

# s/eLORETA model-driven & (new) data-driven inverse solutions for EEG/MEG

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# Model-Driven Linear Distributed Inverse Solutions

## A short History

1984 (Hämäläinen and Ilmoniemi), 1987 (Sarvas)

Minimum Norm: no depth localization, huge localization error

1984→ (many authors)

Weighted Minimum Norm

1994 (Pascual-Marqui)

LORETA: low localization error

1997 (Van Veen et al.)

LCMVB: localization error, not a genuine solution

2002 (Pascual-Marqui)

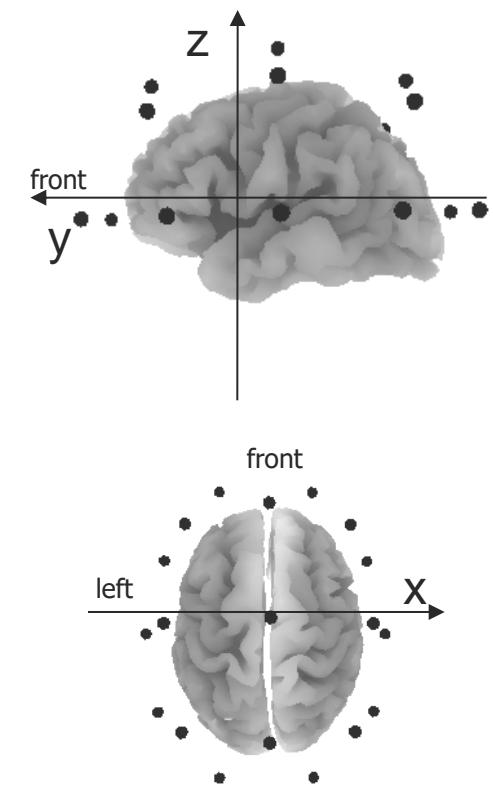
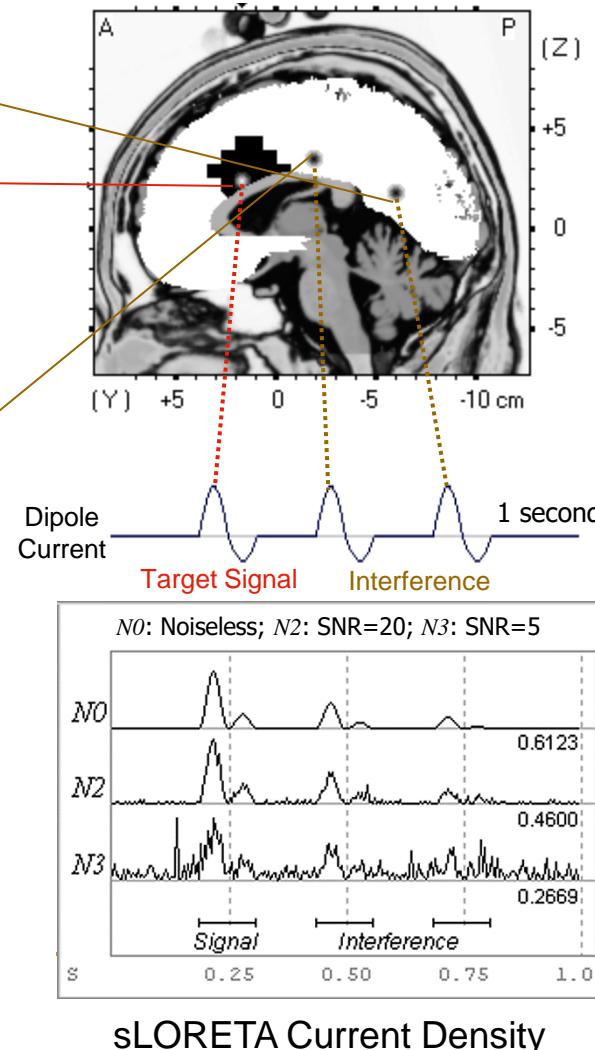
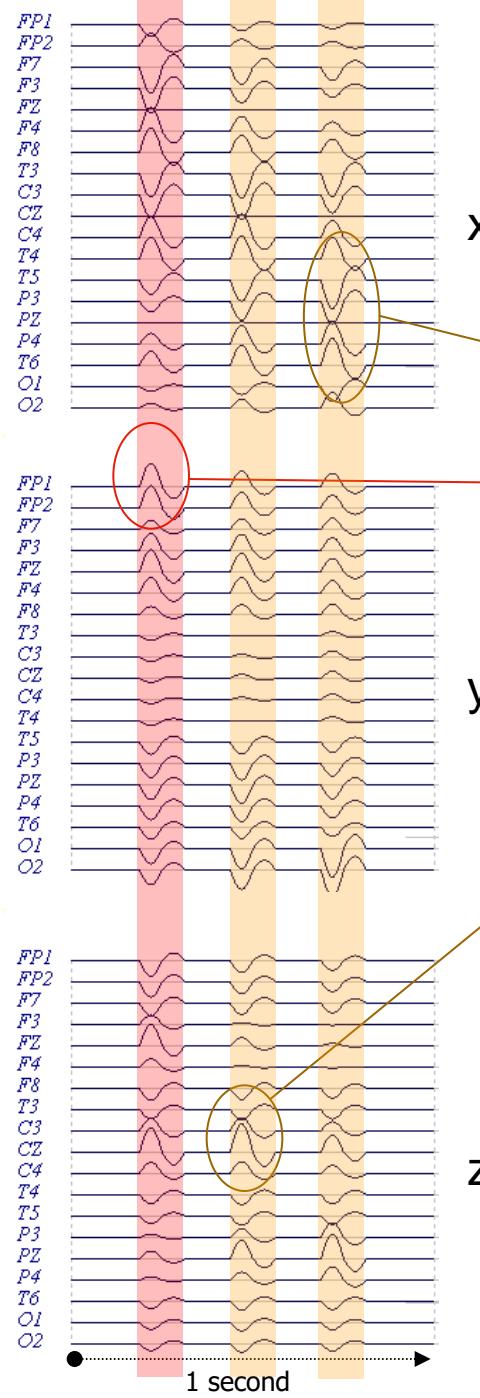
sLORETA → zero localization error, not a genuine solution

