

Morse Theory

- Goal: Investigating how functions defined on a Mfld are related to its geometric aspects

① Basics

- ↳ critical points
- ↳ degenerated & non-degenerated
- ↳ Morse Lemma

② Morse Functions & the two sphere

③ Handle decomposition

- compact surfaces
- compact Mflds

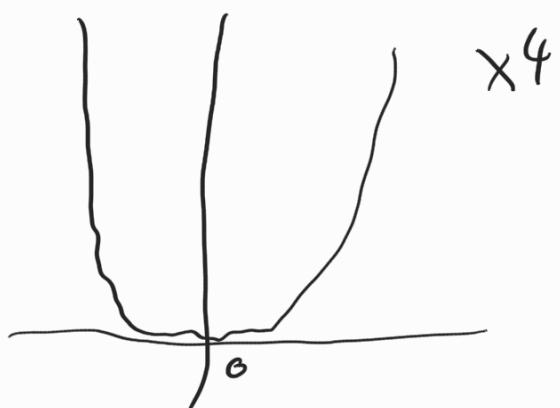
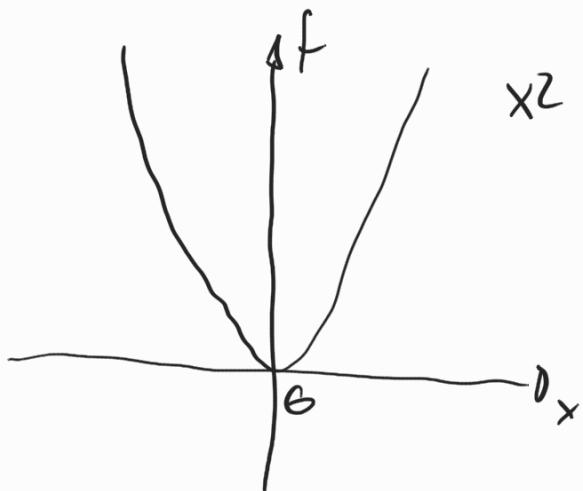
Def. 1.1

Let f be a real valued function.

A point $x_0 \in \mathbb{R}$ w/ $f'(x_0) = 0$ is called a critical point.

x_0 non-deg. if $f''(x_0) \neq 0$

x_0 degenerated if $f''(x_0) = 0$



Under pt:

- Non-deg. critical points are stable
- deg. critical points are unstable

Def. 1.2 The gradient ∇f of a function is the vector field on the domain of f that takes the values $(\frac{\partial f}{\partial x_1}, \dots, \frac{\partial f}{\partial x_n})$ at each point. Denote the ∇f by Df and the value at p as $Df|_p = Df(p)$

Def. 1.3

A critical point of $f: \mathbb{R}^n \rightarrow \mathbb{R}$ is a point $p \in \mathbb{R}^n$ s.t. $Df(p) = 0$.
A critical value of f is a value $c \in \mathbb{R}$ s.t. $f(p) = c$.

Def. 1.4

A critical point p_0 of a smooth function f is called degenerated if $\det(H_f(p_0)) = 0$

J_{P_0} the Jacobian of cond. trafe

$$(y_1, \dots, y_n)^T = J_{P_0} (x_1, \dots, x_n)^T$$

$$\tilde{H}_f(P) = J_{P_0}^T H_f(P_0) J_{P_0}$$

Prop. 1.5 The property that P_0 is a degenerated / non-degenerated critical point does not depend on the choice of local coord.

Def 1.6 Given a smooth Mfld M and a smooth function $f: M \rightarrow \mathbb{R}$, we say that f is Morse if f has no degenerated critical points

Def. 1.7 M be a smooth Mfd.

$f: M \rightarrow \mathbb{R}$ smooth and $p_0 \in M$ is a non-degenerated critical point of f .

Then the index of f at p_0 is defined to be the number of negative eigenvalues of the Hessian at p_0 .

Prop 1.8 The index of f at p_0 do not depend on the choice of local coord.

Proof: Sylvester's law \rightarrow # negative eigenvalues of $H_f(p)$ is independent of the way it is diagonalized.

