

# Aula 06 - Segmentação e Redes Generativas Adversárias

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# Tópicos

- Classificação vs Segmentação
  - Classificação
  - Detecção de Objetos
  - Segmentação
- Redes Generativas Adversárias
  - DCGAN
  - PIX2PIX
- Codificação

# Segmentação

# Classificação vs Segmentação

Is this a dog?



Image Classification

What is there in image  
and where?



Object Detection

Which pixels belong to  
which object?

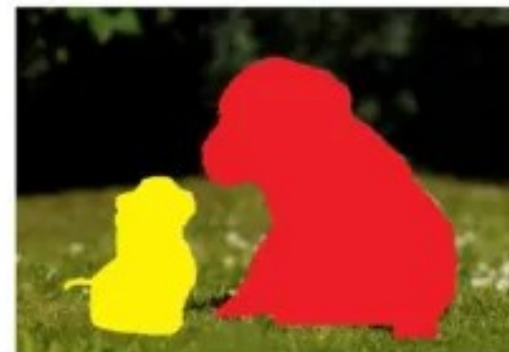
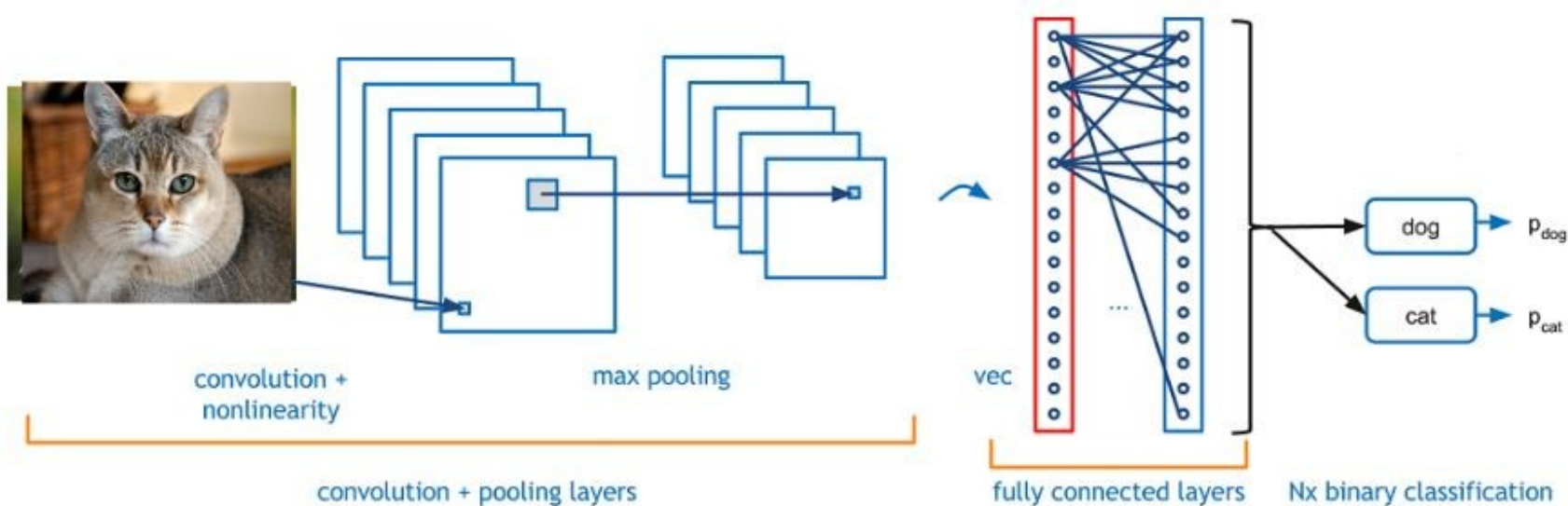


Image Segmentation

# Classificação



# Detecção de Objetos

Is this a dog?



Image Classification

What is there in image  
and where?



Object Detection

Which pixels belong to  
which object?

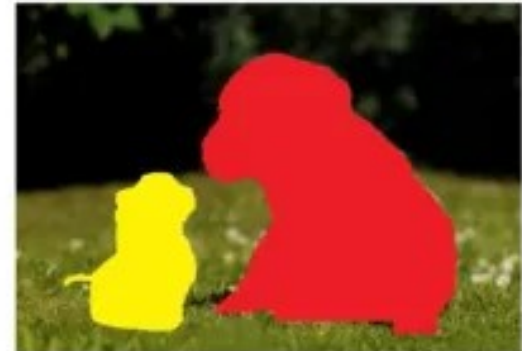
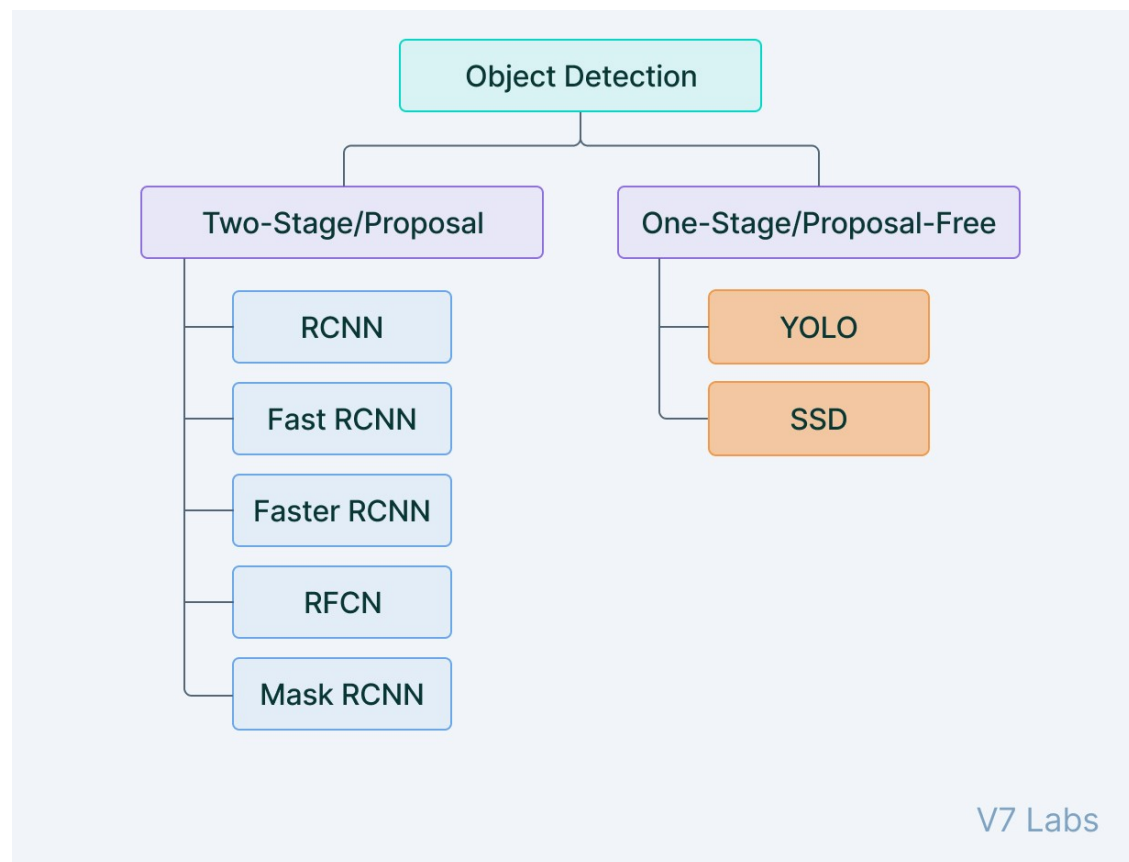
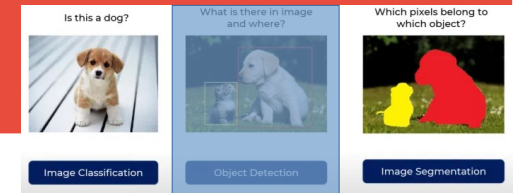
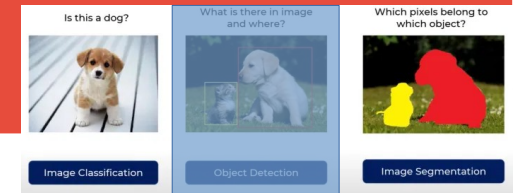