2007 (Pascual-Marqui)

eLORETA → zero localization error and a genuine solution

All the model driven methods results in smooth, low spatial resolution reconstruction

# Spatial Resolution (19 electrodes)



# Notation, Nomenclature and Problem Statement

$N$  sensors

$\mathbf{x}(t) \leftarrow \mathbf{Hx}(t) \in \mathbb{R}^N$  is the **CAR** Sensor Measurement Vector

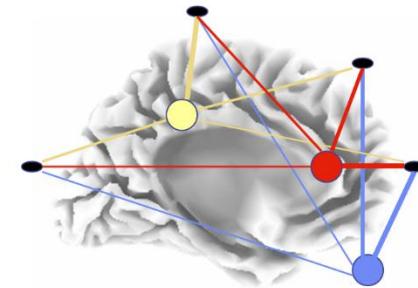
$$\mathbf{H} = \mathbf{I} - \frac{1}{N}\mathbf{1}\mathbf{1}^T \quad \text{is the centering matrix}$$

$Q$  voxels

$\mathbf{j}(t) \in \mathbb{R}^{3Q}$  Current Vector

$$\mathbf{x}(t) = \mathbf{Kj}(t) \quad \textit{Forward problem}$$

$$\mathbf{j}(t) = \mathbf{T}^T \mathbf{x}(t) \quad \textit{Inverse problem}$$



$$\mathbf{K} \in \mathbb{R}^{N \cdot 3Q}; \quad \mathbf{K} = [\mathbf{K}_1 \mathbf{K}_2 \dots \mathbf{K}_Q]; \quad \mathbf{K}_q = [\mathbf{k}_x \mathbf{k}_y \mathbf{k}_z]_q \in \mathbb{R}^{N \cdot 3}$$

Leadfield Matrix

$$\mathbf{T}^T \in \mathbb{R}^{3Q \cdot N}; \quad \mathbf{T} = [\mathbf{T}_1 \mathbf{T}_2 \dots \mathbf{T}_Q]; \quad \mathbf{T}_q = [\mathbf{t}_x \mathbf{t}_y \mathbf{t}_z]_q \in \mathbb{R}^{N \cdot 3}$$

Transfer Matrix

# Notation, Nomenclature and Problem Statement

Given a leadfield matrix  $\mathbf{K}$  the inverse problem has infinite solutions  $\mathbf{T}$ .

