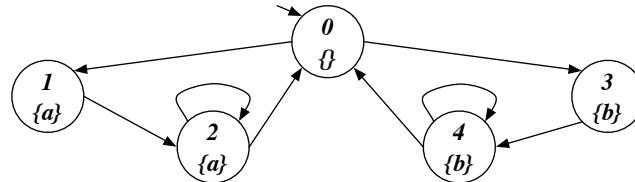


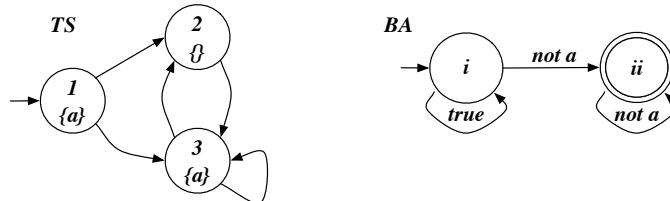
Part 1. Consider the following transition system:



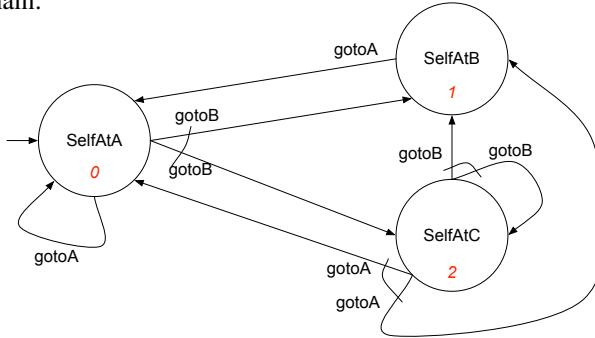
- **Exercise 1.1:** Model check the Mu-Calculus formula: $\nu X.\mu Y.((a \wedge [next]X) \vee (b \wedge \langle next \rangle Y))$

- **Exercise 1.2:** Model check the CTL formula $AF(EG(a \supset AXEX\neg a))$, by translating it in Mu-Calculus.
-

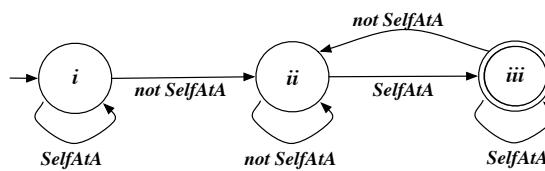
Part 2 Consider the transition system TS below. Model check the LTL formula $\square\lozenge a$, by considering that the Büchi automaton BA for $\neg\square\lozenge a$ (i.e., $\lozenge\square\neg a$) is the one below:



Part 3 Consider the following domain:



- **Exercise 2.1:** Synthesize a strategy (a plan) for realizing the LTLf formula $\lozenge(\neg SelfAtA \wedge \lozenge(SelfAtA \wedge \bullet false))$, by considering that the corresponding DFA is the one below:



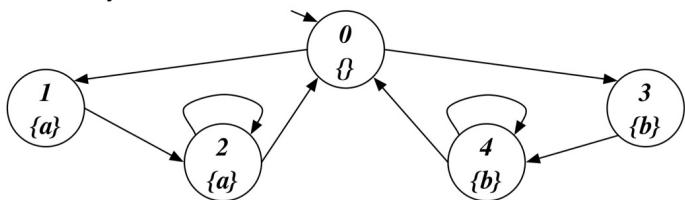
Part 4 (optional) Consider the following program:

```
while (x<10) do x := x + 1
```

Compute its *execution* and *final state*, starting from an *initial state* where $x = 9$, by using:

1. Evaluation Semantics;
 2. Transition Semantics.
-

Part 1. Consider the following transition system:



- **Exercise 1.1:** Model check the Mu-Calculus formula: $\nu X. \mu Y. ((a \wedge [next]X) \vee (b \wedge \langle next \rangle Y))$

- **Exercise 1.2:** Model check the CTL formula $AF(EG(a \supset AXEX\neg a))$, by translating it in Mu-Calculus.

$$1) \quad \varphi = \nu X. \mu Y. ((a \wedge [next]X) \vee (b \wedge \langle next \rangle Y))$$

$$[x_0] = \{0, 1, 2, 3, 4\}$$

$$[x_1] = [\mu Y. ((a \wedge [next]X_0) \vee (b \wedge \langle next \rangle Y))]$$

$$[Y_0] = \emptyset$$

$$[Y_1] = ([a] \cap \text{PREA}(\text{NEXT}, X_0)) \cup ([b] \cap \text{PREE}(\text{NEXT}, Y_0)) =$$

$$= (\{1, 2\} \cap \{0, 1, 2, 3, 4\}) \cup (\{3, 4\} \cap \emptyset) = \{1, 2\}$$

