



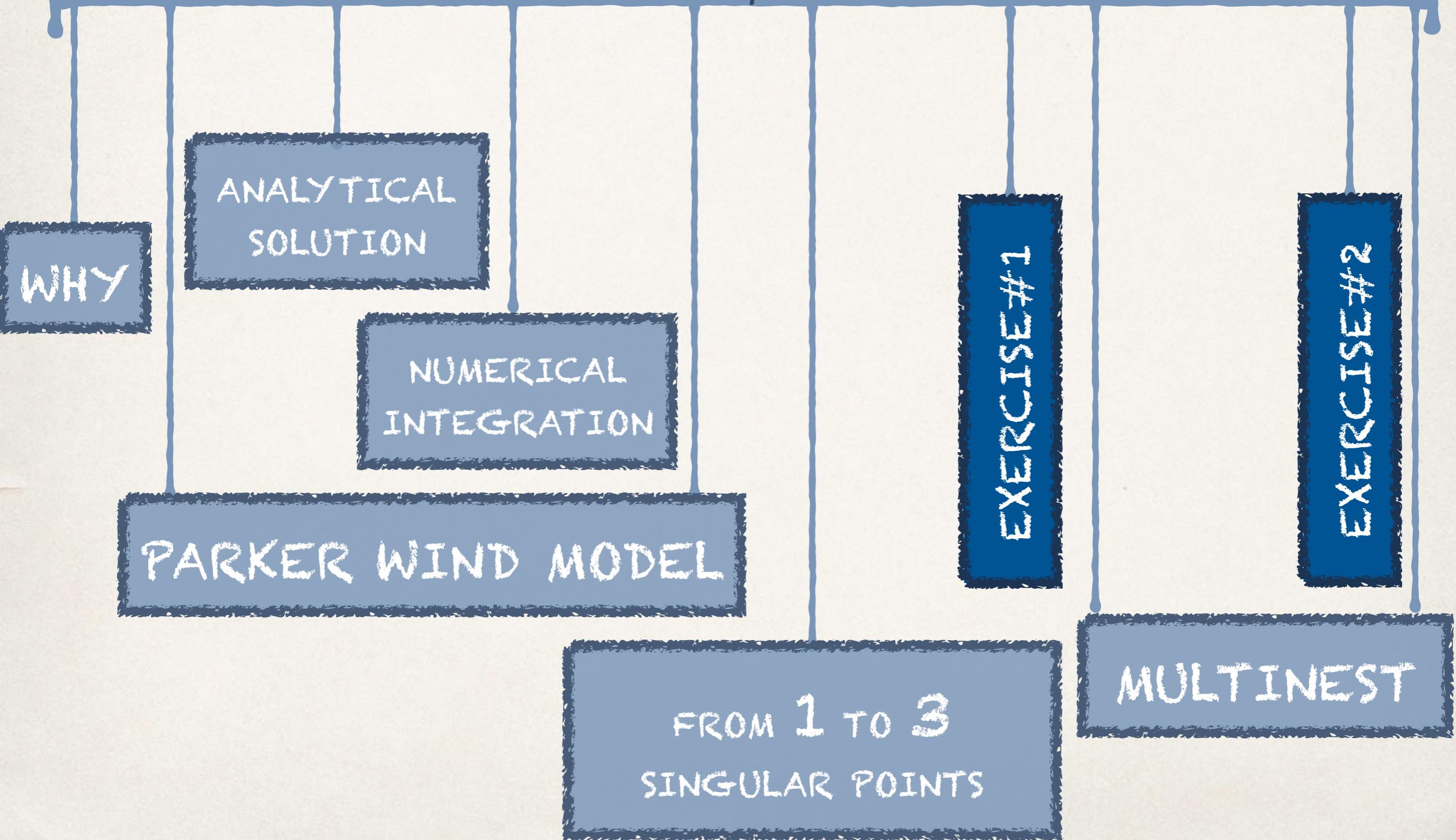
The Magere Brug - oil on canvas by Hubertine Heijermans

# Nonlinear differential equations with singular surfaces: the wind equation

Chiara Ceccobello - PD@Chalmers University of Technology

# OUTLINE

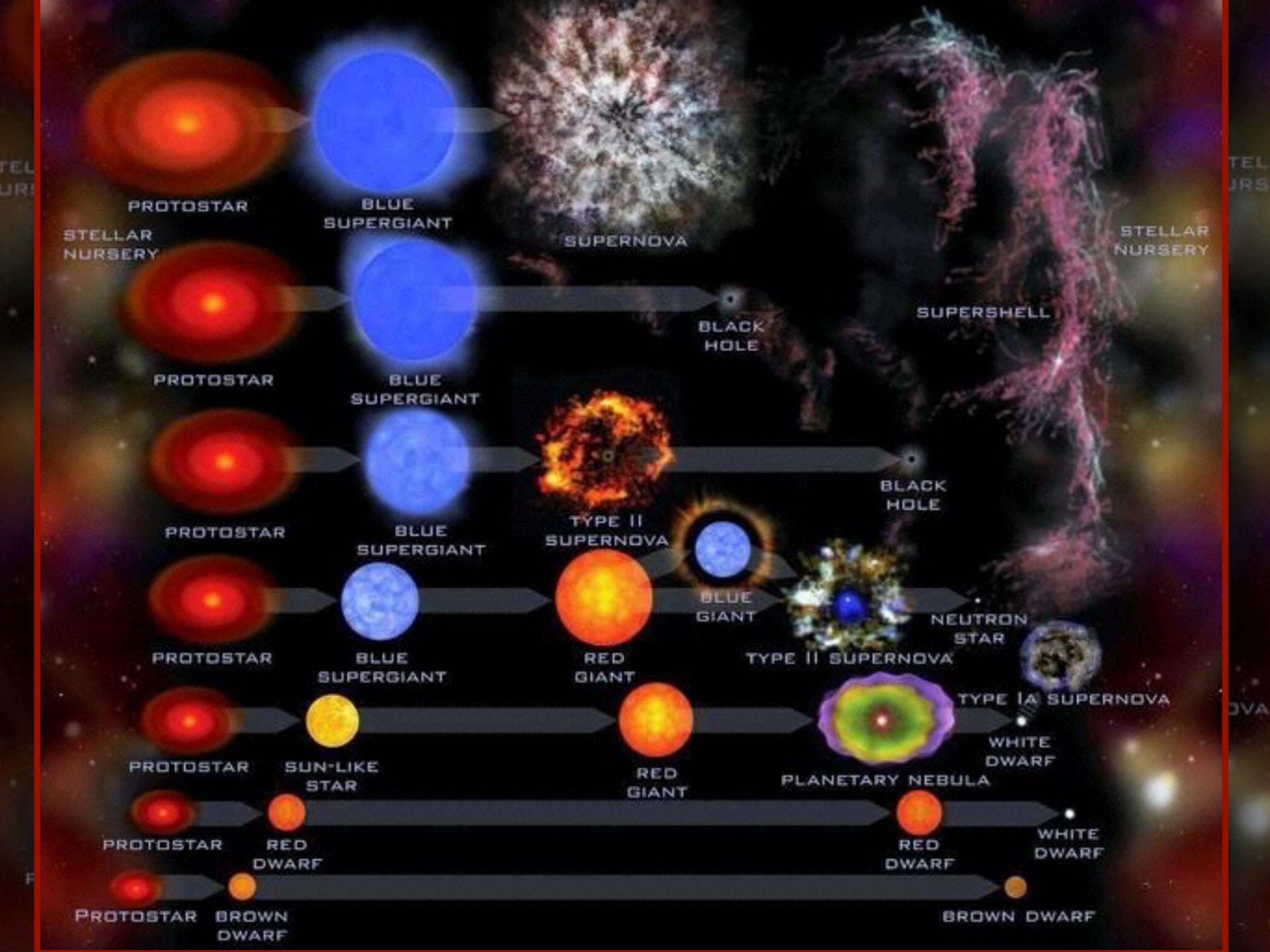
non-linear differential equations with singularities



# Why do we want/need to study non-linear differential equations with singularities in the first place???

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Among other things, they describe the accretion and ejection of matter into and away from an astrophysical object

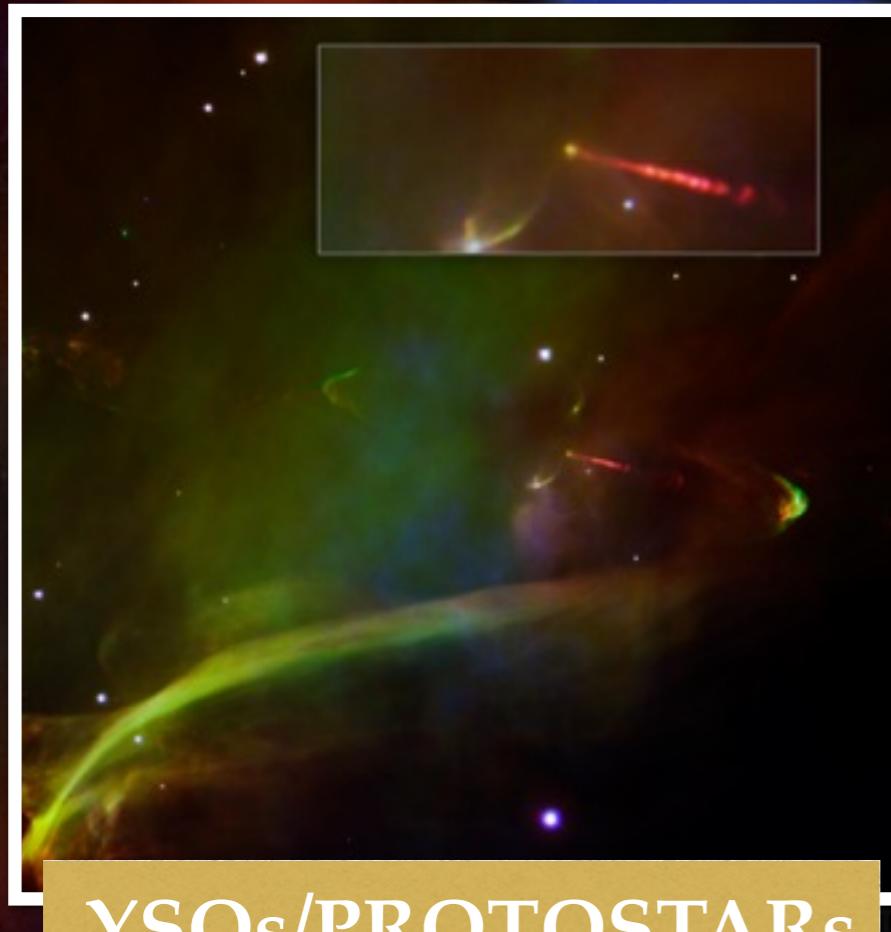


## AGB STARS

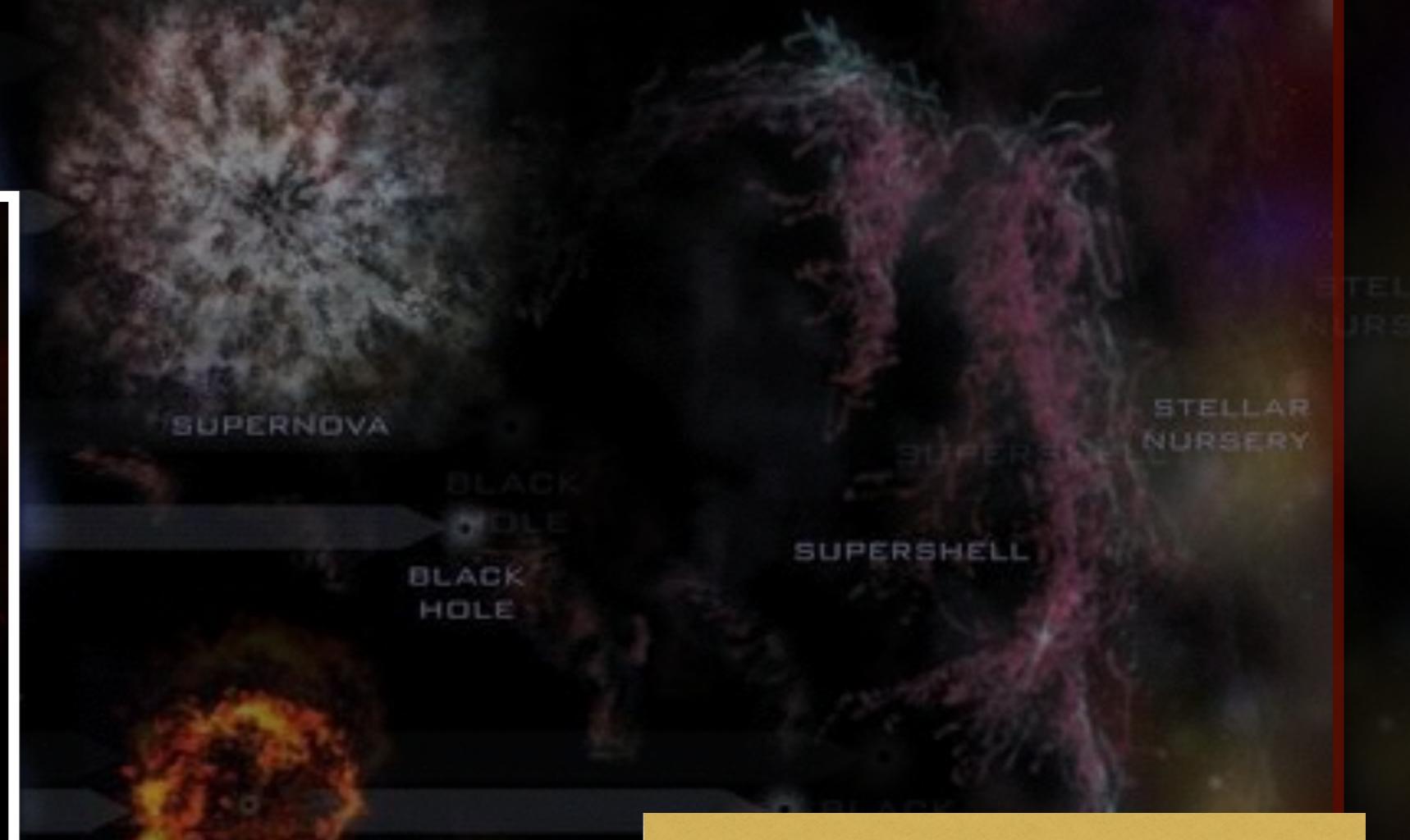


## PLANETARY NEBULAE





YSOs/PROTOSTARS



NS/MAGNETARS

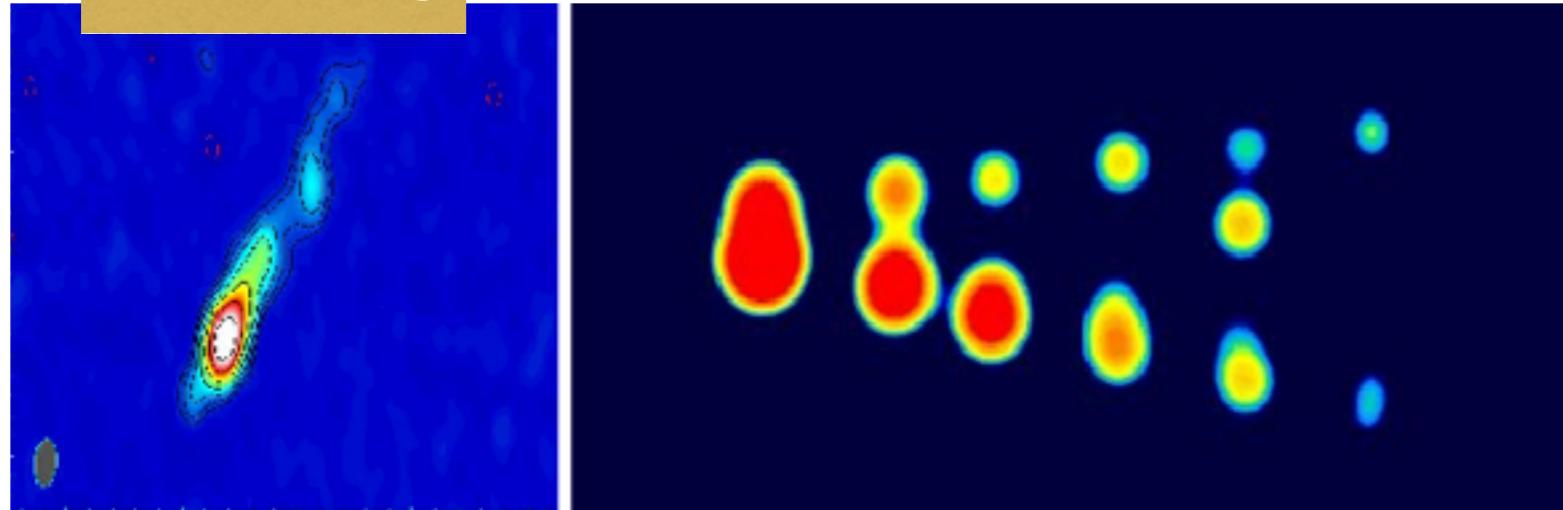


more  
PLANETARY  
NEBULAE

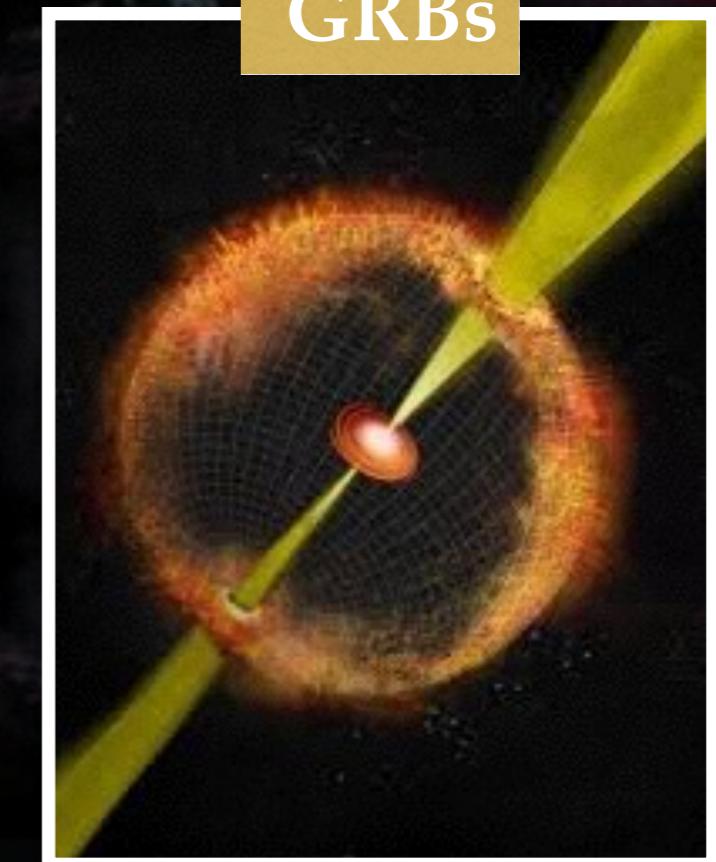


BROWN DWARF

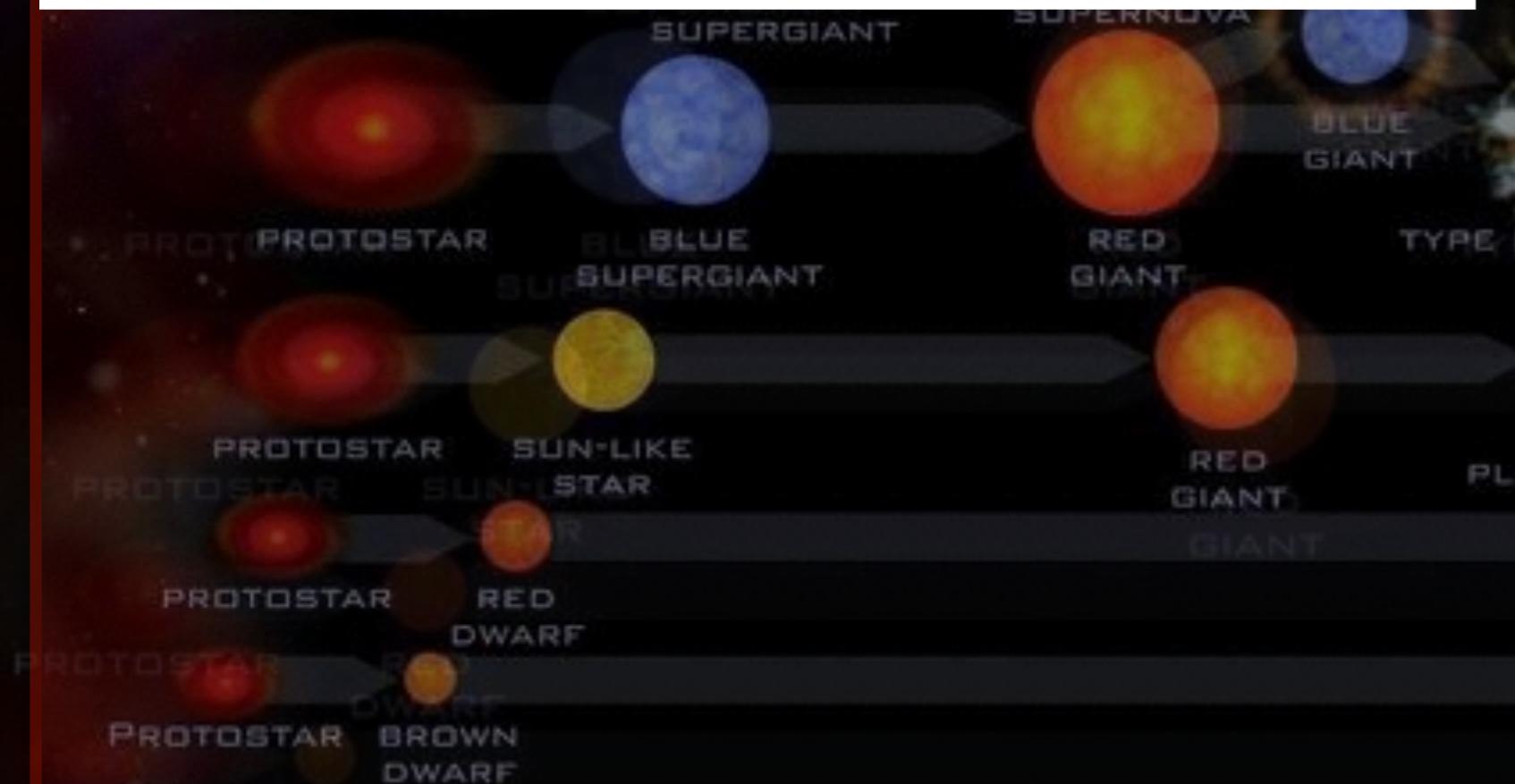
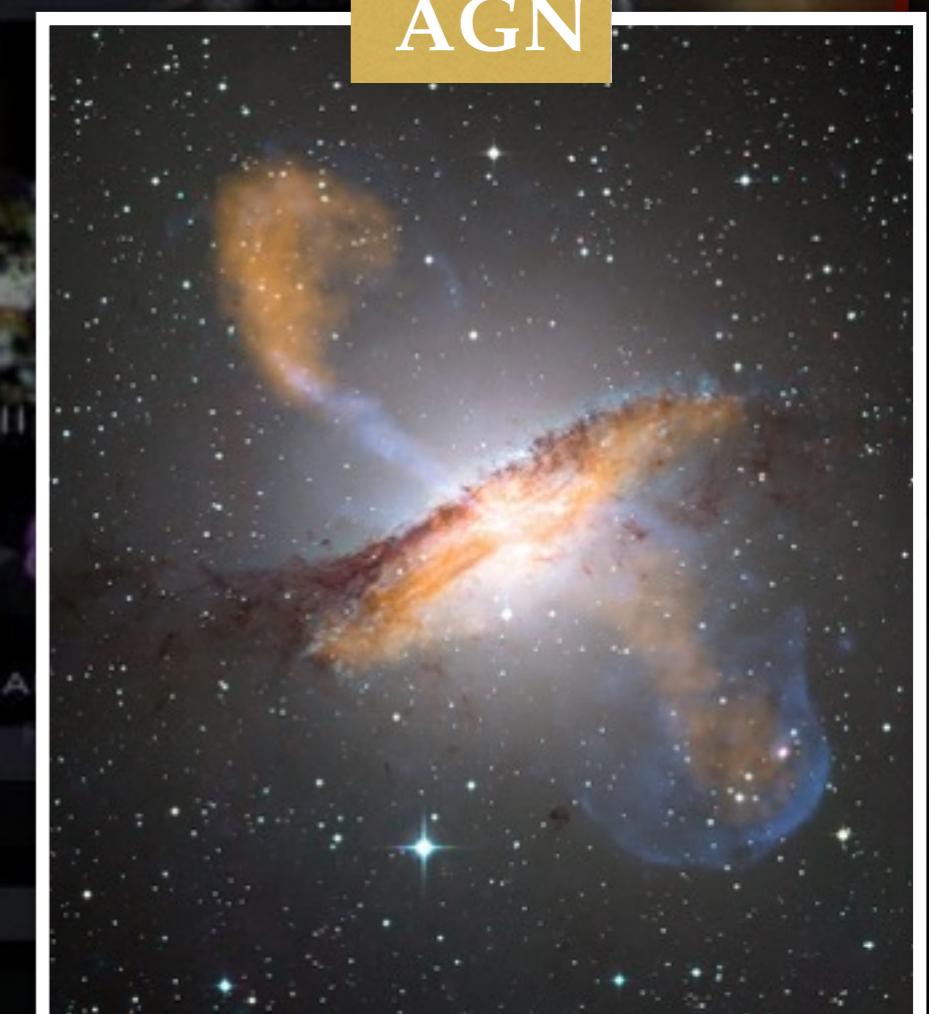
# BHXRBS



