Starting a C++ project using CMake, Catch and google/benchmark

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Coding process (C++)

- Code
- Build
- Test
- Benchmark
- Refactor

Coding process (C++)

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- Build (CMake + Ninja)
- Test (Catch)
- Benchmark (google/benchmark)
- Refactor

Generalities about build systems

Targets and dependencies

Targets

Dependency targets

Source files



Tup - http://gittup.org/tup/

 Incremental builds: rebuild targets only if dependencies have changed or must be rebuilt

How to collect header files?

```
// foo.h
#include "bar.h"
#ifdef USE 42
 #include "42.h"
#else
 #include "49_3.h"
#endif
```

- Manually collect header files (fastidious and error prone)
- Use compiler to collect header files (takes time when compiling)

Incremental build systems

- MSBuild default build system of Visual Studio projects
- Xcode default build system of Xcode projects
- GNU Make Makefiles have to define all dependencies
- Ninja (design) similar to make but can collect header files
- Scons write targets and dependencies in Python
- <u>Bazel</u> higher level description of build targets
- tup bottom-up calculation of targets that must be rebuilt
- Shake similar to make, build scripts are written in Haskell

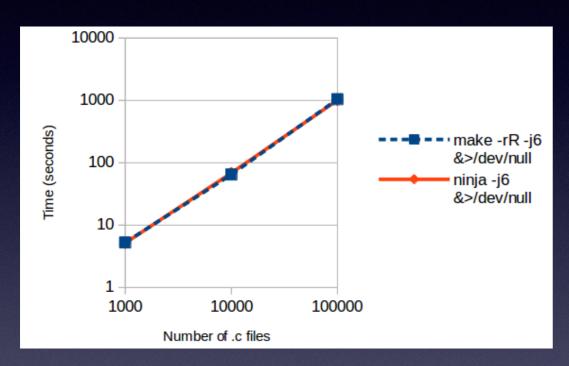
Generators of build systems

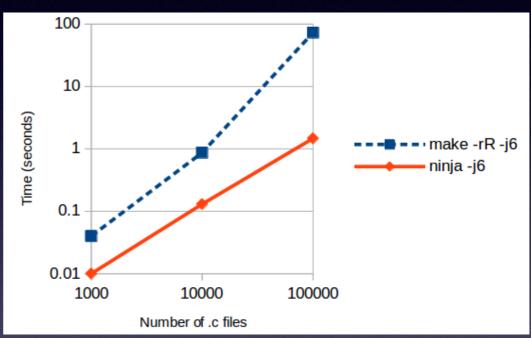
- <u>CMake</u> define high level targets and commands using its own syntax
- Meson scripts written in Python
- Premake scripts written in Lua
- QMake convenient for Qt projects no Ninja generator
 - Gradually replaced by Qbs (similar to Bazel)
- GN (Presentation) replacing GYP (performances issues)

Evaluating build systems

- 1. Correctness (Recompiles if and only if necessary)
- 2. Speed (for full build and incremental builds)
- 3. Build scripts: concise but flexible
- 4. Multi-platforms (requires only few changes)
- **5. Play well with others** (IDEs, third-party libraries)

