

VECTOR MECHANICS FOR ENGINEERS: **STATICS**

Ferdinand P. Beer
E. Russell Johnston, Jr.

Lecture Notes:
J. Walt Oler
Texas Tech University

Distributed Forces:
Centroids and Centers
of Gravity

Vector Mechanics for Engineers: Statics

Contents

[Introduction](#)

[Center of Gravity of a 2D Body](#)

[Centroids and First Moments of Areas
and Lines](#)

[Centroids of Common Shapes of Areas](#)

[Centroids of Common Shapes of Lines](#)

[Composite Plates and Areas](#)

[Sample Problem 5.1](#)

[Determination of Centroids by
Integration](#)

[Sample Problem 5.4](#)

[Theorems of Pappus-Guldinus](#)

[Sample Problem 5.7](#)

[Distributed Loads on Beams](#)

[Sample Problem 5.9](#)

[Center of Gravity of a 3D Body:
Centroid of a Volume](#)

[Centroids of Common 3D Shapes](#)

[Composite 3D Bodies](#)

[Sample Problem 5.12](#)



Vector Mechanics for Engineers: Statics

Introduction

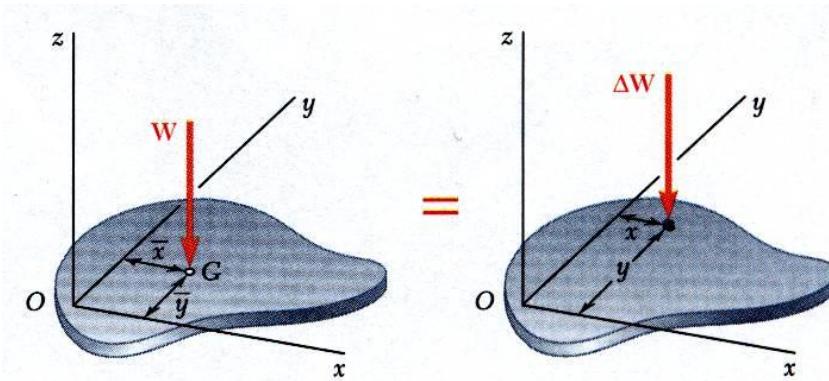
- The earth exerts a gravitational force on each of the particles forming a body. These forces can be replaced by a single equivalent force equal to the weight of the body and applied at the *center of gravity* for the body.
- The *centroid of an area* is analogous to the center of gravity of a body. The concept of the *first moment of an area* is used to locate the centroid.
- Determination of the area of a *surface of revolution* and the volume of a *body of revolution* are accomplished with the *Theorems of Pappus-Guldinus*.



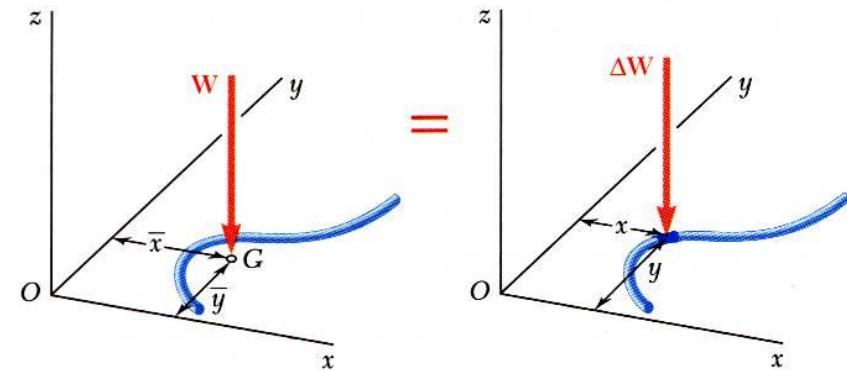
Vector Mechanics for Engineers: Statics

Center of Gravity of a 2D Body

- Center of gravity of a plate



- Center of gravity of a wire



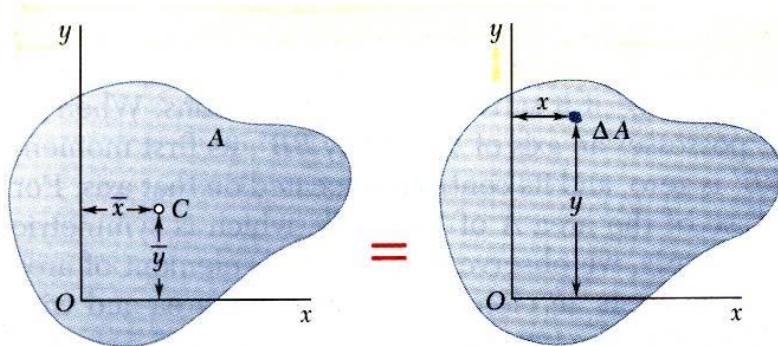
$$\sum M_y \quad \bar{x}W = \sum x\Delta W \\ = \int x dW$$

$$\sum M_x \quad \bar{y}W = \sum y\Delta W \\ = \int y dW$$

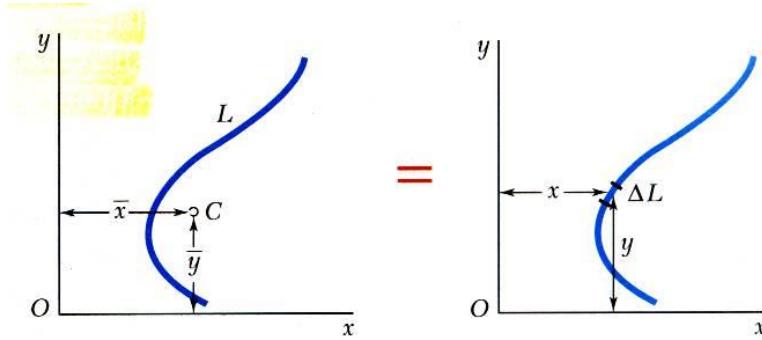
Vector Mechanics for Engineers: Statics

Centroids and First Moments of Areas and Lines

- Centroid of an area



- Centroid of a line



$$\bar{x}W = \int x dW$$

$$\bar{x}(\gamma At) = \int x(\gamma t) dA$$

$$\bar{x}A = \int x dA = Q_y$$

= first moment with respect to y

$$\bar{y}A = \int y dA = Q_x$$

= first moment with respect to x

$$\bar{x}W = \int x dW$$

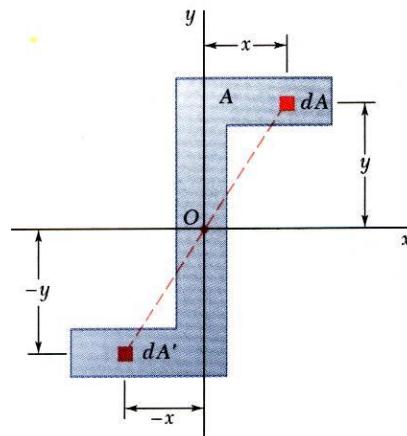
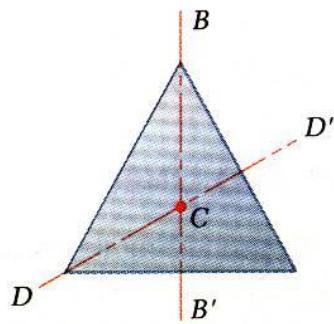
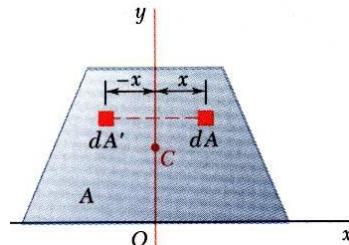
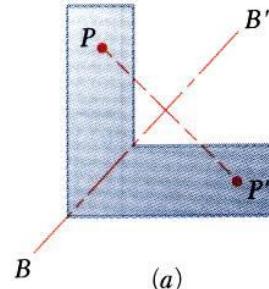
$$\bar{x}(\gamma La) = \int x(\gamma a) dL$$

$$\bar{x}L = \int x dL$$

$$\bar{y}L = \int y dL$$

Vector Mechanics for Engineers: Statics

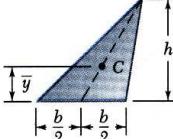
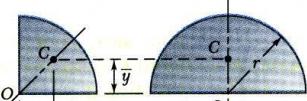
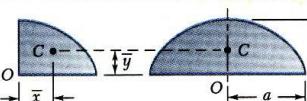
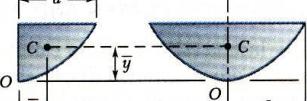
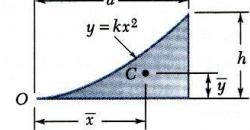
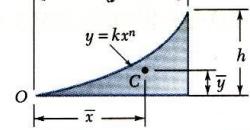
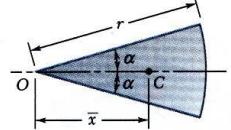
First Moments of Areas and Lines



- An area is symmetric with respect to an axis BB' if for every point P there exists a point P' such that PP' is perpendicular to BB' and is divided into two equal parts by BB' .
- The first moment of an area with respect to a line of symmetry is zero.
- If an area possesses a line of symmetry, its centroid lies on that axis
- If an area possesses two lines of symmetry, its centroid lies at their intersection.
- An area is symmetric with respect to a center O if for every element dA at (x,y) there exists an equal area of dA' at $(-x,-y)$.
- The centroid of the area coincides with the center of symmetry.

