Project 2 MLSec

Universal adversarial attack against three models

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Outline

- Problem and Requirements
- Choosing Models from RobustBench
- Theorethical Approach
- Combining the Models
- Generation of Adversarial Examples
- Results and Transferability
- Challenges and Conclusion

Problem and Requirements

- 1. Generate universal adversarial examples
 - Choose 3 models from RobustBench
 - Using the CIFAR10 dataset and the L-inf-norm
 - Untargeted
 - Universal for all three models at the same time
- 2. Evaluated transferability
 - 7 other models
 - Using the same adverserial examples

Choosing Models from RobustBench

Aspects

- Less adversarial training
- Non robust pretraining (e.g. Reinforcement Learning)
- Are trained with weak or outdated robustness techniques

10 Models

- Hendrycks2019Using
- Chen2020Adversarial
- Wong2020Fast
- Engstrom2019Robustness
- o Ding2020MMA
- Rice2020Overfitting
- Huang2020Self
- Sehwag2021Proxy_R18
- Rebuffi2021Fixing_70_16_cutmix_extra
- o 3. Rade2021Helper_extra

Theoretical Approaches – PGD Attack

Constraint: Maximum-confidence

$$\min_{\|\delta\| \le \epsilon} L(x + \delta, y; \theta)$$

Projected Gradient Descent (PGD)

$$x^* = x + \epsilon \operatorname{sign}(\nabla L(x, y, \theta))$$

$$\max_{\|\delta\|_{\infty}} L(x + \delta, y, \theta)$$

$$\delta^* = \epsilon \operatorname{sign}(\nabla L)$$

Combining the models

- Method1: Averaging of model outputs
 - Computationally expensive
 - Stable and deterministic

$$\frac{1}{M} \sum_{i=1}^{M} f_i(x)$$

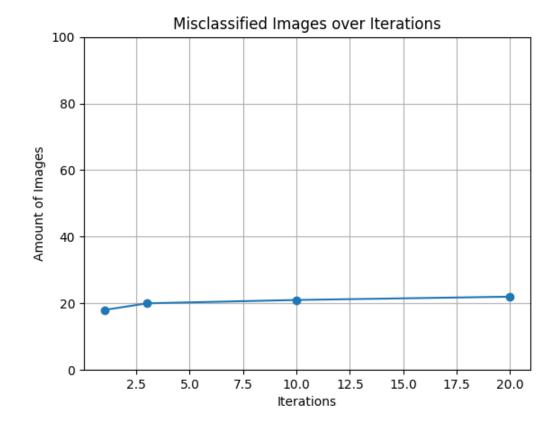
- Method2: Taking the most frequent prediction (Not tracked by us)
 - Simple and efficient method
 - Deterministic
- Method3: Random model selection (uniform distribution)
 - The attack generalizes better
 - Computationally efficient
 - Non-deterministic $F(x) = f_j(x)$, where $j \sim \text{Uniform}(\{1, 2, ..., M\})$

Generation of Adversarial Examples

- Using the PGD attack from SecML
- Using DLR-loss (Difference of Logits Ratio) instead of crossentropy-loss
- Hyperparameter
 - 1. Epsilon = 8/255: Default value from RobustBench
 - 2. N = 100: Number of PGD-iterations
 - 3. Alpha = Eps/N or 1/255: Amount of perturbation at each step (how aggressive)
 - 4. L-inf Norm: Limits the maximum change applied to any pixel

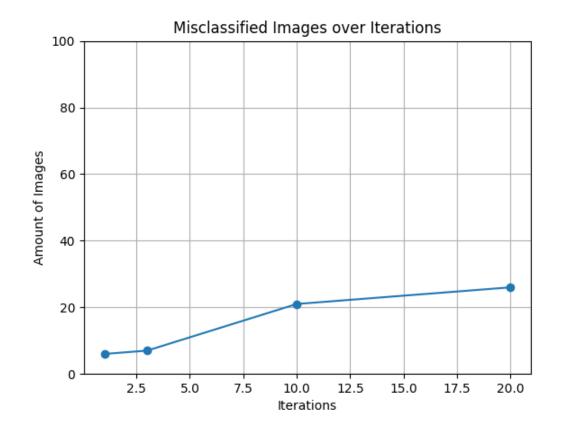
Results – Misclassified Images (Epsilon/N)

- Amount of misclassified images over all 3 models (epsilon/N)
 - 1 Iteration = 18/100 Images
 - 3 Iterations = 20/100 Images
 - 10 Iterations = 21/100 Images
 - 20 Iterations = 22/100 Image