Image Segmentation

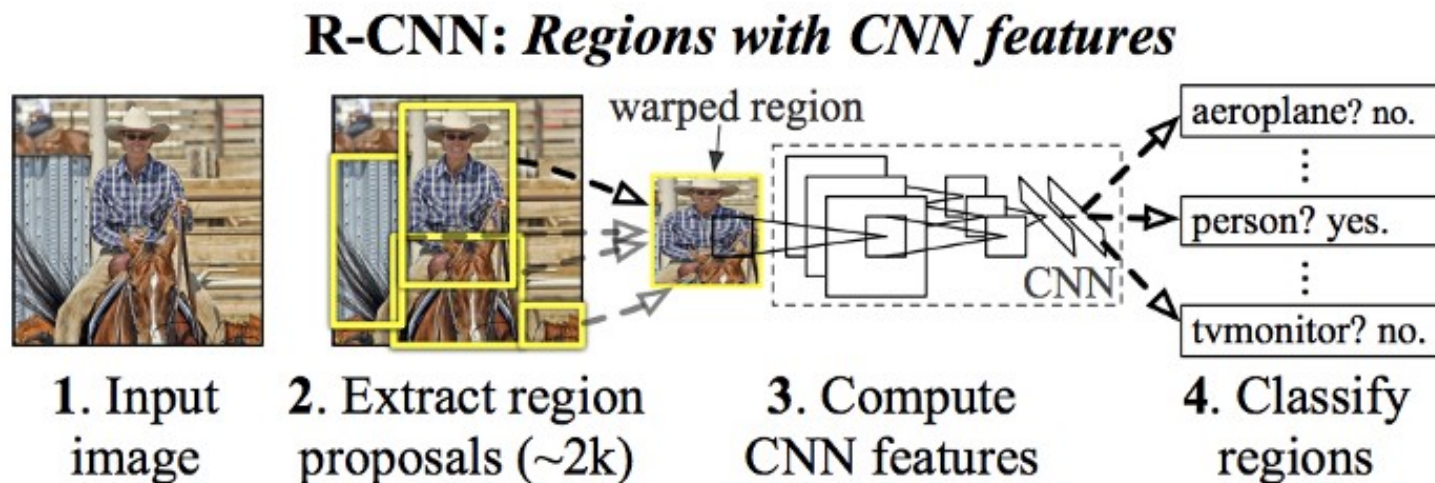
# Detecção de Objetos



# Detecção de Objetos - RCNN

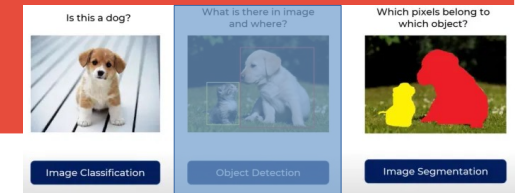


- Region Based Convolutional Neural Network (2014) - Ross Girshick
- Selective Search Algorithm (Region Proposal)
- CNN (Classification)

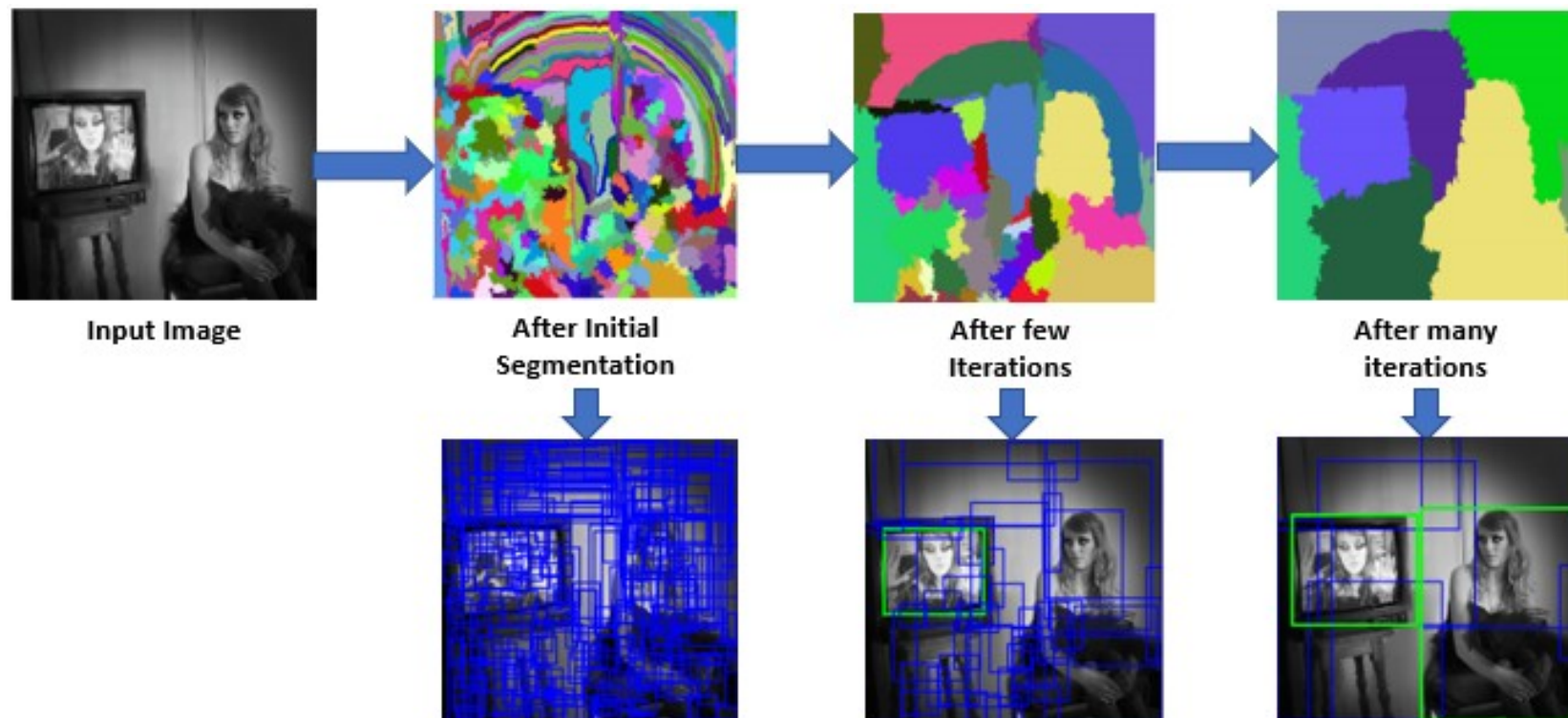




# Detecção de Objetos - RCNN

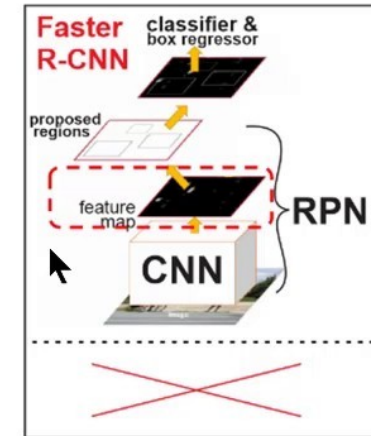
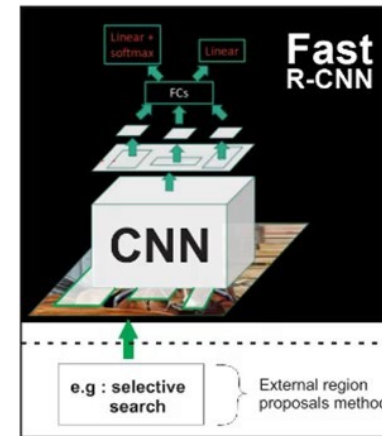
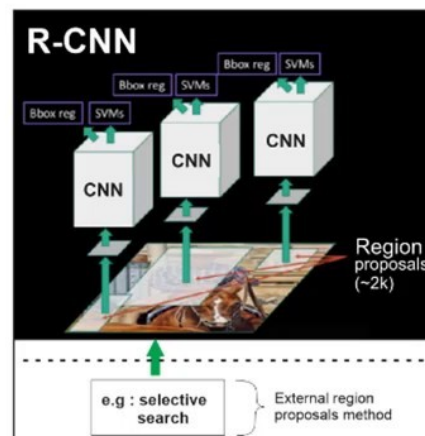
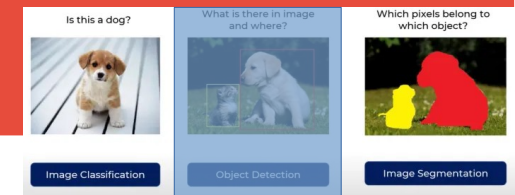


- Selective Search Algorithm (Region Proposal)