\Rightarrow # negative eigenvalues is invariant under local coord. trans.

□

Example:

Height function



$$f(x,y) = \pm \sqrt{1-x^2-y^2}$$

2 critical points

$$P_0 = (0,0,1) \quad q_0 = (0,0,-1)$$

$$H_f(P_0) = \begin{bmatrix} -1 & 0 \\ 0 & -1 \end{bmatrix} \neq 0 \quad \text{index} = 2$$

$$H_f(q_0) = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \neq 0 \quad \text{index} = 0$$

Theorem 1.9 (Existence of Morse functions)

Let M be a closed Mfd and $f_0: M \rightarrow \mathbb{R}$ be smooth. Then there exists a Morse function f on M that is an arbitrarily close approx. of f_0 .

Sketch • $\{U_e\}_{1 \leq e \leq h}$ finite open cover of M .

- For each U_e find compact subset K_e at U_e w/ $\{K_e\}$ a cover of M by compact sets.

\Rightarrow idea: inductively define function f_e on M s.t. f_e is Morse on $\bigcup_{j=1}^e K_j =: C_e$. When $e=h$ we have f_h Morse on $C_h = M$.

hypothesis: $f_{e-1}: M \rightarrow \mathbb{R}$ Morse on C_{e-1}

\Rightarrow exist f_e Morse on $C_{e-1} \cup U_e$

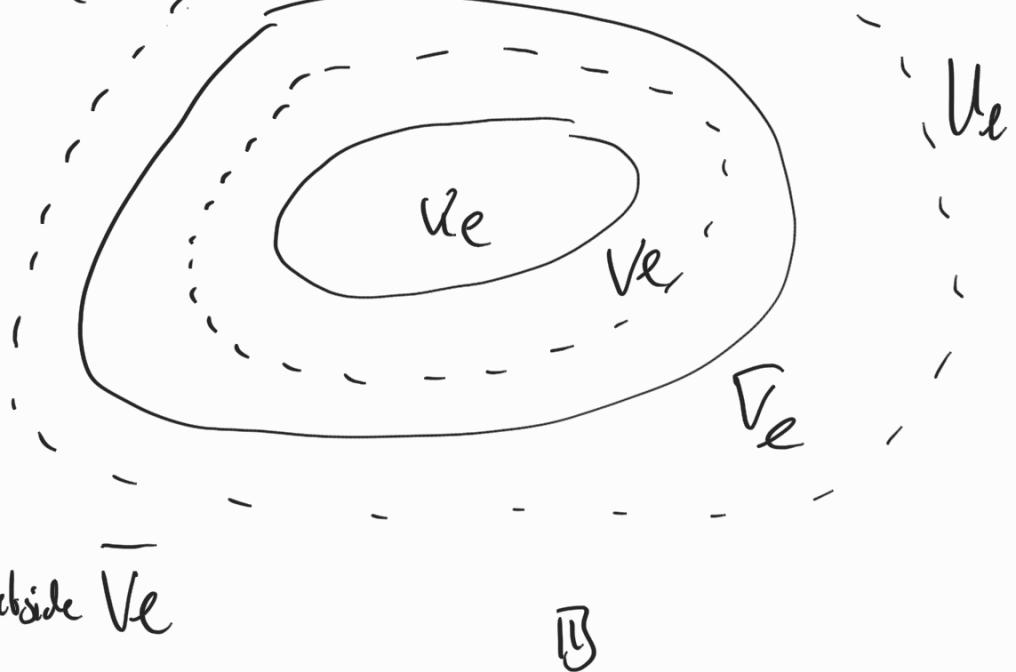
Do this Lemma which states that if $\{x_1, \dots, x_n\}$ are local coord. on U_e , then exists a real number $\{a_i\}$ s.t.

$$f_{\ell-1}(x_1, \dots, x_n) = \underbrace{(a_1 x_1 + a_2 x_2 + \dots + a_n x_n)}_{\text{is Morse on } U_\ell}$$

$h_\ell : U_\ell \rightarrow \{0, 1\}$

being 1 on
open $V_\ell \subset U_\ell$

h_ℓ is 0 outside $\overline{V_\ell}$



Theorem 1.10 (Morse Lemma)

Let f be a Morse function on a smooth manifold M and let p_0 be a critical point of f . Then there exist local coord. (x_1, \dots, x_n) on a neighborhood U of p_0 st. on U f has the form:

$$f(x_1, \dots, x_n) = -x_1^2 - x_2^2 - \dots - x_k^2 + x_{k+1}^2 + \dots + x_n^2$$

where k is the index of f at p_0 .

