Textile Defect Detection CNN

1. Environment Setup

```
import torch
import torch.nn as nn
import torch.optim as optim
from torchvision import transforms, datasets, models
from torch.utils.data import DataLoader
import numpy as np
import matplotlib.pyplot as plt
from sklearn.metrics import classification_report
import time
import os
from pathlib import Path
```

Check CUDA availability

```
In [6]: device = torch.device('cuda' if torch.cuda.is_available() else 'cpu')
    print(f"Using device: {device}")

if torch.cuda.is_available():
    print(f"GPU: {torch.cuda.get_device_name(0)}")
    print(f"CUDA version: {torch.version.cuda}")

Using device: cuda
GPU: NVIDIA GeForce RTX 3060 Laptop GPU
```

2. Data Preparation

CUDA version: 11.8

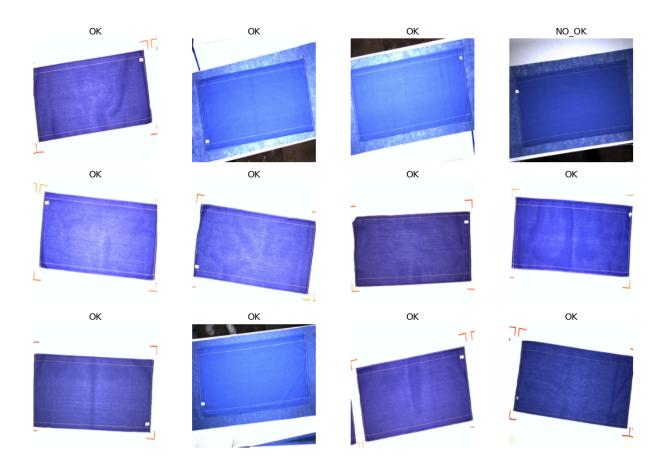
```
In [7]: PROJECT_ROOT = Path.cwd().parent # Goes up from notebooks/ to project root
print(f"Project root: {PROJECT_ROOT}")

# Set up paths relative to project root
DATA_ROOT = PROJECT_ROOT / "data"
TRAIN_DIR = DATA_ROOT / "augmented_train"
TEST_DIR = DATA_ROOT / "split" / "test"

BATCH_SIZE = 32
IMAGE_SIZE = (256, 256) # Adjusted for textile defect detection
```

Project root: c:\Users\Marcony1\OneDrive - Fundacion Universidad de las Americas Pue bla\Documents\Git\textile-image-defect-detector

```
transforms.RandomVerticalFlip(),
             transforms.ToTensor(),
             transforms.Normalize(mean=[0.485, 0.456, 0.406], std=[0.229, 0.224, 0.225])
         ])
         test_transform = transforms.Compose([
             transforms.Resize(IMAGE_SIZE),
             transforms.ToTensor(),
             transforms.Normalize(mean=[0.485, 0.456, 0.406], std=[0.229, 0.224, 0.225])
         ])
In [9]: # Create datasets
         train_dataset = datasets.ImageFolder(TRAIN_DIR, transform=train_transform)
         test_dataset = datasets.ImageFolder(TEST_DIR, transform=test_transform)
In [10]: # Class names
         class_names = train_dataset.classes
         print(f"Classes: {class_names}")
        Classes: ['NO_OK', 'OK']
In [11]: # Create data Loaders
         train_loader = DataLoader(train_dataset, batch_size=BATCH_SIZE, shuffle=True, num_w
         test_loader = DataLoader(test_dataset, batch_size=BATCH_SIZE, shuffle=False, num_wo
In [12]: # Show batch
         def show_batch(images, labels):
             plt.figure(figsize=(12, 8))
             images = images.cpu().numpy().transpose((0, 2, 3, 1))
             mean = np.array([0.485, 0.456, 0.406])
             std = np.array([0.229, 0.224, 0.225])
             images = std * images + mean
             images = np.clip(images, 0, 1)
             for i in range(min(12, len(images))):
                 plt.subplot(3, 4, i+1)
                 plt.imshow(images[i])
                 plt.title(class_names[labels[i]])
                 plt.axis('off')
             plt.tight_layout()
             plt.show()
In [13]: # Display sample
         images, labels = next(iter(train_loader))
         show_batch(images, labels)
```



