

ERROR RATE DUE TO NOISE (Probability of Error of Matched Filter)

- Consider a binary PCM system based on polar non return to zero signaling. In this form of signaling, symbol '1' & '0' are represented by positive and negative rectangular pulses with amplitude A for equal duration.
- The channel noise is modelled as additive white Gaussian noise $w(t)$ of zero mean & power spectral density $N_0/2$.

In the signaling interval $0 \leq t \leq T_b$, the received signal is written as,

$$n = \begin{cases} +A+w, & \text{Symbol 1 was sent} \\ -A+w, & \text{Symbol 0 was sent} \end{cases} \quad \dots \rightarrow ①$$

where T_b = bit duration, A = transmitted pulse amplitude

- Given the noisy signal $n(t)$, the receiver is required to make a decision in each signaling interval as to whether the transmitted symbol is a '1' or a '0'.

Figure: Receiver for baseband transmission of binary-Encoder PCM wave using Polar NRZ Signalling

- If the output sample value is exactly equals to threshold value, the receiver may choose it as 1 (or) 0. Here there two possible kinds of errors to be considered.

Symbol 1 is chosen where a 0 was actually transmitted

Symbol 0 is chosen where a 1 was actually transmitted

Symbol '0' was sent

The received signal is expressed as

$$n(t) = -A+w \text{ for } 0 \leq t \leq T_b \quad \dots \rightarrow ②$$

The output of matched filter is expressed as $y = \int_{-\infty}^{T_b} x(t) dt$

$$\Rightarrow y = -A + \frac{1}{T_b} \int_0^{T_b} w(t) dt \quad \text{--- (3)}$$

The above equation (3) represents the sample value of random variable. It is characterized as

The random variable y is Gaussian distributed with a mean of $-A$.

The variance of the random variable y is

$$\sigma_y^2 = E[(y+A)^2] \Rightarrow \sigma_y^2 = \frac{1}{T_b^2} E \left[\int_0^{T_b} \int_0^{T_b} w(t) w(u) dt du \right]$$

$$\Leftrightarrow \sigma_y^2 = \frac{1}{T_b^2} \int_0^{T_b} \int_0^{T_b} E[w(t) w(u)] dt du$$

$$\Rightarrow \sigma_y^2 = \frac{1}{T_b^2} \int_0^{T_b} \int_0^{T_b} R_w(t, u) dt du \quad \text{--- (4)}$$

where $R_w(t, u)$ is the auto correlation function of the white noise $w(t)$.

$$R_w(t, u) = \frac{N_0}{2} \delta(t-u) \quad \text{--- (5)}$$

where $\delta(t-u)$ is the shifted delta function

(3) into (4)

$$\Rightarrow \sigma_y^2 = \frac{1}{T_b^2} \int_0^{T_b} \int_0^{T_b} \frac{N_0}{2} \delta(t-u) dt du$$

~~(3) into (4)~~



$$\Rightarrow \sigma_y^2 = \frac{1}{T_b^2} \frac{N_0}{2} \int_0^{T_b} 1 du \int_0^{T_b} \delta(t-u) dt$$

$$\sigma_y^2 = \frac{1}{T_b^2} \frac{N_0}{2} [u]_0^{T_b} [1]_{t=u}$$

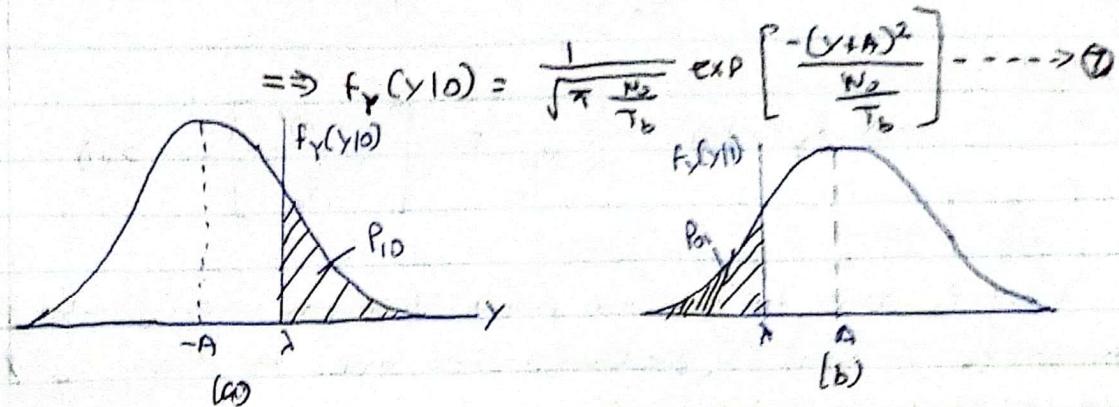
$$\sigma_y^2 = \frac{1}{T_b^2} \frac{N_0}{2} [T_b] = \Rightarrow \sigma_y^2 = \frac{N_0}{2 T_b} \quad \text{--- (6)}$$

