Neural networks

CISC 5800

Professor Daniel Leeds

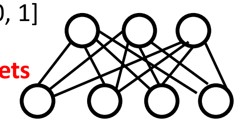
Two breeds of deep networks

Discriminative: unit^k(**x**) = ($\mathbf{w}^k$)^T**x**+b = [0, 1]

Neural networks / Convolutional neural networks

Generative: unit^k(**x**) = P(**x**; $\boldsymbol{\theta}^k$) = [0, 1]

Bayes Nets / Deep Belief Nets



2

Network architecture

Input layer:

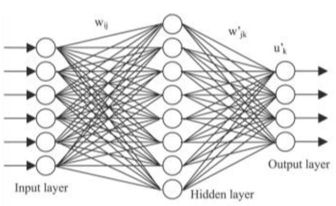
- Compute based on initial features

“Hidden” layers

- Compute based on new features

“Output” layer

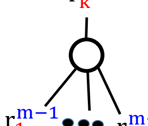
- Output final class or high-level features



Each unit takes inputs from past layer, outputs to next layer

3

Neural network building blocks

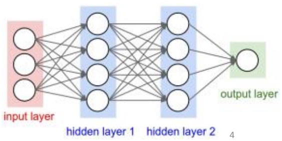


Individual unit “perceptron”:

- Typically logistic function unit(**x**) = g(h=$\mathbf{w}^T$**x**+b)=$\frac{1}{1+e^{-h}}$

Inter-layer computations

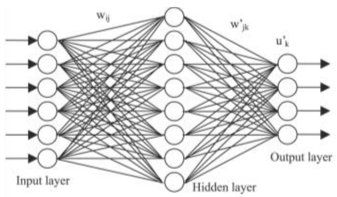
- Output $r_{unit\#}^{level}$: $r_k^m = g\left(\sum_j w_{k,j}^m r_j^{m-1} + b_k^m\right)$
- Parameters $w_{unit\#,input\#}^{level}$: $w_{k,j}^m$



4

Flow of calculation

Calculate output of each unit at layer 1 (based on input)
Calculate output of each unit at layer 2 (based on layer 1)
⋮
Calculate output of each unit at layer out (based on layer out-1)

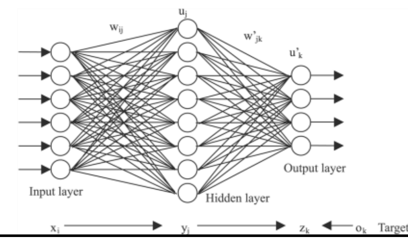


5

Top layer units

r^{top}_{classY} Find the unit with $r^{top}=1$ – that is your class

$r^{top}_{newFeatK}$ Use outputs of all r^{top} for new classifier (e.g., SVM)



6

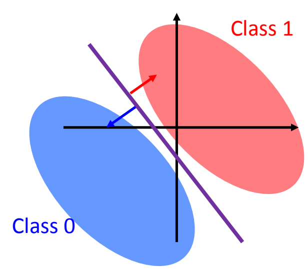
Parameters: $w^{m}_{k,i}$ - weights for every unit

Hyper-parameters:
- number of layers
- number of units per layer
- (sigmoid alternatives g(…) with hyper-parameters)
- learning step weight

