Dagu Robotics Rover 5 RF controlled - Arduino / nRF24L01

Download source code:
https://github.com/marcelocampos

nRF24L01

1: GND
2: VCC
3: CE
4: CS
5: SCK
6: MOSI
7: MISO
8: IRQ

MISO - 12
MOSI - 11
SCK - 13
CE - 8
CSN - 7

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+3.3V

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Motor 'B'
defined in
Sketch:
IN3 = 10
IN4 = 6

Motor 'A'
defined in
Sketch:
IN1 = 3
IN2 = 5

MMA7361

H-Bridge L298

ROVER 5   Motor A

Motor B

Rev0 - Mar/16

Marcelo Campos