## Face Processing

IN4393 – Computer Vision



#### Introduction

- Face processing/analysis comprises a number of different tasks:
  - Face detection ("where is a face?")
  - Face recognition ("of whom is this face?")
  - Face verification ("are these faces the same?")
  - Expression recognition ("is this face happy or not?")

• Train a *classifier* to predict whether a bounding box contains a face or not:



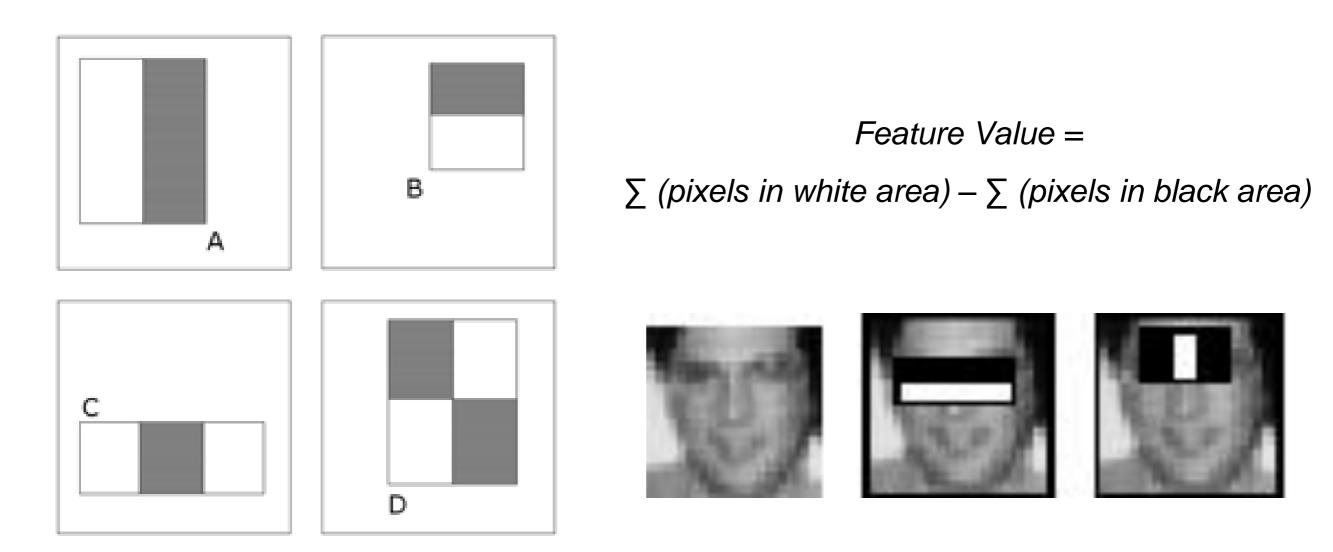
feature 1 →

At test time, use a sliding window detector for multiple scales:



• Use non-maxima suppression in x-y-scale space to filter classifier predictions

• Extract *Haar features* from the image patch, using the *integral image*:



• We find features that are common in faces, and use these as weak learners

• Features can be computed efficiently using the *integral image*:

12	8	2	4	7	12	20	22	26	33
2	11	3	6	8	14	33	38	48	63
3	2	0	1	10	17	38	43	54	79
1	5	2	7	2	18	44	51	69	96
0	0	2	3	2	18	44	53	74	103

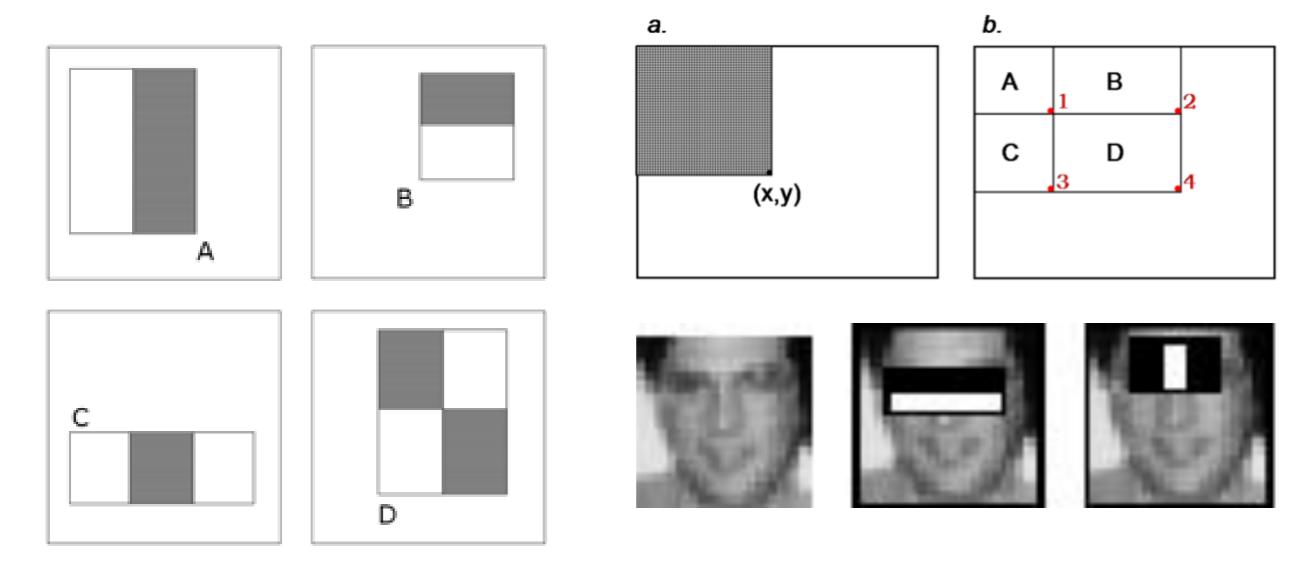
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AdaBoost training on annotated data set; learns collection of weak learners:

$$h(\mathbf{x}) = \operatorname{sign}\left[\sum_{i=1}^{m} \alpha_i h_i(\mathbf{x})\right]$$

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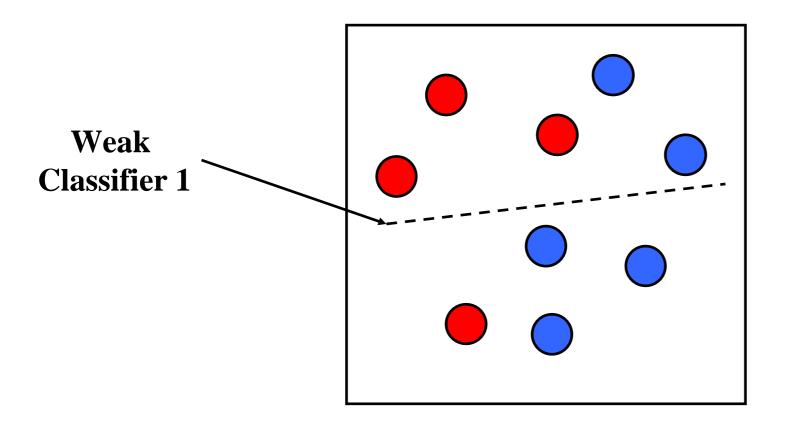
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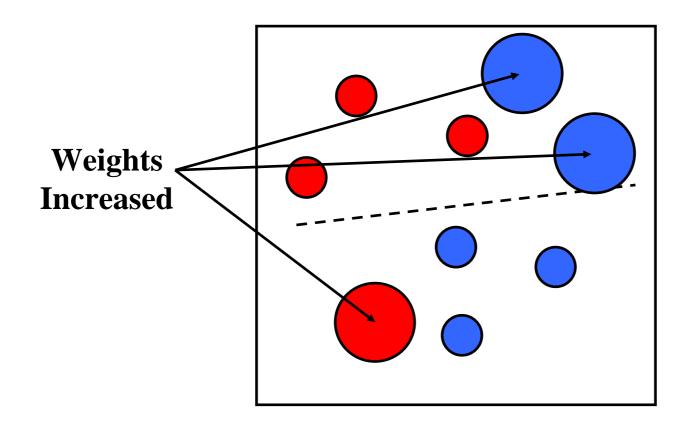
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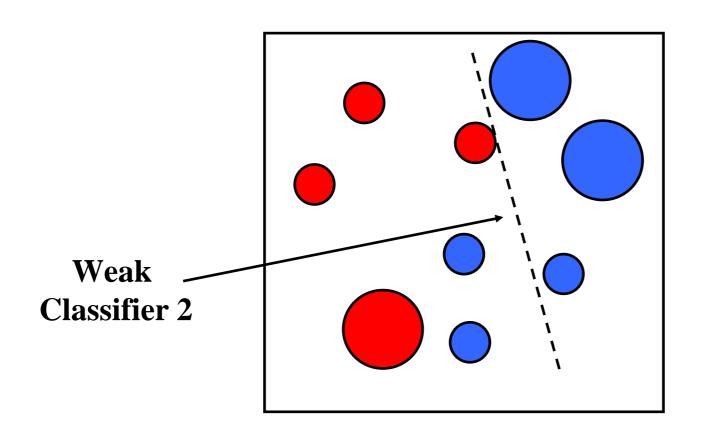
• Iteratively select the learner that minimizes the weighted classification error:

