

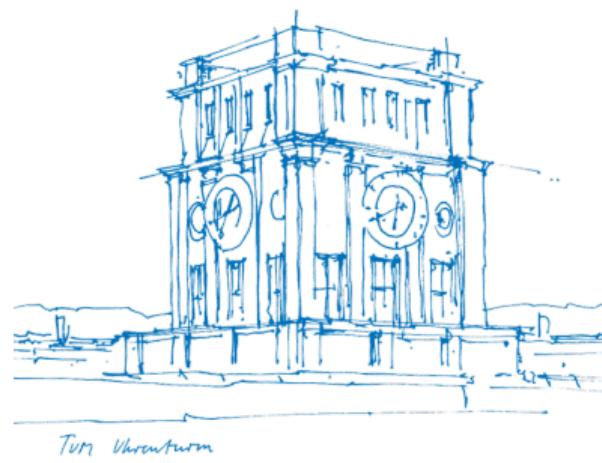
# Earth Observation and Machine Learning

From Language Model to Earth Model

Marc Rußwurm M.Sc., advised by Dr. Marco Körner

Technical University of Munich, Germany  
Remote Sensing Technology

May 3rd 2019, OATML-Lab, Oxford, UK



# About



# Background

## Earth Observation



2012-2018  
**Bachelor/Master**  
Geodesy and Geoinformation

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**Opium Poppy Detection**

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**PhD** with Supervisor from  
Computer Vision  
Multi-temporal Earth Obser-  
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2018  
Participant  
Frontier Developments Lab  
Disaster Relief with **CNN**  
**data fusion**

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Lab in France  
**Early Classification of Time  
Series**

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## Machine Learning



## This Talk

Organized in three parts

**Part I** Overview Earth Observation

**Part II** Research and Projects

**Part III** Workshops and Programs around EO and ML



# Part I: Earth Observation

# System Earth

Partially measuring System Earth

$$\mathbf{X} = \text{satellite icon} (\text{Earth icon})$$

**knowledge extraction** through pattern recognition  
and machine learning

$$? = f(\mathbf{X})$$



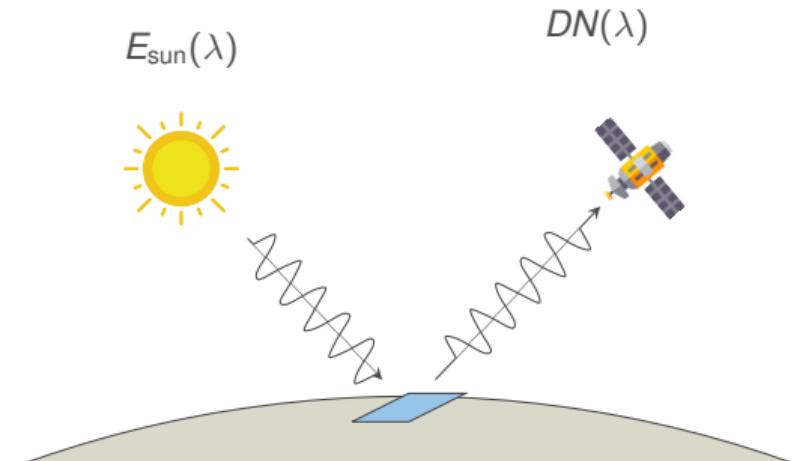
# Passive Optical Sensors

Sensor measures **Digital Numbers**  $DN(\lambda)$  for each band wavelength  $\lambda$ .

Digital Numbers are normalized to Radiance  $L(\lambda)$ ,  $\left[ \frac{W}{sr m^{-2}}$  ] by gain and offset calibration.

Radiance is normalized to top-of-atmosphere reflectance  $\rho(\lambda)$

Bottom-of-atmosphere reflectances are reconstructed using a functional model of the atmosphere.



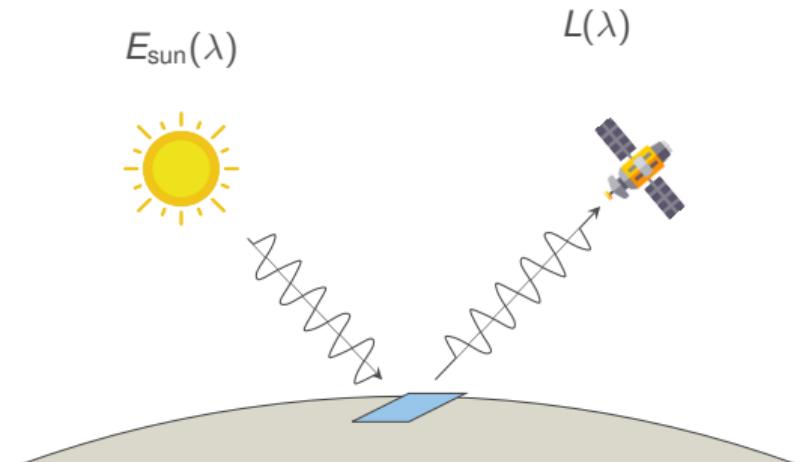
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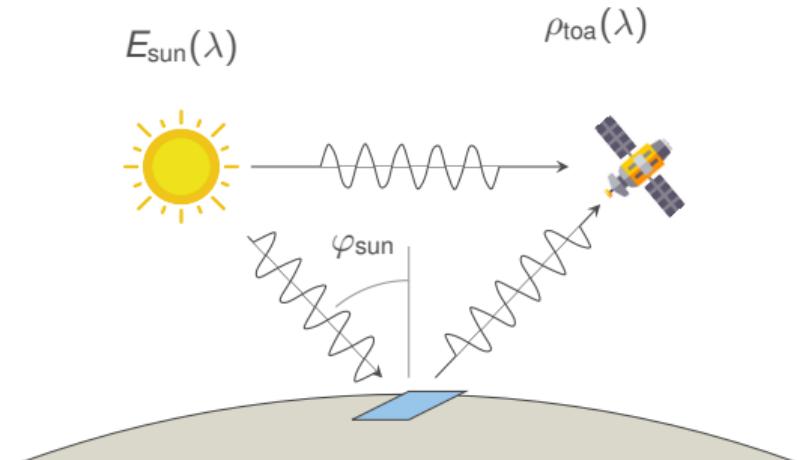
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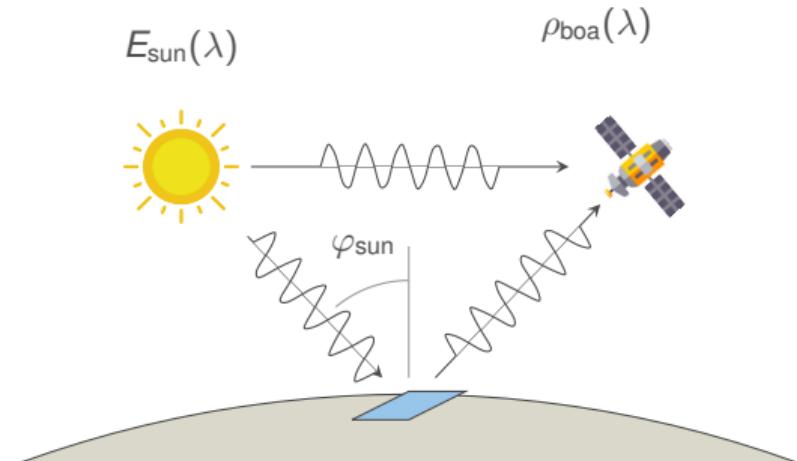
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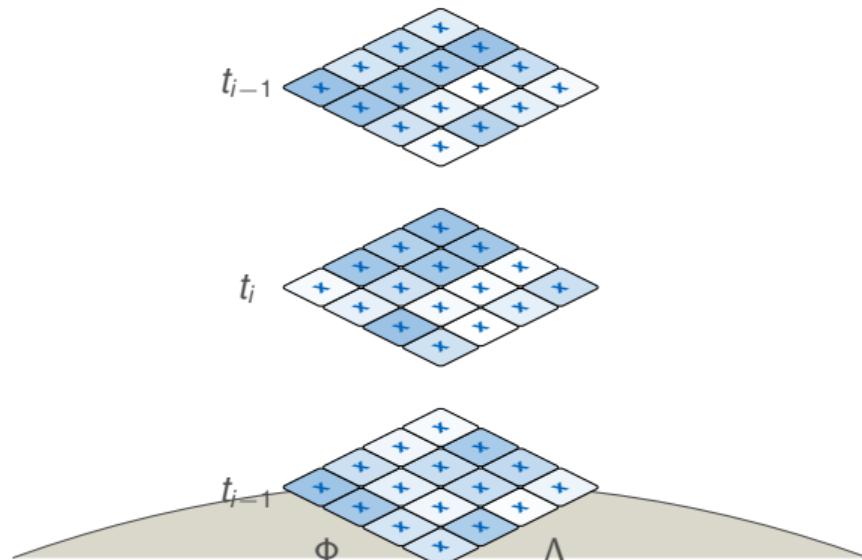
**Bottom-of-atmosphere reflectances** are reconstructed using a functional model of the atmosphere.



## Spatial and Temporal Discretization

$$\mathbf{X} = \begin{pmatrix} \rho_{\lambda_1} \\ \rho_{\lambda_2} \\ \dots \\ \rho_{\lambda_n} \end{pmatrix}$$

Spectral reflectance of **spectral bands** discretized on a **spatial grid**. Each grid cell is georeferenced by its Longitude  $\Lambda$  and Latitude  $\Phi$ . Acquisitions in regular **temporal intervals**.



**Hands-on:**

Optical Earth Observation

# Weather Satellites

At the Langrange 1 Point

dscovr:epic

8 km spatial resolution  
image every 20s  
10 spectral channels



[twitter.com/dscovr\\_epic](https://twitter.com/dscovr_epic) [epic.gsfc.nasa.gov](http://epic.gsfc.nasa.gov)



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1.5 Mio km



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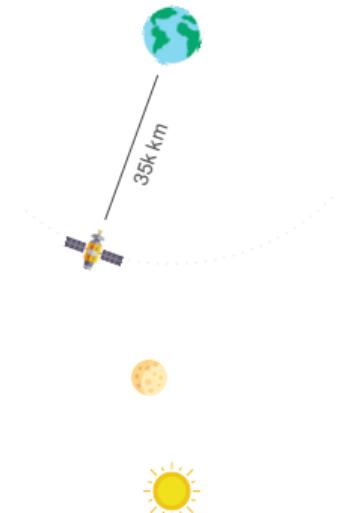


# Weather Satellites

At geostationary orbit

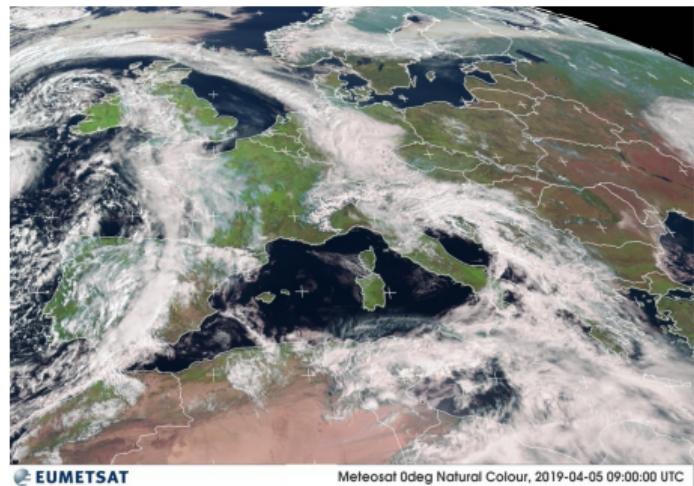
## MeteoSAT, GOES

2.5 - 5km km spatial  
resolution  
image every 15 minutes  
12 spectral Ochannels



<http://oiswww.eumetsat.org>

Icons from <https://www.flaticon.com>



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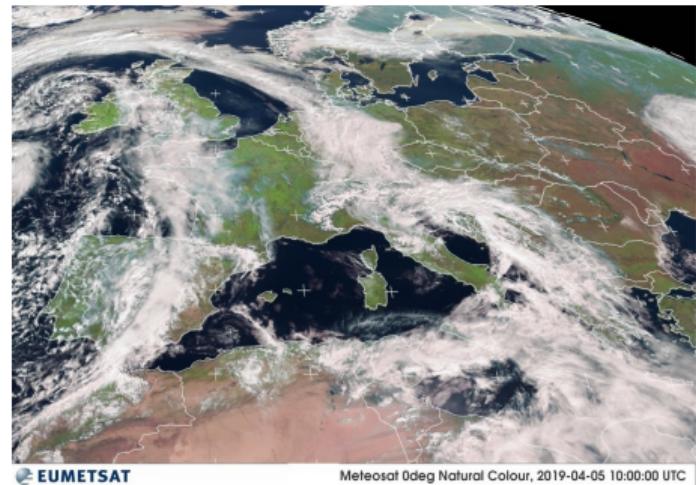


35k km



<http://oiswww.eumetsat.org>

Icons from <https://www.flaticon.com>

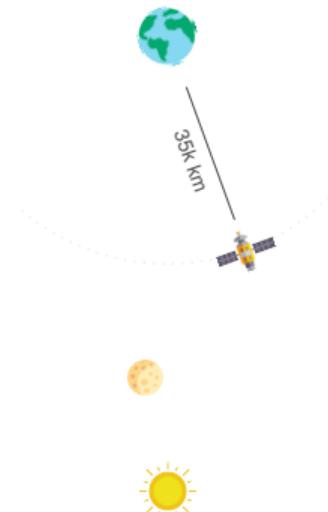


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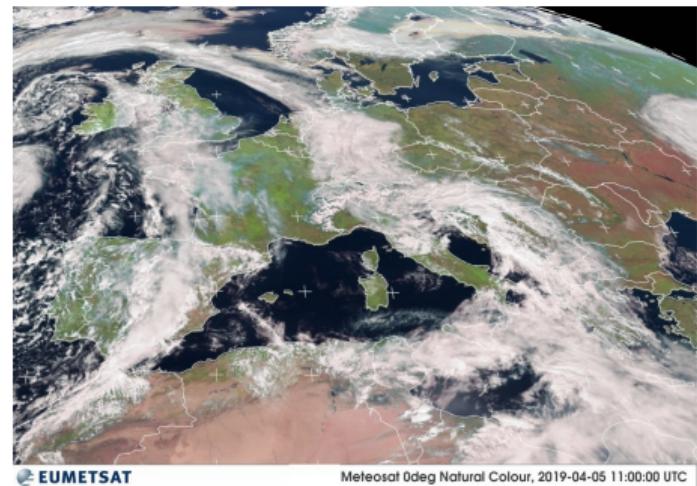
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## Sun Synchronous Orbit

**Environmental Satellites** with 1km spatial resolution every day

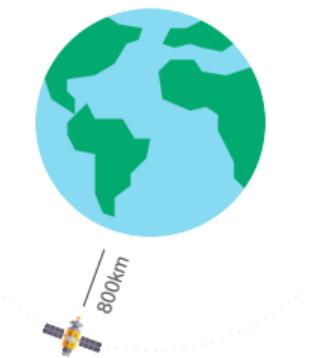
NASA's MODIS Aqua/Terra

ESA's Sentinel 3

**Multi-spectral satellites** with 10-60m spatial resolution 3-10 days

NASA's Landsat Satellites (since 70s!)

ESA's Sentinel 2



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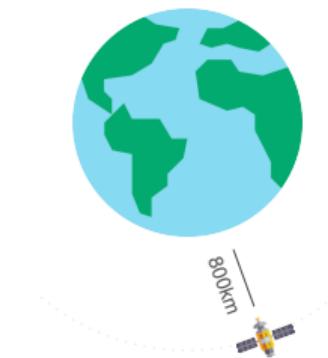
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**Multi-spectral satellites** with 10-60m spatial resolution 3-10 days

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# Global Environmental Satellites

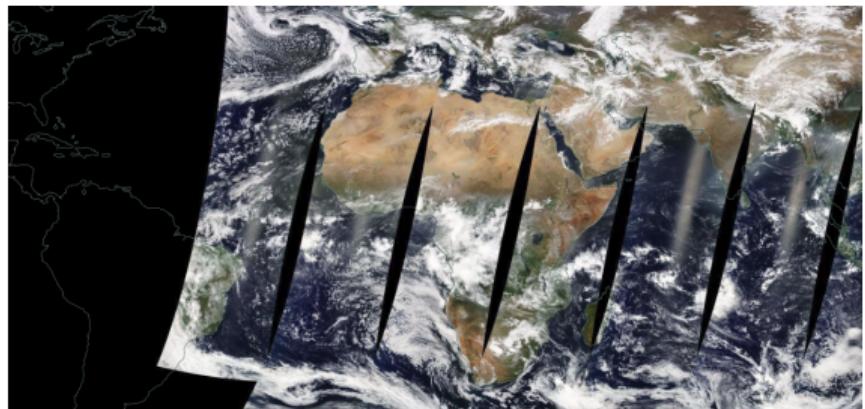
Moderate Resolution Spectrometer

images every day

resolution  $\approx 1\text{km}$

> 50 spectral bands

<https://worldview.earthdata.nasa.gov/>



## Multi Spectral Satellites – Example Sentinel 2 or Landsat

### USGS Landsat

spatial resolution 30m

covers every point on Earth every 16 days

11 spectral bands

since the 80s

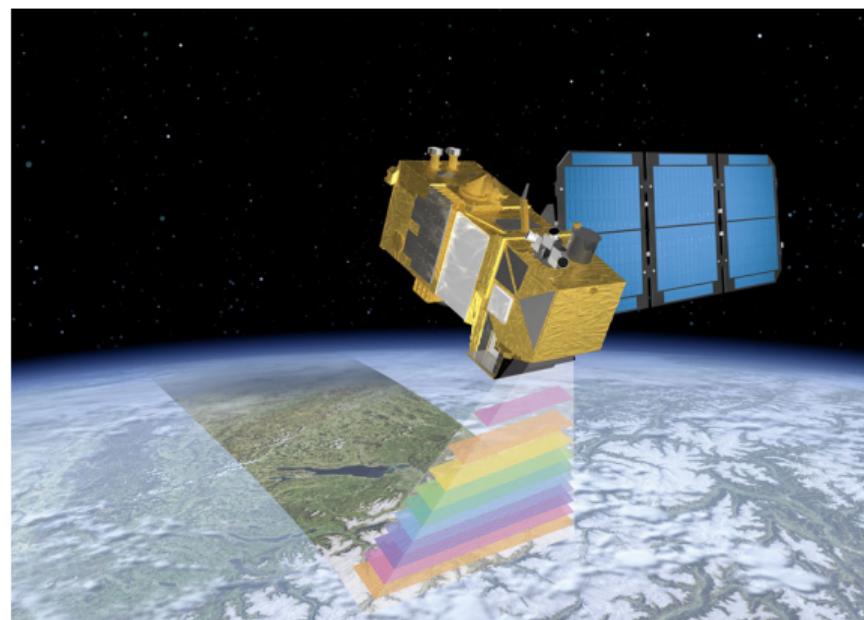
### ESA Sentinel-2

spatial resolution 10m-60m

covers every point on Earth every 2-5 days

13 spectral bands

since 2016



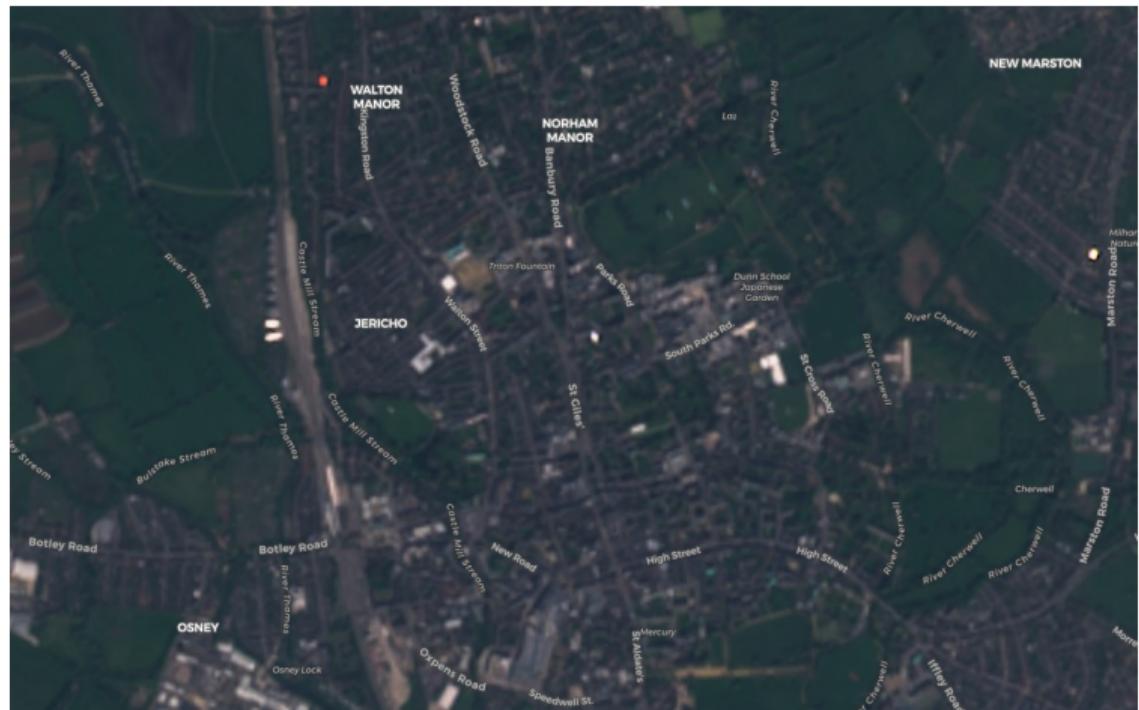
©AIRBUS DEFENCE AND SPACE

# Multi Spectral Satellites – Example Sentinel 2

True Color

$$X = \begin{pmatrix} \rho_{B1} \\ \rho_{B2} \\ \rho_{B3} \\ \rho_{B4} \\ \rho_{B5} \\ \rho_{B6} \\ \rho_{B7} \\ \rho_{B8} \\ \rho_{B8A} \\ \rho_{B9} \\ \rho_{B10} \\ \rho_{B11} \\ \rho_{B12} \end{pmatrix} \xrightarrow{\text{visualize}} \begin{pmatrix} \rho_{B4} \\ \rho_{B3} \\ \rho_{B2} \end{pmatrix}$$