# Detecção de Objetos - RCNN

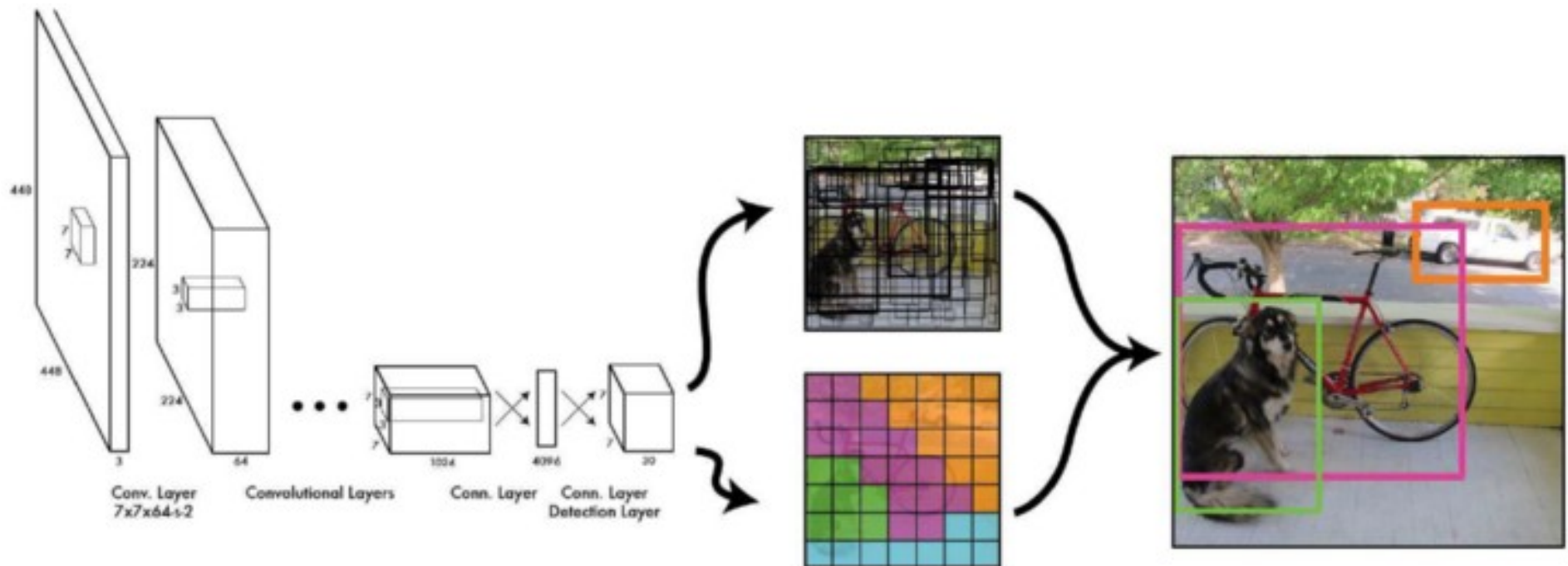
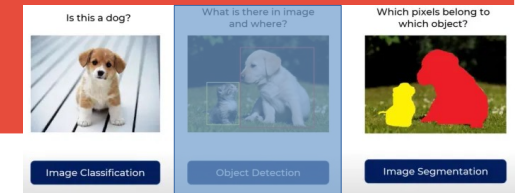
- R-CNN: Selective Search->CNN
- Fast: End-to-end (Sel. Search->ROI Pooling->FC)
- Faster: Region Proposal Network (RPN)



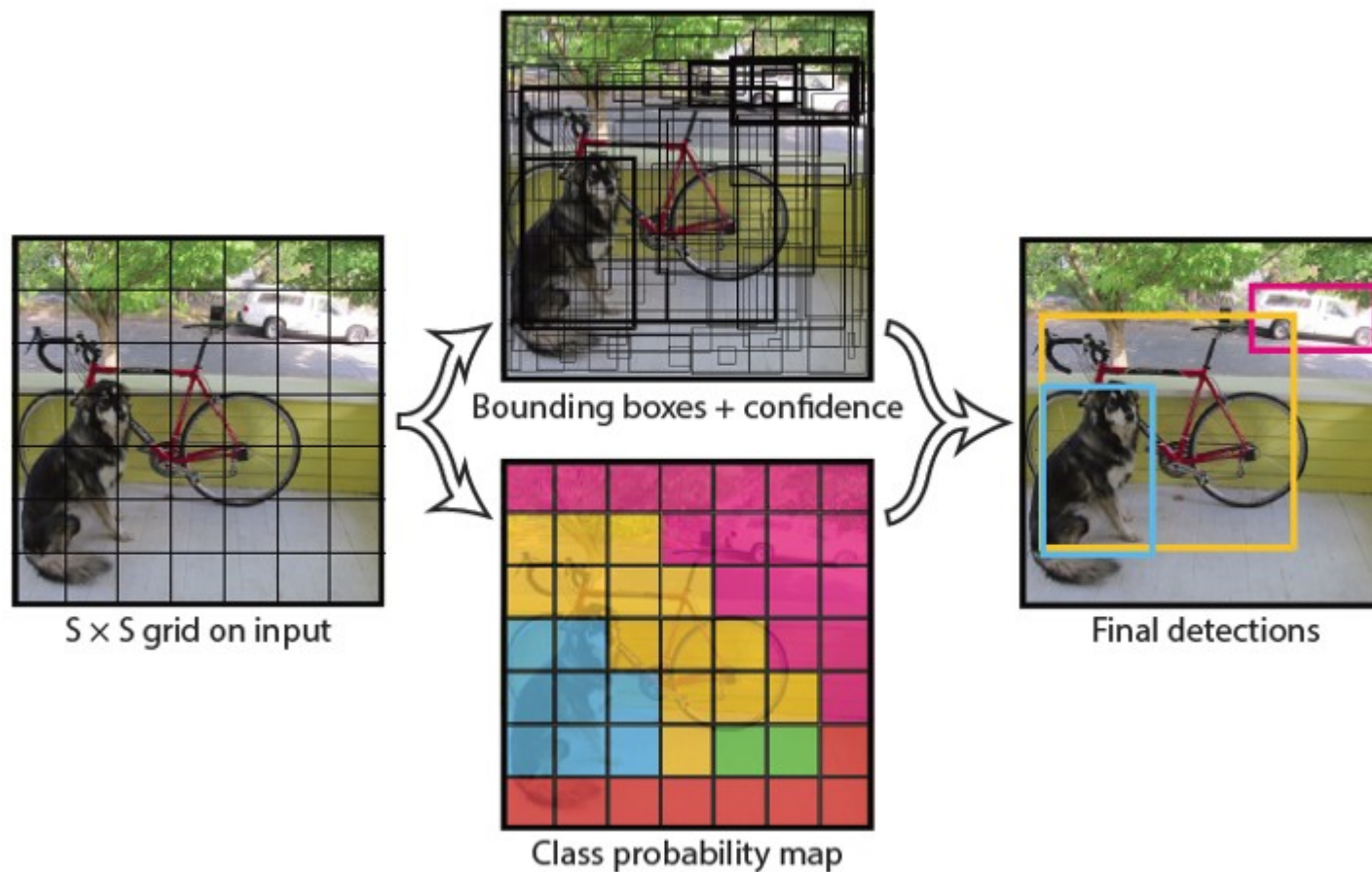
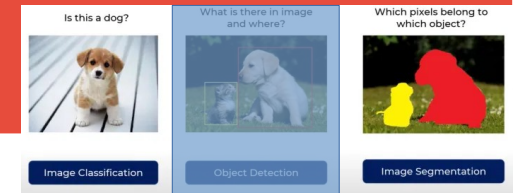
	R-CNN	Fast R-CNN	Faster R-CNN
Test time per image	50 seconds	2 seconds	0.2 seconds
Speed-up	1x	25x	250x
mAP (VOC 2007)	66.0%	66.9%	66.9%

# Detecção de Objetos - Yolo

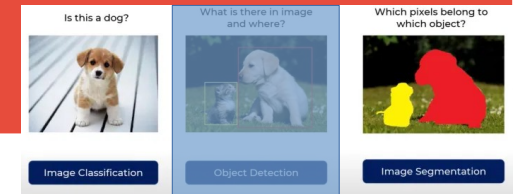
- You Look Once (2015)
- Joseph Redmon / Ross Girshick



# Detecção de Objetos - Yolo



# Let's Code



- YOLO Inference
  - COLAB [\[LINK\]](#)
  - CPU (local)
    - <https://github.com/Asadullah-Dal17/yolov4-opencv-python>



# Segmentação

Is this a dog?



Image Classification

What is there in image  
and where?



Object Detection

Which pixels belong to  
which object?