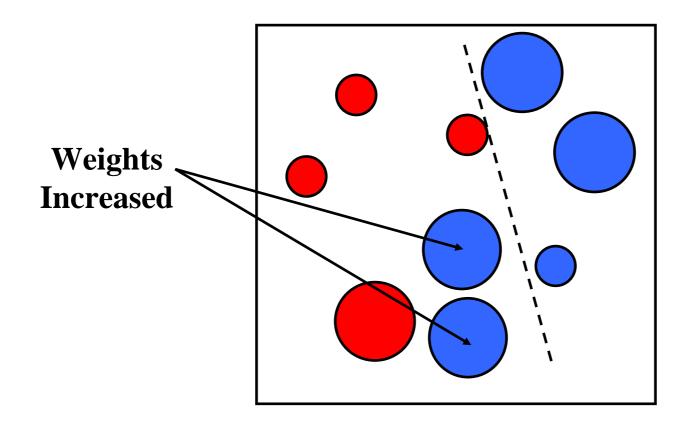
$$e_i = \sum_{n=1}^{N} w_{n,i} (1 - \delta(y_n, h_i(\mathbf{x}_n; \theta_i)))$$

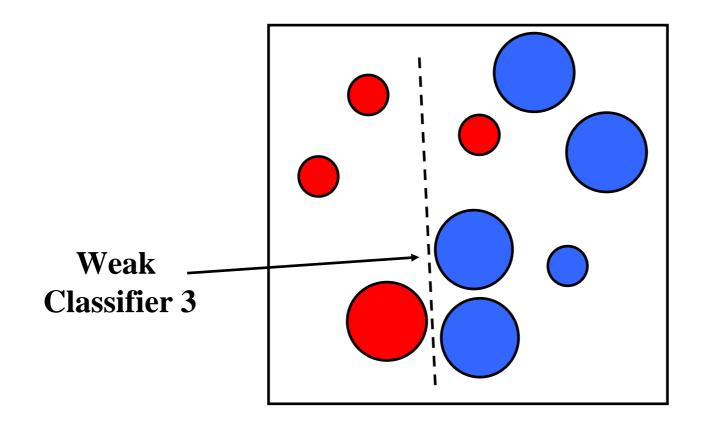
- Efficient algorithms exist to find the threshold in linear time
- Update the *per-instance weights* based on the classification error of weak learner



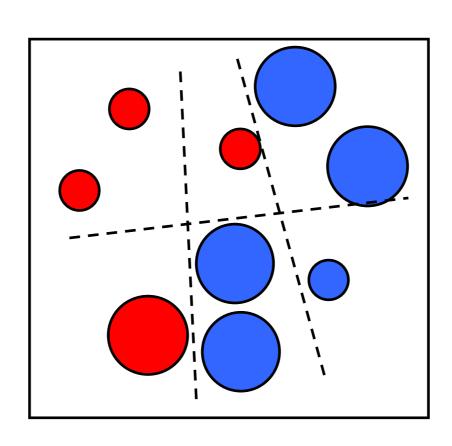






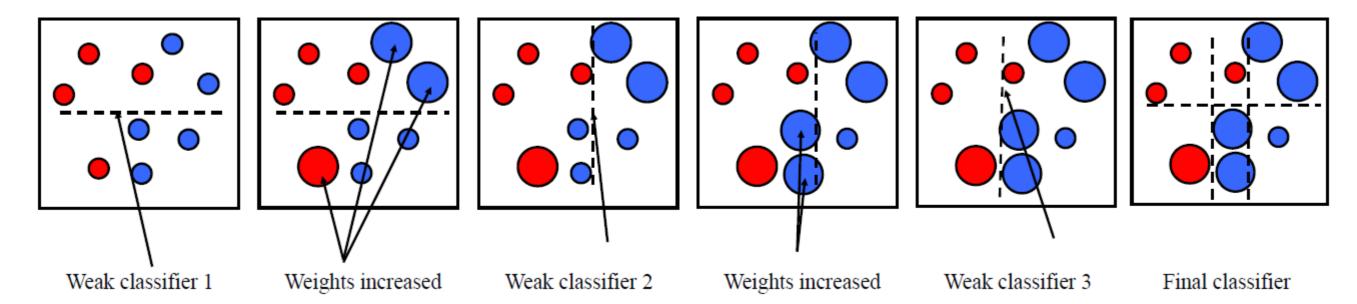


Final classifier is a combination of weak classifiers



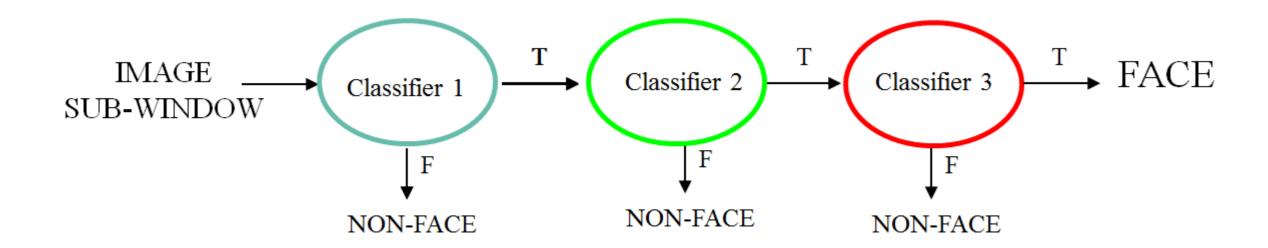
#### Face detection

Schematic overview of AdaBoost learning with decision stumps:



- Update for per-instance weights:  $w_{n,i+1} \leftarrow w_{n,i} \left(\frac{e_i}{1-e_i}\right)^{1-\delta(y_n,h_i(\mathbf{x}_n;\theta_i))}$
- Weak-learner weights given by:  $\alpha_i = -\log\left(\frac{e_i}{1-e_i}\right)$

- To perform the detection, we use a sliding window detector (at multiple scales)
- The classification of a patch can be performed using a cascaded classifier.



Note that this is extremely fast at test time: for negative examples, we typically only need to compute a very small number of features!

• False positive rate of a cascade with K classifiers:  $FPR = \prod_{i=1}^{K} FPR_i$ 

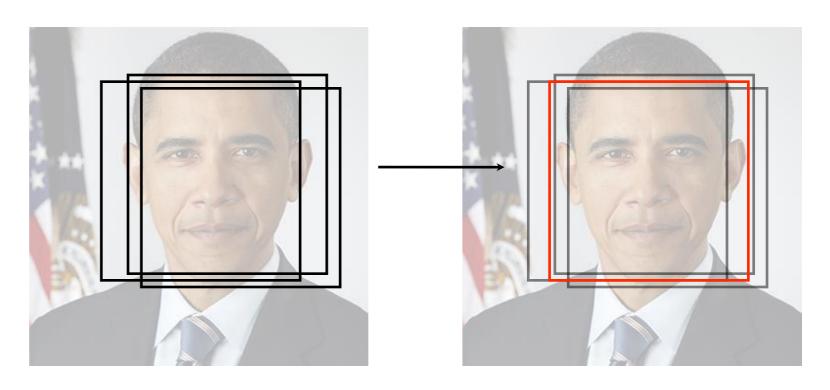
• Detection rate of a cascade with K classifiers:  $DR = \prod DR_i$ 

- False positive rate of a cascade with K classifiers:  $FPR = \prod_{i=1}^{K} FPR_i$
- Detection rate of a cascade with K classifiers:  $DR = \prod^{-1} DR_i$

- Assume we have a cascade of K = 32 classifiers:
  - To get a false positive rate of 10<sup>-6</sup>, each classifier may have FPR of 65%
  - To get a detection rate of 90%, each classifier should have DR of 99.7%

Multiple locations near a face will typically yields multiple detections

- In the original V&J detector, the detections are post-processed as follows:
  - Whenever two detections overlap, the bounding boxes are merged
  - The final detection is the average of the corners of all merged detections:

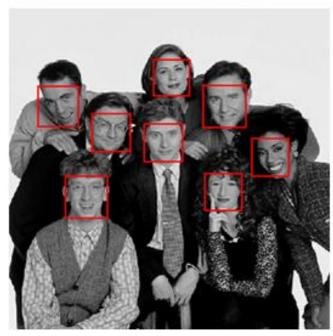


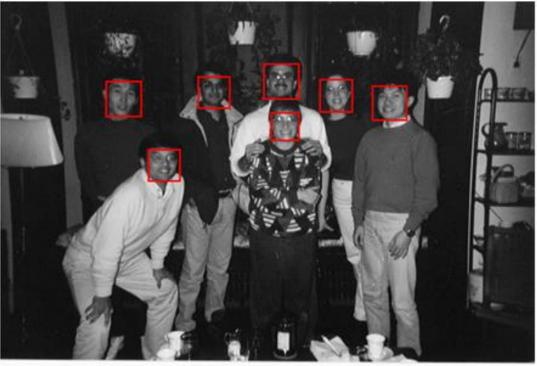
• Examples of face detections (using V&J implementation in OpenCV):











• Detection of profile faces requires training on separate data set:

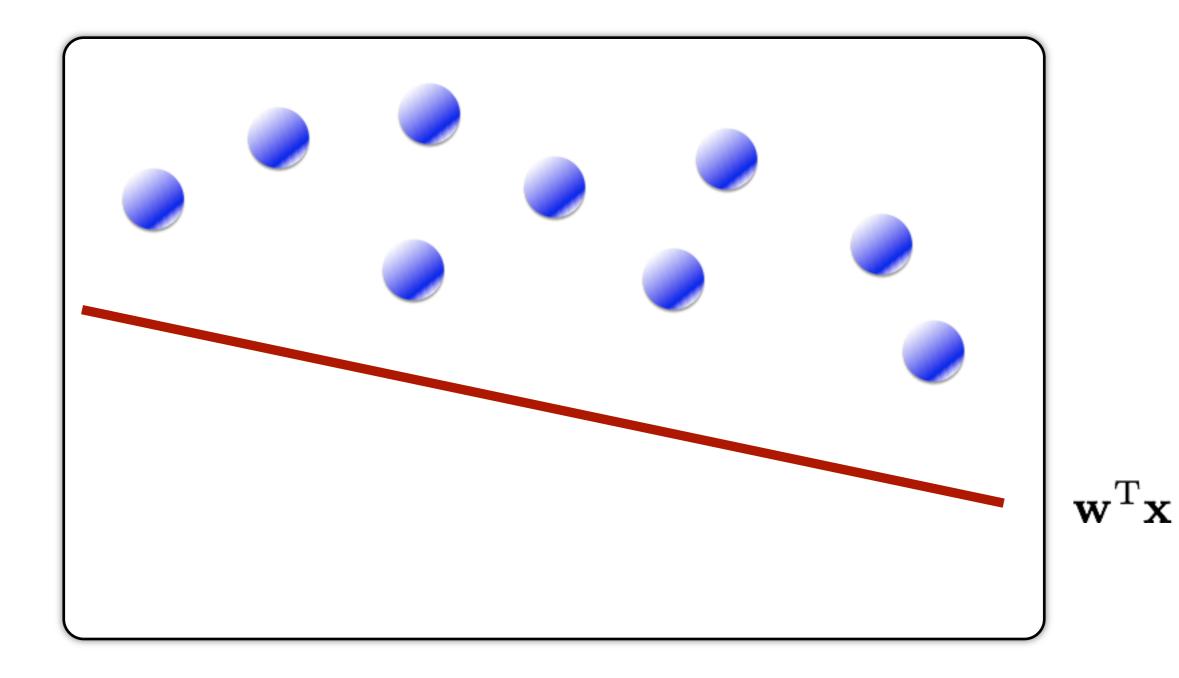


Consider face images as high-dimensional data points

Apply dimension reduction on the images to obtain low-dimensional features

• The reduction is performed using *principal components analysis* 

• Principal Components Analysis maps the data in a *linear subspace*, such that the *variance* of the projected data is maximized:



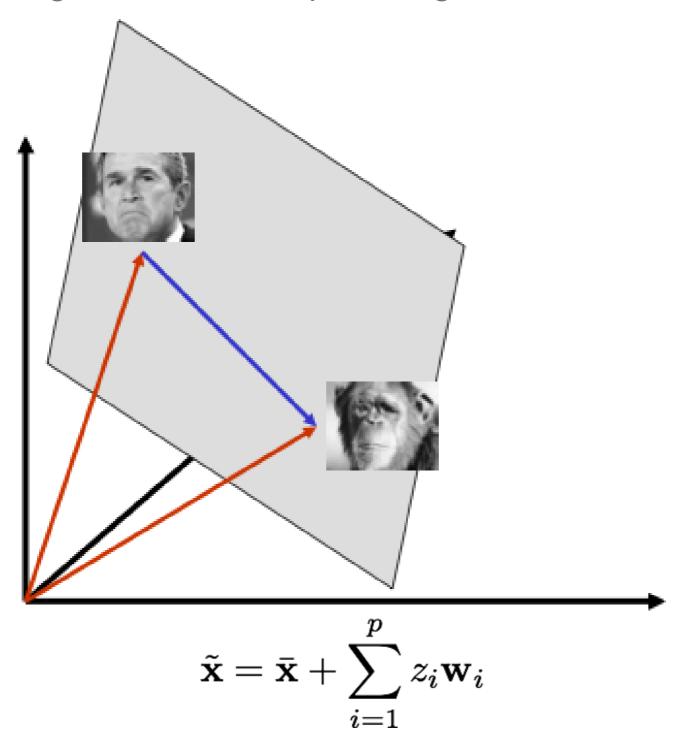
- Our objective is to maximize variance:  $\max_{\|\mathbf{w}\|^2=1} var(\mathbf{w}^T\mathbf{X})$
- Assuming zero-mean data:  $var(\mathbf{w}^T\mathbf{X}) = [\mathbf{w}^T\mathbf{X}\mathbf{X}^T\mathbf{w}] = [\mathbf{w}^T\mathbf{C}\mathbf{w}]$

• Enforce constraint using Lagrange multipliers:

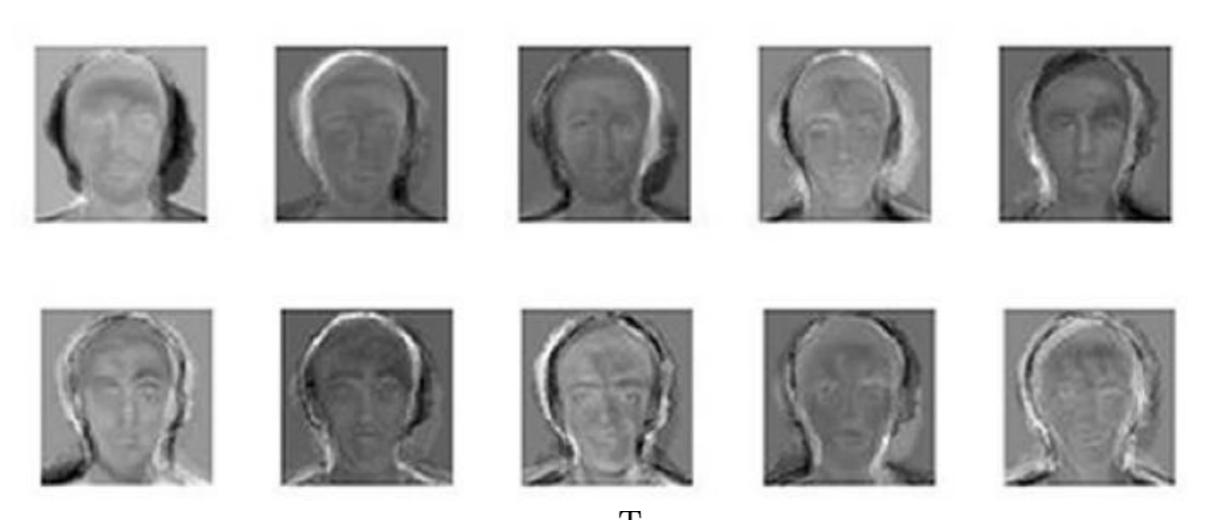
$$\max_{\|\mathbf{w}\|^2=1} var(\mathbf{w}^T \mathbf{X}) = \max_{\mathbf{w}, \lambda} \mathbf{w}^T \mathbf{C} \mathbf{w} - \lambda (\mathbf{w}^T \mathbf{w} - 1)$$

• Set gradient with respect to  ${f w}$  to zero:  ${f Cw}-\lambda{f w}=0$   ${f Cw}=\lambda{f w}$ 

We can move through the PCA subspace to generate new faces:

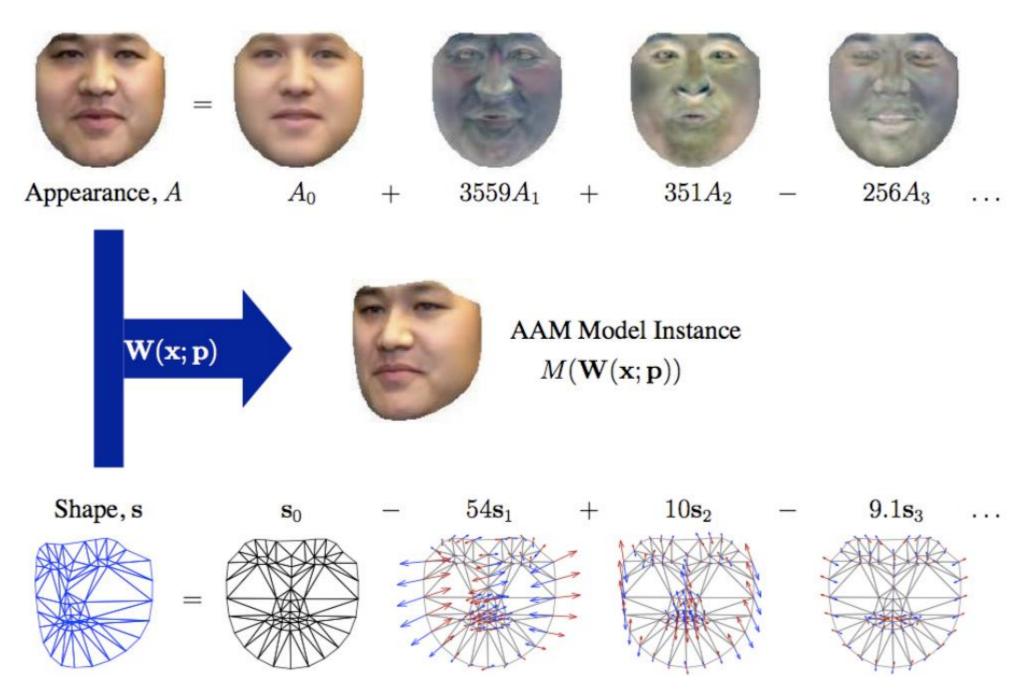


• We can visualize the eigenfaces to show the main sources of variation:

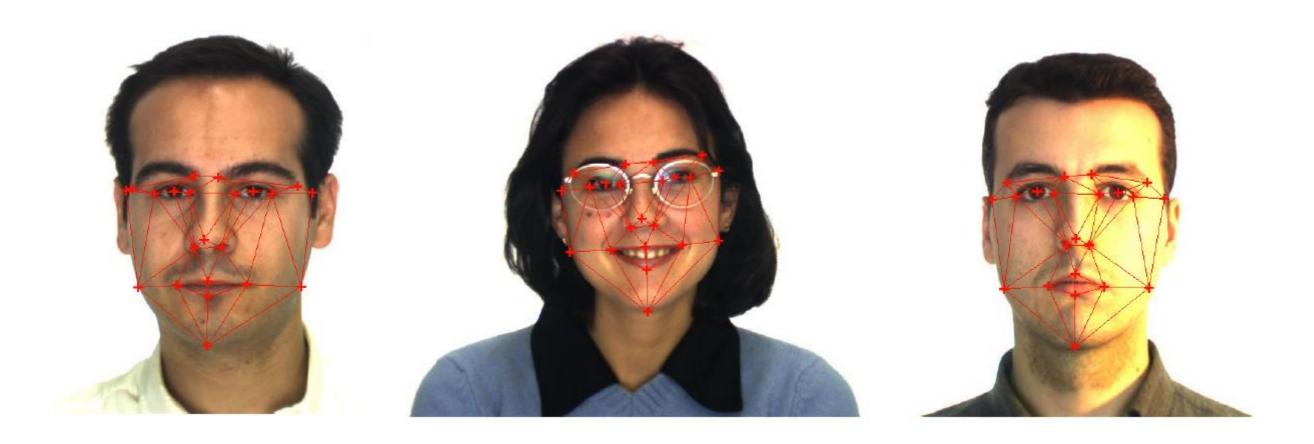


• We may use  $\mathbf{z} = \left[\mathbf{w}_1^{\mathrm{T}}\mathbf{x}, \dots, \mathbf{w}_p^{\mathrm{T}}\mathbf{x}\right]^{\mathrm{T}}$  as features for identity recognition

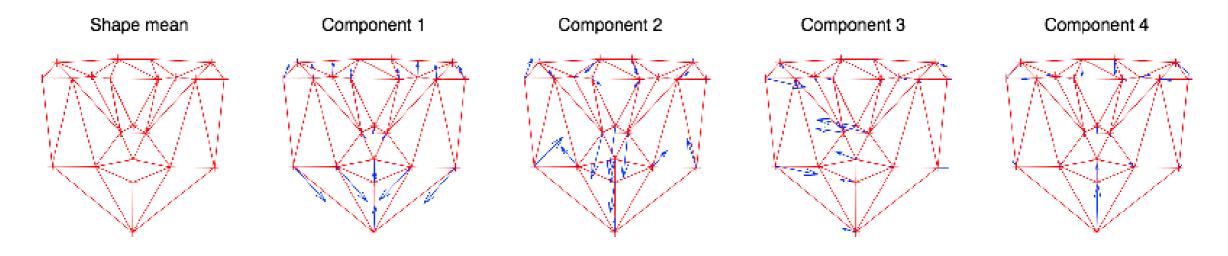
• Separates face variations into *shape* and *texture* variation:



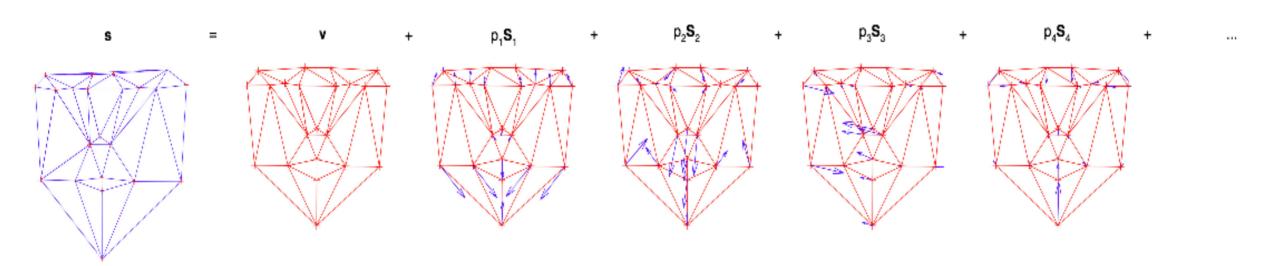
- Gather a data set of face images with annotated feature points
- Remove translations and rotations from point annotations (Procrustes alignment)
- Learn point distribution model and texture model from the data



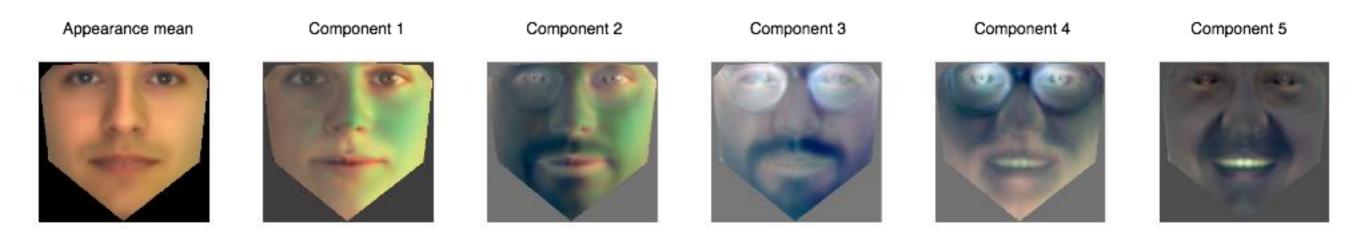
Point distribution model is obtained using PCA:



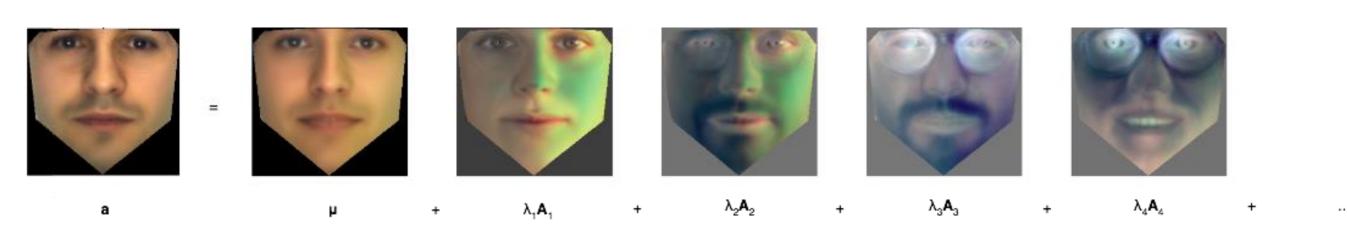
New facial shape is generated by linearly combining the components:



• Texture model is also obtained using PCA:



New facial textures are generated using a linear combination of components:



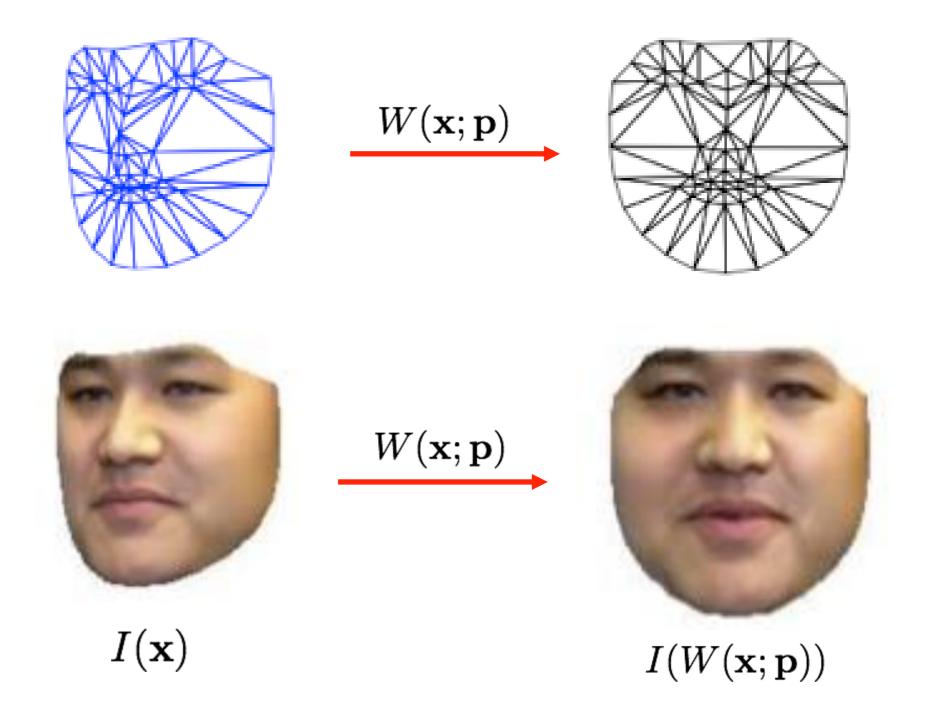
• We receive a new face image in which we want to measure facial features:



- Now what do we do to fit the active appearance model to this new face?
  - Find parameters of the model that best fit the face (minimizing sum of squared errors) using *Lucas-Kanade algorithm*