<https://apps.sentinel-hub.com>



# Multi Spectral Satellites – Example Sentinel 2

False Color

$$X = \begin{pmatrix} \rho_{B1} \\ \rho_{B2} \\ \rho_{B3} \\ \rho_{B4} \\ \rho_{B5} \\ \rho_{B6} \\ \rho_{B7} \\ \rho_{B8} \\ \rho_{B8A} \\ \rho_{B9} \\ \rho_{B10} \\ \rho_{B11} \\ \rho_{B12} \end{pmatrix} \xrightarrow{\text{visualize}} \begin{pmatrix} \rho_{B8} \\ \rho_{B4} \\ \rho_{B3} \end{pmatrix}$$



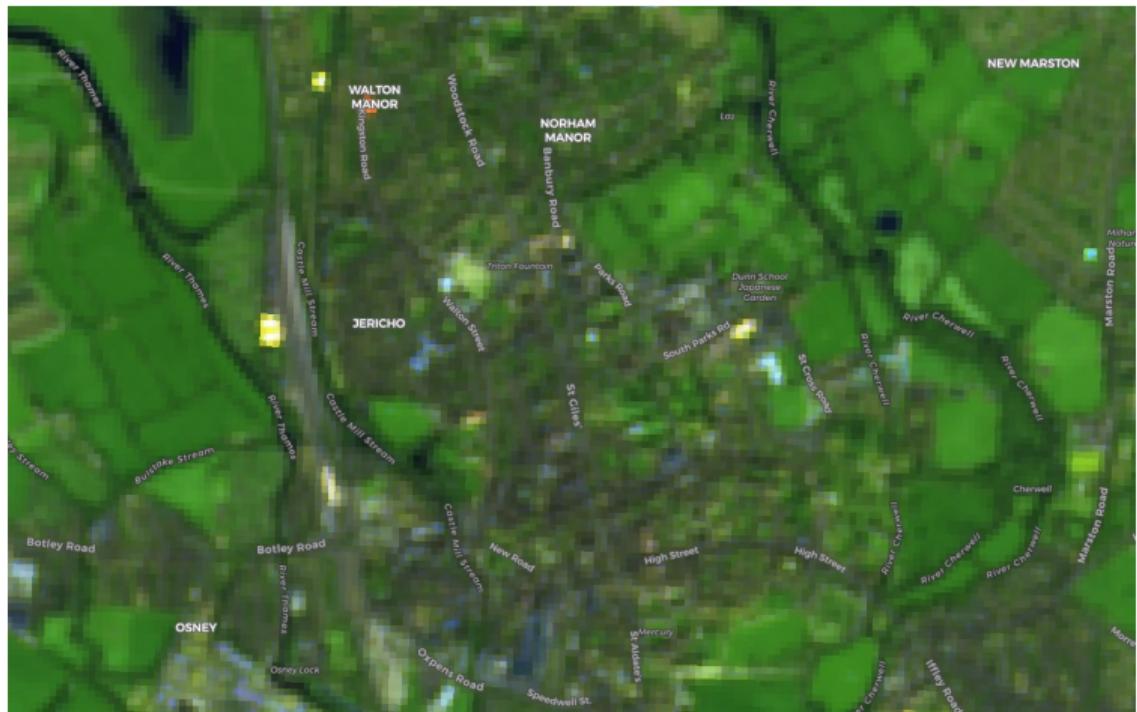
<https://apps.sentinel-hub.com>

# Multi Spectral Satellites – Example Sentinel 2

False Color Urban

$$X = \begin{pmatrix} \rho_{B1} \\ \rho_{B2} \\ \rho_{B3} \\ \rho_{B4} \\ \rho_{B5} \\ \rho_{B6} \\ \rho_{B7} \\ \rho_{B8} \\ \rho_{B8A} \\ \rho_{B9} \\ \rho_{B10} \\ \rho_{B11} \\ \rho_{B12} \end{pmatrix} \xrightarrow{\text{visualize}} \begin{pmatrix} \rho_{B12} \\ \rho_{B11} \\ \rho_{B4} \end{pmatrix}$$

<https://apps.sentinel-hub.com>

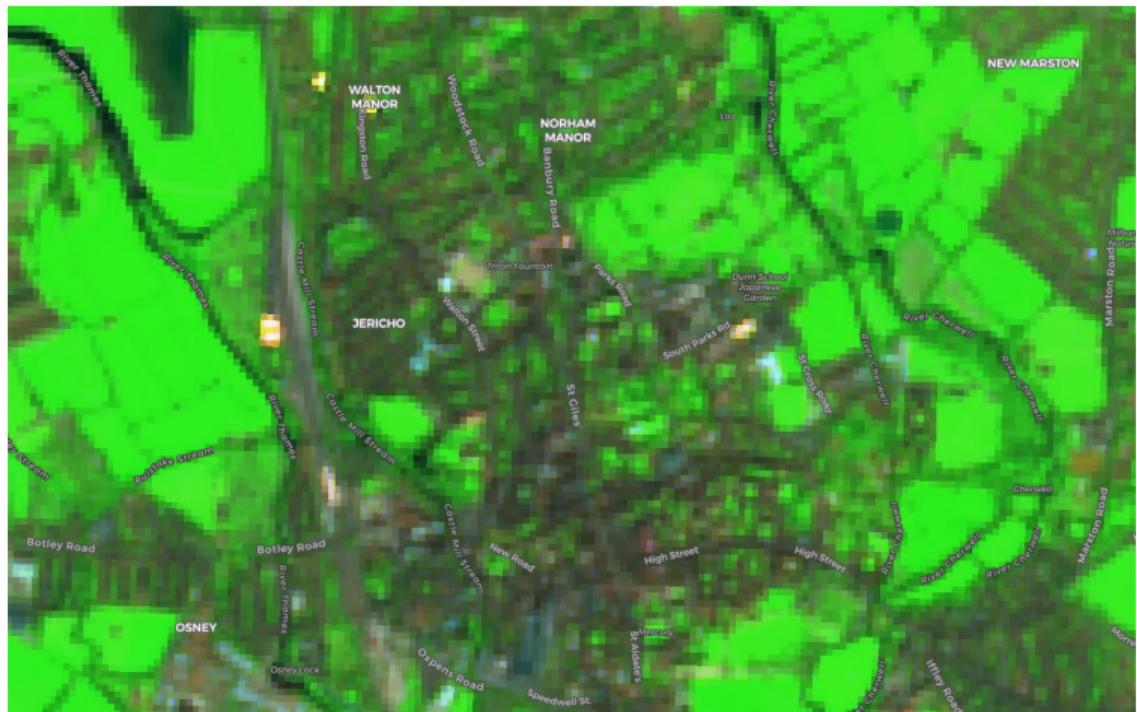


## Multi Spectral Satellites – Example Sentinel 2

## Short-Wave Infra Red Bands

$$X = \begin{pmatrix} \rho_{B1} \\ \rho_{B2} \\ \rho_{B3} \\ \color{orange}\rho_{B4} \\ \rho_{B5} \\ \rho_{B6} \\ \rho_{B7} \\ \rho_{B8} \\ \color{orange}\rho_{B8A} \\ \rho_{B9} \\ \rho_{B10} \\ \rho_{B11} \\ \color{orange}\rho_{B12} \end{pmatrix} \xrightarrow{\text{visualize}} \begin{pmatrix} \rho_{B12} \\ \rho_{B8A} \\ \color{orange}\rho_{B4} \end{pmatrix}$$

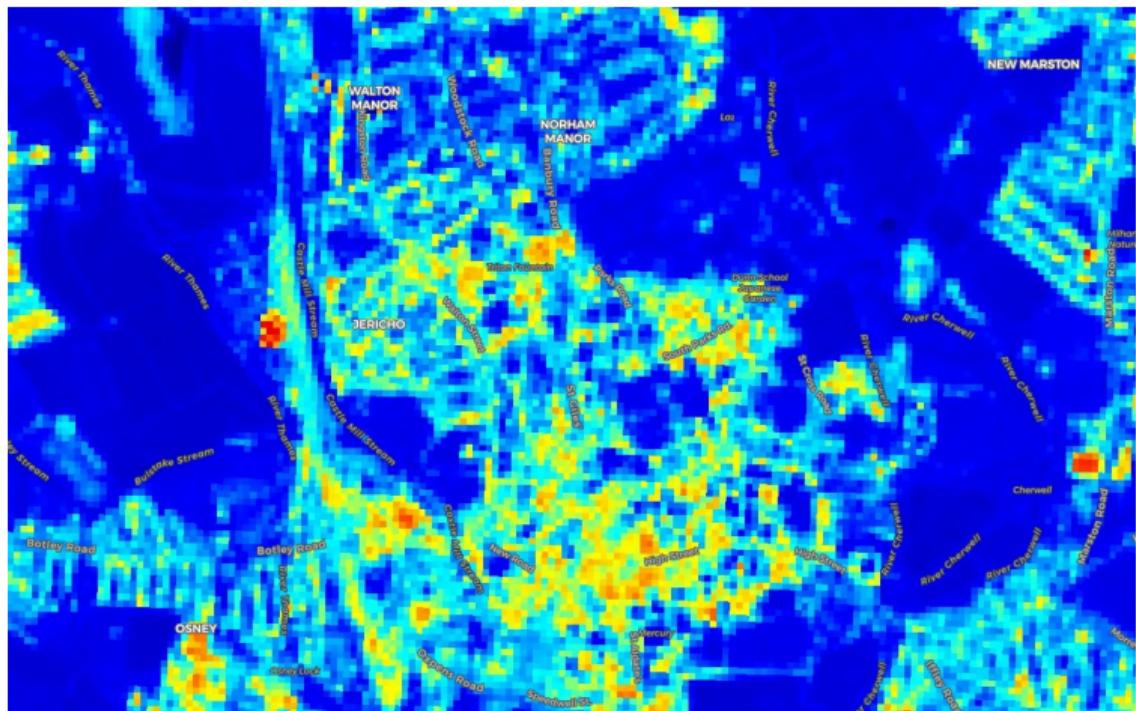
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# Multi Spectral Satellites – Example Sentinel 2

MoistureIndex

$$X = \begin{pmatrix} \rho_{B1} \\ \rho_{B2} \\ \rho_{B3} \\ \rho_{B4} \\ \rho_{B5} \\ \rho_{B6} \\ \rho_{B7} \\ \rho_{B8} \\ \textcolor{orange}{\rho_{B8A}} \\ \rho_{B9} \\ \rho_{B10} \\ \textcolor{orange}{\rho_{B11}} \\ \rho_{B12} \end{pmatrix} \xrightarrow{\text{visualize}} \left( \frac{\rho_{B8A} - \rho_{B11}}{\rho_{B8A} + \rho_{B11}} \right)$$



<https://apps.sentinel-hub.com>

## Multi Spectral Satellites – Example Sentinel 2

Vegetation Index (NDVI)

$$X = \begin{pmatrix} \rho_{B1} \\ \rho_{B2} \\ \rho_{B3} \\ \color{red}\rho_{B4} \\ \rho_{B5} \\ \rho_{B6} \\ \rho_{B7} \\ \color{red}\rho_{B8} \\ \rho_{B8A} \\ \rho_{B9} \\ \rho_{B10} \\ \rho_{B11} \\ \rho_{B12} \end{pmatrix} \xrightarrow{\text{visualize}} \left( \frac{\rho_{B8} - \rho_{B4}}{\rho_{B8} + \rho_{B4}} \right)$$

<https://apps.sentinel-hub.com>



## Multi Spectral Satellites – Example Sentinel 2

Water Index (NDWI)

$$X = \begin{pmatrix} \rho_{B1} \\ \rho_{B2} \\ \color{red}\rho_{B3} \\ \rho_{B4} \\ \rho_{B5} \\ \rho_{B6} \\ \rho_{B7} \\ \color{red}\rho_{B8} \\ \rho_{B8A} \\ \rho_{B9} \\ \rho_{B10} \\ \rho_{B11} \\ \rho_{B12} \end{pmatrix} \xrightarrow{\text{visualize}} \left( \frac{\rho_{B3} - \rho_{B8}}{\rho_{B3} + \rho_{B8}} \right)$$

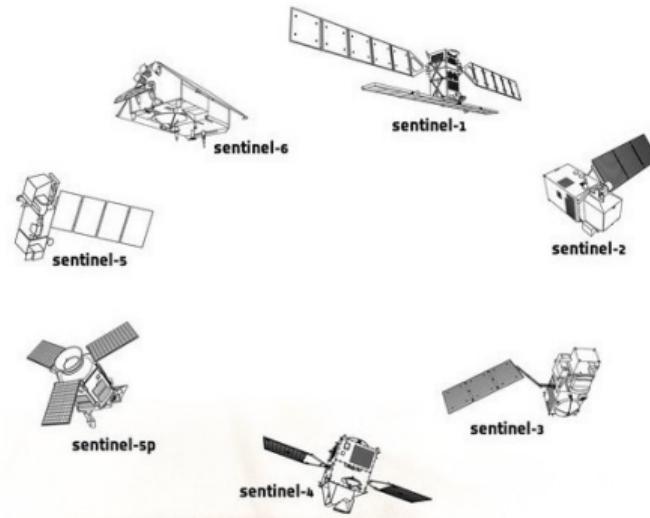
<https://apps.sentinel-hub.com>



**Takeaway:** Each pixel has rich physical information

# Open Data Policy!

This data is acquired globally  
at regular time intervals  
and is completely free to the public



<https://wdc.dlr.de/sensors/modis/>

<https://www.usgs.gov/land-resources/nli/landsat>

[http://www.esa.int/spaceinimages/Images/2014/04/Sentinel\\_family](http://www.esa.int/spaceinimages/Images/2014/04/Sentinel_family)

## High (spatial) Resolution Satellites

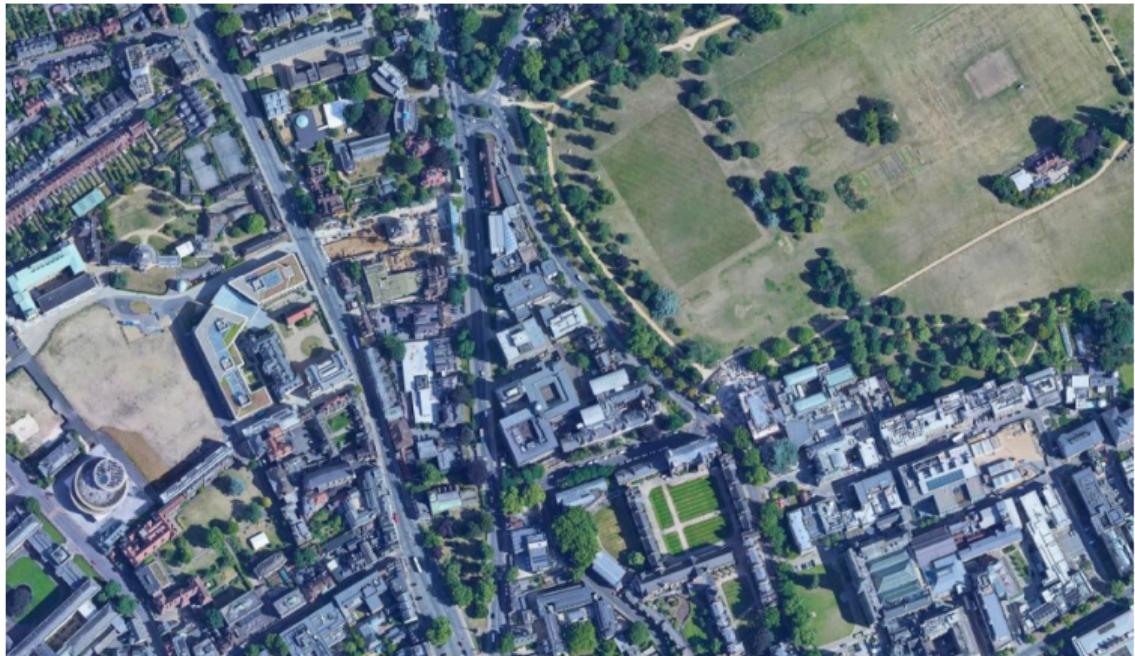
Highest spatial detail (< 1m spatial resolution).

Images acquired on an acquisition schedule

$$\mathbf{X} = \begin{pmatrix} \rho_{\text{red}} \\ \rho_{\text{green}} \\ \rho_{\text{blue}} \\ \rho_{\text{near-infrared}} \end{pmatrix}$$

**AIRBUS** DigitalGlobe

planet.earth



# Computer Vision and High Resolution Data

## SpaceNet Challenge

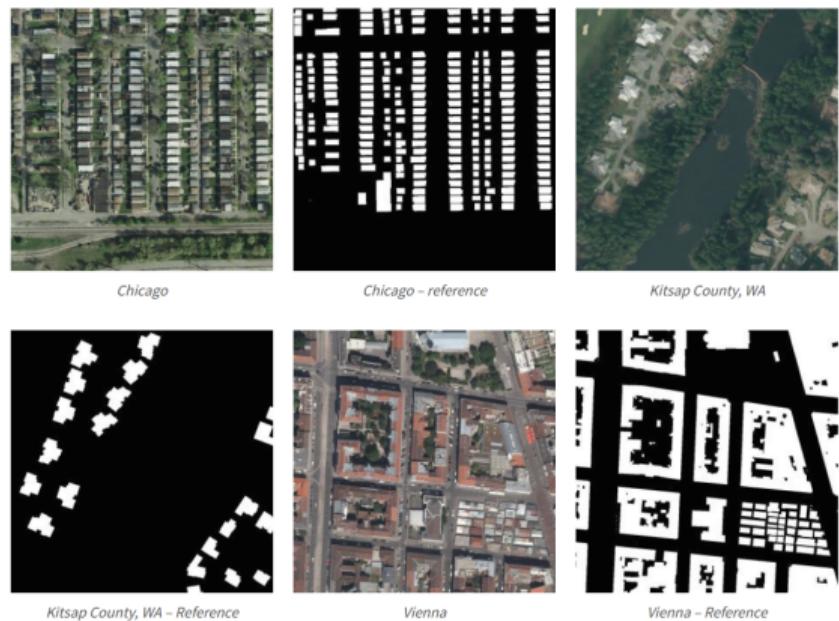
<https://spacenetchallenge.github.io/>

## Inria Aerial Labelling Dataset

<https://project.inria.fr/aerialimagelabeling/>



Inria Aerial Image Labeling Dataset



**Takeaway:**

EO data has potential

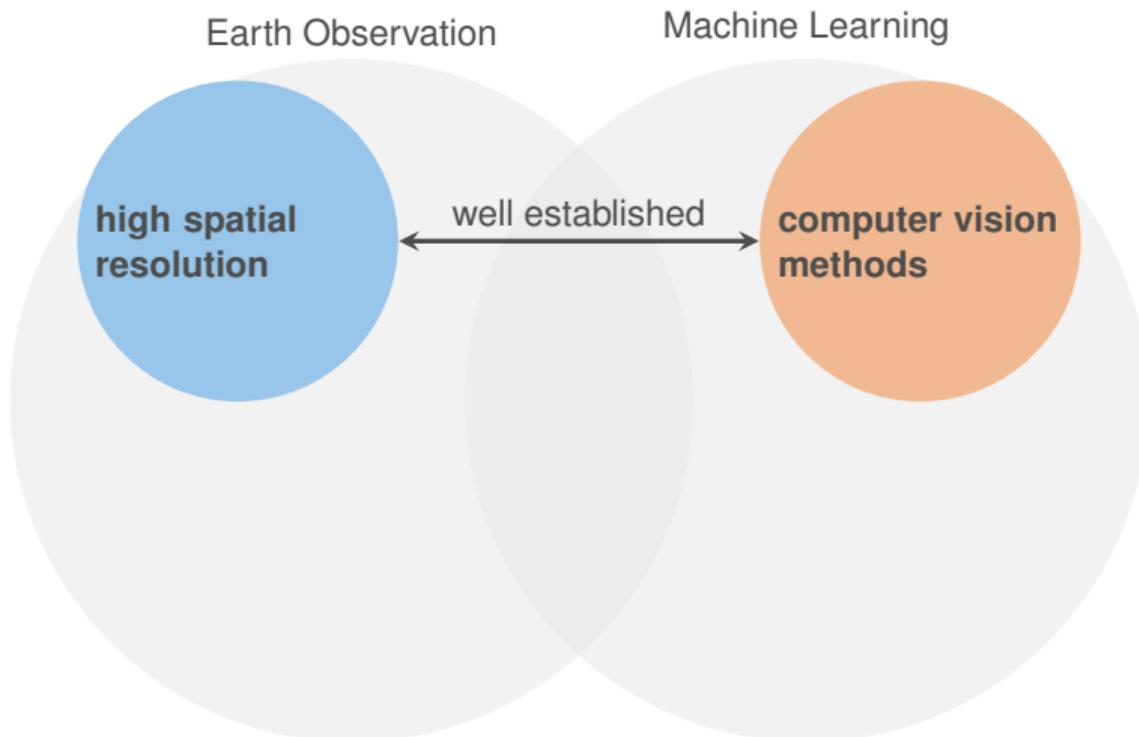
## Takeaway:

only VHR has exposure in ML

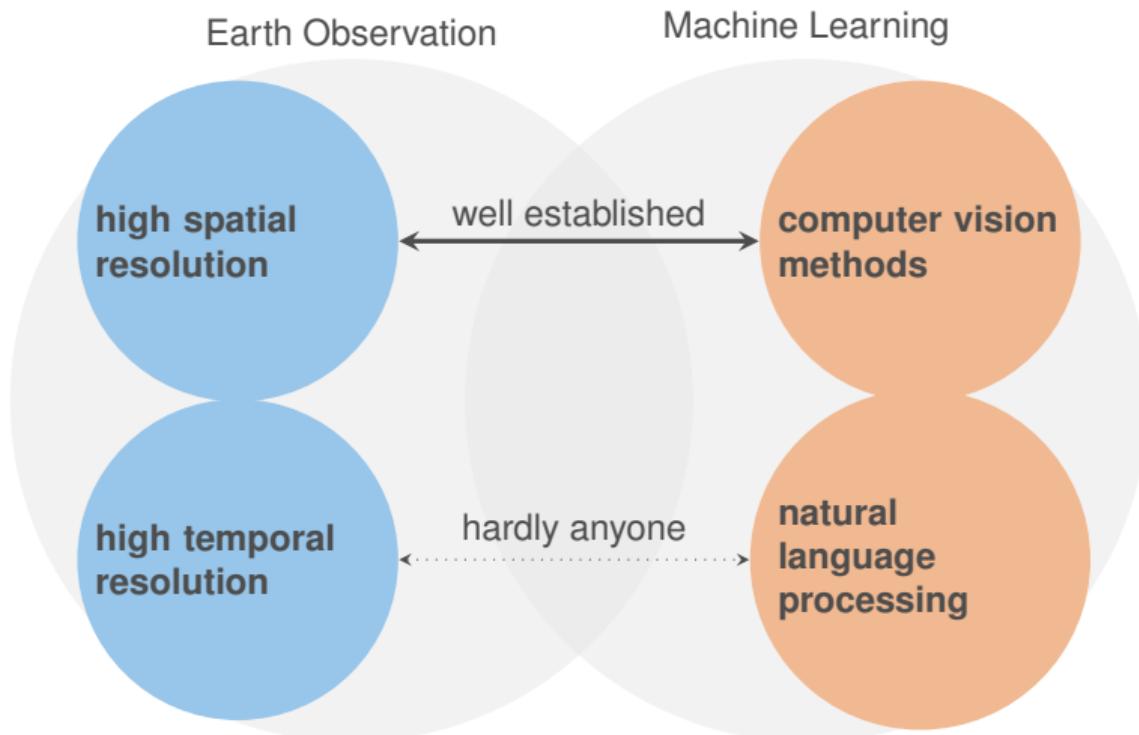
## Part II: Projects and Research



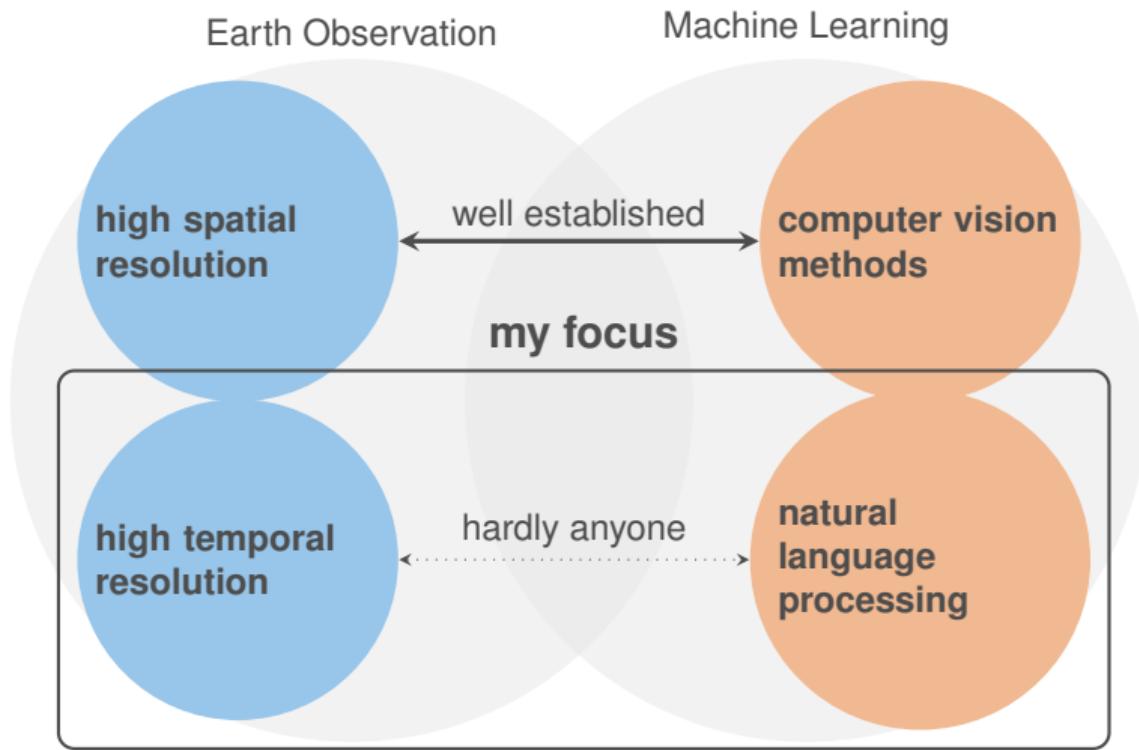
## Multi-temporal Earth observation



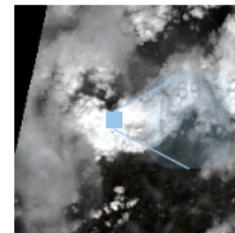
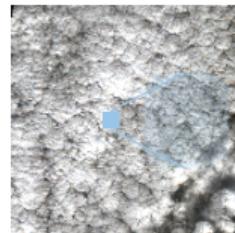
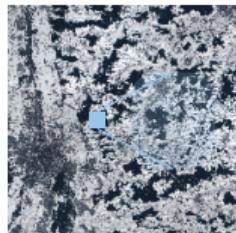
## Multi-temporal Earth observation



# Multi-temporal Earth observation



## Example Analogy to Natural Language Processing

 $x_1$  $x_2$  $x_3$  $x_4$ 

EO model  $\longrightarrow f(\mathbf{X})$

$$E(\text{The}) = \begin{pmatrix} 49 \\ 86 \\ 80 \end{pmatrix}$$

$$E(\text{eagle}) = \begin{pmatrix} 26 \\ 68 \\ 56 \end{pmatrix}$$

$$E(\text{has}) = \begin{pmatrix} 95 \\ 98 \\ 18 \end{pmatrix}$$

$$E(\text{landed}) = \begin{pmatrix} 44 \\ 87 \\ 99 \end{pmatrix} \xrightarrow{\text{NLP model}} f(\mathbf{X})$$

## Structure

**Vegetation Monitoring** Learn a supervised classification model for Vegetation Classification

**Early Time Series Classification** Identify the class as early in the sequence as possible

**Compiling Public Datasets** bringing together the two communities by establishing datasets for multi-temporal Earth Observation data

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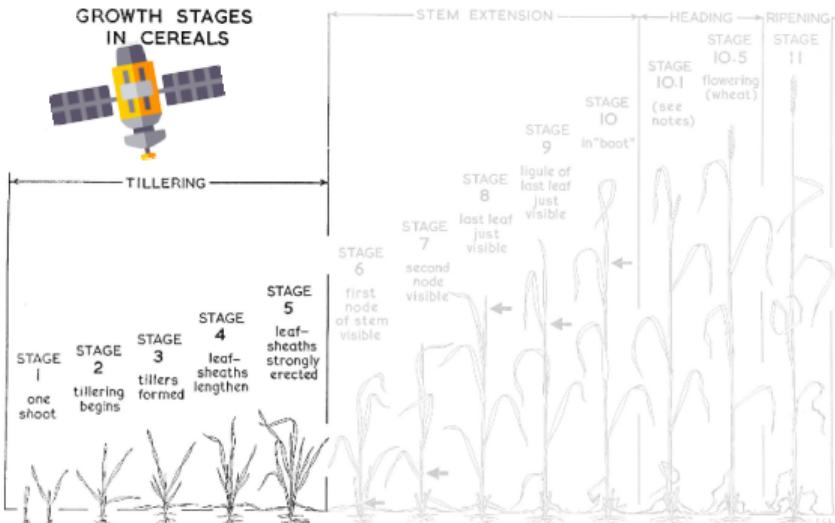
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Vegetation Monitoring



# Multi-temporal Vegetation Monitoring

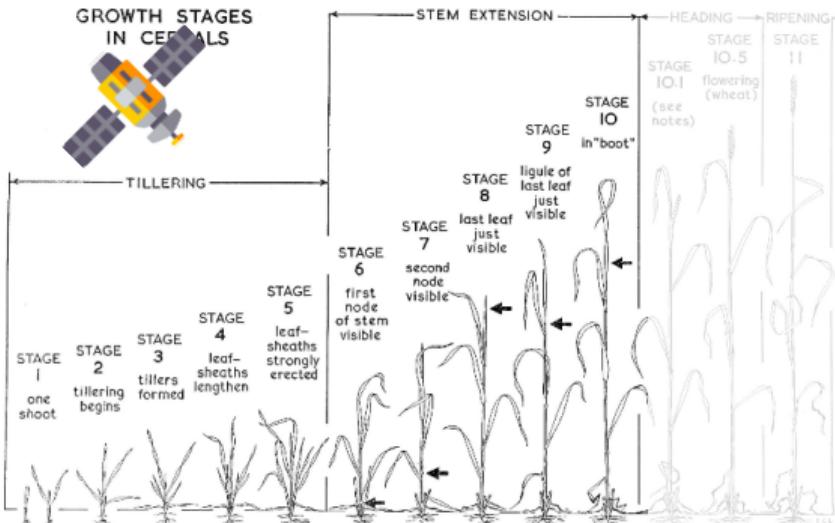


$$\mathbf{y} = f_{\text{phenology}}(\mathbf{x}_t)$$

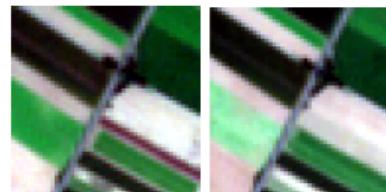


Large, E. C. (1954). Growth stages in cereals illustration of the Feekes scale. Plant pathology, 3(4), 128-129.

# Multi-temporal Vegetation Monitoring

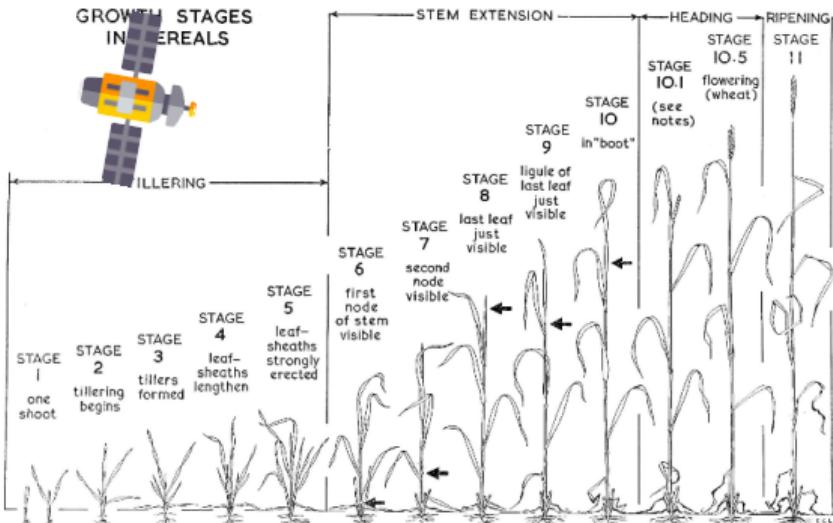


$$\mathbf{y} = f_{\text{phenology}}(\mathbf{x}_t, \mathbf{x}_{t+1})$$



Large, E. C. (1954). Growth stages in cereals illustration of the Feekes scale. Plant pathology, 3(4), 128-129.

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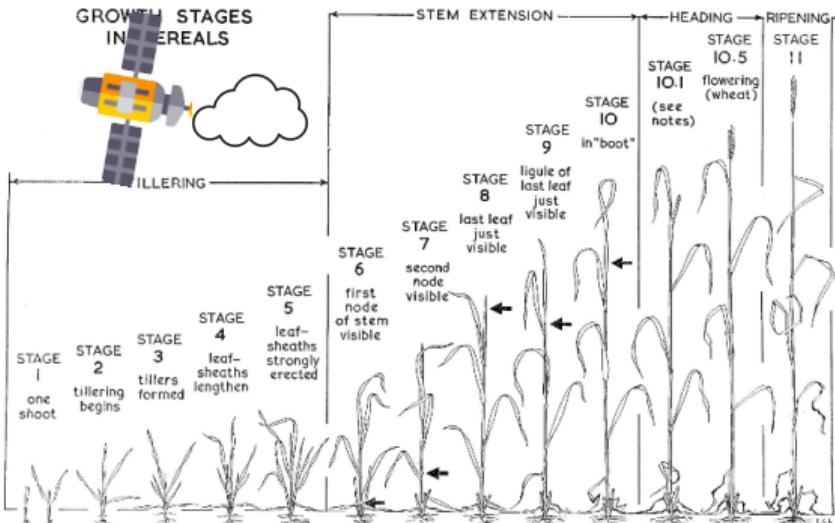


$$\mathbf{y} = f_{\text{phenology}}(\mathbf{x}_t, \mathbf{x}_{t+1}, \mathbf{x}_{t+2})$$



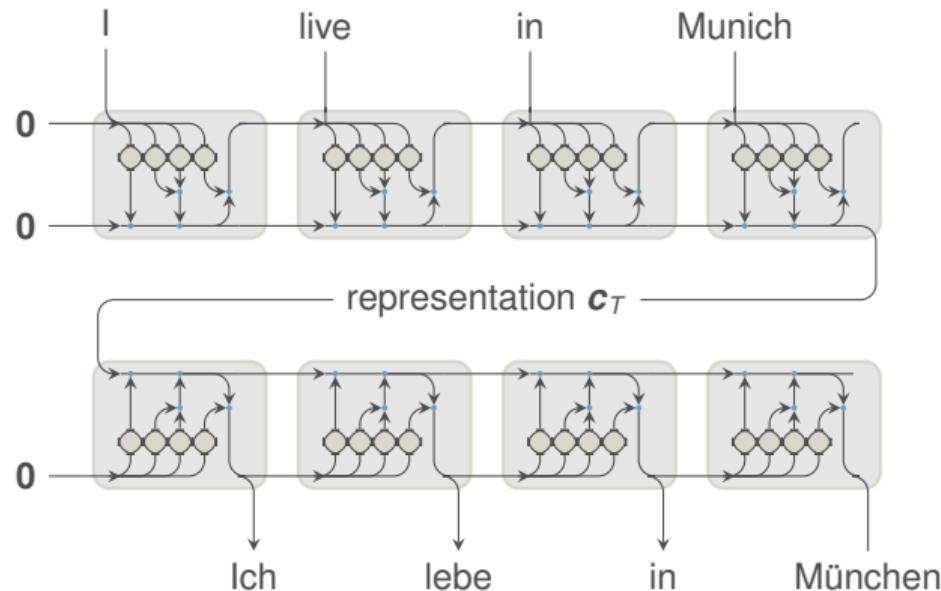
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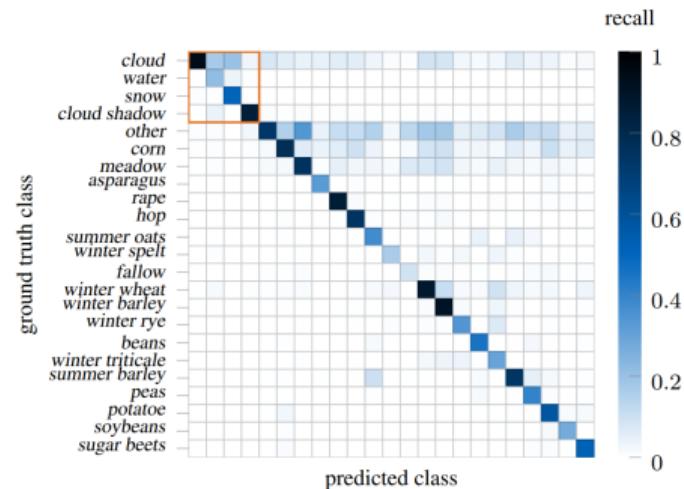
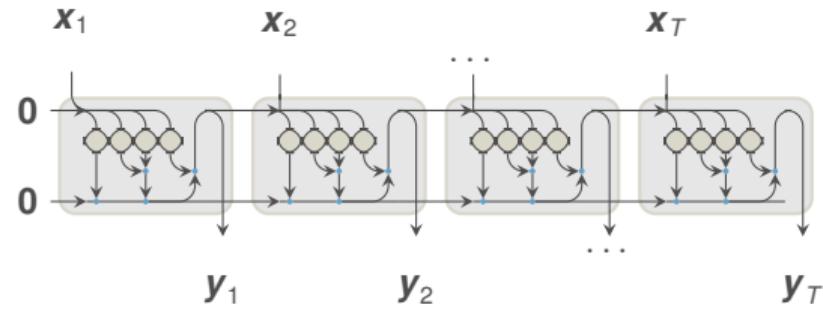
## Looking at Sequence to Sequence Models from NLP



Sutskever, I., Vinyals, O., & Le, Q. V. (2014). Sequence to sequence learning with neural networks. In Advances in neural information processing systems (pp. 3104-3112).

# Temporal Vegetation Modelling with LSTMs

CVPR Earthvision 2017



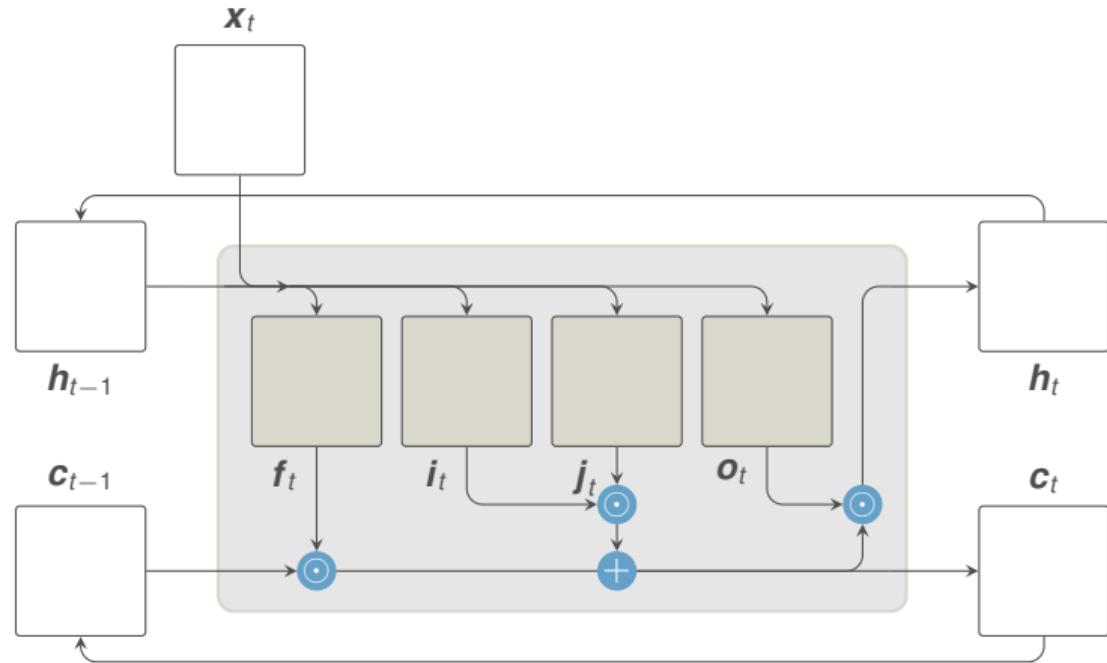
Rußwurm, M. and Körner, M. (2017). **Temporal Vegetation Modelling using Long Short-Term Memory Networks for Crop Identification from Medium-Resolution Multi-Spectral Satellite Images**. In IEEE/ISPRS EarthVision 2017 Workshop, Proceedings of the IEEE CVPR Workshops. **Best Paper Award**

# Recurrent Convolutional Neural Networks

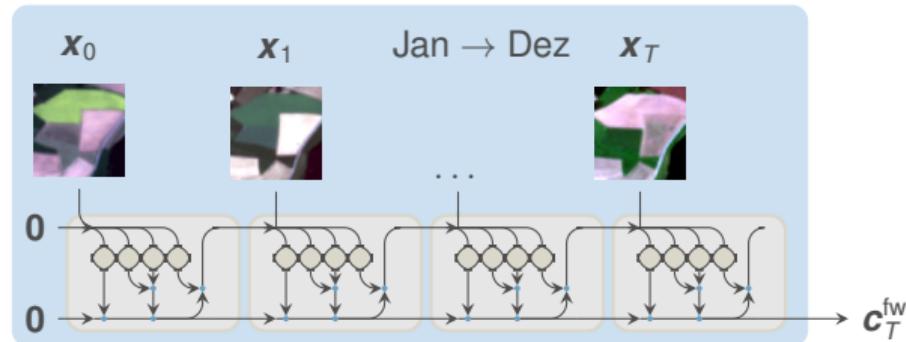
Convolutional Long Short-Term Memory — ConvLSTM (Hochreiter & Schmidhuber, 1997)

## Convolutional LSTM:

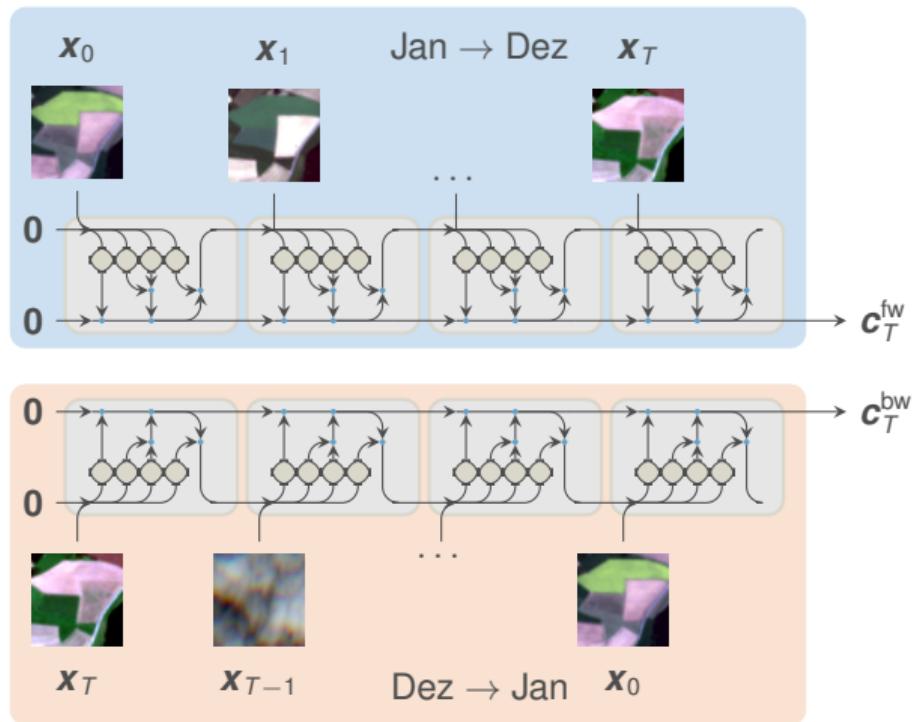
Xingjian, S. H. I., Chen, Z., Wang, H., Yeung, D. Y., Wong, W. K., & Woo, W. C. (2015). Convolutional LSTM network: A machine learning approach for precipitation nowcasting. In Advances in neural information processing systems (pp. 802-810).