We know that, Gaussian density function is

$$f_x(x) = \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{(x-\mu)^2}{2\sigma^2}}$$

Then the conditional probability density function of random variable y where binary '0' is transmitted is

$$f_y(y|0) = \frac{1}{\sqrt{\pi \frac{N_0}{2T_b}}} e^{-\frac{(y-A)^2}{2\frac{N_0}{2T_b}}}$$



- Fig: (a) Pdf of random variable y at matched filter output when '0' is transmitted.
- Fig: (b) Pdf of random variable y at matched filter output when '1' is transmitted.

Let P_{10} denote the conditional probability of error, when symbol 0 was sent. $P_{10} = P(Y > A | \text{symbol 0 was sent})$

$$\begin{aligned} P_{10} &= \int_A^\infty f_y(y|0) dy \Rightarrow P_{10} = \int_A^\infty \frac{1}{\sqrt{\pi \frac{N_0}{2T_b}}} \exp\left[-\frac{(y-A)^2}{\frac{N_0}{2T_b}}\right] dy \\ &\Rightarrow P_{10} = \frac{1}{\sqrt{\pi \frac{N_0}{2T_b}}} \int_A^\infty \exp\left[-\frac{(y-A)^2}{\frac{N_0}{2T_b}}\right] dy \quad \dots \rightarrow ⑧ \end{aligned}$$

Introduce the complementary error function for simplification

of equation ⑧

$$\operatorname{erfc}(u) = \frac{2}{\sqrt{\pi}} \int_u^\infty e^{-z^2} dz \quad \dots \rightarrow ⑨$$

Simplify the equation ⑧, let us take, $z = \frac{y-A}{\sqrt{\frac{N_0}{2T_b}}}$

$$P_{10} = \frac{1}{\sqrt{\pi}} \int_{\frac{A-A}{\sqrt{\frac{N_0}{2T_b}}}}^\infty e^{-z^2} dz \Rightarrow P_{10} = \frac{1}{2} \operatorname{erfc}\left(\frac{A-A}{\sqrt{\frac{N_0}{2T_b}}}\right) \quad \dots \rightarrow ⑩$$

Symbol '1' was sent

The conditional probability density function of random variable 'y' where binary '1' is transmitted is

$$f_Y(y|1) = \frac{1}{\sqrt{2\pi \frac{N_0}{T_b}}} e^{-\frac{(y-A)^2}{2 \frac{N_0}{T_b}}}$$

$$\Rightarrow f_Y(y|1) = \frac{1}{\sqrt{\pi \frac{N_0}{T_b}}} \exp\left[-\frac{(y-A)^2}{\frac{N_0}{T_b}}\right] \rightarrow ①$$

Let P_{01} denote the conditional probability error, when symbol 1 was transmitted. In figure (b), the shaded area under the curve $f_Y(y|1)$ over the limits $-\infty$ to λ gives P_{01} .

$$P_{01} = P(Y < \lambda | \text{symbol 1 was sent})$$

$$P_{01} = \int_{-\infty}^{\lambda} f_Y(y|1) dy \Rightarrow P_{01} = \int_{-\infty}^{\lambda} \frac{1}{\sqrt{\pi \frac{N_0}{T_b}}} \exp\left[-\frac{(y-A)^2}{\frac{N_0}{T_b}}\right] dy$$
$$\Rightarrow P_{01} \approx \frac{1}{\sqrt{\pi \frac{N_0}{T_b}}} \int_{-\infty}^{\lambda} \exp\left[-\frac{(y-A)^2}{\frac{N_0}{T_b}}\right] dy \rightarrow ②$$