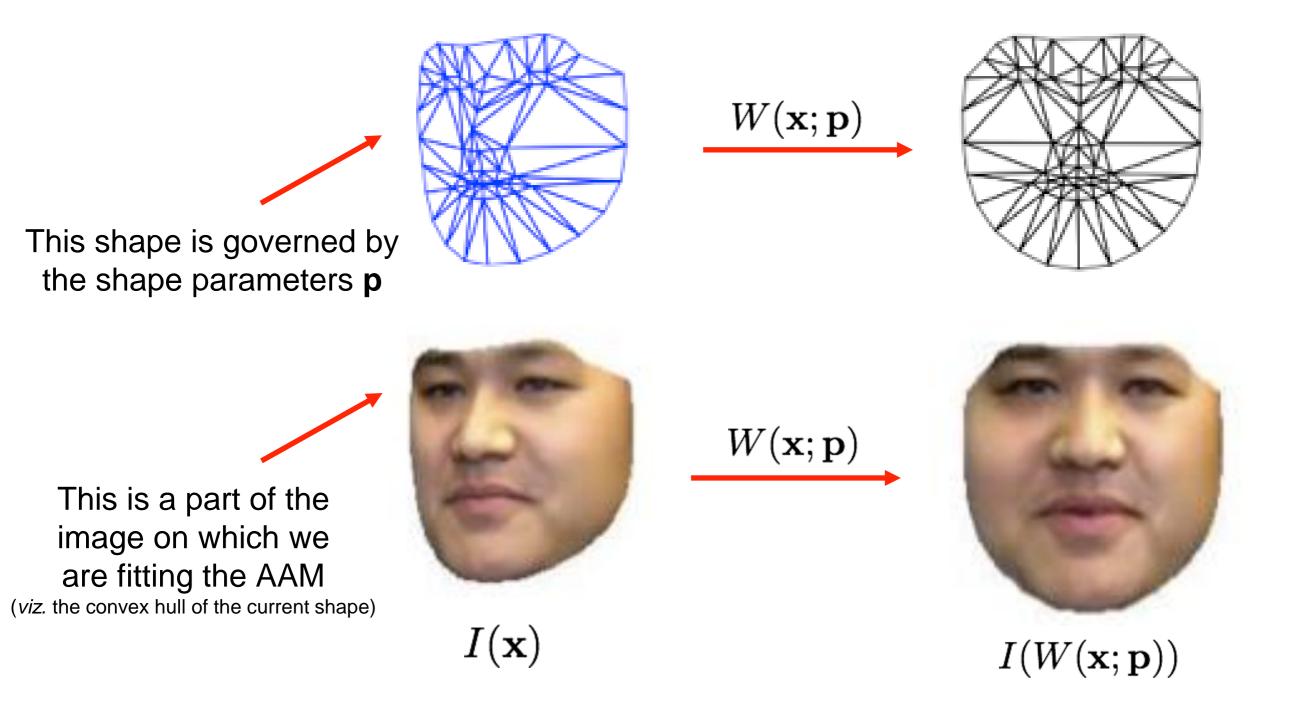
## Image warp

• We can warp between an arbitrary shape and the base shape (and vice versa):

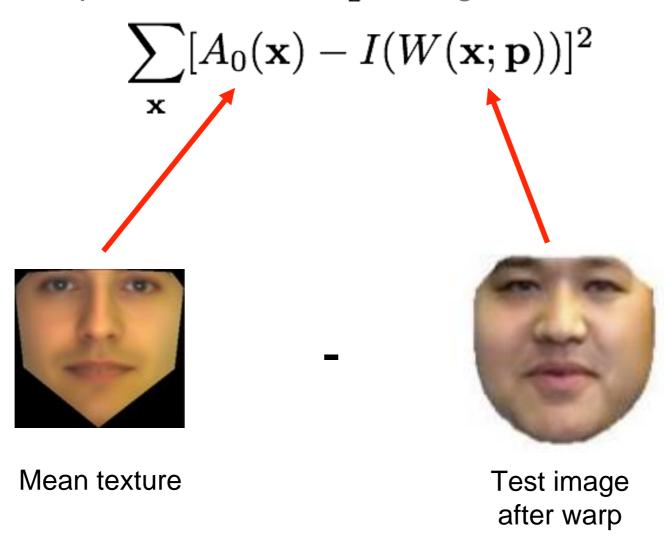


#### Image warp

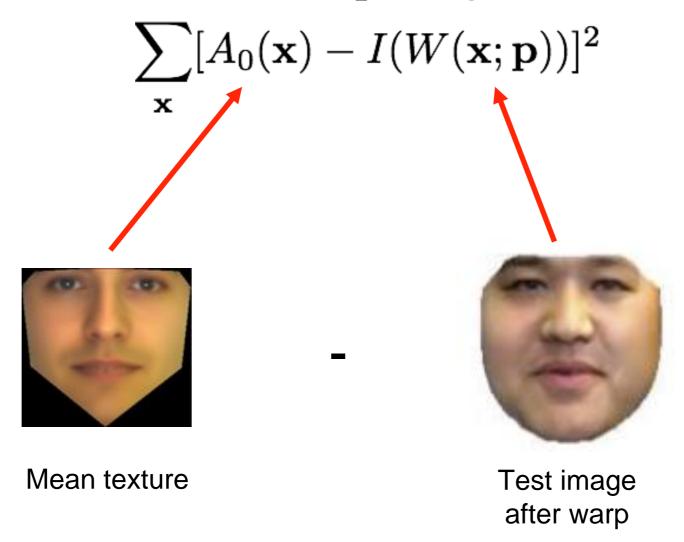
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• Minimizes sum of squared error w.r.t. **p** using *Gauss-Newton* algorithm:



Minimizes sum of squared error w.r.t. p using Gauss-Newton algorithm:



Goal: Set the shape parameters **p** such that the left image looks as much as possible like the right image

• Minimizes sum of squared error w.r.t. **p** using *Gauss-Newton* algorithm:

$$\sum_{\mathbf{x}} [A_0(\mathbf{x}) - I(W(\mathbf{x}; \mathbf{p}))]^2$$

• Iteratively solve for parameter increment  $\Delta {f p}$ :

$$\min_{\Delta \mathbf{p}} \sum_{\mathbf{x}} [A_0(\mathbf{x}) - I(W(\mathbf{x}; \mathbf{p} + \Delta \mathbf{p}))]^2$$

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• This is strongly non-linear, so write down *first-order Taylor expansion*:

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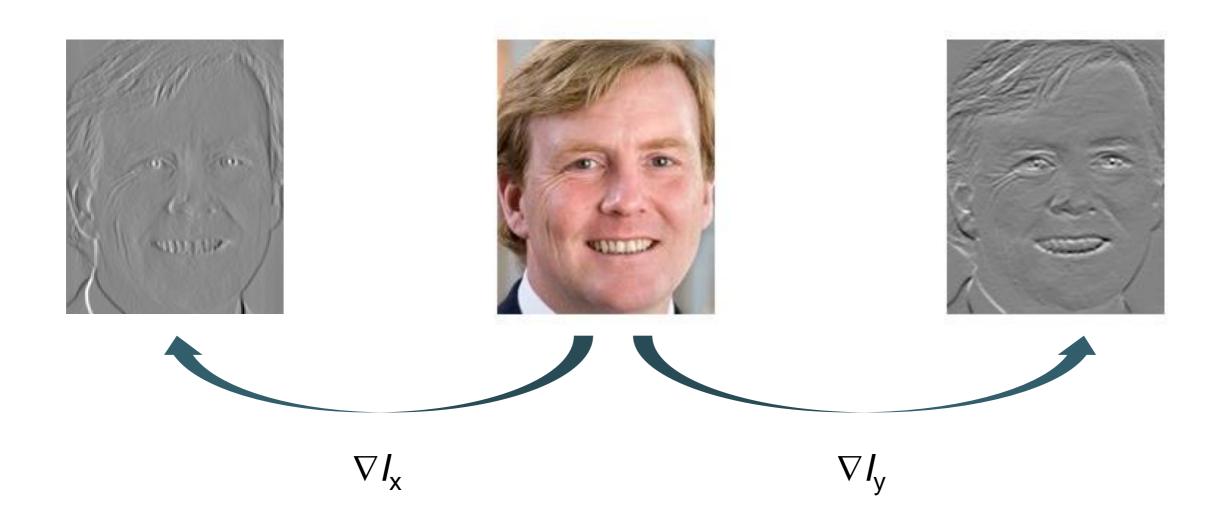
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$$\min_{\Delta \mathbf{p}} \sum_{\mathbf{x}} \left[ A_0(\mathbf{x}) - I(W(\mathbf{x}; \mathbf{p})) - \nabla I \frac{\partial W}{\partial \mathbf{p}} \Delta \mathbf{p} \right]^2$$

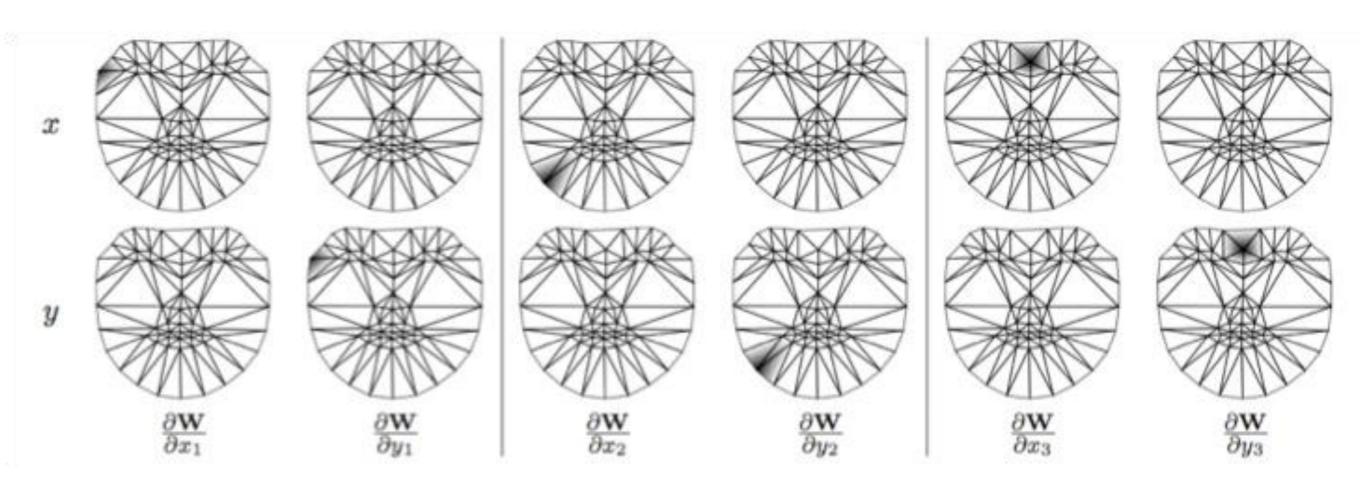
• As expected, this is a standard linear least squares problem