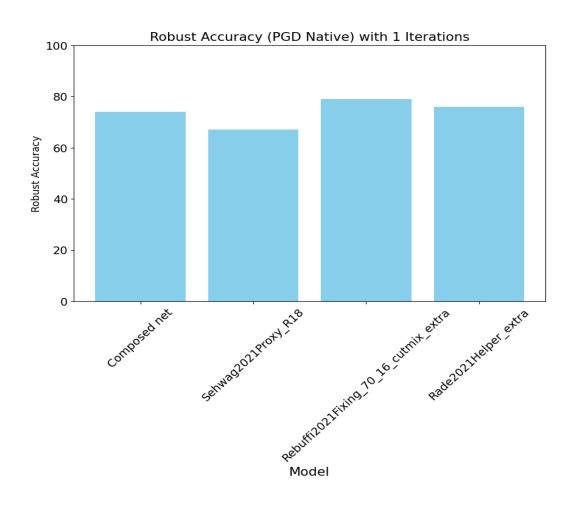


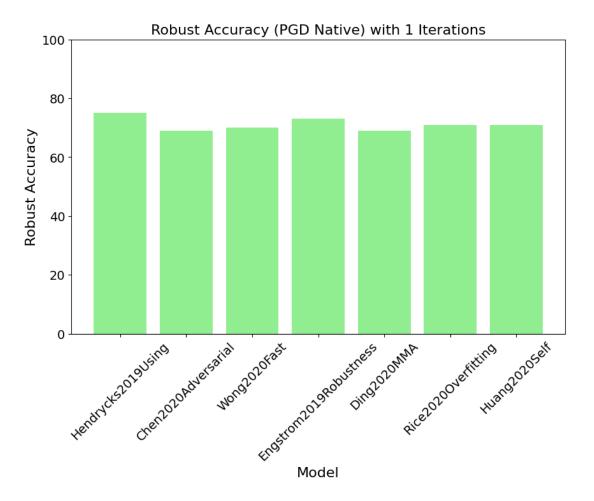
Results – Misclassified Images (1/255)

- Amount of misclassified images over all 3 models (epsilon/N)
 - 1 Iteration = 6/100 Images
 - 3 Iterations = 7/100 Images
 - 10 Iterations = 21/100 Images
 - 100 Iterations = 26/100 Images

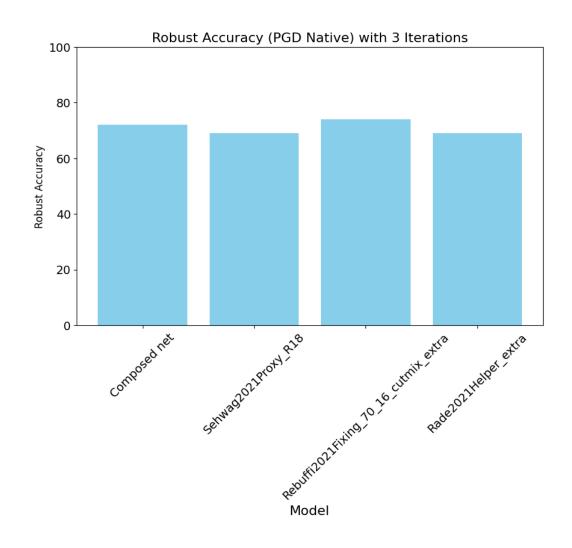


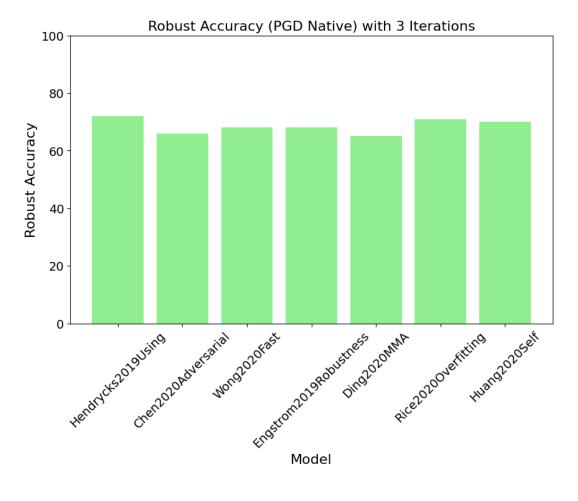
Results - Transferability (N=1, Alpha=Eps/N)