Benchmark: Ninja vs Make



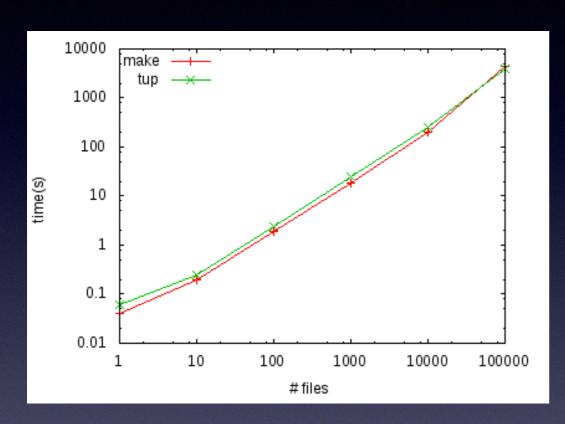


Fresh build

No op build

http://david.rothlis.net/ninja-benchmark/

Benchmark: tup vs Make



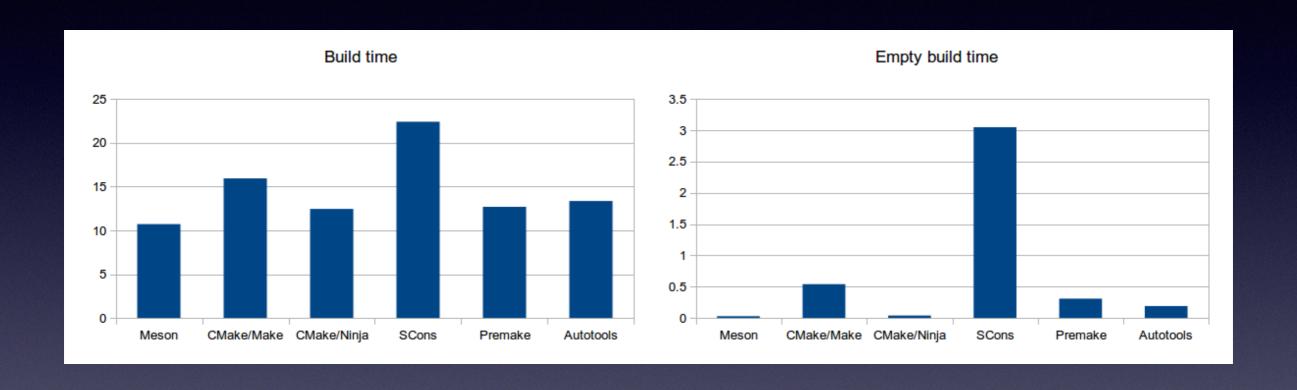
10000 make tup 1000 100 time(s) 10 1 0.1 0.01 10 100 1000 10000 100000 # files

Fresh build

No op build

http://gittup.org/tup/make_vs_tup.html

Benchmark: Meson vs CMake vs Premake vs SCons vs Autotools



Experiment with 1,000 simple c files

https://sourceforge.net/p/meson/wiki/ Simple%20comparison/

CMake tutorial

First CMakeLists.txt (1)

Index of source directory e.g. 1 -> 01_...

```
cmake_minimum_required(VERSION 3.7)
```

project(hwProj LANGUAGES CXX VERSION 1.0)

```
add_executable(helloWorld
    main.cpp
```

Running cmake & ninja (1)

```
$ mkdir ../build_aux && cd ../build_aux
```

```
$ cmake -G"CodeBlocks - Ninja" \
-DCMAKE_BUILD_TYPE=Release \
-DCMAKE_CXX_FLAGS="-std=c++1z" \
../01-helloWorld
```

\$ ninja

\$./helloWorld

Adding install target (2)

```
cmake_minimum_required(VERSION 3.7)

project(hwProj LANGUAGES CXX VERSION 1.0)

add_executable(helloWorld
    main.cpp
)
```

install(TARGETS helloWorld RUNTIME DESTINATION bin

Running cmake & ninja (2)

```
$ mkdir ../build_aux && cd ../build_aux
```

```
$ cmake -G"CodeBlocks - Ninja" \
   -DCMAKE_BUILD_TYPE=Release \
   -DCMAKE_CXX_FLAGS="-std=c++1z" \
   -DCMAKE_INSTALL_PREFIX=../install_aux \
   ../02-helloWorld-installTarget
```

\$ ninja install

\$../install_aux/bin/helloWorld

Creating library (3)

```
cmake_minimum_required(
   VERSION 3.7)
project(moplot
   LANGUAGES CXX
   VERSION 1.0)
add_library(moplot
   curve2D.cpp
   curve2D.hpp
add_executable(testMoplot
   testCurve2D.cpp
target_link_libraries(testMoplot
   PUBLIC moplot
```