P corresponds to the origin of this coord. system.

Lem 1.11

$f: \mathbb{R}^n \rightarrow \mathbb{R}$ be smooth on a convex neighborhood $U \subset \mathbb{R}^n$ containing the origin and suppose $f(0, \dots, 0) = 0$.

Then there ex. smooth functions $\{g_i\}_{1 \leq i \leq n}$ defined on U st.

$$f = \sum_{i=1}^n x_i g_i$$

$$\text{w/ } g_i(0, \dots, 0) = \frac{\partial f}{\partial x_i}(0, \dots, 0)$$

Proof (Theorem 1.10)

$\{y_1, \dots, y_n\}$ being local coord. on U of P

using Lem 1.11:

$$g_i: \mathbb{R}^n \rightarrow \mathbb{R} \text{ st } f(y_1 - y_i) = \sum_{j=1}^n y_j g_j(y_1 - y_j)$$

$$w/ g_i(\delta) = \frac{\partial f}{\partial x_i}(\delta)$$

\Rightarrow apply again on g_i

$$h_{ij}: \mathbb{R}^n \rightarrow \mathbb{R} \text{ s.t., } h_{ij}(\delta) = \frac{\partial g_i}{\partial x_j}(\delta)$$

$$\Rightarrow f(y_1, \dots, y_n) = \sum_{i=1}^n \sum_{j=1}^n y_j y_i h_{ij}(y_1, \dots, y_n)$$

$$\frac{\partial f^2}{\partial y_i \partial y_j}(P) = \begin{cases} 2h_{ii} & i=j \\ h_{ij} & i \neq j \end{cases} \quad P = (0, \dots, 0)$$