A genuine solution should reproduce the measurement such that  $\mathbf{x}(t) = \mathbf{K}\mathbf{T}^T\mathbf{x}(t) \rightarrow \mathbf{K}\mathbf{T}^T = \mathbf{H}$

and should feature zero-localization error in psf  $\rightarrow \mathbf{T}^T\mathbf{K}$  is ‘block-diagonally dominant’

$$\mathbf{j}_q = \mathbf{T}_q^T \mathbf{x} \in \mathbb{R}^3 \quad \text{Single-Voxel Current}$$

$$\gamma_q = \|\mathbf{j}_q\|^2 = \mathbf{x}^T \boldsymbol{\Xi}_q \mathbf{x}, \quad \boldsymbol{\Xi}_q = \mathbf{T}_q \mathbf{T}_q^T \in \mathbb{R}^{N \cdot N} \quad \text{Single-Voxel Current Density}$$

$$\gamma_\Omega = \sum_{q \in \Omega} \mathbf{x}^T \boldsymbol{\Xi}_q \mathbf{x} = \mathbf{x}^T \boldsymbol{\Xi}_\Omega \mathbf{x}, \quad \boldsymbol{\Xi}_\Omega = \sum_{q \in \Omega} \mathbf{T}_q \mathbf{T}_q^T \in \mathbb{R}^{N \cdot N} \quad \text{ROI Current Density}$$

# Covariance (Data) and LeadField (Model)

$$\mathbf{C} = E(\mathbf{x}\mathbf{x}^T)$$

Sensor Covariance Matrix

$$\mathbf{x}(t) = \mathbf{Kj}(t)$$

Forward Problem

$$\mathbf{C} = \mathbf{k}_{xq}\mathbf{k}_{xq}^T$$

for 1 dipole  $x$ -oriented at voxel  $q$  and amplitude 1

$$\mathbf{C} = \mathbf{K}_q\boldsymbol{\theta}_q\boldsymbol{\theta}_q^T\mathbf{K}_q^T$$

for 1 dipole oriented as  $\boldsymbol{\theta}_q = [x, y, z]$  at voxel  $q$  and amplitude 1

$$\mathbf{C} = \mathbf{K}_q\boldsymbol{\theta}_q\sigma_q^2\boldsymbol{\theta}_q^T\mathbf{K}_q^T$$

for 1 dipole oriented as  $\boldsymbol{\theta}_q$  and amplitude  $\sigma_q$  at voxel  $q$

$$\mathbf{C} = \mathbf{K}_q\boldsymbol{\theta}_q\sigma_q^2\boldsymbol{\theta}_q^T\mathbf{K}_q^T + \mathbf{K}_j\boldsymbol{\theta}_j\sigma_j^2\boldsymbol{\theta}_j^T\mathbf{K}_j^T$$

for 2 dipoles oriented as  $\boldsymbol{\theta}_p$  and  $\boldsymbol{\theta}_q$  and amplitude  $\sigma_p$  and  $\sigma_q$  at voxel  $p$  and  $q$

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$\mathbf{KK}^T$  Gram Matrix

# Weighted Regularized Minimum Norm Solution

$$\mathbf{j} = \mathbf{T}^T \mathbf{x} \quad \text{Inverse problem}$$

$$\mathbf{T}^T = \mathbf{K}^T \left( \mathbf{K} \mathbf{K}^T + \alpha \mathbf{H} \right)^{-1}, \quad \alpha \geq 0 \quad \rightarrow \text{Minimum Norm}$$

if  $\alpha = 0$  then  $\mathbf{T}^T = \mathbf{K}^+$

$$\mathbf{T}^T = \boldsymbol{\Theta}^{-1} \mathbf{K}^T \left( \mathbf{K} \boldsymbol{\Theta}^{-1} \mathbf{K}^T + \alpha \mathbf{H} \right)^{-1},$$

with  $\boldsymbol{\Theta} \in \mathbb{R}^{3Q \times 3Q}$  symmetric

$\rightarrow$  Weighted Minimum Norm  
(e.g., LORETA, eLORETA, but NOT sLORETA)