$$[Y_2] = ([a] \cap \text{PREA}(\text{NEXT}, X_0)) \cup ([b] \cap \text{PREE}(\text{NEXT}, Y_1)) =$$

$$= (\{1, 2\} \cap \{0, 1, 2, 3, 4\}) \cup (\{3, 4\} \cap \{0, 1, 2\}) = \{1, 2\}$$

$$[Y_1] = [Y_2] = [x_1] = \{1, 2\}$$

$$[x_2] = [\mu Y. ((a \wedge [next]X_1) \vee (b \wedge \langle next \rangle Y))]$$

$$[Y_0] = \emptyset$$

$$[Y_1] = ([a] \cap \text{PREA}(\text{NEXT}, X_1)) \cup ([b] \cap \text{PREE}(\text{NEXT}, Y_0)) =$$

$$= (\{1, 2\} \cap \{1\}) \cup (\{3, 4\} \cap \emptyset) = \{1\}$$

$$[Y_2] = ([a] \cap \text{PREA}(\text{NEXT}, X_1)) \cup ([b] \cap \text{PREE}(\text{NEXT}, Y_0)) =$$

$$= (\{1, 2\} \cap \{1\}) \cup (\{3, 4\} \cap \{0\}) = \{1\}$$

$$[Y_1] = [Y_2] = [x_2] = \{1\}$$

$$[x_3] = [\mu Y. ((a \wedge [next]X_2) \vee (b \wedge \langle next \rangle Y))]$$

$$[Y_0] = \emptyset$$

$$[Y_1] = ([a] \cap \text{PREA}(\text{NEXT}, X_2)) \cup ([b] \cap \text{PREE}(\text{NEXT}, Y_0)) =$$

$$= (\{1, 2\} \cap \emptyset) \cup (\{3, 4\} \cap \emptyset) = \emptyset$$

$$[Y_0] = [Y_1] = [x_3] = \emptyset$$

$$[x_4] = [\mu Y. ((\alpha \wedge [NEXT]X_3) \vee (b \wedge \langle NEXT \rangle Y))]$$

$$[Y_0] = \emptyset$$

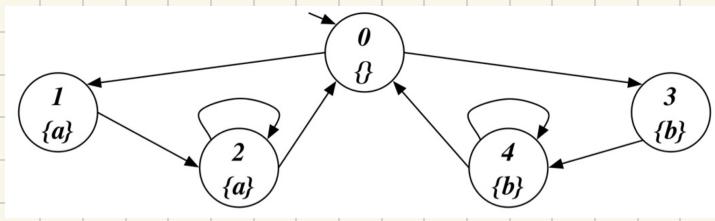
$$\begin{aligned}[Y_1] &= ([\alpha] \cap PREA(NEXT, X_3)) \cup ([b] \cap PREE(NEXT, Y_0)) = \\ &= (\{1, 2\} \cap \emptyset) \cup (\{3, 4\} \cap \emptyset) = \emptyset\end{aligned}$$

$$[Y_0] = [Y_1] = [X_3] = \emptyset$$

$$[X_3] = [X_4] = \emptyset$$

2) $AF(EG(\alpha \Rightarrow AXEX \gamma \alpha))$

$$\begin{array}{c} \alpha \\ \hline \beta \\ \hline \gamma \\ \hline \delta \\ \hline \epsilon \end{array}$$



$$[\alpha] = [EX \gamma \alpha] = [\langle NEXT \rangle \gamma \alpha] = PREE(NEXT, \gamma \alpha) = \{0, 2, 3, 4\} = [\alpha]$$

$$[\beta] = [AX \alpha] = [[NEXT] \alpha] = PREA(NEXT, \alpha) = \{1, 2, 3, 4\} = [\beta]$$

$$[\gamma] = [\alpha \Rightarrow \beta] = [\gamma \alpha] \cup [\beta] = \{0, 3, 4\} \cup \{1, 2, 3, 4\} = \{0, 1, 2, 3, 4\} = [\gamma]$$

$$[\delta] = [EG \gamma] = [UZ. \gamma \wedge \langle NEXT \rangle Z]$$

$$[Z_0] = \{0, 1, 2, 3, 4\}$$

$$[Z_1] = [\gamma] \cap PREE(NEXT, Z_0) =$$

$$= \{0, 1, 2, 3, 4\} \cap \{0, 1, 2, 3, 4\} = \{0, 1, 2, 3, 4\} \quad [Z_0] = [Z_1] = [\delta] = \{0, 1, 2, 3, 4\}$$