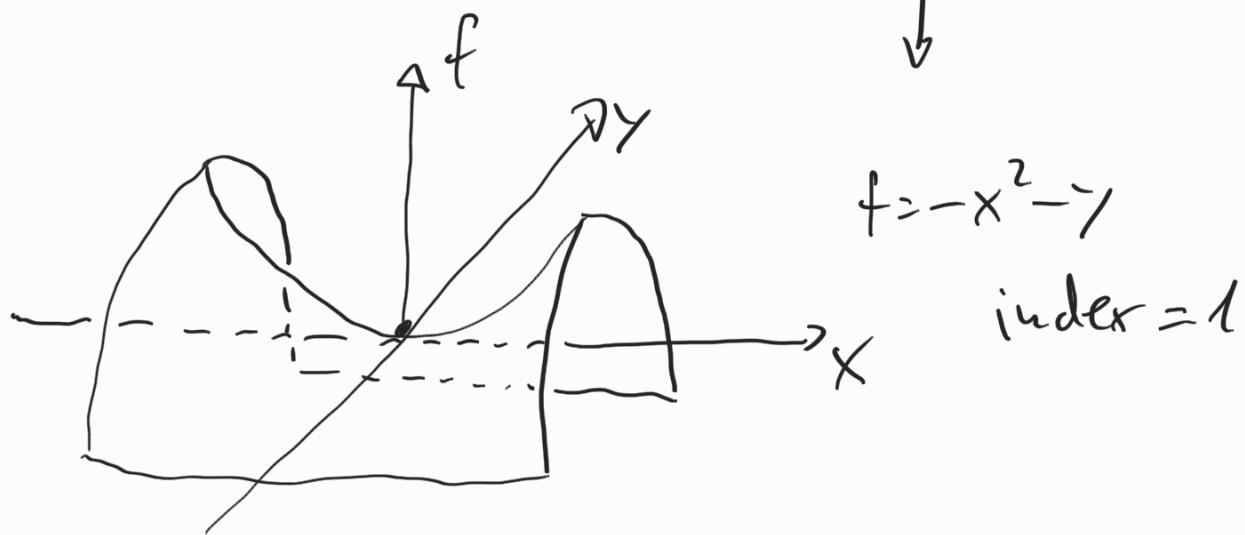
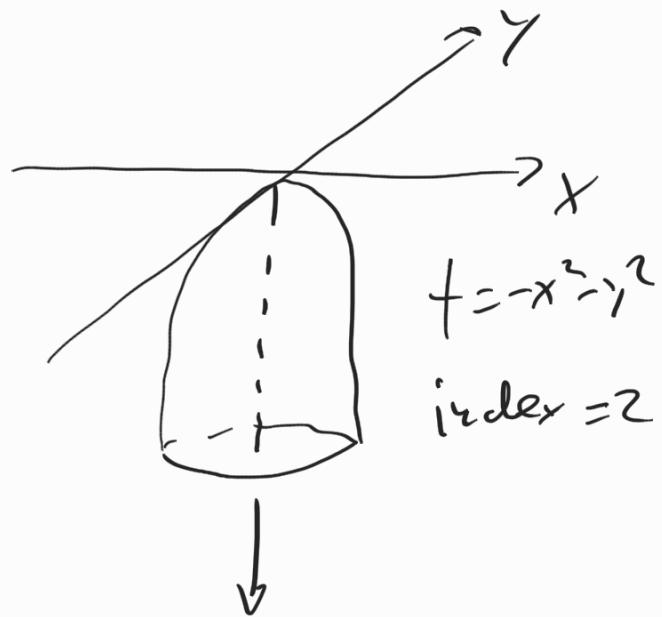
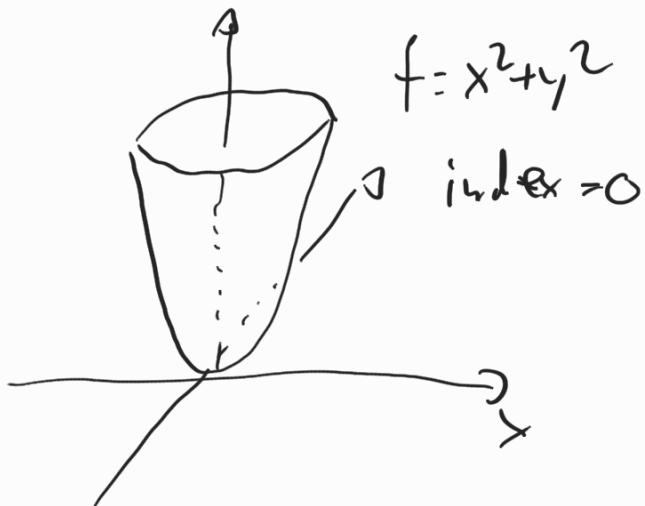
\Rightarrow Diagonalize Hessian $\rightarrow \lambda_i$ be the
ith diagonal entry of $H_f(P)$

$$\Rightarrow f(\bar{x}_1, \dots, \bar{x}_n) = \sum_{i=1}^n \frac{\lambda_i}{2} \bar{x}_i^2$$

$$x_i = \partial_p(\bar{x}_i) = \underbrace{\text{sign}(\lambda_i)}_{\frac{|\lambda_i|}{2}} \bar{x}_i$$

$$\Rightarrow f(x_1, \dots, x_n) = \text{sign}(\lambda_1)x_1^2 + \dots + \text{sign}(\lambda_n)x_n^2$$

Example 2-dim case



$\Rightarrow f$ must not have any critical point too near to any other.

Corollary 1.12 Non-deg. critical points on any Mfld can be isolated by open neighborhoods

②

Thm 2.1

Let M be a closed surface.

Suppose that there exist a Morse function $f: M \rightarrow \mathbb{R}$ w/ exactly two critical points. Then M is diffeomorphic to S^2 .