# GRBs



# AGN



# Impact of outflows

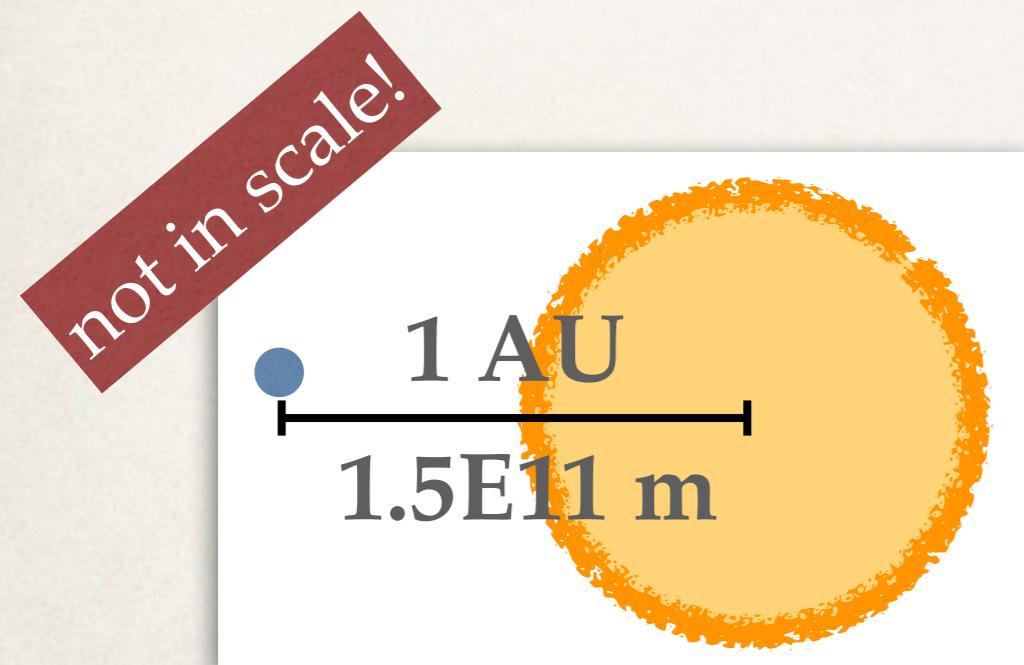
*Interaction and feedback*

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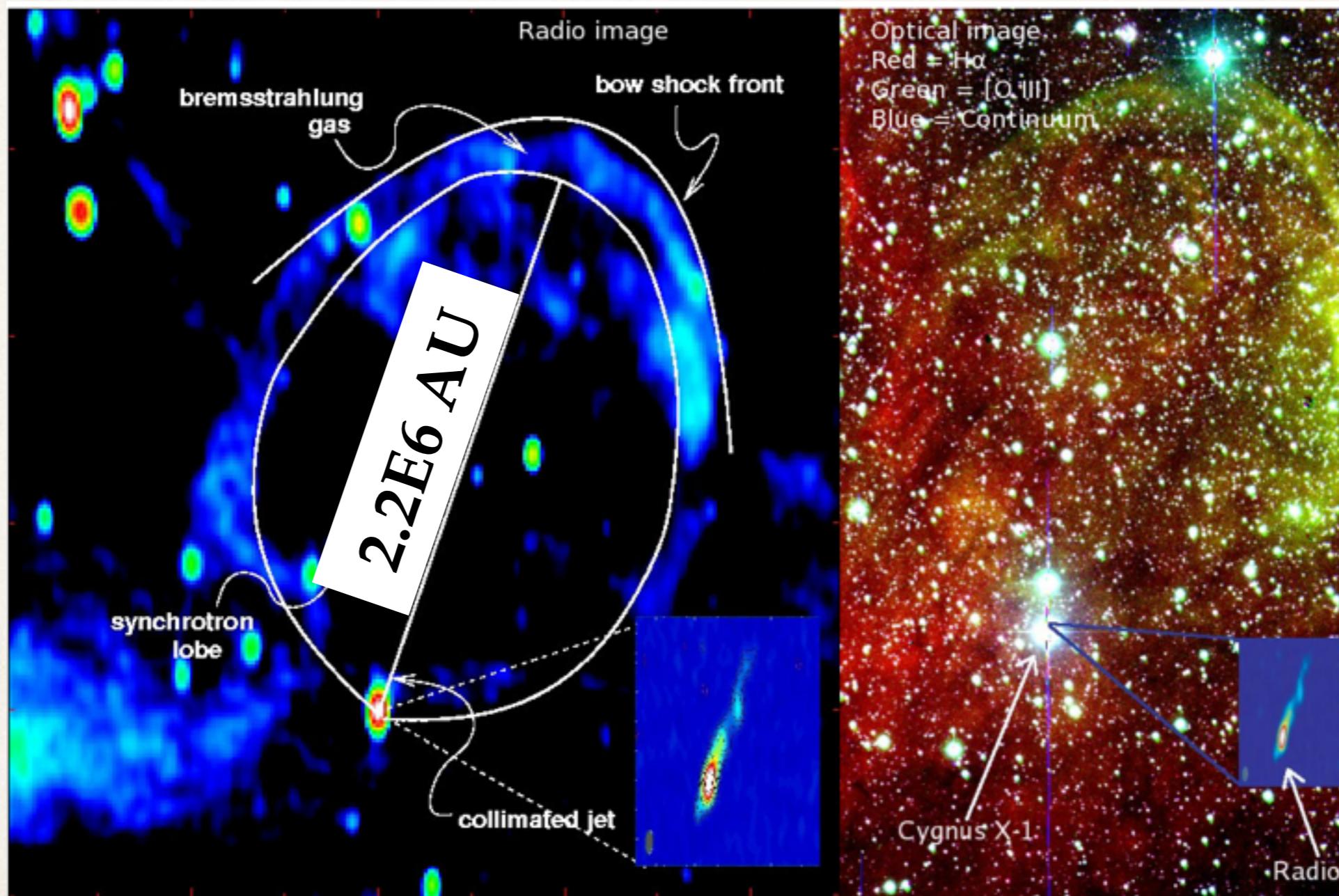
Asymptotic Giant Branch Star - Mira  
NASA/JPL-Caltech/C. Martin/M. Seibert

8.2E5 AU



# Impact of outflows

## *Interaction and feedback*

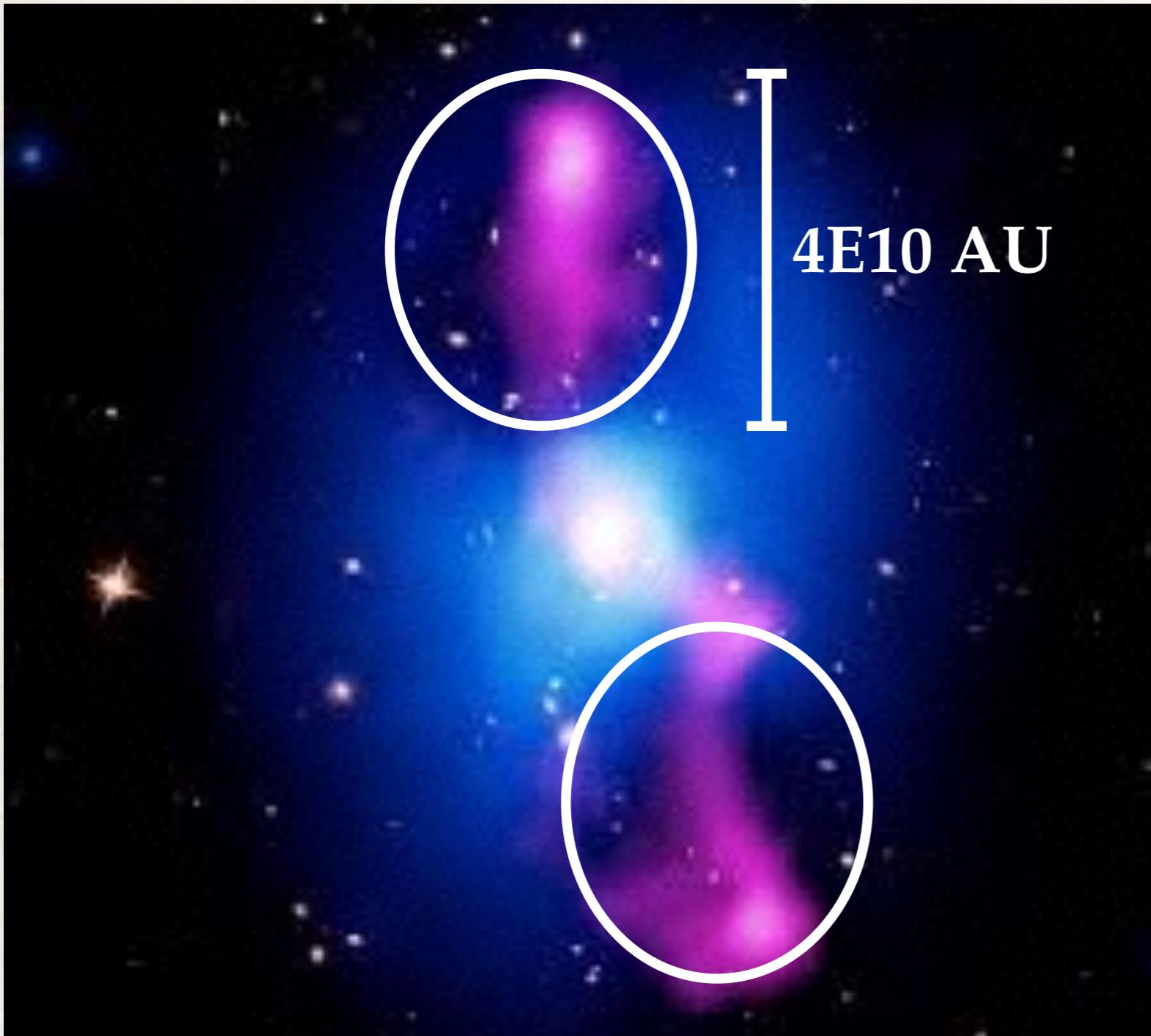


Black Hole X-Ray Binary - Cygnus X-1: Gallo et al. 2005, Russell et al. 2007

# Impact of outflows

## *Interaction and feedback*

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BLUE: X-ray  
PINK: radio  
BG: optical

Credit:  
X-ray: NASA / CXC / Univ. of Waterloo /  
A. Vantyghem et al;  
Optical: NASA / STScI;  
Radio: NRAO / VLA

**HOW DO  
THEY  
FORM?**

**WHAT  
ARE THEY  
MADE OF?**

**WINDS  
OUTFLOWS  
JETS**

**HOW MUCH  
ENERGY  
DO THEY  
CARRY?**

**HOW  
DO THEY  
RADIATE?**

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**HOW  
DO THEY  
RADIATE?**

# How do outflows(/inflows) form?

## The MHD system of equations

---

We saw that

- stars can loose mass through stellar wind
- gravitating objects can attract matter from the interstellar medium or a companion
- accreting objects can launch outflows of different types (collimated / uncollimated winds, jets,...)

To study both accretion/ejection of gas into/away from a source, we need to solve *a set of equations describing a decelerating/accelerating fluid in the gravitational field of the source and possibly in the presence of large-scale magnetic fields*

# Parker HD wind model (1958)

---

The simplest case of study is a radial flow, either towards or away from an object of mass  $M$ .

We assume the following:

- ✿ Spherically symmetric  $\Rightarrow$  radial flow, i.e.  $v = v(r)$
- ✿ Perfect, non self-gravitating gas  $\Rightarrow$  
$$\Phi = -\frac{GM}{r}$$
- ✿ Isothermal  $\Rightarrow$  constant sound speed, i.e. 
$$c_s^2 = \frac{p}{\rho}$$

# Parker HD wind model (1958)

---

The governing equations are:

- ✿ Mass conservation:

$$4\pi r^2 \rho v = -\dot{M}$$

- if  $v > 0$ : STELLAR WIND
- if  $v < 0$ : ACCRETION FLOW
- the mass-loss / -accretion rate,  $\dot{M}$ , is constant

- ✿ Equation of state:

$$p = K\rho^\Gamma$$

- which reduces to  $c_s^2 = p/\rho$  in the isothermal case

- ✿ Equation of motion:

$$\rho v \frac{dv}{dr} = -\rho \frac{d\Phi}{dr} - \frac{dp}{dr}$$

# Analytical integration

$$\rho v \frac{dv}{dr} = -\rho \frac{d\Phi}{dr} - \frac{dp}{dr}$$

- ✿ To perform the integration of the Parker wind equation, we first need to get rid of as many unknown as possible by using the constraints we know from the other equations
- ✿ Namely, we want to find a version of the above equation which is only function of  $v, r + \text{constants}$

$$\frac{dv}{dr} = \mathcal{F}(r, v; c_s, G, M)$$

# Analytical integration

$$\rho v \frac{dv}{dr} = -\rho \frac{d\Phi}{dr} - \frac{dp}{dr}$$

- 
- Let's rearrange it and use  $c_s^2 = p/\rho$  to eliminate p

$$v \frac{dv}{dr} + \frac{c_s^2}{\rho} \frac{d\rho}{dr} + \frac{GM}{r^2} = 0$$

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$$v \frac{dv}{dr} + \frac{c_s^2}{\rho} \frac{d\rho}{dr} + \frac{GM}{r^2} = 0$$

- Then we use the mass conservation law to get rid of  $\rho$

$$\frac{d}{dr}(4\pi r^2 \rho v) = 0, \quad \frac{d}{dr}(r^2 \rho v) = \rho \frac{d}{dr}(r^2 v) + r^2 v \frac{d\rho}{dr} = 0$$

➡  $\frac{1}{r^2 v} \frac{d}{dr}(r^2 v) = -\frac{1}{\rho} \frac{d\rho}{dr}$

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➡  $\frac{1}{r^2 v} \frac{d}{dr}(r^2 v) = -\frac{1}{\rho} \frac{d\rho}{dr}$

- so the wind equation becomes

$$v \frac{dv}{dr} - \frac{c_s^2}{r^2 v} \frac{d}{dr}(r^2 v) + \frac{GM}{r^2} = 0 \rightarrow v \frac{dv}{dr} - \frac{c_s^2}{r^2 v} \left( 2rv + r^2 \frac{dv}{dr} \right) + \frac{GM}{r^2} = 0$$

# Analytical integration

$$\rho v \frac{dv}{dr} = -\rho \frac{d\Phi}{dr} - \frac{dp}{dr}$$

We obtain this form

$$\left(v - \frac{c_s^2}{v}\right) \frac{dv}{dr} = \frac{2c_s^2}{r} - \frac{GM}{r^2}$$

Rearranging the equation in the form of  $dv/dr = N/D$

**WIND  
EQUATION**

$$\frac{dv}{dr} = \frac{v}{r} \frac{(2c_s^2 - GM/r)}{(v^2 - c_s^2)}$$

we show that it has a singular point  $(0/0)$ , called the **SONIC POINT** at  $v = c_s$  and  $r = r_c$  with  $r_c = GM/(2c_s^2)$

# Analytical integration

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$$\frac{dv}{dr} = \frac{v (2c_s^2 - GM/r)}{r (v^2 - c_s^2)}$$

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We can rewrite it in terms of the **Mach number**

$$\mathcal{M} = \frac{v}{c_s}$$

**WIND  
EQUATION**

$$\frac{d\mathcal{M}^2}{dr} = \frac{4\mathcal{M}^2}{r^2} \frac{(r - r_c)}{(\mathcal{M}^2 - 1)}$$

# Analytical integration

$$\rho v \frac{dv}{dr} = -\rho \frac{d\Phi}{dr} - \frac{dp}{dr}$$

---

We can now separate the variables

$$\int \left( v - \frac{c_s^2}{v} \right) dv = 2 \int \frac{c_s^2}{r^2} (r - r_c) dr$$

# Analytical integration

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$$\int \left( v - \frac{c_s^2}{v} \right) dv = 2 \int \frac{c_s^2}{r^2} (r - r_c) dr$$

Changing the variable on the lhs to  $(v/c_s)^2$  and to  $r/r_c$ , we get

$$\int \frac{1}{2v} \left( v - \frac{c_s^2}{v} \right) 2v \frac{dv}{c_s^2} = 2 \int \left( \frac{r_c}{r} - \frac{r_c^2}{r^2} \right) d \left( \frac{r}{r_c} \right)$$

$$\frac{1}{2} \int d \left( \frac{v^2}{c_s^2} \right) - \frac{1}{2} \int \frac{c_s^2}{v^2} d \left( \frac{v^2}{c_s^2} \right) = 2 \int \frac{r_c}{r} d \left( \frac{r}{r_c} \right) - 2 \int \frac{r_c^2}{r^2} d \left( \frac{r}{r_c} \right)$$

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$$\left( \frac{v}{c_s} \right)^2 - \ln \left( \frac{v^2}{c_s^2} \right) = 4 \ln \left( \frac{r}{r_c} \right) + 4 \frac{r_c}{r} + C$$

when  $v = c_s$  and  $r = r_c$   
**SONIC POINT**  
 $C = -3$

# Analytical integration

$$\rho v \frac{dv}{dr} = -\rho \frac{d\Phi}{dr} - \frac{dp}{dr}$$

$$\left(\frac{v}{c_s}\right)^2 - \ln\left(\frac{v^2}{c_s^2}\right) = 4 \ln\left(\frac{r}{r_c}\right) + 4 \frac{r_c}{r} + C$$

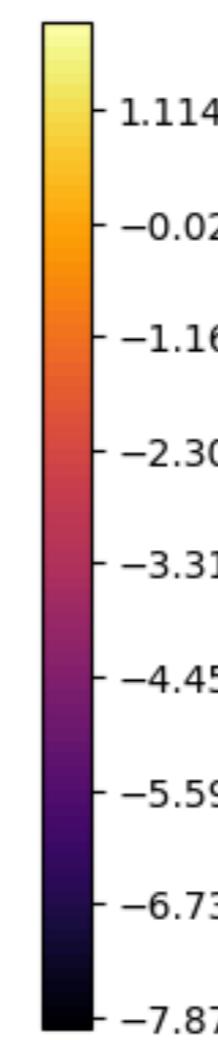
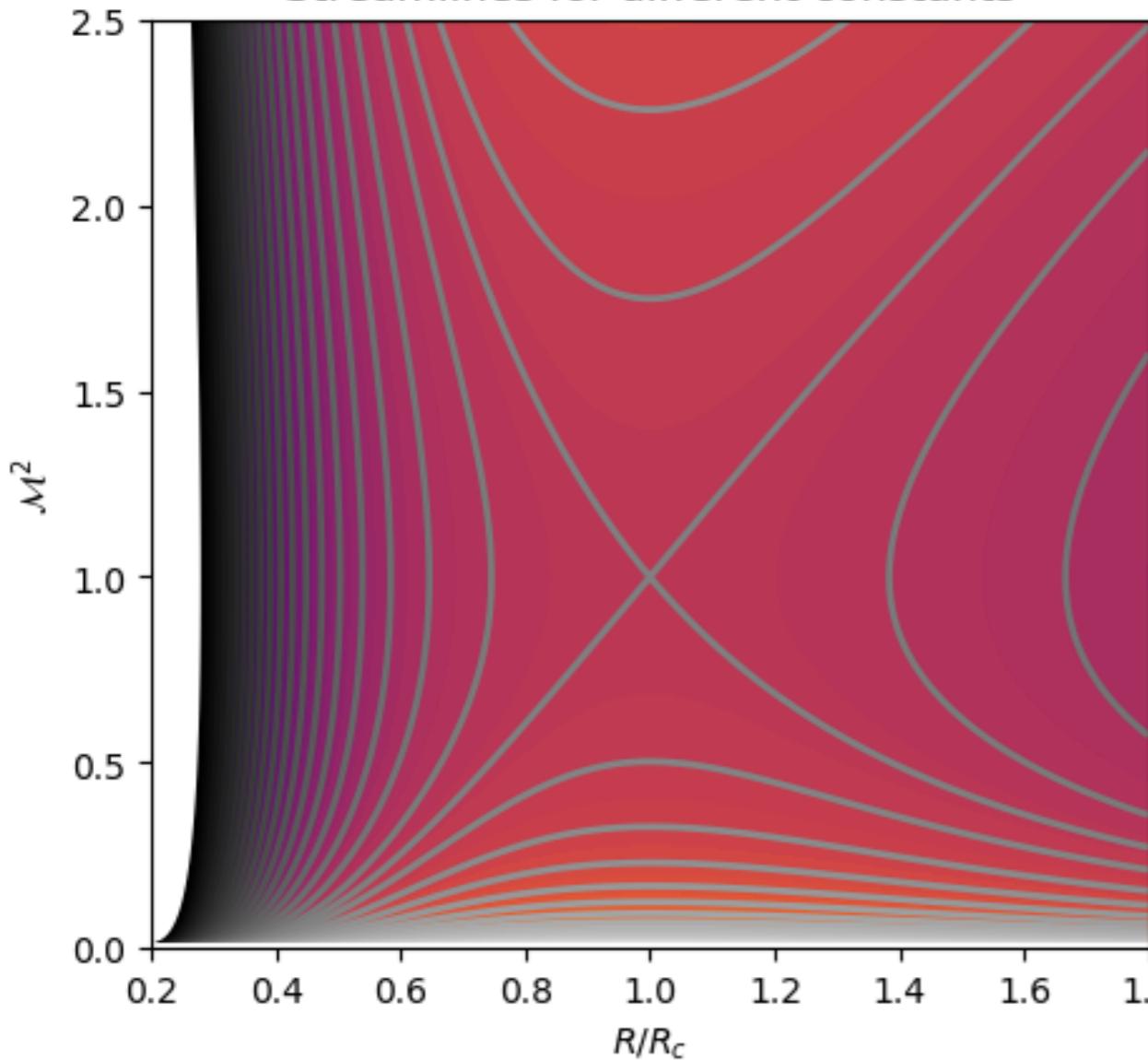
when  $v = c_s$  and  $r = r_c$   
SONIC POINT  
 $C = -3$

or in the Mach number variable  $\mathcal{M} = \frac{v}{c_s}$

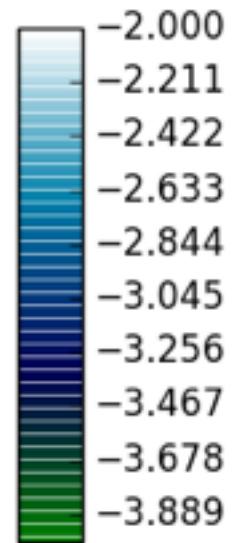
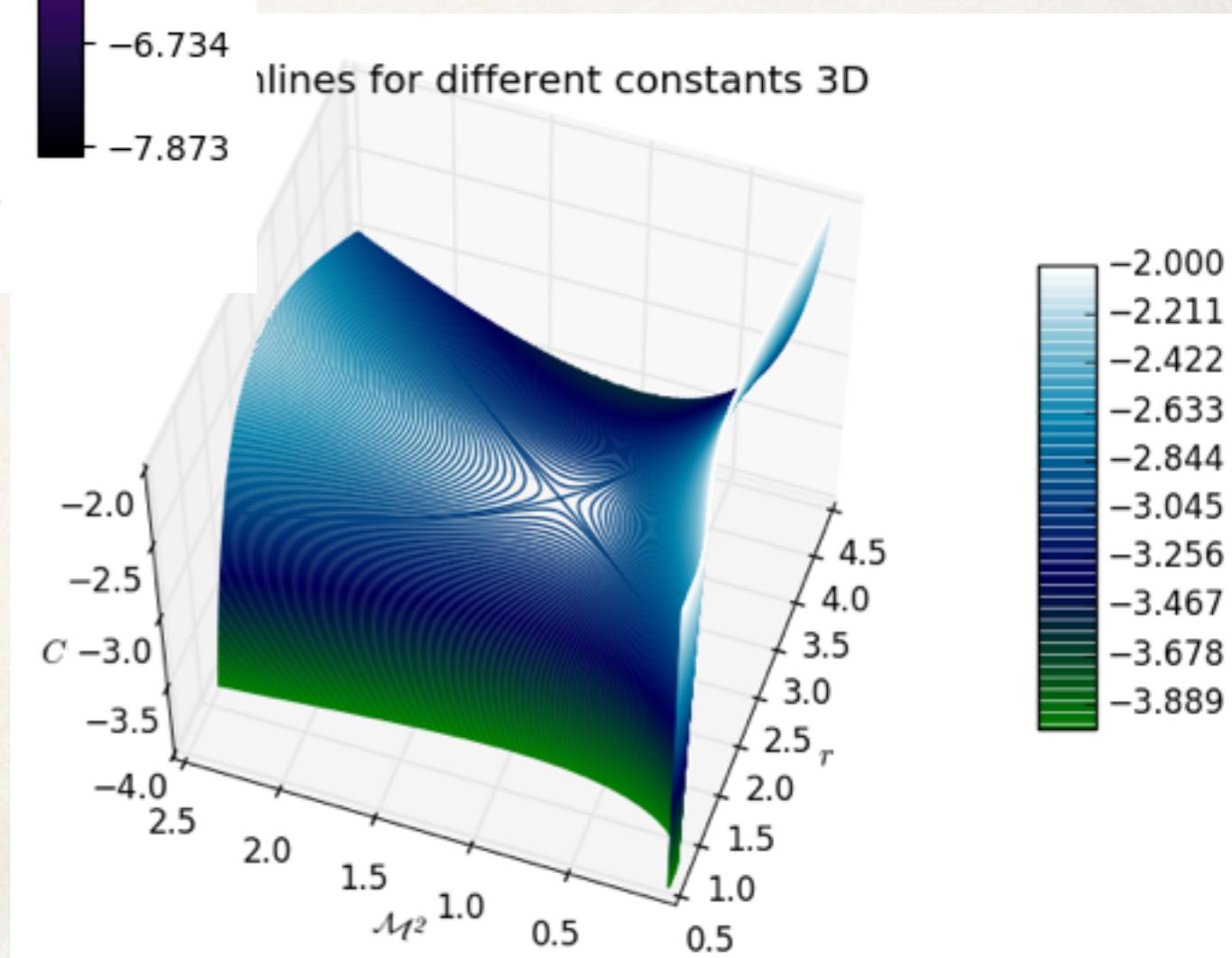
$$\mathcal{M}^2 - \ln \mathcal{M}^2 - 4 \ln\left(\frac{r}{r_c}\right) - 4 \frac{r_c}{r} + C' = 0$$

Let's now make some contour plots of the solution space.