# sLORETA and eLORETA

sLORETA family (NOT a genuine solution)

$$\mathbf{T}_q^T = \left[ \left( \mathbf{K}_q^T \mathbf{Z} \mathbf{K}_q \right)^{-\frac{1}{2}} \mathbf{K}_q^T \mathbf{Z} \right]; \quad \mathbf{Z} \in \mathbb{R}^{N \times N} \text{ symmetric}$$

$$\mathbf{Z} = (\mathbf{K} \mathbf{K}^T + \alpha \mathbf{H})^{-1} \quad \rightarrow \text{sLORETA (model driven, maximum entropy, no a-priori)}$$

$$\mathbf{Z} = (\mathbf{C} + \alpha \mathbf{H})^{-1} \quad \rightarrow \text{sLORETA (data driven)}$$

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eLORETA (a genuine solution)

$$\mathbf{T}_q^T = \boldsymbol{\Theta}_q^{-1} \mathbf{K}_q^T \left( \mathbf{K} \boldsymbol{\Theta}^{-1} \mathbf{K}^T + \alpha \mathbf{H} \right)^{-1}, \quad \boldsymbol{\Theta} \in \mathbb{R}^{3Q \times 3Q} \text{ symmetric and block-diagonal,}$$

$$\boldsymbol{\Theta}_q^{-1} = \left[ \mathbf{K}_q^T \left( \mathbf{K} \boldsymbol{\Theta}^{-1} \mathbf{K}^T + \alpha \mathbf{H} \right)^{-1} \mathbf{K}_q \right]^{\frac{1}{2}}$$

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$\mathbf{K} \mathbf{K}^T$  Gram Matrix

$\mathbf{K} \boldsymbol{\Theta}^{-1} \mathbf{K}^T$  Weighted Gram Matrix

# eLORETA: another view

$$\boldsymbol{\Theta}_q^{-1} = \left[ \mathbf{K}_q^T \left( \mathbf{K} \boldsymbol{\Theta}^{-1} \mathbf{K}^T + \alpha \mathbf{H} \right)^+ \mathbf{K}_q \right]^{\frac{1}{2}}$$

is the solution to the optimization problem:

$$\min_{\boldsymbol{\Theta}} \left\| \mathbf{I} - \left[ \boldsymbol{\Theta}^{-1} \mathbf{K}^T \left( \mathbf{K} \boldsymbol{\Theta}^{-1} \mathbf{K}^T + \alpha \mathbf{H} \right)^+ \mathbf{K} \boldsymbol{\Theta}^{-1} \right] \right\|^2,$$

which satisfies the set of matrix equations

$$\boldsymbol{\Theta}_q^2 = \mathbf{K}_q^T \left( \mathbf{K} \boldsymbol{\Theta}^{-1} \mathbf{K}^T + \alpha \mathbf{H} \right)^+ \mathbf{K}_q, \text{ for all } q : 1 \dots Q$$

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In practice: within-voxels and between-voxels uncorrelation criterium!

# eLORETA algorithm

**Initialize**  $\boldsymbol{\Theta} = \mathbf{I} \in \mathbb{R}^{3Q \times 3Q}$

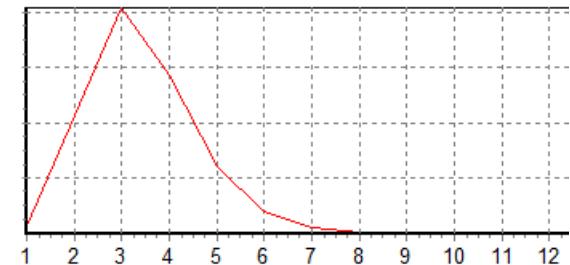
**Repeat**

$$\boldsymbol{\Pi} = (\mathbf{K}\boldsymbol{\Theta}^{-1}\mathbf{K}^T + \alpha\mathbf{H})^+ \in \mathbb{R}^{N \times N}$$

for each voxel  $q$  do  $\boldsymbol{\Theta}_q^{-1} = (\mathbf{K}_q^T \boldsymbol{\Pi} \mathbf{K}_q)^{-\frac{1}{2}} \in \mathbb{R}^{3 \times 3}$