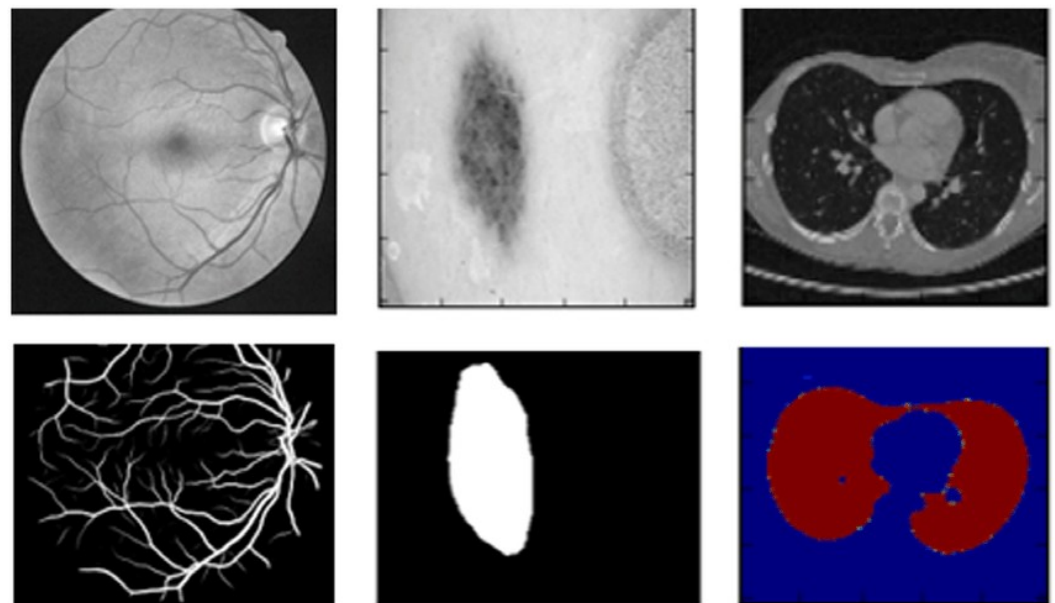
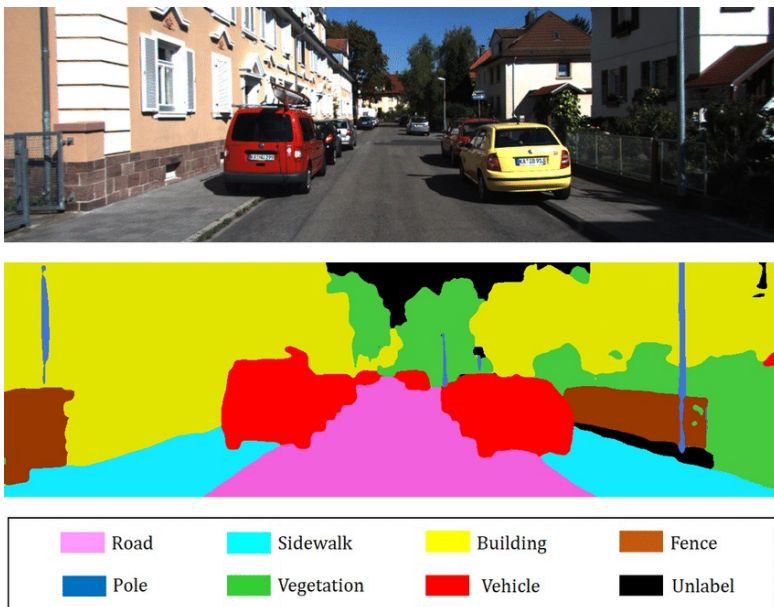


Image Segmentation

# Segmentação



- Classificação a nível de pixel

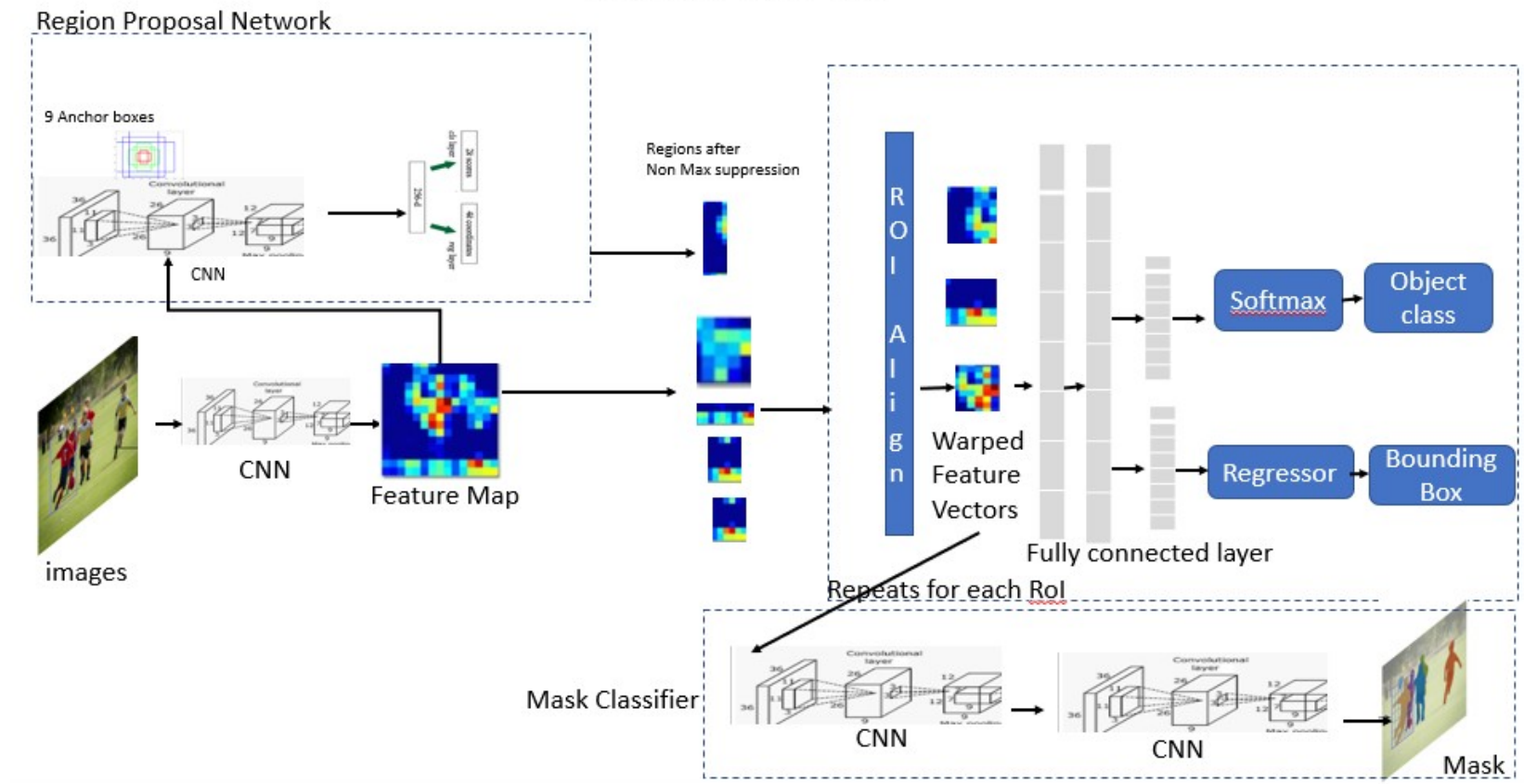


# Segmentação - Mask RCNN

- Faster R-CNN with Binary Mask (2017)



