







# PIConGPU: Designing An Application

On the shoulders of alpaka, openPMD and beyond...

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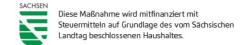












# Highlights of PIConGPU's adaption of alpaka, openPMD

and more...

#### **Execution and lockstep programming**

- Tailored kernel execution interface
- Abstraction for iterations



#### **Memory Management**

- Static: HostDeviceBuffer
- Dynamic: MallocMC



### I/O and In-Situ Processing

- OpenPMD as a backend
- Plugin system



#### **Other Learnings**

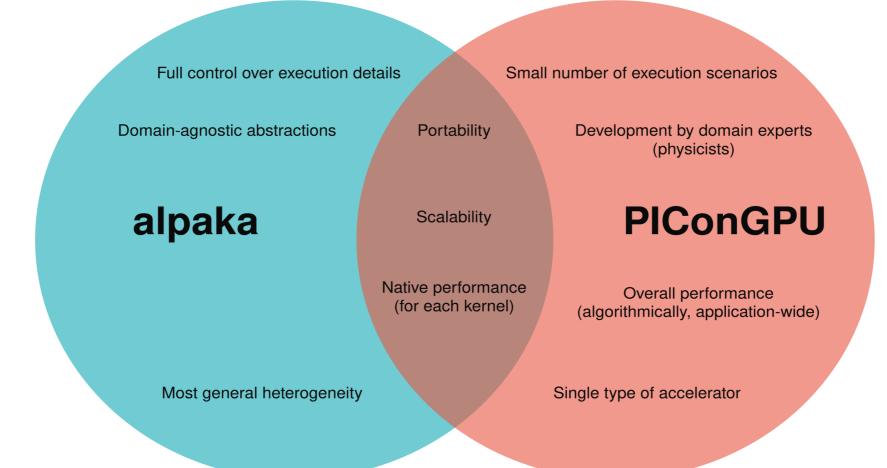
- Floating point precision and normalisation
- Performance tuning
- Professional software development





# alpaka is not (yet!) tailored to your needs

Design goals, requirements and constraints





# **Execution & Lockstep**

Tailored kernel definition and execution



# The Idea: An Interface Fitting Your Task

## Lockstep Programming

## The Physicist's Task

Conceptually most of our code is this:

```
void processAllCells() {
    for (auto& cell : cells)
    {
       process(cell);
    }
}
```

Physicist: Write the process (cell) function.

#### **The Software Engineer's Tasks**

- Keeping track of parallelisation parameters
- Handling indices
- Bounds checks
- Distributing work amongst threads
- Handling special cases
- ..

#### Provide a suitable interface!

- The details of your application of alpaka are not generic to all applications.
- But within your application you should provide tailored abstractions and interfaces!





# The ForEach API: Abstracting iteration

## **Lockstep Programming**

#### PIConGPU's ForEach User Code

```
auto procestAllCells = [l ALPAKA FN_ACC (auto const& worker) {
    auto forEachCell = makeForEach<numberOfCells>(worker);

    forEachCell(
        [](uint32_t const idx) {
            process(cells[idx]);
        }
    );
};
```

#### What does ForEach do? (see include/pmacc/lockstep/ForEach.hpp)

- Keep track of parallelisation parameters (152-154)
- Iteration with bounds checks, grid striding, etc. (192-232)
- Handle special cases like single-threading (235-243)





# **Tailored Execution: Exposing What You Need**

#### Kernel execution

### The PMACC\_LOCKSTEP\_KERNEL Macro

#### The Call Stack (see include/pmacc/lockstep/Kernel.hpp and include/pmacc/exec/KernelLauncher.hpp)

- PMACC\_LOCKSTEP\_KERNEL (Kernel.hpp#295 → 281) → KernelPreparationWrapper (70)
  - · debugging information, user kernel, launcher factory
- .config<...>(...) (100) → KernelLauncher (KernelLauncher.hpp#49)
  - execution details (in PIConGPU data structures), application context (event system, etc.)
- .operator() (87)
  - translate details to alpaka data structures, call alpaka::enqueue(...), inform event system





## The Worker: Accelerator++

#### **Execution & Lockstep**

```
template<typename T_Acc, typename T_BlockCfg>
class Worker {
   T_Acc const& m_acc;
    uint32_t const m_workerIdx;
    static constexpr uint32_t numWorkers() {
        return T_BlockCfg::numWorkers();
    static constexpr uint32_t blockDomSize() {/*...*/}
    static constexpr auto blockDomSizeND() {/*...*/}
    // . . .
    void sync() const {
        alpaka::syncBlockThreads(m_acc);
```

