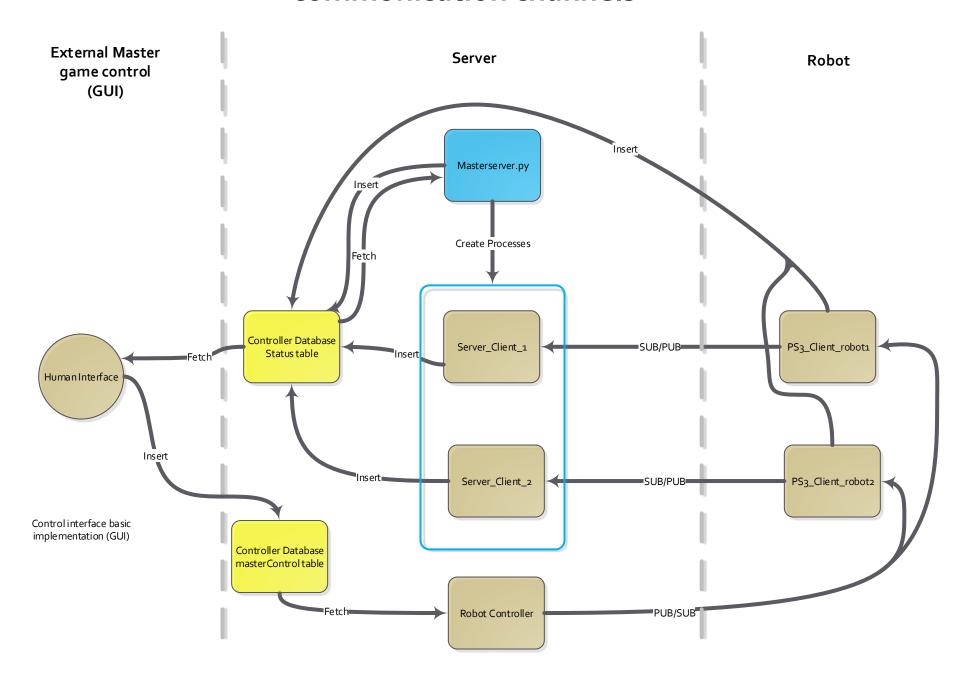
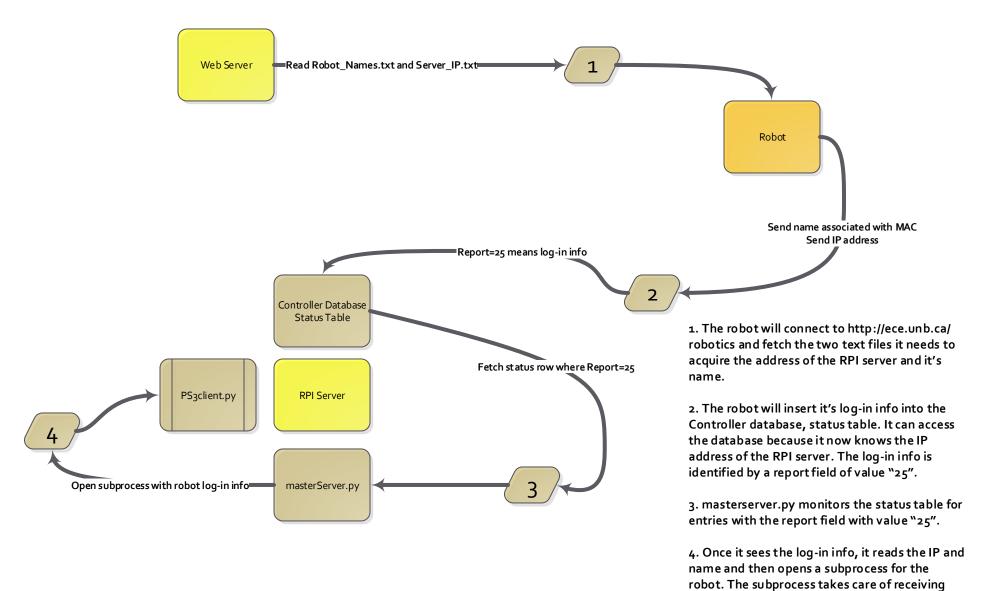
## File structure and communication channels



## **Log-in Process**



data from the robot and updating the status table accordingly. Once the log-in info is read, the masterserver.py will change the value to report = "2" to prevent creating multiple

processes per robot.