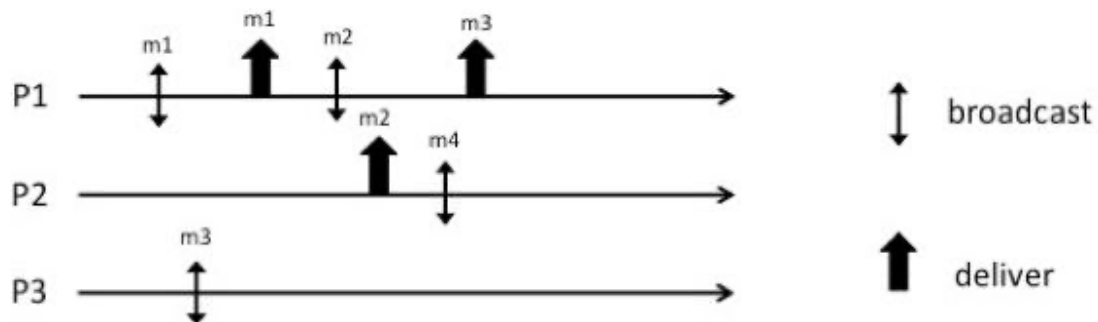


**Dependable Distributed Systems**  
**Master of Science in Engineering in Computer Science**

AA 2024/2025

**Lecture 16 – Exercises**  
**November 6<sup>th</sup>, 2024**

**Ex 1:** Let us consider the following partial execution



Answer the following points:

1. Provide all the possible sequences satisfying Causal Order
2. Complete the execution to have a run satisfying FIFO order but not causal order

**Ex 2:** Consider a distributed system constituted by  $n$  processes  $\Pi = \{p_1, p_2, \dots, p_n\}$  with unique identifiers that exchange messages through FIFO perfect point-to-point links and are structured through a line (i.e., each process  $p_i$  can exchange messages only with processes  $p_{i-1}$  and  $p_{i+1}$  when they exist). Processes may crash and each process is equipped with a perfect oracle (having the interface  $new\_right(p)$  and  $new\_left(p)$ ) reporting a new neighbor when the previous one is failing.

Write the pseudo-code of an algorithm implementing a Perfect failure detector primitive.

**Ex 3:** Consider a distributed system constituted by  $n$  processes  $\Pi = \{p_1, p_2, \dots, p_n\}$  with unique identifiers that exchange messages through perfect point-to-point links and are structured through a ring (i.e., each process  $p_i$  can exchange messages only with processes  $p_{i-1}$  and  $p_{i+1 \pmod n}$ ). Processes may crash and each process is equipped with a perfect oracle (having the interface  $new\_next(p)$ ) reporting a new neighbor when the previous one is failing.

Write the pseudo-code of an algorithm implementing a Uniform Reliable Broadcast communication primitive.

**Ex 4:** A transient failure is a failure that affects a process temporarily and that randomly alter the state of the process (i.e., when the process is affected by a transient failure, its local variables assume a random value).

Let us consider a distributed system composed by  $N$  processes where  $f_c$  processes can fail by crash and  $f_t$  processes can suffer transient failures between time  $t_0$  and  $t_{stab}$ .

Let us consider the following algorithm implementing the Regular Reliable Broadcast specification

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**Algorithm 3.2:** Lazy Reliable Broadcast

---

**Implements:**  
ReliableBroadcast, **instance**  $rb$ .

**Uses:**  
BestEffortBroadcast, **instance**  $beb$ ;  
PerfectFailureDetector, **instance**  $\mathcal{P}$ .

**upon event**  $\langle rb, Init \rangle$  **do**  
     $correct := \Pi$ ;  
     $from[p] := [\emptyset]^N$ ;

**upon event**  $\langle rb, Broadcast \mid m \rangle$  **do**  
    **trigger**  $\langle beb, Broadcast \mid [DATA, self, m] \rangle$ ;

**upon event**  $\langle beb, Deliver \mid p, [DATA, s, m] \rangle$  **do**  
    **if**  $m \notin from[s]$  **then**  
        **trigger**  $\langle rb, Deliver \mid s, m \rangle$ ;  
         $from[s] := from[s] \cup \{m\}$ ;  
        **if**  $s \notin correct$  **then**  
            **trigger**  $\langle beb, Broadcast \mid [DATA, s, m] \rangle$ ;