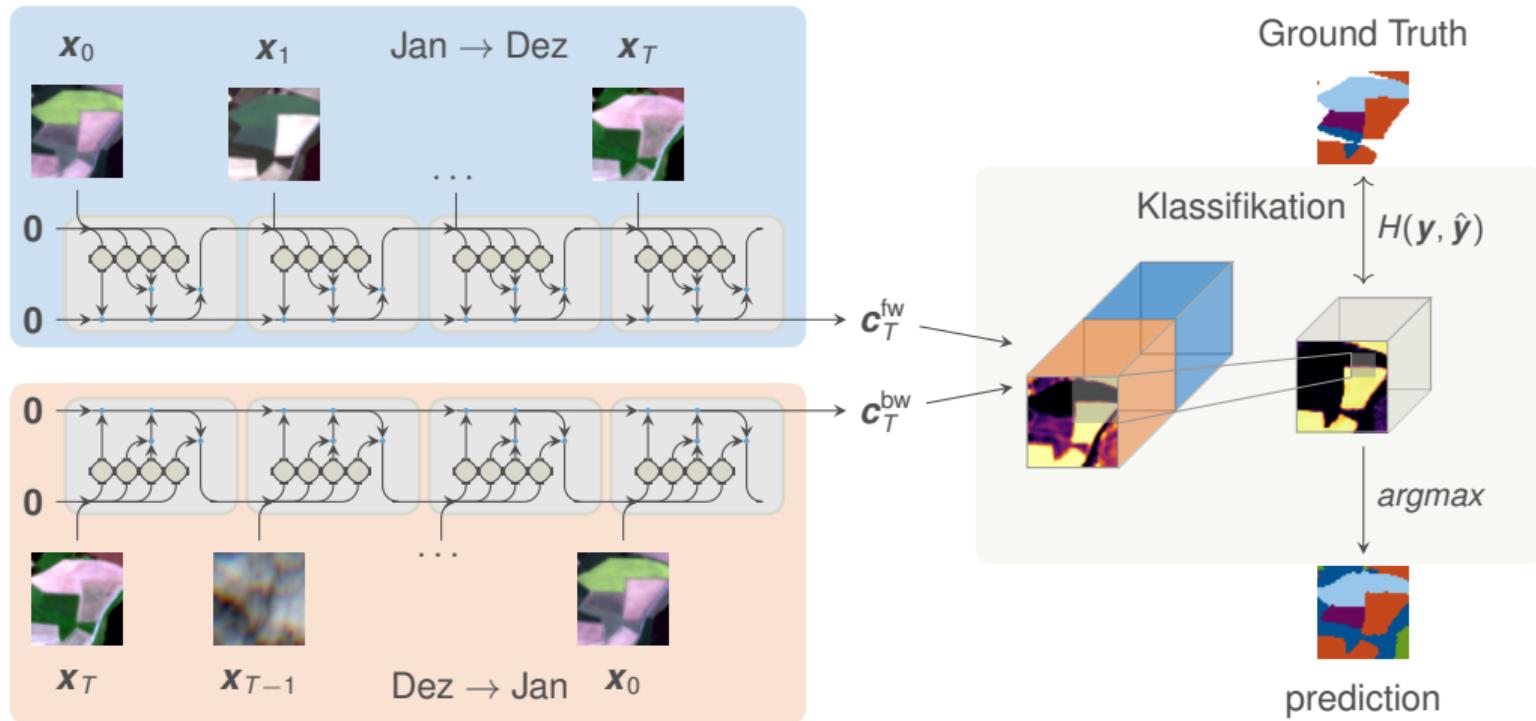
## Classification ConvLSTM Network



## Classification ConvLSTM Network

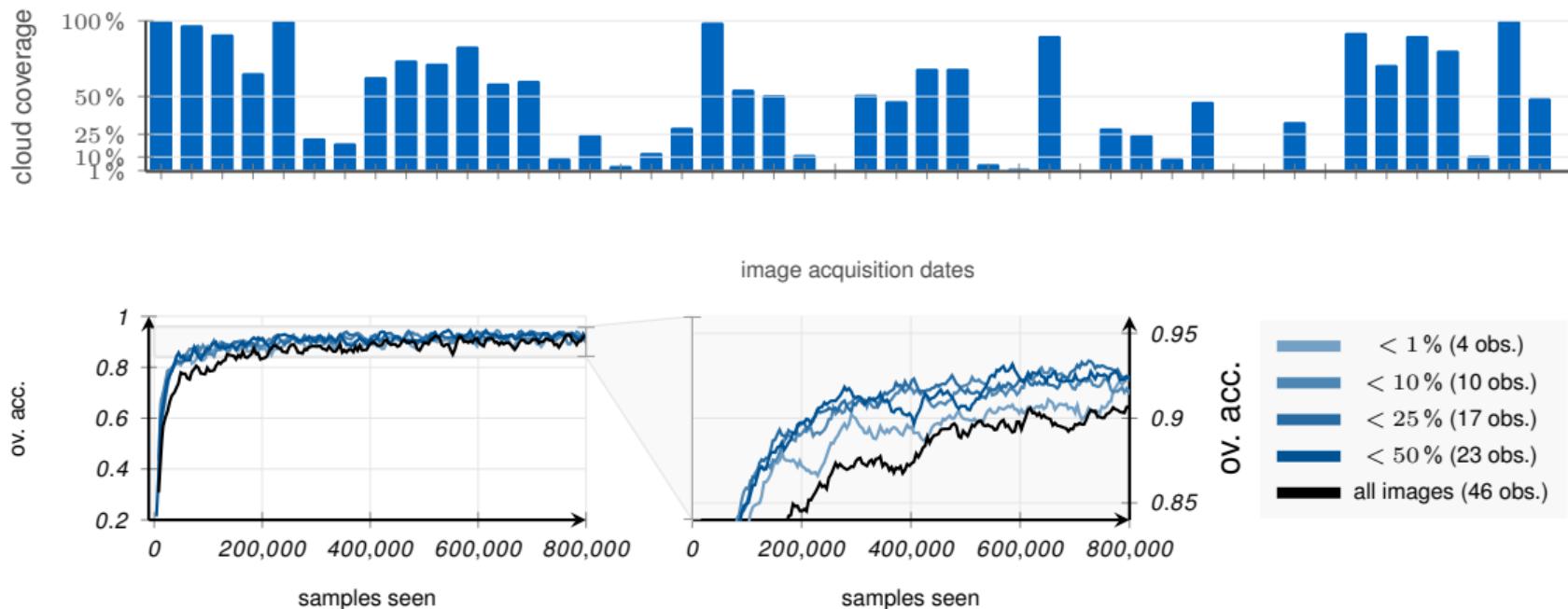


# Classification ConvLSTM Network



**Surprise:** It worked without specifically labeling clouds!

## ConvLSTM robust to clouds



# Remembering Karpathy's "Unreasonable Effectiveness of RNNs"

Cell sensitive to position in line:

The sole importance of the crossing of the Berezina lies in the fact that it plainly and indubitably proved the fallacy of all the plans for cutting off the enemy's retreat and the soundness of the only possible line of action--the one Kutuzov and the general mass of the army demanded--namely, simply to follow the enemy up. The French crowd fled at a continually increasing speed and all its energy was directed to reaching its goal. It fled like a wounded animal and it was impossible to block its path. This was shown not so much by the arrangements it made for crossing as by what took place at the bridges. When the bridges broke down, unarmed soldiers, people from Moscow and women with children who were with the French transport, all--carried on by vis inertiae--pressed forward into boats and into the ice-covered water and did not, surrender.

Cell that turns on inside quotes:

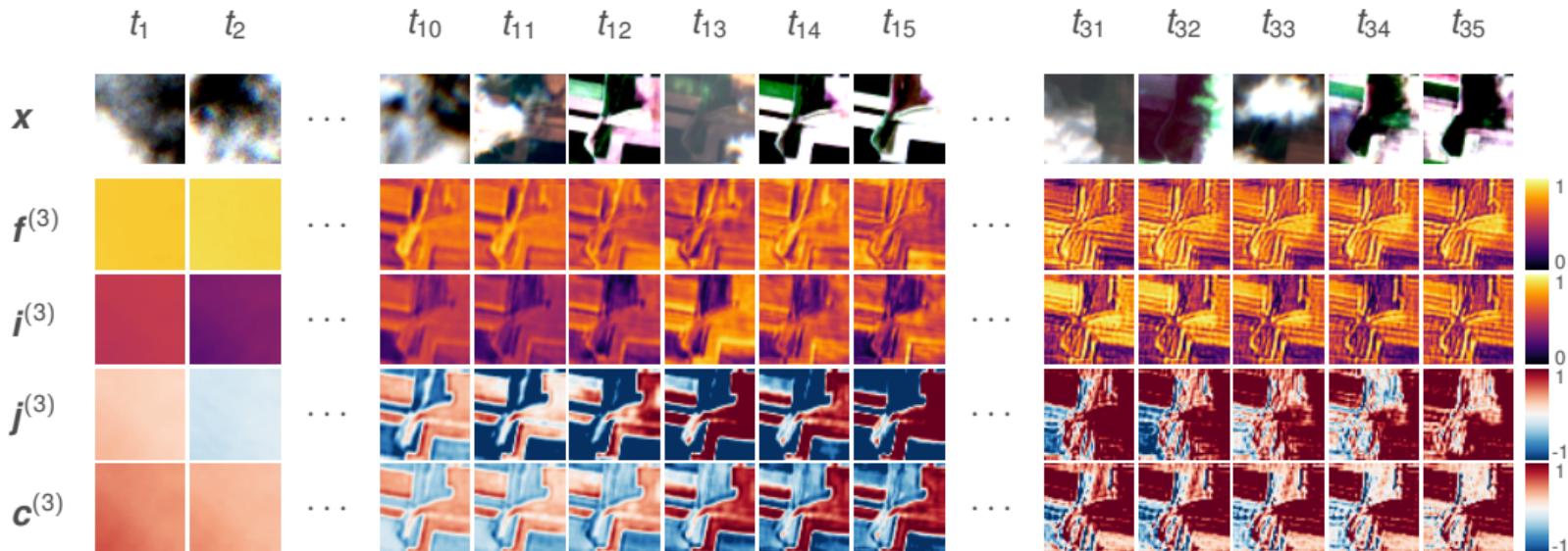
"You mean to imply that I have nothing to eat out of.... On the contrary, I can supply you with everything even if you want to give dinner parties," warmly replied Chichagov, who tried by every word he spoke to prove his own rectitude and therefore imagined Kutuzov to be animated by the same desire.

Kutuzov, shrugging his shoulders, replied with his subtle penetrating smile: "I meant merely to say what I said."

<http://karpathy.github.io/2015/05/21/rnn-effectiveness/>

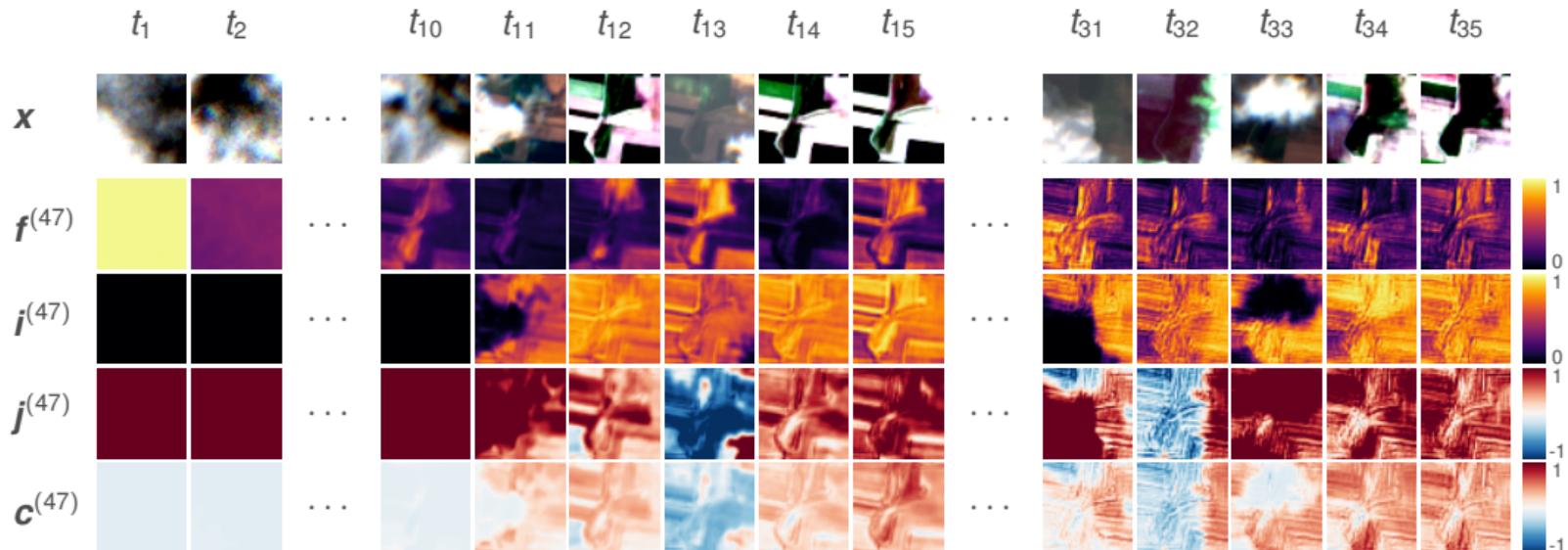
# Internal States Encode increasingly Classification Features

LSTM cell 47 of 256



# Found Cloud Masking Cells in the RNN

LSTM cell 47 of 256



## Paper and Code

Github + DockerHub + Continuation with GAF AG



<https://github.com/TUM-LMF/MTLCC> <https://github.com/TUM-LMF/MTLCC-pytorch>  
<http://www.lmf.bgu.tum.de/vision/>

Rußwurm, M. and Körner, M. (2017). *Temporal Vegetation Modelling using Long Short-Term Memory Networks for Crop Identification from Medium-Resolution Multi-Spectral Satellite Images*. In IEEE/ISPRS EarthVision 2017 Workshop, Proceedings of the IEEE CVPR Workshops.

Rußwurm M., Körner M. (2018). *Multi-Temporal Land Cover Classification with Sequential Recurrent Encoders*. ISPRS International Journal of Geo-Information. <https://arxiv.org/abs/1802.02080>. (in review)



**Early Time Series  
Classification**



**IRISA**

# Winter Research Stay at IRISA Obelix Lab in France

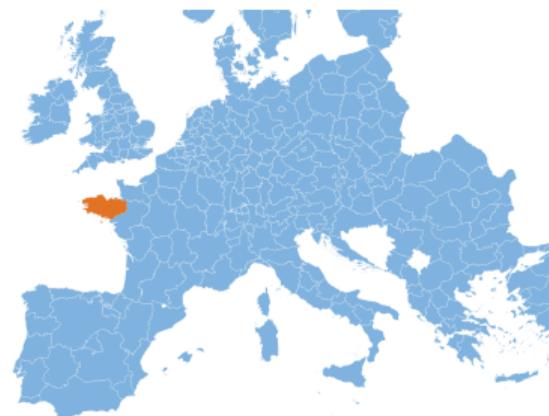
Research Stay

Prof. Sébastien Lefèvre and Prof. Romain Tavenard

Obelix: Environment observation with complex imagery

Vannes and Rennes, Brittany, France

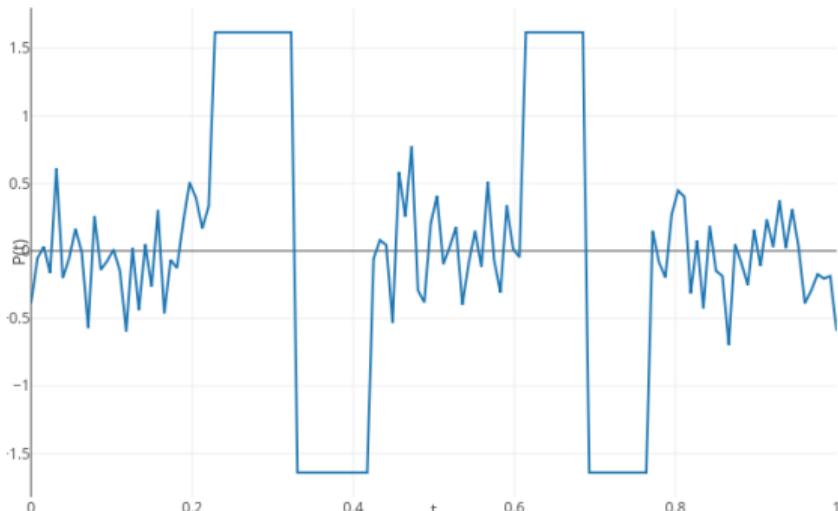
<http://www-obelix.irisa.fr/>



## Class Predictions

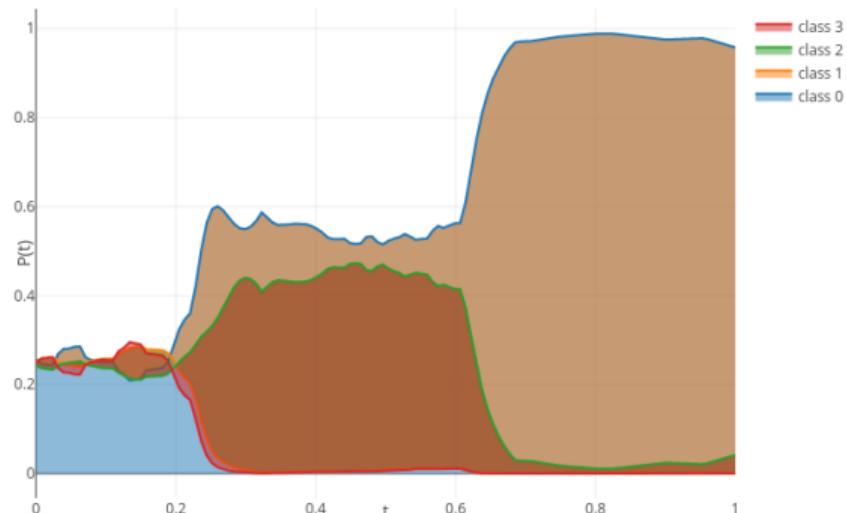
inputs  $x_t$

sample 0  $x$  (class=0)



softmaxed class scores  $\hat{y}_t$

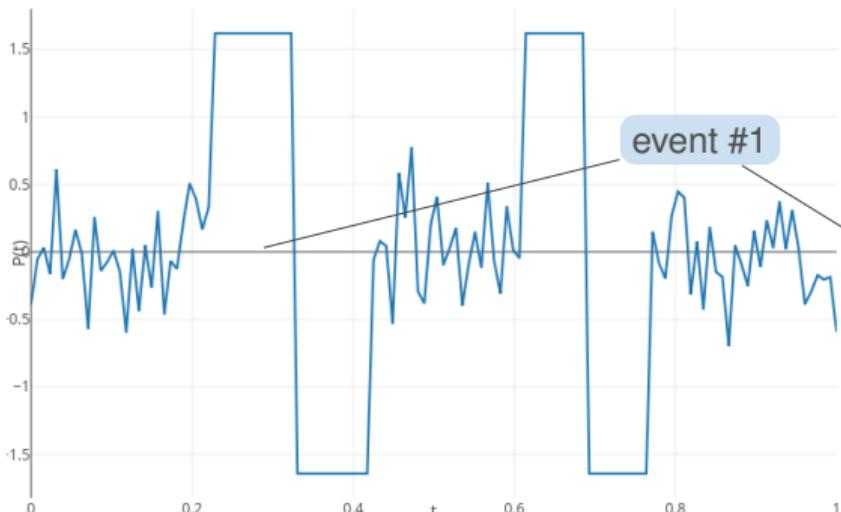
sample 0  $P(y)$  (class=0)