Streamlines for different constants

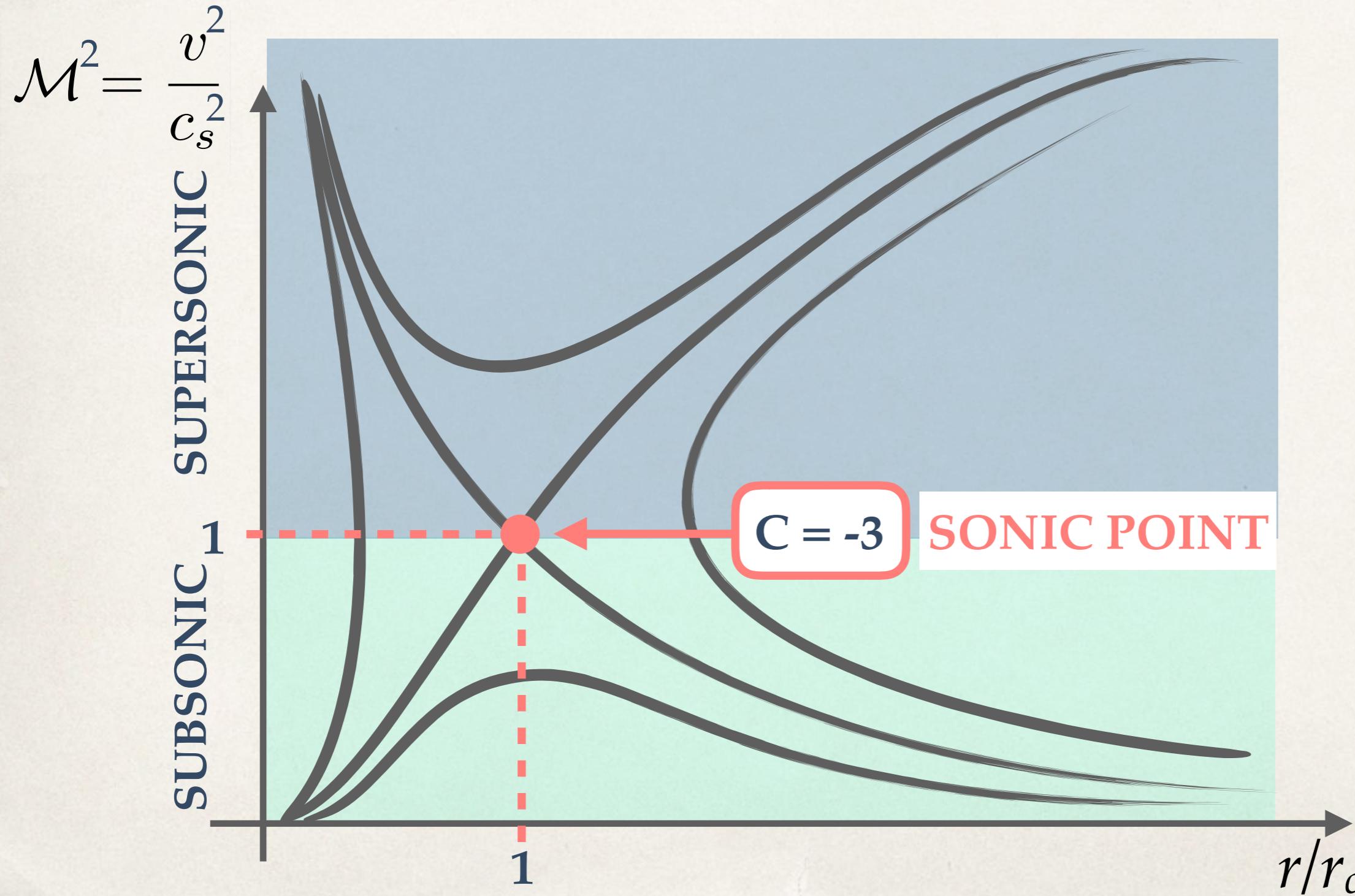


Streamlines for different constants 3D



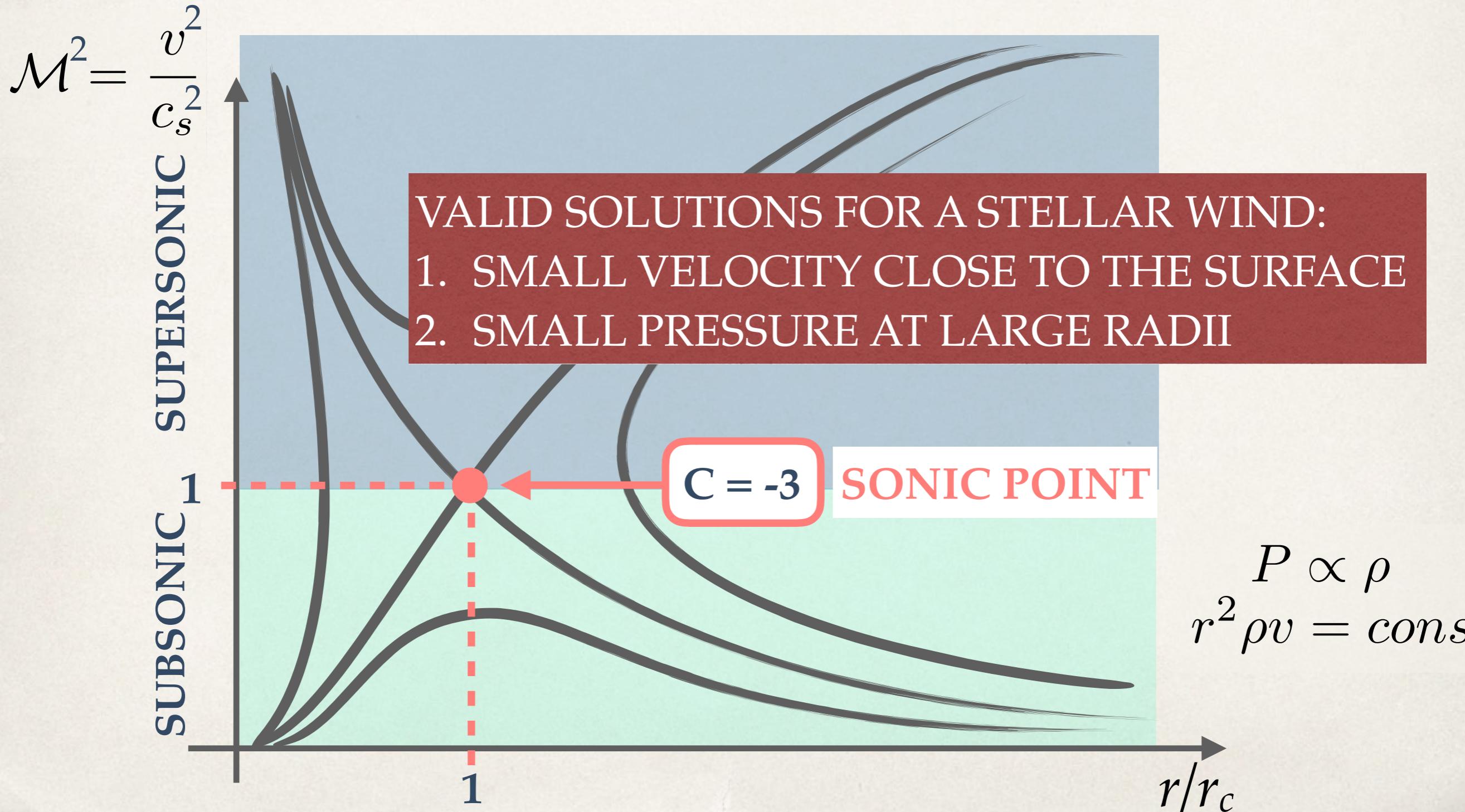
# Families of solutions

$$\mathcal{M}^2 - \ln \mathcal{M}^2 - 4 \ln \left( \frac{r}{r_c} \right) - 4 \frac{r_c}{r} + C' = 0$$



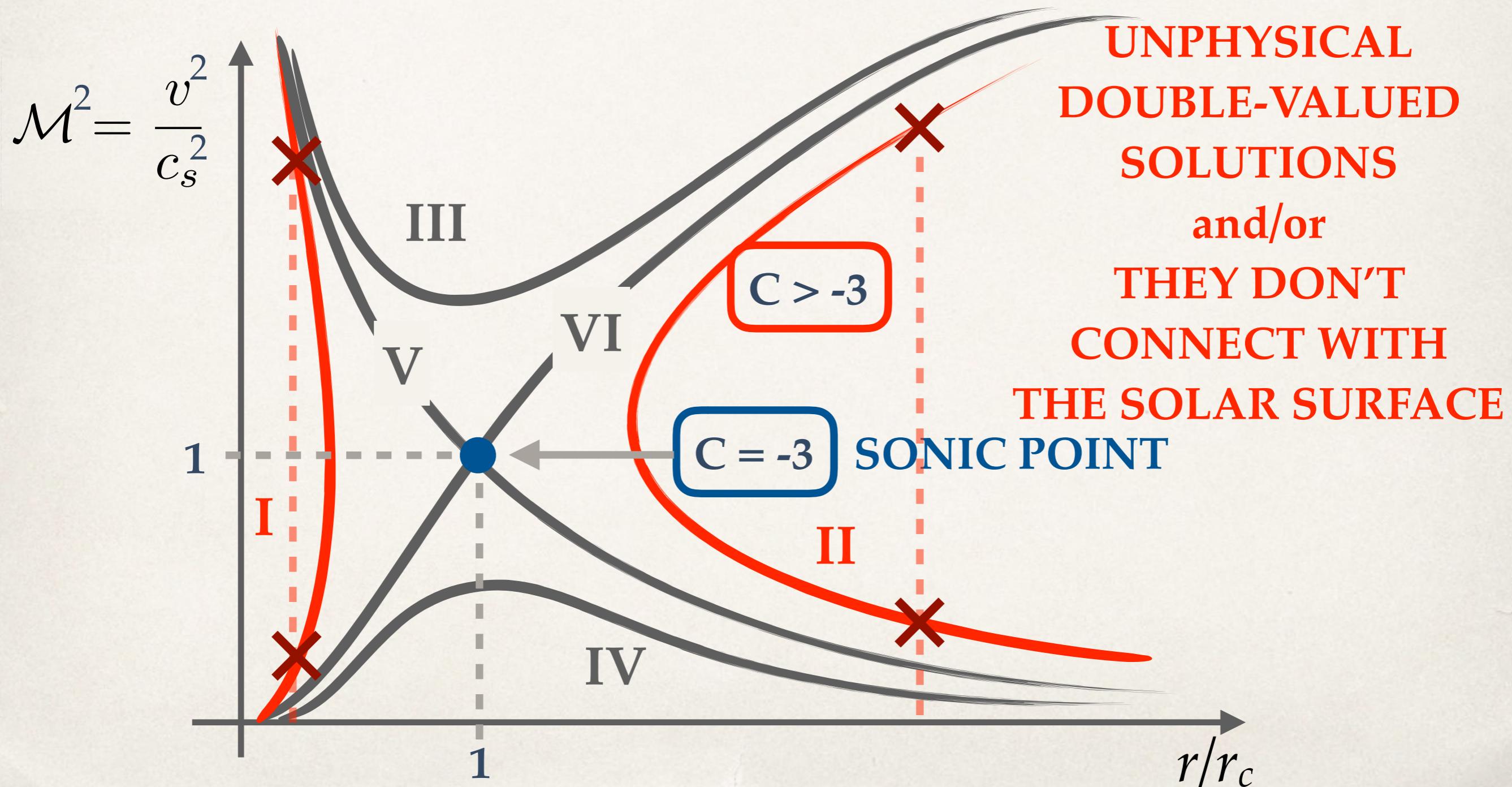
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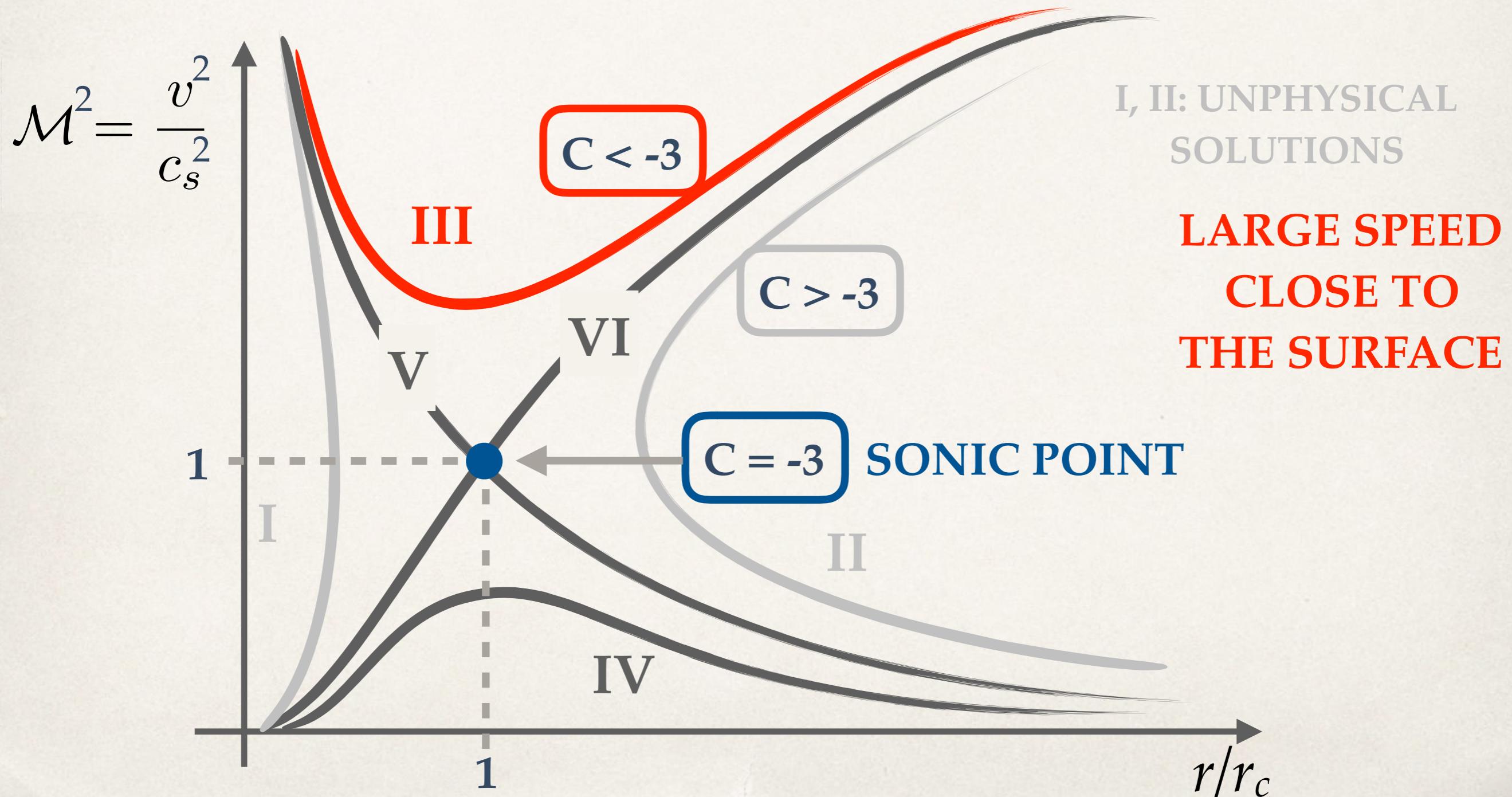
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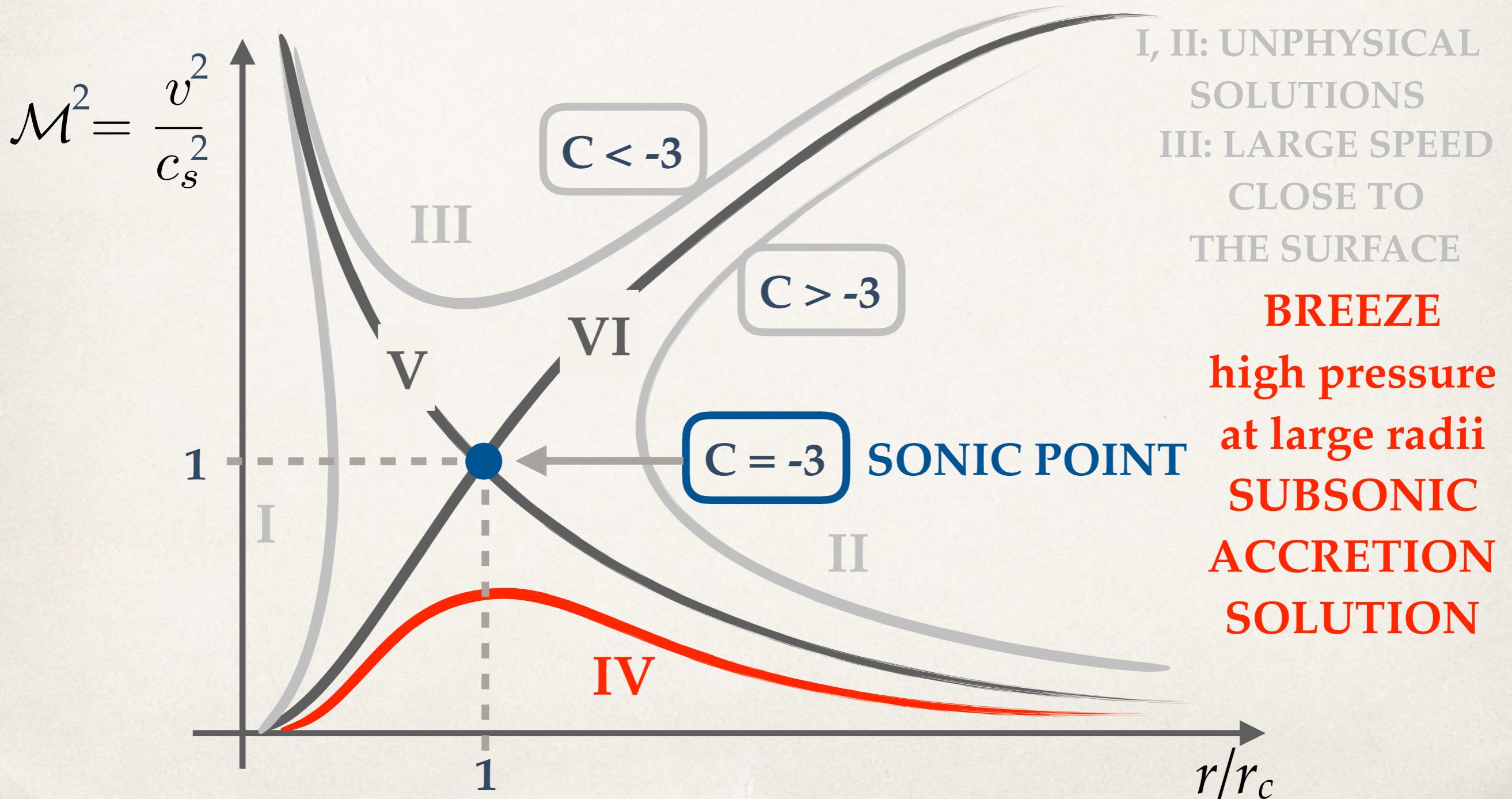
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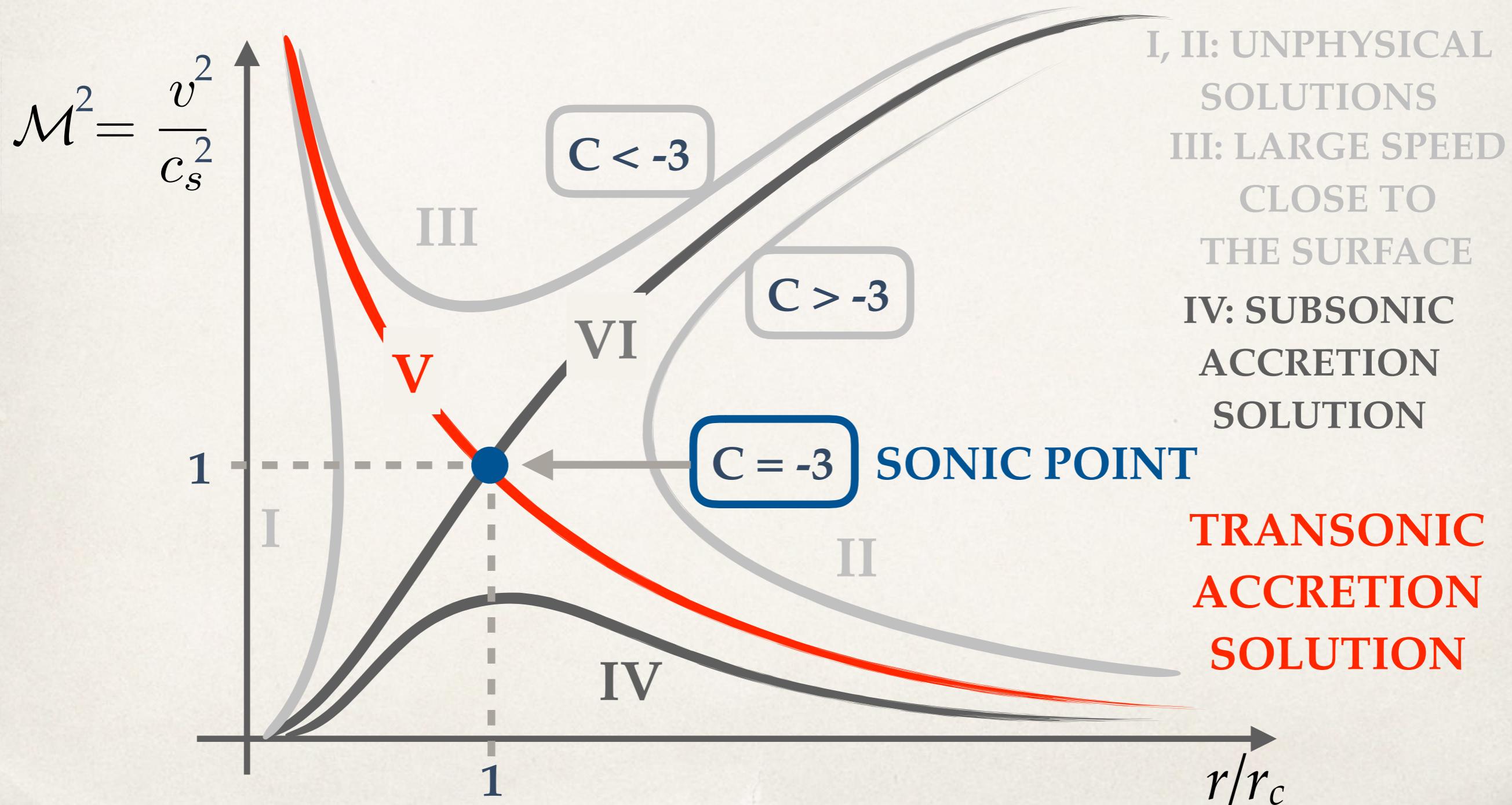
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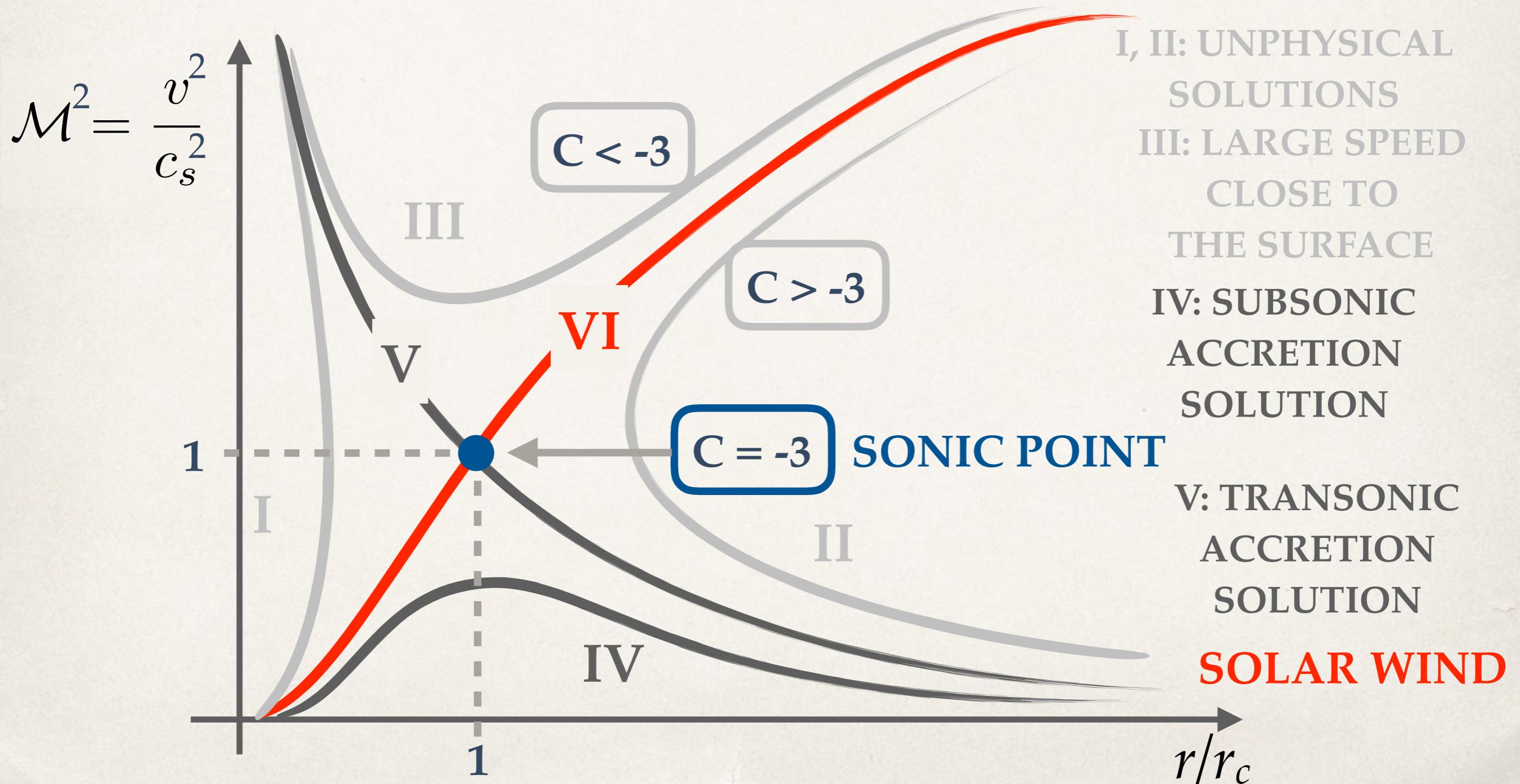
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# Families of solutions

$$\mathcal{M}^2 - \ln \mathcal{M}^2 - 4 \ln \left( \frac{r}{r_c} \right) - 4 \frac{r_c}{r} + C' = 0$$