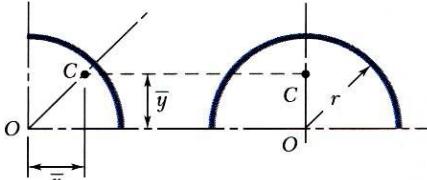
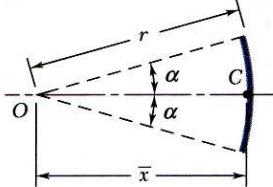
Vector Mechanics for Engineers: Statics

Centroids of Common Shapes of Areas

| Shape | Diagram | \bar{x} | \bar{y} | Area |
|-------------------------|--|----------------------------------|---------------------|---------------------|
| Triangular area |  | | $\frac{h}{3}$ | $\frac{bh}{2}$ |
| Quarter-circular area |  | $\frac{4r}{3\pi}$ | $\frac{4r}{3\pi}$ | $\frac{\pi r^2}{4}$ |
| Semicircular area | | 0 | $\frac{4r}{3\pi}$ | $\frac{\pi r^2}{2}$ |
| Quarter-elliptical area |  | $\frac{4a}{3\pi}$ | $\frac{4b}{3\pi}$ | $\frac{\pi ab}{4}$ |
| Semielliptical area | | 0 | $\frac{4b}{3\pi}$ | $\frac{\pi ab}{2}$ |
| Semiparabolic area |  | $\frac{3a}{8}$ | $\frac{3h}{5}$ | $\frac{2ah}{3}$ |
| Parabolic area | | 0 | $\frac{3h}{5}$ | $\frac{4ah}{3}$ |
| Parabolic spandrel |  | $\frac{3a}{4}$ | $\frac{3h}{10}$ | $\frac{ah}{3}$ |
| General spandrel |  | $\frac{n+1}{n+2}a$ | $\frac{n+1}{4n+2}h$ | $\frac{ah}{n+1}$ |
| Circular sector |  | $\frac{2r \sin \alpha}{3\alpha}$ | 0 | αr^2 |

Vector Mechanics for Engineers: Statics

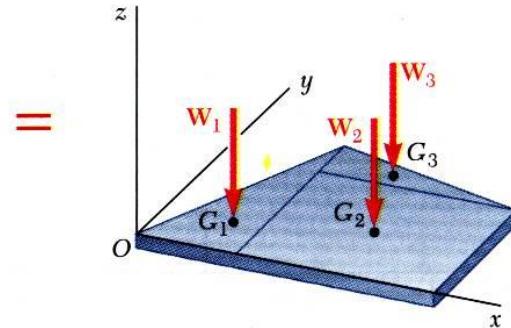
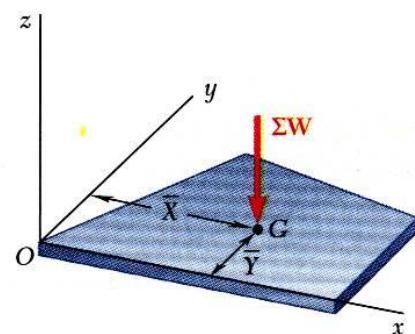
Centroids of Common Shapes of Lines

| Shape | | \bar{x} | \bar{y} | Length |
|----------------------|--|--------------------------------|------------------|-------------------|
| Quarter-circular arc |  | $\frac{2r}{\pi}$ | $\frac{2r}{\pi}$ | $\frac{\pi r}{2}$ |
| Semicircular arc | | 0 | $\frac{2r}{\pi}$ | πr |
| Arc of circle |  | $\frac{r \sin \alpha}{\alpha}$ | 0 | $2\alpha r$ |



Vector Mechanics for Engineers: Statics

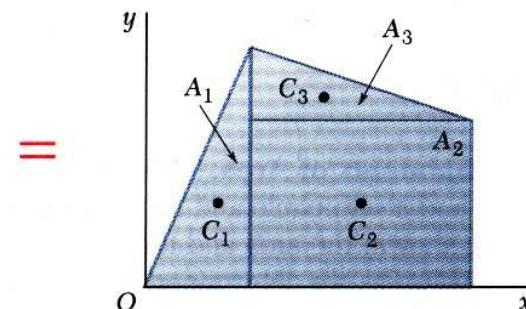
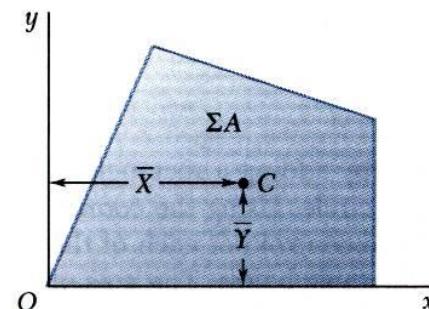
Composite Plates and Areas



- Composite plates

$$\bar{X} \sum W = \sum \bar{x} W$$

$$\bar{Y} \sum W = \sum \bar{y} W$$



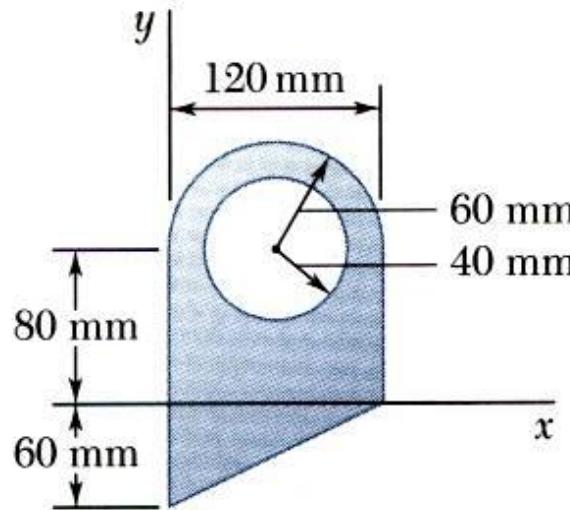
- Composite area

$$\bar{X} \sum A = \sum \bar{x} A$$

$$\bar{Y} \sum A = \sum \bar{y} A$$

Vector Mechanics for Engineers: Statics

Sample Problem 5.1



For the plane area shown, determine the first moments with respect to the x and y axes and the location of the centroid.

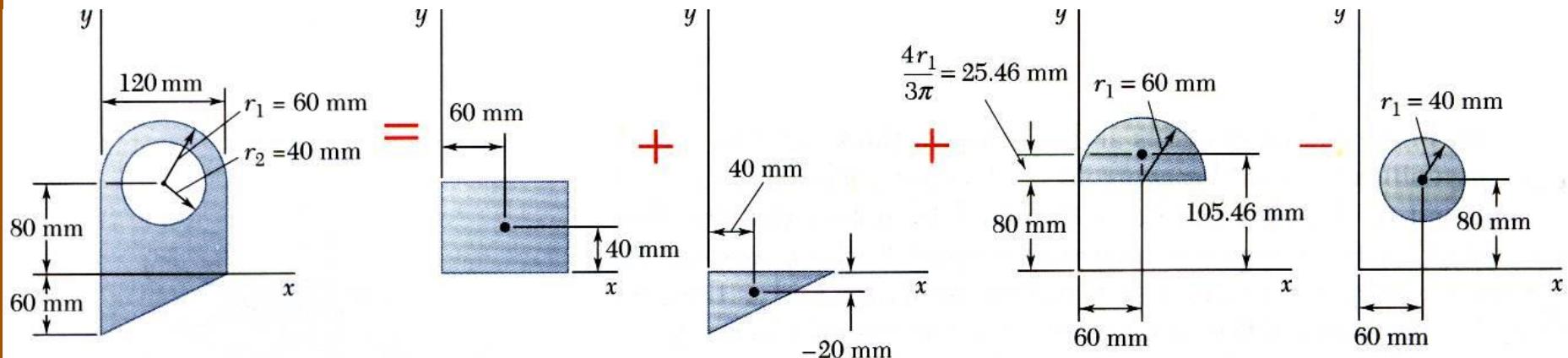
SOLUTION:

- Divide the area into a triangle, rectangle, and semicircle with a circular cutout.
- Calculate the first moments of each area with respect to the axes.
- Find the total area and first moments of the triangle, rectangle, and semicircle. Subtract the area and first moment of the circular cutout.
- Compute the coordinates of the area centroid by dividing the first moments by the total area.