For the simplification of Eq. ②, we take $z = \frac{A-y}{\sqrt{\frac{N_0}{T_b}}}$

Interchanging the limits,

$$P_{01} = \frac{1}{\sqrt{\pi}} \int_{\frac{A-\lambda}{\sqrt{\frac{N_0}{T_b}}}}^{\infty} \exp(-z^2) dz$$

Using error function expression, the above equation is written as

$$\Rightarrow P_{01} = \frac{1}{2} \operatorname{erfc}\left(\frac{A-\lambda}{\sqrt{\frac{N_0}{T_b}}}\right) \rightarrow ③$$

Therefore the average probability of symbol errors, P_E is

$$P_E = P_0 P_{10} + P_1 P_{01}$$

$$P_E = \frac{P_0}{2} \operatorname{erfc}\left(\frac{A+\lambda}{\sqrt{\frac{N_0}{T_b}}}\right) + \frac{P_1}{2} \operatorname{erfc}\left(\frac{A-\lambda}{\sqrt{\frac{N_0}{T_b}}}\right)$$

If symbols 0 & 1 are equiprobable, then $P_0 = P_1 = \frac{1}{2}$

Take the optimum value of threshold is equal to zero. i.e., $\lambda_{opt} = 0$

$$P_E = \frac{1/2}{2} \operatorname{erfc}\left(\frac{A+0}{\sqrt{\frac{N_0}{T_b}}}\right) + \frac{1/2}{2} \operatorname{erfc}\left(\frac{A-0}{\sqrt{\frac{N_0}{T_b}}}\right)$$

$$P_E = \frac{1}{4} \operatorname{erfc}\left(-\frac{A}{\sqrt{\frac{N_0}{T_b}}}\right) + \frac{1}{4} \operatorname{erfc}\left[\frac{A}{\sqrt{\frac{N_0}{T_b}}}\right]$$

$$\Rightarrow P_E = \frac{1}{2} \operatorname{erfc}\left[\frac{A}{\sqrt{\frac{N_0}{T_b}}}\right] \quad \dots \rightarrow (14)$$

The energy of transmitted signal, E_b is $E_b = A^2 T_b$

$$\Rightarrow A = \sqrt{\frac{E_b}{T_b}}$$

$A \rightarrow (14)$

$$P_E = \frac{1}{2} \operatorname{erfc}\left[\frac{\sqrt{E_b/T_b}}{\sqrt{N_0/T_b}}\right]$$

$$\Rightarrow P_E = \frac{1}{2} \operatorname{erfc}\left[\sqrt{\frac{E_b}{N_0}}\right]$$

Where, E_b is transmitted signal energy per bit and N_0 is the noise spectral density

Nyquist's Criterion for distortionless Baseband binary transmission

• We know that, $y(t_i) = a_i + \sum_{k=-\infty}^{\infty} a_k P[(i-k) T_b] + h(t_i)$

• **Time domain criterion:** From the above equation, we know that the second term (summation) must be zero to eliminate effect of ISI. This is possible if the received pulse $p(t)$ is controlled such that,

$$P[(i-k) T_b] = \begin{cases} 1 & \text{for } i=k \\ 0 & \text{for } i \neq k \end{cases} \quad \text{--- (1)}$$

• If $p(t)$ satisfies the above condition, then we get a signal which is free from ISI. i.e., $y(t_i) = a_i$ for all i .

Frequency domain criterion: Let $p(n T_b)$ represent the impulses at which $p(t)$ is sampled for decision. These samples are taken at the rate of T_b .

• Fourier spectrum of these impulses is given as

$$P_S(f) = f_b \sum_{n=-\infty}^{\infty} P(f - nf_b) \quad \text{--- (2)}$$

• Where, f_b is bit rate in bits per second (b/s)

$P_S(f)$ Fourier transform of infinite periodic sequence of delta functions of period T_b .