Note: Generalization to n -dim:

Reeb sphere theorem

\Rightarrow homeomorphic to S^n

Lem 2.2

Let $f: M \rightarrow \mathbb{R}$ be a smooth function which takes constant values on the boundary circles $C(p_0)$ & $C(q_0)$.

Assume f has no critical point M .

Then $M \cong C(q_0) \times [0, 1]$

Lemma 2.3

Let $h: \partial D_1 \rightarrow \partial D_1$ be a diffeom. Then we can extend h to a diffeom. $H: D_1 \rightarrow D_1$

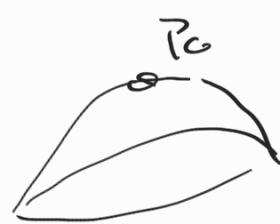
Proof

f is smooth, M compact $\Rightarrow p_0$ maximum value

q_0 minimum value

Theore 1.10 express f locally;

$$f = \begin{cases} -x^2 - y^2 + A & , \text{ around } p_0 \\ x^2 + y^2 + a & , \text{ around } q_0 \end{cases}$$



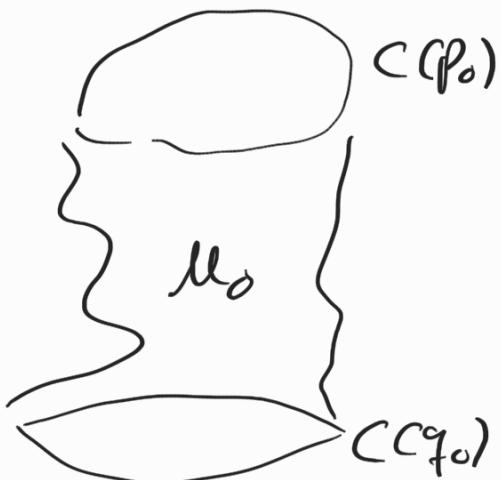
?



$$\begin{aligned} D(p_0) &:= \left\{ \text{set of pairs } p \in M \text{ w/ } A - \varepsilon \leq f(p) \leq A \right\} \\ &= \left\{ (x, y) \mid x^2 + y^2 \leq \varepsilon \right\} \cong D^2 \end{aligned}$$

$$D(q_0) \cong D^2$$

$$M_0 := M \setminus (D(p_0) \cup D(q_0))$$



Restriction of $f: M_0 \rightarrow \mathbb{R}$

takes constant values on
 $C(p_0)$ & $C(q_0)$

\Rightarrow use Lemma 2.2. since $C(q_0) \cong S^1$

$$\Rightarrow M_0 \cong S^1 \times [0, 1]$$

$$N_0 := M_0 \cup D(q_0) \quad (\text{along boundary of } D(q_0))$$

$$H_1: N_0 \rightarrow D_-$$

$$h: C(p_0) \rightarrow \partial N_0$$

$$H_1|_{\partial N_0} \circ h: C(p_0) \rightarrow \partial D_- \cong \partial D_+$$

Lemma 2.3 extends to a diffeo

$$H_2: D(p_0) \rightarrow D_+$$

\rightarrow Gluing two diff'os together:

$$H: M \cup_{U_h D(p_0)} M \longrightarrow D_- \cup D_+ \cong S^2$$

□

Lemma 2.4

A Morse function $f: M \rightarrow \mathbb{R}$ defined on a closed Mfld. M has only finite number of critical points

Contradiction infinitely many critical points
 \Rightarrow seq. of critical points:
 $\{q_n\}_{n \in \mathbb{N}} \subset M$

Compacts \rightarrow converg. sub.

\Rightarrow choose further $\{q_{n_k}\}_{k \in \mathbb{N}} \subset U$

$q_{n_k} \rightarrow q_0, k \rightarrow \infty$

$f(q_0)$ is also critical point. 

③

$f : M \rightarrow \mathbb{R}$ Morse function. M closed & connected surface.