Vector Mechanics for Engineers: Statics

Sample Problem 5.1



| Component | A, mm^2 | \bar{x}, mm | \bar{y}, mm | $\bar{x}A, \text{mm}^3$ | $\bar{y}A, \text{mm}^3$ |
|------------|--|----------------------|----------------------|--|--|
| Rectangle | $(120)(80) = 9.6 \times 10^3$ | 60 | 40 | $+576 \times 10^3$ | $+384 \times 10^3$ |
| Triangle | $\frac{1}{2}(120)(60) = 3.6 \times 10^3$ | 40 | -20 | $+144 \times 10^3$ | -72×10^3 |
| Semicircle | $\frac{1}{2}\pi(60)^2 = 5.655 \times 10^3$ | 60 | 105.46 | $+339.3 \times 10^3$ | $+596.4 \times 10^3$ |
| Circle | $-\pi(40)^2 = -5.027 \times 10^3$ | 60 | 80 | -301.6×10^3 | -402.2×10^3 |
| | $\Sigma A = 13.828 \times 10^3$ | | | $\Sigma \bar{x}A = +757.7 \times 10^3$ | $\Sigma \bar{y}A = +506.2 \times 10^3$ |

- Find the total area and first moments of the triangle, rectangle, and semicircle. Subtract the area and first moment of the circular cutout.

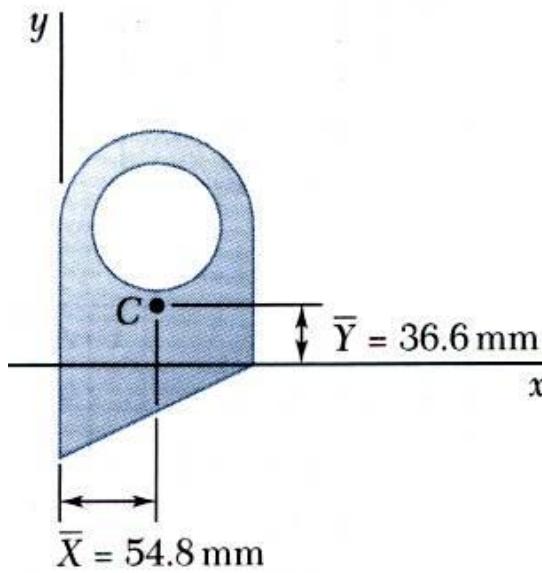
$$Q_x = +506.2 \times 10^3 \text{ mm}^3$$

$$Q_y = +757.7 \times 10^3 \text{ mm}^3$$

Vector Mechanics for Engineers: Statics

Sample Problem 5.1

- Compute the coordinates of the area centroid by dividing the first moments by the total area.



$$\bar{X} = \frac{\sum \bar{x}A}{\sum A} = \frac{+757.7 \times 10^3 \text{ mm}^3}{13.828 \times 10^3 \text{ mm}^2}$$

$$\boxed{\bar{X} = 54.8 \text{ mm}}$$

$$\bar{Y} = \frac{\sum \bar{y}A}{\sum A} = \frac{+506.2 \times 10^3 \text{ mm}^3}{13.828 \times 10^3 \text{ mm}^2}$$

$$\boxed{\bar{Y} = 36.6 \text{ mm}}$$

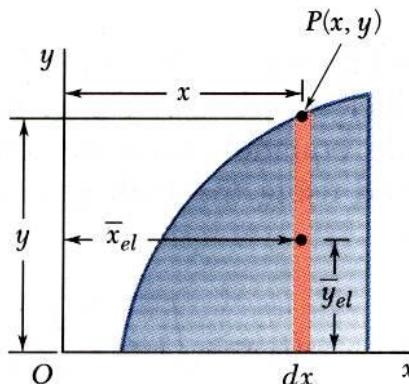
Vector Mechanics for Engineers: Statics

Determination of Centroids by Integration

$$\bar{x}A = \int x dA = \iint x dx dy = \int \bar{x}_{el} dA$$

$$\bar{y}A = \int y dA = \iint y dx dy = \int \bar{y}_{el} dA$$

- Double integration to find the first moment may be avoided by defining dA as a thin rectangle or strip.

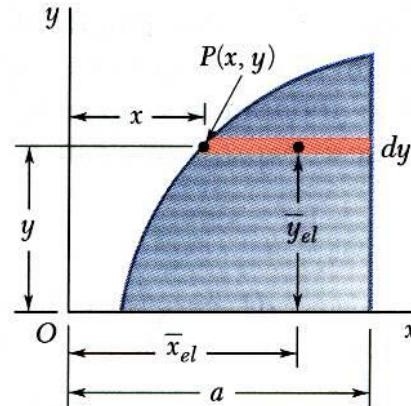


$$\bar{x}A = \int \bar{x}_{el} dA$$

$$= \int x (y dx)$$

$$\bar{y}A = \int \bar{y}_{el} dA$$

$$= \int \frac{y}{2} (y dx)$$

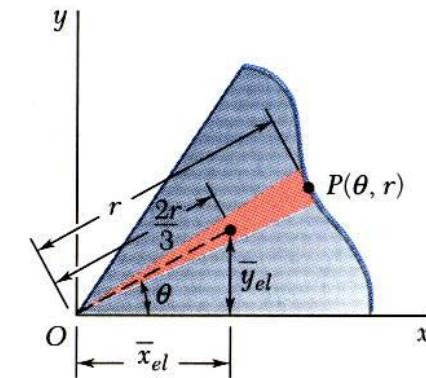


$$\bar{x}A = \int \bar{x}_{el} dA$$

$$= \int \frac{a+x}{2} [(a-x) dy]$$

$$\bar{y}A = \int \bar{y}_{el} dA$$

$$= \int y [(a-x) dy]$$



$$\bar{x}A = \int \bar{x}_{el} dA$$

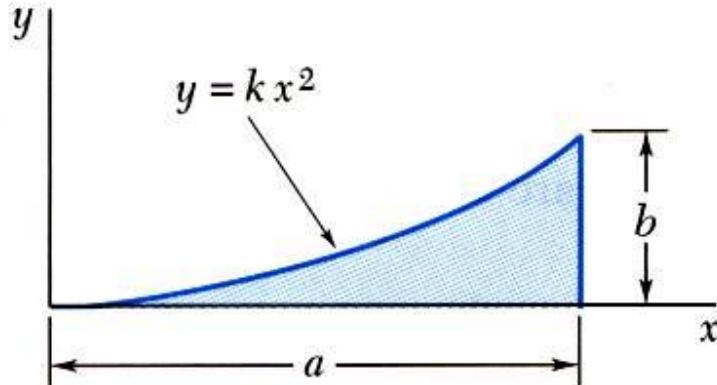
$$= \int \frac{2r}{3} \cos \theta \left(\frac{1}{2} r^2 d\theta \right)$$

$$\bar{y}A = \int \bar{y}_{el} dA$$

$$= \int \frac{2r}{3} \sin \theta \left(\frac{1}{2} r^2 d\theta \right)$$

Vector Mechanics for Engineers: Statics

Sample Problem 5.4



Determine by direct integration the location of the centroid of a parabolic spandrel.

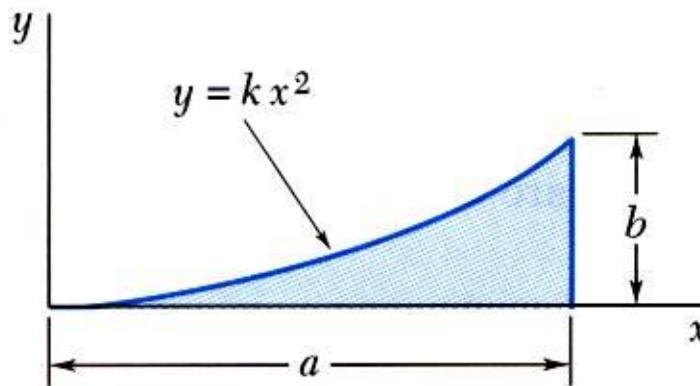
SOLUTION:

- Determine the constant k .
- Evaluate the total area.
- Using either vertical or horizontal strips, perform a single integration to find the first moments.
- Evaluate the centroid coordinates.