The time domain representation of pulse signal $P_S(f)$ is

$$P_S(t) = \sum_{n=-\infty}^{\infty} p(n T_b) \delta(t - n T_b) \quad \text{--- (3)}$$

• The Fourier transform of $P_S(f)$ is

$$P_S(f) = \int_{-\infty}^{\infty} P_S(t) e^{-j2\pi f t} dt$$

$$\Rightarrow P_S(f) = \int_{-\infty}^{\infty} \sum_{n=-\infty}^{\infty} p(n T_b) \delta(t - n T_b) e^{-j2\pi f t} dt$$

Let the integer, $n = i - k$

$$P_S(f) = \int_{-\infty}^{\infty} \sum_{k=-\infty}^{\infty} P((i-k)T_b) \delta(t - (i-k)T_b) e^{-j2\pi ft} dt$$

- Now let us apply the condition of equation (1) to above equation

$$\text{By } P_S(f) = \begin{cases} \int_{-\infty}^{\infty} \sum_{k=-\infty}^{\infty} P(0) \delta(t) e^{-j2\pi ft} dt & \text{for } i=k \\ \int_{-\infty}^{\infty} \sum_{k=-\infty}^{\infty} 0 \delta(t) e^{-j2\pi ft} dt & \text{for } i \neq k \end{cases}$$

Therefore,

$$P_S(f) = \int_{-\infty}^{\infty} P(0) \delta(t) e^{-j2\pi ft} dt \quad \text{for } i=k$$

$$P_S(f) = P(0) \int_{-\infty}^{\infty} \delta(t) e^{-j2\pi ft} dt$$

Using Shifting Property of delta function,

$$P_S(f) = P(0) [e^{-j2\pi ft}] \text{ at, } t=0 \text{ for } i=k$$

$$\Rightarrow P_S(f) = P(0) \Rightarrow P_S(f) = 1$$

Hence $\sigma(f)$ becomes,

$$1 = f_b \sum_{n=-\infty}^{\infty} P(f-nf_b) \Rightarrow \sum_{n=-\infty}^{\infty} P(f-nf_b) = \frac{1}{f_b}$$

$$\Rightarrow \sum_{n=-\infty}^{\infty} P(f-nf_b) = T_b \rightarrow ④$$

In frequency function,

Above equation is called Nyquist Pulse Shaping criterion for baseband transmission.

Raised Cosine Spectrum

Ideal Nyquist Channel

The simplest way of satisfying

$$\sum_{n=-\infty}^{\infty} P(f - nR_b) = T_b \quad (\text{or}) \quad \sum_{n=-\infty}^{\infty} P(f - nR_b) < T_b \rightarrow \text{①}$$

For now, the L.H.S corresponds to $P(f)$ and it represents a frequency function with the narrowest band which satisfies equation ①.

The range of frequencies for $P(f)$ will extend from $-W$ to W ($-R_b$ to R_b) where W or B_b corresponds to half the bit rate.

$$\text{Hence, } W = \frac{f_b}{2} \text{ (or) } \frac{R_b}{2}.$$

This equation is to specify the frequency function $P(f)$ to be in the form of a rectangular function, it is shown as

$$P(f) = \begin{cases} \frac{1}{2W} & ; -W < f < W \\ 0 & ; |f| > W \end{cases}$$

$$P(f) = \frac{1}{2W} \operatorname{rect}\left(\frac{f}{2W}\right) \rightarrow \text{②}$$

The overall system bandwidth ' W ' is defined by,

$$W = \frac{R_b}{2} = \frac{1}{2T_b} \rightarrow \text{③}$$

The signal that produces zero ISI can be obtained by taking the IFT of $P(f)$.

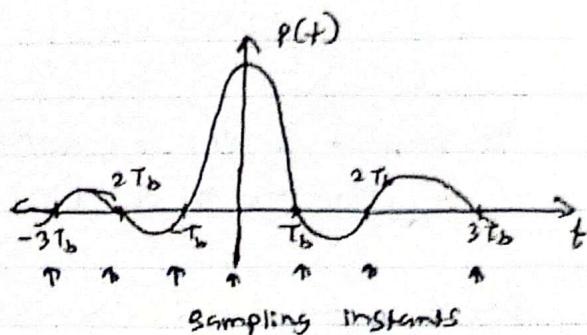
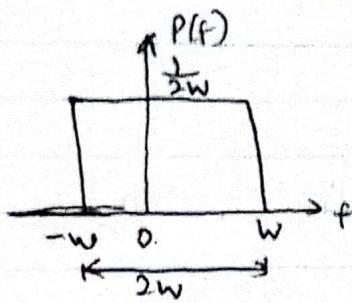
This means that we have,