## Class Predictions

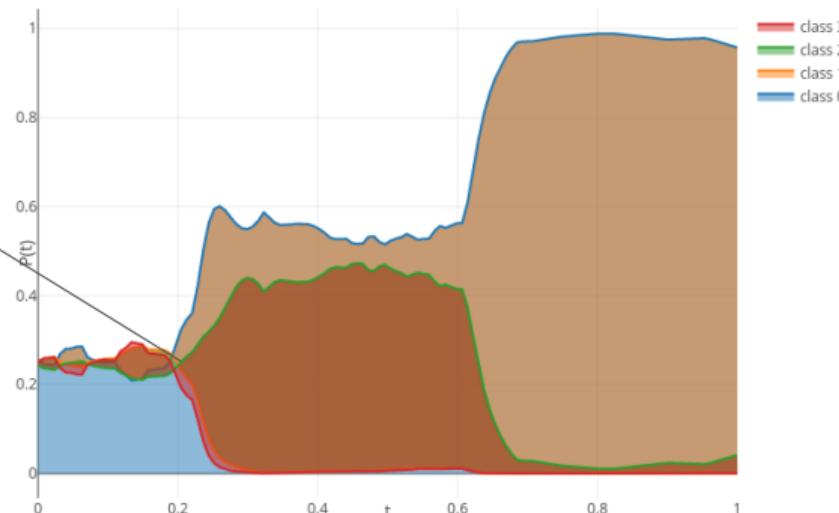
inputs  $x_t$

sample 0  $x$  (class=0)



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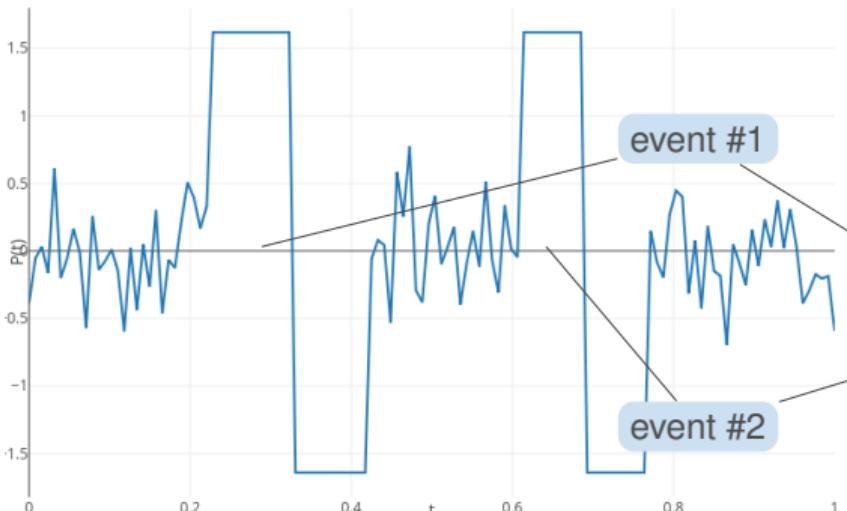
sample 0  $P(y)$  (class=0)



## Class Predictions

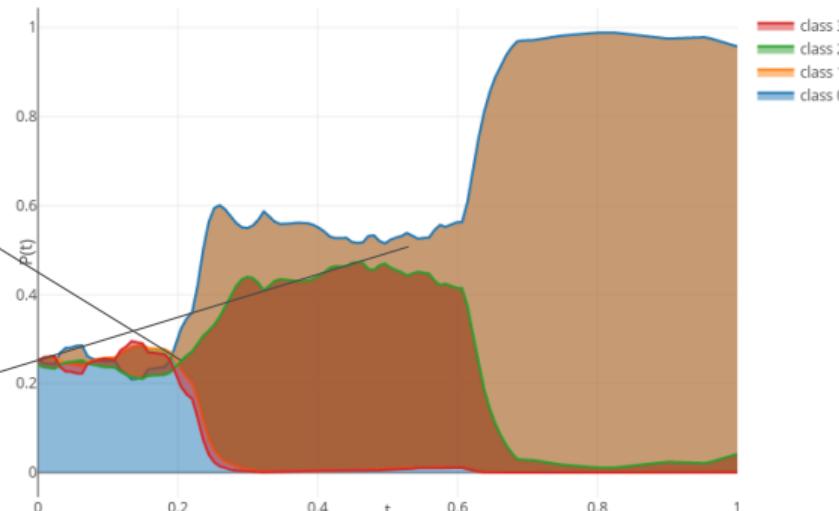
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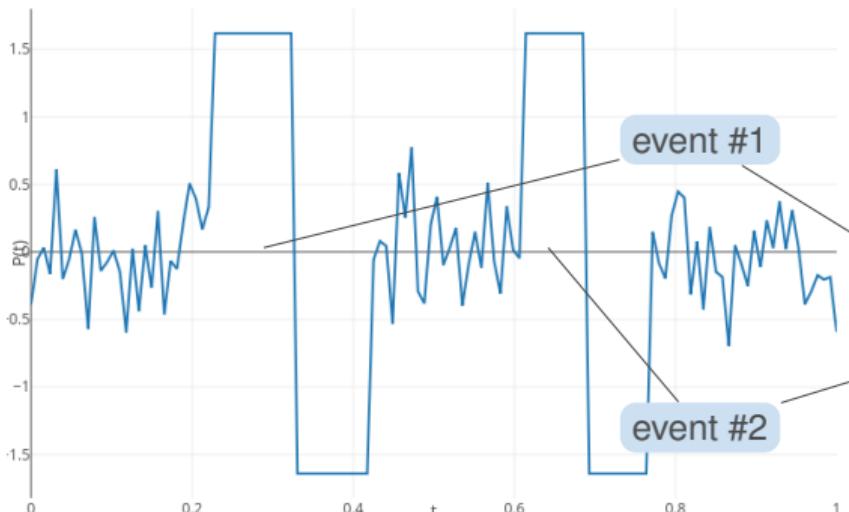
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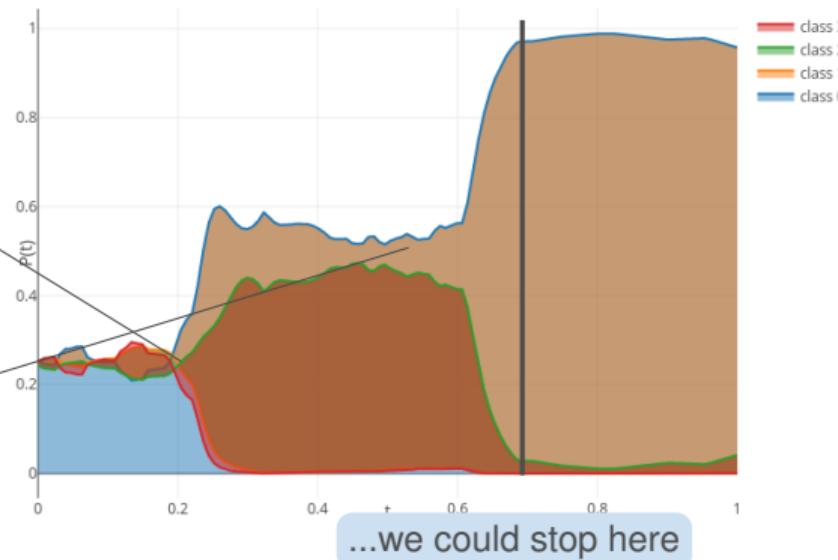
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# ArXiv Paper: End-to-end Learning for Early Classification of Time Series

Rußwurm, M., Lefèvre, S., Courty, N., Emonet, R., Körner, M., & Tavenard, R. (2019). **End-to-end Learning for Early Classification of Time Series.** arXiv preprint arXiv:1901.10681.

arXiv:1901.10681v1 [cs.LG] 30 Jan 2019

## End-to-end Learning for Early Classification of Time Series

Marc Russwurm<sup>1,\*</sup>, Sébastien Lefèvre<sup>2</sup>, Nicolas Courty<sup>2,†</sup>, Rined Emonet<sup>3</sup>, Marco Körner<sup>1</sup>, Romain Tavenard<sup>1,‡</sup>

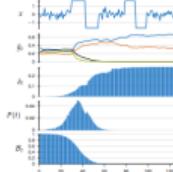
### Abstract

Classification of time series is a topical issue in machine learning. While accuracy stands for the most important evaluation criterion, some applications require to evaluate the model's performance as early as possible. Optimization should then target a compromise between both metrics, i.e., a capacity of predicting the class of a time series while maintaining accuracy. In this work, we propose a generic, end-to-end learning framework for early classification of time series. This framework embeds a learnable decision mechanism that can be plugged into a wide range of neural network topologies. We compare our results obtained with deep neural networks on a diverse set of time series classification problems. Our approach is competitive with state-of-the-art competitors while being easily adaptable by any existing neural network topology that evaluates a hidden state at each time step.

### 1. Introduction

Classification of time series is a common problem in machine learning. Learning methods, such as deep networks, are very efficient at achieving high classification accuracy when predicting on a test set. However, there are some contexts where the accuracy is not the single goal. For instance, when the classification accuracy is not high enough to treat the patient with the most appropriate treatment as early as possible by space-time imagery analysis allows local authorities to distribute resources efficiently and prevent the spread of disease. The need for early classification in machine learning is known as early classification (Xing et al., 2012).

Early classification methods generally rely on a learning architecture that performs a classification only after obtaining enough information. This is often done by collecting a large amount of data and then training a classifier. This approach is not always feasible, especially when the data collection process is slow and expensive. To overcome this limitation, we propose an end-to-end learning framework that is optimized jointly on accuracy and time by collecting a stopping probability  $\delta$ . Based on a fixed budget  $B$ , the learning framework optimizes the stopping probability  $\delta$  parametrized accordingly with respect to our loss function. The proposed framework is able to learn the best stopping probability  $\delta$  for a given budget  $B$ .

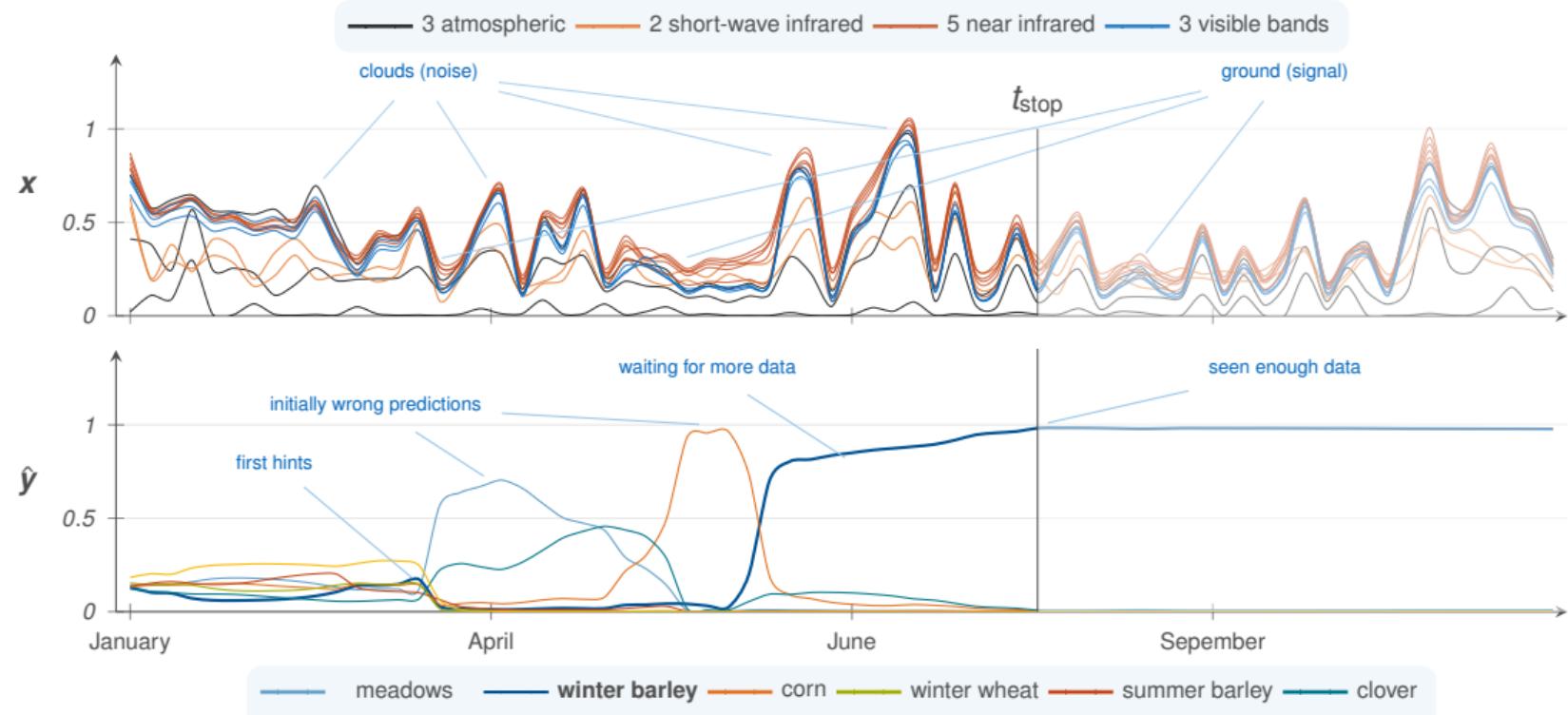


**Figure 1.** Qualitative example of the learnable decision mechanism produced by a 1D convolutional model. The model evaluates a sequence of hidden states  $g_t$  over time. The learned decision boundary  $g_t$  and a stopping probability  $p_t$  are derived. To parameterize this stopping probability at training time, an optimization algorithm minimizes the loss function based on a given budget  $B$ , as shown in the bottom two figures.

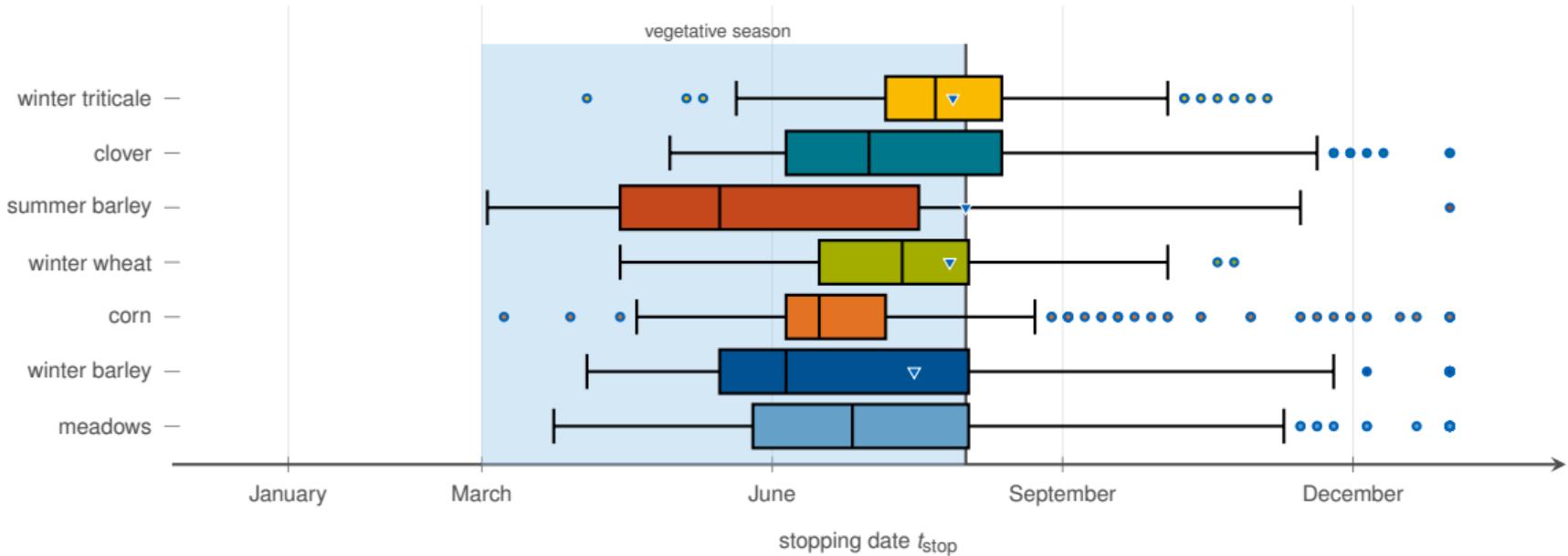
and it designs an early stopping criterion that utilizes predictions from these classifiers.

Compared to existing works, we propose an end-to-end learning framework that is optimized jointly on accuracy and time by collecting a stopping probability  $\delta$ . Based on a fixed budget  $B$ , the learning framework optimizes the stopping probability  $\delta$  parametrized accordingly with respect to our loss function. This is used to focus the loss penalty to specific times in the sequence and is subtracted from a monotonically decreasing loss function. The loss function is then used to train the components. Note that the stopping probability  $\delta$  increases after processing a classification characteris-

# Early Classification on Remote Sensing Data



## Stopping times per crop Class



# Impact of Early Classification on Vegetation Data

**supervised end-to-end** learning scenario

we get a stopping time **for free** solely from classifying labels

relate to **characteristic features**, i.e., **crop phenology**

next: assess seasonal shifts in **vegetation phenology** due to **environmental conditions**

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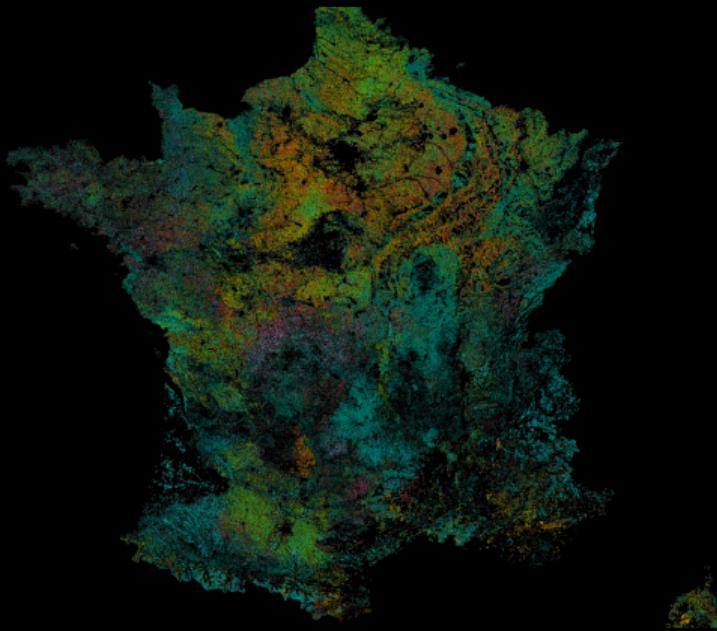
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# Compiling Datasets



## Two Perspectives

### Earth Observation

**method** is a **tool** for our  
**data**

**should generalize** to  
applications of a  
specific sub-field

data has specific  
**physical properties**

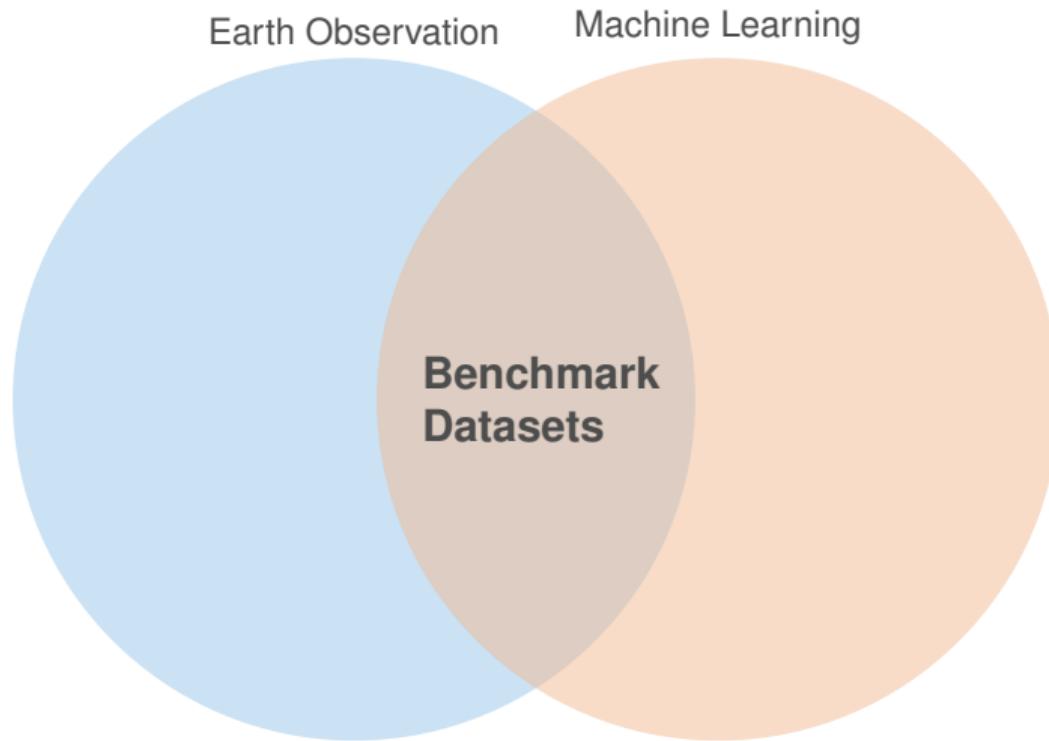
### Machine Learning

**data** is a **benchmark**  
for our **method**

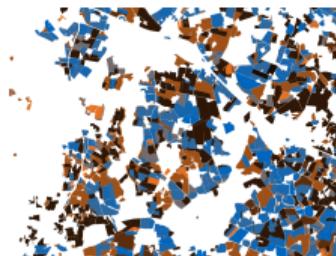
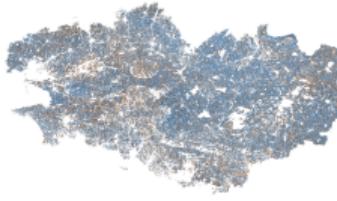
**must generalize** to  
many fields of applica-  
tions

data is a **feature vector**

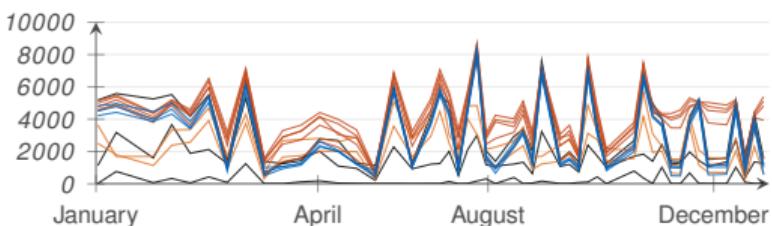
## Common Datasets



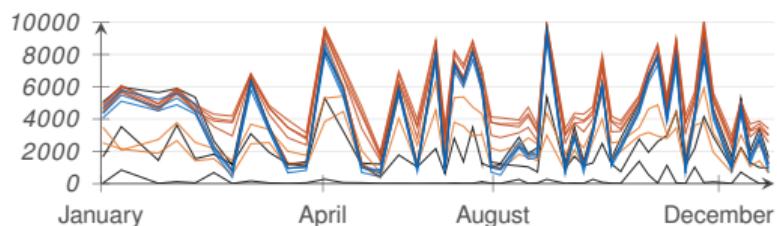
## BreizhCrops Dataset (available by next week!)