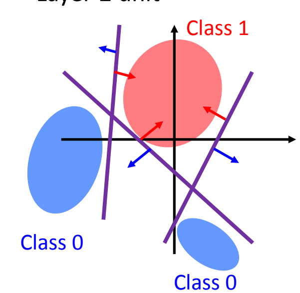
7

Neural Network units dividing feature space

Layer 1 unit



Layer 2 unit



8

Simple feedforward practice

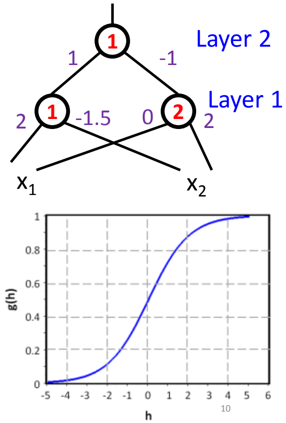
Find r_1^1, r_2^1, r_1^2 Assume b=0

x_1=0.1 x_2=0.9

r_1^1=sigmoid(0.1x2+0.9x-1.5)=
sigmoid(0.2-1.35)=sigmoid(-1.15)=0.2

r_2^1=sigmoid(0.1x0+0.9x2)=
sigmoid(0+1.8)=sigmoid(1.8)=0.85

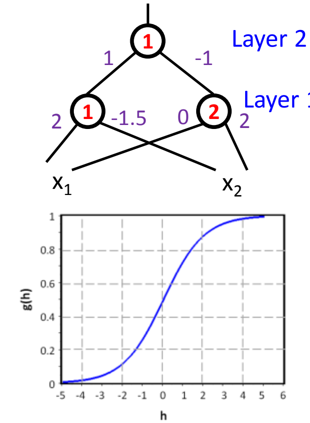
r_1^2=sigmoid(0.2x1+0.85x-1)=
sigmoid(0.2-0.85)=sigmoid(-0.65)=0.3



10

Simple feedforward practice

What is $w_{1,2}^2$? It is 1
$w_{2,1}^1$? It is 0



Learning parameters: back-propagation

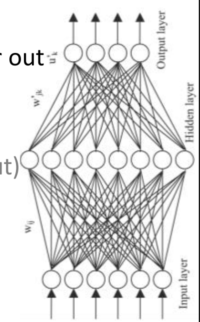
Training data: input $\mathbf{x}^i$ and class $\mathbf{y}^i$
Compute $\mathbf{x}^i$'s output for all units, from layer 1 to layer out
Adjust weights in reverse order

Δw for each unit at layer out (based on y^i)

Δw for each unit at layer out-1 (based on layer out)

⋮

Δw for each unit at layer 1 (based on layer 2)



Parameters: $w_{k,i}^m$ - weights for every unit

Hyper-parameters:

- number of layers
- number of units per layer
- (sigmoid alternatives g(…) with hyper-parameters)
- ϵ learning step weight

14

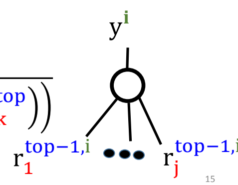
Learning parameters: back-propagation

First: Change **w** in layer top for each unit

Want to minimize the error, as measured $\sum_i \left(r_k^{top,i} - y_k^i\right)^2$

- $r_k^{top} = g\left(\sum_j w_{k,j}^{top} r_j^{top-1} + b_k^{top}\right)$

$$= \frac{1}{1 + \exp\left(-\left(\sum_i w_{k,j}^{top} r_j^{top-1} + b_k^{top}\right)\right)}$$



15

Δw at each layer

Calculate change to w's at layer top

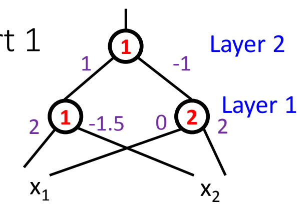
$$\Delta w_{k,j}^{top} = \epsilon \underbrace{\left(1 - r_k^{top,i}\right)\left(y^i - r_k^{top,i}\right)}_{\text{Error correction}} r_k^{top,i} \underbrace{r_j^{top-1,i}}_{\text{input j effect}}$$

Define error signal δ: $\delta_k^{top,i} = \left(1 - r_k^{top,i}\right)\left(y^i - r_k^{top,i}\right) r_k^{top,i}$

Send error signal back to layer m-1

16

Simple feedback practice, part 1



Inputs: x_1=0.1 x_2=0.9

Outputs: r_1^1=0.3 r_2^1=0.8

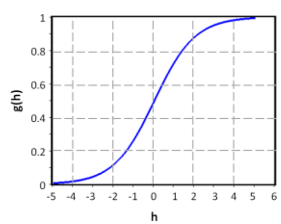
r_1^2= 0.4

y=1 ϵ=0.1

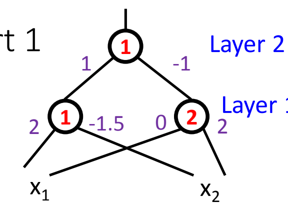
Update layer 2 unit:

$\Delta w_{k,j}^{top}$ =

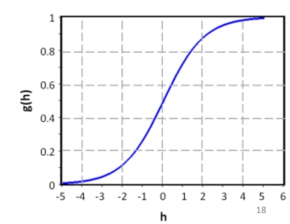
$\epsilon\left(1 - r_k^{top,i}\right)\left(y^i - r_k^{top,i}\right) r_k^{top,i} r_j^{top-1,i}$



