Lecture 02 - Image Filtering

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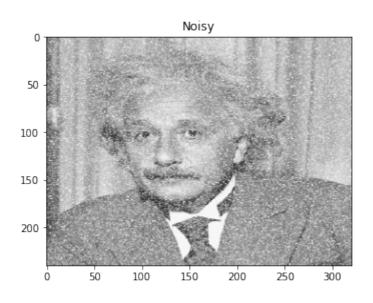
Topics

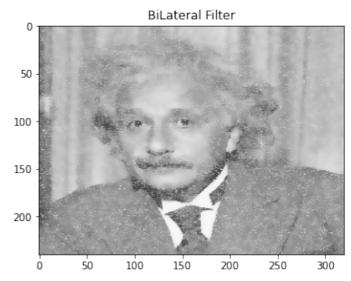
- Discussion of Practice 01
- Image Filtering
 - Convolution
 - Mean, Median, Gaussian Filters
- Practice



Image Filtering

- Image Enhacement
- Noise Reduction
- Mathematical Operations



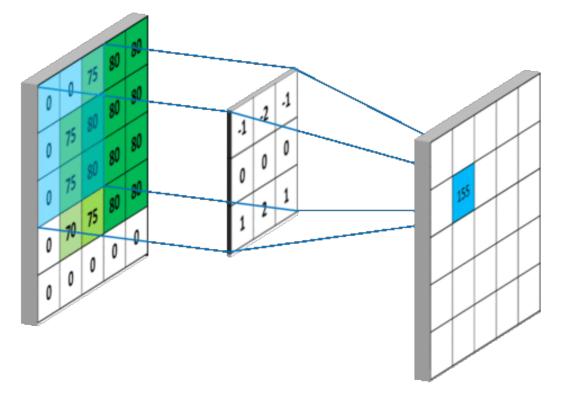


Convolution

Slides a kernel (a.k.a convolution filter) in the entire image

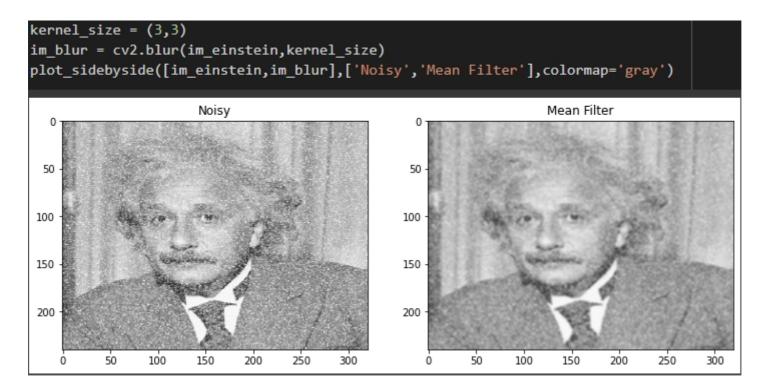
Transforming the pixel in the center of the kernel by the weights of its

neighbors



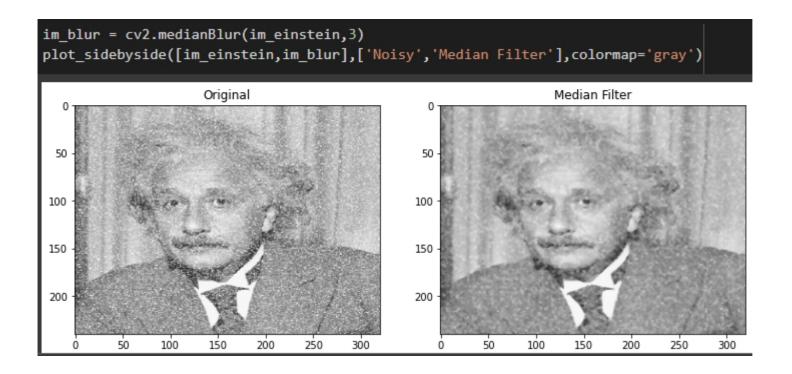
Mean Filter

- Replaces the center pixel with the mean of its neighborhood
- Spreads the outlier value to its neighbors
- Details are smoothed



Median Filter

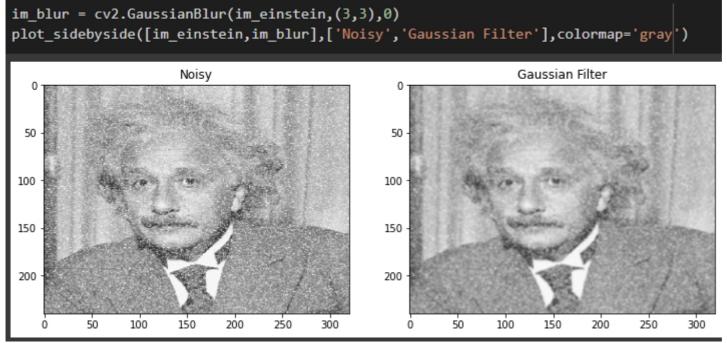
- Replaces the center pixel with by a median of its neighborhood
- Preserves more details when compared to the mean filter



Gaussian Filter

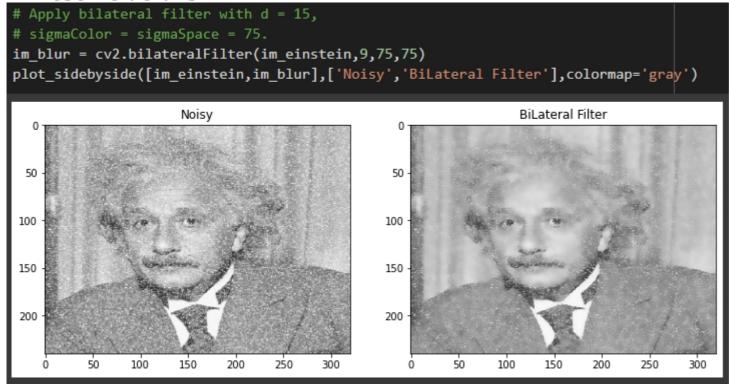
- Gaussian distribution of pixels
- The kernel is composed of probabilities
- Weighted Mean

The standard deviation determines the blur degree



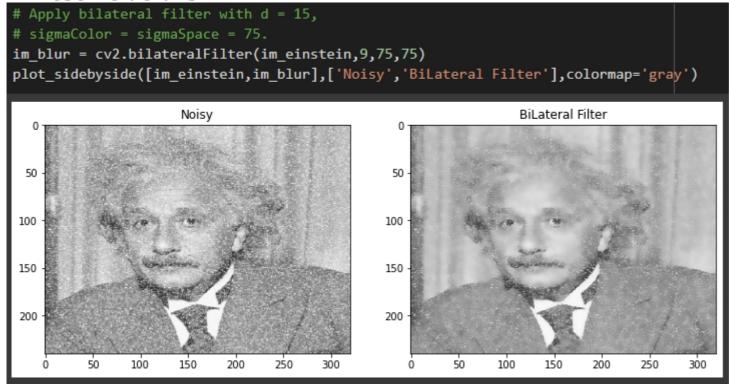
Bilateral Filter

- Gaussian Distribution based
- Add Normalization Factors and Range Weight
- Preserve details



Bilateral Filter

- Gaussian Distribution based
- Add Normalization Factors and Range Weight
- Preserve details



Practice

Link: Practice 02