#continuation

install(TARGETS moplot
RUNTIME DESTINATION bin
LIBRARY DESTINATION lib
ARCHIVE DESTINATION lib)
install(FILES curve2D.hpp
DESTINATION include/moplot
COMPONENT Devel)

Running cmake & ninja (3)

```
$ mkdir ../build_aux && cd ../build_aux
```

```
$ cmake -G"CodeBlocks - Ninja" \
   -DCMAKE_BUILD_TYPE=Release \
   -DCMAKE_CXX_FLAGS="-std=c++1z" \
   -DCMAKE_INSTALL_PREFIX=../install_aux \
   ../03-libMoplot
```

\$ ninja install

\$./testMoplot

Separate directories (4)

```
# ./CMakeLists.txt
cmake_minimum_required(
    VERSION 3.7)
project(moplot LANGUAGES CXX
    VERSION 1.0)
add_subdirectory(src)
add_subdirectory(tests)
```

```
# tests/CMakeLists.txt
add_executable(testMoplot
    testCurve2D.cpp
)
target_link_libraries(testMoplot
    PUBLIC moplot
)
```

```
# src/CMakeLists.txt
add_library(moplot
   curve2D.cpp
   curve2D.hpp
target_include_directories(moplot
   PUBLIC.
install(TARGETS moplot
   RUNTIME DESTINATION bin
   LIBRARY DESTINATION lib
   ARCHIVE DESTINATION lib)
install(FILES curve2D.hpp
   DESTINATION include/moplot
   COMPONENT Devel)
```

Running cmake & ninja (4)

```
$ mkdir ../build_aux && cd ../build_aux
```

```
$ cmake -G"CodeBlocks - Ninja" \
   -DCMAKE_BUILD_TYPE=Release \
   -DCMAKE_CXX_FLAGS="-std=c++1z" \
   -DCMAKE_INSTALL_PREFIX=../install_aux \
   ../04-libMoplot-separateDirectories
```

\$ ninja install

\$./tests/testMoplot

Importing Catch Library (5)

```
# tests/CMakeLists.txt
find_file(CatchHeader catch/catch.hpp)
if(NOT CatchHeader)
   message(FATAL_ERROR "Could not find Catch header: ${CatchHeader}")
endif()
get_filename_component(CatchIncludeDir ${CatchHeader} DIRECTORY)
message(STATUS "Catch found in ${CatchIncludeDir}")
add_library(catch INTERFACE IMPORTED GLOBAL)
set_property(TARGET catch PROPERTY
   INTERFACE_INCLUDE_DIRECTORIES ${CatchIncludeDir})
add_executable(testMoplot
    testCurve2D.cpp
target_link_libraries(testMoplot
    PUBLIC moplot catch
```

Enabling ctest (5)

```
# ./CMakeLists.txt
cmake_minimum_required(VERSION 3.7)
project(moplot LANGUAGES CXX VERSION 1.0)
enable_testing()
add_subdirectory(src)
add_subdirectory(tests)
```

Running cmake & ninja (5)

```
$ mkdir ../build_aux && cd ../build_aux
$ cmake -G"CodeBlocks - Ninja" \
    -DCMAKE_BUILD_TYPE=Release \
    -DCMAKE_CXX_FLAGS="-std=c++1z" \
    -DCMAKE_INSTALL_PREFIX=../install_aux \
    -DCMAKE_PREFIX_PATH=$third_parties
    ../05-importedLibrary
$ ninja
```

\$ CTEST_OUTPUT_ON_FAILURE=true ninja test

\$ ninja install

Using CatchMain Library (6)

```
# tests/CMakeLists.txt
find_package(CatchMain REQUIRED)
add_executable(testMoplot
  testCurve2D.cpp
target_link_libraries(testMoplot
  PUBLIC moplot CatchMain
add_test(NAME testMoplot
  COMMAND testMoplot ~[Skip])
```