Simple feedback practice, part 1



- x_1=0.1 x_2=0.9
- r_1^1=0.2 r_2^1=0.8
- r_1^2=0.3
- y=1 ϵ=0.1
- $\Delta w_{k,j}^{top}$ = $\epsilon\left(1 - r_k^{top,i}\right)\left(y^i - r_k^{top,i}\right) r_k^{top,i} r_j^{top-1,i}$



18

Δw at non-top layer

Top layer error signal δ: $\delta_k^{top,i} = \left(1 - r_k^{top,i}\right)\left(y^i - r_k^{top,i}\right) r_k^{top,i}$

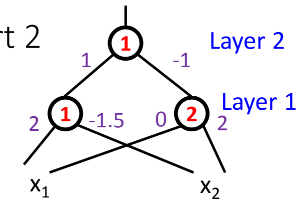
Calculate change to w's at layer m<top

$$\Delta w_{k,j}^{m} = \epsilon\left(1 - r_k^{m,i}\right)\underbrace{\left(\textstyle\sum_n w_{n,k}^{m+1,i}\delta_n^{m+1,i}\right)}_{\text{Error correction}} r_k^{m,i}\underbrace{r_j^{m-1,i}}_{\text{input j effect}}$$

Define error signal δ: $\delta_k^{m} = \left(1 - r_k^{m,i}\right)\sum_n\left(w_{n,k}^{m+1,i}\delta_n^{m+1,i}\right) r_k^{m,i}$

21

Simple feedback practice, part 2

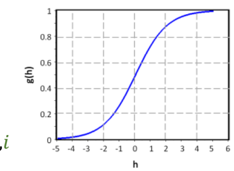


Inputs: x_1=0.1 x_2=0.9

Outputs: r_1^1=0.2 r_2^1=0.8

r_1^2= 0.3

y=1 ϵ=0.1



Update layer 1, unit 2:

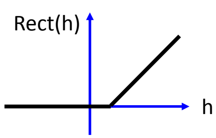
$\delta_k^{top,i} = \left(1 - r_k^{top,i}\right)\left(y^i - r_k^{top,i}\right) r_k^{top,i}$

$\Delta w_{k,j}^{m} = \epsilon\left(1 - r_k^{m,i}\right)\left(\sum_n w_{n,k}^{m+1,i}\delta_n^{m+1,i}\right) r_k^{m,i} r_j^{m-1,i}$

22

Alternative input transformations

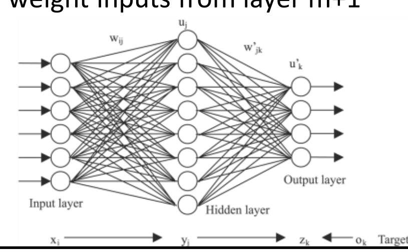
- Traditional: Sum+sigmoid g($\mathbf{w}^T\mathbf{x}$ + b)
- Straight sum $\mathbf{w}^T\mathbf{x}$ + b
- Sum+rectify
- Max (no weights!)



24

Alternative weights

- Traditional: weight inputs from layer m-1
- Competition/Normalization: weight inputs from layer m
- Feedback: weight inputs from layer m+1



25

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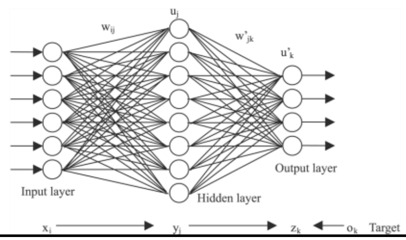
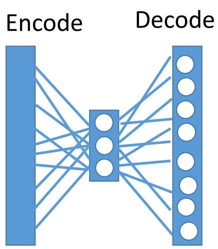


26

Autoencoder

- Input data in large feature space (e.g., 1,000,000 features)
- Intermediate layer has small number of units (e.g., 100 units)
- Output layer has same number of units as input features (e.g., 1,000,000 units)
- Optimize network so output units produce same values as inputs
- Middle units are reduced feature space!



27

Convolutional neural networks

- Wait until end of semester!

28