Artificial Intelligence and Machine Learning UNIT 5 - NEURAL NETWORKS

ReLU:

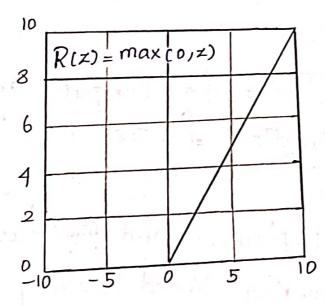
=> Rectified Linear Unit (ReLU) Solve the Vanishing Pradient Problem. ReLU is a non-linear function or Piecewise linear function that will output the input directly if it is Positive, Otherwise, it will output Zero.

=> It is most Commonly used activation function in neural networks, especially in Convolutional Neural Networks (CNNs) and Multilayer Perceptions.

>> Mathematically, it is expressed as

f(x) = max (o,x)

Where x: input to neuron



RelU function

=> The derivative of an activation function is required Whon updating the weights during the back Propagation of the error. The Slope of Reluis 1 for Positive Values and O for negative Values. It becomes non-differentiable when the input x is Zero, but it can be Safely assumed to Zero and Causes no Problem in Practice. => Reluis used in the hidden layers instead of Sigmoid or tanh. The ReLU function Solves the Problem of Computational Complexity of the Logistic Sigmoid and Tanh functions => A ReLu activation unit is known to be less likely to (reale a Vanushing gradient Problem because its derivative is always I for Positive Values of the argument.

Advantages

a, ReLvis Simple to Compute and has a
Predictable gradient for the back Propagation

of the error.

b) Easy to implement and Very fast

(, The Calculation Speed is Very fast. The ReLU function has only a direct Yelationship.

d, It Can be used for deep network training.

Disadvantages: a, When the input is negative, ReLV is not fully functional which means when it Comes to the wrong number installed, ReLU will die. This Problem is also known as the dead Neurons Problem. b, ReLU function Can Only be used within hidden layers of a Neural Network Model

2, Gradient Descent Optimization: => Gradient descent is an optimization algorithmin gadget mastering used to limit a feature with the aid of iteratively moving towards the minimal fee of the Charateristic => Le essentially use this algorithm when we have to locate the least Possible Values which Could fulfilla, given fee function. In gadget getting to know, greater regularly that not we Try to limit loss features Mike mean Squared error). By minimizing the loss Characteristic, we will improve our model and Gradient descent is one of the most Popular algorithms used for this Cause.

=> The graph Shows Exactly Now Gradient Descent Sel of Yales Works => We first take a factor in the Value function and begin Shiffing in Steps in the direction of Gradient descent algorithm the minimum factor. The Size of that Step, Or how quickly we ought to Converge to the minimum factoris defined by Learning Rate. We Can cowl more location with better learning fee but at the risk of Overshooting the minima. Un the opposite hand, Small Steps / Smaller gaining knowledge of charges will eat a number of time to atlain the lowest point => Now, the direction wherein algorithm hasto transpor (Closerto minimal) is also important. This is Calculated using derivatives. A Spinoff is largely Calculated because of the Slope. Lle get that tangent line to graphat the Point. The extra Steep the tangent, would Suggest more Steps would be needed to reach minimum Point, much less Steepmight Suggest lesser Steps are required to reach the minimum factor.

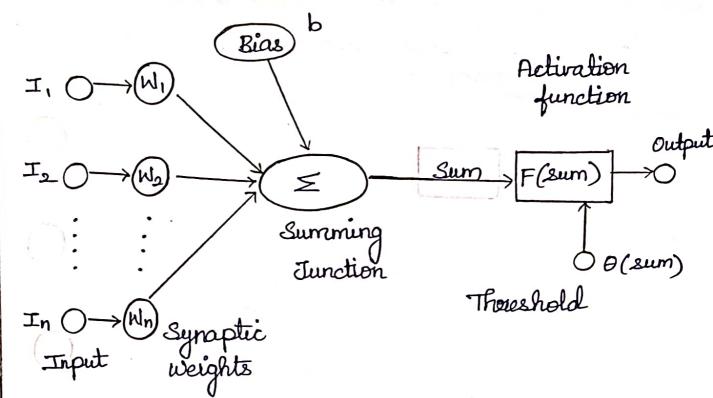
3. Evror Backpropagation:

- * Backpropagation is one of the important concepts of a newral network.
- * Its algorithm calculates the gradient of the ever function.
- * And the set of methods used to efficiently train artificial newal networks following a gradient descent approach which exploits the chair rule.
- * The main features of backpropagation are the iterative, recursive and efficient method through which it calculates the updated weight to improve the network
- * Perivatives of the activation function to be known at network design time is required to backpropagation.

How backpropagation algorithm works?

- * The algorithm in newal network computes the gradient of the loss function for a single weight by the chain rule.
- * It efficiently computes one layer at a time, unlike a native direct computation.
- * It computes the gradient, but it does not define how the gradient is used

* It generalizes the computation in the delta rule.



- 1. Inputs arrive through the preconnected path.
- 2. Input is modeled using real weights W.

The weights are usually randomly selected.

3. calculate the output for every newson from the input layer, to the hidden layers to output. 4. calculate the ever in the outputs.

Evore = Actual output - desired output.

- 5. Travel back from the output layer to hidden layer to adjust the weights such the even is decreased.
- 6. Repeating the process until the desired of

Types of backpropagation networks:

Two types of backpropagation networks are,

a. Static backpropagation,

b. Recurrent backpropagation.

Static backpropagation:

* It is one kind of backpropagation network which produces a mapping of a static input for static output.

* It useful to solve static classification issues like optical character recognition.

Recurrent backpropagation:

* Recurrent back propagation in data mining is fed forward until a fixed value is achieved.

* After that the ever is computed and

propagated backward.

Advantages

* It does not have any parameters to tune except for the number of inputs.

* It is a standard process that usually

works well.

Disadvantages -

* The performance of backpropagation relies very heavily on the training data.

It needs a very large amount of time

for training.

4- Shallow Networks:

of layers in a neural network.

* It have small number of layers, usually regarded as having a single hidden layer and deep newal network refer to neural networks that have multiple hidden layers.

* Both types of networks perform certain tasks better than the other and selecting the right network depth is important for creating successful model.

* The values of the feature vector of the data to be classified are passed to a hidden layer of nodes

* which generates a response according to some activation function.g, acting on the weighted sum of those values Z.

* The responses of each unit in the hidden layer is then passed to a final, entpulayer, whose activation produces the classification prediction output.

Deep Network:

* Deep learning is a new exea of machine learning research, and multiple levels of representation and abstraction that help to make sense of data such as images, sound, text...

* It means using a newal network with several layers of nodes between input and output.

* deep multilayer newal networks with many hiddepn layers.

TensorFlow:

* Tensor Flow is one of the most popular frameworks used to build deep leaving models.

* The framework is developed by Google Brain Team.

* Languages like C++, R and python are supported by the framework to create the models as well as the libraries.

* Fg: The translator used by Google is the best example of TensorFlow.

* some of the characteristics of Tensorflow

il Multiple GPU supported.

ii) one can visualise graphs and queues easily using Tensor Board.

iii) power documentation and larger support @

- * Kerae is built purely on python and can sun on the top of TensorFlow.
- * Due to this complexity and use of low level libraries, Tensor Flow can be comparatively harder to adapt for new users as compared to keras.
- * Keras has been developed keeping in mind the complexities in the deep learning models, and it can sun quickly to get the results in minimum time.
- * Convolutional as well as Recurrent Newal Networks are supported in Keras.

* The framework can run easily on cpu and

* The models in kexas can be classified into a categories.

1. <u>Sequential</u> model:-

*The layers in the deep learning model are defined in a sequential manner.

* The implementation of the layers in this model will also be done sequentially.

2. Keras functional API:

Deep learning models that has multiple outputs or has shared layers i.e more complex models can be implemented in Kexas function API