Exporting cmake file (6)

```
# src/CMakeLists.txt
add_library(moplot
   curve2D.cpp
    curve2D.hpp
target_include_directories(moplot PUBLIC
    $<BUILD_INTERFACE:${CMAKE_CURRENT_SOURCE_DIR}>
    $<INSTALL_INTERFACE:include/moplot>
install(TARGETS moplot EXPORT moplotConfig
    RUNTIME DESTINATION bin
    LIBRARY DESTINATION lib
    ARCHIVE DESTINATION lib
install(FILES curve2D.hpp
    DESTINATION include/moplot
    COMPONENT Devel)
include(CMakePackageConfigHelpers)
install(EXPORT moplotConfig
```

Exporting dependencies

```
# https://github.com/Marc--Olivier/third_parties/blob/master/src/google-benchmark-main/CMakeLists.txt
install(TARGETS GoogleBenchmarkMain EXPORT GoogleBenchmarkMainTarget
    RUNTIME DESTINATION bin
    LIBRARY DESTINATION lib
    ARCHIVE DESTINATION lib)
include(CMakePackageConfigHelpers)
set(ConfigPackageLocation lib/cmake/GoogleBenchmarkMain)
install(FILES GoogleBenchmarkMainConfig.cmake
    DESTINATION ${ConfigPackageLocation})
install(EXPORT GoogleBenchmarkMainTarget
    FILE GoogleBenchmarkMainTarget.cmake
    NAMESPACE "benchmark::"
    DESTINATION ${ConfigPackageLocation})
```

```
# https://github.com/Marc--Olivier/third_parties/blob/master/src/google-benchmark-main/GoogleBenchmarkMainConfig.cmake

if(NOT TARGET benchmark::benchmark)
    find_package(benchmark)

endif()

include("${CMAKE_CURRENT_LIST_DIR}/GoogleBenchmarkMainTarget.cmake")
```

Packaging binaries (7)

```
# ./CMakeLists.txt
cmake_minimum_required(VERSION 3.7)
project(pwd LANGUAGES CXX VERSION 1.0)
find_package(Boost REQUIRED COMPONENTS filesystem system)
add_executable(pwd
   main.cpp
# To run pwd, set PATH (Windows), LD_LIBRARY_PATH (Linux),
# or DYLD_LIBRARY_PATH (macOS) to $THIRD_PARTIES/lib
target_link_libraries(pwd PUBLIC
    Boost::boost ${Boost_FILESYSTEM_LIBRARY} $
{Boost_SYSTEM_LIBRARY})
install(TARGETS pwd
    RUNTIME DESTINATION bin
    LIBRARY DESTINATION lib)
install(FILES ${Boost_FILESYSTEM_LIBRARY} ${Boost_SYSTEM_LIBRARY}
    DESTINATION bin)
# BundleUtilities should be used to fix runtime dependencies
include(CPack)
```

Evaluating CMake

Advantages

- Reliable
- Fast (at least when used with Ninja)
- Not many differences between different platforms
- Plays well with IDEs (Visual Studio, Xcode, QtCreator, CLion, Eclipse, CodeBlocks)
- Plays well with third-party libraries (easy to switch between debug and release)
- Compiles in external build directories

Drawbacks

- Writing CMake extensions (functions, macros) is painful
- Export of libraries could be improved (aliases, package dependencies)
- Lack of documentation to create redistributable binaries (e.g. copying third-party dlls on Windows, fix rpath on macOS)

Catch (short) tutorial

First test using Catch (5)

```
// tests/testCurve2D.cpp
#define CATCH_CONFIG_MAIN
#include <catch.hpp>
#include "Curve2D.hpp"
namespace moplot {
namespace tests {
SCENARIO("Test create Curve2D", "[Curve2D]") {
   GIVEN("None") {
       WHEN("curve = Curve2D{{1.0, 2.0}, {}}") {
           auto curve = Curve2D{{1.0, 2.0}, {}};
```

Why using library CatchMain (6)