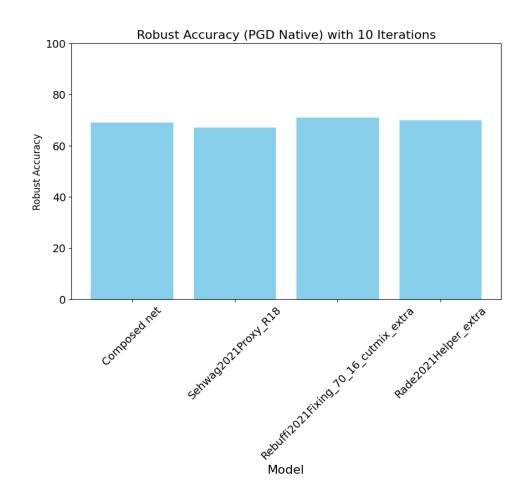


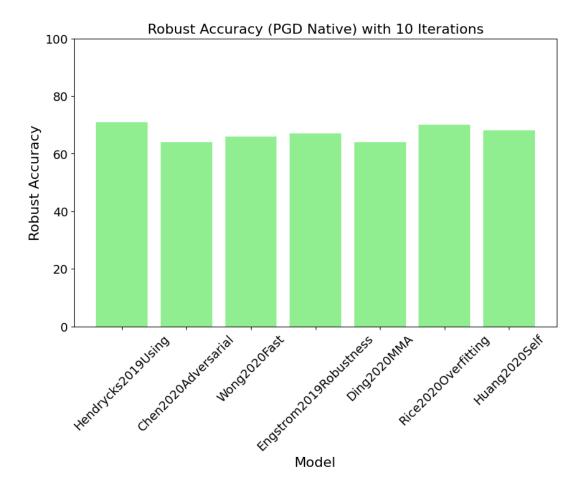
Results – Transferability (N=3, Alpha=Eps/N)



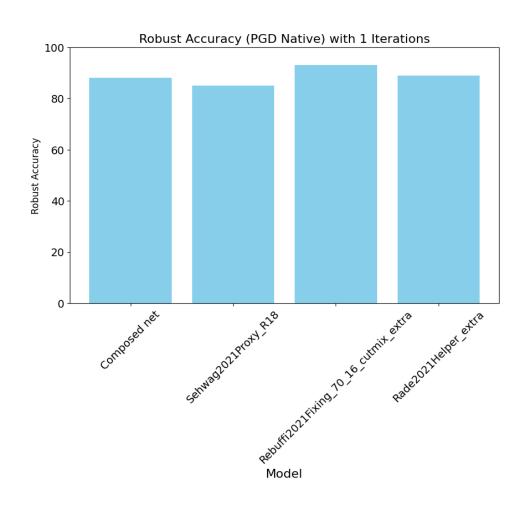


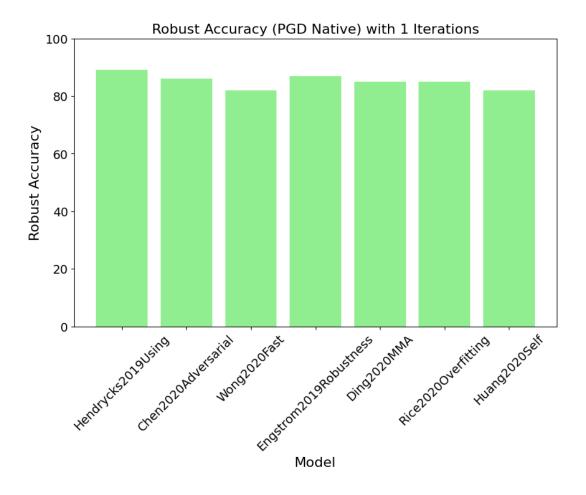
Results - Transferability (N=10, Alpha=Eps/N)