**corn grain and silage**



**temporary meadows**



580k samples of Time Series  $X$  and labels  $y$ .

<https://github.com/TUM-LMF/BreizhCrops>

## Challenges and Impact

### Impact

large scale **real-world dataset**

effectively **unlimited data** (spatially and temporally)

**assessing generalization** over large regions

potential for further **vegetation characteristics** (drought indicator, early classification, crop yield)

## Challenges and Impact

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large scale **real-world dataset**

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### Challenges

**Imbalanced class labels**

Classes with **similar characteristics**

Non-Gaussian noise induced by **clouds**

**Regional variations** in the class distributions

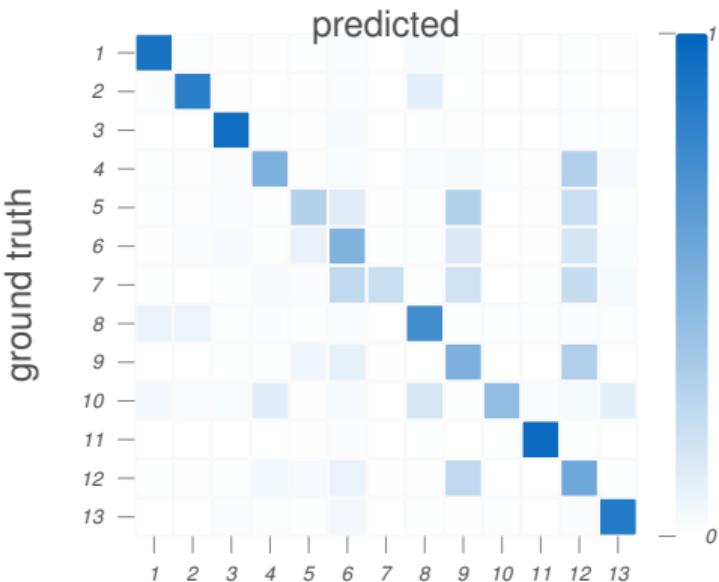
**Spatial autocorrelation**

**Irregular temporal sampling** distance

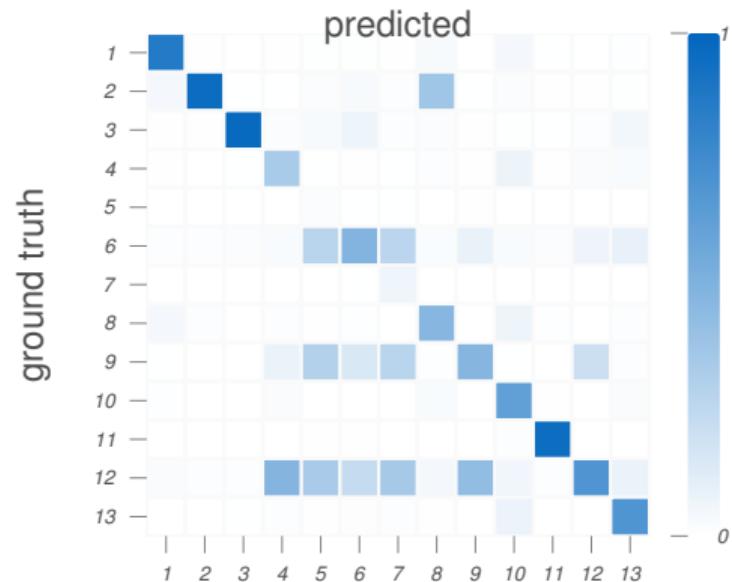
**Variable sequence length**

# Multi-Layer RNN baseline

Precision

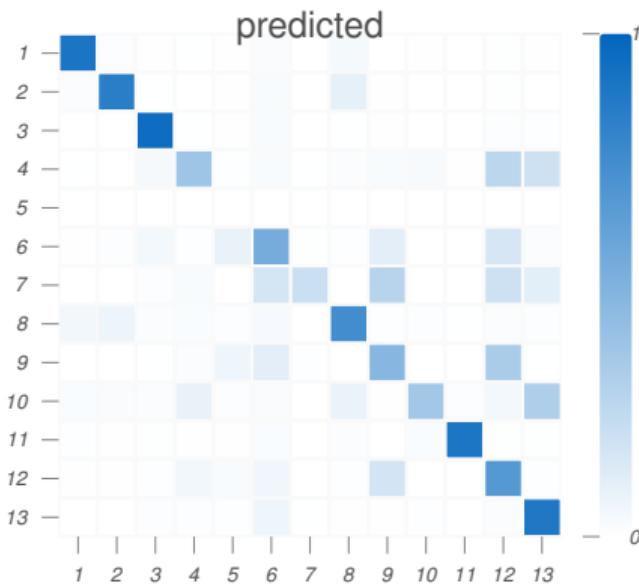


Recall

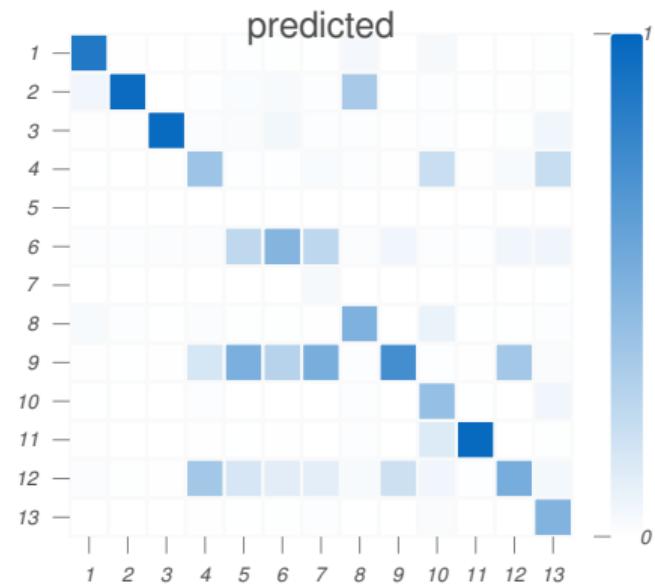


## Transformer baseline

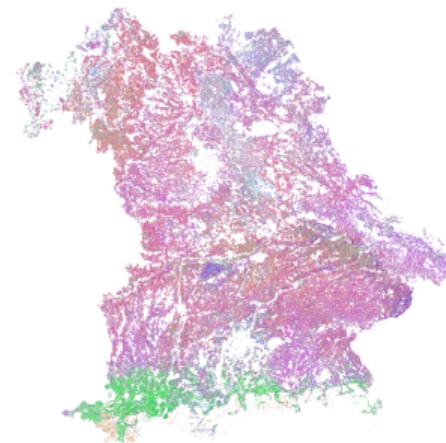
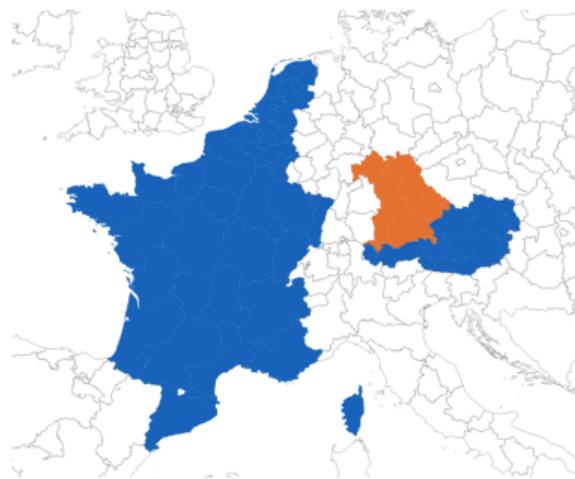
ground truth



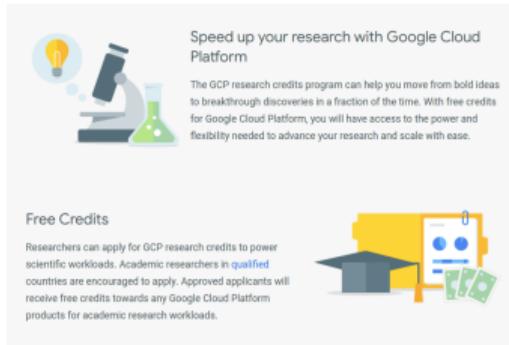
ground truth



Going Big...



# Supported by Google Research Credits



Speed up your research with Google Cloud Platform

The GCP research credits program can help you move from bold ideas to breakthrough discoveries in a fraction of the time. With free credits for Google Cloud Platform, you will have access to the power and flexibility needed to advance your research and scale with ease.

**Free Credits**

Researchers can apply for GCP research credits to power scientific workloads. Academic researchers in **qualified countries** are encouraged to apply. Approved applicants will receive free credits towards any Google Cloud Platform products for academic research workloads.



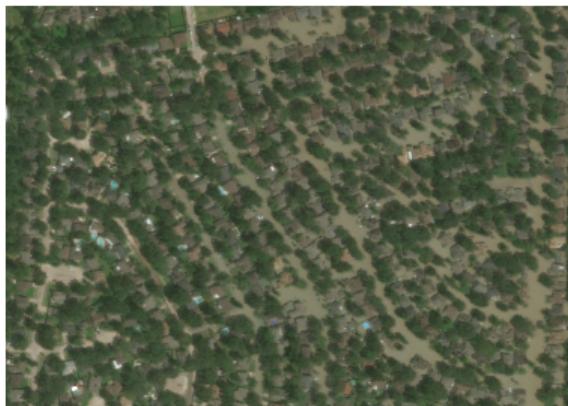
## Part III: Initiatives between EO and ML

# Satellite Data Fusion for disaster response



# Detection of Flooded Buildings with Multi-Sensor Data Fusion

0.5m post-disaster



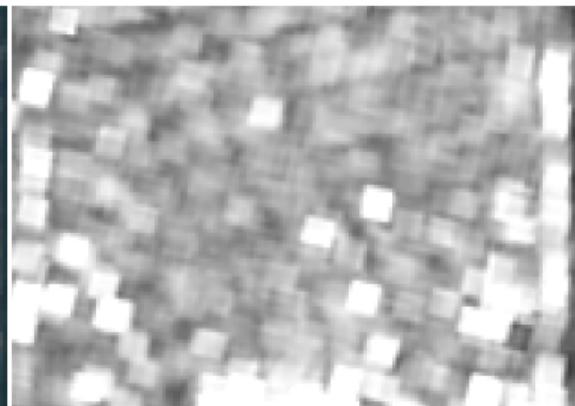
very high resolution

10m pre-disaster



optical

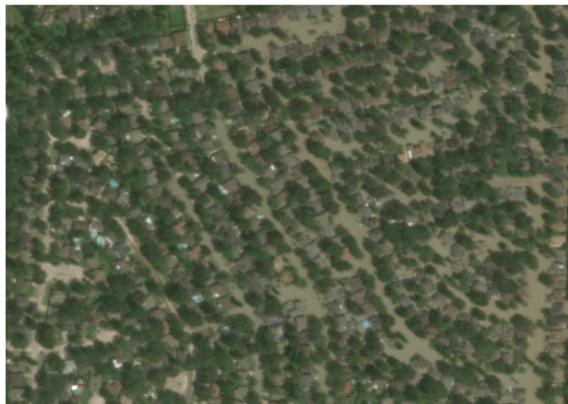
10m pre-disaster



radar

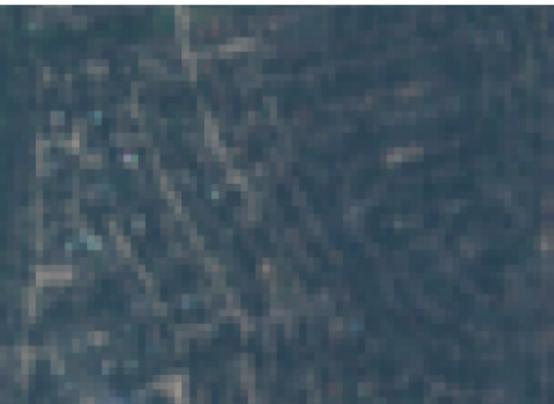
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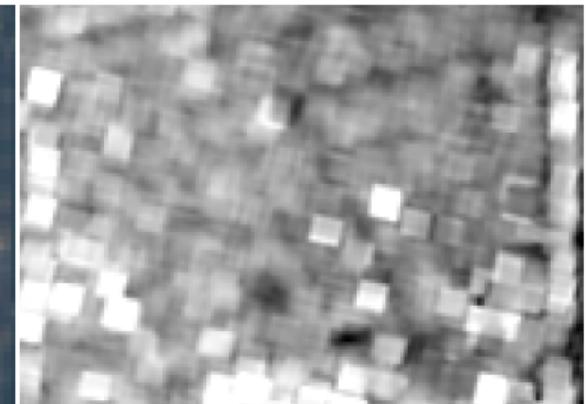
very high resolution

10m post-disaster



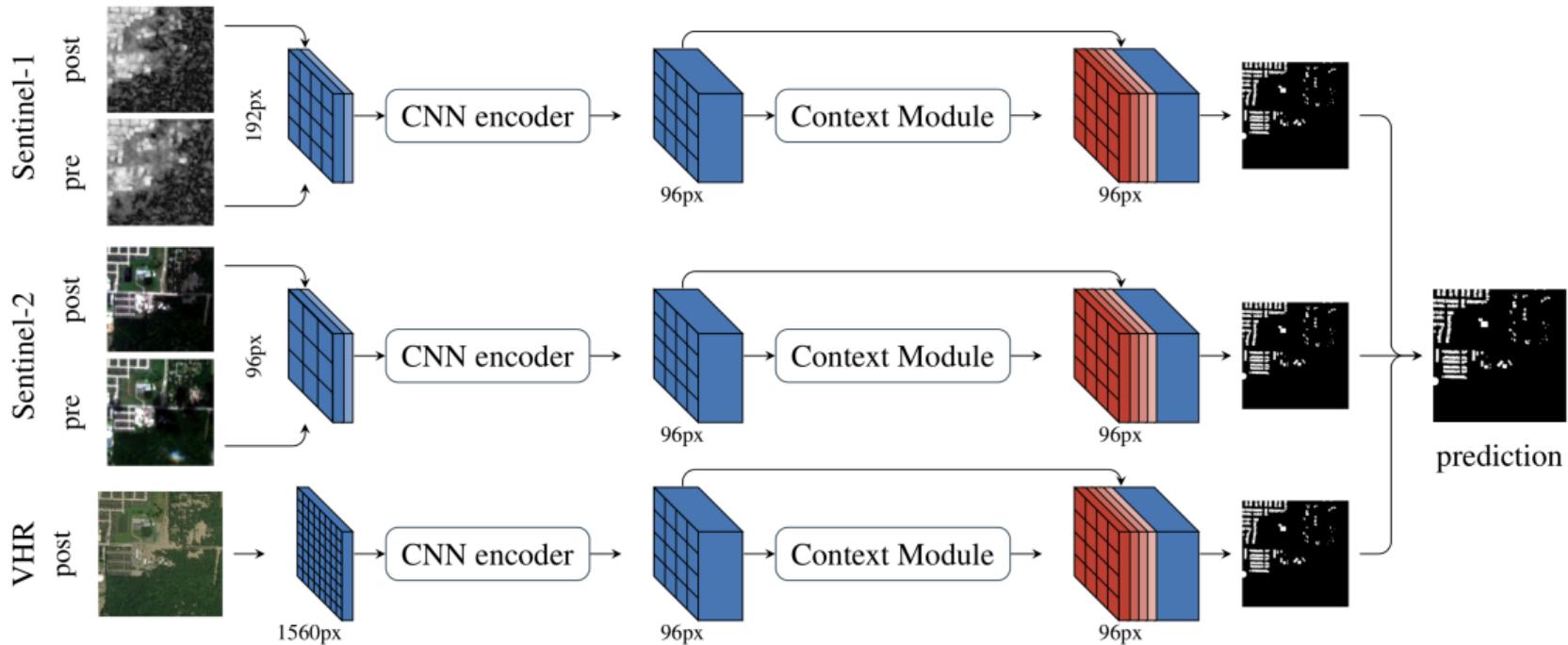
optical

10m post-disaster



radar

# Multi<sup>3</sup>Net



## Publications and Code

### **AAAI 2019 Conference Paper:**

Rudner, T. G., Rußwurm, M., Fil, J., Pelich, R., Bischke, B., Kopackova, V., & Bilinski, P. (2019). Multi<sup>3</sup> Net: Segmenting Flooded Buildings via Fusion of Multiresolution, Multisensor, and Multitemporal Satellite Imagery. Association for the Advancement of Artificial Intelligence AAAI-19.