See /include/pmacc/lockstep/Worker.hpp





# A (Trivial) Real-World Example: Generating an ID

## **Execution & Lockstep**

```
class IdProvider { // include/pmacc/IdProvider.hpp
   // ...
   uint64_t getNewIdHost()
        HostDeviceBuffer<uint64_t, 1> newIdBuf(DataSpace<1>(1));
        auto kernel = [] ALPAKA FN ACC
                (auto const& acc, auto idGenerator, uint64_t* nextId)
            -> void {
                *nextId = idGenerator.fetchInc(acc);
            };
        PMACC LOCKSTEP KERNEL (kernel)
            .config<1>(1)
            (getDeviceGenerator(), newIdBuf.getDeviceBuffer().data());
        newIdBuf.deviceToHost();
        return *newIdBuf.getHostBuffer().data();
```

# A (Non-Trivial) Real-World Example: Transition Rates

## **Lockstep Programming**

#### What does it do? (see /include/picongpu/particles/atomicPhysics/kernel/FillLocalRateCache\_BoundFree.kernel#L193)

- Request and initialise shared memory (214-228)
  - · Only one single thread in use
  - PMACC\_SMEM forwards to alpaka::declareSharedVar
  - makeMaster forwards to makeForEach<1, 1>
- Min/Max reduction over cells (230-258)
  - One thread handles one cell
  - Use atomics on shared memory
- Reduction of ~N<sup>2</sup> transition rates to one sum per state (260-303)
  - One thread handles transitions from one state
  - Thread-local reduction doesn't need atomics



## **Summary: Trade-Offs**

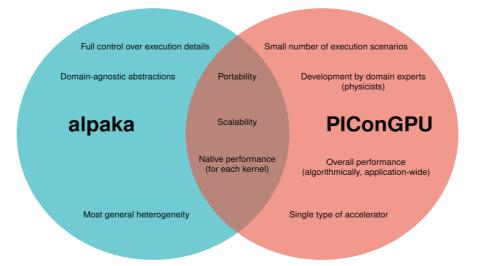
## Lockstep Programming

#### **Advantages**

- Clean interface & reduction of boilerplate
- Versatile iteration schemes
- Compile-time known memory access
- Library agnostic

## **Restrictions of generality**

- Block sizes must be compile-time const
- Execution details are inaccessible to user (device, queue, accelerator)



# Outlook: That's just a tiny glimpse

## **Lockstep Programming**

#### Features we didn't cover

- Another layer of abstraction to iterate through our most common data structures
- ContextVariables allow carrying state between ForEachs
- Self-aware functors can express constraints on their execution parameters
- Might be coming to alpaka!

#### **Lessons learnt**

Adoption of alpaka is best performed via...
an application-specific interface layer...
concretising (and hiding) application-specific choices.





# **Memory Management**

Domain-specific memory handling





# Integration into application context: Static == Fields

#### Memory Management

#### alpaka::Buf

- Basics: malloc/free
- Metadata: type, extent and pitch (host only)
- Explicit interface and fully flexible:
  - Device
  - Queues

## PMacc's requirements

- Convenient interface (STL-like, ...)
- Metadata: on device!
- Concrete environment:
  - Fixed device
  - Integration into event system
- Association of host and device buffers
- Communication awareness (MPI)

alpaka::Buf (storage)

pmacc::Buffer
(interface & metadata)

pmacc::HostBuffer
pmacc::DeviceBuffer
(interface implementation)

pmacc::HostDeviceBuffer (association)

pmacc::GridBuffer
(communication awareness)





# **Single Buffers**

Memory Management (static)

### pmacc::Buffer

- Interface & default implementations
- Stores own size in alpaka::Buf
- Models memory owning

alpaka::Buf (storage)

pmacc::Buffer (interface & metadata)

pmacc::HostBuffer
pmacc::DeviceBuffer
interface implementation)

pmacc::HostDeviceBuffer (association)

pmacc::GridBuffer
(communication awareness)





# **Single Buffers**

Memory Management (static)

#### pmacc::HostBuffer & pmacc::DeviceBuffer

- Keep memory in alpaka::Buf
- Stores size on device
- Operations interact with event system
- Provides copy operations

alpaka::Buf (storage)

pmacc::Buffer
(interface & metadata)

pmacc::HostBuffer
pmacc::DeviceBuffer
(interface implementation)

pmacc::HostDeviceBuffer (association)

pmacc::GridBuffer
(communication awareness)





## **Double Buffers**

## Memory Management (static)

### pmacc::HostDeviceBuffer

- Associates one host and one device buffer
- Adds sync operations for convenience

alpaka::Buf (storage)

pmacc::Buffer
(interface & metadata)

pmacc::HostBuffer pmacc::DeviceBuffer (interface implementation)

pmacc::HostDeviceBuffer (association)

pmacc::GridBuffer
(communication awareness)





## **Double Buffers**

## Memory Management (static)

#### pmacc::GridBuffer

- MPI communication interface
  - send
  - receive
  - sync
- Awareness of memory distribution

alpaka::Buf (storage)

pmacc::Buffer (interface & metadata

pmacc::HostBuffer pmacc::DeviceBuffer interface implementation

pmacc::GridBuffer
(communication awareness)