# What if...

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Let's assume that:

- ⌘ There is **no analytical solution** to the Parker wind equation
- ⌘ **We don't know there is an intermediate critical point**

We want to integrate the equation

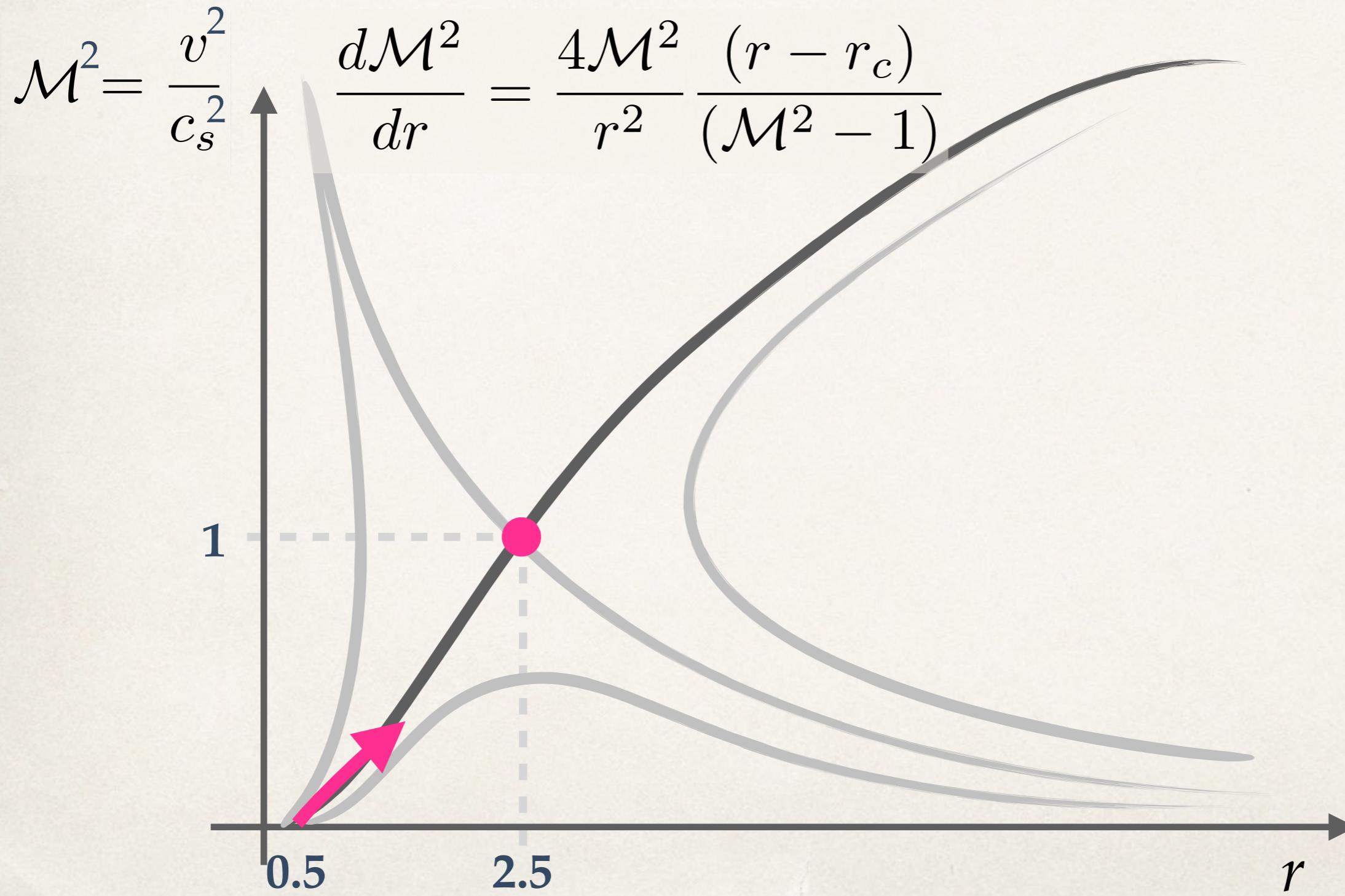
$$\frac{d\mathcal{M}^2}{dr} = \frac{4\mathcal{M}^2}{r^2} \frac{(r - r_c)}{(\mathcal{M}^2 - 1)}$$

from  $r = 0.5$  (to avoid to take the  $\log 0$ ) with some arbitrary value of the critical radius, let's say  $r_c = 2.5$ .

Excluding troublesome behaviour at the boundary is easier.

# Integrating towards singularities

## The case of unknown intermediate singularities



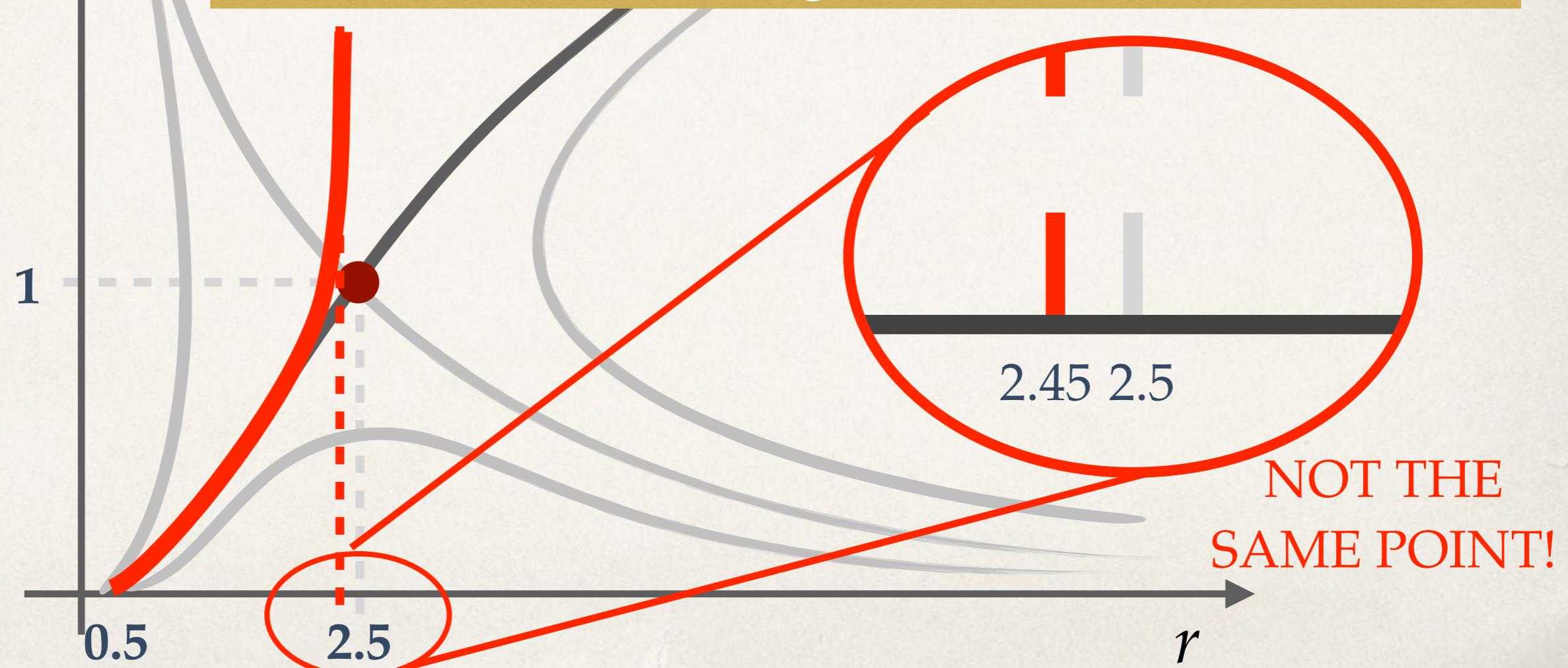
# Integrating towards singularities

$$\mathcal{M}^2 = \frac{v^2}{c_s^2}$$

$$\frac{d\mathcal{M}^2}{dr}$$

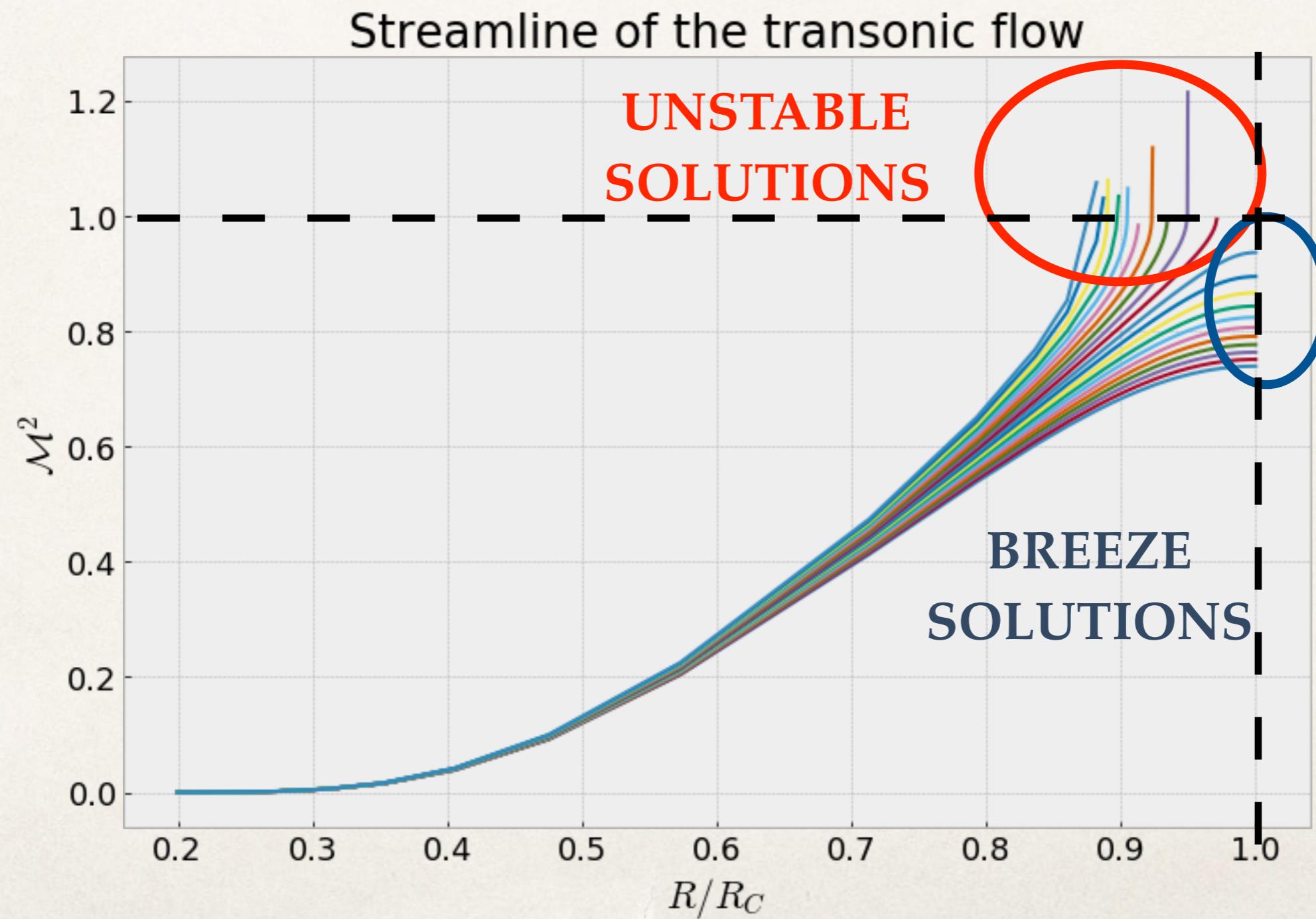
$$4\mathcal{M}^2 \cdot (r - r_*)$$

Numerically, if the numerator and denominator are approaching zero at a different pace, the integration fails!



# Integrating towards singularities

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# Alternative approach needed!

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- ✿ In physical problems with a finite solution, if there is a singularity in the integration interval ( $0/0$ ,  $\pm\infty/\pm\infty$ ), usually there is a **regularity condition** which gives the finite value of the solution at the point.
- ✿ Integrating numerically an equation with intermediate unknown singularities is equivalent to **solving a problem with intermediate boundary conditions** where special values of the variables need to satisfy the regularity condition there and we cannot formulate this condition analytically.
- ✿ We need to get creative!

# de l'Hôpital's rule

---

L'Hôpital's rule states that for functions  $f$  and  $g$  which are differentiable on an open interval  $I$  except possibly at a point  $a \in I$ , if  $\lim_{x \rightarrow a} f(x) = \lim_{x \rightarrow a} g(x) = 0$  or  $\pm \infty$

for all  $x \in I$  with  $x \neq a$  and the limit  $\lim_{x \rightarrow a} \frac{f'(x)}{g'(x)}$  exists, then

$$\lim_{x \rightarrow a} \frac{f(x)}{g(x)} = \lim_{x \rightarrow a} \frac{f'(x)}{g'(x)}$$

# de l'Hôpital's rule

$$\lim_{x \rightarrow a} \frac{f(x)}{g(x)} = \lim_{x \rightarrow a} \frac{f'(x)}{g'(x)}$$

---

Given the wind equation

$$\frac{d\mathcal{M}^2}{dr} = \frac{4\mathcal{M}^2}{r^2} \frac{(r - r_c)}{(\mathcal{M}^2 - 1)}$$

we can define  $f(r)$  and  $g(r)$  as follows and calculate their derivatives wrt  $r$

$$f(r) = 4\mathcal{M}^2(r - r_c)$$

$$g(r) = r^2(\mathcal{M}^2 - 1)$$

$$f'(r) = 4 \frac{d\mathcal{M}^2}{dr} (r - r_c) + 4\mathcal{M}^2$$

$$g'(r) = r^2 \frac{d\mathcal{M}^2}{dr} + \frac{dr^2}{dr} (\mathcal{M}^2 - 1)$$

# de l'Hôpital's rule

$$\lim_{x \rightarrow a} \frac{f(x)}{g(x)} = \lim_{x \rightarrow a} \frac{f'(x)}{g'(x)}$$

Given the wind equation

$$\frac{d\mathcal{M}^2}{dr} = \frac{4\mathcal{M}^2}{r^2} \frac{(r - r_c)}{(\mathcal{M}^2 - 1)}$$

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$$g'(r) = r^2 \frac{d\mathcal{M}^2}{dr} + \frac{dr^2}{dr} (\mathcal{M}^2 - 1)$$

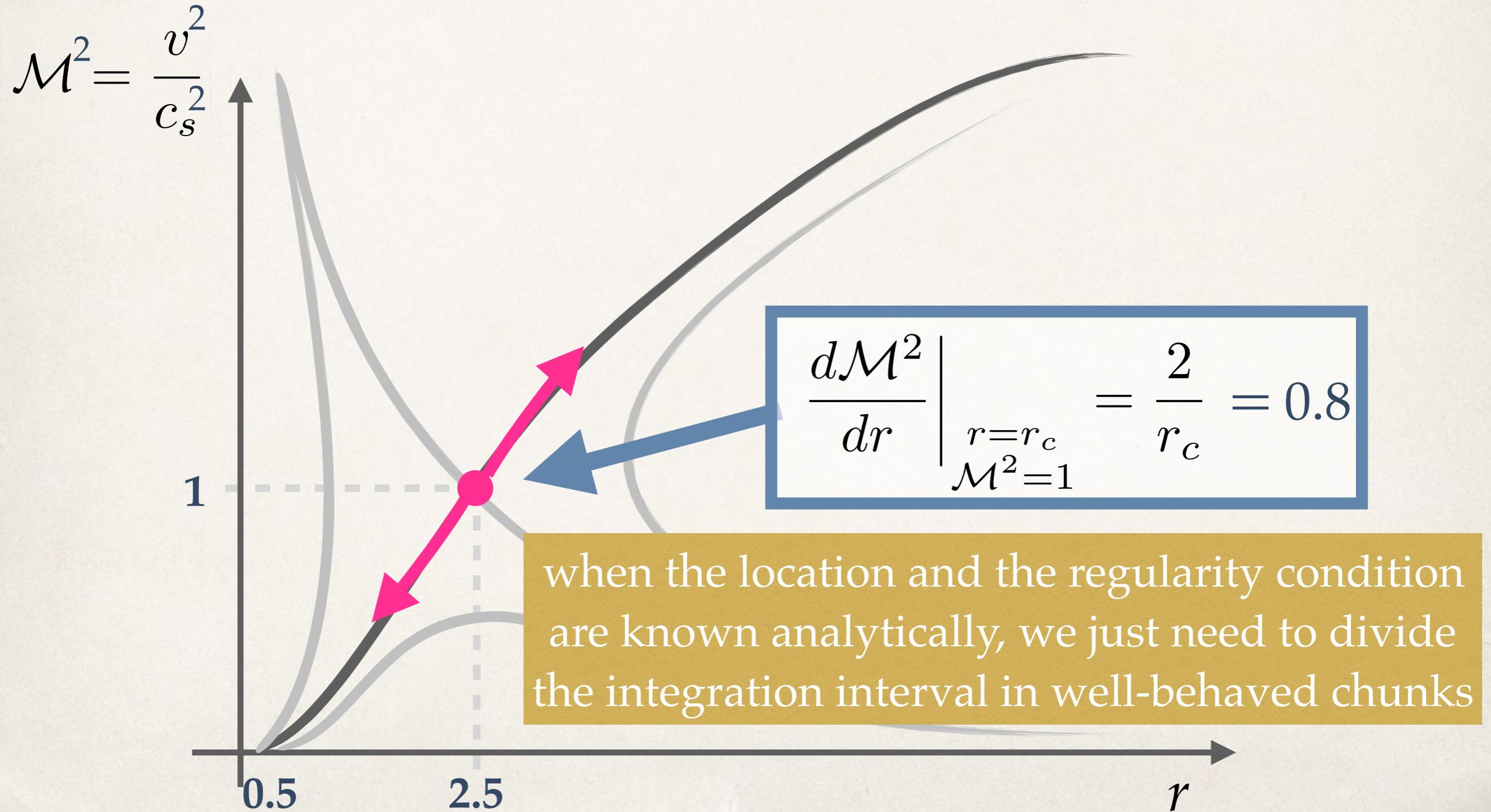
The resulting limit of the ratio of the derivatives for  $r$  approaching  $r_c$  is finite

$$\lim_{\substack{r \rightarrow r_c \\ \mathcal{M}^2 \rightarrow 1}} \frac{f'(x)}{g'(x)} = \frac{4}{r_c^2} \frac{1}{\left( \frac{d\mathcal{M}^2}{dr} \right)}$$

$$\frac{d\mathcal{M}^2}{dr} \Big|_{\substack{r=r_c \\ \mathcal{M}^2=1}} = \frac{2}{r_c}$$