### **2 NeurIPS Workshop Papers at AI for Social Good and Spatio-Temporal Workshops.**

**GitHub** <https://github.com/FrontierDevelopmentLab/multi3net>

# Workshops

## CVPR EarthVision

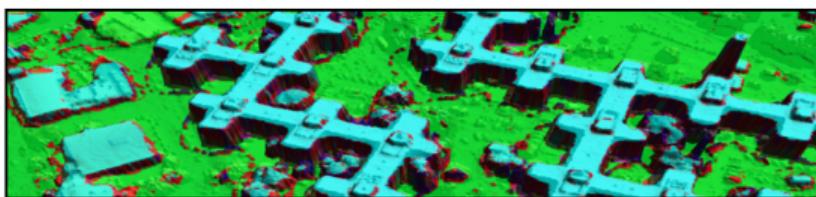
### EARTHVISION 2019

IEEE/ISPRS Workshop. Large Scale Computer Vision for Remote Sensing Imagery

June 17, 2019, Long Beach, CA

in conjunction with the Computer Vision and Pattern Recognition (CVPR) 2019 Conference

[Home](#)   [People](#)   [Program](#)   [Submission](#)   [Important Dates](#)   [CVPR 2019](#)



Workshop CVPR June 17, 2019

<https://www.grss-ieee.org/earthvision2019/>

## ECML MACLEAN



Deadline **Deadline June 10th, 2019**  
Workshop **ECML September 20th, 2019**

# Summary

## Earth Observation

general overview on optical data

complexity of Earth Observation data

showed the balance between **spatial**, **temporal**  
and **spectral** resolution



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## Projects

illustrated some ML-related tasks

translate methods between disciplines

connect via huge Benchmark Datasets



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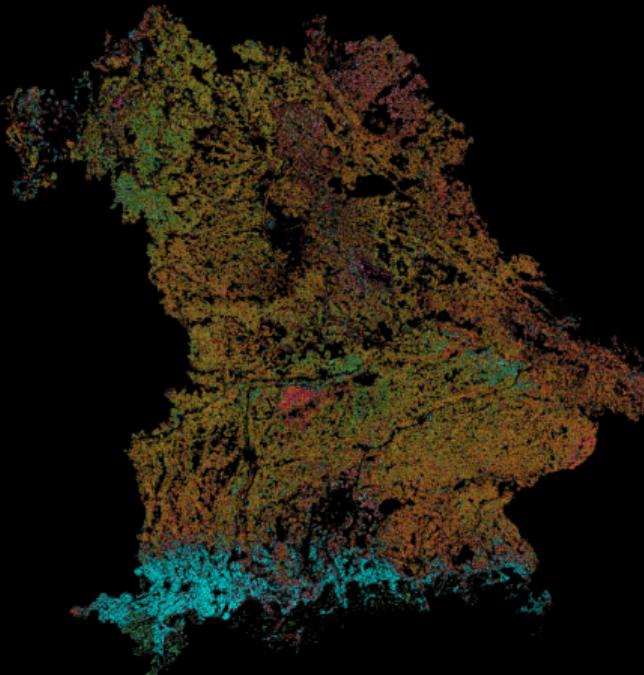
connect via huge Benchmark Datasets

## Initiatives

hope to **see you at one of the Workshops**

or at **Frontier Developments Lab!**

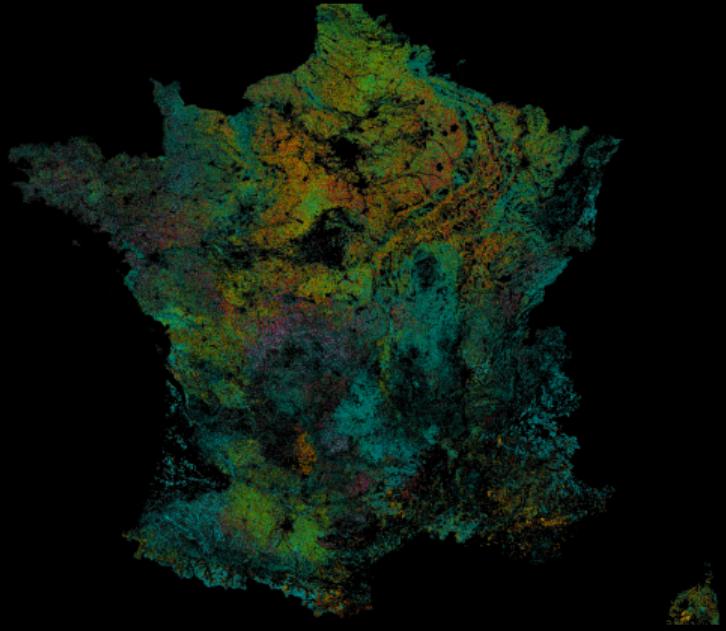




# Thank you!

**Twitter:** @marccoru — **Github:** @marccoru or @tum-lmf — **Chair** lmf.bgu.tum.de/vision

BreizhCrops <https://github.com/TUM-LMF/BreizhCrops>



# Questions/Input?

**Twitter:** @marccoru — **Github:** @marccoru or @tum-lmf — **Chair** lmf.bgu.tum.de/vision

BreizhCrops <https://github.com/TUM-LMF/BreizhCrops>

# Thank you!

## Papers:

Rußwurm, M. and Körner, M. (2017). **Temporal Vegetation Modelling using Long Short-Term Memory Networks for Crop Identification from Medium-Resolution Multi-Spectral Satellite Images.** In IEEE/ISPRS EarthVision 2017 Workshop, Proceedings of the IEEE CVPR Workshops. **Best Paper Award**

Rußwurm, M., Lefèvre, S., Courty, N., Emonet, R., Körner, M., & Tavenard, R. (2019). **End-to-end Learning for Early Classification of Time Series.** arXiv preprint arXiv:1901.10681.

Rußwurm, M., & Körner, M. (2018). **Multi-temporal land cover classification with sequential recurrent encoders.** ISPRS International Journal of Geo-Information, 7(4), 129.

Rußwurm, M., & Körner, M. (2018). **Convolutional LSTMs for Cloud-Robust Segmentation of Remote Sensing Imagery.** NeurIPS2018 Spatiotemporal Workshop. <https://openreview.net/pdf?id=Sye7df9CK7>

Rudner, T. G. J.; Rußwurm, M.; Fil, J.; Pelich, R.; Bischke, B.; Kopačková, V.; Biliński, P. (2019) **Segmenting Flooded Buildings via Fusion of Multiresolution, Multisensor, and Multitemporal Satellite Imagery.** In AAAI.

## Twitter

<https://twitter.com/MarcCoru>

## Github

<https://github.com/marccoru>

<https://github.com/TUM-LMF>

## Our Agenda

use pure **data-driven end-to-end** learning

- no pre/postprocessing of data

- top-of-atmosphere data

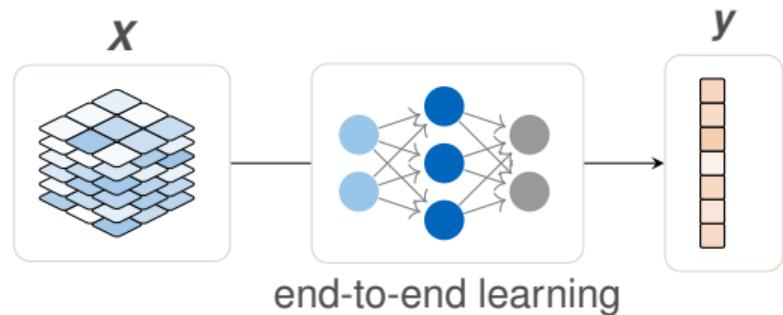
- no atmospheric correction

- no cloud filtering

- no additional image registration

adapt established methods to EO Sensors

- NLP to EO: Sentence translation to image sequence classification



## UCR Datasets

broad family of **46 diverse datasets**

**accuracies reported** from other early classification approaches

covers **sensor data, motion tracking, electrocardiography data**

many, but **small datasets** (overall circa 500 MB)



<http://www.timeseriesclassification.com/>

# Communications

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**method** is a **tool** for our  
**data**

**should generalize** to  
applications of a  
specific sub-field

data has specific  
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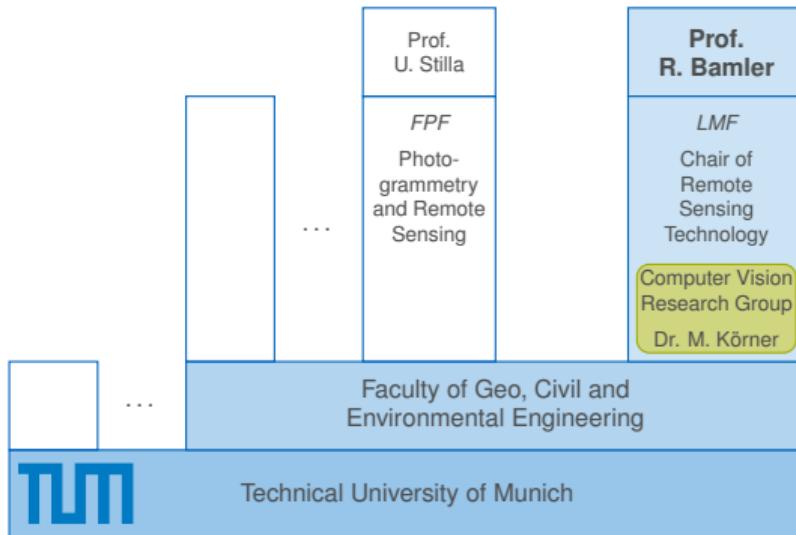
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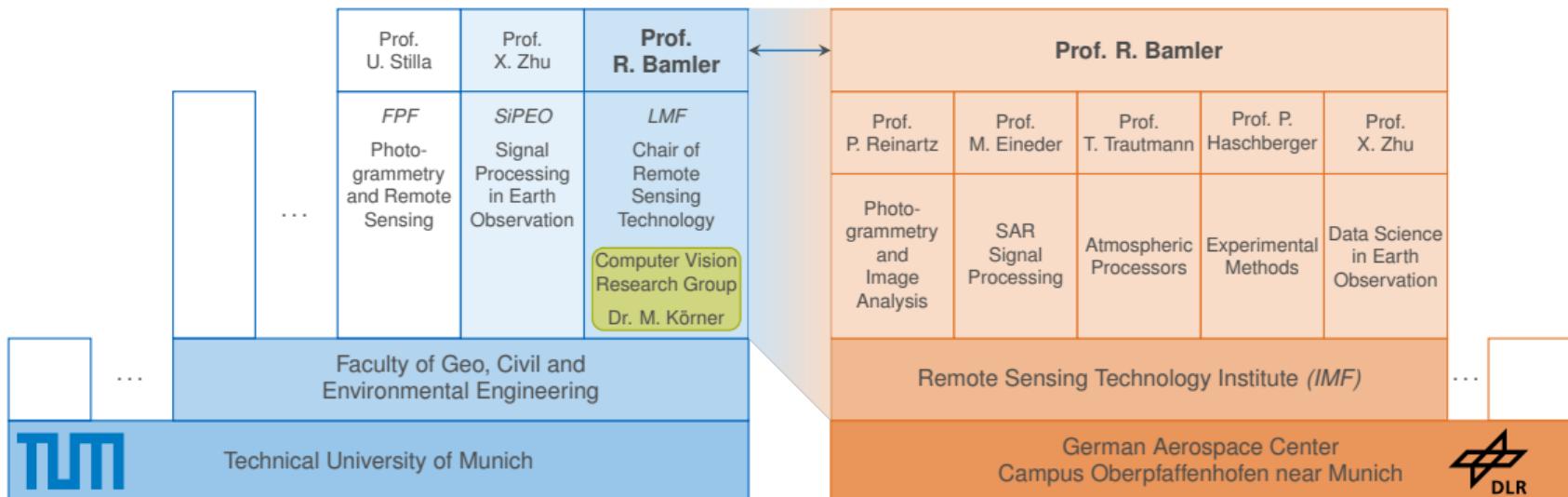
**must generalize** to  
many fields of applica-  
tions

data is a **feature vector**

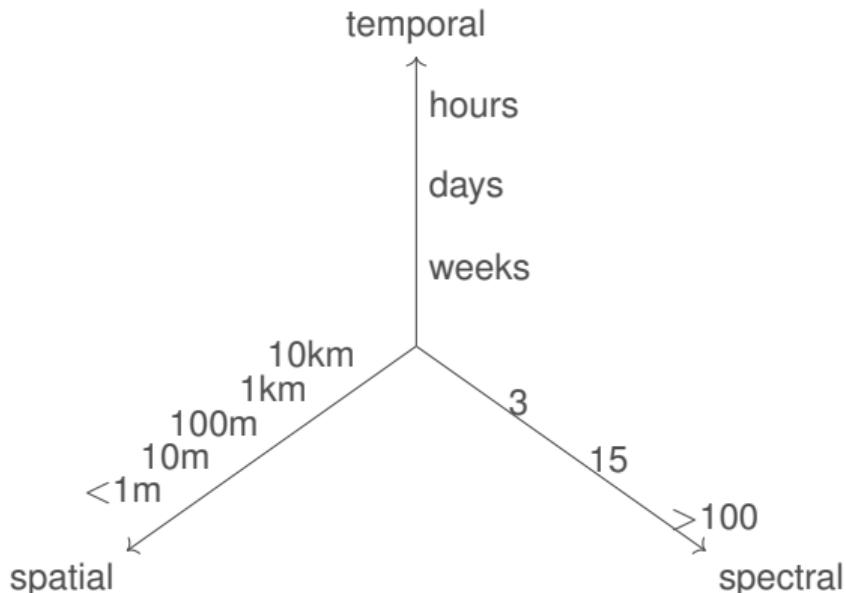
Chair of Remote Sensing Technology



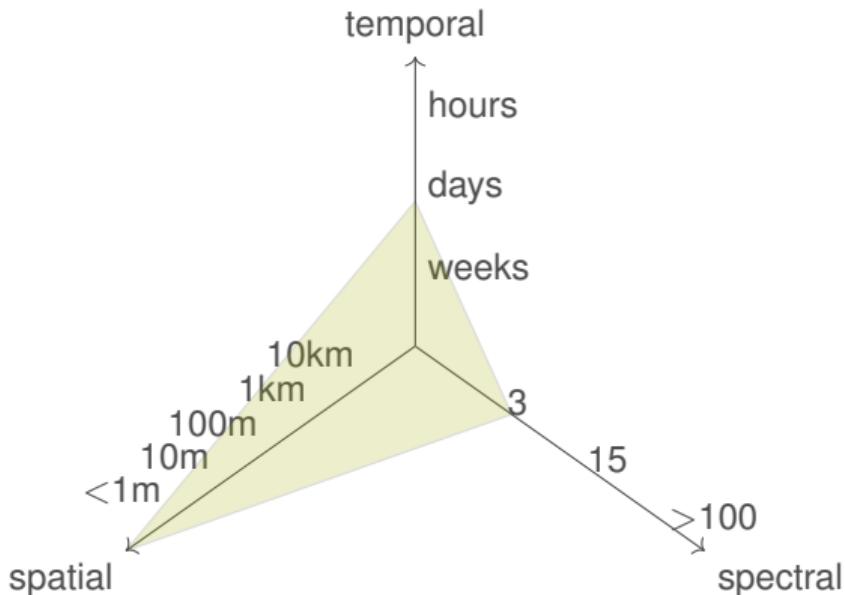
# Chair of Remote Sensing Technology



## Summary: Balancing Resolutions



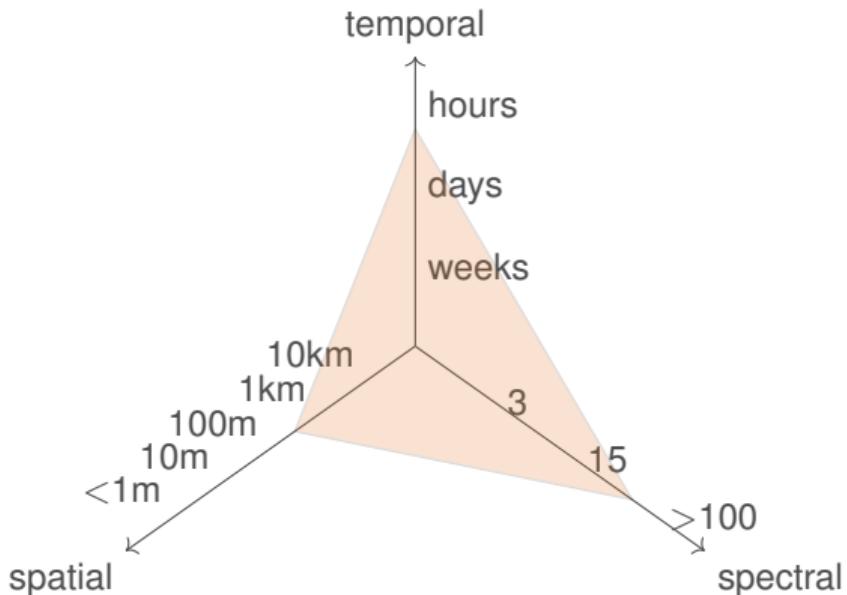
## Summary: Balancing Resolutions



### Scheduled Acquisitions

very high spatial Resolution Imagery

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very high spatial Resolution Imagery

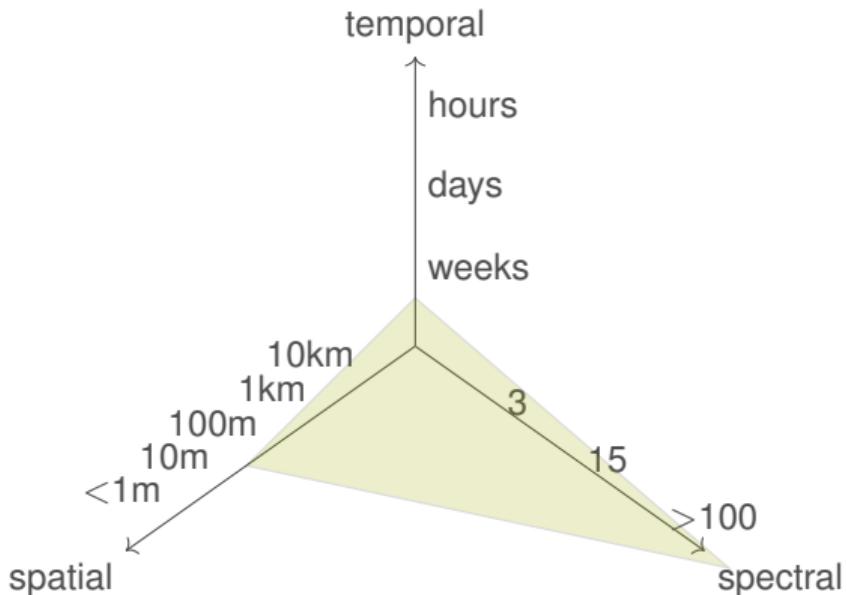
### Global coverage and open data policy

multi-spectral satellites

environmental satellites

weather satellites

## Summary: Balancing Resolutions



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very high spatial Resolution Imagery

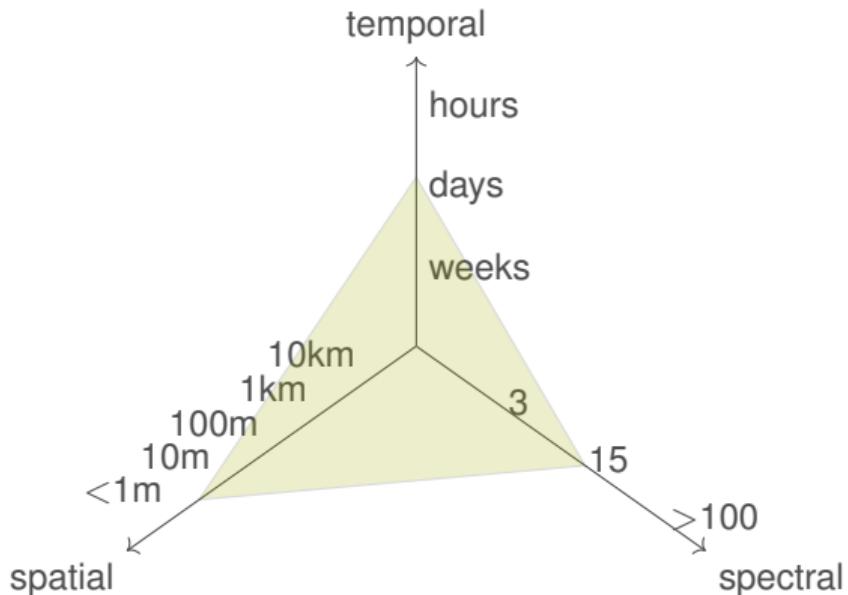
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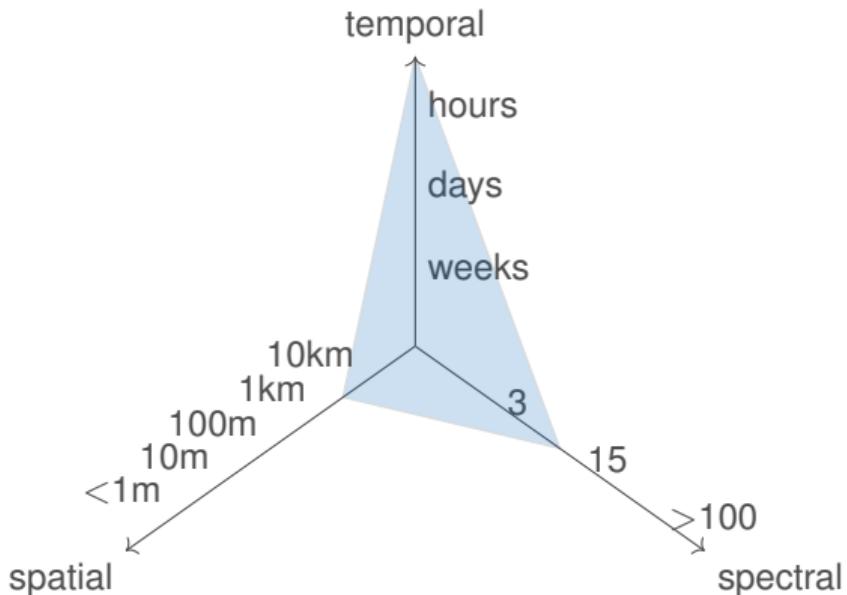
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## Summary: Balancing Resolutions