**Until Convergence** (small changes in  $\boldsymbol{\Theta}$ )

Example Convergence (N=19)



→ eLORETA (model driven)

Trick:  $\mathbf{K}\boldsymbol{\Theta}^{-1}\mathbf{K}^T = \sum_q \mathbf{K}_q \boldsymbol{\Theta}_q^{-1} \mathbf{K}_q^T$

$$\boldsymbol{\Pi} = (\mathbf{C} + \alpha\mathbf{H})^+ \in \mathbb{R}^{N \times N}$$

for each voxel  $q$  do  $\boldsymbol{\Theta}_q^{-1} = (\mathbf{K}_q^T \boldsymbol{\Pi} \mathbf{K}_q)^{-\frac{1}{2}} \in \mathbb{R}^{3 \times 3}$

→ eLORETA (data driven) ?

Finally compute for each voxel  $q$

$$\mathbf{T}_q^T = \boldsymbol{\Theta}_q^{-1} \mathbf{K}_q^T (\mathbf{K}\boldsymbol{\Theta}^{-1}\mathbf{K}^T + \alpha\mathbf{H})^+$$

# Interesting Similarities

## Vector Type

$$\mathbf{T}_q^T = \left[ \left( \mathbf{K}_q^T \mathbf{C}^+ \mathbf{K}_q \right)^{-\frac{1}{2}} \mathbf{K}_q^T \mathbf{C}^+ \right] \rightarrow \text{sLORETA (data driven)}$$

$$\mathbf{T}_q^T = \left[ \left( \mathbf{K}_q^T \mathbf{C}^+ \mathbf{K}_q \right)^{-1} \mathbf{K}_q^T \mathbf{C}^+ \right] \rightarrow \text{LCMV Beamforming}$$

(must be normalized somehow: Sekihara and Nagarajan, 2008)

## Scalar Type

$$\mathbf{T}_q^T = \frac{\mathbf{k}_q^T \mathbf{C}^+}{\sqrt{\mathbf{k}_q^T \mathbf{C}^+ \mathbf{k}_q}} \rightarrow \text{sLORETA (data driven)}$$

$$\mathbf{T}_q^T = \frac{\mathbf{k}_q^T \mathbf{C}^+}{\mathbf{k}_q^T \mathbf{C}^+ \mathbf{k}_q} \rightarrow \text{LCMV Beamforming}$$

(must be normalized somehow)