Vector Mechanics for Engineers: Statics

Sample Problem 5.4



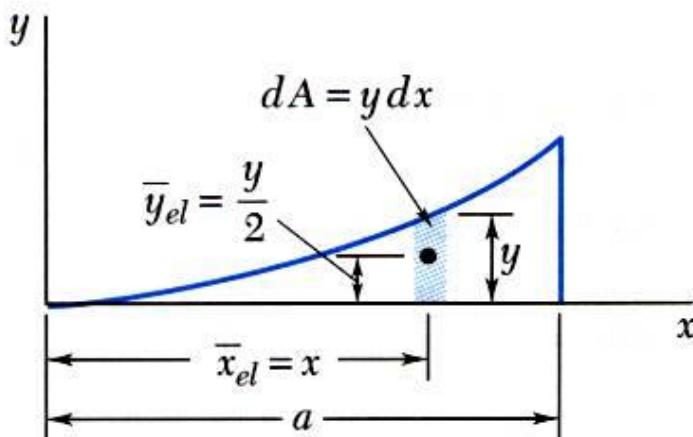
SOLUTION:

- Determine the constant k .

$$y = k x^2$$

$$b = k a^2 \Rightarrow k = \frac{b}{a^2}$$

$$y = \frac{b}{a^2} x^2 \quad \text{or} \quad x = \frac{a}{b^{1/2}} y^{1/2}$$



- Evaluate the total area.

$$A = \int dA$$

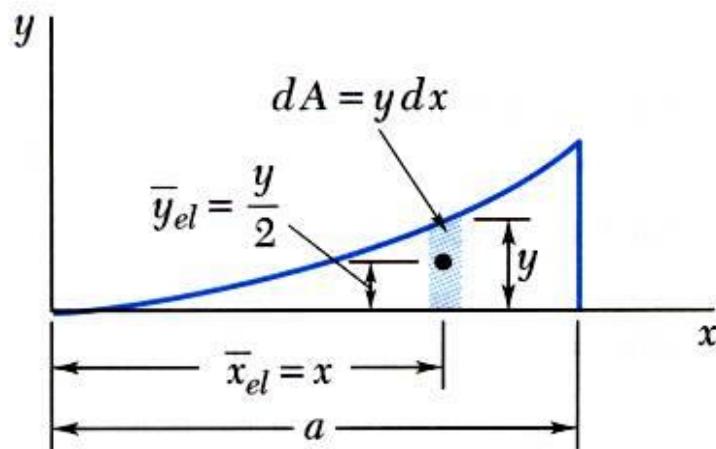
$$= \int y dx = \int_0^a \frac{b}{a^2} x^2 dx = \left[\frac{b}{a^2} \frac{x^3}{3} \right]_0^a$$

$$= \frac{ab}{3}$$

Vector Mechanics for Engineers: Statics

Sample Problem 5.4

- Using vertical strips, perform a single integration to find the first moments.



$$\begin{aligned}Q_y &= \int \bar{x}_{el} dA = \int xy dx = \int_0^a x \left(\frac{b}{a^2} x^2 \right) dx \\&= \left[\frac{b}{a^2} \frac{x^4}{4} \right]_0^a = \frac{a^2 b}{4}\end{aligned}$$

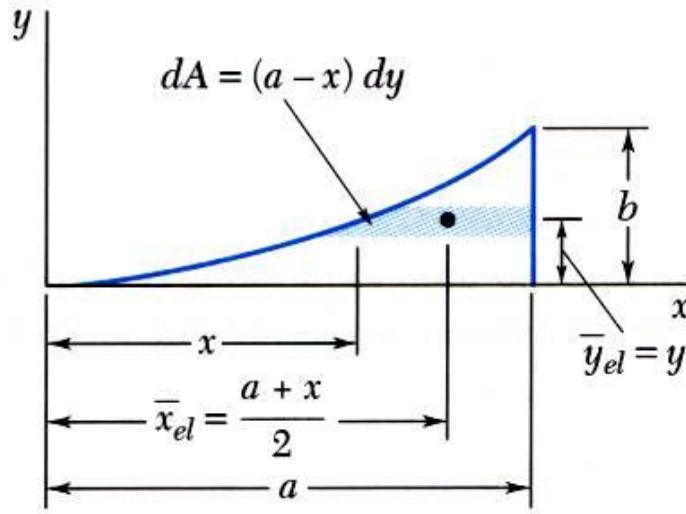
$$\begin{aligned}Q_x &= \int \bar{y}_{el} dA = \int \frac{y}{2} y dx = \int_0^a \frac{1}{2} \left(\frac{b}{a^2} x^2 \right)^2 dx\end{aligned}$$

$$= \left[\frac{b^2}{2a^4} \frac{x^5}{5} \right]_0^a = \frac{ab^2}{10}$$

Vector Mechanics for Engineers: Statics

Sample Problem 5.4

- Or, using horizontal strips, perform a single integration to find the first moments.

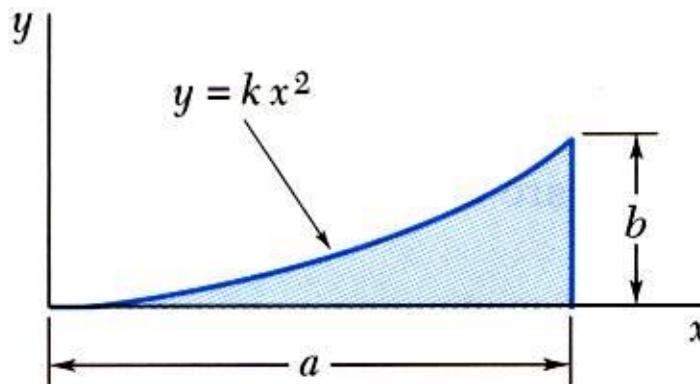


$$\begin{aligned}Q_y &= \int \bar{x}_{el} dA = \int \frac{a+x}{2} (a-x) dy = \int_0^b \frac{a^2 - x^2}{2} dy \\&= \frac{1}{2} \int_0^b \left(a^2 - \frac{a^2}{b} y \right) dy = \frac{a^2 b}{4}\end{aligned}$$

$$\begin{aligned}Q_x &= \int \bar{y}_{el} dA = \int y (a-x) dy = \int y \left(a - \frac{a}{b^{1/2}} y^{1/2} \right) dy \\&= \int_0^b \left(ay - \frac{a}{b^{1/2}} y^{3/2} \right) dy = \frac{ab^2}{10}\end{aligned}$$

Vector Mechanics for Engineers: Statics

Sample Problem 5.4



- Evaluate the centroid coordinates.

$$\bar{x}A = Q_y$$

$$\bar{x} \frac{ab}{3} = \frac{a^2b}{4}$$

$$\boxed{\bar{x} = \frac{3}{4}a}$$

$$\bar{y}A = Q_x$$

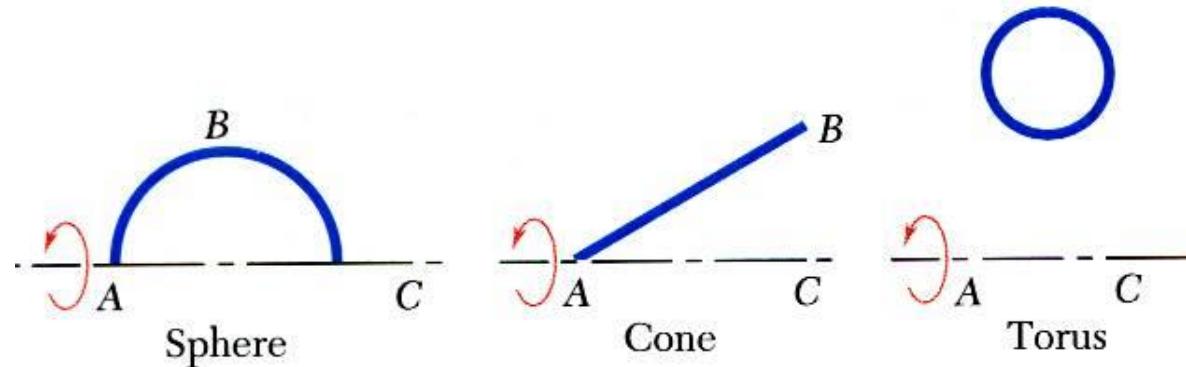
$$\bar{y} \frac{ab}{3} = \frac{ab^2}{10}$$

$$\boxed{\bar{y} = \frac{3}{10}b}$$

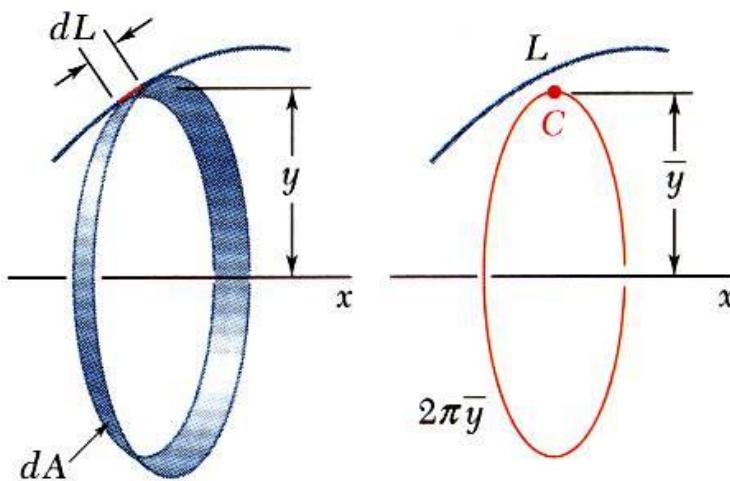


Vector Mechanics for Engineers: Statics

Theorems of Pappus-Guldinus



- Surface of revolution is generated by rotating a plane curve about a fixed axis.