**upon event**  $\langle \mathcal{P}, Crash \mid p \rangle$  **do**  
     $correct := correct \setminus \{p\}$ ;  
    **forall**  $m \in from[p]$  **do**  
        **trigger**  $\langle beb, Broadcast \mid [DATA, p, m] \rangle$ ;

---

Answer to the following questions:

1. For every property of the Regular Reliable Broadcast specification, discuss if it is guaranteed between time  $t_0$  and  $t_{stab}$  and provide a motivation for your answer.
2. For every property of the Regular Reliable Broadcast specification, discuss if it is eventually guaranteed after  $t_{stab}$  and provide a motivation for your answer.
3. Assuming that the system is synchronous, explain if and how you can modify the algorithm (no pseudo-code required) to guarantee that No Duplication, Validity and Agreement properties will be eventually guaranteed after  $t_{stab}$ .

**Ex 5:** Let us consider the following algorithm

```

upon event  $\langle frb, Init \rangle$  do
   $lsn := 0;$ 
   $pending := \emptyset;$ 
   $next := [1]^N;$ 

upon event  $\langle frb, Broadcast \mid m \rangle$  do
  for each  $p$  do
    trigger  $\langle l, send \mid p, [DATA, self, m, lsn] \rangle;$ 
   $lsn := lsn + 1;$ 

upon event  $\langle l, deliver \mid p, [DATA, s, m, sn] \rangle$  do
   $pending := pending \cup \{(s, m, sn)\};$ 

while exists  $(s, m', sn') \in pending$  such that  $sn' = next[s]$  do
   $next[s] := next[s] + 1;$ 
   $pending := pending \setminus \{(s, m', sn')\};$ 
  trigger  $\langle frb, Deliver \mid s, m' \rangle.$ 

```

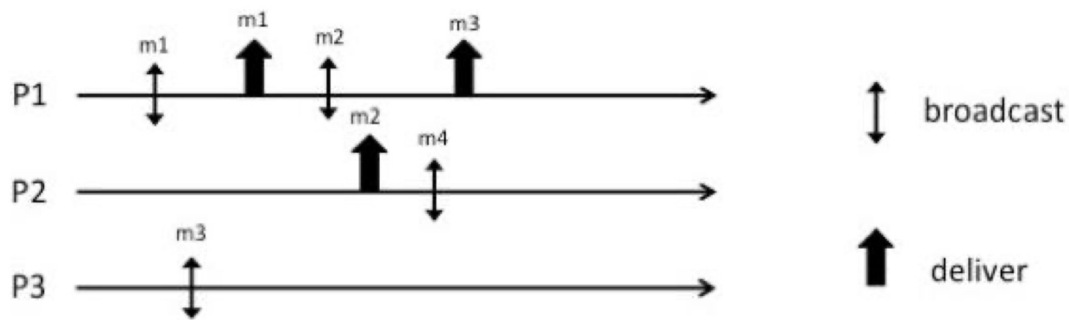
Let us consider the following properties:

- **Validity:** If a correct process  $p$  broadcasts a message  $m$ , then  $p$  eventually delivers  $m$ .
- **No duplication:** No message is delivered more than once.
- **No creation:** If a process delivers a message  $m$  with sender  $s$ , then  $m$  was previously broadcast by process  $s$ .
- **Agreement:** If a message  $m$  is delivered by some correct process, then  $m$  is eventually delivered by every correct process.
- **FIFO delivery:** If some process broadcasts message  $m_1$  before it broadcasts message  $m_2$ , then no correct process delivers  $m_2$  unless it has already delivered  $m_1$ .

Assuming that every process may fail by crash, address the following points:

1. Considering that messages are sent by using *perfect point to point links*, for each property mentioned, discuss if it is satisfied or not and provide a motivation for your answer;
2. Considering that messages are sent by using *fair loss links*, for each property mentioned, discuss if it is satisfied or not and provide a motivation for your answer.