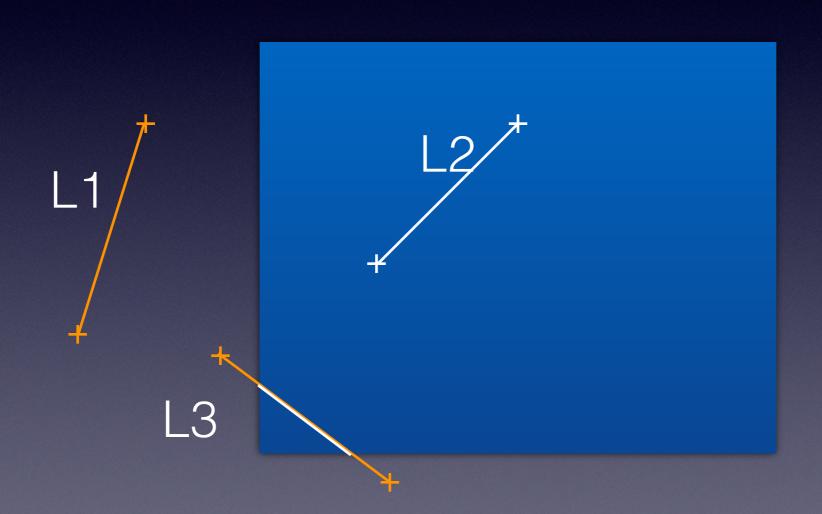
```
// ${third_parties}/CatchMain/catchMain.cpp
#define CATCH_CONFIG_MAIN
#include <catch.hpp>
```

```
// tests/testCurve2D.cpp
#include <catch.hpp>
#include "Curve2D.hpp"
namespace moplot {
namespace tests {
SCENARIO("Test create Curve2D", "[Curve2D]") {
    GIVEN("None") {
         WHEN("curve = Curve2D{{1.0, 2.0}, {}}") {
             auto curve = Curve2D{{1.0, 2.0}, {}};
```

Checking exception (8)

```
SCENARIO("Test create Curve2D", "[Curve2D]") {
   GIVEN("None") {
       WHEN("curve = Curve2D{{1.0, 2.0}, {}}") {
          THEN("Throws std::invalid_argument("
                 "\"Invalid sizes: 2 xvals vs. 0 yvals\")") {
              CHECK_THROWS_AS(Curve2D({1.0, 2.0}, {}),
                 std::invalid_argument);
              CHECK_THROWS_WITH(Curve2D({1.0, 2.0}, {}),
                 "Invalid sizes: 2 xvals vs. 0 yvals");
```

Intersection line/rectangle



Checking intersection (8)

```
SCENARIO("Intersection line/rectangle", "[Curve2D]") {
 GIVEN("rect = Rect{xmin=100, xmax=500, ymin=10, ymax=60}") {
   WHEN("intersection = intersect("
       "rect, Line\{x1=350, y1=20, x2=120, y2=40\})") {
    auto intersection = intersect(rect, Line{350.0, 20.0, 120.0, 40.0});
    THEN("!intersection.empty and "
         "intersection.line == Line\{x1=350, y1=20, x2=120, y2=40\}") {
       REQUIRE(!intersection.empty);
       CHECK(intersection.line.x1 == Approx(350.0));
       CHECK(intersection.line.y1 == Approx(20.0));
       CHECK(intersection.line.x2 == Approx(120.0));
       CHECK(intersection.line.y2 == Approx(40.0));
```

Rect, Line, Intersection (8)

```
struct Rect {
    double xmin;
    double xmax;
    double ymin;
    double ymax;
};
struct Line {
    double x1;
    double y1;
    double x2;
    double y2;
struct Intersection {
    Line line;
    bool empty;
Intersection intersect(const Rect& rect, const Line& line);
```