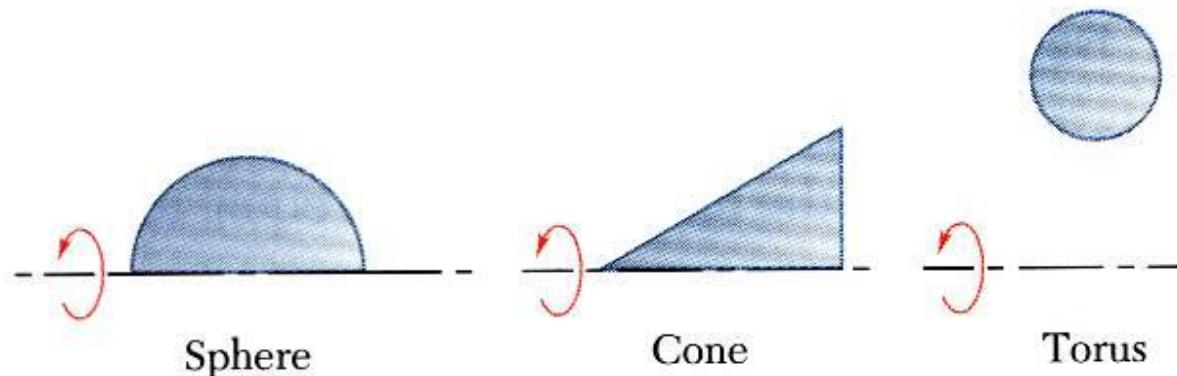


- Area of a surface of revolution is equal to the length of the generating curve times the distance traveled by the centroid through the rotation.

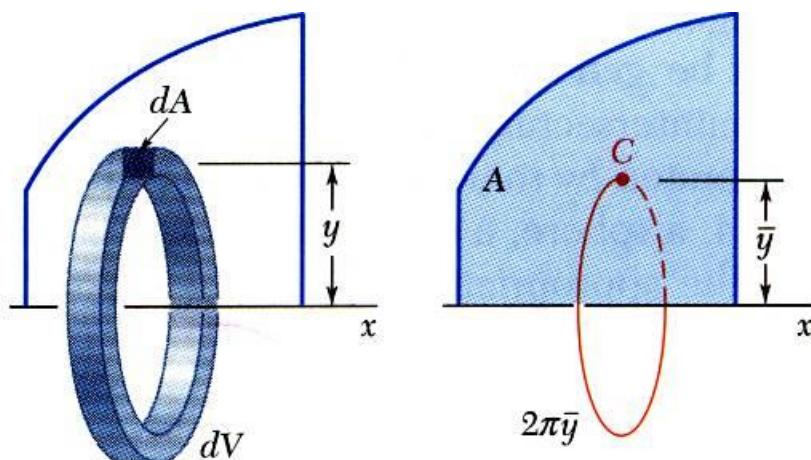
$$A = 2\pi \bar{y} L$$

Vector Mechanics for Engineers: Statics

Theorems of Pappus-Guldinus



- Body of revolution is generated by rotating a plane area about a fixed axis.

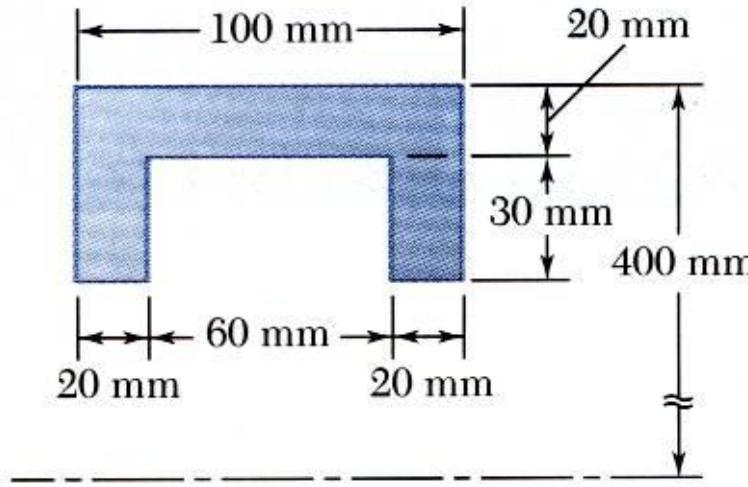


- Volume of a body of revolution is equal to the generating area times the distance traveled by the centroid through the rotation.

$$V = 2\pi \bar{y} A$$

Vector Mechanics for Engineers: Statics

Sample Problem 5.7



SOLUTION:

- Apply the theorem of Pappus-Guldinus to evaluate the volumes or revolution for the rectangular rim section and the inner cutout section.
- Multiply by density and acceleration to get the mass and weight.

The outside diameter of a pulley is 0.8 m, and the cross section of its rim is as shown. Knowing that the pulley is made of steel and that the density of steel is $\rho = 7.85 \times 10^3 \text{ kg/m}^3$ determine the mass and weight of the rim.

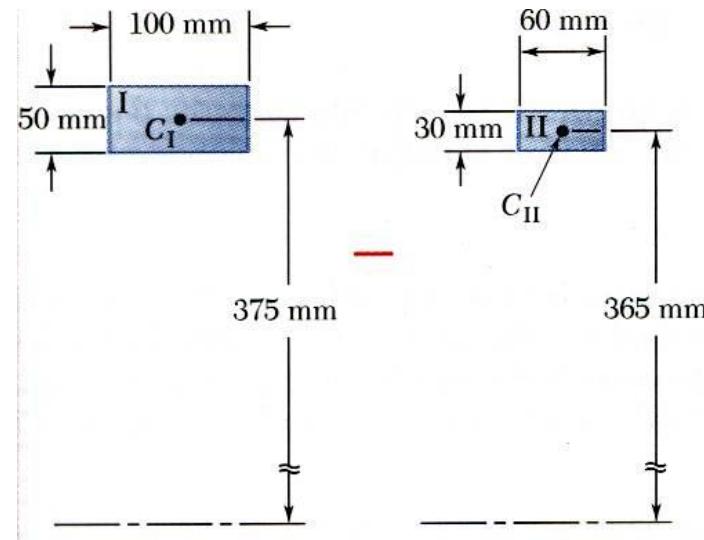


Vector Mechanics for Engineers: Statics

Sample Problem 5.7

SOLUTION:

- Apply the theorem of Pappus-Guldinus to evaluate the volumes of revolution for the rectangular rim section and the inner cutout section.
- Multiply by density and acceleration to get the mass and acceleration.



| | Area, mm ² | \bar{y} , mm | Distance Traveled by C , mm | Volume, mm ³ |
|----|-----------------------|----------------|-------------------------------|-------------------------------------|
| I | +5000 | 375 | $2\pi(375) = 2356$ | $(5000)(2356) = 11.78 \times 10^6$ |
| II | -1800 | 365 | $2\pi(365) = 2293$ | $(-1800)(2293) = -4.13 \times 10^6$ |
| | | | | Volume of rim = 7.65×10^6 |

$$m = \rho V = (7.85 \times 10^3 \text{ kg/m}^3) (7.65 \times 10^6 \text{ mm}^3) \left(10^{-9} \text{ m}^3/\text{mm}^3 \right)$$