## Mask RCNN

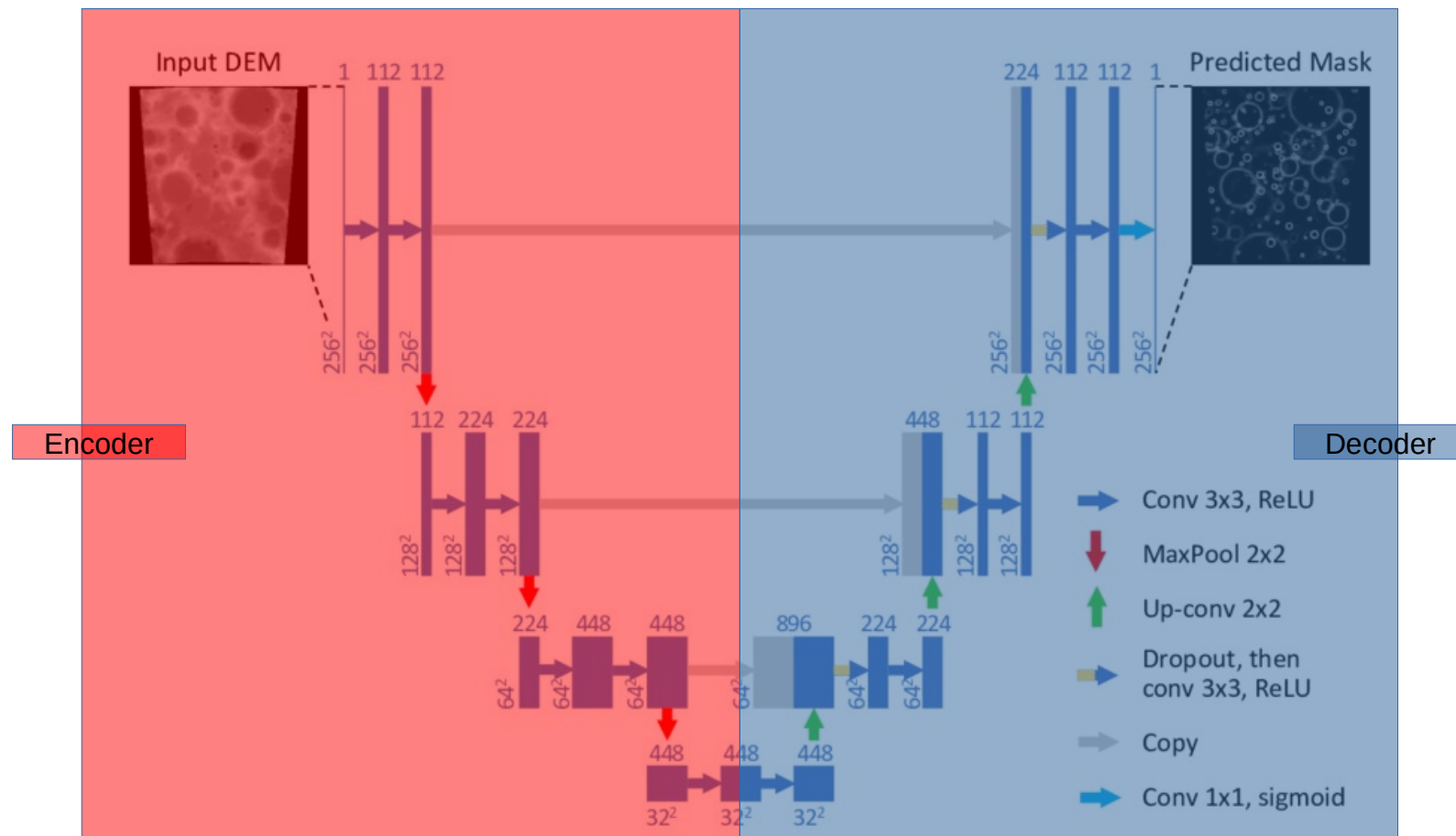




# Segmentação - UNET



- U-Net (Encoder and Decoder)



# Let's Code

- U-NET (Treino e Inferência)
- [\[LINK\]](#)



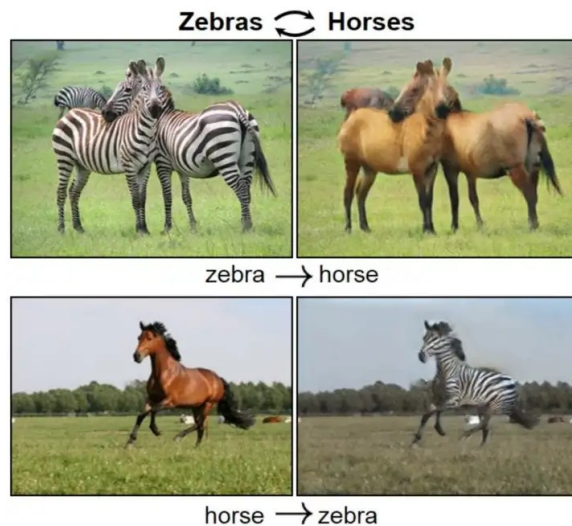
# Redes Generativas Adversárias

# Tópicos

- DCGAN
- PIX2PIX
- Prática

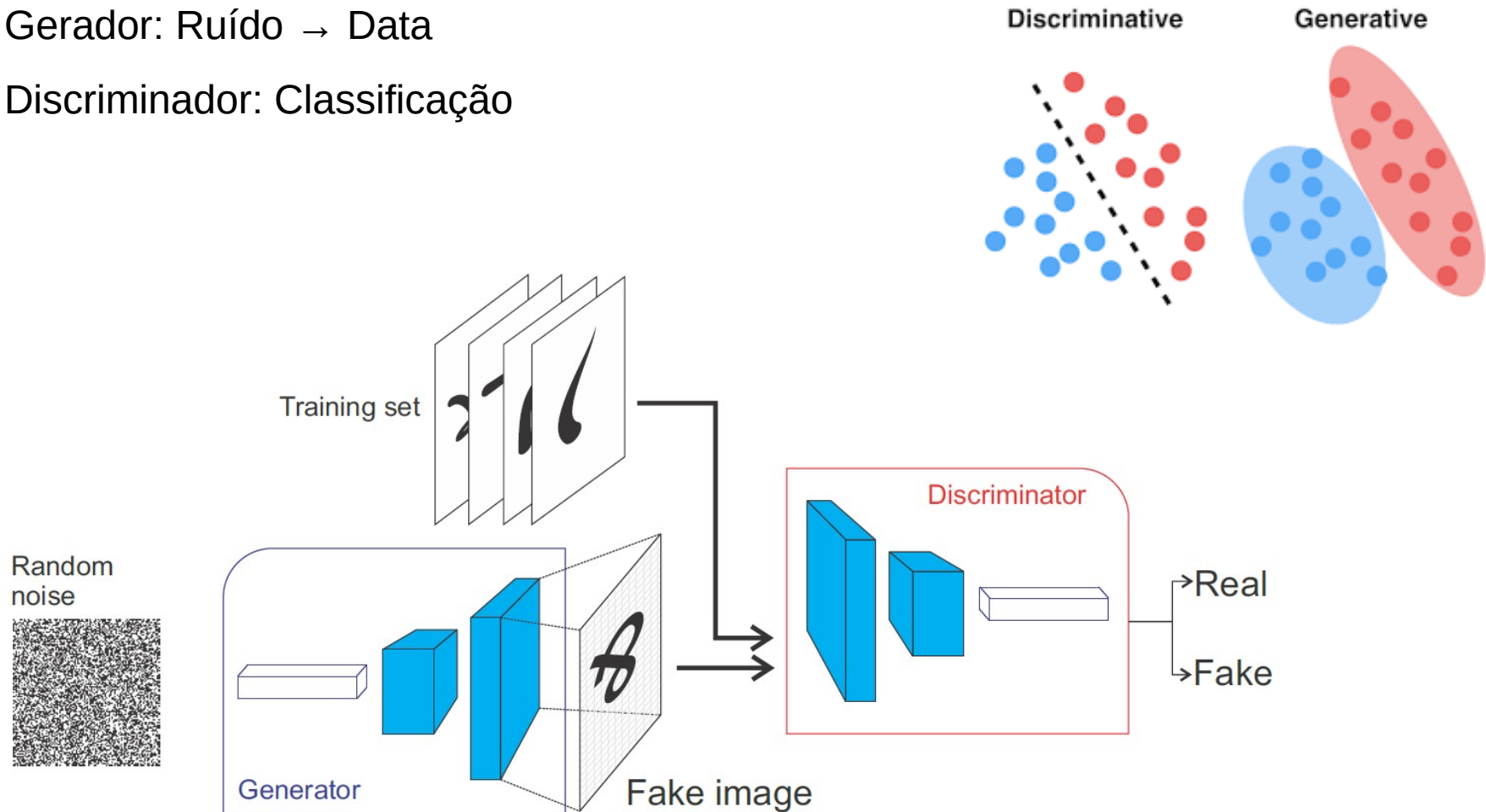
# Deep Fakes

- Generalização: Dados Sintéticos gerados a partir do aprendizado da distribuição real do dado
- Aplicações
  - Filmes (Cenários Sintéticos)
  - Fotografia (Estimação de Pose, Coloração Artificial, Redução de Ruído)
  - Troca de Contexto (Zebra->Cavalo)
  - .....