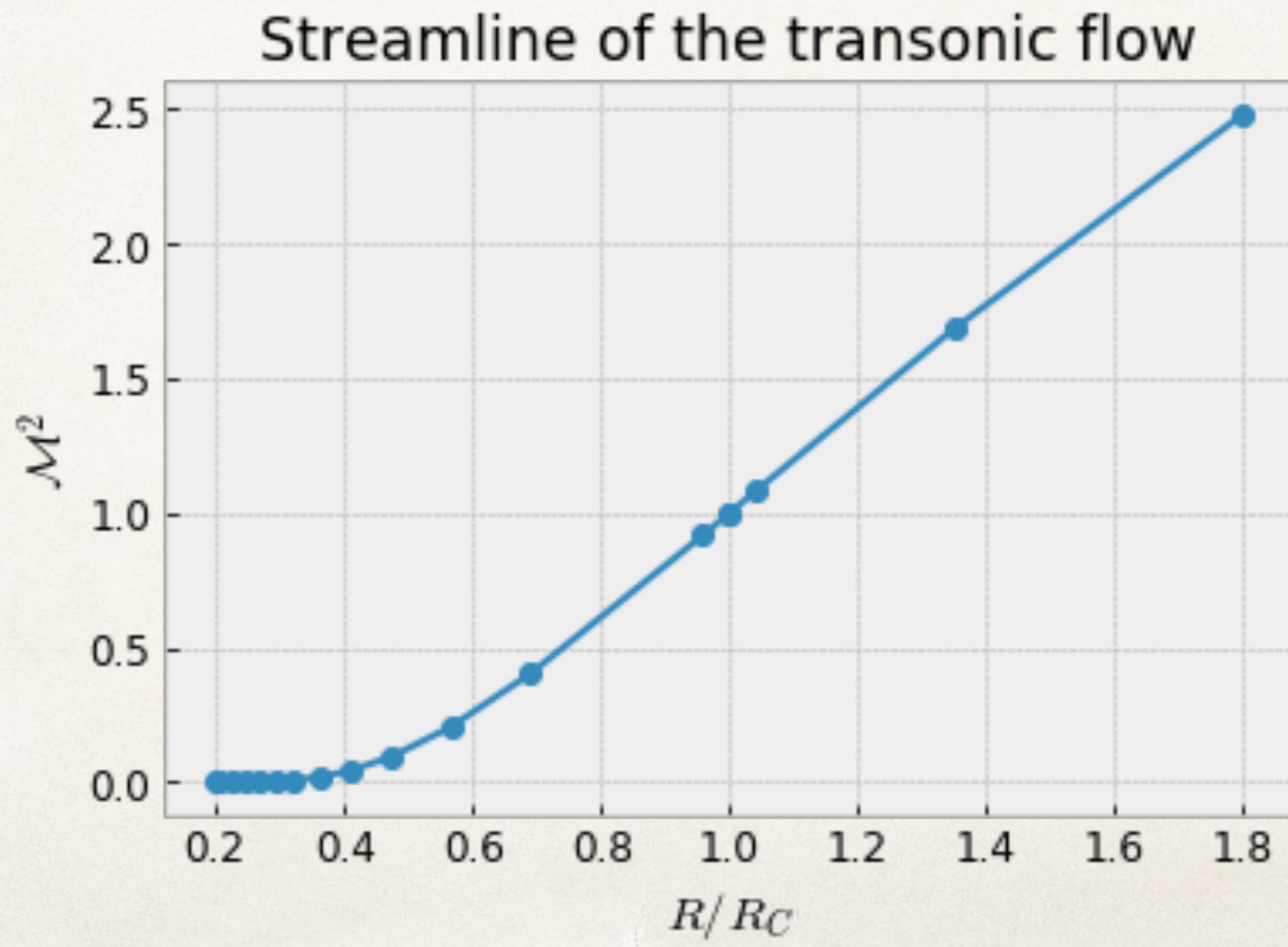
REGULARITY  
CONDITION  
AT SP

# Integrating away from singularities



# Integrating away from singularities

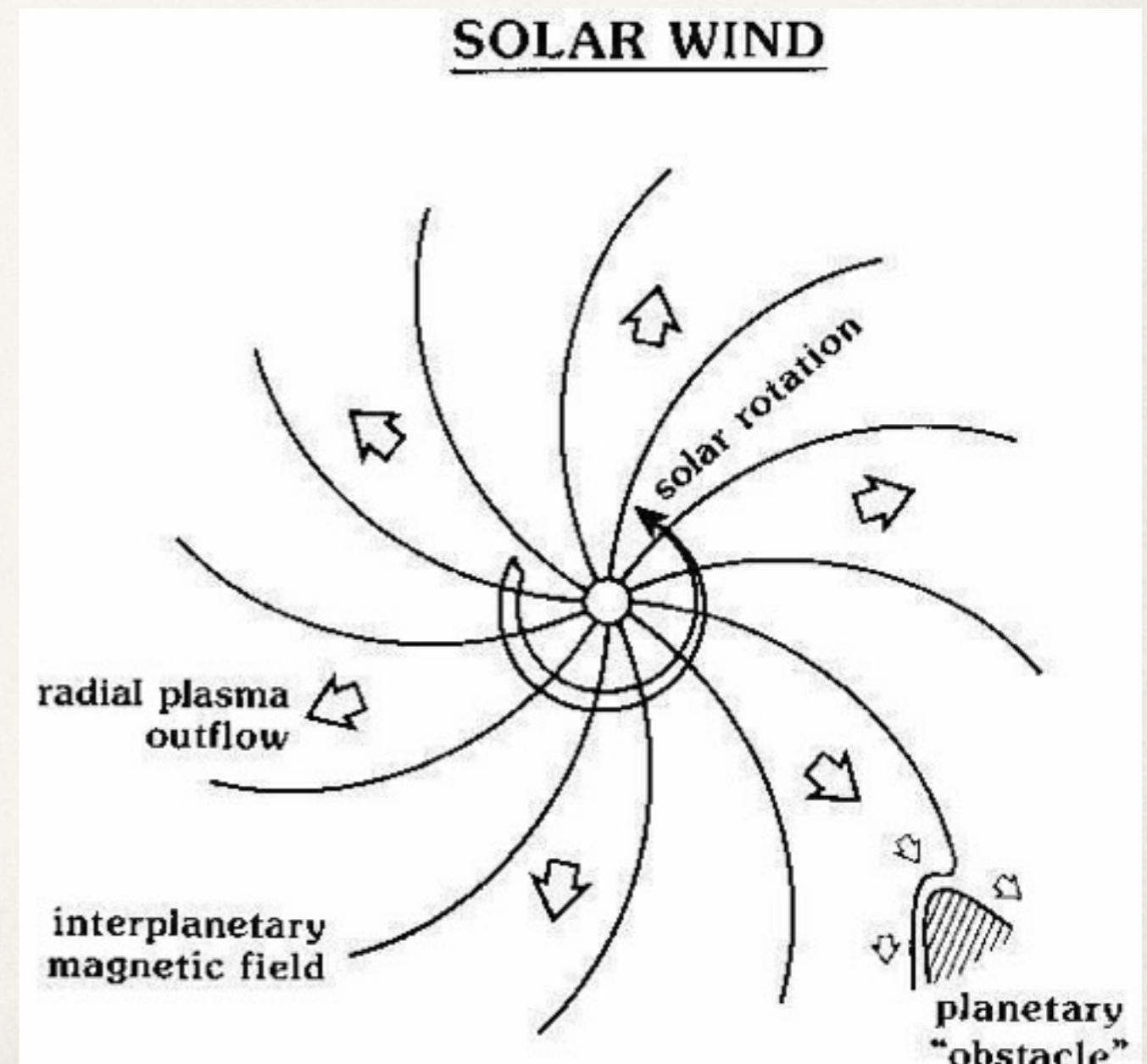
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# Parker vs Reality

## Introducing rotation

- ✿ The Parker wind speed increases with increasing temperature
- ✿ This trend is not observed, so we miss some important physics!
- ✿ First of all, **rotation**, but even more importantly...

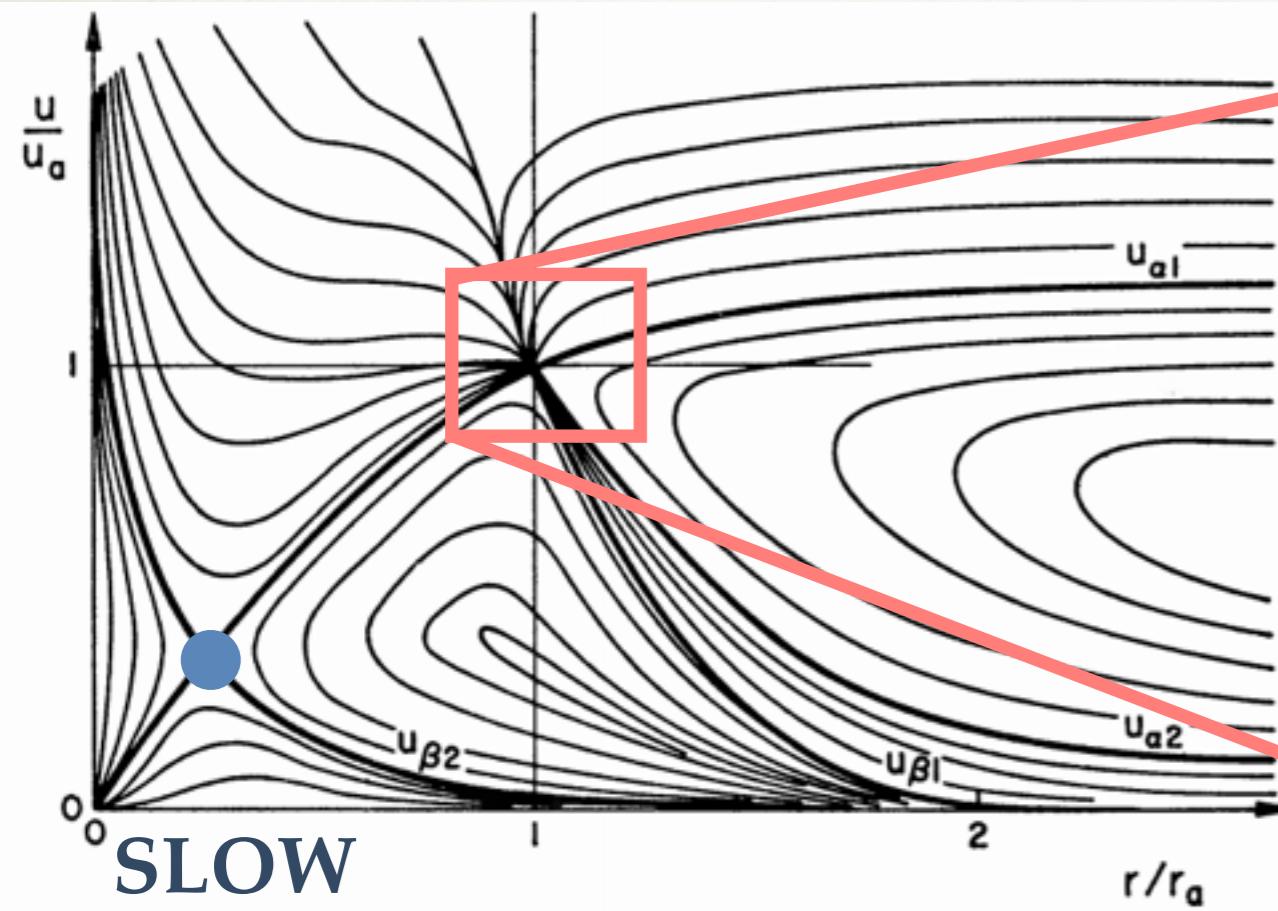


Parker's spiral

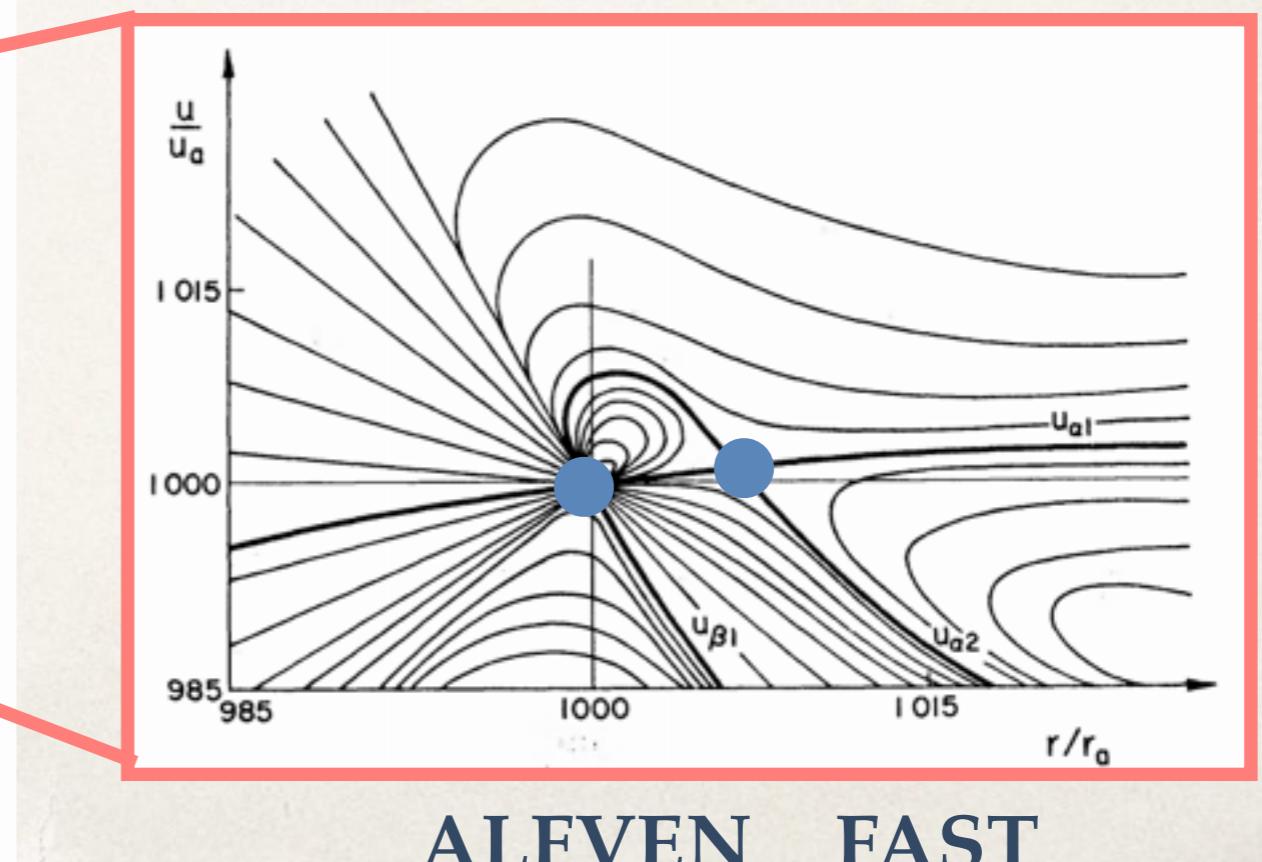
# Introducing magnetic fields

Weber & Davis 1967: 1D wind; Sakurai 1985: 2D collimated wind

- The wind equation of a MHD wind has three singular points/surfaces: SLOW, ALFVEN and FAST
- The SLOW point reduces to the sonic point when  $B=0$ .
- The rotating object has to be a **fast magnetic rotator** ( $E_0 \ll M$ ): regular stars are too slow ( $E_0 \gg M$ )!



$$E = K + T + G + M = E_0 + M$$



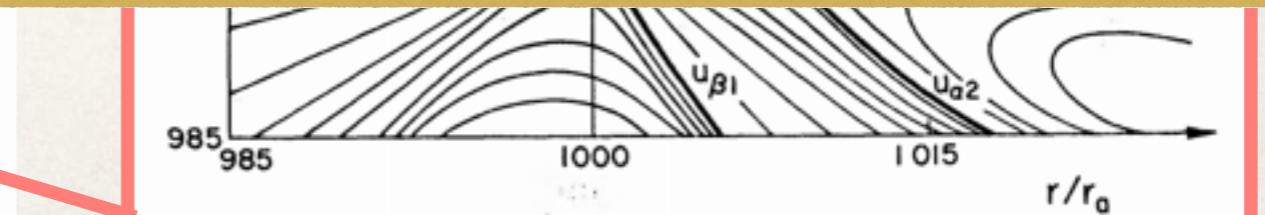
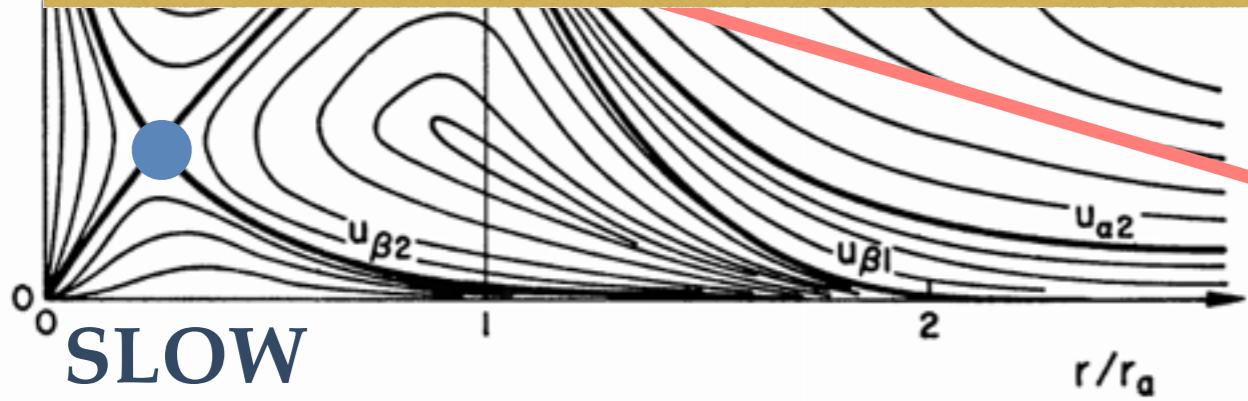
# Introducing magnetic fields

Weber & Davis 1967: 1D wind; Sakurai 1985: 2D collimated wind

## APPLICATIONS

- **AGN**: Blandford & Payne 1982, Camenzind 1986a, 1986b, Ferrari et al. 1985, 1986, Konigl 1989, Mobarrey & Lovelace 1986, Takahashi et.al. 1990 and Beskin & Par'ev 1993...
- **PULSARS**: Michel 1969, Camenzind 1989, Beskin 1993, Sulkanen & Lovelace 1990...
- **YOUNG STELLAR OBJECTS**: Pelletier 1992, Pudritz & Norman 1986, Mundt et al. 1986....

For a discussion on the meaning of the singular points: Bogovalov 1994



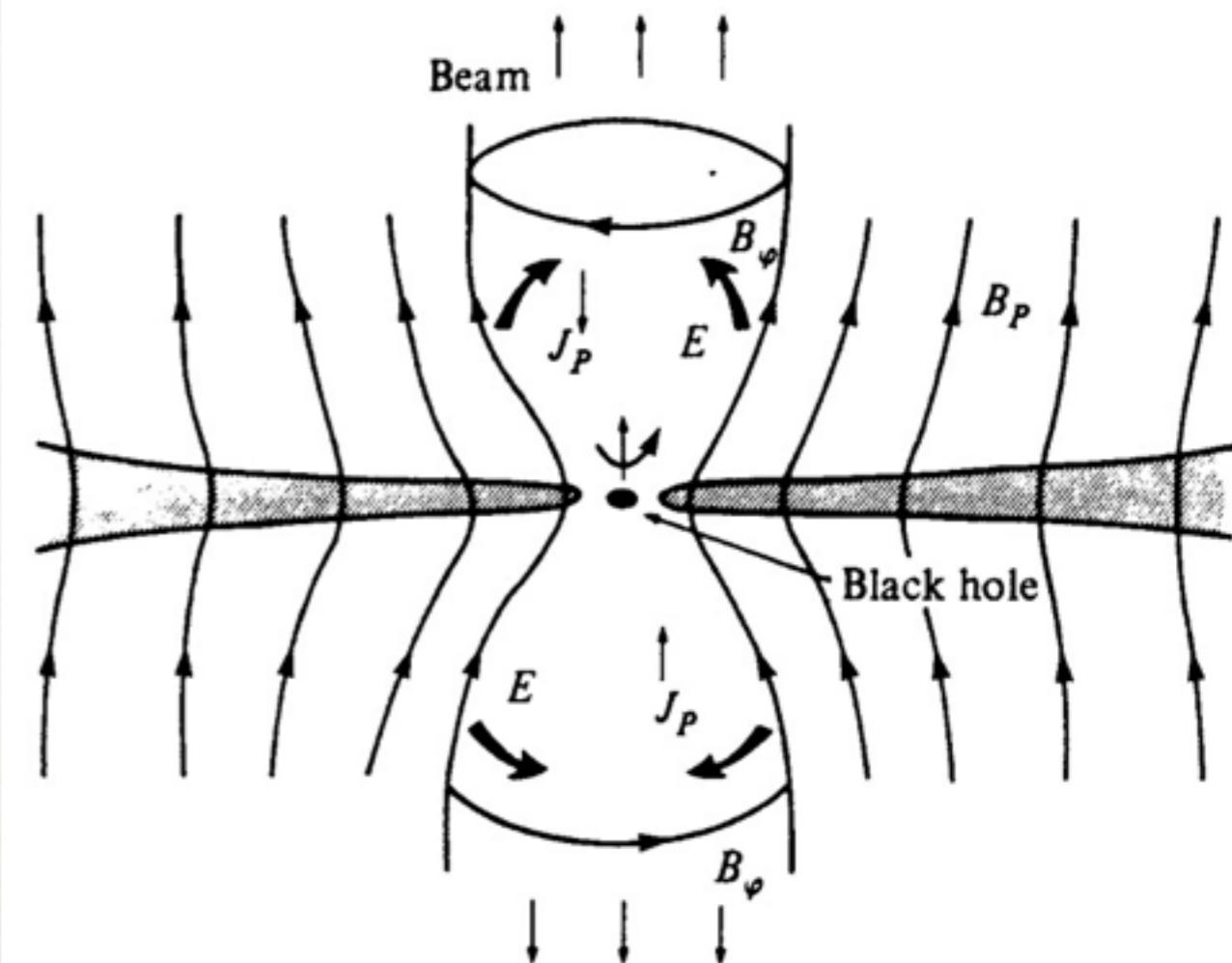
ALFVEN    FAST

# Disk-driven jets

# Blandford & Payne 1982

BP82 model describe a radial \*self-similar\* disk-driven wind/jet which is launched via magneto-centrifugal forces

- ✿ The thermal energy of the plasma is NOT taken into account, so these are **cold outflows** and they **don't cross the magnetosonic slow surface**
  - ✿ They **don't cross the magnetosonic fast surface either**



# Disk-driven jets

Background

- Heyvaerts & Norman's 1989, 2003: asymptotic analyses of rotating / magnetized outflows
- Li et al. 1992: relativistic self-similar cold MHD jets, no gravity
- Contopoulos & Lovelace 1994: different field line geometries
- Ostriker 1997: self-similar disk winds with cylindrical asymptotics
- Sauty & Tsinganos 1994: meridional self-similar MHD jets and criterion for collimation
- Vlahakis & Tsinganos 1998: construction of self-similar models of MHD outflows
- Vlahakis et al. 2000: crossing of ALL the critical surfaces, non-relativistic + gravity
- Vlahakis & Königl 2003, 2004: relativistic self-similar warm MHD jets, no gravity
- Sauty, Trussoni, Tsinganos (1994 - 2005): on analytical modelling self-similar MHD outflows
- Ferreira, Casse, Keppens, Romanova (1997, 2002, 2004, 2006): magnetized accretion-ejection structures
- Polko et al. (2010 - 2014): radial self-similar relativistic warm MHD jets with gravity crossing all the critical surfaces
- Ceccobello et al. 2018: extended parameter study of the Polko et al. eqns

# The self-similarity assumption

All the streamlines filling the space are the same: they never cross each other

---

If we know one streamline, we can build all the others. One streamline needs to cross smoothly all the three critical surfaces.

- ✿ In a spherical- or axi- symmetric system, the natural variables are the poloidal Mach number and the magnetic flux function ( $M, A$ ), which are functions of the preferred coordinate system  $(x_1, x_2)$ . i.e.  $M(x_1, x_2)$  and  $A(x_1, x_2)$ .
- ✿ ANSATZ: We want to separate the variables in such a way that, i.e.  $M = M(\chi)$ , where what  $\chi$  is is defined by the specific self-similar assumption we make. In spherical coordinates  $x_1=r, x_2=\theta$ , so we have:
  - ✿  $\chi=r$ : meridional self-similar models with spherical critical surfaces
  - ✿  $\chi=\theta$ : radial self-similar models with conical critical surfaces

# The self-similarity assumption

All the streamlines filling the space are the same: they never cross each other

---

If we know one streamline, we can build all the others. One streamline needs to cross smoothly all the three critical surfaces.

- \* In a spherical- or axi- symmetric system, the natural variables are the radial coordinate  $r$ , the polar angle  $\theta$  and the azimuthal angle  $\phi$ . When the problem is reduced to 1D, the critical surfaces are POINTS on a streamline and, *because of the self-similar assumption*, the locations of the slow and fast magneto sonic points are not coincidental with the classical ones, so they are called “modified” slow/fast points.

make. In spherical coordinates  $x_1=r$ ,  $x_2=\theta$ , so we have:

- \*  $\chi=r$ : meridional self-similar models with spherical critical surfaces
- \*  $\chi=\theta$ : radial self-similar models with conical critical surfaces

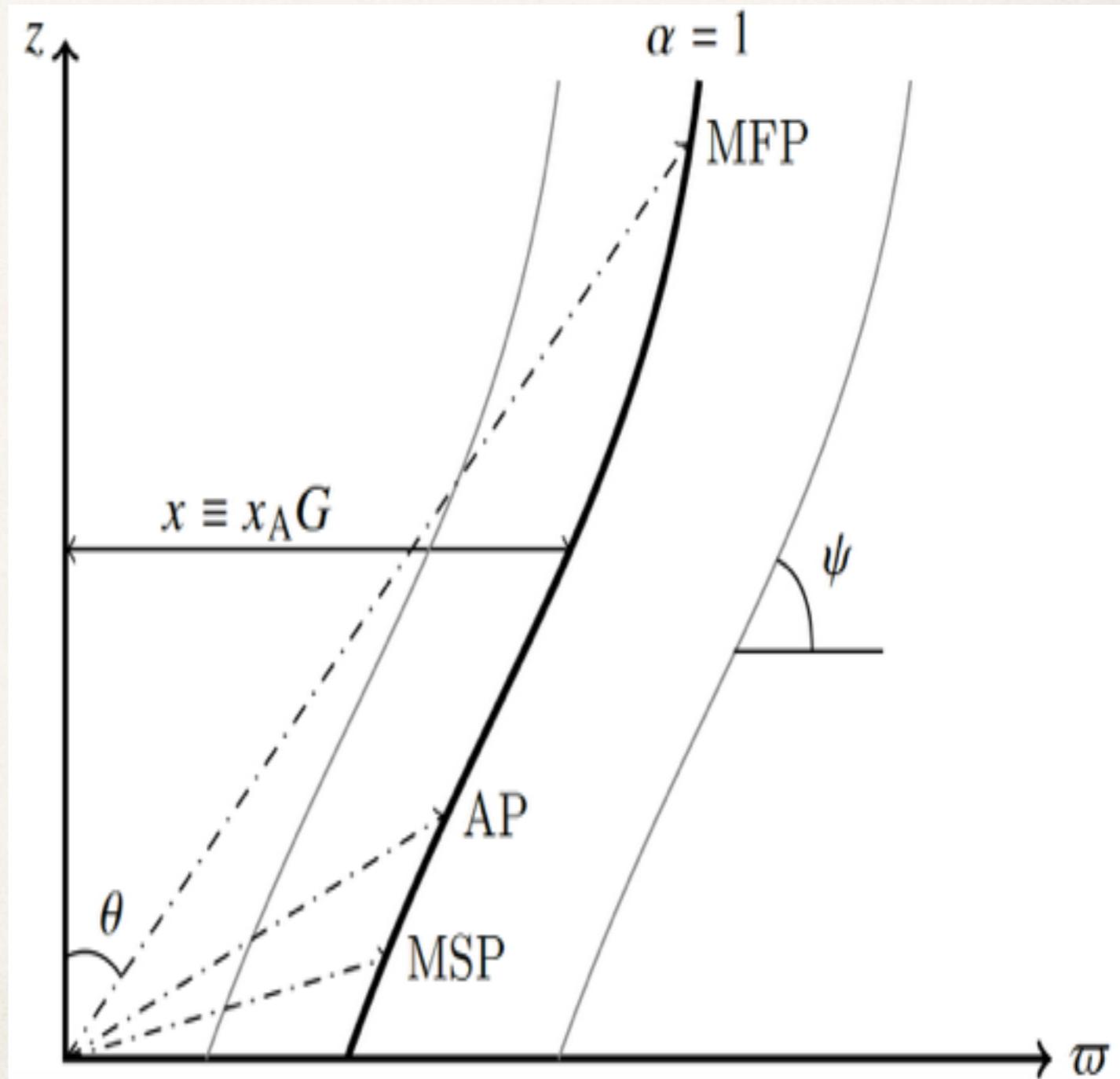
# NRMHD

Vlahakis et al. 2000, Ceccobello et al. in prep.