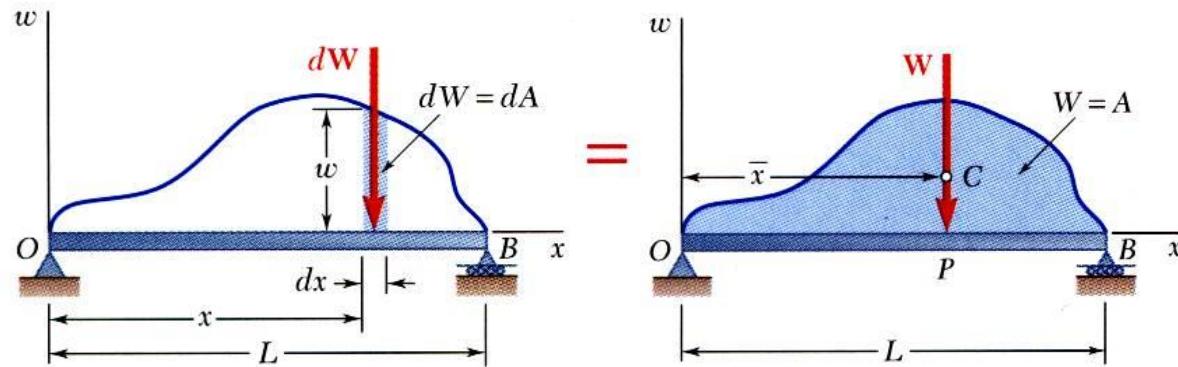
$$W = mg = (60.0 \text{ kg}) (9.81 \text{ m/s}^2)$$

$$m = 60.0 \text{ kg}$$

$$W = 589 \text{ N}$$

Vector Mechanics for Engineers: Statics

Distributed Loads on Beams



$$W = \int_0^L w dx = \int dA = A$$

- A distributed load is represented by plotting the load per unit length, w (N/m). **The total load is equal to the area under the load curve.**

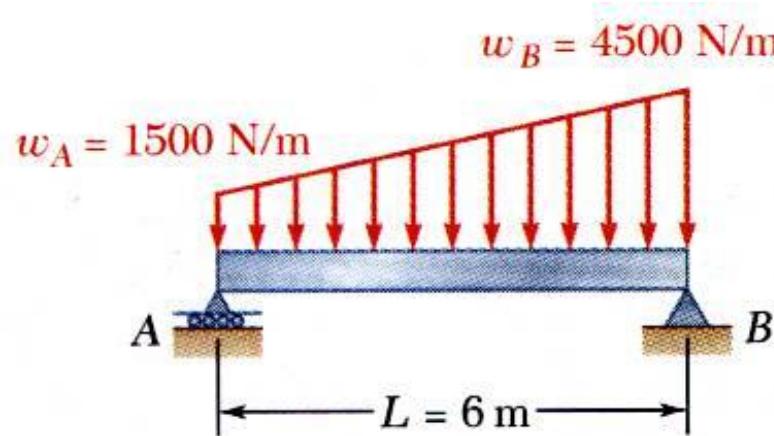
$$(OP)W = \int x dW$$

$$(OP)A = \int x dA = \bar{x}A$$

- A distributed load can be replaced by a concentrated load with a magnitude equal to the area under the load curve and a line of action passing through the area centroid.

Vector Mechanics for Engineers: Statics

Sample Problem 5.9



A beam supports a distributed load as shown. Determine the equivalent concentrated load and the reactions at the supports.

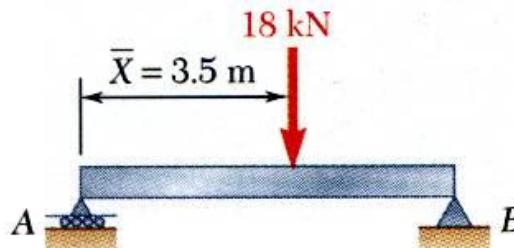
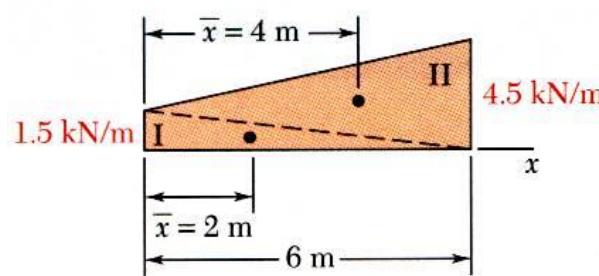
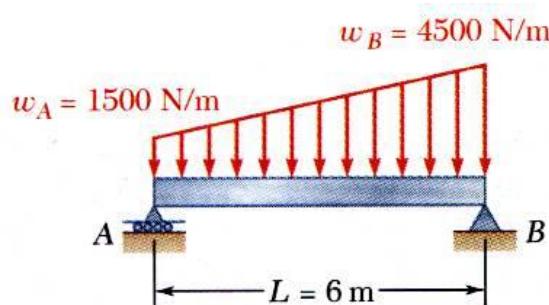
SOLUTION:

- The magnitude of the concentrated load is equal to the total load or the area under the curve.
- The line of action of the concentrated load passes through the centroid of the area under the curve.
- Determine the support reactions by summing moments about the beam ends.



Vector Mechanics for Engineers: Statics

Sample Problem 5.9



SOLUTION:

- The magnitude of the concentrated load is equal to the total load or the area under the curve.

$$F = 18.0 \text{ kN}$$

- The line of action of the concentrated load passes through the centroid of the area under the curve.

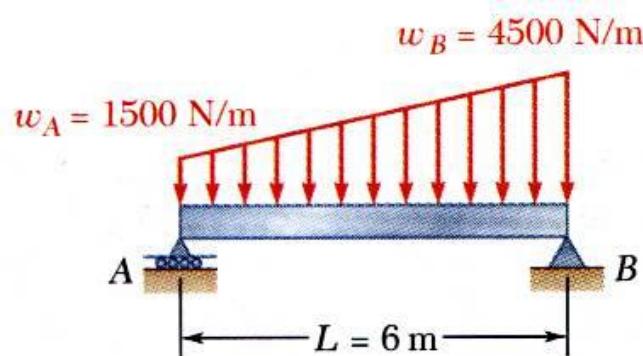
$$\bar{X} = \frac{63 \text{ kN} \cdot \text{m}}{18 \text{ kN}}$$

$$\bar{X} = 3.5 \text{ m}$$

| Component | A, kN | \bar{x}, m | $\bar{x}A, \text{kN} \cdot \text{m}$ |
|-------------------|----------------|---------------------|--------------------------------------|
| Triangle I | 4.5 | 2 | 9 |
| Triangle II | 13.5 | 4 | 54 |
| $\Sigma A = 18.0$ | | | $\Sigma \bar{x}A = 63$ |

Vector Mechanics for Engineers: Statics

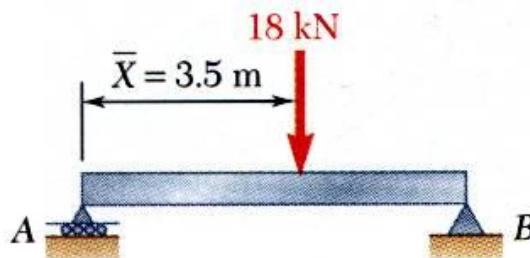
Sample Problem 5.9



- Determine the support reactions by summing moments about the beam ends.