$$P(t) = F^{-1}[P(f)] \Rightarrow p(t) = F^{-1}\left[\frac{1}{2W} \operatorname{rect}\left(\frac{f}{2W}\right)\right]$$

$$\Rightarrow p(t) = \operatorname{sinc}(2\pi Wt) \text{ or or } p(t) = \frac{\sin(2\pi Wt)}{2\pi Wt} \rightarrow \text{④}$$

The ideal base band data transmission system described by equation ④ in frequency domain and equation ④ in time domain is called the

Ideal Nyquist channel.



(a) Graphical representation of $P(f)$

(b) Time-domain representation

Advantages of using the Sinc Pulse:

- Bandwidth requirement (of the channel) is reduced.
- ISI is reduced to zero.

Possible Difficulties: This ideal Nyquist channel have two practical difficulties.

- The $P(f)$ is plot from $-W$ to W & zero elsewhere.

This is physically unimplementable because of the abrupt transitions at the edges $\pm W$.

Raised cosine channels (2) Raised cosine spectrum

We know that,

$$\sum_{n=-\infty}^{\infty} P(f-nf_b) = T_b \quad (or) \quad \sum_{n=-\infty}^{\infty} P(f-nR_b) = T_b = \frac{1}{R_b} = \frac{1}{f_b}$$

$$\dots + P(f+3R_b) + P(f+2R_b) + P(f+R_b) + P(f) + P(f-R_b) \\ + P(f-2R_b) + P(f-3R_b) \dots = \frac{1}{R_b} = T_b$$

- But, $W = \frac{R_b}{2} \Rightarrow R_b = 2W$

$$\dots + P(f+6W) + P(f+4W) + P(f+2W) + P(f) + P(f-2W) + P(f-4W) \\ + P(f-6W) + \dots = \frac{1}{2W}$$

$$P(f+2W) + P(f) + P(f-2W) = \frac{1}{2W} ; -W \leq f \leq W \quad (1)$$

- Raised cosine spectrum consists of a flat portion and a roll off portion. The raised cosine spectrum is expressed mathematically as

$$P(f) = \begin{cases} \frac{1}{2W} ; & \text{(flat portion)} \\ \frac{1}{4W} \left\{ 1 - \sin \left[\frac{\pi(2|f|-w)}{2w-2f_1} \right] \right\} ; & |f| \leq f_1 \leq 2W-f_1 \\ 0 ; & |f| \geq 2W-f_1 \end{cases}$$

- The frequency parameter f_1 & bandwidth W are related by

$$\alpha = 1 - \frac{f_1}{W} \quad (3)$$

- The parameter α is called the roll off factor, it indicates excess bandwidth over the ideal solution W .

- The transmission bandwidth B_T , is defined by

$$B_T = 2W - f_1 \Rightarrow B_T = W(1+\alpha) \quad (4)$$

- The normalized frequency response of raised cosine function is obtained by multiplying $P(f)$ by $2W$ and it is plotted in figure (a), for different values of α . The corresponding time response $p(t)$ is shown in figure (b).