## **Gradient Images**

• Illustration of the image gradient  $\nabla I$ 

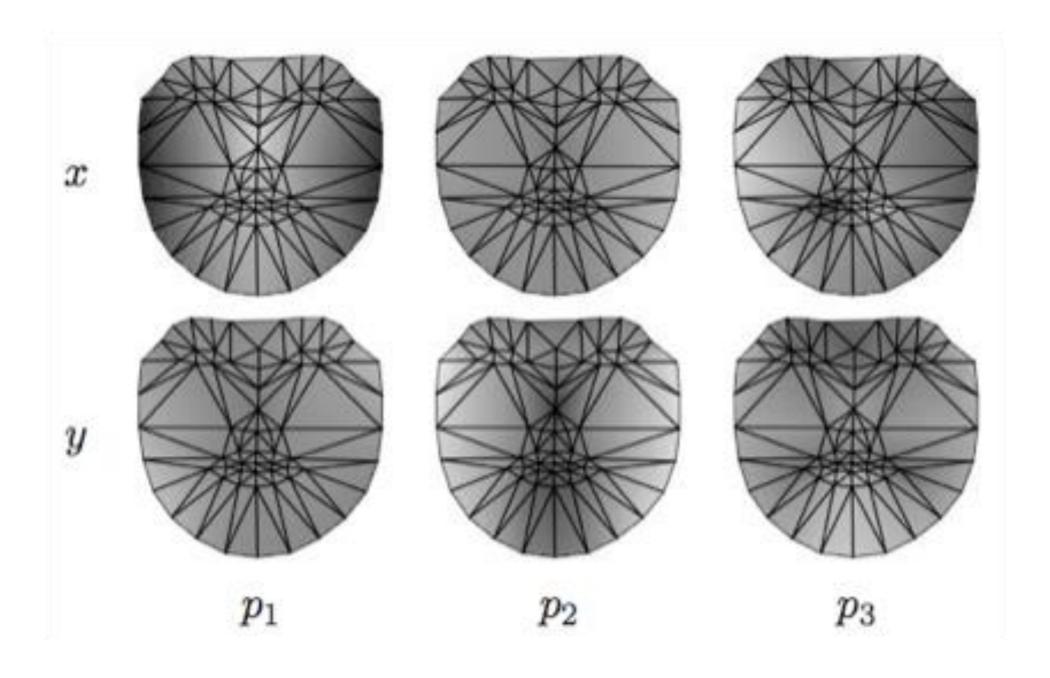


• Illustration of the warp Jacobian:  $\frac{\partial W}{\partial \mathbf{p}} = \frac{\partial W}{\partial \mathbf{x}} \frac{\partial \mathbf{x}}{\partial \mathbf{p}}$ 



• Illustration of the warp Jacobian:  $\frac{\partial W}{\partial x}$ 

$$\frac{\partial W}{\partial \mathbf{p}} = \frac{\partial W}{\partial \mathbf{x}} \frac{\partial \mathbf{x}}{\partial \mathbf{p}}$$



Closed-form solution for the parameter update:

$$\Delta \mathbf{p} = \mathbf{H}^{-1} \sum_{\mathbf{x}} \left[ \nabla I \frac{\partial W}{\partial \mathbf{p}} \right]^{\mathrm{T}} \left[ A_0(\mathbf{x}) - I(W(\mathbf{x}; \mathbf{p})) \right]$$

ullet Herein, old H is the Gauss-Newton approximation to the Hessian:

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Every iteration requires computation of warp Jacobian and Hessian

- 1. Warp *I* with  $\mathbf{W}(\mathbf{x};\mathbf{p}) \Rightarrow I(\mathbf{W}(\mathbf{x};\mathbf{p}))$
- 2. Compute error image  $A_o(x) I(\mathbf{W}(\mathbf{x}; \mathbf{p}))$
- 3. Warp gradient of I to compute  $\nabla I$
- 4. Evaluate Jacobian  $\frac{\partial \mathbf{W}}{\partial \mathbf{p}}$
- 5. Compute Hessian
- 6. Compute  $\Delta \mathbf{p}$
- 7. Update parameters  $\mathbf{p} \leftarrow \mathbf{p} + \Delta \mathbf{p}$