$$\sum M_A = 0: B_y(6 \text{ m}) - (18 \text{ kN})(3.5 \text{ m}) = 0$$

$$B_y = 10.5 \text{ kN}$$

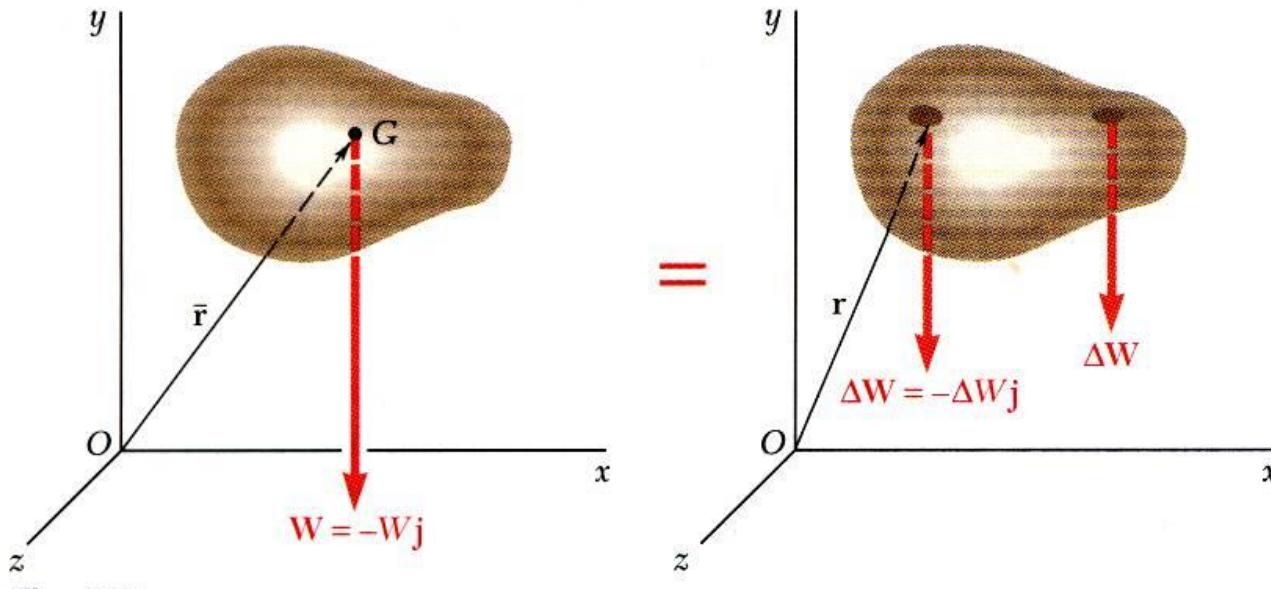


$$\sum M_B = 0: -A_y(6 \text{ m}) + (18 \text{ kN})(6 \text{ m} - 3.5 \text{ m}) = 0$$

$$A_y = 7.5 \text{ kN}$$

Vector Mechanics for Engineers: Statics

Center of Gravity of a 3D Body: Centroid of a Volume



- Center of gravity G

$$-W\vec{j} = \sum(-\Delta w \vec{j})$$

$$\vec{r}_G \times (-W\vec{j}) = \sum[\vec{r} \times (-\Delta w \vec{j})]$$

$$\vec{r}_G W \times (-\vec{j}) = (\sum \vec{r} \Delta w) \times (-\vec{j})$$

$$W = \int dw \quad \vec{r}_G W = \int \vec{r} dw$$

- Results are independent of body orientation,

$$\bar{x}W = \int x dW \quad \bar{y}W = \int y dW \quad \bar{z}W = \int z dW$$

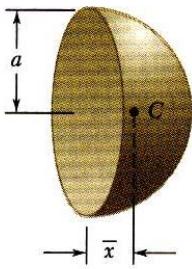
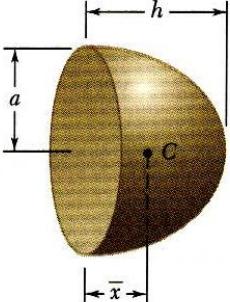
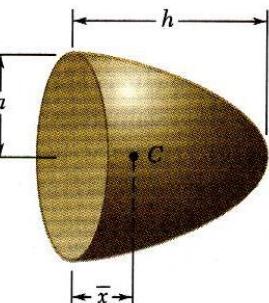
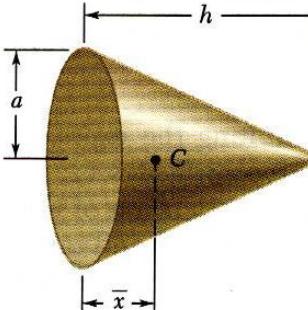
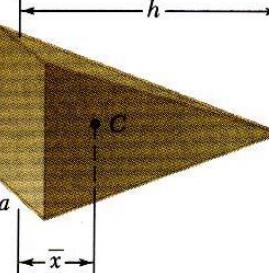
- For homogeneous bodies,

$$W = \gamma V \text{ and } dW = \gamma dV$$

$$\bar{x}V = \int x dV \quad \bar{y}V = \int y dV \quad \bar{z}V = \int z dV$$

Vector Mechanics for Engineers: Statics

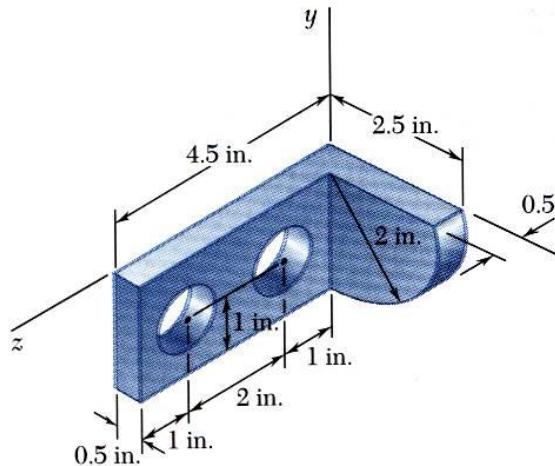
Centroids of Common 3D Shapes

| Shape | | \bar{x} | Volume |
|-----------------------------|---|----------------|------------------------|
| Hemisphere |  | $\frac{3a}{8}$ | $\frac{2}{3}\pi a^3$ |
| Semiellipsoid of revolution |  | $\frac{3h}{8}$ | $\frac{2}{3}\pi a^2 h$ |
| Paraboloid of revolution |  | $\frac{h}{3}$ | $\frac{1}{2}\pi a^2 h$ |
| Cone |  | $\frac{h}{4}$ | $\frac{1}{3}\pi a^2 h$ |
| Pyramid |  | $\frac{h}{4}$ | $\frac{1}{3}abh$ |



Vector Mechanics for Engineers: Statics

Composite 3D Bodies

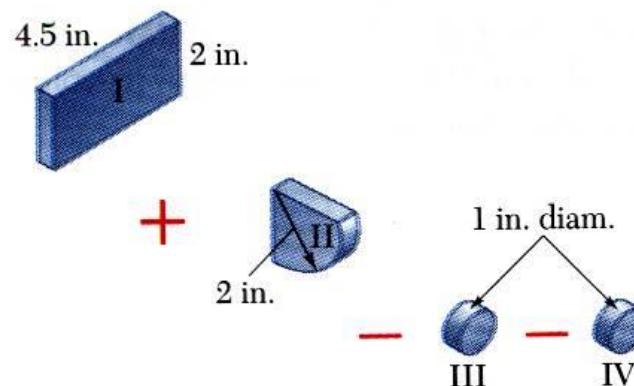


- Moment of the total weight concentrated at the center of gravity G is equal to the sum of the moments of the weights of the component parts.

$$\bar{X} \sum W = \sum \bar{x}W \quad \bar{Y} \sum W = \sum \bar{y}W \quad \bar{Z} \sum W = \sum \bar{z}W$$

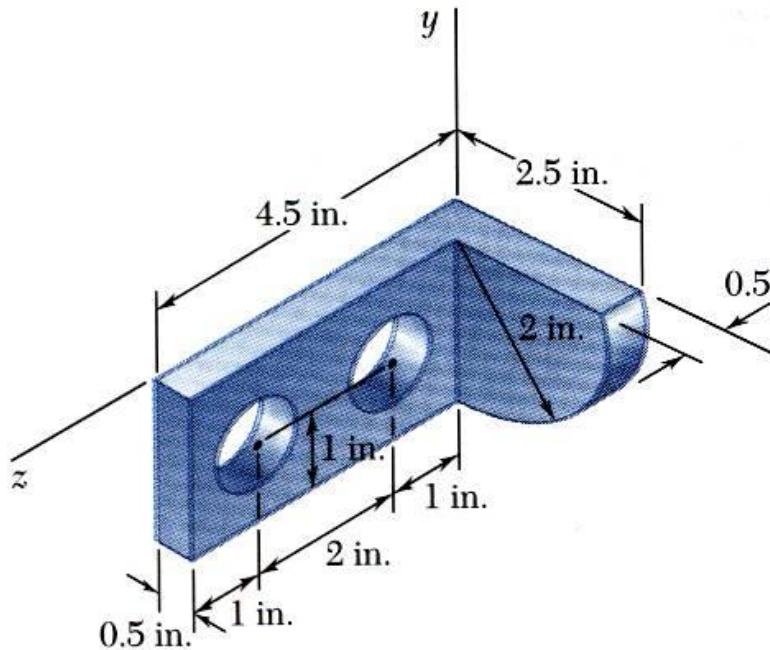
- For homogeneous bodies,

$$\bar{X} \sum V = \sum \bar{x}V \quad \bar{Y} \sum V = \sum \bar{y}V \quad \bar{Z} \sum V = \sum \bar{z}V$$



Vector Mechanics for Engineers: Statics

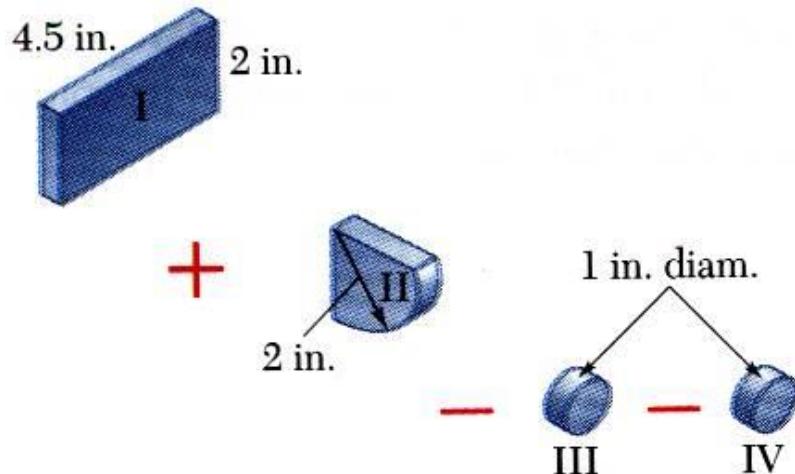
Sample Problem 5.12



Locate the center of gravity of the steel machine element. The diameter of each hole is 1 in.

