

**Interrupt with LL Libraries** 

rev1.0 24/03/2020

#### GOAL

# Generate an interrupt when the blue push button has been pressed

#### **PREREQUISITES**

#### **Software needed:**

STM32IDE

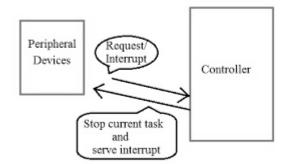
#### Hardware used in this example:

NUCLEO-F446ZE

#### What is an Interrupt?

An *interrupt* is an asynchronous signal that allows you to manage situations in which particular attention is needed: there may be events such that it is necessary for the microcontroller to temporarily interrupt the normal execution of the program in order to execute a certain process.

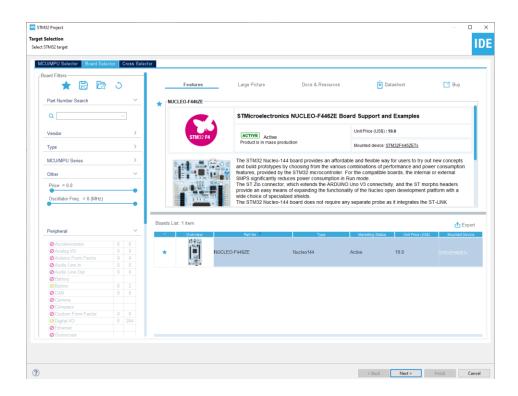
Examples that generate an interrupt may be the pressing of a button, rather than an event at regular time intervals (**timers**) or a certain input being exceeded by a certain threshold.



# Start a new project

From the stm32IDE software click on File -> New -> STM32 Project.

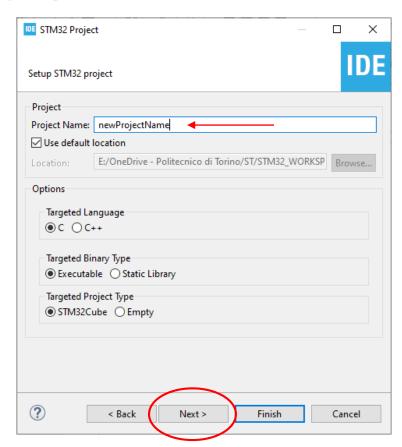
Select your board or your uC and click next.



## Start a new project

Type the name of your project and click next.

By default the project will be created in the workspace folder.



## Start a new project

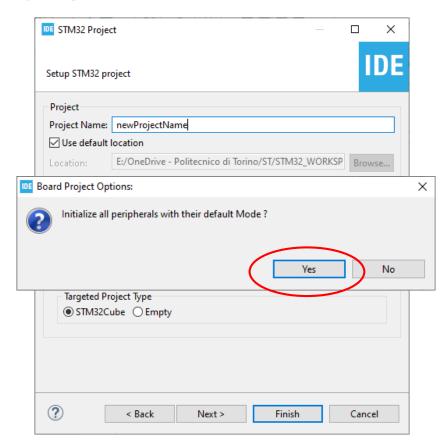
Type the name of your project and click next.

By default the project will be created in the *workspace* folder.

The *STM32IDE* has the option to initialize all the peripheral with their *default* mode:

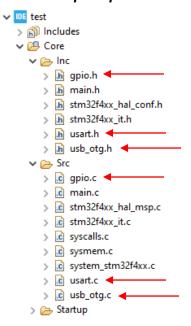
Clicking Yes the USART3, all the LEDs and the blue UserButton will be configured as default.

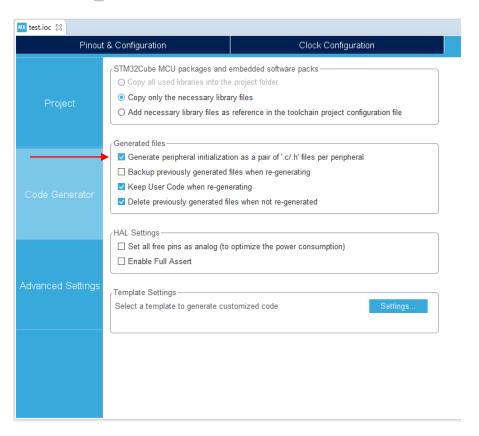
Click Yes.



#### **Project Manager**

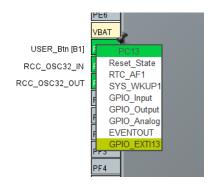
In the Code Generator Tab check the **Generate peripheral initialization [...]** box: each periperhal will have a disting periph.c and periph.h files.

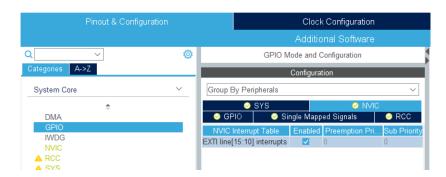




#### Impostare un GPIO come interrupt

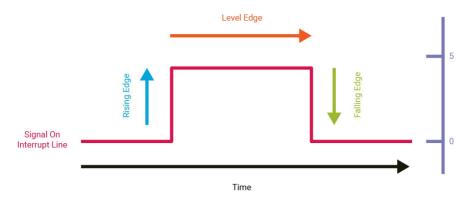
- From CubeMX it is necessary to set the GPIO pin as GPIO\_EXTIXX.
- From the NVIC (Nested vector interrupt control) Tab we enable the interrupt: this causes CubeMX to worry about enabling the interrupt and setting its priority.