Ex 1: Let us consider the following partial execution



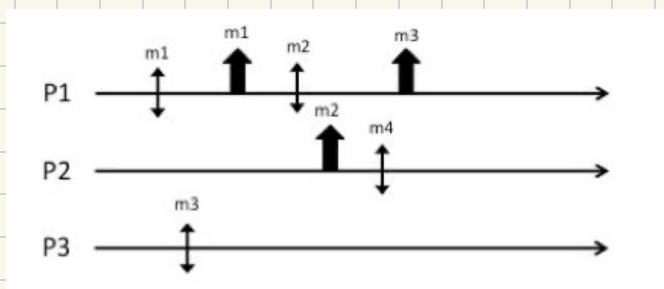
Answer the following points:

1. Provide all the possible sequences satisfying Causal Order
2. Complete the execution to have a run satisfying FIFO order but not causal order

**CASUAL ORDER = FIFO ORDER + LOCAL ORDER**

**LOCAL ORDER:** IF A PROCESS DELIVERS A MESSAGE  $m_i$ , BEFORE SENDING A MESSAGE  $m_j$ , THEN NO CORRECT PROCESS DELIVER  $m_j$  IF IT HAS NOT ALREADY DELIVERED  $m_i$ .

1)



$m_1 \rightarrow m_2$  FIFO ORDER  
 $m_2 \rightarrow m_4$  LOCAL ORDER

POSSIBLE SEQUENCES.

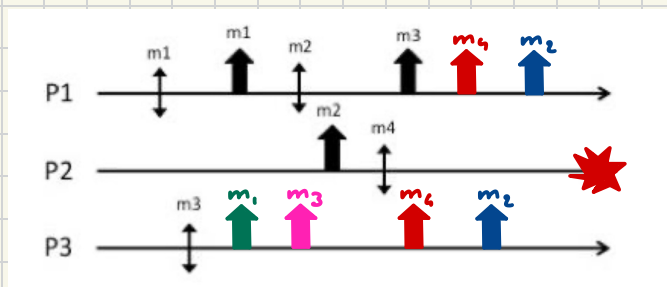
$m_1, m_2, m_3, m_4$

$m_1, m_2, m_4, m_3$

$m_1, m_3, m_2, m_4$

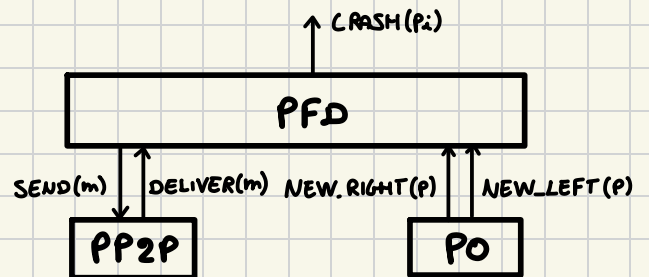
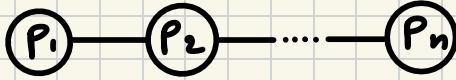
$m_3, m_1, m_2, m_4$  NOT FOR P<sub>1</sub>

2)



$m_1 \rightarrow m_2$  FIFO ORDER  
 ~~$m_2 \rightarrow m_4$~~  NOT CASUAL ORDER

Ex 2: Consider a distributed system constituted by  $n$  processes  $\Pi = \{p_1, p_2, \dots, p_n\}$  with unique identifiers that exchange messages through FIFO perfect point-to-point links and are structured through a line (i.e., each process  $p_i$  can exchange messages only with processes  $p_{i-1}$  and  $p_{i+1}$  when they exist). Processes may crash and each process is equipped with a perfect oracle (having the interface  $new\_right(p)$  and  $new\_left(p)$ ) reporting a new neighbor when the previous one is failing. Write the pseudo-code of an algorithm implementing a Perfect failure detector primitive.