# Relevant Performance Indeces

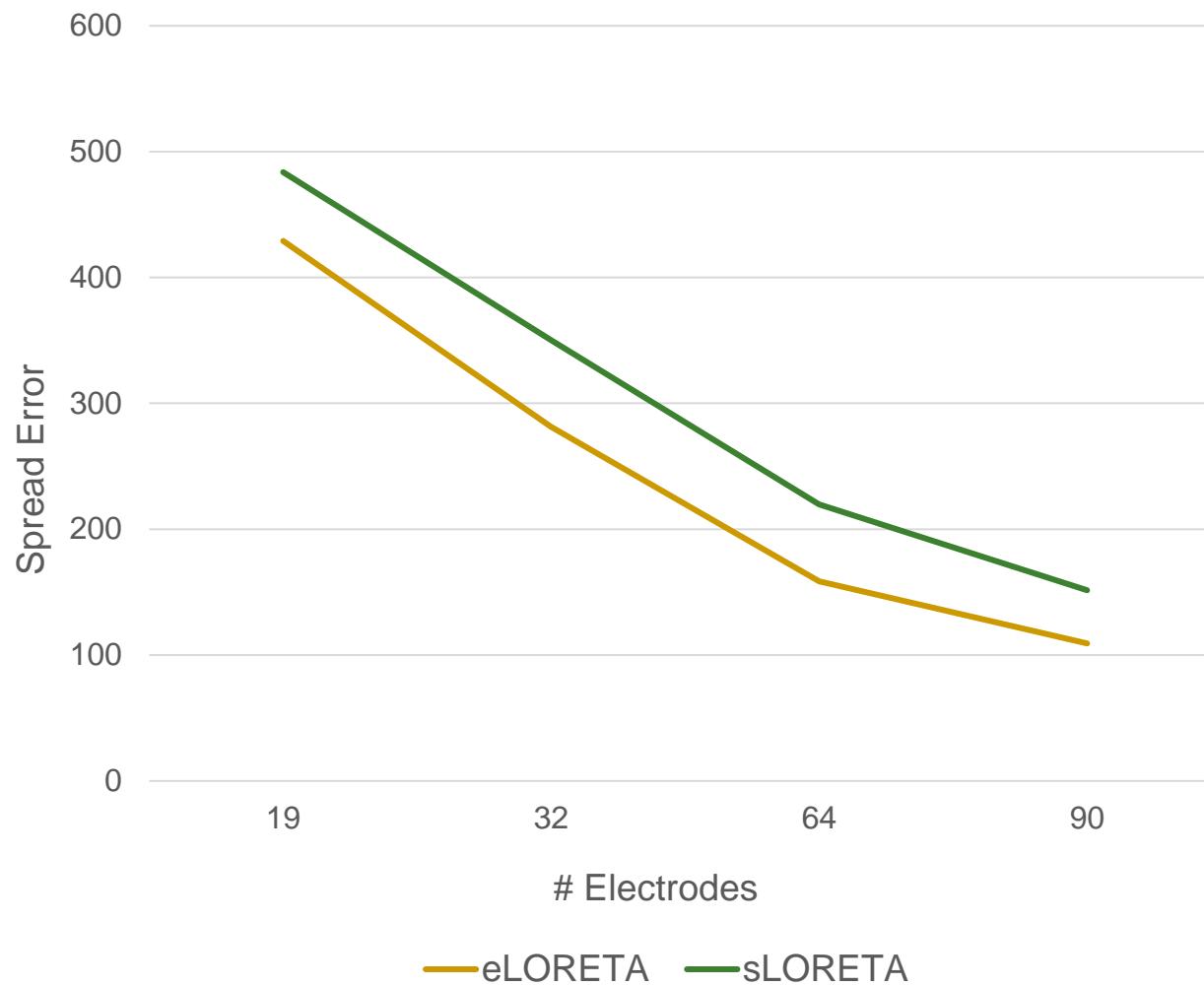
- Spread Error:

Average (energy not in test location / energy in test location)