Define $M_t := \{p \in M \mid f(p) \leq t\} \subset M$

$L_t := \{p \in M \mid f(p) = t\} \subset M$

$$t \leq a \Rightarrow M_t = \emptyset$$

$$A \leq t \Rightarrow M_t = M$$



Lemma 3.1

Let $b < c$ s.t. f has no critical point in (b, c) . Then M_b & M_c are diffeomorphic

1) index of p_0 is zero

locally form: $f = x^2 + y^2 + c_0$

if c_0 minimum $\Rightarrow M_{c_0-\varepsilon} = \emptyset$

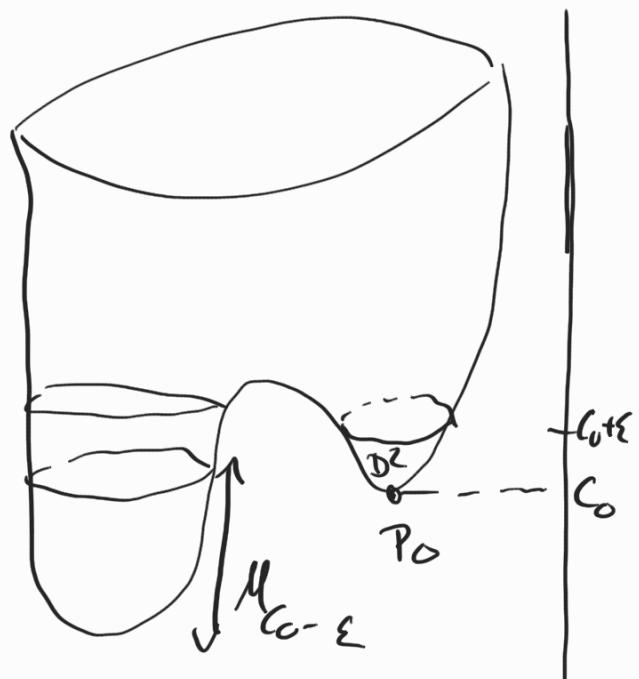
$$\begin{aligned}M_{c_0+\varepsilon} &= \left\{ p \in M \mid f(p) \leq c_0 + \varepsilon \right\} \\&= \left\{ (x, y) \mid x^2 + y^2 \leq \varepsilon \right\} \cong D^2\end{aligned}$$

c_0 not minimum, $M_{c_0-\varepsilon} \neq \emptyset$

$$\Rightarrow M_{c_0+\varepsilon} \cong M_{c_0-\varepsilon} \cup D^2$$

Crossing c_0 , a disk
pops out and it
becomes disjoint.