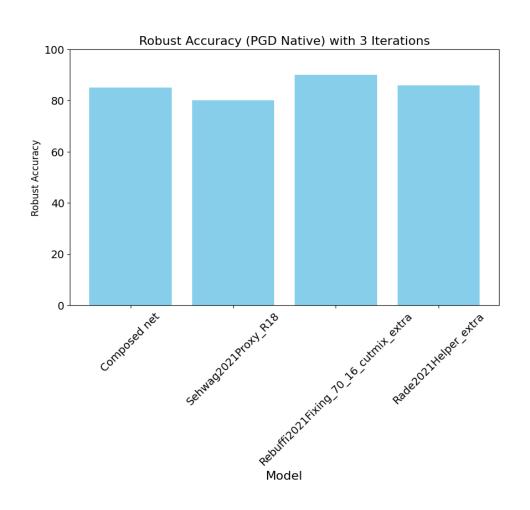


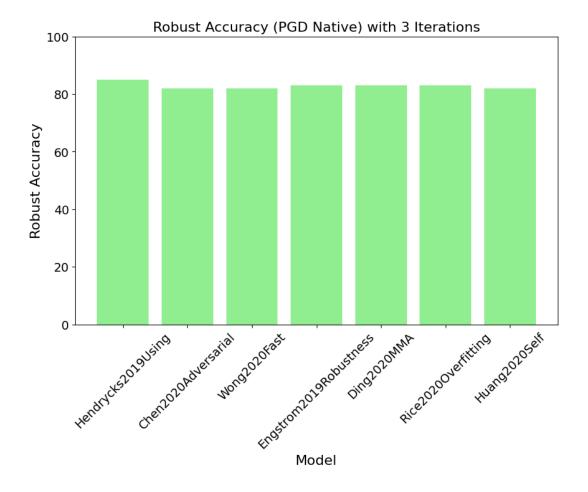
Results - Transferability (N=1, Alpha=1/255)



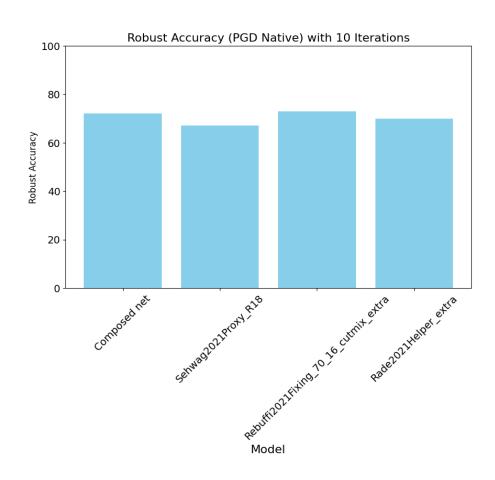


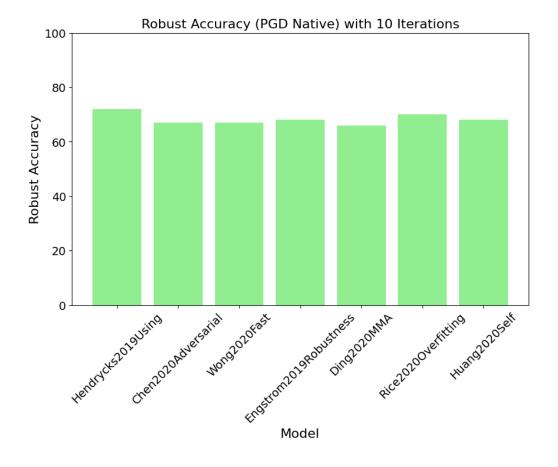
Results - Transferability (N=3, Alpha=1/255)



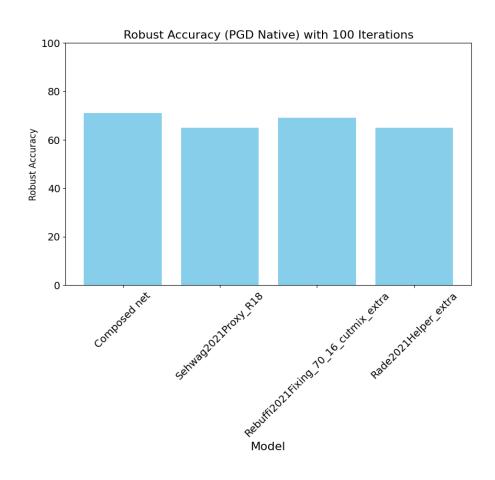


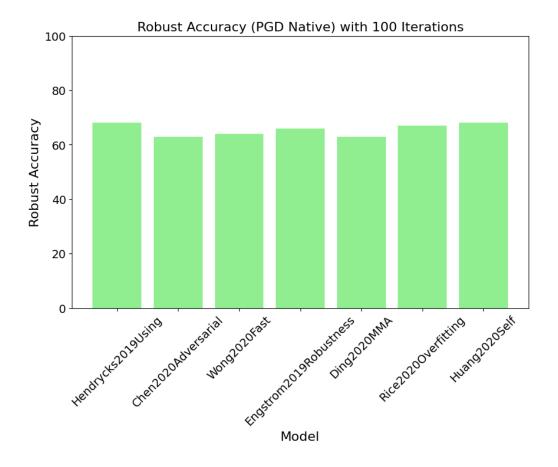
Results - Transferability (N=10, Alpha=1/255)





Results - Transferability (N=100, Alph=1/255)





Challenges and Conclusion

- With combination of 3 models the attack generalizes very good
- Finding the optimal hyperparameters is hard
 - Long runtime of the attack
 - Depending on concrete conditions (i.e. choosing epsilon)
 - Finding the optimal loss-function
 - Understanding the connection between the step size and the number of iterations