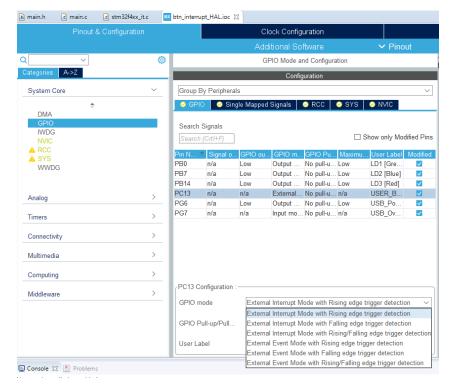




#### Falling & Rising edge detection

From the GPIO card, on the other hand, it is possible to manage the interrupt mode, in particular choosing whether the interrupt should be generated when detecting the rising edge rather than the falling edge, or both.





At this point we just have to generate the code and start writing our program. In this regard, we want to recreate the previous example but with the difference that this time when the button is pressed an *interrupt* will be generated.



- It is useful to note how CubeMX has already generated Handler for our interrupt. All Handlers are managed within the stm32f4xx it.c file.
- The HAL\_GPIO\_EXTI\_IRQHandler()
  will check that the interrupt was
  generated by the correct line.
- In that case, it will call the Callback function that we define in gpio.c file

```
*stm32f4xx it.c \times btn interrupt HAL.ioc
            .c main.c
h main.h
         @brief This function handles EXTI line[15:10] interrupts.
 202
203@ void EXTI15 10 IRQHandler(void)
204 {
       /* USER CODE BEGIN EXTI15 10 IRQn 0 */
 206
 207
       /* USER CODE END EXTI15 10 IRQn 0 */
       HAL_GPIO_EXTI_IRQHandler(GPIO_PIN_13);
       /* USER CODE BEGIN EXTI15 10 IRQn 1 */
 210
 211
       /* USER CODE END EXTI15 10 IRQn 1 */
212 }
213
      /* USER CODE BEGIN 1 */
 215
 216⊕ /* USER CODE END 1 */
                                 (C) COPYRIGHT STMicroelectronics *****END OF FILE****/
218
```

Each time the button is pressed, our counter variable will then be increased following the generation of the interrupt.

 Now we just have to slightly modify the code that we wrote in the previous example: the function that took care of reading the button and increasing the counter has been eliminated, this is because now everything is managed through the interrupt.

```
ic main.c ⋈ ic *stm32f4xx_it.c
                                          btn_interrupt_HAL.ioc
       /* Infinite loop */
       /* USER CODE BEGIN WHILE */
       while (1)
98
           int timer=USR TIME; //max time for make the decision : press the button one or two times
100
           while(timer>0 && counter<2){
101
                 timer--:
102
                 HAL Delay(1)://wait 1ms
103
104
105
           switch (counter) {
106
             case 1: //blink led
107
                 blink once(BLINK TIME, LD1 GPIO Port, LD1 Pin);
108
109
             case 2: //LEDs on
110
                 HAL_GPIO_WritePin(LD1_GPIO_Port, LD1_Pin, SET);
111
112
              default: //do nothing
113
                 break:
114
115
         /* USER CODE END WHILE */
116
117
        /* USER CODE BEGIN 3 */
118
119
       /* USER CODE END 3 */
120 }
```

## Debug

- To view the correct management of the interrupt, it may be useful to start the program in debug mode \*\* , put a breakpoint inside the Callback function and start debugging.
- When the button is pressed, it will take you to the function that manages the interrupt, as in the next figure.
- At this point it is possible to press resume again or move within the program using the step arrows.

```
.c main.c 

□ stm32f4xx_it.c
               .h main.h
                                                              MX btn_interrupt_HAL.ioc
                        /* EXTI interrupt init*/
                237
                       HAL_NVIC_SetPriority(EXTI15_10_IRQn, 0, 0);
ISTM32 Cortex-
                238
                       HAL NVIC EnableIRQ(EXTI15 10 IRQn);
cores: 01
                239
core: 0] (Suspen
                240
                241
Callback() at ma
                242 /* USER CODE BEGIN 4 */
RQHandler() at
                243@ void HAL GPIO EXTI Callback(uint16 t GPIO Pin){
ndler() at stm32
                          if (GPIO Pin==USER Btn Pin) {
alled>() at 0xfff
                245
                               //HAL GPIO TogglePin(LD2 GPIO Port, LD2 Pin);
stm32f4xx hal.c
               246
                               counter++:
m32f4xx_hal.c:4
                248
102 0x8000530
.2.0/STM32Cub
```