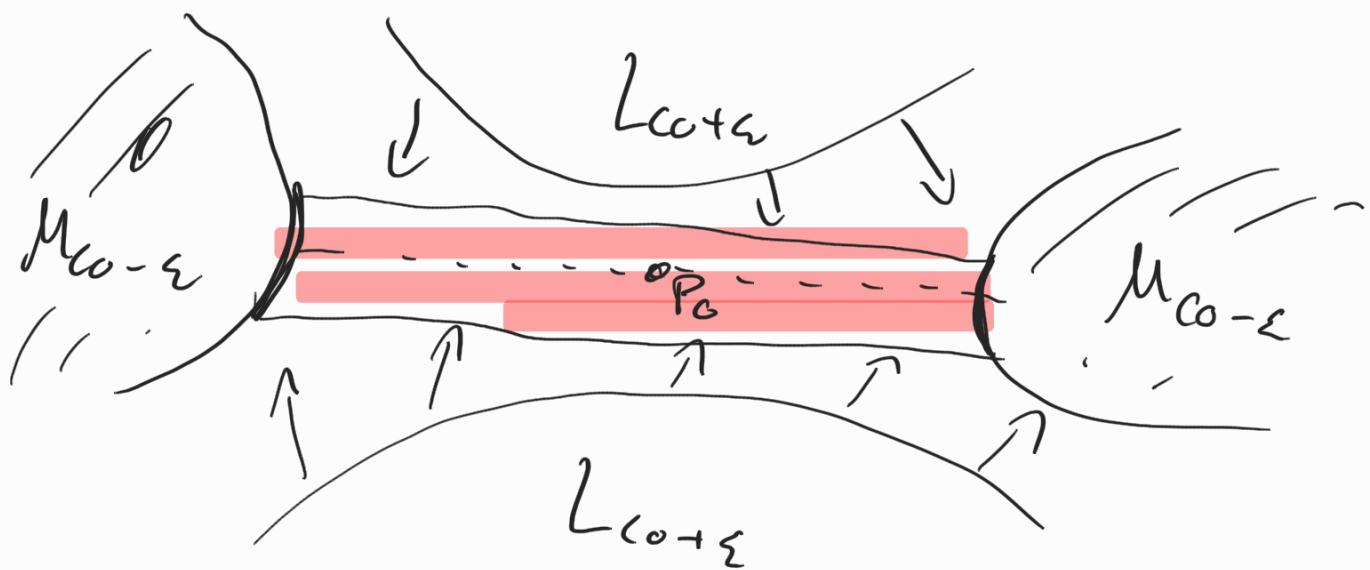
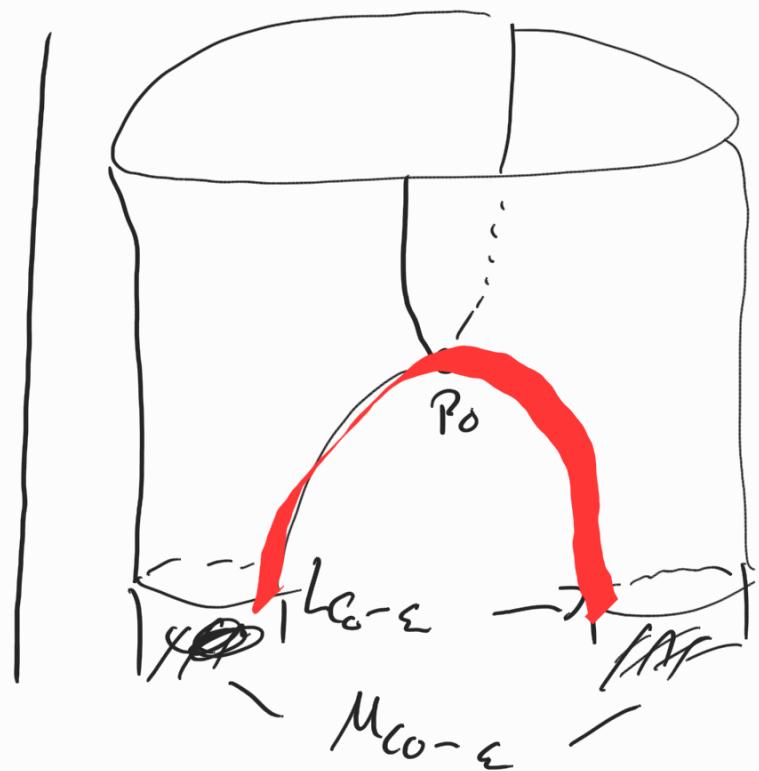
to disjoint union of
 $M_{c_0-\varepsilon} \cup D^2$



2) Index of f_0 is equal over

local form : $f = -x^2 + y^2 + c_0$

red line connecting
edges $L_{c_0-\epsilon}$



Different to rectangle $\Rightarrow D_1 \times D_1$
intersecting w/ $M_{c_0-\epsilon}$ corresponds

to point $\boxed{\partial D^1 \times D^1} \Rightarrow$ 1-handle attached
to $M_{C_0-\varepsilon}$