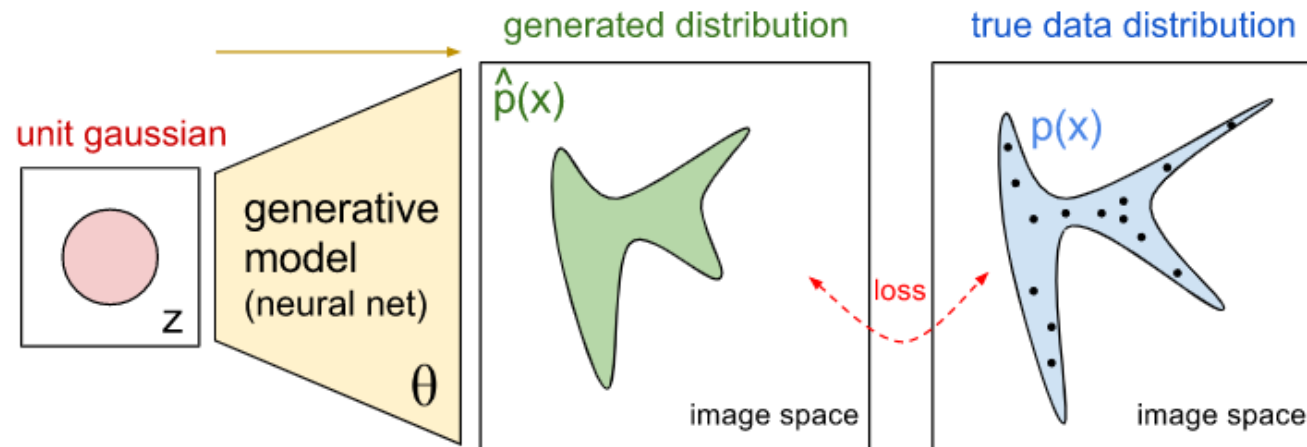
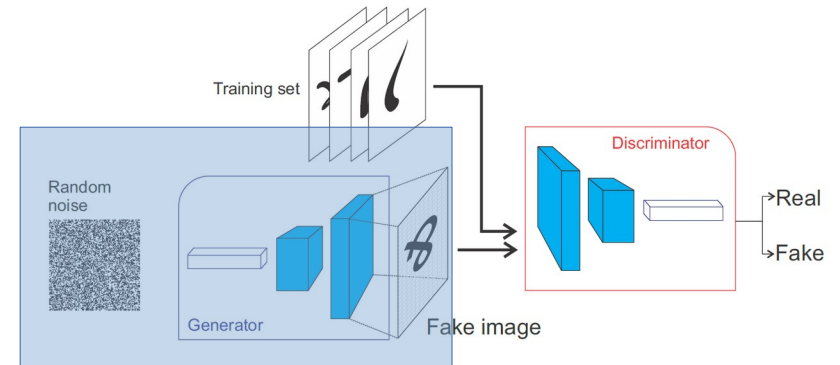
# Generative Adversarial Networks (GAN's)

- Gerador: Ruído → Data
- Discriminador: Classificação

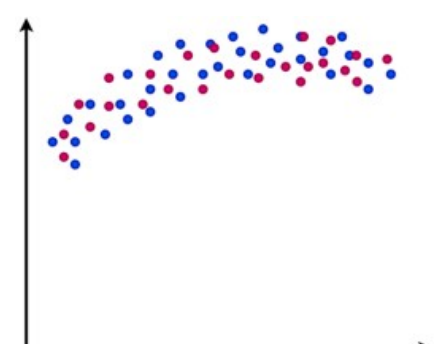
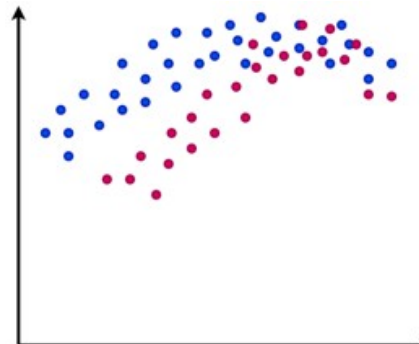
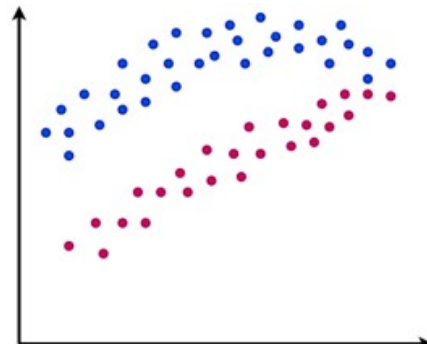
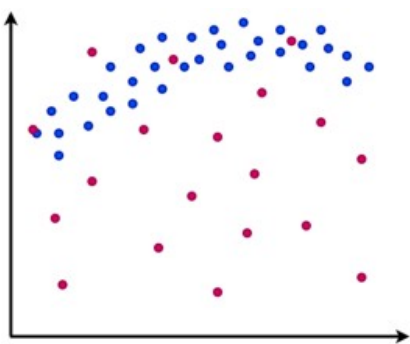
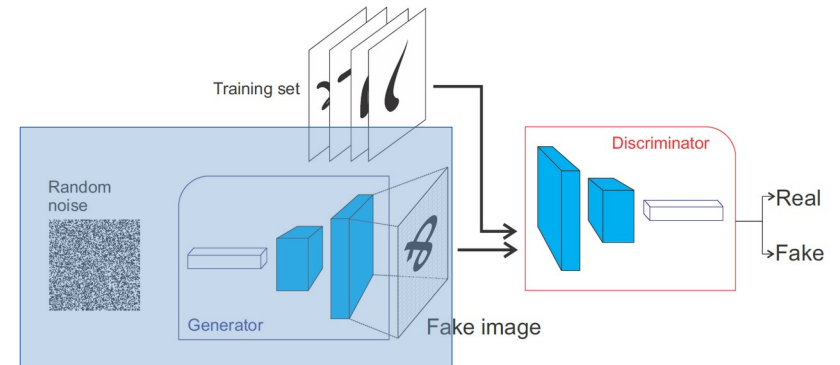
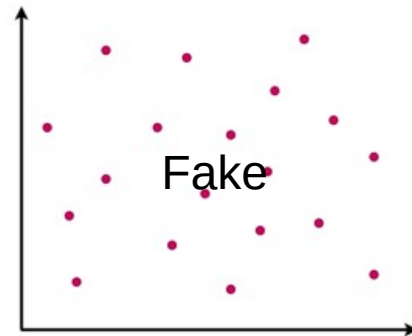
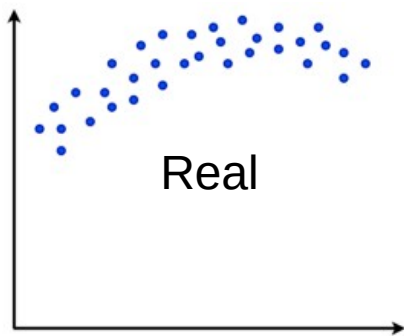


# Modelo Generativo

- Aprende a distribuição do dado



# Modelo Generativo

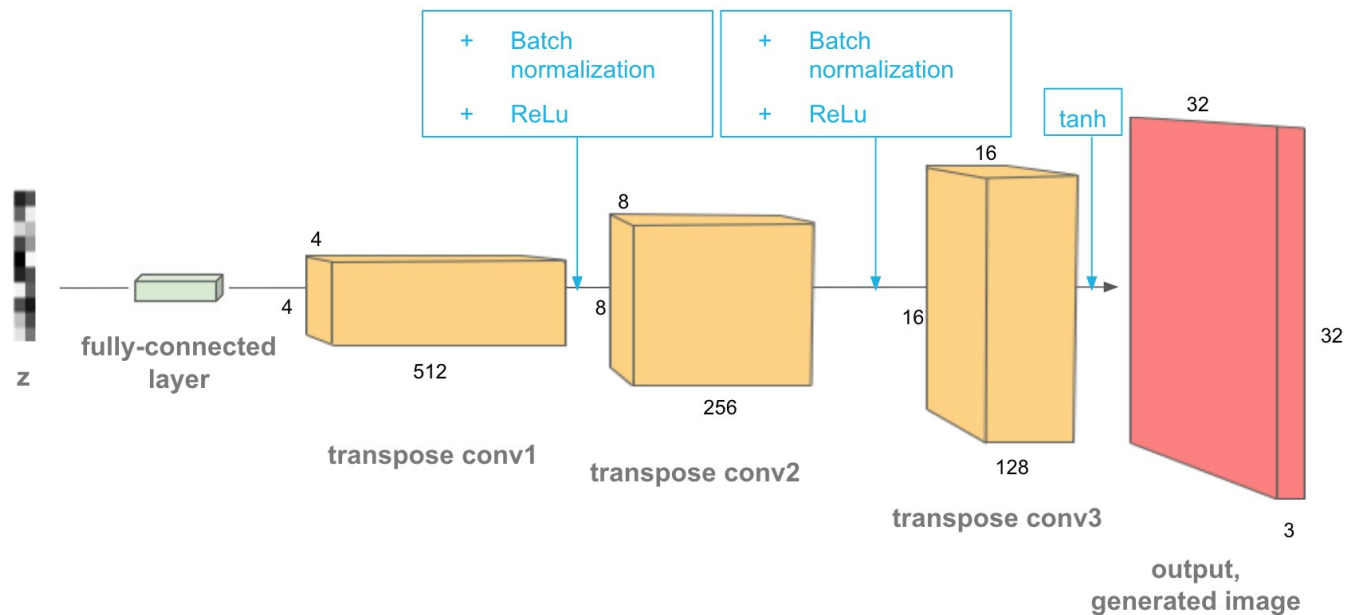
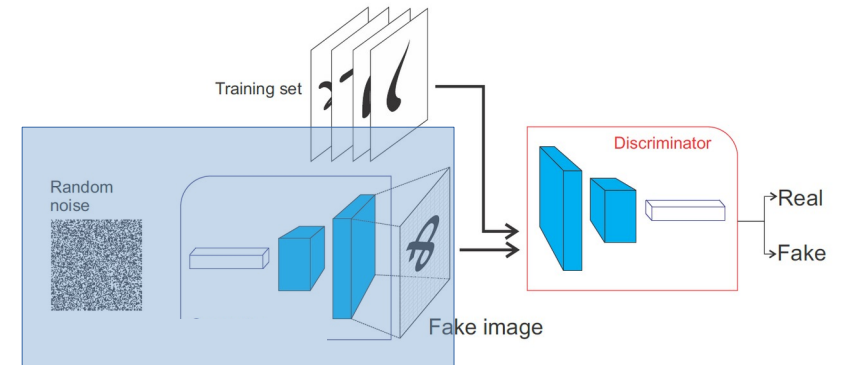


