

Quiz 3

1. (a) For constrained SVM

$$\min_{w, b, \xi_i} \|w\|_2^2 + \frac{1}{n} \sum_{i=1}^n \xi_i \quad (1)$$

$$y_i(w^T v_i - b) \geq 1 - \xi_i \text{ for } \forall i \quad (2)$$

$$\xi_i \geq 0 \text{ for } \forall i \quad (3)$$

(2) is the same as $\xi_i \geq 1 - y_i(w^T v_i - b)$

consider (2) and (3) together, to min ξ_i ,

$$\xi_i \geq \max(0, 1 - y_i(w^T v_i - b)) = (1 - y_i(w^T v_i - b))^+$$

plug it into (1) get

$$\min_{w, b} \|w\|_2^2 + \frac{1}{n} \sum_{i=1}^n (1 - y_i(w^T v_i - b))^+, \text{ which is the above formula.}$$

(b) For $w = \frac{1}{j} \sum \phi(x_j) = \Phi^T \alpha$ for $\alpha \in \mathbb{R}^n$ where $\Phi \in \mathbb{R}^{n \times D}$ with $\phi(x_i)^T \in \mathbb{R}^D$ as the i th row.

$$\text{so } \phi(x_i)^T w = (\Phi \Phi^T \alpha)_i = (K \alpha)_i, K = \Phi \Phi^T.$$

$$\|w\|_2^2 = w^T w = \alpha^T \Phi \Phi^T \alpha.$$

$$J(w) = \frac{1}{n} \sum_{i=1}^n (1 - y_i(\phi(x_i)^T w))^+ + \|w\|_2^2$$

$$= \frac{1}{n} \sum_{i=1}^n (1 - y_i(K \alpha)_i)^+ + \alpha^T K \alpha$$

$$= \frac{1}{n} \sum_{i=1}^n (1 - y_i(K \alpha)_i)^+ + \frac{1}{2} \alpha^T K \alpha$$

$$\text{so } \frac{1}{2} J(\alpha) = \frac{1}{n} \sum_{i=1}^n (1 - y_i(K \alpha)_i)^+ + \frac{1}{2} \alpha^T K \alpha \text{ where } \frac{1}{2} = \frac{1}{2}.$$

$$\text{For } J(\alpha) = \frac{1}{n} \sum_{i=1}^n (1 - y_i(K \alpha)_i)^+ + \frac{1}{2} \alpha^T K \alpha,$$

$$\frac{\partial}{\partial \alpha} J = \frac{1}{n} \sum_{i=1}^n t_i \cdot (-y_i \cdot k_i) + \frac{1}{2} K \alpha$$

$$t_i = \begin{cases} 1 & \text{if } y_i(K \alpha)_i < 1 \\ 0 & \text{if } y_i(K \alpha)_i \geq 1 \end{cases}$$

(c) ~~start from α .~~

~~for t in range(max-iteration):~~

~~if $y_i(K \alpha)_i < 1$:~~

~~gradient $= -y_i \cdot k_i$~~

start from α .

for i in range(max-iteration):

for j in range(x -length):

if $y_j(K \alpha)_j < 1$:

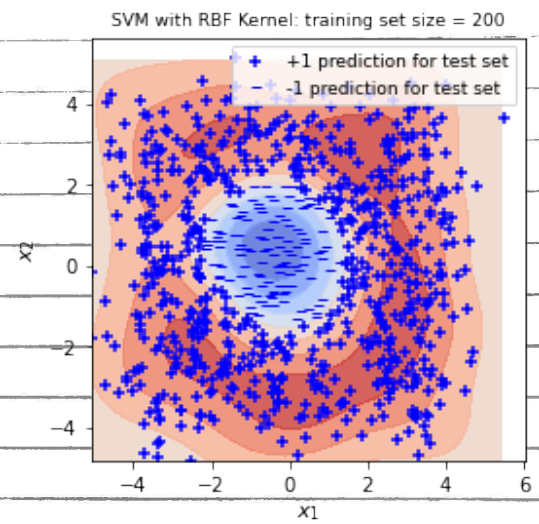
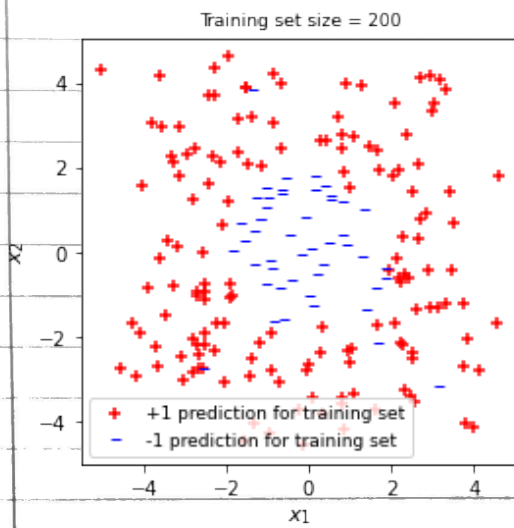
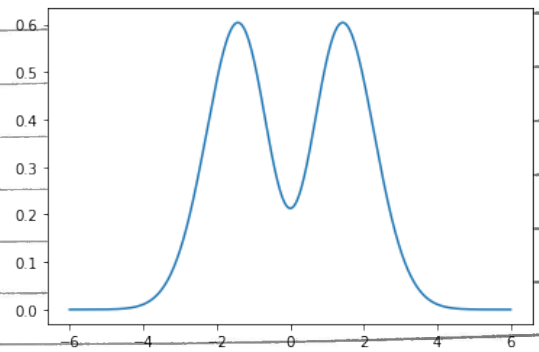
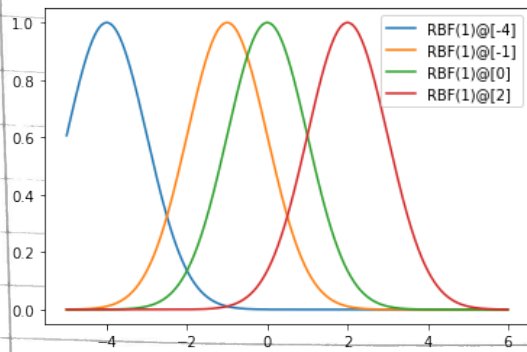
$$\text{gradient} = -y_j \cdot k_{ij} + \frac{1}{2} K \alpha.$$

else:

$$\text{gradient} = \frac{1}{2} K \alpha.$$

$$\alpha = \alpha - t * \text{gradient}.$$

2,



3. (a) safe arm $\sim \text{Ber}(1+\epsilon/2)$ $E(\text{arm 1}) = G_1/S_1$
 risky arm $\sim \text{Ber}(1-\epsilon/2)$ $E(\text{arm 2}) = G_2/S_2$

$$\begin{cases} S_1(1+\epsilon) = 2G_1 \\ S_2(1-\epsilon) = 2G_2 \end{cases} \quad \begin{cases} S_1 - \epsilon = 2G_1 - S_1 \\ S_2 - \epsilon = S_2 - 2G_2 \end{cases} \quad \text{combine}$$

$(S_1 + S_2)\epsilon = 2G_1 - 2G_2 + S_2 - S_1$ where $\epsilon > 0$ and $S_1 > 0$ and $S_2 > 0$.
 So $2G_1 - 2G_2 + S_2 - S_1 > 0$.

If arm 2 is safe, we have the same expression as above except $\epsilon < 0$. Then $2G_1 - 2G_2 + S_2 - S_1 < 0$.

Thus $2G_1 - 2G_2 + S_2 - S_1 > 0$, arm 1 is safe.

$2G_1 - 2G_2 + S_2 - S_1 < 0$, arm 2 is safe.

(b) For arm 1, set $[y_1, y_2, \dots, y_n]$, $y_i \in \{0, 1\}$, $r(\text{arm 1}) = G$.

For arm 2, set $[x_1, x_2, \dots, x_n]$, $x_i \in \{0, 1\}$, $x_i = |1 - y_i|$, $r(\text{arm 2}) = a - G$.

At a constant speed, since ϵ is small, we are put in higher risk of being stuck in the risky arm. Thus can't go far.