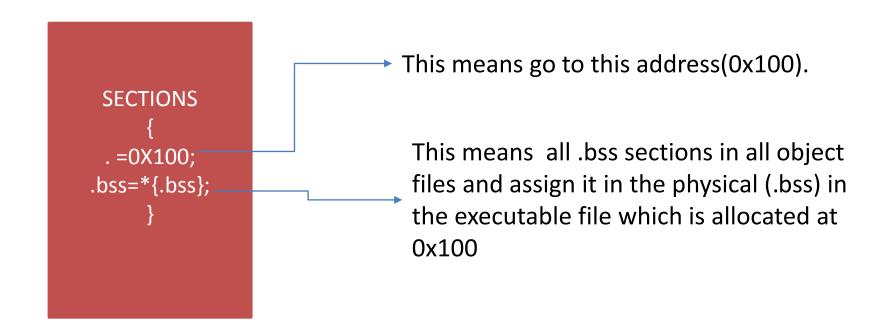
3- initialize interrupt vector table

4-call entry point( main function)



# Linker script

- The linker script is a script that the linker function is based on. The linker will give the memory sections its physical addresses based on what written in linker script, so it can be describes as the code of the linker tool.





### bootloader

- The bootloader is a written code that can change from one communication protocol to another protocol to enable a microcontroller to be programmed with a protocol different from its default protocol.
- i.e a controller that is programmed by SPI can now be programmed by UART using UART-SPI bootloader.
- After translating to the required protocol the flash memory of the target controller is updated with the code.
- In this case the processor is working during the program burning as if it programs itself so it is called self programming.



### The End ...





# Assignment

### **Expected Output**

#### **Assignment Description:**







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