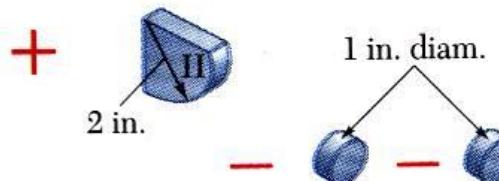
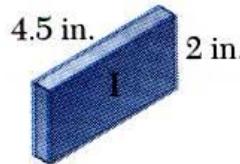
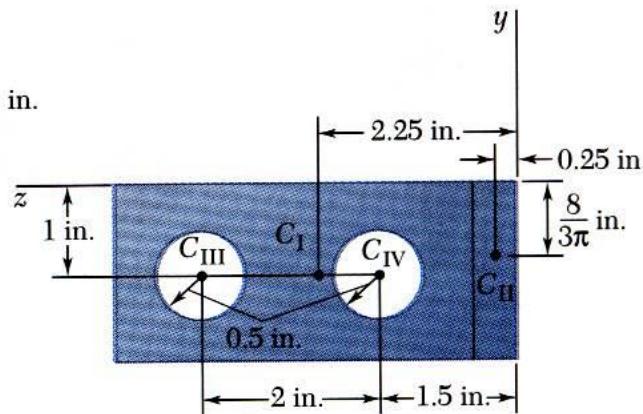
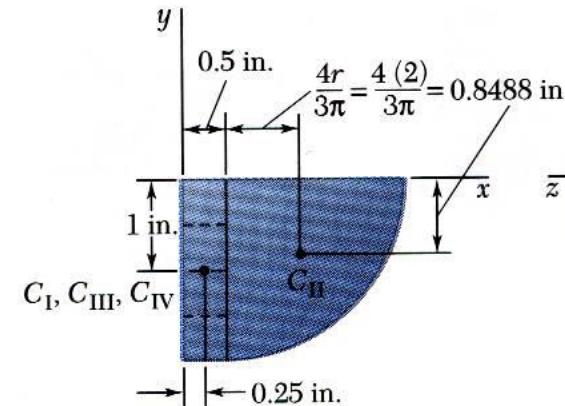
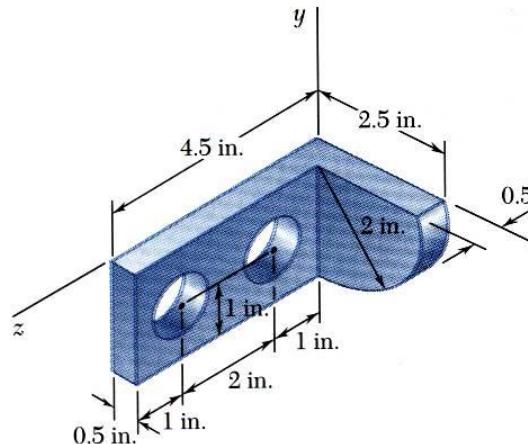
SOLUTION:

- Form the machine element from a rectangular parallelepiped and a quarter cylinder and then subtracting two 1-in. diameter cylinders.



Vector Mechanics for Engineers: Statics

Sample Problem 5.12

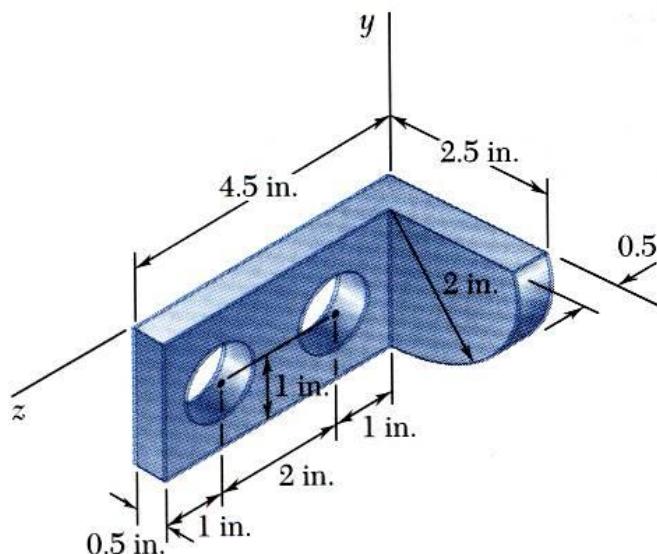


| | $V, \text{ in}^3$ | $\bar{x}, \text{ in.}$ | $\bar{y}, \text{ in.}$ | $\bar{z}, \text{ in.}$ | $\bar{x}V, \text{ in}^4$ | $\bar{y}V, \text{ in}^4$ | $\bar{z}V, \text{ in}^4$ |
|-----|------------------------------------|------------------------|------------------------|------------------------|---------------------------|----------------------------|---------------------------|
| I | $(4.5)(2)(0.5) = 4.5$ | 0.25 | -1 | 2.25 | 1.125 | -4.5 | 10.125 |
| II | $\frac{1}{4}\pi(2)^2(0.5) = 1.571$ | 1.3488 | -0.8488 | 0.25 | 2.119 | -1.333 | 0.393 |
| III | $-\pi(0.5)^2(0.5) = -0.3927$ | 0.25 | -1 | 3.5 | -0.098 | 0.393 | -1.374 |
| IV | $-\pi(0.5)^2(0.5) = -0.3927$ | 0.25 | -1 | 1.5 | -0.098 | 0.393 | -0.589 |
| | $\Sigma V = 5.286$ | | | | $\Sigma \bar{x}V = 3.048$ | $\Sigma \bar{y}V = -5.047$ | $\Sigma \bar{z}V = 8.555$ |

Vector Mechanics for Engineers: Statics

Sample Problem 5.12

| | $V, \text{ in}^3$ | $\bar{x}, \text{ in.}$ | $\bar{y}, \text{ in.}$ | $\bar{z}, \text{ in.}$ | $\bar{x}V, \text{ in}^4$ | $\bar{y}V, \text{ in}^4$ | $\bar{z}V, \text{ in}^4$ |
|-----|------------------------------------|------------------------|------------------------|------------------------|---------------------------|----------------------------|---------------------------|
| I | $(4.5)(2)(0.5) = 4.5$ | 0.25 | -1 | 2.25 | 1.125 | -4.5 | 10.125 |
| II | $\frac{1}{4}\pi(2)^2(0.5) = 1.571$ | 1.3488 | -0.8488 | 0.25 | 2.119 | -1.333 | 0.393 |
| III | $-\pi(0.5)^2(0.5) = -0.3927$ | 0.25 | -1 | 3.5 | -0.098 | 0.393 | -1.374 |
| IV | $-\pi(0.5)^2(0.5) = -0.3927$ | 0.25 | -1 | 1.5 | -0.098 | 0.393 | -0.589 |
| | $\Sigma V = 5.286$ | | | | $\Sigma \bar{x}V = 3.048$ | $\Sigma \bar{y}V = -5.047$ | $\Sigma \bar{z}V = 8.555$ |



$$\bar{X} = \sum \bar{x}V / \sum V = (3.048 \text{ in}^4) / (5.286 \text{ in}^3)$$

$$\bar{X} = 0.577 \text{ in.}$$

$$\bar{Y} = \sum \bar{y}V / \sum V = (-5.047 \text{ in}^4) / (5.286 \text{ in}^3)$$

$$\bar{Y} = -0.955 \text{ in.}$$

$$\bar{Z} = \sum \bar{z}V / \sum V = (8.555 \text{ in}^4) / (5.286 \text{ in}^3)$$

$$\bar{Z} = 1.618 \text{ in.}$$