Training



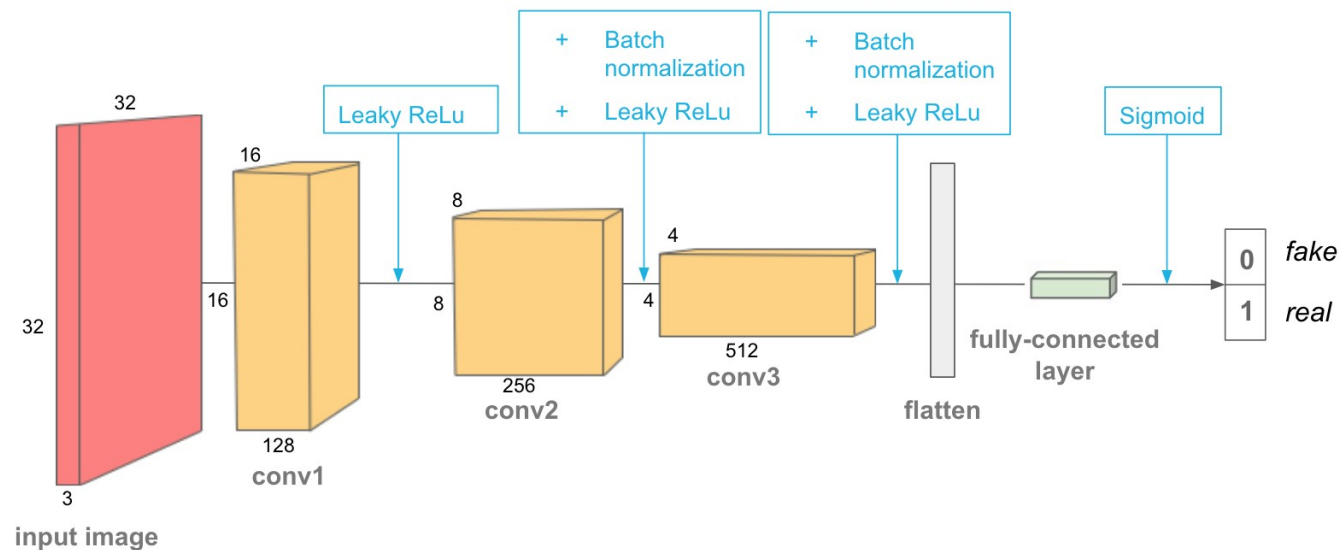
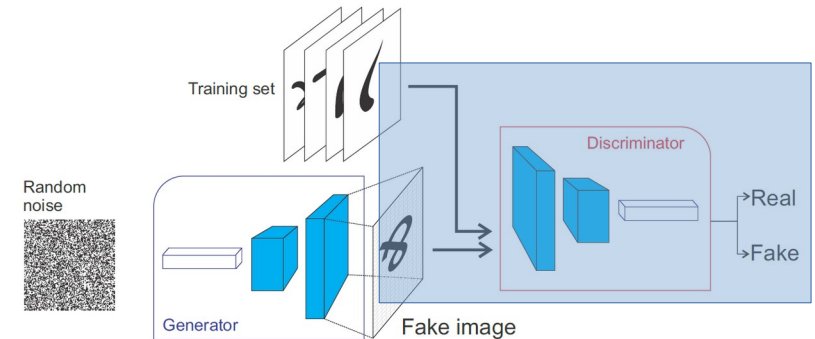
# Modelo Generativo Profundo

- Camadas Des-Convolucionais (upsampling)
  - Ruído → Imagens Sintéticas



# Modelo Discriminante

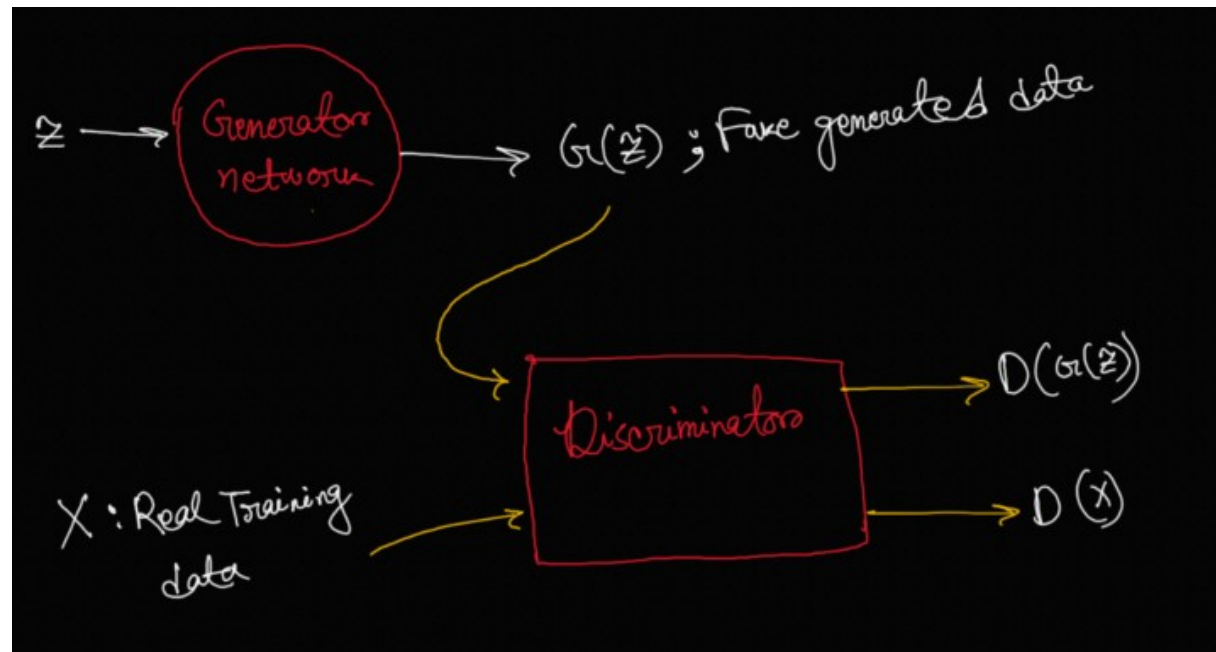
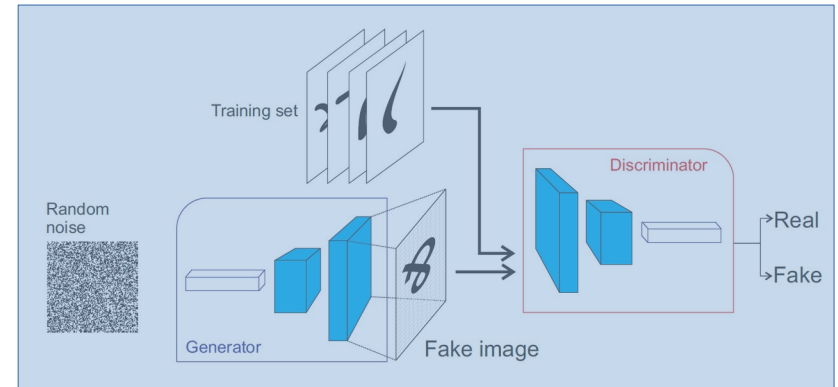
- Classificação: Falso ou Real ?
- CNN