INIT

```

ALIVE =  $\Pi$ 
SUSPECTED =  $\emptyset$ 
IF ID == 1
  LEFT = NULL
ELSE IF ID == n
  RIGHT = NULL
ELSE
  LEFT =  $p_{i-1}$ 
  RIGHT =  $p_{i+1}$ 
STARTTIMER(A)
  
```

UPON EVENT  $\langle PO, NEW\_RIGHT / p \rangle$  DO

```

IF RIGHT != NULL
  CRASH.R = RIGHT
  SUSPECTED = SUSPECTED  $\cup$  {CRASH.R}
  TRIGGER  $\langle PFD, CRASH / CRASH.R \rangle$ 
  TRIGGER  $\langle PP2PL, PP2PL.SEND / [CRASH, CRASH.R] \rangle$  TO RIGHT
  
```

UPON EVENT  $\langle PO, NEW\_LEFT / p \rangle$  DO

```

IF LEFT != NULL
  CRASH.L = LEFT
  SUSPECTED = SUSPECTED  $\cup$  {CRASH.L}
  TRIGGER  $\langle PFD, CRASH / CRASH.L \rangle$ 
  TRIGGER  $\langle PP2PL, PP2PL.SEND / [CRASH, CRASH.L] \rangle$  TO LEFT
  
```

UPON EVENT  $\langle PP2PL, PP2PL.DELIVER / [CRASH, p] \rangle$  DO

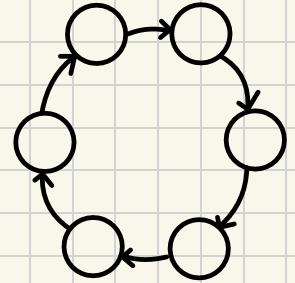
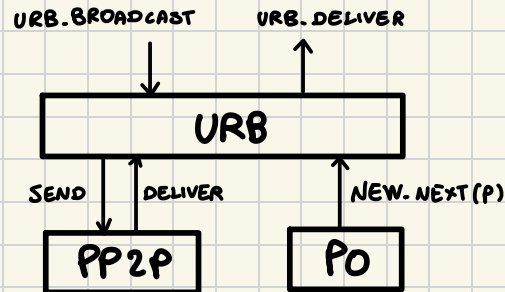
```

IF SUSPECTED !=  $\emptyset$ 
  FOR EACH  $p_i$  IN SUSPECTED
    LEFT = NEW_LEFT
    RIGHT = NEW_RIGHT
    TRIGGER  $\langle PP2PL, PP2PL.SEND / [CRASH] \rangle$  TO LEFT
    TRIGGER  $\langle PP2PL, PP2PL.SEND / [CRASH] \rangle$  TO RIGHT
  
```



Ex 3: Consider a distributed system constituted by  $n$  processes  $\Pi = \{p_1, p_2, \dots, p_n\}$  with unique identifiers that exchange messages through perfect point-to-point links and are structured through a ring (i.e., each process  $p_i$  can exchange messages only with processes  $p_{i-1}$  and  $p_{i+1 \pmod n}$ ). Processes may crash and each process is equipped with a perfect oracle (having the interface  $new\_next(p)$ ) reporting a new neighbor when the previous one is failing.

Write the pseudo-code of an algorithm implementing a Uniform Reliable Broadcast communication primitive.



INIT

```

CORRECT =  $\Pi$ 
PENDING =  $\emptyset$ 
DELIVERED =  $\emptyset$ 
ACK =  $\emptyset$ 
FLAG = FALSE

```

UPON EVENT  $\langle \text{URB}, \text{SEND} | m \rangle$  DO

```

FLAG = TRUE
TRIGGER  $\langle \text{PP2PL}, \text{SEND} | (\text{ACK}, m) \rangle$  TO NEXT

```

UPON EVENT  $\langle \text{PP2PL}, \text{DELIVER} | (\text{ACK}, m) \rangle$  FROM  $p$  DO

```

ACK = ACK  $\cup \{p\}$ 
IF  $m \notin \text{PENDING}$ 
    PENDING = PENDING  $\cup \{m\}$ 
    IF RIGHT.FLAG  $\neq$  TRUE
        TRIGGER  $\langle \text{PP2PL}, \text{SEND} | (\text{ACK}, m) \rangle$  TO NEXT

```

FUNCTION CANDELIVER( $m$ ) RETURNS BOOLEAN IS  
 RETURN CORRECT  $\subseteq$  ACK( $m$ )