$$M_{C_0+\varepsilon} \cong M_{C_0-\varepsilon} \cup D^1 \times D^1$$

3) Index to p_0 is equal two

local form: $f = -x^2 - y^2 + c_0$

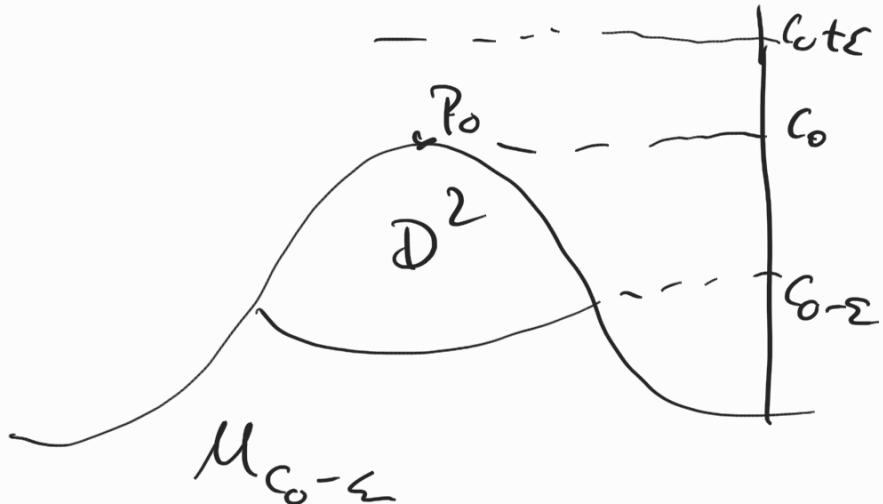
$$\Rightarrow M_{C_0-\varepsilon} = \{(x,y) \mid x^2 + y^2 \geq \varepsilon\}$$

$M_{C_0-\varepsilon}$ outside a disk w/ radius $\sqrt{\varepsilon}$

Bowl D^2 capping

$M_{C_0-\varepsilon}$ from

above \Rightarrow 2-handle



$$\boxed{M_{C_0+\varepsilon} \cong M_{C_0-\varepsilon} \cup D^2}$$

Lemma 3.2

Let M be a smooth Mfd w/ f is a Morse func \sim on M . Then if $p \neq q$ are both critical points of f s.t. $f(p) = f(q)$, then there exists a smooth Mfld $M' \cong M$ s.t. $f(p) \neq f(q)$

Theorem 3.3

A closed surface M admits a Morse func \sim $f: M \rightarrow \mathbb{R}$ and therefore M can be described as a union of finitely many $0, 1, 2$ handles.

Proof:

M compact \Rightarrow th. 1.3 exists of a Morse func \sim .

$$A, B \subset \mathbb{R} \text{ s.t. } M_A = \{\emptyset\}, M_B = M$$

Compaction guarantees \rightarrow finitely many critical points. Lem 2.4.

Lem 3.2 says that we can adjust M by diffeo. s.t. $f(p_i) < f(p_j)$ $i \neq j$

$$L := \{ \# \text{ critical points} \}$$

Index each critical point s.t. if $i < j$

$$\Rightarrow f(p_i) < f(p_j)$$

p_1 lowest critical point & p_L highest.

Define $a_i : i = \frac{f(p_i) + f(p_{i+1})}{2}$ $i \in \{1, \dots, L-1\}$

$\Rightarrow a_i$ defined in that way s.t.

Sublevel sets M_{a_i} containing only critical points up to p_i .

$$\text{Set } M_0 = \{\emptyset\} \quad M_L = M$$

We see that $f^{-1}[\alpha_i, \alpha_{i+1}]$ contains exactly one critical point.

$M_{\alpha_{i+1}}$ is diffeomorphic to M_α attached to h-handle $(\alpha_1, 2)$ where is the index of α_{i+1}

Furthermore from 3.1. we have that the topology of the two sublevel sets M_{α_i} and M_b ($b > \alpha_i$) only differ when $b > f(p_{i+1})$

Therefore, the sequence $\{M_0, M_1, \dots, M_{l-1}, M_l\}$ is a handle decomposition of M \square

Theorem 3.4

Let M be a compact smooth Mfd.
and $f: M \rightarrow \mathbb{R}$ be a Morse function.
Suppose $a, b \in \mathbb{R}$ st $f^{-1}[a, b]$ non-empty
If $f^{-1}[a, b]$ containing one critical point
at f w/ index k , the M_b is
diffeomorphic to the union of M_a with a
 k -handle.

Theorem 3.5

There exists a handle decomposition
for every compact smooth Mfd.