# Treinamento Adversário

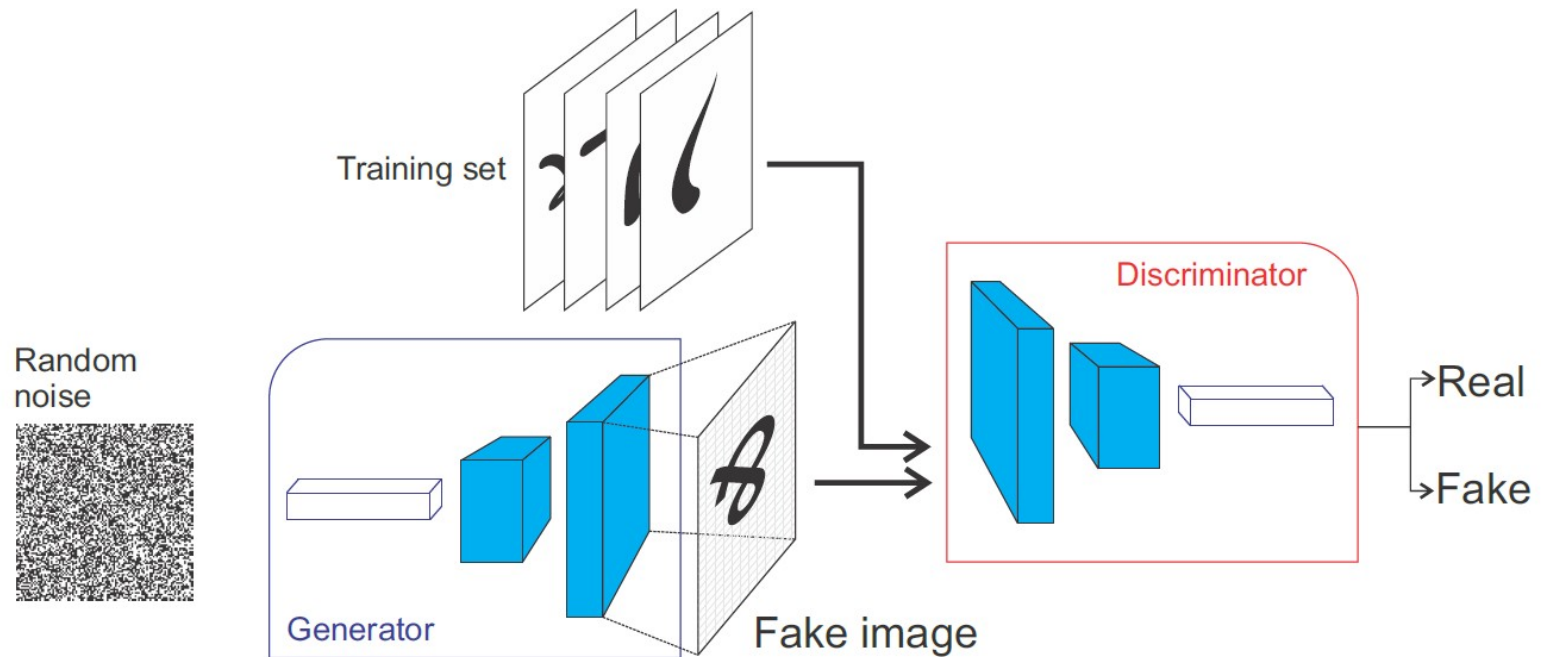
- Erro Adversário (Min-Max)

$$\min_G \max_D V(D, G) = \mathbb{E}_{x \sim p_{data}} [\log D(x)] + \mathbb{E}_{z \sim p_z(z)} [\log(1 - D(G(z)))]$$



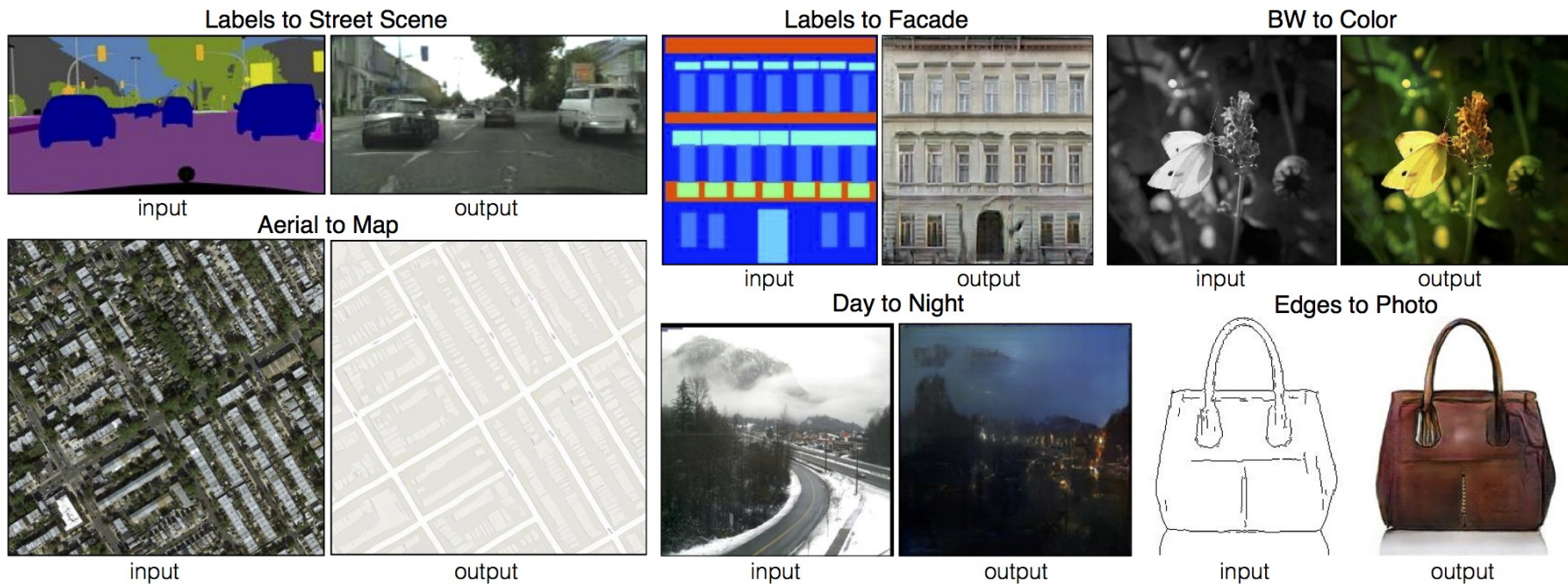
# Let's Code

- [LINK: Lecture\\_12-DCGAN.ipynb](#)



# Pix2Pix

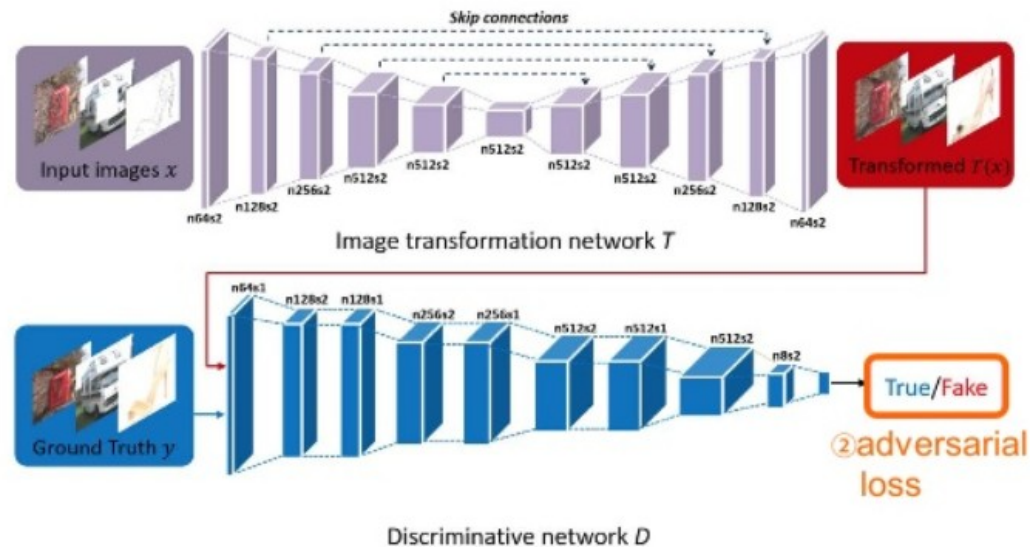
- Transformação de Contexto (Image Translation)



# Pix2Pix

- Modelo Generativo: Arquitetura Encoder-Decoder (i.e U-Net)
- Base de Dados Pareada (Origem->Destino)

## Pix2Pix (①+②)





# Let's Code

- [LINK: Lecture\\_12-pix2pix.ipynb](#)