UPON EXISTS  $m \in \text{PENDING}$  SUCH THAT CANDELIVER( $m$ )  $\wedge m \notin \text{DELIVERED}$  DO  
 DELIVERED = DELIVERED  $\cup \{m\}$   
 TRIGGER  $\langle \text{URB}, \text{DELIVER} | m \rangle$

UPON EVENT  $\langle \text{CRASH} | p \rangle$  DO

```

CORRECT = CORRECT  $\setminus \{p\}$ 
TRIGGER  $\langle \text{NEW\_NEXT} | p \rangle$ 

```

UPON EVENT  $\langle \text{NEW\_NEXT} | p \rangle$  DO

```

NEXT =  $p$ 
FORALL  $m$  IN PENDING
    TRIGGER  $\langle \text{PP2PL}, \text{SEND} | (\text{ACK}, m) \rangle$  TO NEXT

```

**Ex 4:** A transient failure is a failure that affects a process temporarily and that randomly alter the state of the process (i.e., when the process is affected by a transient failure, its local variables assume a random value).

Let us consider a distributed system composed by  $N$  processes where  $f_c$  processes can fail by crash and  $f_t$  processes can suffer transient failures between time  $t_0$  and  $t_{stab}$ .

Let us consider the following algorithm implementing the Regular Reliable Broadcast specification

---

**Algorithm 3.2:** Lazy Reliable Broadcast

---

**Implements:**

ReliableBroadcast, instance  $rb$ .

**Uses:**

BestEffortBroadcast, instance  $beb$ ;

PerfectFailureDetector, instance  $\mathcal{P}$ .

**upon event**  $\langle rb, Init \rangle$  **do**

$correct := \Pi$ ;

$from[p] := \{\emptyset\}^N$ ;

**upon event**  $\langle rb, Broadcast \mid m \rangle$  **do**

**trigger**  $\langle beb, Broadcast \mid [DATA, self, m] \rangle$ ;

**upon event**  $\langle beb, Deliver \mid p, [DATA, s, m] \rangle$  **do**

**if**  $m \notin from[s]$  **then**

**trigger**  $\langle rb, Deliver \mid s, m \rangle$ ;

$from[s] := from[s] \cup \{m\}$ ;

**if**  $s \notin correct$  **then**

**trigger**  $\langle beb, Broadcast \mid [DATA, s, m] \rangle$ ;

**upon event**  $\langle \mathcal{P}, Crash \mid p \rangle$  **do**

$correct := correct \setminus \{p\}$ ;

**forall**  $m \in from[p]$  **do**

**trigger**  $\langle beb, Broadcast \mid [DATA, p, m] \rangle$ ;

---

Answer to the following questions:

1. For every property of the Regular Reliable Broadcast specification, discuss if it is guaranteed between time  $t_0$  and  $t_{stab}$  and provide a motivation for your answer.
2. For every property of the Regular Reliable Broadcast specification, discuss if it is eventually guaranteed after  $t_{stab}$  and provide a motivation for your answer.
3. Assuming that the system is synchronous, explain if and how you can modify the algorithm (no pseudo-code required) to guarantee that No Duplication, Validity and Agreement properties will be eventually guaranteed after  $t_{stab}$ .

1) BETWEEN  $\tau_0$  AND  $\tau_{stab}$  LOCAL VARIABLES OF  $P_i$  PROCESSES CAN ASSUME RANDOM VALUES.

VALIDITY: NOT GUARANTEED BECAUSE OF TRANSIENT FAILURE THAT CAN ALTER THE VALUE OF THE MESSAGE SENT BUT NOT ALREADY DELIVERED.

NO DUPLICATION: NOT GUARANTEED SINCE THE VALUES ARE RANDOM AND COULD HAPPEN TO HAVE TWO SAME VALUES TO DELIVER.

NO CREATION: NOT GUARANTEED BECAUSE OF TRANSIENT FAILURE THAT ALTERING VALUES COULD CREATE A NEW MESSAGE.

AGREEMENT: NOT GUARANTEED. DUE TO TRANSIENT FAILURE, ONE OR MORE PROCESSES MAY DELIVER  $m$ , WHILE OTHERS MAY NOT.

