objectTracking

private:

□ Mat ImgHSV□ Mat ImgOpening□ Mat ImgClosing□ Mat ImgCentroid

public:
O Mat Img
O int imageX
O int imageY
O uint16_t posX
O uint16_t posY
O uint16_t lastX
O uint16 t lastY

~objectTracking()

objectTracking(image transport::ImageTransport *it)

void centroid(Mat & Image, uint16 t &x, uint16 t &y)

void rgb2hsv(Mat & Image, Mat &Image)

void publishCoordinates(int x, int y)

void callBack(const sensor_msgs::ImageConstPtr &msg_)void imageViewer(Mat &Image, string windowName)

void morphologyOperation(Mat &_Image, Mat &Image_, int oper, int size, int elemen)

void drawCentroid(Mat & Image, Mat & Image, uint16 t posx, uint16 t posy, uint16 t lastx, uint16 t lasty)

□ image_transport
 □ Subscriber sub
 □ string nameOriginal
 □ string nameHSV
 □ string nameFilter
 □ string nameCentroid