# Integration into application context: Static == Fields

#### Memory Management

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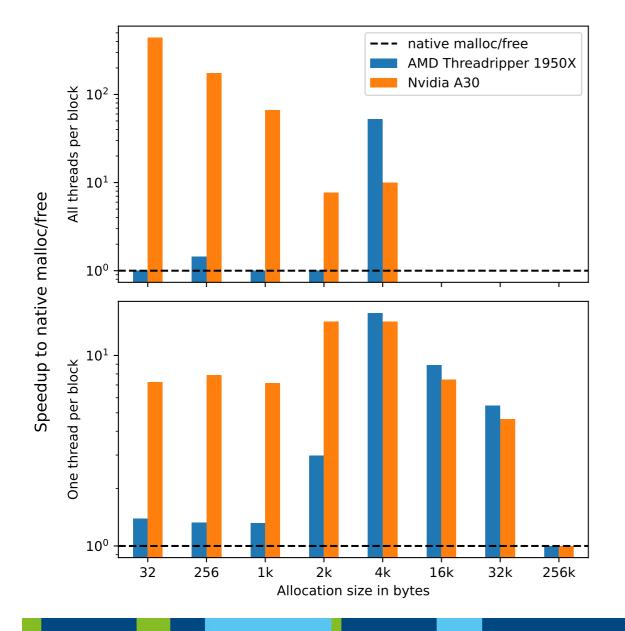
pmacc::HostBuffer
pmacc::DeviceBuffer
(interface implementation)

pmacc::HostDeviceBuffer (association)

pmacc::GridBuffer
(communication awareness)







## mallocMC: Dynamic == Particles

## **Memory Management**

Particles move around,...

... so we need **dynamic**, **in-kernel allocations**!

#### Memory usage pattern:

- Allocate static memory on host and device.
- Reserve remaining device memory.
- Dynamically allocate particles...
- ... on host (standard malloc/free) and
- ... on device within reservation (mallocMC).
- Quantise allocations in "particle frames".





# I/O And Processing

Build only what you're an expert in





# I/O should be a thin layer in your application

## I/O And Processing

#### You are...

... most likely not an expert in (all) distributed file systems and file formats.

... probably not paid for becoming one.

... hopefully an expert in how your numbers in memory shall related to numbers on disk.

#### Conclusion

You should employ a capable backend and only code the domain specifics on top.







## **Success Stories**

#### I/O And Processing

## **Migrating to Frontier**

- World's largest supercomputer
- Problem: I/O ran out of CPU memory
- Solution: New ADIOS2 engine
- Diff: +0 -0



#### **Enabling streaming**

- Avoid filesystem limitations
- Solution: openPMD streaming API
- Diff: +72 -19



#### **Writing Metadata**

- Metadata is backend independent.
- Problem: Different APIs for file formats
- Solution: openPMD's tailored API
- Diff: +162 -395



## **Open Source: Advance the community**

- Allow aspects to mature in implementations.
- Contribute back:
  - ED-PIC extension
  - Dataset-specific compression







# **Further Learnings**

Everything else we could possibly think off...



## **Precision and Normalisation**

Know your limits and go beyond them!

#### Floating-point precision matters!

- Smaller type = larger memory throughput
- Specialisation of hardware (not always!)
- Rounding errors accumulate
- Domain's values might span large ranges

#### **Example: Laser-Plasma Physics**

- Speed ~ speed of light ~ 108 m/s
- Time ~ plasma freq ~ PIC time step ~ 10<sup>-16</sup> s
- Mass ~ macro-particle electron ~ 10<sup>25-31</sup> kg
- Length ~ Time \* Speed ~ 10<sup>-8</sup> m

#### Normalisation and the unit system (see /include/picongpu/unitless/simulation.unitless)

- In appropriate units all occurring numbers will be close to one. → Low precision required.
- Configurable precision allows easier adaption to new hardware.
- Implementing a unit system allows convenient interfacing with domain experts.
- Not all operations allow reduced precision! (Example: sqrt)





# **Performance Tuning and Optimisation**

## Some Tips and Tricks

## **Understand your code!**

- Everything happens for a reason!
- Compilers and tools are always right (except for when they are wrong)!
- Benchmark, trace and profile (potentially roofline models for bottlenecks)
- Feedback from production (ask users, check logs, check cluster statistics, ...)

#### alpaka: Tips and Tricks

- alpaka compiles to native code. → Use vendor tools!
  - Typically optimisations boost all vendors (but not all hardware types).
- Single-header alpaka for compiler explorer
- Check register counts, spills and occupancies: -Dalpaka\_CUDA\_SHOW\_REGISTERS
- Use -Dalpaka\_DEBUG=2 to check workDivs



# **Professional Software Development**

#### The Basics

#### **Automated testing and continuous integration**

→ Vary architectures, compilers and libraries, too!

#### **Manage contributions**

→ Pull requests, issues, code reviews, ...

#### Communicate about your code

→ Ask questions, pair programming, code reviews, ...

#### Less is more!

→ If your team is small, keep your code small! (If your team is large, still keep your code small!)





# Thanks for the attention!