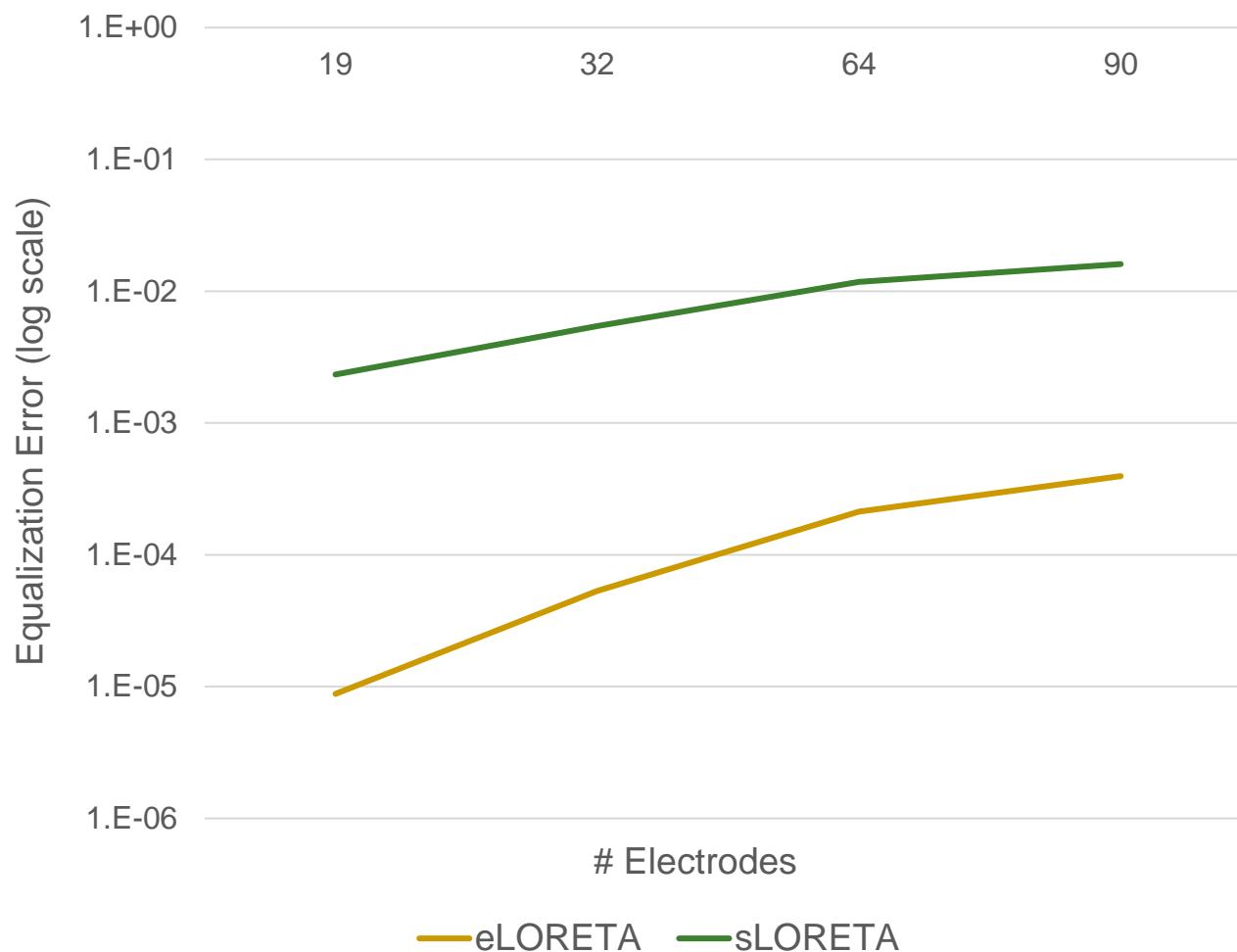
- Equalization Error:

variance of energy across test locations and orientations

# Comparing sLORETA vs eLORETA



# Comparing sLORETA vs eLORETA



# Upper Bounds for Data Driven sLORETA

$$\mathbf{T}_q^T = \left( \mathbf{K}_q^T \mathbf{C} \mathbf{K}_q \right)^{-\frac{1}{2}} \mathbf{K}_q^T \mathbf{C}$$

- $\mathbf{C} = (\mathbf{K}\mathbf{K}^T)^+ \rightarrow$  sLORETA  
(no a-priori, maximum entropy, model-driven covariance)
  
- $\mathbf{C} = (\mathbf{K}_q \mathbf{K}_q^T)^+ \rightarrow$  Position
  
- $\mathbf{C} = (\mathbf{K}_\theta \mathbf{K}_\theta^T)^+ \rightarrow$  Orientation
  
- $\mathbf{C} = (\mathbf{k}_{q\theta} \mathbf{k}_{q\theta}^T)^+ \rightarrow$  Position + Orientation

# Results (1/2)

Ratio: 1495					
SPREAD ERROR	eLORETA	sLORETA	Pos+Orient	Pos	Orient
19	429.0615974	483.6912568	0.32347742	0.47575874	406.1040238
32	281.2597383	350.1400515	0.19188051	0.27920945	296.7390919
64	158.5638184	219.6632052	0.08993596	0.11086595	167.5994111
90	109.2754763	151.5266824	0.02709140	0.02887675	107.3542492

Ratio: 5593

# Results (2/2)

EQUALIZATION ERROR					
Electrodes	eLORETA	sLORETA	Pos+Orient	Pos	Orient
19	0.00000881	0.00233484	0.00002256	0.00003151	0.00794155
32	0.00005328	0.00545325	0.00001283	0.00001824	0.01568172
64	0.00021251	0.01177894	0.00000722	0.00001068	0.03443352
90	0.00039541	0.01606805	0.00000190	0.00000194	0.04777370

Ratio: 103

Ratio: 8457