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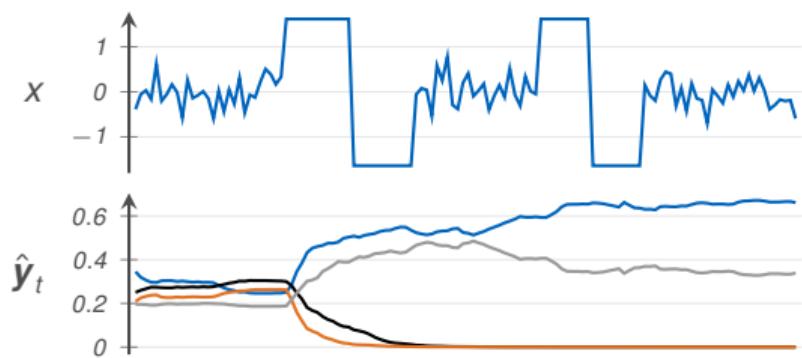
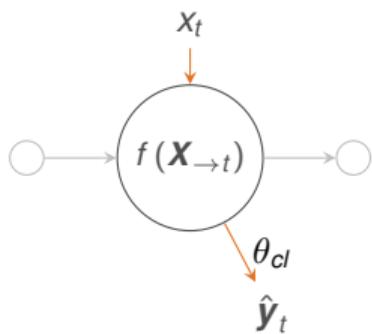
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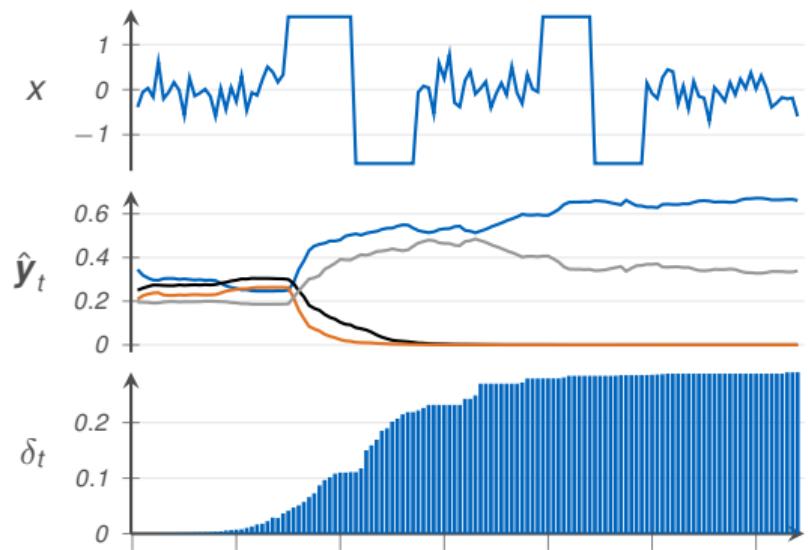
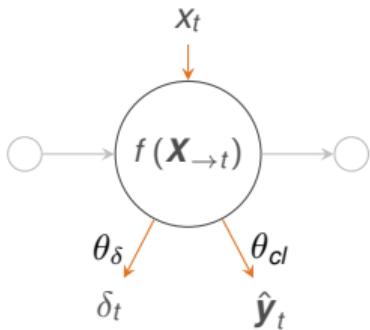
environmental satellites

weather satellites

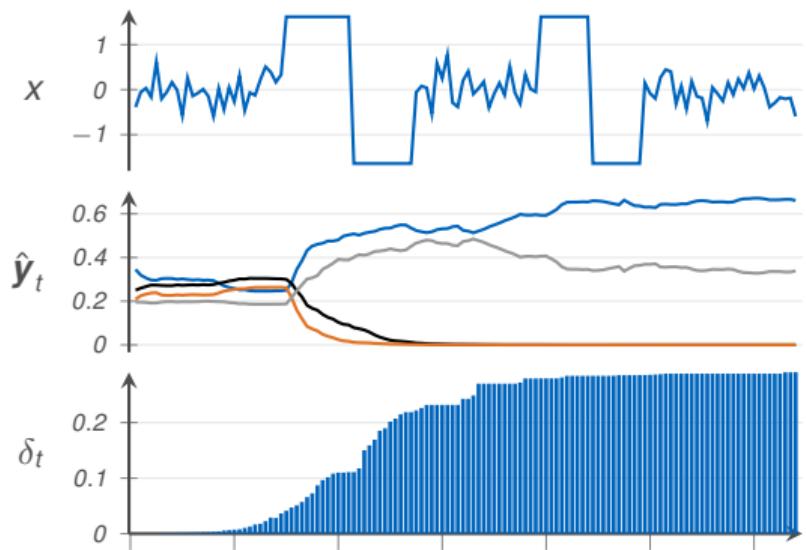
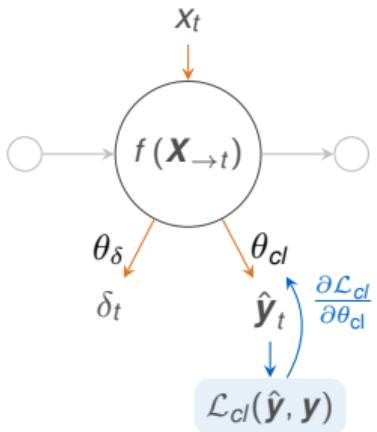
# Augmenting Classification Models



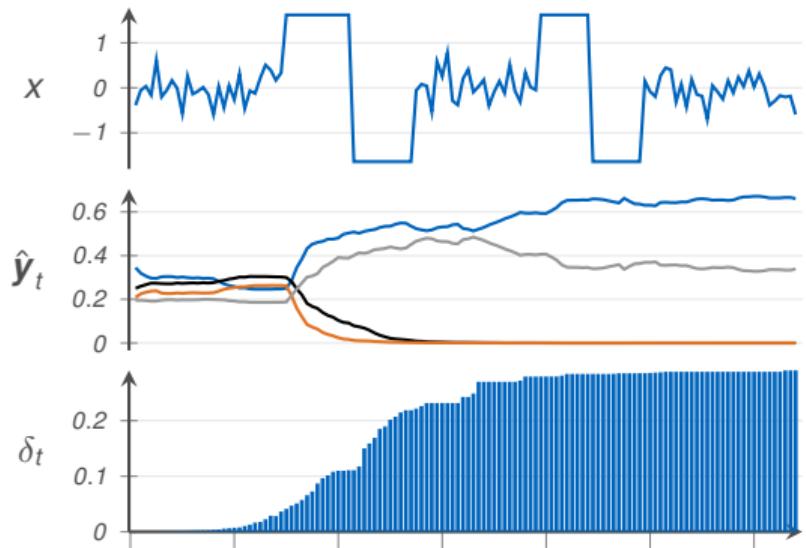
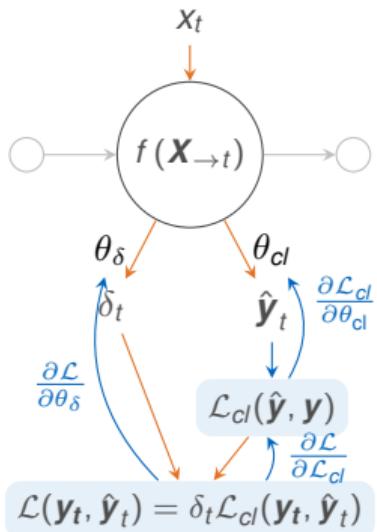
# Augmenting Classification Models



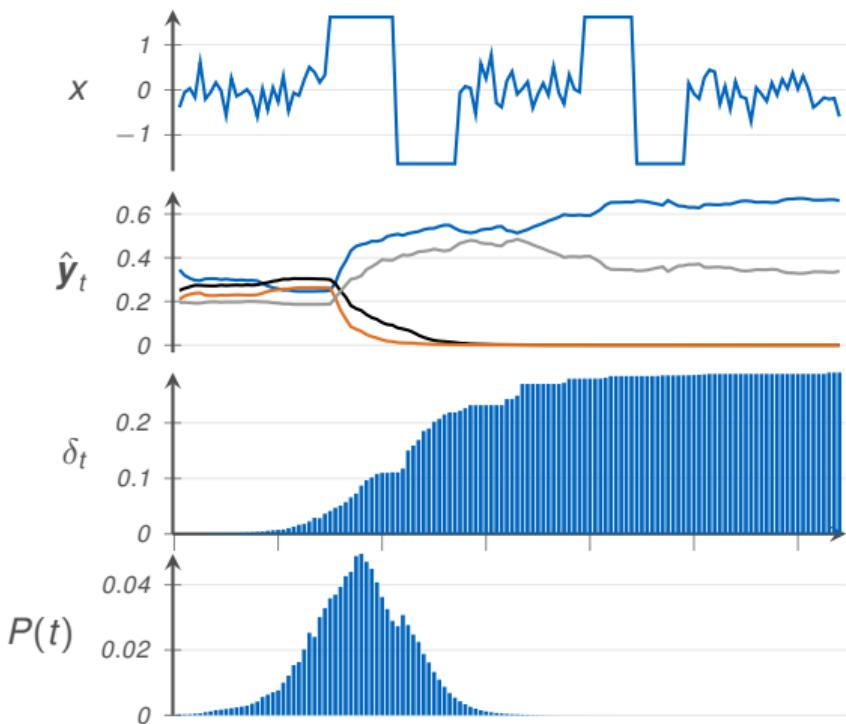
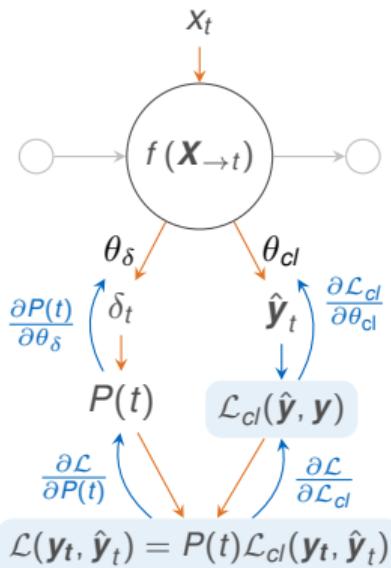
# Augmenting Classification Models



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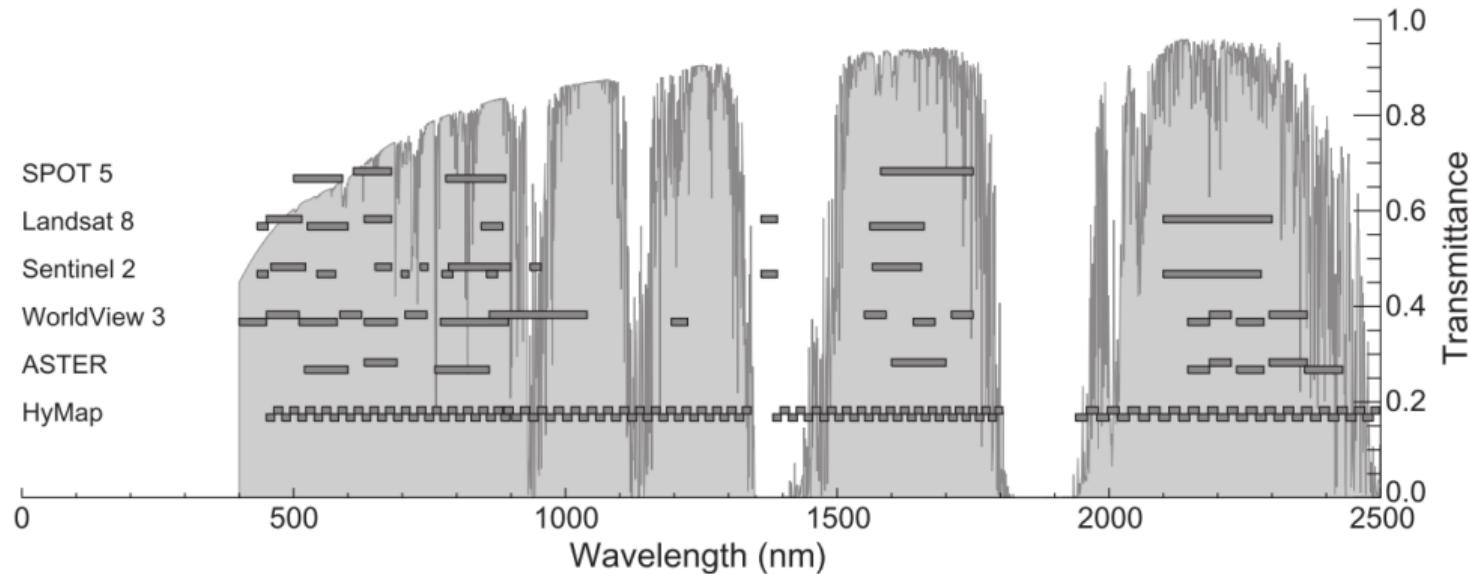
# Augmenting Classification Models



## Earliness-Aware Loss function

$$\mathcal{L} = P(t) \left( \alpha(1 - \hat{\mathbf{y}}^+) + (1 - \alpha) \frac{t}{T} \right)$$

## Spectral Bands



Van der Meer, F. D., Van der Werff, H. M. A., & Van Ruitenbeek, F. J. A. (2014). Potential of ESA's Sentinel-2 for geological applications. *Remote sensing of environment*, 148, 124-133.

## Benchmark Datasets

broad family of **46 diverse datasets**

**accuracies reported** from other early classification approaches

covers **sensor data, motion tracking, electrocardiography data**

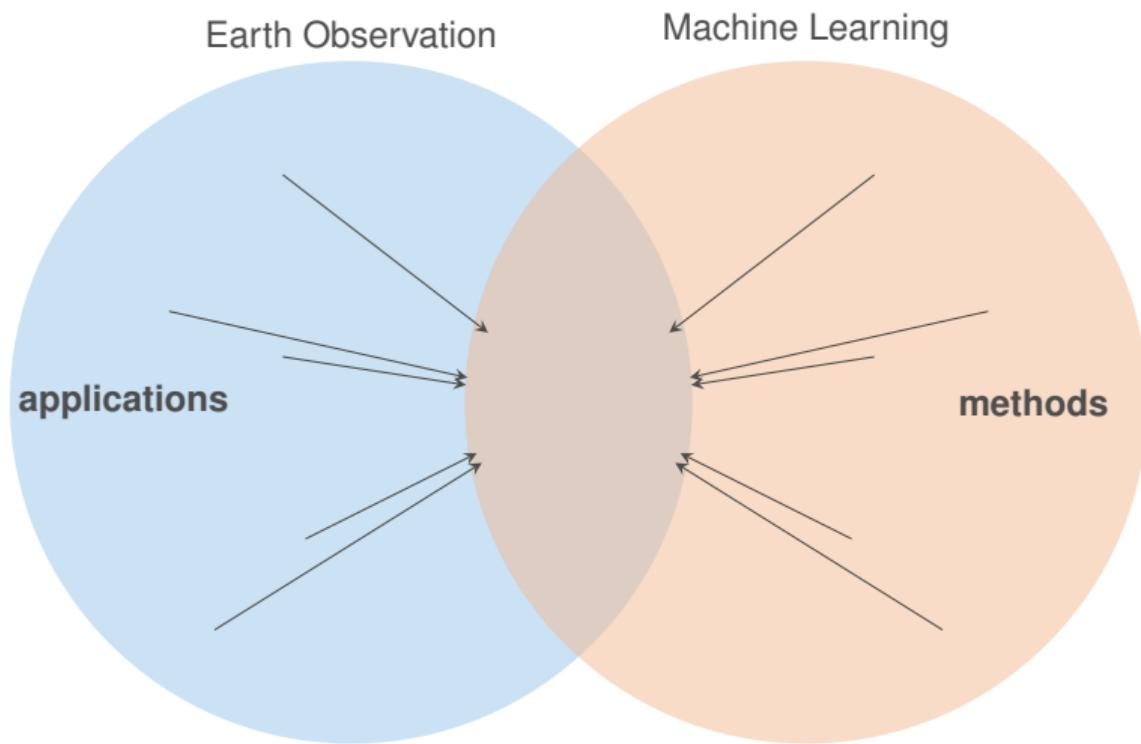
many, but **small datasets** (overall circa 500 MB)



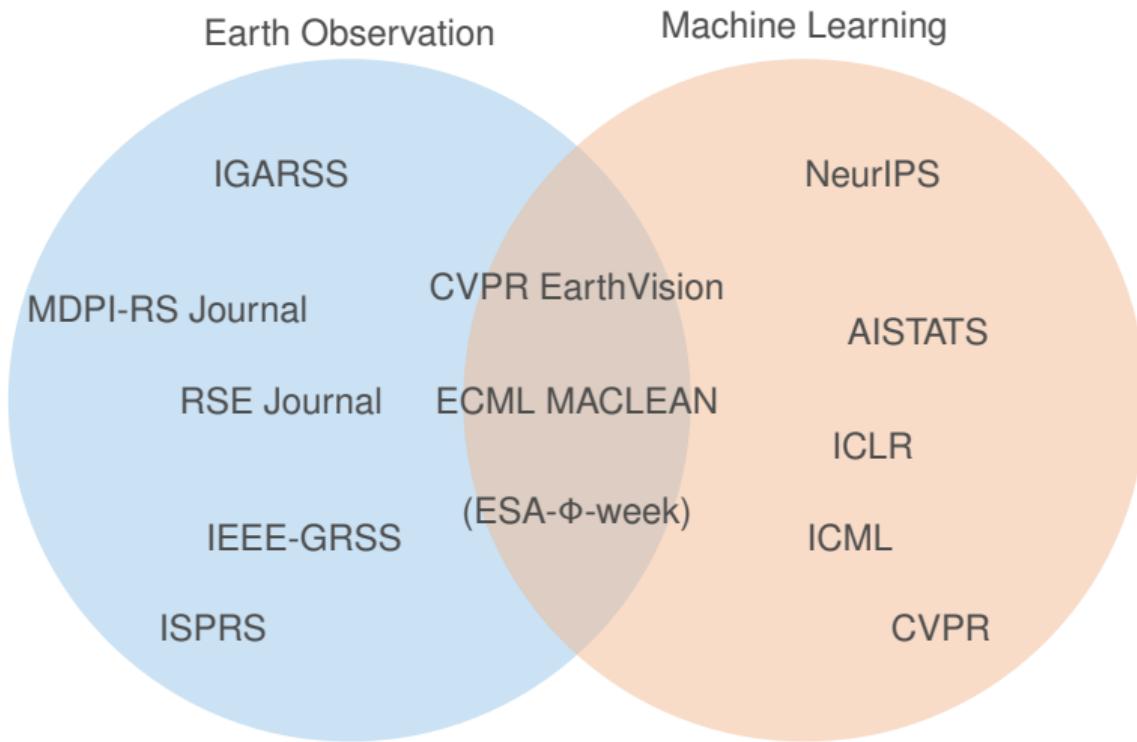
**GunPoint** dataset

<http://www.timeseriesclassification.com/>

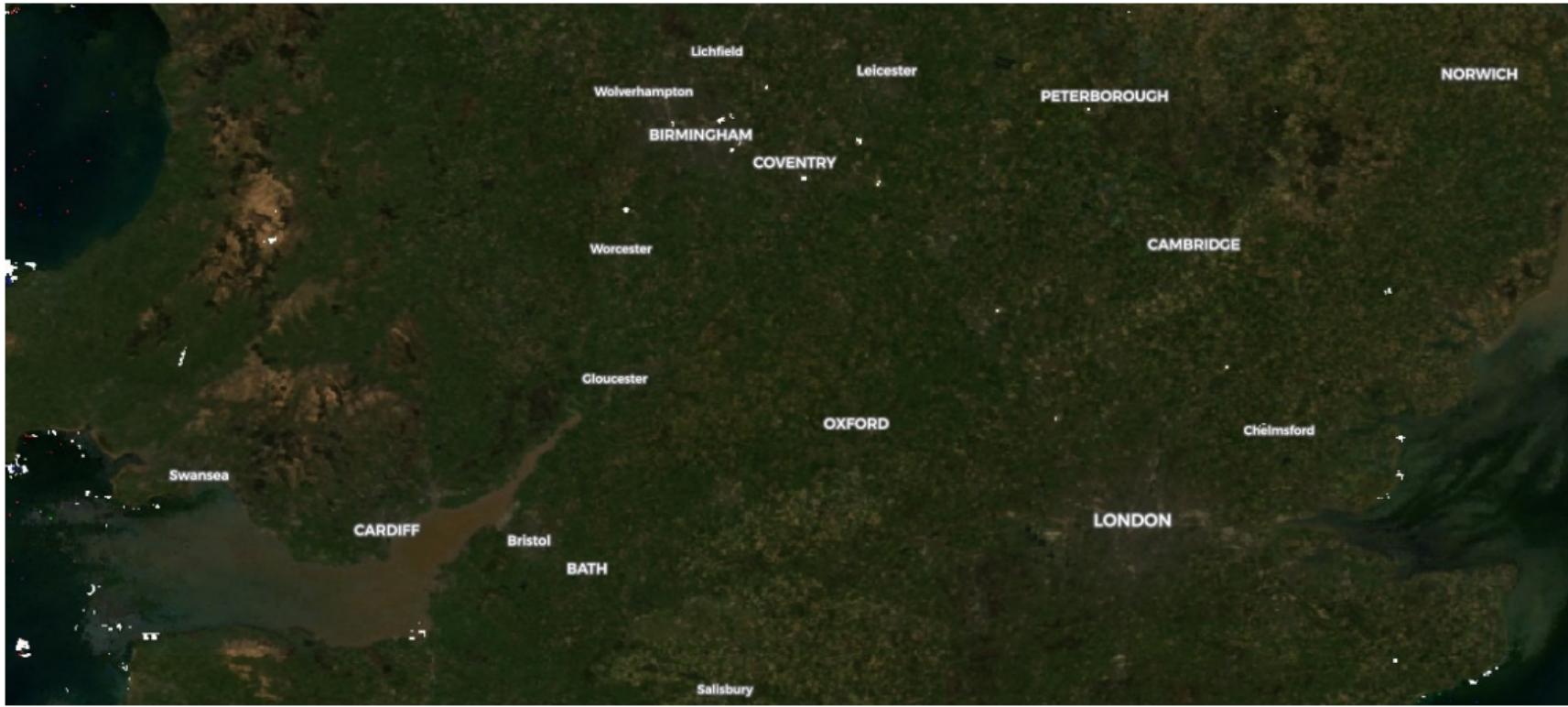
## Two Fields



## Communities



# MODIS Satellite



# MODIS Satellite

