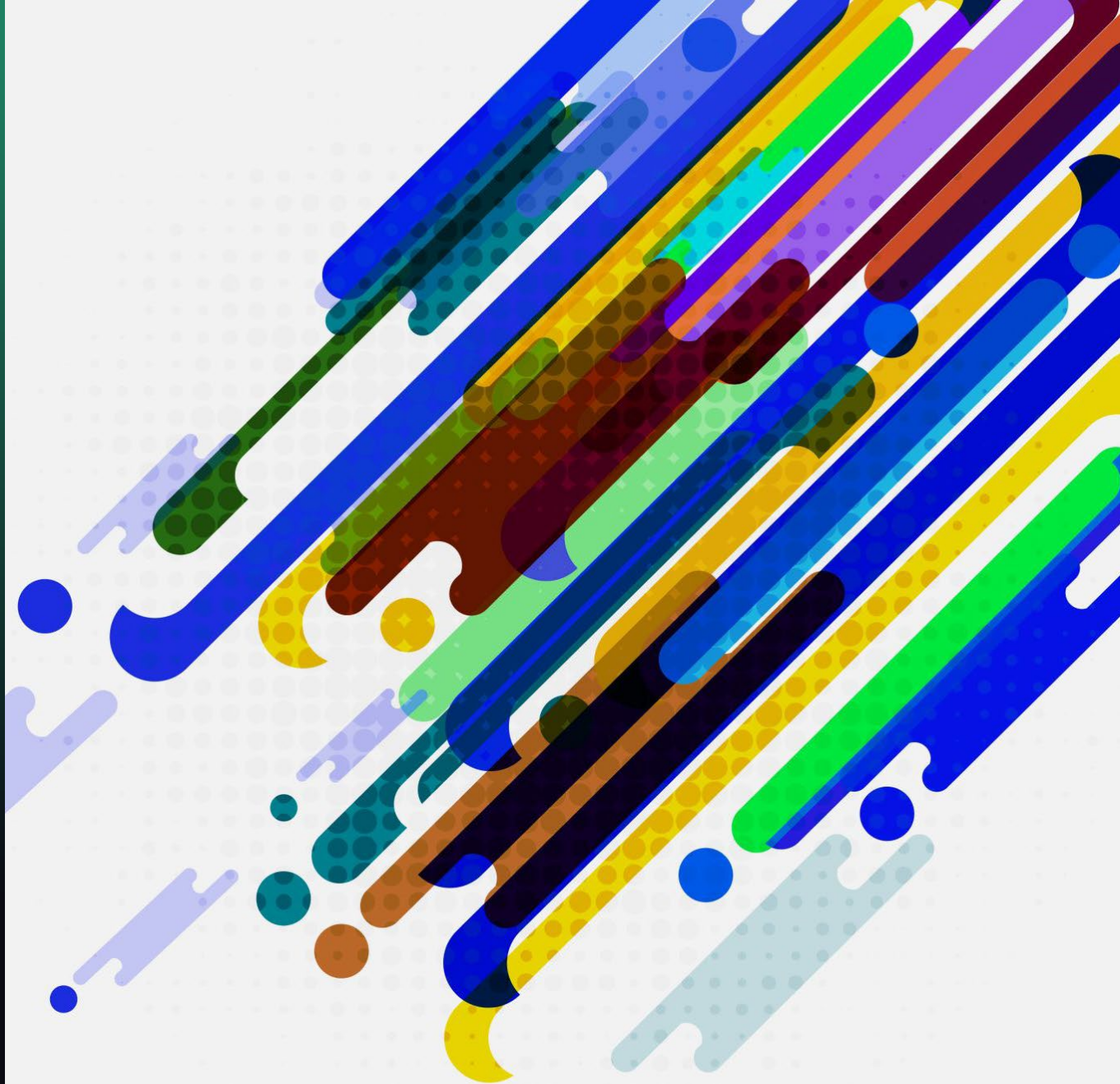


Gaussian mixture models and Expectation maximization



Clustering methods



K Means
Clustering

Hierarchical
Clustering

Gaussian
Mixture
Models

Gaussian Distribution

- In one dimension probability density function of a Gaussian Distribution

$$G(X|\mu, \sigma) = \frac{1}{\sigma\sqrt{2\pi}} e^{-\frac{(x-\mu)^2}{2\sigma^2}}$$

- where μ and σ are respectively the mean and variance of the distribution

Multivariate Gaussian distribution

$$G(X|\mu, \Sigma) = \frac{1}{\sqrt{(2\pi)^d |\Sigma|}} \exp \left(-\frac{1}{2} (X - \mu)^T \Sigma^{-1} (X - \mu) \right)$$

Here μ is a d dimensional vector denoting the mean of the distribution and Σ is the $d \times d$ covariance matrix.

Gaussian Mixture Model

- Suppose there are K clusters
- the probability density is defined as a linear function of densities of all these K distributions

$$p(X) = \sum_{k=1}^K \pi_k G(X | \mu_k, \Sigma_k)$$

Gaussian Mixture Model

- Π_k is the mixing coefficient for kth distribution
- For estimating the parameters by the maximum log-likelihood method

$$\begin{aligned}\ln p(X|\mu, \Sigma, \pi) &= \sum_{i=1}^N \ln p(X_i) \\ &= \sum_{i=1}^N \ln \sum_{k=1}^K \pi_k G(X_i|\mu_k, \Sigma_k)\end{aligned}$$

Bayes theorem

$$\begin{aligned}\gamma_k(X) &= \frac{p(X|k)p(k)}{\sum_{k=1}^K p(k)p(X|k)} \\ &= \frac{p(X|k)\pi_k}{\sum_{k=1}^K \pi_k p(X|k)}\end{aligned}$$

Gaussian Mixture Model

- *So equating the derivative of $p(X|\mu, \Sigma, \pi)$ with respect to μ to zero and rearranging the terms,*

$$\mu_k = \frac{\sum_{n=1}^N \gamma_k(x_n) x_n}{\sum_{n=1}^N \gamma_k(x_n)}$$

Gaussian Mixture Model

$$\Sigma_k = \frac{\sum_{n=1}^N \gamma_k(x_n) (x_n - \mu_k) (x_n - \mu_k)^T}{\sum_{n=1}^N \gamma_k(x_n)}$$

$$\pi_k = \frac{1}{N} \sum_{n=1}^N \gamma_k(x_n)$$

denotes the total number of sample points in the kth cluster.