$$[\epsilon] = [AF \delta] = [\mu Z. \delta \vee [NEXT] Z]$$

$$[Z_0] = \emptyset$$

$$[Z_1] = [\delta] \cup PREA(NEXT, Z_0) =$$

$$= \{0, 1, 2, 3, 4\} \cup \emptyset = \{0, 1, 2, 3, 4\}$$

$$[Z_2] = [\delta] \cup PREA(NEXT, Z_1) =$$

$$= \{0, 1, 2, 3, 4\} \cup \{0, 1, 2, 3, 4\} = \{0, 1, 2, 3, 4\}$$

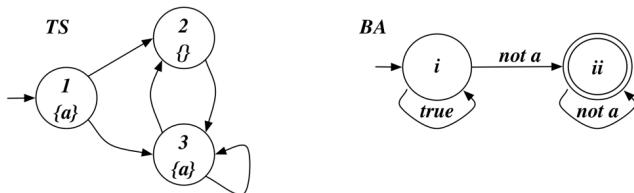
$$[Z_3] = [\delta] \cup PREA(NEXT, Z_2) =$$

$$= \{0, 1, 2, 3, 4\} \cup \{0, 1, 2, 3, 4\} = \{0, 1, 2, 3, 4\}$$

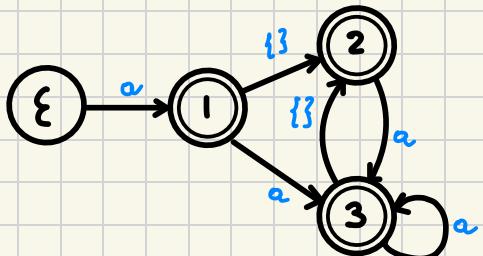
$$[Z_2] = [Z_3] = [\epsilon] = \{0, 1, 2, 3, 4\}$$

$S_0 \in [\epsilon] ? \quad YES!$

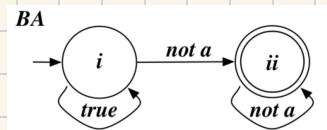
Part 2 Consider the transition system TS below. Model check the LTL formula $\square \diamond a$, by considering that the Büchi automaton BA for $\neg \square \diamond a$ (i.e., $\diamond \square \neg a$) is the one below:



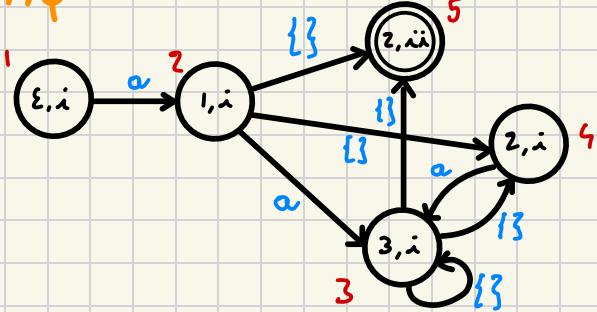
A_T :



$A_{T\varphi}$:



$A_T \cap A_{T\varphi}$:



$$\varphi = \cup X. \mu Y. (F \wedge \text{NEXT } X \vee \text{NEXT } Y)$$

$$[X_0] = \{1, 2, 3, 4, 5\}$$

$$[X_1] = [\mu Y. (F \wedge \text{NEXT } X_0 \vee \text{NEXT } Y)]$$

$$[Y_0] = \emptyset$$

$$[Y_1] = [F] \cap \text{PREE}(\text{NEXT}, X_0) \cup \text{PREE}(\text{NEXT}, Y_0) =$$

$$= \{5\} \cap \{1, 2, 3, 4\} \cup \emptyset = \emptyset$$

$$[Y_2] = [Y_1] = [X_1] = \emptyset$$

$$[X_2] = [\mu Y. (F \wedge \text{NEXT } X_1 \vee \text{NEXT } Y)]$$

$$[Y_0] = \emptyset$$

$$[Y_1] = [F] \cap \text{PREE}(\text{NEXT}, X_1) \cup \text{PREE}(\text{NEXT}, Y_0) =$$

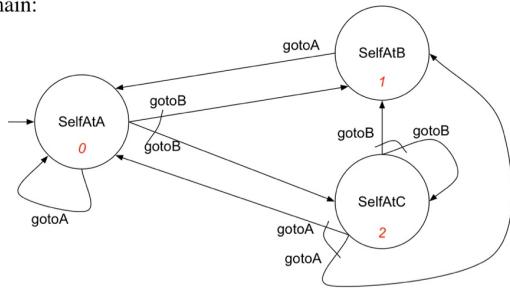
$$= \{5\} \cap \emptyset \cup \emptyset = \emptyset$$

$$[Y_2] = [Y_1] = [X_1] = \emptyset$$

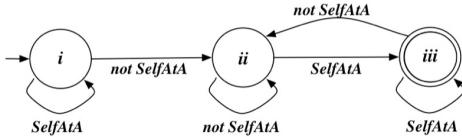
$$[X_1] = [X_2] = \emptyset$$

$S_1 \in [\varphi] = \emptyset ? \text{NO!}$

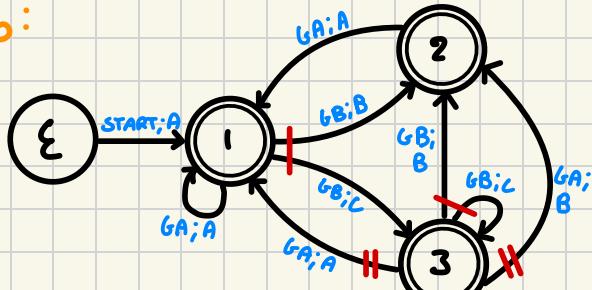
Part 3 Consider the following domain:



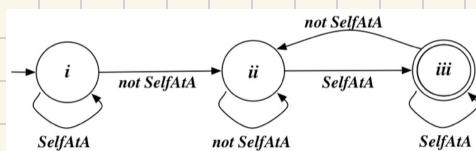
- Exercise 2.1:** Synthesize a strategy (a plan) for realizing the LTLf formula $\diamond(\neg \text{SelfAtA} \wedge \diamond(\text{SelfAtA} \wedge \bullet \text{false}))$, by considering that the corresponding DFA is the one below:



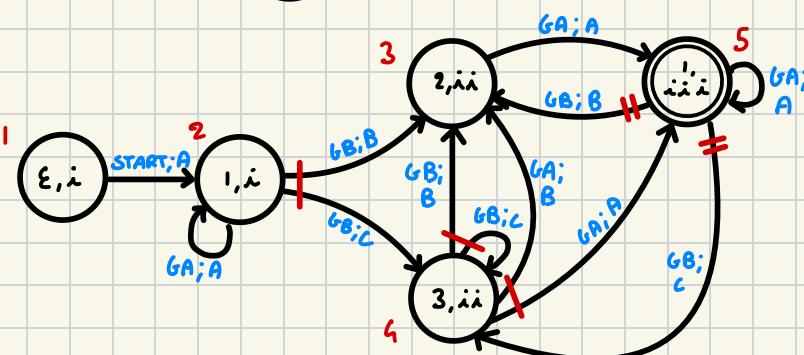
A_D :



A_φ :



$A_D \times A_\varphi$



$$W_0 = \{\epsilon\}$$

$$W_1 = W_0 \cup \text{PREADV}(W_0) = \{3, 5\}$$

$$W_2 = W_1 \cup \text{PREADV}(W_1) = \{3, 4, 5\}$$

$$W_3 = W_2 \cup \text{PREADV}(W_2) = \{2, 3, 4, 5\}$$

$$W_4 = W_3 \cup \text{PREADV}(W_3) = \{1, 2, 3, 4, 5\}$$

$$W_5 = W_4 \cup \text{PREADV}(W_4) = \{1, 2, 3, 4, 5\}$$

$$W_4 = W_5$$

$$\begin{aligned} W(1) &= \{\text{START}\} \\ W(2) &= \{GB\} \\ W(3) &= \{GA\} \\ W(4) &= \{GA, GB\} \\ W(5) &= \text{WIN} \end{aligned}$$

$$\begin{aligned} w_c(1) &= \text{START} \\ w_c(2) &= GB \\ w_c(3) &= GA \\ w_c(4) &= GA \\ w_c(5) &= \text{WIN} \end{aligned}$$

$$T = (2^x, S, S_0, P, w_c)$$

$$S = \{1, 2, 3, 4, 5\}$$

$$S_0 = \{1\}$$

$$P(S, x) = d(S, (w_c(S), x))$$

Part 4 (optional) Consider the following program:

while ($x < 10$) do $x := x + 1$

Compute its *execution* and *final state*, starting from an *initial state* where $x = 9$, by using:

1. *Evaluation Semantics*;
2. *Transition Semantics*.

1) $S_0 = \{x = 9\}$

$$\frac{\text{WHILE } (x < 10) \text{ DO } x := x + 1, S_0 \rightarrow S_F}{(x = x + 1, S_0) \xrightarrow{\text{TRUE}} S_1 \wedge (\text{WHILE } (x < 10) \text{ DO } x := x + 1, S_1) \xrightarrow{\text{TRUE}} S_F}$$

$$S_1 = S_F = \{x = 10\}$$

2) FIRST STEP

$$\frac{\text{WHILE } (x < 10) \text{ DO } x := x + 1, S_0 \rightarrow (d_1, S_1)}{x := x + 1, S_0 \xrightarrow{\text{TRUE}} (\epsilon, S_1)}$$

$$S_1 = \{x = 10\}$$

SECOND STEP

$$\frac{\epsilon; \text{ WHILE } (x < 10) \text{ DO } x := x + 1, S_1 \rightarrow (d_2, S_2)}{\text{TRUE}}$$

$$S_F = S_2 = S_1 = \{x = 10\}$$