# RMHD

Vlahakis & Königl, 2003; Polko et al. 2010, 2013, 2014;  
Ceccobello et al. 2018

- The non-relativistic and relativistic set of equations described in the papers listed above include **gravity** and **thermal energy** of the plasma, therefore they describe **warm/hot disk-driven jets with different velocities**
- The most recently found **solutions** of both problems are **all crossing smoothly the three singular points** and cover large volumes of the parameter space



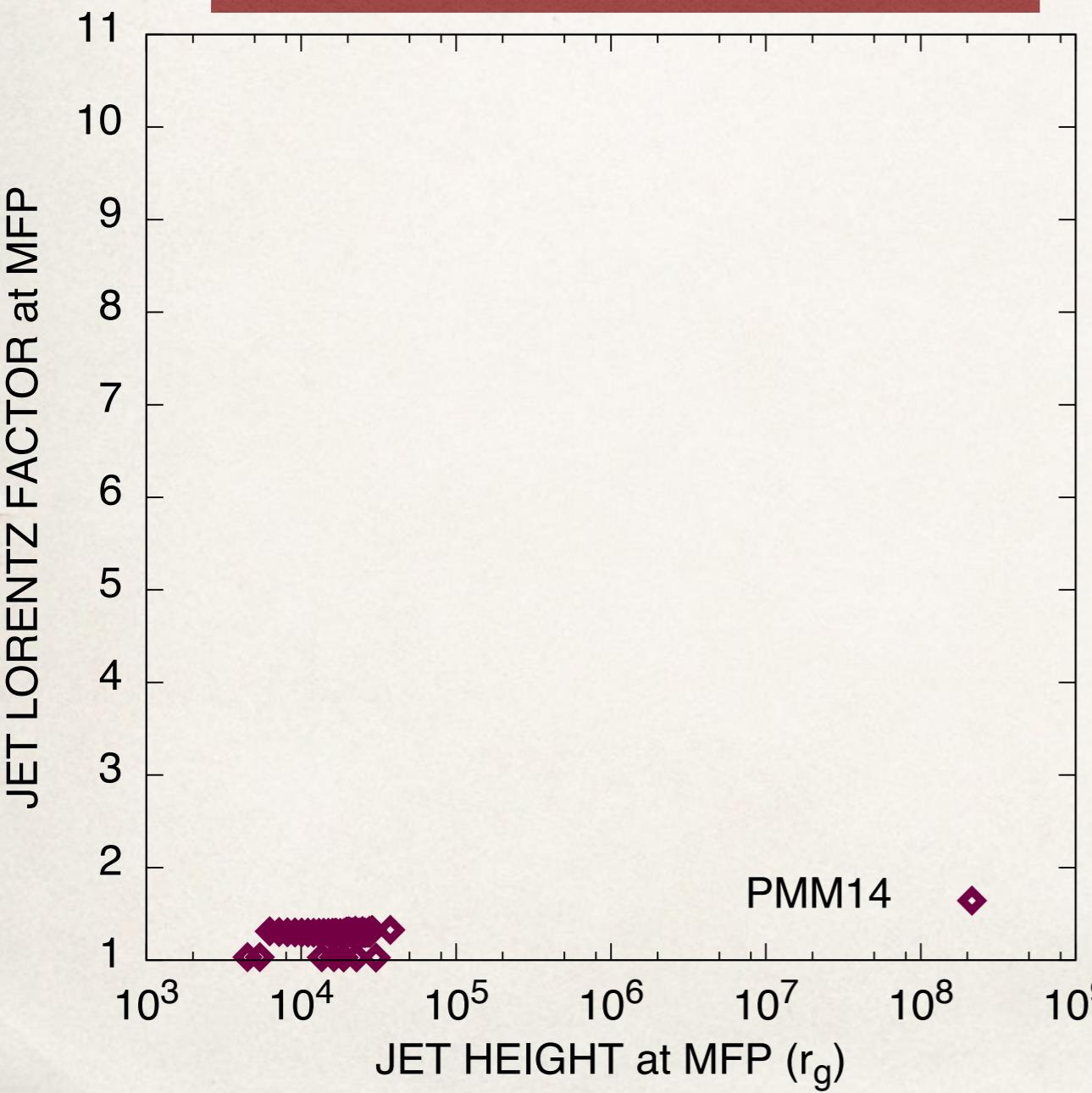
# NRMHD

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# RMHD

Vlahakis & Königl, 2003; Polko et al. 2010,2013,2014;  
Ceccobello et al. 2018

# INTEGRATING TOWARDS UNKNOWN SINGULARITIES



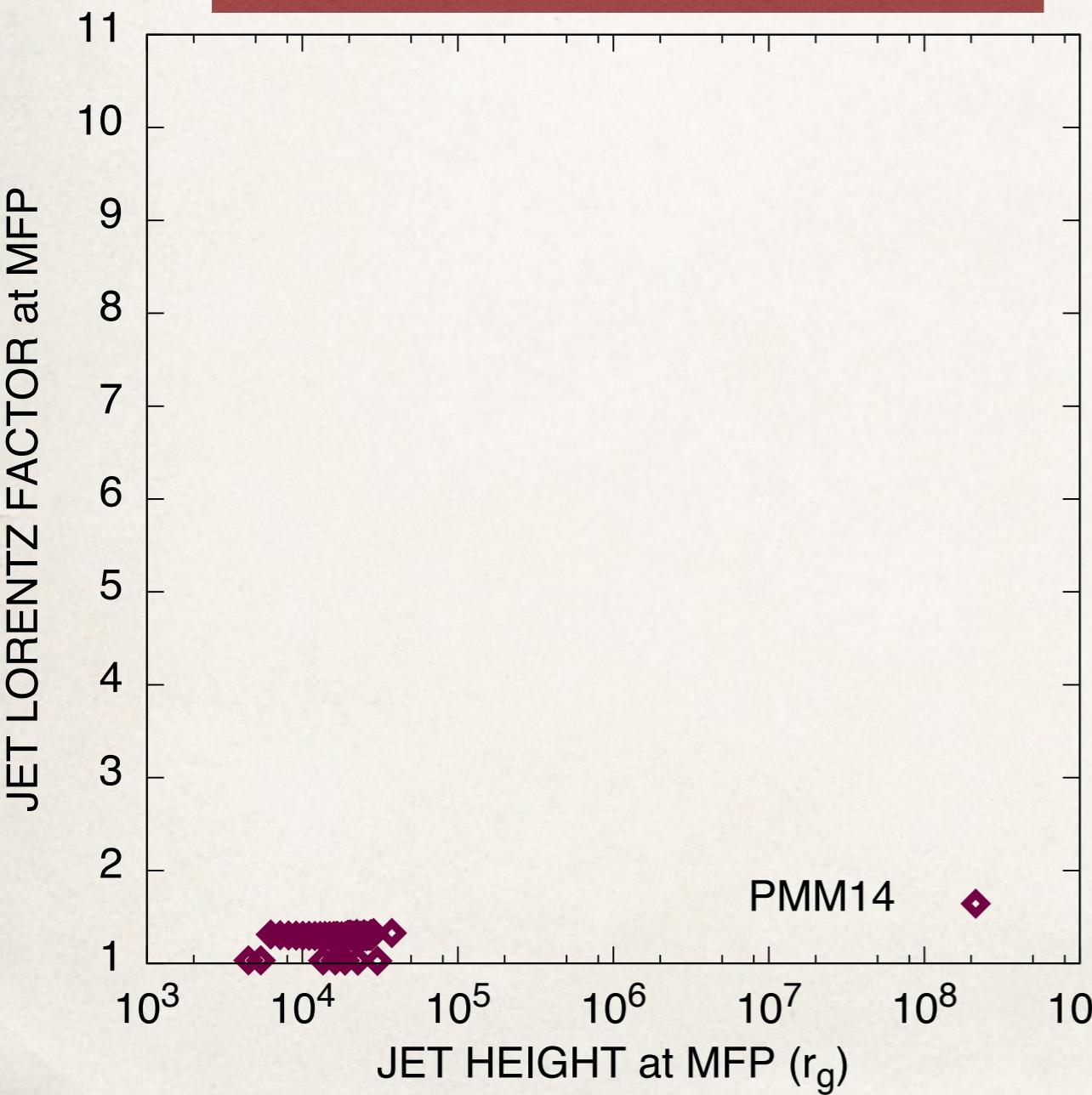
# NRMHD

Vlahakis et al. 2000, Ceccobello et al. in prep.

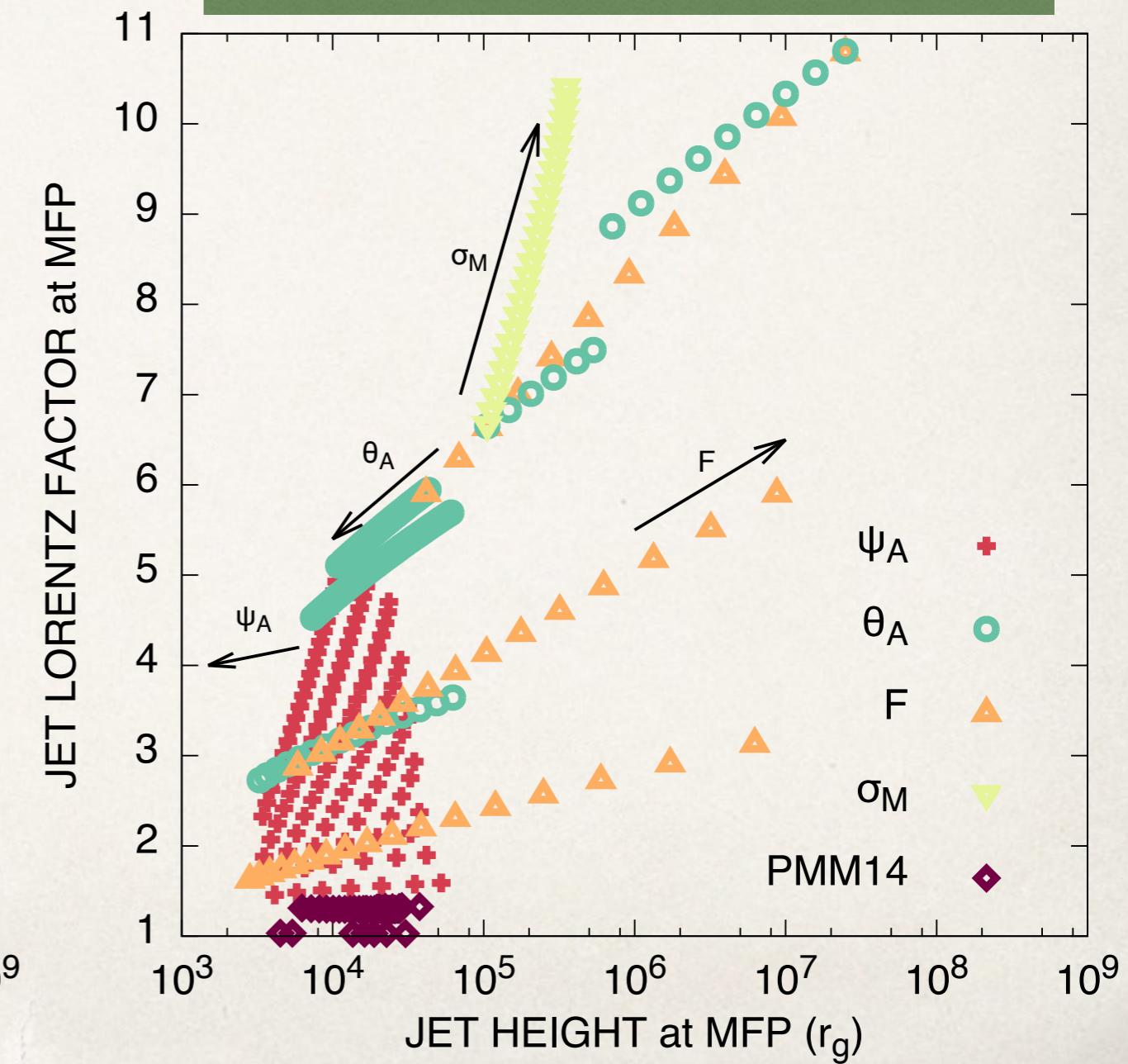
# RMHD

Vlahakis & Königl, 2003; Polko et al. 2010, 2013, 2014;  
Ceccobello et al. 2018

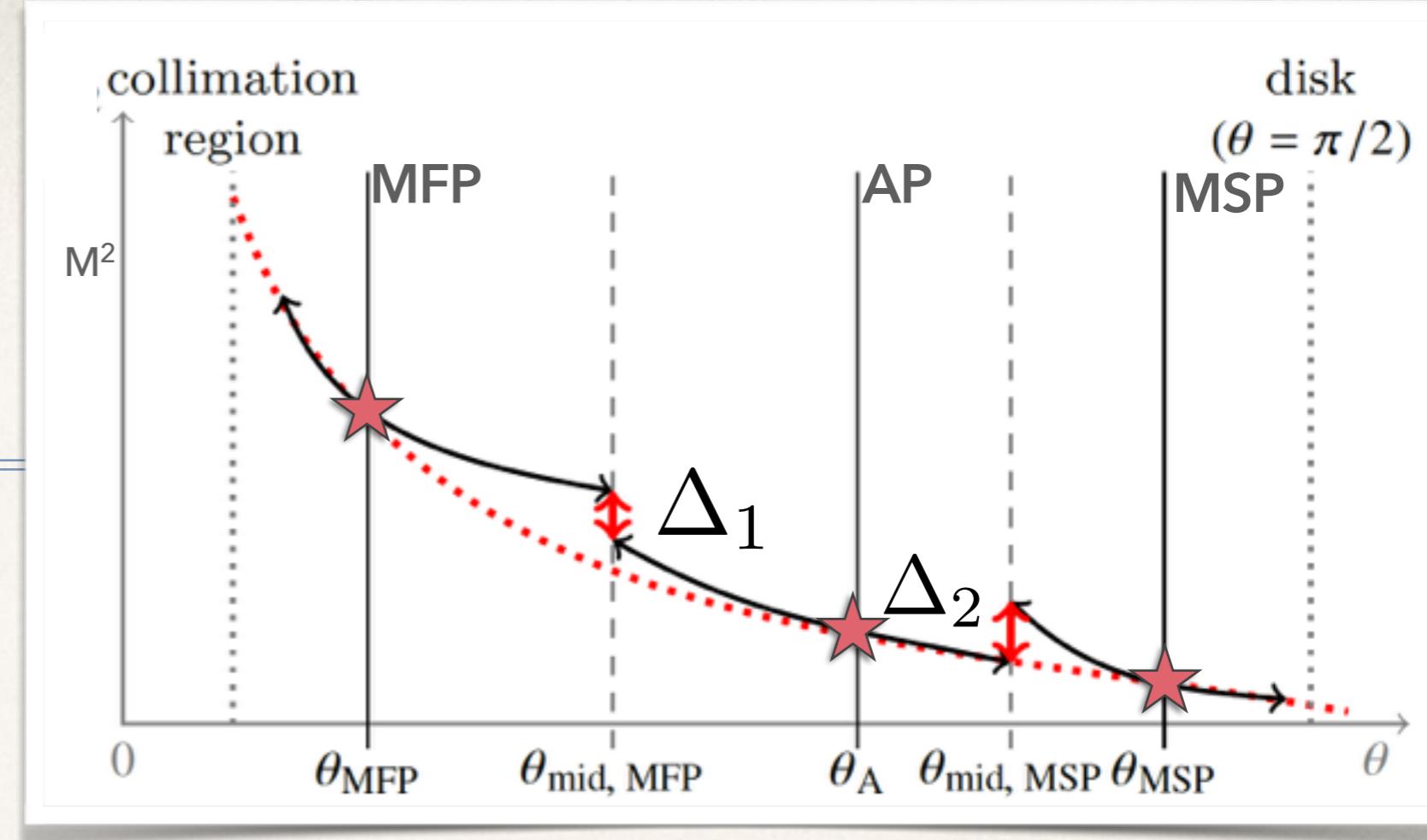
## INTEGRATING TOWARDS UNKNOWN SINGULARITIES



## INTEGRATING AWAY FROM UNKNOWN SINGULARITIES



# The method



- We guess  $\theta_{\text{MSP}}$  and  $\theta_{\text{MFP}}$  and derive values for  $M^2, G^2$  and their derivatives which satisfy the condition that 
$$\left. \frac{dM^2}{dr} \right|_* = \frac{0}{0}$$
- We integrate away from AP, MSP and MFP towards the midpoints and upstream of MSP and downstream of MFP
- We use **MultiNest** to minimise the offsets at the midpoints to finally find the best set of parameters to describe a given solution.

\* = MSP or MFP

$$\begin{aligned}
\frac{dM^2}{d\theta} = & -2 \frac{\sin(\theta + \psi)}{\cos(\theta + \psi)} \left\{ -\frac{k_{\text{VTST}}^2 \sin \theta}{G} - \mu_{\text{VTST}}(F - 2) M^{4-2\Gamma} \right. \\
& + \frac{M^4}{G^4} (1 - M^2) \frac{\cos \psi \sin \theta}{\sin(\theta + \psi)} - \frac{M^4}{G^4} (F - 2) \frac{\sin^2 \theta}{\cos^2(\theta + \psi)} \\
& - \lambda_{\text{VTST}}^2 \frac{M^4}{G^2} (F - 2) \left( \frac{1 - G^2}{1 - M^2} \right) + \lambda_{\text{VTST}}^2 \frac{M^2}{G^2} \frac{G^4 - M^2}{1 - M^2} \\
& \left. - \lambda_{\text{VTST}}^2 \frac{\cos \psi}{\sin \theta \sin(\theta + \psi)} \frac{(2M^2 - 1)G^4 - M^4}{G^2(1 - M^2)} \right\} \\
& \times \left\{ \Gamma \mu_{\text{VTST}} (1 - M^2) M^{-2\Gamma} - 2\lambda_{\text{VTST}}^2 \frac{M^2}{G^2} \left( \frac{1 - G^2}{1 - M^2} \right)^2 \right. \\
& \left. + 2 \frac{M^4 \sin^2 \theta}{G^4} \left( 1 - \frac{1}{M^2 \cos^2(\theta + \psi)} \right) \right\}^{-1}
\end{aligned}$$

radial  
 self-similar  
 NRMHD  
 WIND  
 EQUATION  
 for warm jets  
 with gravity

$$\frac{dG^2}{d\theta} = \frac{2 G^2 \cos \psi}{\sin \theta \cos(\theta + \psi)}$$

equation for the cylindrical radius of the streamline

Alfven Regularity Condition

$$\begin{aligned}
& (F - 2)(4\lambda_{\text{VTST}}^2 + p_\star^2 \sin^2 \theta_\star) \tan^2(\theta_\star + \psi_\star) \\
& + (F - 2) \left( \mu_{\text{VTST}} p_\star^2 + p_\star^2 \sin^2 \theta_\star + \frac{4\lambda_{\text{VTST}}^2}{\tan^2 \theta_\star} \right) \\
& + \left( p_\star^3 \sin^2 \theta_\star + 4\lambda_{\text{VTST}}^2 p_\star + 8\lambda_{\text{VTST}}^2 \frac{F - 2}{\tan \theta_\star} \right) \tan(\theta_\star + \psi_\star) \\
& + k_{\text{VTST}}^2 p_\star^2 \sin \theta_\star - \lambda_{\text{VTST}}^2 p_\star \left( p_\star - \frac{4}{\tan \theta_\star} \right) = 0
\end{aligned}$$

# Exercise #1

---

## Integration of the Parker wind equation

**Check out the python notebook: parker.ipynb**

USE:

**\$ python -m jupyter notebook --no-browser --ip=000.000.00.00 --port=8890**

The number in ip has to be changed into the IP of your VM

# MultiNest

---

# Bayesian Inference

---

$$\begin{aligned} \text{Likelihood} \times \text{Prior} &= \text{Evidence} \times \text{Posterior} \\ L(\theta) \times \pi(\theta)d\theta &= Z \times p(\theta)d\theta \end{aligned}$$

- ✿ The **prior distribution** is the distribution of the parameter(s) before any data is observed
- ✿ The sampling distribution or **likelihood** is the distribution of the observed data conditional on its parameters
- ✿ The **posterior distribution** is the distribution of the parameter(s) after taking into account the observed data
- ✿ The **marginal likelihood (or evidence)** is the distribution of the observed data *marginalized* over the parameter(s)

# Bayesian Inference

---

- ❖ **Parameter estimation:** often we use bayesian inference to obtain the posterior distribution of one or more parameters that better explains the observed data. In this case, **the marginal likelihood is only a normalisation and can be neglected**

$$\text{posterior} \propto \text{likelihood} \times \text{prior}$$

- ❖ **Model selection:** we have to choose between two models on the basis of observed data D, the plausibility of the two different models  $H_0$  and  $H_1$ , parametrised by model parameter vectors,  $\Theta_0$  and  $\Theta_1$ , is assessed by the **Bayes factor K** given by

$$\frac{\text{posterior of } H_1}{\text{posterior of } H_0} = \frac{\text{marginal likelihood of } H_1 \times \text{prior of } H_1}{\text{marginal likelihood of } H_0 \times \text{prior of } H_0}$$

# Bayesian Inference

- ✿ **Parameter estimation:** often we use bayesian inference to estimate the posterior distribution of one or more parameters that are not directly observed. In this case, **the marginal likelihood is very small and can be neglected**

Markov Chain  
Monte Carlo  
Nested Sampling

posterior  $\propto$  likelihood x prior

- ✿ **Model selection:** we have to choose between two models H<sub>0</sub> and H<sub>1</sub>. Given observed data D, the plausibility of the two different models, parametrised by model parameter vectors, Θ<sub>0</sub> and Θ<sub>1</sub>, is assessed by the Bayes factor K given by

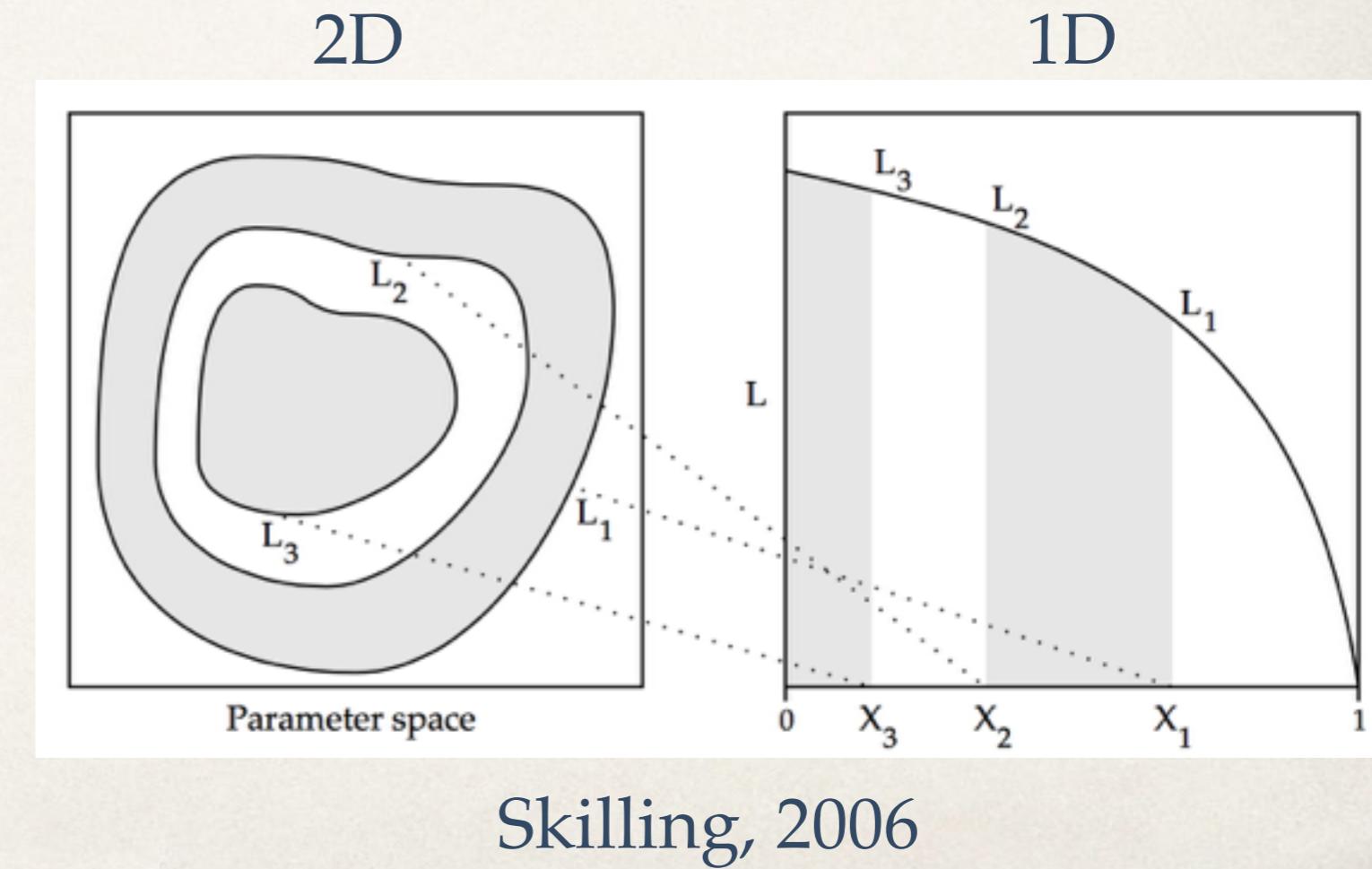
$$K = \frac{\text{posterior of } H_1}{\text{posterior of } H_0} = \frac{\text{marginal likelihood of } H_1 \times \text{prior of } H_1}{\text{marginal likelihood of } H_0 \times \text{prior of } H_0}$$

# Nested Sampling (Skilling, 2004)

## Still a Monte Carlo technique, but....

$$\begin{aligned} \text{Likelihood} \times \text{Prior} &= \text{Evidence} \times \text{Posterior} \\ L(\theta) \times \pi(\theta)d\theta &= Z \times p(\theta)d\theta \end{aligned}$$

- \* Problem: when the dimension of  $\theta$  is high, the calculation of the evidence is challenging, but needed especially for model comparison problems.