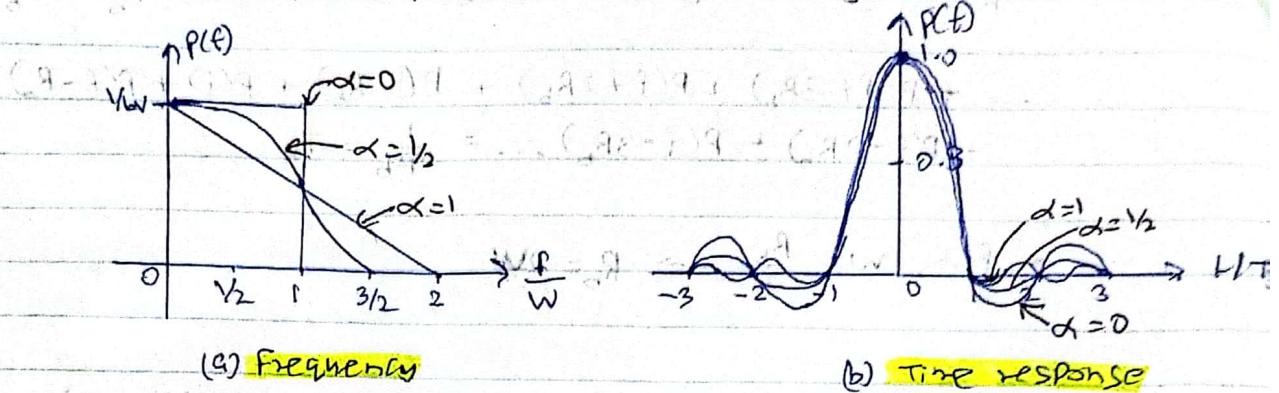


Fig. Responses for different roll-off factors, α

- a) For $\alpha = 0.5$ and 1 , the characteristics of $p(t)$ changes gradually with respect to frequency. Hence, it is easier to realize this characteristics practically. The time response $p(t)$ is the I.F.T. of $P(f)$ i.e., $p(t) = \text{sinc}(2\pi Wt) \left[\frac{\cos(2\pi Wt)}{1 - (\frac{t}{T_b})^2} \right]$ — (5)
- b) The time response has a sinc shape and all the sinc function pass through zero at $t = \pm T_b, \pm 2T_b, \dots$

Effects of Gaussian Noise:-

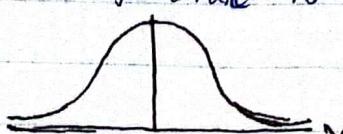
Noise \rightarrow causes error

- Error rate \rightarrow depend on signal & noise amplitude & characteristics of noise

- Noise of large amplitude spike will introduce error in the detected signals

It is assumed to be gaussian

e.g. Gaussian noise generated to a resistor



$$\nabla \nabla \Rightarrow \text{PDF} \downarrow$$

$$M=0 \\ \max V=0$$

Error Function

$$\text{erf}(y) = \frac{2}{\sqrt{\pi}} \int_0^y e^{-z^2} dz \quad 0 \leq \text{erf} \leq 1$$

$\Rightarrow \frac{2}{\sqrt{\pi}} f(y)$

$$e^y = 1 + \frac{y}{1} + \frac{y^2}{2!} + \frac{y^3}{3!}$$

$$\begin{aligned} & \frac{2}{\sqrt{\pi}} \int_0^y \left[1 + \frac{-z^2}{1} + \frac{(-z^2)^2}{2!} + \frac{(-z^2)^3}{3!} + \dots \right] dz \\ &= \frac{2}{\sqrt{\pi}} \left[y - \frac{z^3}{3 \cdot 1!} + \frac{z^5}{5 \cdot 2!} - \frac{z^7}{7 \cdot 3!} + \dots \right]_0^y \end{aligned}$$

$$\text{erf}(y) = \frac{2}{\sqrt{\pi}} \left[y - \frac{y^3}{3 \cdot 1!} + \frac{y^5}{5 \cdot 2!} - \frac{y^7}{7 \cdot 3!} + \dots \right]$$

$$\begin{aligned} \text{erf}(\infty) &= \frac{2}{\sqrt{\pi}} \int_0^\infty e^{-z^2} dz & \int_0^\infty e^{-z^2} dz \\ &= \frac{2}{\sqrt{\pi}} \times \frac{\sqrt{\pi}}{2} = 1 &= \frac{\sqrt{\pi}}{2} \end{aligned}$$

$$\text{erf}(\infty) = 1$$

$$y=0 \Rightarrow \text{erf}(y)=0$$

$$\text{erf}(z) = \frac{2}{\sqrt{\pi}} \int_0^z e^{-t^2} dt$$

Symmetry Property: $\text{erf}(y) = -\text{erf}(-y)$

Complementary error function :-

$$\text{erfc}(y) = 1 - \text{erf}(y) = \frac{2}{\sqrt{\pi}} \int_y^\infty e^{-z^2} dz$$

$$y \uparrow \Rightarrow \text{erfc}(y) \downarrow$$

Decreasing function of y