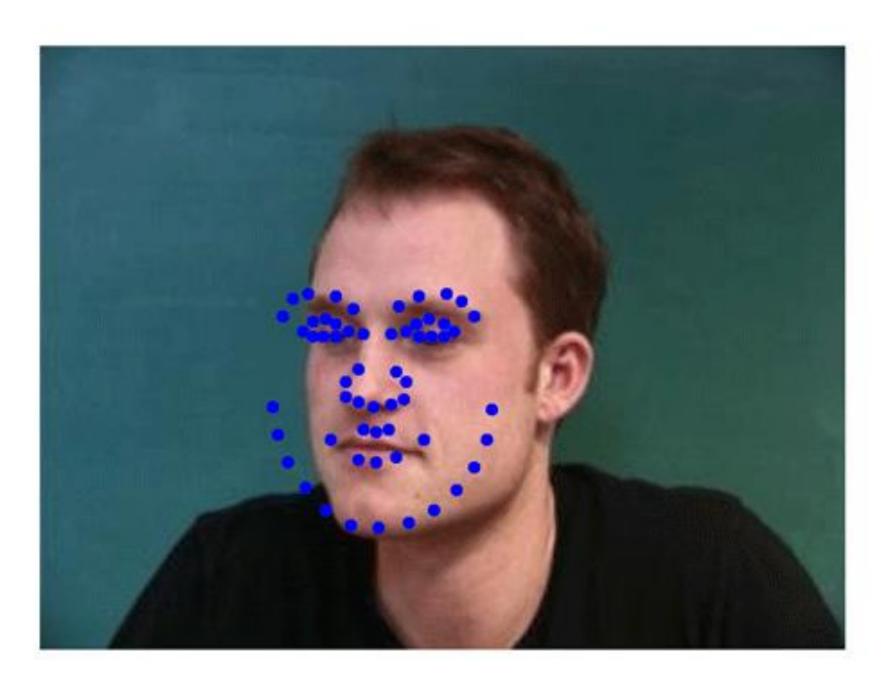


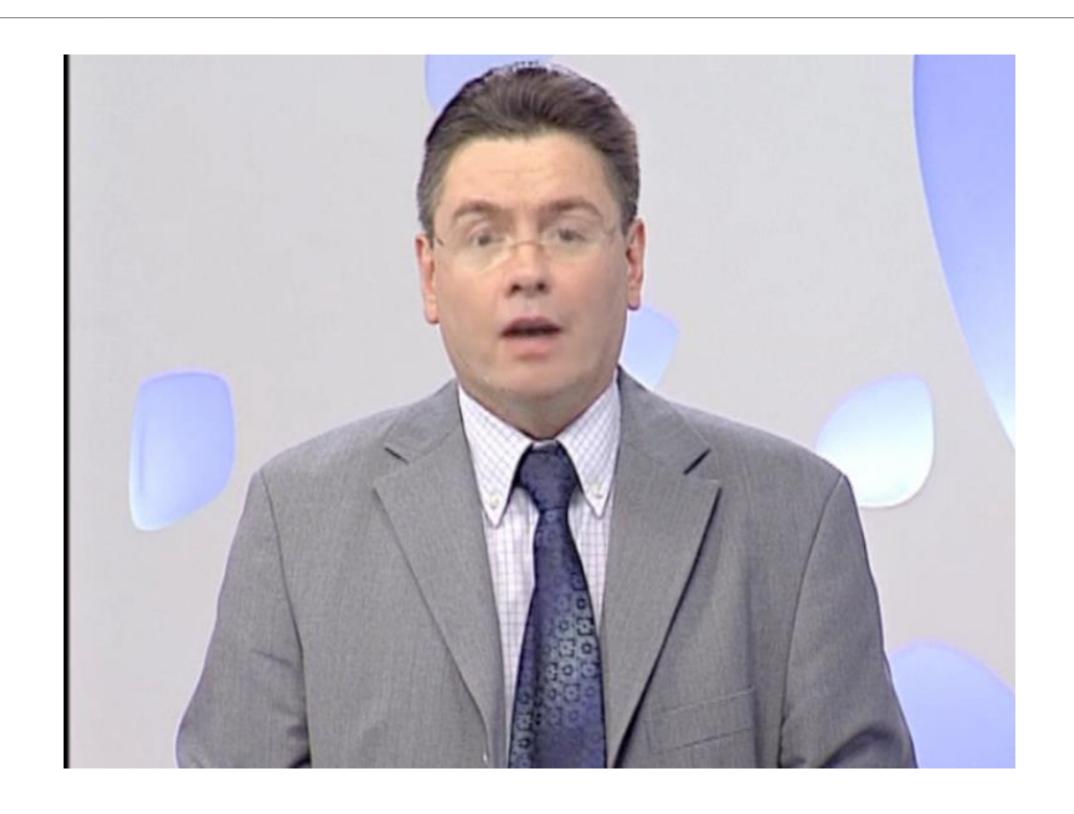


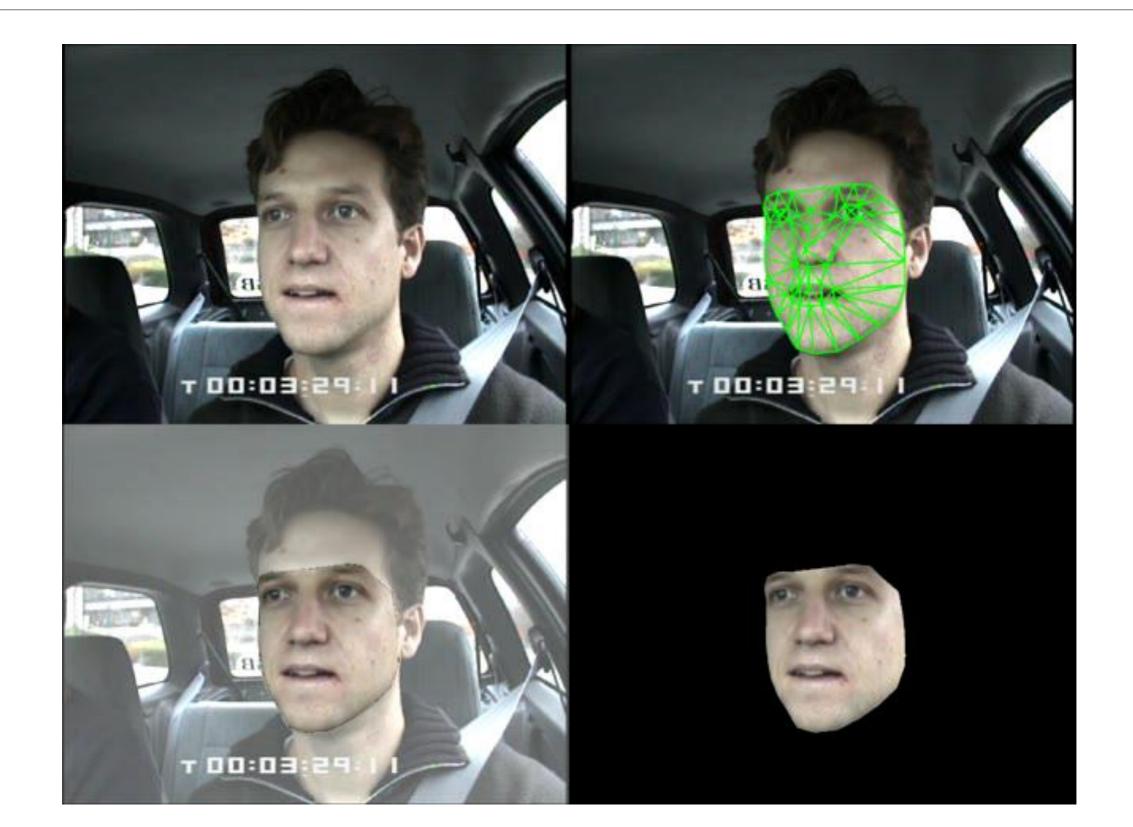




• Illustration of fitting a shape model:







### Face recognition and expression analysis

- Facial feature points (landmarks) can be used for a number of tasks:
  - Facial expression analysis:
    - Measure variations of landmark locations over time (shape variation); use texture features to measure presence of wrinkles (texture variation), etc.

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  - Facial expression analysis:
    - Measure variations of landmark locations over time (shape variation); use texture features to measure presence of wrinkles (texture variation), etc.
  - Facial identity recognition or face verification (passport control):
    - Measure characteristics that are invariant under expressions but person-specific: inter-ocular distance, relative position of nose, *etc.*
    - Build skin models:







### Example: Recognition of Action Units (FACS)



AU 1
Inner brow raise



AU 2
Outer brow raise



AU 4 Brow lower



AU 6 Cheek raise



AU 9 Nose wrinkler



AU 12 Lip corner pull



AU 15 Lip corner depress



AU 20 Lip strecher

### Example: Recognition of Action Units (FACS)

- Inner brow raiser:
- Outer brow raiser:
- Brow lowerer:
- Upper lid raiser:
- Nose wrinkler:
- Lip corner depressor:
- Etcetera...