# Nested Sampling (Skilling, 2004)

## Still a Monte Carlo technique, but....

$$Z = \int L(\theta) \pi(\theta) d\theta$$

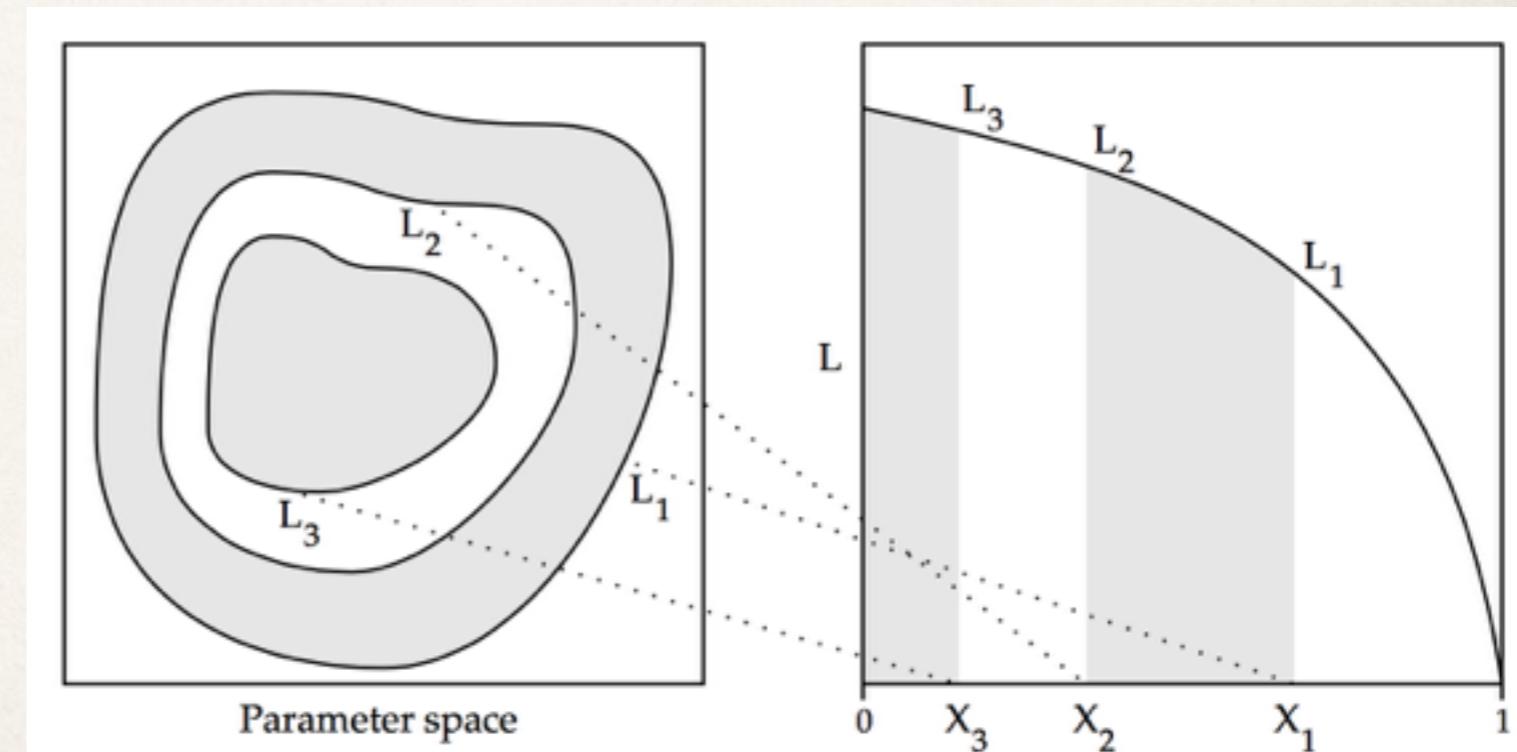
$X$  is the amount of prior probability with likelihood greater than  $\lambda$ .

Roughly,  $X$  is the volume with likelihood above  $\lambda$ .

$$dX = \pi(\theta) d\theta$$

$$X(\lambda) = \int_{L(\theta) > \lambda} \pi(\theta) d\theta$$

$$Z = \int_0^1 L(X) dX$$



Skilling, 2006

# Nested sampling: pros and cons

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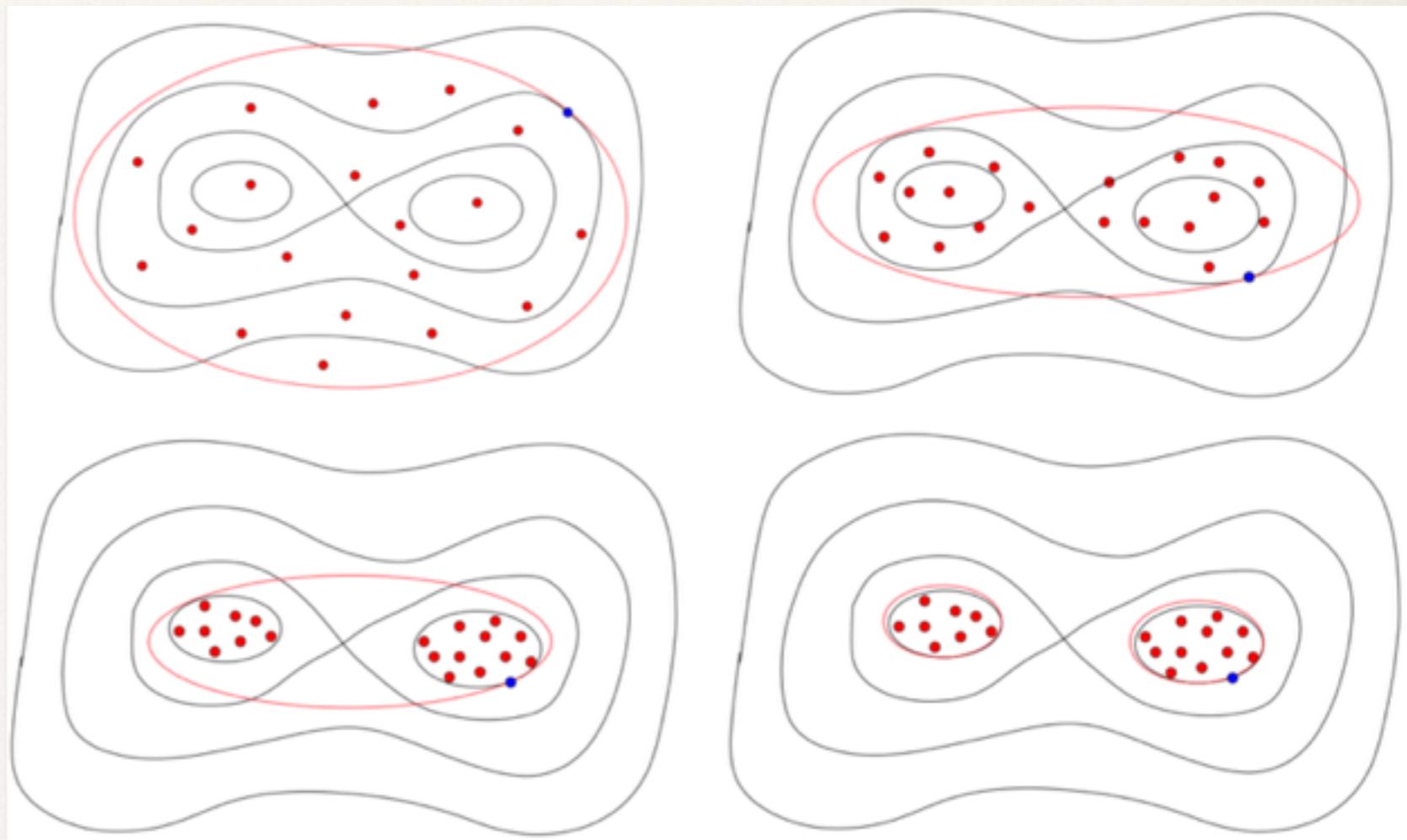
- ✿ Nested sampling is good for irregular likelihood landscapes and more efficient than MCMC, but it's still not enough...
- ✿ There is still the risk of not finding the global maximum.
- ✿ If sampling the space uniformly in a high dimensional problem, it can be slow.

# MultiNest

Feroz & Hobson 2008; Feroz et al. 2009, 2013

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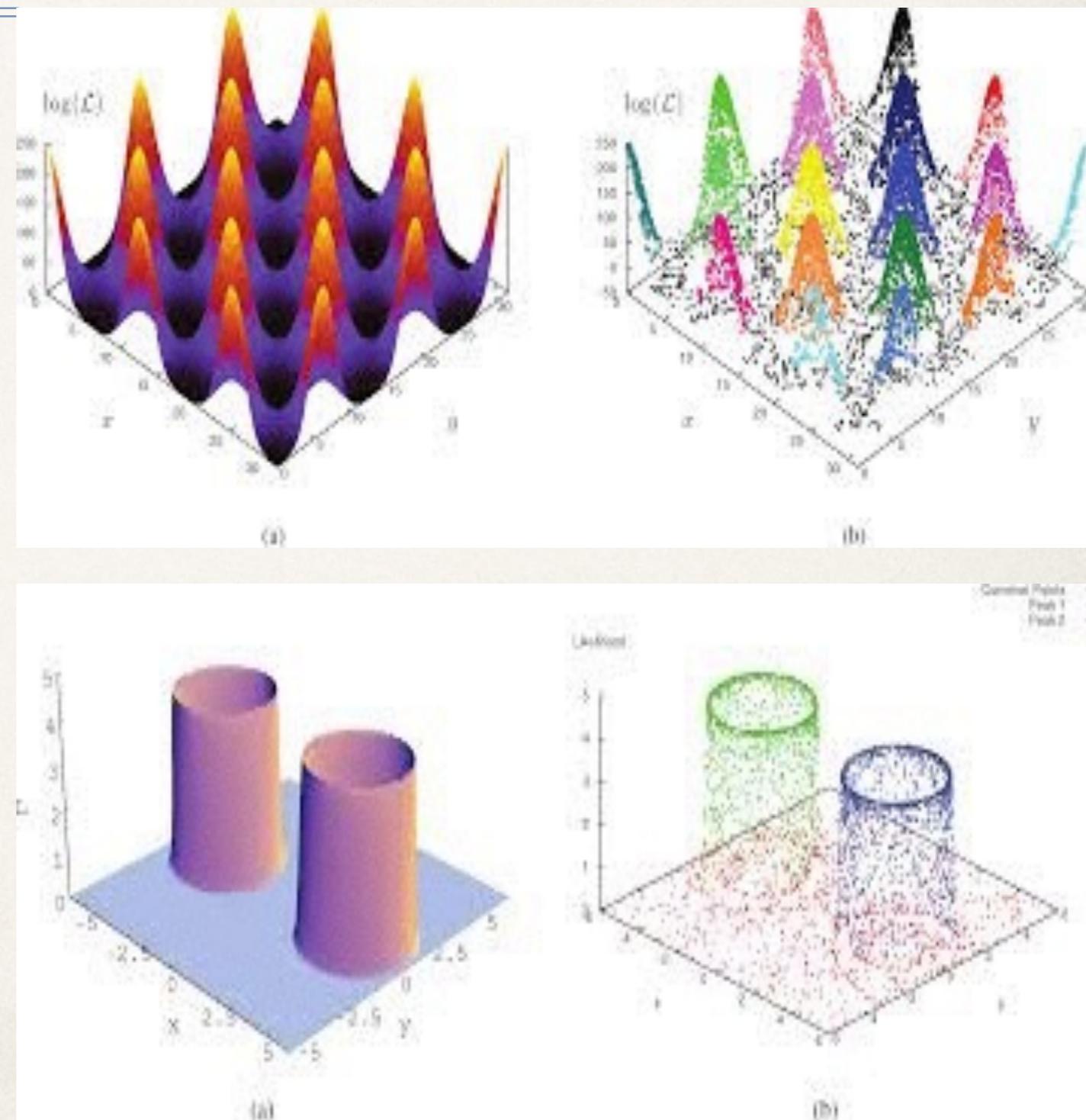
- ❖ Solid algorithm for multi-modal likelihood landscapes
- ❖ Instead of using a multi-dimensional uniform prior for each replacement point, use an n-dimensional ellipsoid for resampling



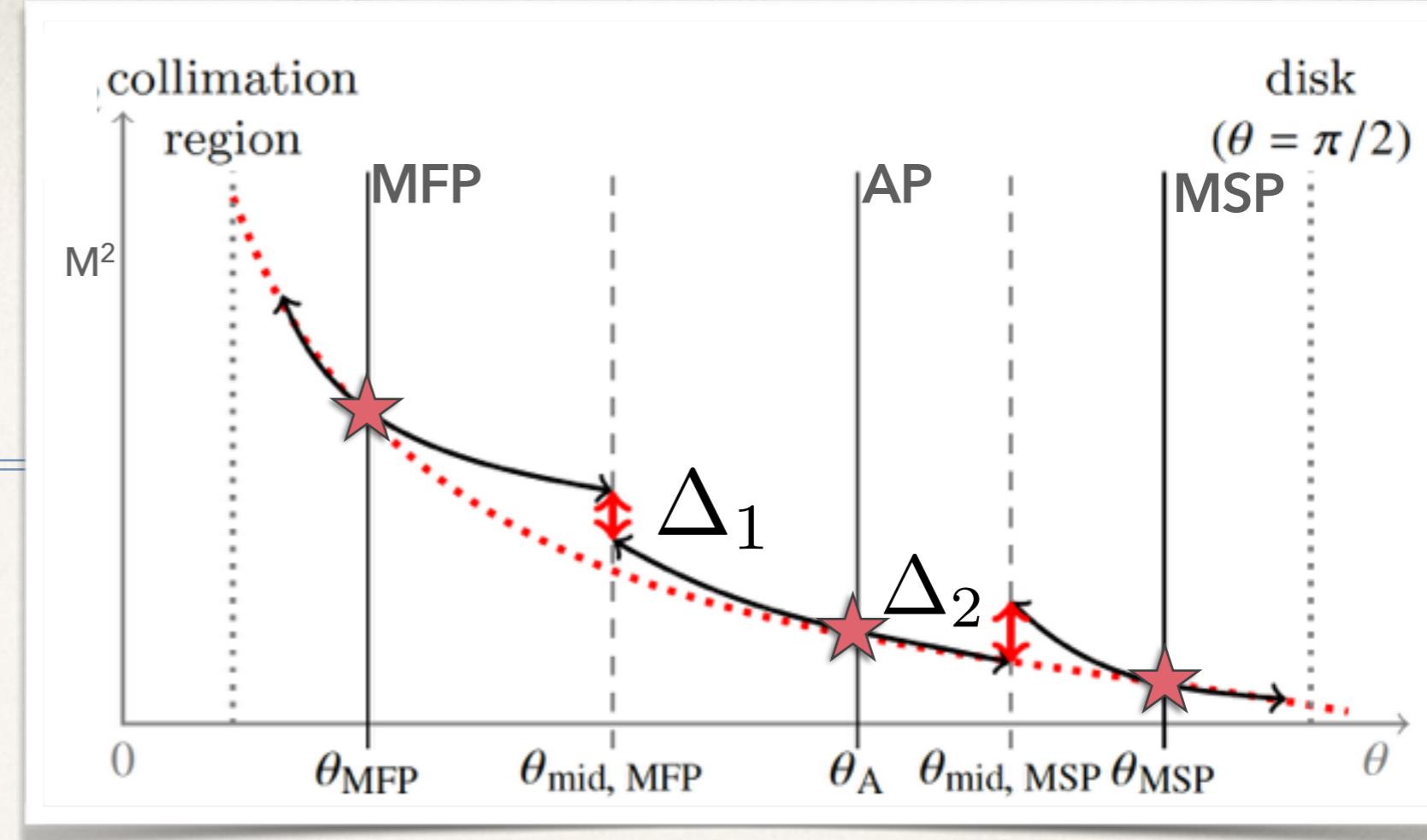
# MultiNest

Feroz & Hobson 2008; Feroz et al. 2009, 2013

Disjoint regions as well as multi-dimensional multi-modal regions can be found efficiently without continual resampling of the whole space.



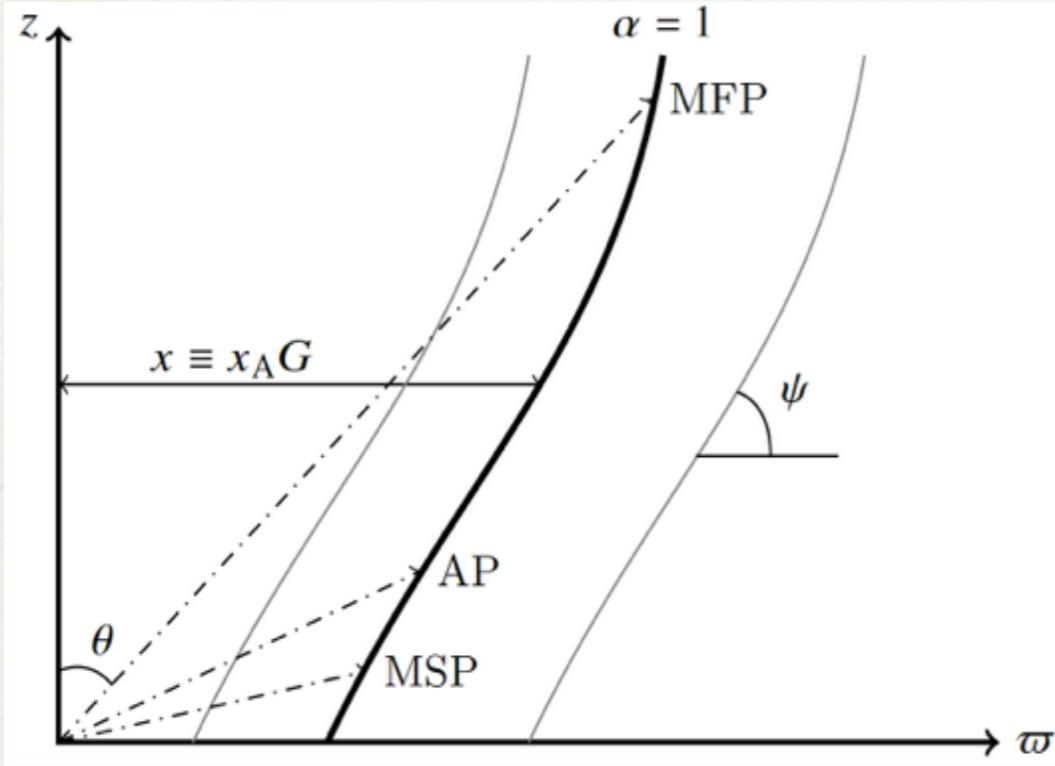
# The method



- We guess  $\theta_{\text{MSP}}$  and  $\theta_{\text{MFP}}$  and derive values for  $M^2, G^2$  and their derivatives which satisfy the condition that 
$$\left. \frac{dM^2}{dr} \right|_* = \frac{0}{0}$$
- We integrate away from AP, MSP and MFP towards the midpoints and upstream of MSP and downstream of MFP
- We use **MultiNest** to minimise the offsets at the midpoints to finally find the best set of parameters to describe a given solution.