Using matchers (8)

```
SCENARIO("Intersection line/rectangle", "[Curve2D]") {
        GIVEN("rect = Rect{xmin=100, xmax=500, ymin=10, ymax=60}") {
                WHEN("intersection = intersect("
                                         "rect, Line\{x1=350, y1=20, x2=120, y2=40\})") {
                       auto intersection = intersect(rect, Line{350.0, 20.0, 120.0,
                       40.0});
                       THEN("!intersection.empty and "
                                                 "intersection.line == Line\{x1=350, y1=20, x2=120, y1=20, y1=20,
                                               y2=40}") {
                                       REQUIRE(!intersection.empty);
                                       CHECK_THAT(intersection.line,
                                                Equals(Line{350.0, 20.1, 120.0, 40.0}));
```

Implementing matcher (8)

```
class MatcherLineEquals : public Catch::MatcherBase<Line> {
 Line& const line;
public:
 MatcherLineEquals(Line const& line): line_(line) {}
 virtual bool match(Line const& rhs) const override { return
  rhs.x1 == Approx(line_.x1) && rhs.y1 == Approx(line_.y1) &&
  rhs.x2 == Approx(line_.x2) \&\& rhs.y2 == Approx(line_.y2);
 virtual std::string describe() const override {
  return "!= " + Catch::toString(line_);
inline auto Equals(Line const& line) {
 return MatcherLineEquals(line);
```

Catch::StringMaker (8)

```
namespace Catch {
template<> struct StringMaker<moplot::Line> {
   static std::string convert(moplot::Line const& line) {
      std::ostringstream ss;
      ss << "{x1=" << line.x1 << ", y1=" << line.y1
          << ", x2=" << line.x2 << ", y2=" << line.y2 << "}";
      return ss.str();
```

"Programming with GUTs"

Kevlin Henney, Build Stuff 2015

video: https://www.youtube.com/watch?v=azoucC_fwzw

Google benchmark

in 4 slides

Running google benchmark

Benchmark	Time	CPU I	terations
BM_Intersect/1024	19855 ns	19806 ns	40715
BM Intersect/2048	68584 ns	68397 ns	12973
BM_Intersect/4096	163424 ns	162922 ns	4407

Function name

Input size

Minimum real time

Minimum CPU time

Number of iterations

"In all cases, the number of iterations for which the benchmark is run is governed by the amount of time the benchmark takes"

https://github.com/google/benchmark#controllingnumber-of-iterations

CMake & google benchmark (9)

```
# tests/CMakeLists.txt
find_package(benchmark)
add_executable(benchmarkMoplot
  benchmarkCurve2D.cpp
target_link_libraries(benchmarkMoplot
  PUBLIC moplot benchmark::benchmark
```

Implementing benchmark (9)

```
#include <benchmark/benchmark.h>
#include "Curve2D.hpp"
BENCHMARK_MAIN();
namespace moplot { namespace bm {
void BM_Intersect(benchmark::State& state) {
    auto lines = generateLines(state.range(0), Rect{0.0, 1000.0, 0.0, 100.0});
    Rect rect{200.0, 800.0, 20.0, 80.0};
    while (state.KeepRunning()) {
        for(const auto& line: lines) {
            intersect(rect, line);
BENCHMARK(BM_Intersect)->RangeMultiplier(2)->Range(1 << 10, 1 << 12);
```

"Tuning C++: Benchmarks, and CPUs, and Compilers! Oh My!"

Chandler Carruth, CppCon 2015

video: https://www.youtube.com/watch?v=nXaxk27zwlk

You can now

- Code
- Build
- Test
- Benchmark
- Refactor

Thank you!

References

- [1] CMake documentation https://cmake.org/cmake/help/latest/
 index.html
- [2] CMake/Tutorials https://cmake.org/Wiki/CMake/Tutorials
- [3] cmake-packages https://cmake.org/cmake/help/latest/manual/cmake-packages.7.html
- [4] ctest(1) https://cmake.org/cmake/help/latest/manual/ctest.1.html
- [5] Catch documentation https://github.com/philsquared/Catch/
 tree/master/docs
- [6] Google/benchmark https://github.com/google/benchmark