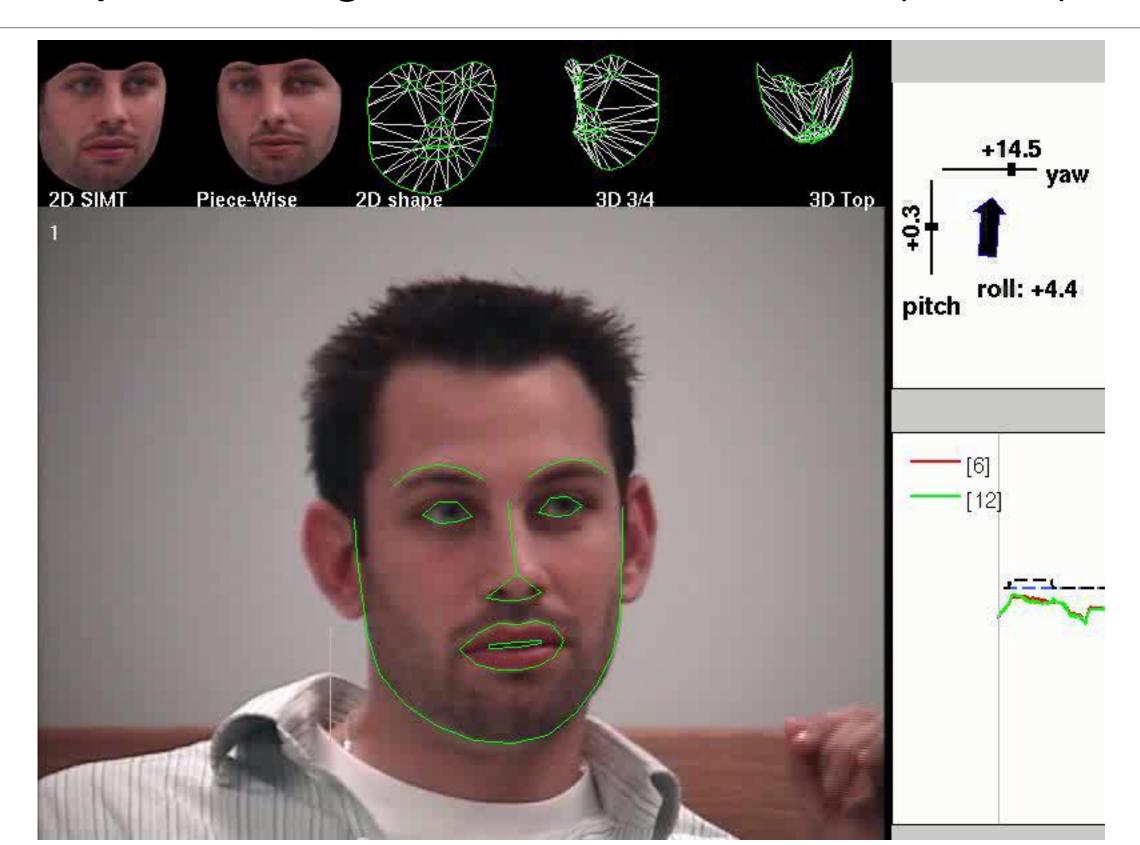




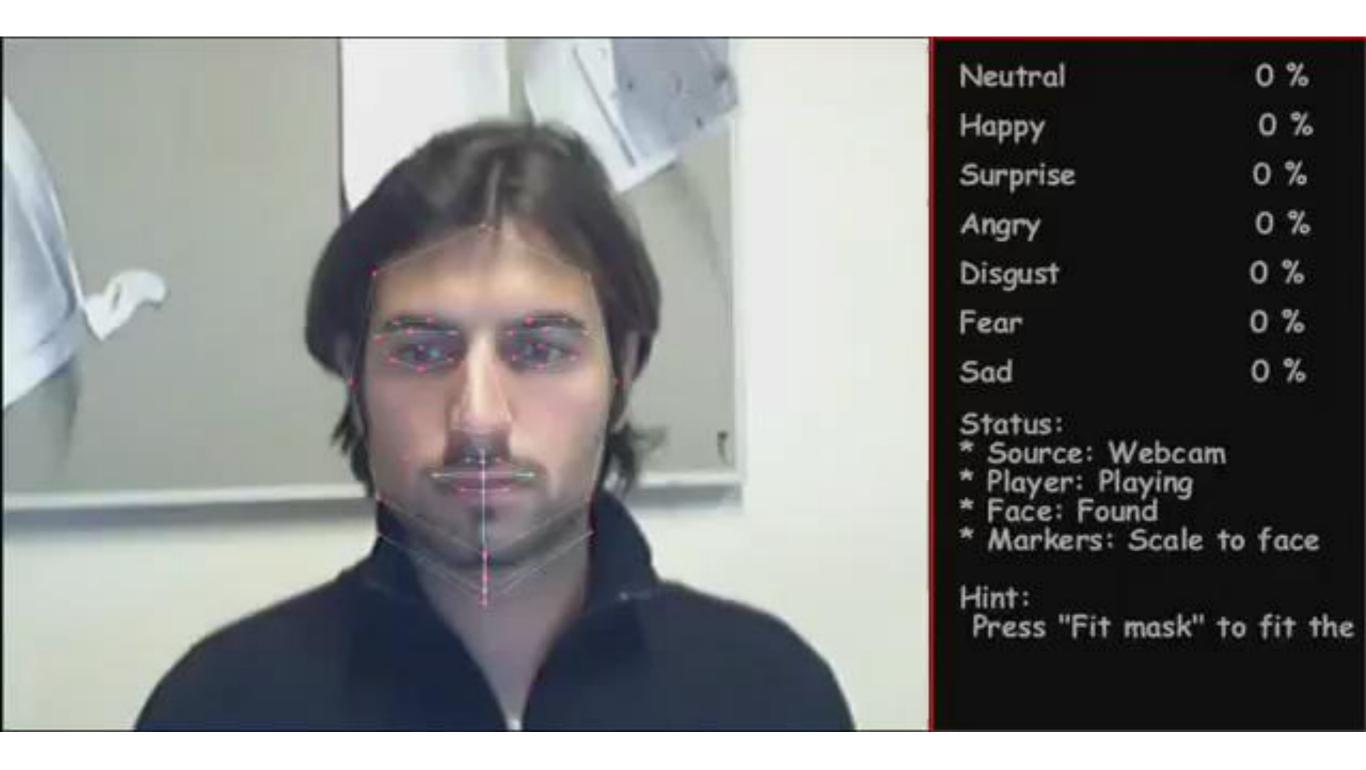




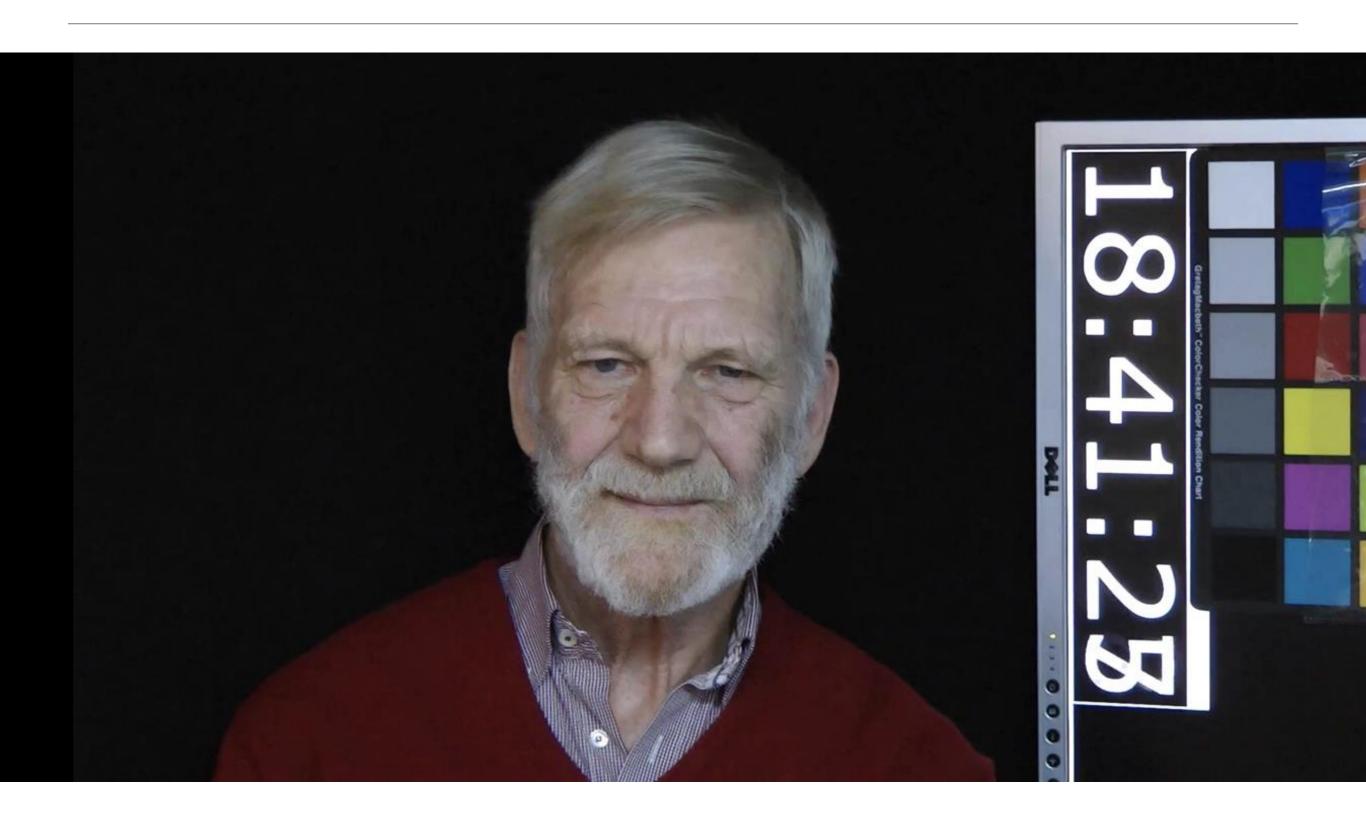
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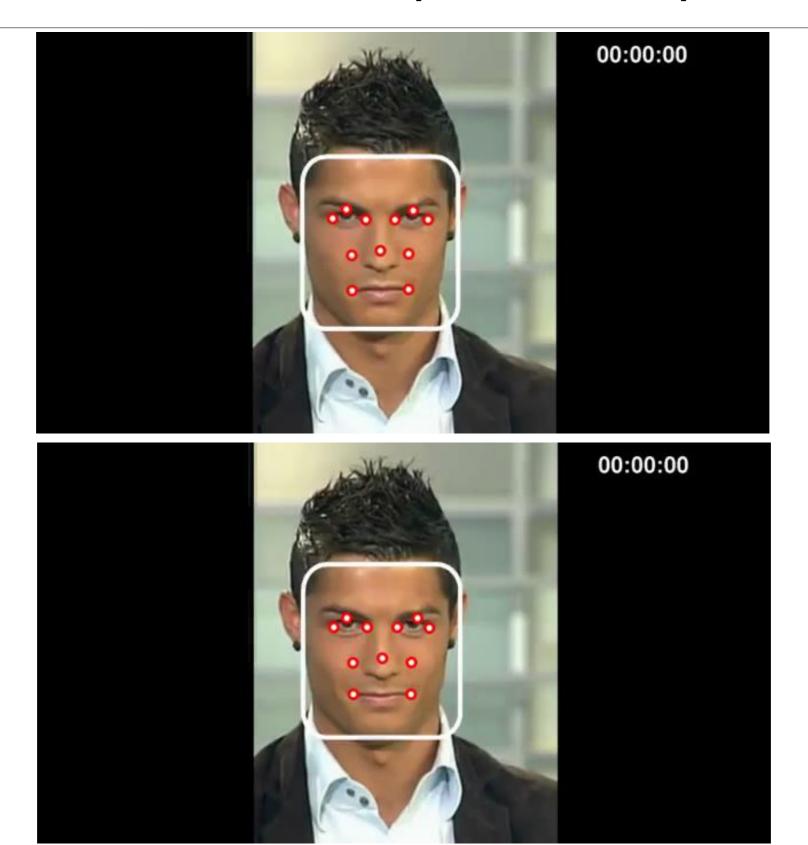
### **Example: Expression Recognition**



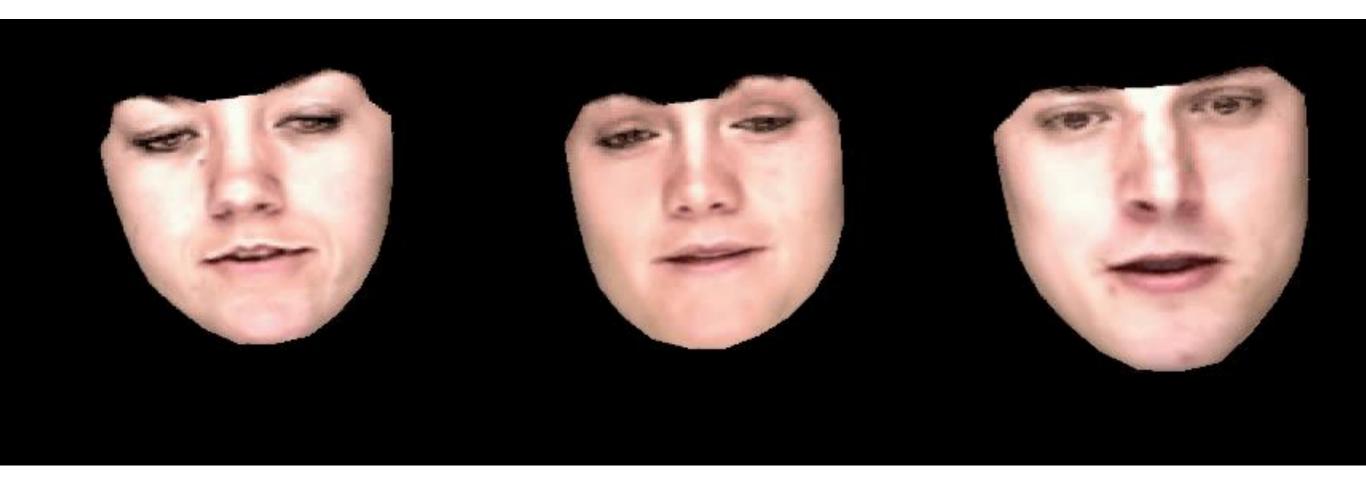
## Example: Detection of Expression Spontaneity



## Example: Detection of Expression Spontaneity



# Example: Expression cloning

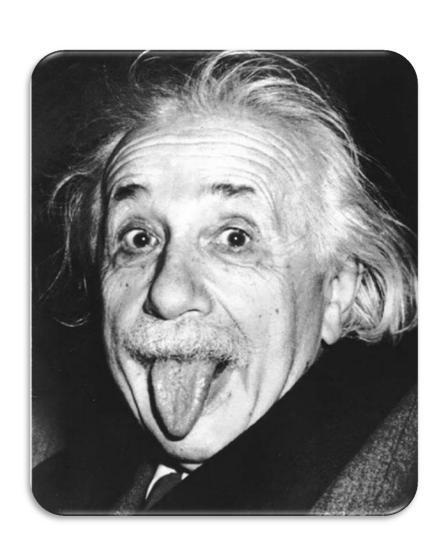


## Example: Expression cloning



### MSc Projects

- Are you interested in face processing?
  - Face Tracking
  - Expression Analysis
  - Age Estimation
  - Face Recognition
  - Kinship Verification/Recognition
  - Automatic Assessment of Depression
  - And more... (only limit is your imagination)



Reading material: Section 14.1 and 14.2 Section 1 and 2 of "Lucas-Kanade 20 Years on"