



Theme 4. Camera Views

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Bachelor's Degree in Video Game Design
and Development



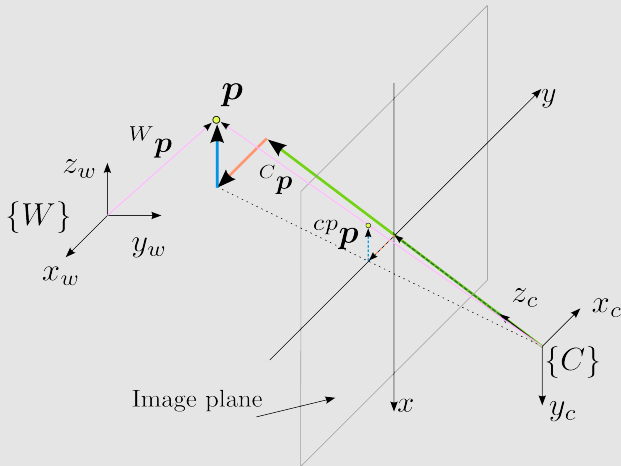
- 1 Simple Camera Model
- 2 Perspective Transformation
- 3 Homework



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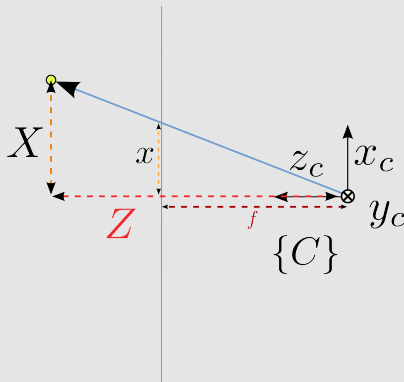
Simple Camera Model

What is the representation of p on the camera plane?



Simple Camera Model

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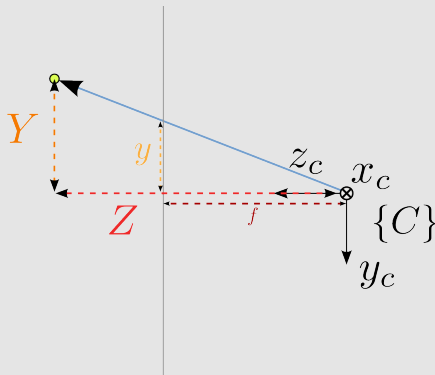
$${}^C\mathbf{p} = \begin{pmatrix} X \\ Y \\ Z \end{pmatrix}$$

$${}^{cp}\mathbf{p} = \begin{pmatrix} x \\ y \end{pmatrix}$$

f is the **focal length**: distance between the image plane and the camera

Simple Camera Model

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Simple Camera Model

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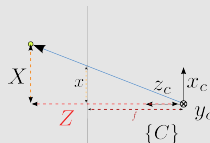
Thales Theorem about similar triangles establishes

$$\frac{X}{Z} = \frac{x}{f}$$

$$\frac{Y}{Z} = \frac{y}{f}$$

which implies that

$${}^{cp}\mathbf{p} = \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} \frac{X}{Z}f \\ \frac{Y}{Z}f \end{pmatrix}$$





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Perspective Transformation

$${}^c p \mathbf{p} = \begin{pmatrix} \frac{X}{Z} f \\ \frac{Y}{Z} f \end{pmatrix}$$

is a transformation, known as [Perspective Transformation](#), with the properties

- It is a mapping from 3-dimensional space to 2-dimensional space.
- **Straight** lines in the world are projected to **straight** lines in the camera plane.
- **Parallel** lines in the world are translated to lines that intersect at a **vanishing point**.



Perspective Transformation

- **Conics** (circles, ellipses, parabolas and hyperbolas) are translated to other **conics**.
- The transformation does not preserve **angles** between lines.
- The mapping in general has not a unique **inverse**: any point

$${}^c\mathbf{p} = \begin{pmatrix} \lambda X \\ \lambda Y \\ \lambda Z \end{pmatrix}, \forall \lambda$$

is mapped to the same point ${}^c\mathbf{p}$ on the camera



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Homework

Camera Views

Exercises

- Mock exam: Exercise 4
- Re-evaluation exam: Exercise 5