2) AFTER  $\tau_{stab}$ , THE PROCESSES BECAME NORMAL AND THEY CANNOT CHANGE ARBITRARY THEIR LOCAL VARIABLES AND THOSE VALUES CAN BE WRONG. SO VALIDITY, NO DUPLICATION AND AGREEMENT ARE NOT GUARANTEED, BUT NO CREATION IS GUARANTEED BECAUSE A PROCESS WILL NOT DELIVER  $m$  IF THE MESSAGE WAS NEVER SENT.

3) IN ORDER TO GUARANTEE VALIDITY, NO DUPLICATION AND AGREEMENT WE HAVE TO STORE THE STATUS OF SENT AND RECEIVED MESSAGES TO RETRIEVE THE STATUS, TO UNIQUELY IDENTIFY MESSAGES THROUGH TIMESTAMPS AND TO RETRANSMIT MESSAGES AFTER  $\tau_{stab}$ .

Ex 5: Let us consider the following algorithm

```
upon event ( frb, Init ) do
  lsn := 0;
  pending := ∅;
  next := [1]N;

upon event ( frb, Broadcast | m ) do
  for each p do
    trigger ( l, send | p, [DATA, self, m, lsn] );
    lsn := lsn + 1;

upon event ( l, deliver | p, [DATA, s, m, sn] ) do
  pending := pending ∪ {(s, m, sn)};

while exists (s, m', sn') ∈ pending such that sn' = next[s] do
  next[s] := next[s] + 1;
  pending := pending \ {(s, m', sn')};
  trigger ( frb, Deliver | s, m' );
```

- Let us consider the following properties:
- **Validity:** If a correct process p broadcasts a message m, then p eventually delivers m.
  - **No duplication:** No message is delivered more than once.
  - **No creation:** If a process delivers a message m with sender s, then m was previously broadcast by process s.
  - **Agreement:** If a message m is delivered by some correct process, then m is eventually delivered by every correct process.
  - **FIFO delivery:** If some process broadcasts message m<sub>1</sub> before it broadcasts message m<sub>2</sub>, then no correct process delivers m<sub>2</sub> unless it has already delivered m<sub>1</sub>.

Assuming that every process may fail by crash, address the following points:

1. Considering that messages are sent by using *perfect point to point links*, for each property mentioned, discuss if it satisfied or not and provide a motivation for your answer;
2. Considering that messages are sent by using *fair loss links*, for each property mentioned, discuss if it satisfied or not and provide a motivation for your answer.

Proprietà	PP2PL	FLL
Perdita di messaggi	Nessuna perdita.	I messaggi possono essere persi.
Duplicazione	Nessun messaggio duplicato.	I messaggi possono essere duplicati.
Creazione	Nessun messaggio creato arbitrariamente.	Nessun messaggio creato arbitrariamente.
Garanzia di consegna	Sempre garantita.	Garantita solo con ritrasmissione.

1) PP2PL

**VALIDITY:** GUARANTEED ONLY IF THE PROCESS DOESN'T CRASH BEFORE TRANSMITTING m.  
**NO DUPLICATION:** GUARANTEED THANKS TO PERFECT CHANNELS AND DUPLICATE CONTROL.  
**NO CREATION:** GUARANTEED, BECAUSE MESSAGES MUST BE TRANSMITTED BY AN IDENTIFIABLE PROCESS.  
**AGREEMENT:** NOT GUARANTEED, BECAUSE NOT HAVING A PFD WE CANNOT KNOW IF m IS DELIVERED BY A CORRECT PROCESS OR NOT.  
**FIFO DELIVERY:** NOT GUARANTEED, SAME AS ABOVE.

2) FLL

**VALIDITY:** NOT GUARANTEED, NOT HAVING PERFECT LINKS A MESSAGE CAN BE LOST.  
**NO DUPLICATION:** NOT GUARANTEED, SINCE DUPLICATES ARE ALLOWED IN FLL.  
**NO CREATION:** GUARANTEED, FROM NO CREATION PROPERTY OF FLL.  
**AGREEMENT:** NOT GUARANTEED, BECAUSE NOT HAVING A PFD WE CANNOT KNOW IF m IS DELIVERED BY A CORRECT PROCESS OR NOT.  
**FIFO DELIVERY:** NOT GUARANTEED, SAME AS ABOVE.