\* = MSP or MFP

# Fitted parameters and fitness function in the NRMHD problem

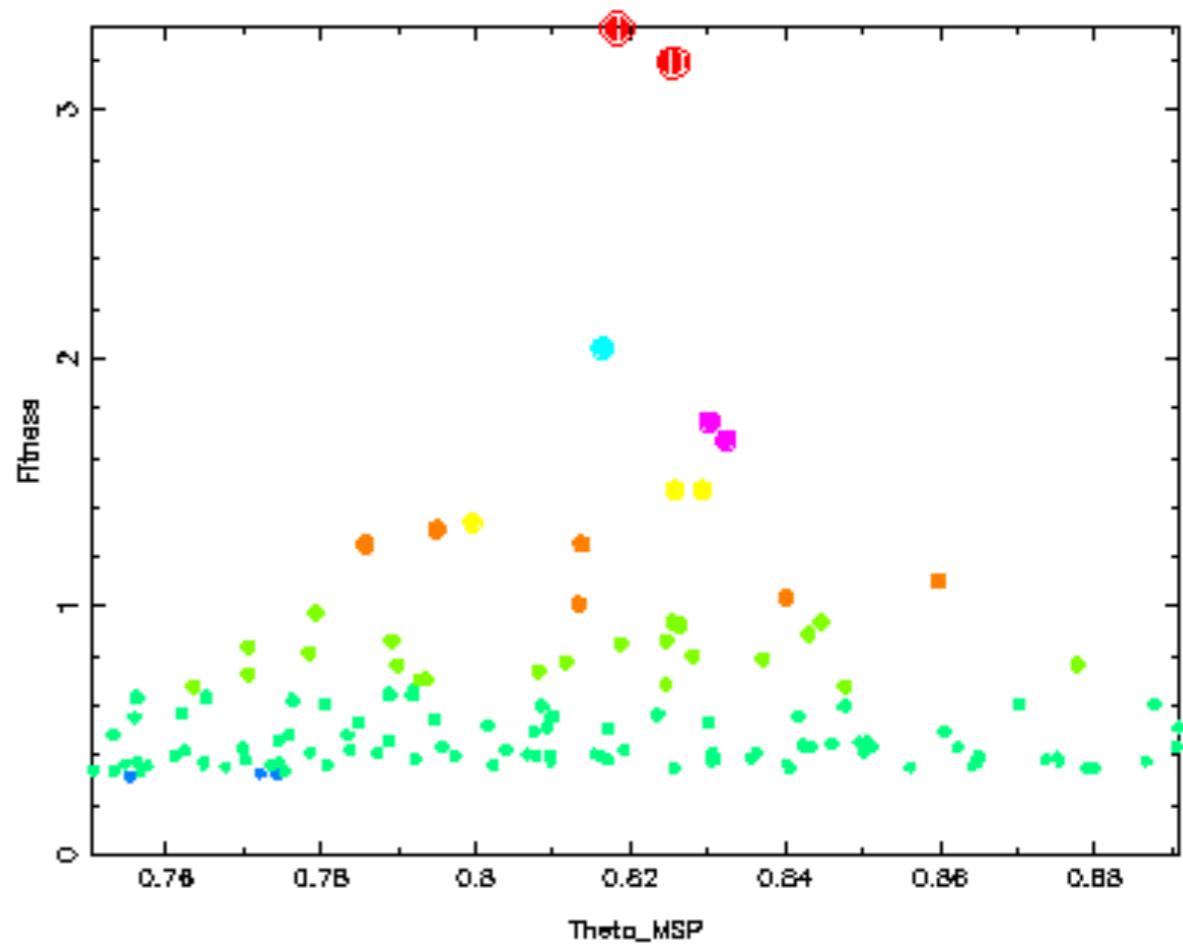
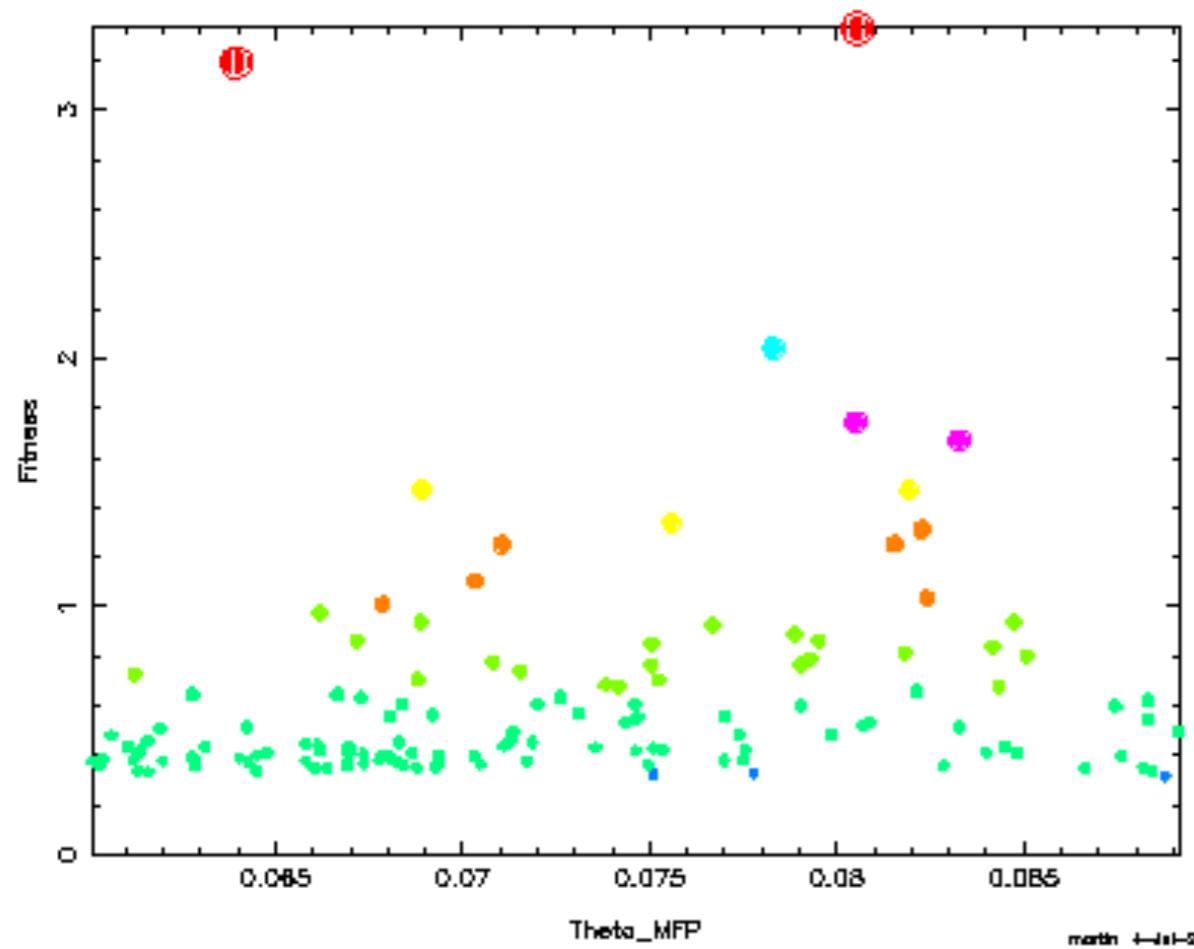
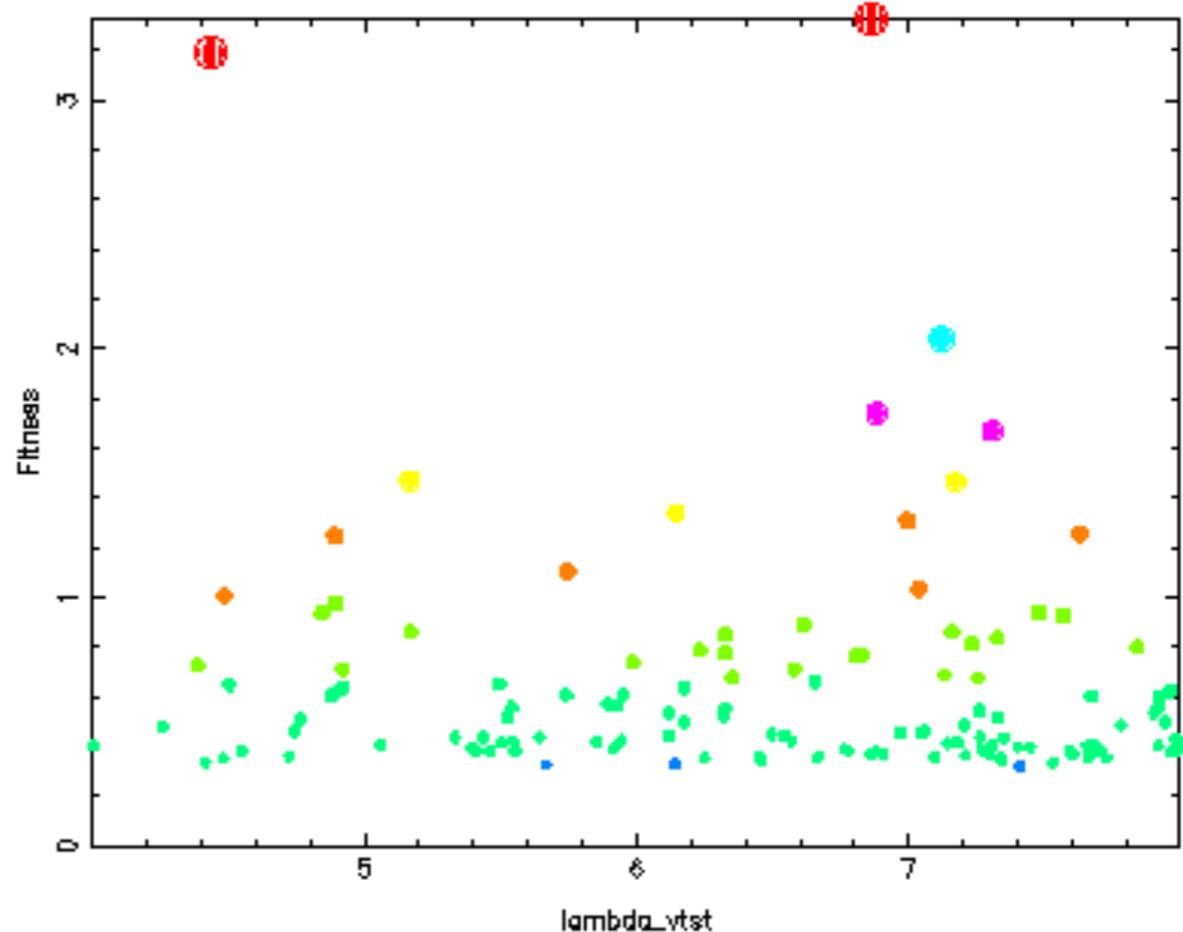
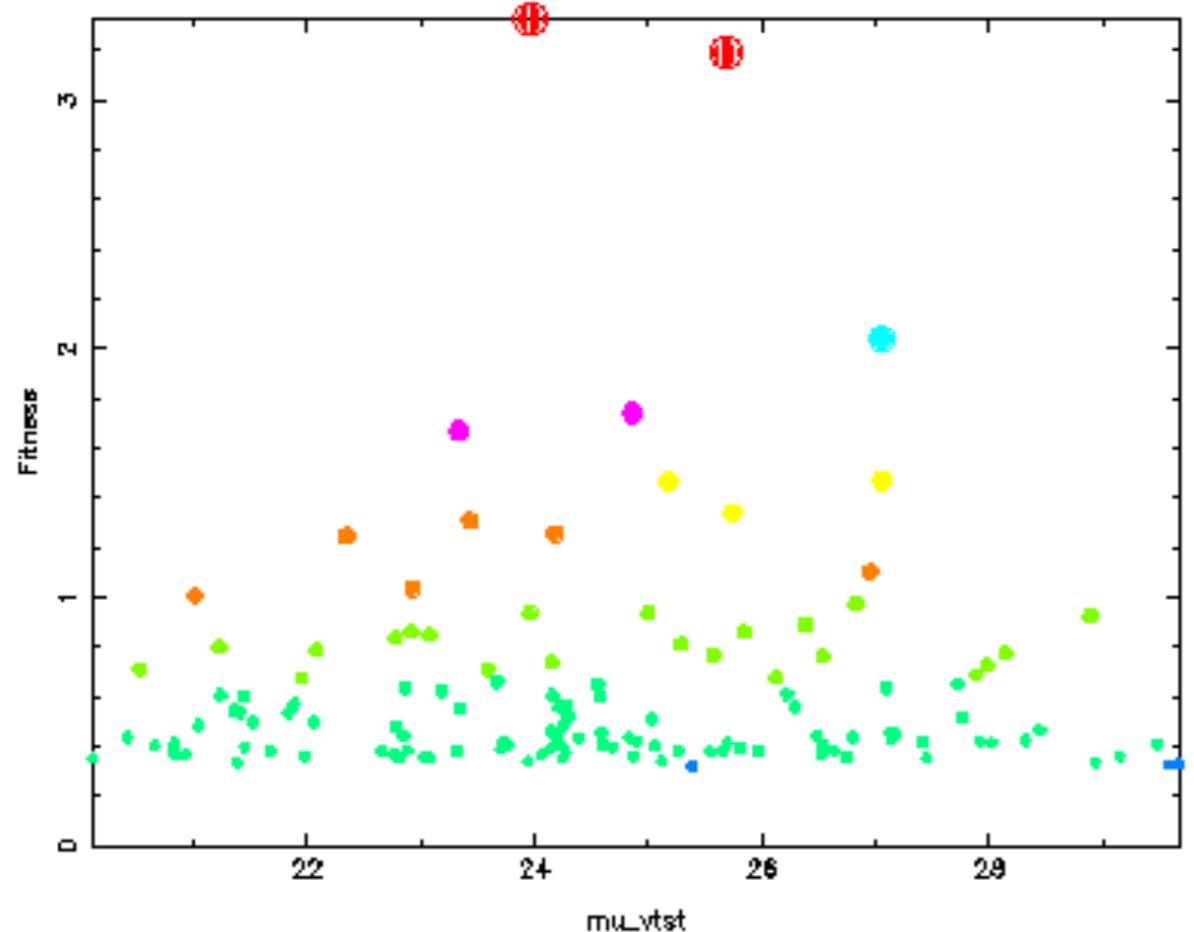


$$\mathcal{F} = [f_{G,F}^2 + f_{M,F}^2 + f_{G,S}^2 + f_{M,S}^2]^{-1/2}$$

$$f_{G,*} = \frac{2(G_L^2 - G_R^2)}{(G_L^2 + G_R^2)} \Big|_{\theta_{\text{mid},*}}$$

$$f_{M,*} = \frac{2(M_L^2 - M_R^2)}{(M_L^2 + M_R^2)} \Big|_{\theta_{\text{mid},*}}$$

Input parameters	
$F$	determines the shape of the magnetic field at the base
$\Gamma$	polytropic index of the gas
$\theta_*$	angular distance of the AP from the jet axis
$\psi_*$	inclination of the stream line with respect to the horizontal axis at the AP
$k_{\text{VTST}}$	mass loss parameter at AP
Fitted parameters	
$\theta_{\text{MFP}}$	angular distance of MFP from the jet axis
$\theta_{\text{MSP}}$	angular distance of MSP from the jet axis
$\mu_{\text{VTST}}$	scaling of the plasma- $\beta$ at AP
$\lambda_{\text{VTST}}$	specific angular momentum in units of $V_* \varpi_*$



# Exercise #2

---

MultiNest: optimization of the parameters

# How to run the NRMHD code: I

## Setting the parameters and boxes and compile

- ✿ \$ cd Multinest/Code/
- ✿ Open the file **params.f90** with your favourite editor (VIM, EMACS, etc.) and set **next\_maxIter = 100**
- ✿ Open the file **main.f90** and set the intervals for the input parameters as in the table →
- ✿ \$ ./Compile-mhd %this will create a mhd.exe file one folder above. Every time you change one of the files in Code, you **need to run** this command **again** and create a new exe file

	main.f90
$\mu_{\text{VTST}}$	20.0 - 30.0
$\lambda_{\text{VTST}}$	1 - 8
$\theta_{\text{MFP}}$	0,06 - 0,08
$\theta_{\text{MSP}}$	0,75 - 0,90

# How to run the NRMHD code: II

## Running the code and check the best fit (so far)

---

- ✿ \$ cd ..
- ✿ \$ ./mhd.exe >> mhd.log %while running the code, you are writing a log file and every time you run it again, it will append the new results after the old ones.
- ✿ \$ fgrep Fit\_ness mhd.log | sort -g -k 3 > fitness\_XXX.log %takes all the fitness values from the log file, sort them in increasing order and place them in the file fitness\_XXX.log . Remember to change the XXX in fitness\_XXX.log each run!
- ✿ \$ tail fitness\_XXX.log %only shows the end of the file where the highest fitness solution is.
- ✿ **Repeat all the steps so far a few times, e.g. 5, to get solutions with increasing fitness.**

# How to run the NRMHD code: III

Prepare a run with more iterations to find a **true solution** for comparison

---

- ✿ \$ cd Multinest/Code/
- ✿ Open the file **params.f90** with a text editor (VIM, EMACS, etc.) and set **next\_maxIter = 5000**
- ✿ \$ ./Compile-mhd %this will create a mhd.exe file one folder above. Every time you change one of the files in Code, you **need to run** this command **again** and create a new exe file

# How to run the NRMHD code: IV

## Running the code and check the best fit

---

- ✿ \\$ cd ..
- ✿ \\$ rm Chains/\* %to clean the results of the last run in case something went wrong before restarting a new run
- ✿ \\$ ./mhd.exe >> mhd\_true.log %while running the code, you are writing a log file and every time you run it again, it will append the new results after the old ones. You can run this in the background by adding the character & to the command as ./mhd.exe >> mhd\_true.log &
- ✿ \\$ fgrep Fit\_ness mhd\_true.log | sort -g -k 3 > fitness\_true.log %takes all the fitness values from the log file, sort them in increasing order and place them in the file fitness\_true.log
- ✿ \\$ tail fitness\_true.log %only shows the end of the file where the highest fitness solution is.
- ✿ Copy the last solution in the fitness\_true.log into Solutions/collective-data.dat

# How to run the NRMHD code

## Generate solution files

---

- ✿ Choose a few solutions with different low fitness, e.g. 3, 7, 12, 25, from your fitness\_\*.log files and add those to the file Solutions/collective-data.dat
- ✿ \$ cd Solutions
- ✿ \$ ./mhd-generate.exe %it creates the solution files, e.g. solution\_XXXX.dat, and the collective-results.dat.
- ✿ If the above step is done **before** the last long run is over, you need to remove the collective-results.dat and solution\_\*.dat files and run the mhd-generate.exe script again.
- ✿ Now we can run the notebook multinest.ipynb to plot the results
- ✿ \$ python -m jupyter notebook --no-browser -- ip=000.000.00.00 -- port=8890

# Priors, iter and best fit results

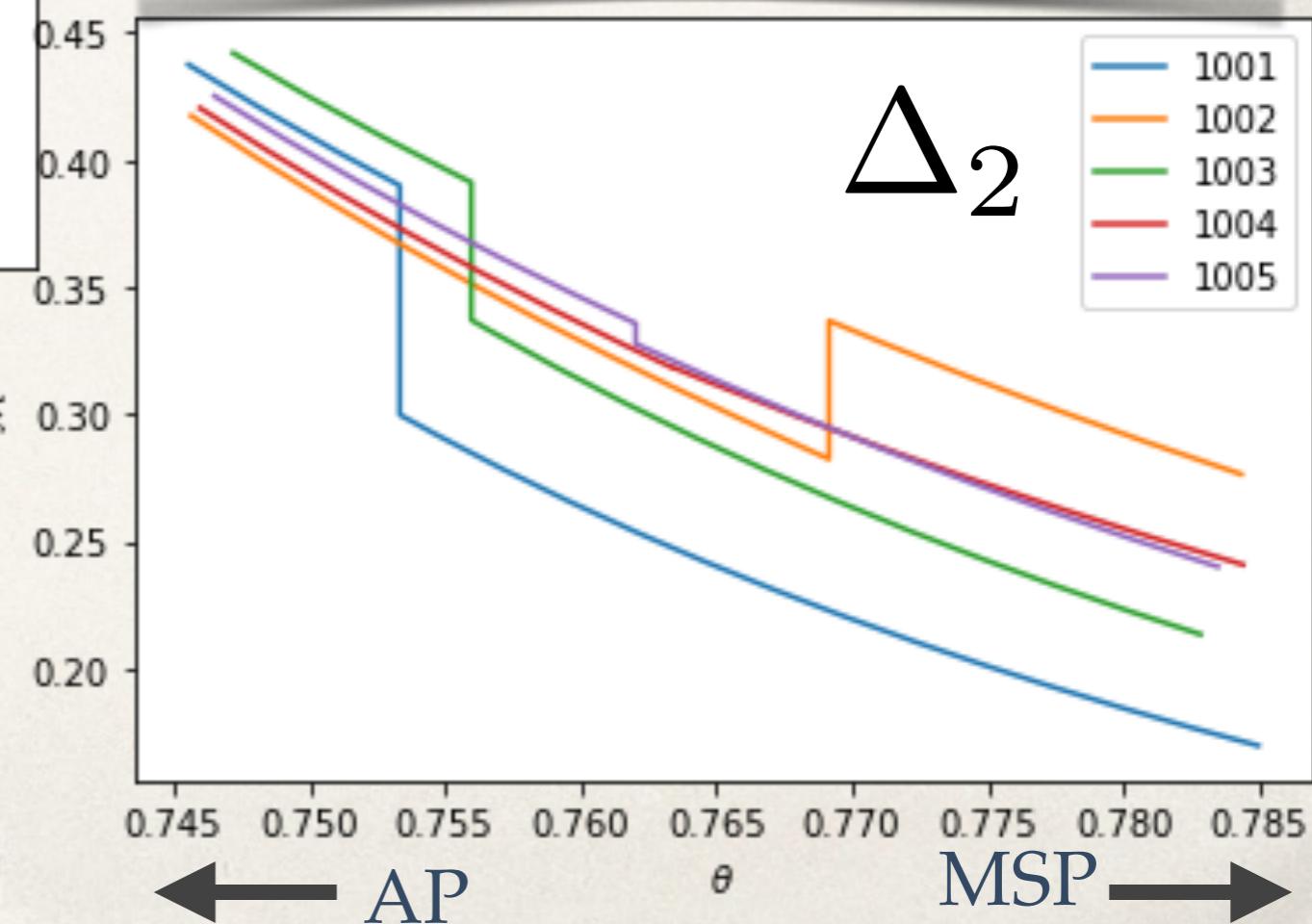
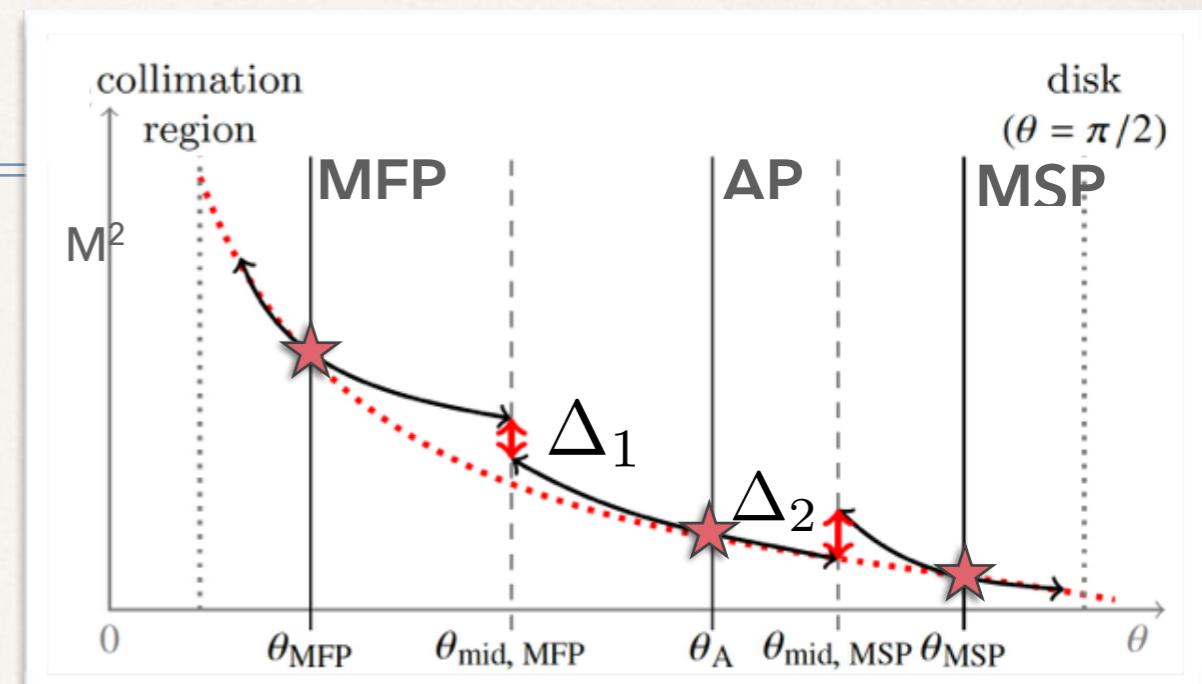
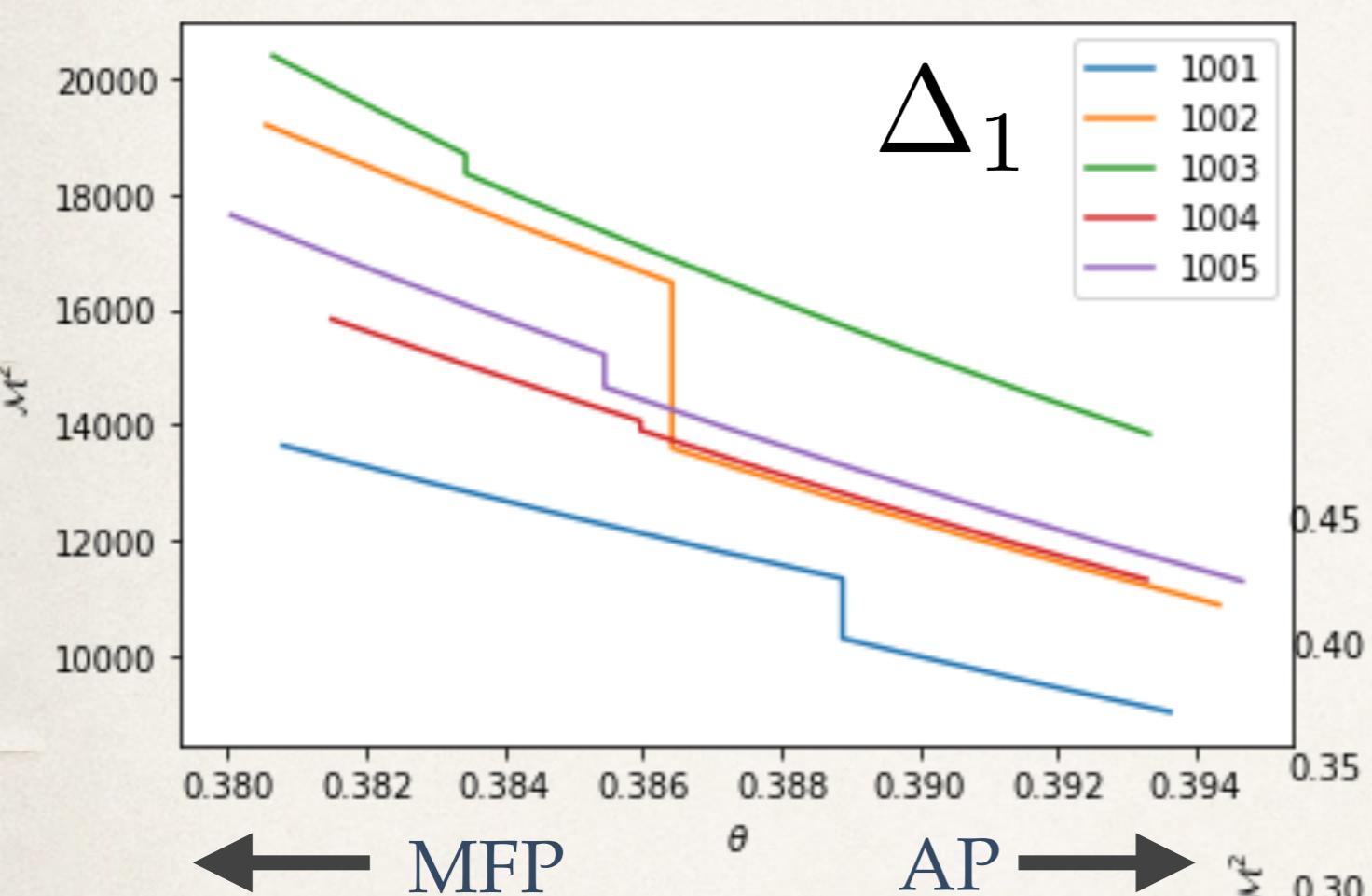
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	main.f90
$\mu_{\text{VTST}}$	20.0 - 30.0
$\lambda_{\text{VTST}}$	1.0 - 8.0
$\theta_{\text{MFP}}$	0,06 - 0,08
$\theta_{\text{MSP}}$	0,75 - 0,90

	params.f90	params.f90
<b>next_maxIter</b>	100(x5)	5000(x1)

	results
$\mu_{\text{VTST}}$	26,54
$\lambda_{\text{VTST}}$	5,783
$\theta_{\text{MFP}}$	0,072
$\theta_{\text{MSP}}$	0,828
$\theta_A$	40° (0,698)
$\psi_A$	55°
$\Gamma$	4/3
$k_{\text{VTST}}$	5,0

# Examples of low-fitness offsets





**THE END**  
*and don't forget to enjoy Amsterdam!*