3. CNN Model Definition

```
In [14]: class TextileDefectCNN(nn.Module):
             def __init__(self, num_classes=2):
                  super(TextileDefectCNN, self).__init__()
                  self.features = nn.Sequential(
                     nn.Conv2d(3, 32, kernel_size=3, padding=1),
                     nn.ReLU(),
                     nn.MaxPool2d(2, 2),
                     nn.Conv2d(32, 64, kernel_size=3, padding=1),
                     nn.ReLU(),
                     nn.MaxPool2d(2, 2),
                     nn.Conv2d(64, 128, kernel_size=3, padding=1),
                     nn.ReLU(),
                     nn.MaxPool2d(2, 2),
                     nn.Conv2d(128, 256, kernel_size=3, padding=1),
                     nn.ReLU(),
                     nn.MaxPool2d(2, 2)
                  )
                  self.classifier = nn.Sequential(
                     nn.Flatten(),
                     nn.Linear(256 * 16 * 16, 512),
                     nn.ReLU(),
                     nn.Dropout(0.5),
```

```
nn.Linear(512, num_classes)
                 )
             def forward(self, x):
                 x = self.features(x)
                 x = self.classifier(x)
                 return x
In [15]: model = TextileDefectCNN(num_classes=2).to(device)
In [16]: # Print summary
         print(model)
        TextileDefectCNN(
          (features): Sequential(
            (0): Conv2d(3, 32, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
            (1): ReLU()
            (2): MaxPool2d(kernel_size=2, stride=2, padding=0, dilation=1, ceil_mode=False)
            (3): Conv2d(32, 64, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
            (4): ReLU()
            (5): MaxPool2d(kernel_size=2, stride=2, padding=0, dilation=1, ceil_mode=False)
            (6): Conv2d(64, 128, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
            (7): ReLU()
            (8): MaxPool2d(kernel_size=2, stride=2, padding=0, dilation=1, ceil_mode=False)
            (9): Conv2d(128, 256, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
            (10): ReLU()
            (11): MaxPool2d(kernel_size=2, stride=2, padding=0, dilation=1, ceil_mode=False)
          (classifier): Sequential(
            (0): Flatten(start_dim=1, end_dim=-1)
            (1): Linear(in_features=65536, out_features=512, bias=True)
            (2): ReLU()
            (3): Dropout(p=0.5, inplace=False)
            (4): Linear(in_features=512, out_features=2, bias=True)
        )
         4. Training Setup
In [17]: # Loss and optimizer
         criterion = nn.CrossEntropyLoss()
         optimizer = optim.Adam(model.parameters(), lr=0.001, weight_decay=1e-4)
         scheduler = optim.lr_scheduler.ReduceLROnPlateau(optimizer, 'min', patience=3, fact
```

```
scheduler = optim.lr_scheduler.ReduceLROnPlateau(optimizer, 'min', patience=3, fact

In []:
# Training function
def train_model(model, criterion, optimizer, scheduler, num_epochs=25):
    since = time.time()
    best_acc = 0.0

    train_loss_history = []
    train_acc_history = []
    val_loss_history = []
    val_acc_history = []
```

```
for epoch in range(num_epochs):
    print(f'Epoch {epoch+1}/{num_epochs}')
    print('-' * 10)
   # Training phase
   model.train()
    running_loss = 0.0
    running_corrects = 0
    for inputs, labels in train_loader:
        inputs = inputs.to(device)
        labels = labels.to(device)
        optimizer.zero_grad()
        outputs = model(inputs)
        _, preds = torch.max(outputs, 1)
        loss = criterion(outputs, labels)
        loss.backward()
        optimizer.step()
        running_loss += loss.item() * inputs.size(0)
        running_corrects += torch.sum(preds == labels.data)
    epoch_loss = running_loss / len(train_dataset)
    epoch_acc = running_corrects.double() / len(train_dataset)
   train_loss_history.append(epoch_loss)
   train_acc_history.append(epoch_acc)
    print(f'Train Loss: {epoch_loss:.4f} Acc: {epoch_acc:.4f}')
   # Validation phase
   model.eval()
    running_loss = 0.0
    running_corrects = 0
   with torch.no_grad():
        for inputs, labels in test_loader:
            inputs = inputs.to(device)
            labels = labels.to(device)
            outputs = model(inputs)
            _, preds = torch.max(outputs, 1)
            loss = criterion(outputs, labels)
            running_loss += loss.item() * inputs.size(0)
            running_corrects += torch.sum(preds == labels.data)
    epoch_loss = running_loss / len(test_dataset)
    epoch_acc = running_corrects.double() / len(test_dataset)
    val_loss_history.append(epoch_loss)
    val_acc_history.append(epoch_acc)
```

```
scheduler.step(epoch_loss)

print(f'Val Loss: {epoch_loss:.4f} Acc: {epoch_acc:.4f}')
print()

# Save best model
if epoch_acc > best_acc:
    best_acc = epoch_acc
    torch.save(model.state_dict(), '../models/best_model_baseline.pt')

time_elapsed = time.time() - since
print(f'Training complete in {time_elapsed // 60:.0f}m {time_elapsed % 60:.0f}s
print(f'Best val Acc: {best_acc:.4f}')

return model, train_loss_history, train_acc_history, val_loss_history, val_acc_
```

5. Model Training

```
In [19]: # Train the model
    model, train_loss, train_acc, val_loss, val_acc = train_model(
        model, criterion, optimizer, scheduler, num_epochs=20
)
```

Epoch 1/20

Train Loss: 0.6745 Acc: 0.7380 Val Loss: 0.5828 Acc: 0.7391

Epoch 2/20

Train Loss: 0.5874 Acc: 0.7380 Val Loss: 0.5926 Acc: 0.7391

Epoch 3/20

Train Loss: 0.5740 Acc: 0.7380 Val Loss: 0.5643 Acc: 0.7391

Epoch 4/20

Train Loss: 0.5710 Acc: 0.7380 Val Loss: 0.5541 Acc: 0.7391

Epoch 5/20

Train Loss: 0.5615 Acc: 0.7343 Val Loss: 0.5597 Acc: 0.7391

Epoch 6/20

Train Loss: 0.5565 Acc: 0.7380 Val Loss: 0.5493 Acc: 0.7391

Epoch 7/20

Train Loss: 0.5263 Acc: 0.7429 Val Loss: 0.5759 Acc: 0.7681

Epoch 8/20

Train Loss: 0.5044 Acc: 0.7651 Val Loss: 0.5126 Acc: 0.7826

Epoch 9/20

Train Loss: 0.4589 Acc: 0.7909 Val Loss: 0.5122 Acc: 0.7391

Epoch 10/20

Train Loss: 0.4561 Acc: 0.7946 Val Loss: 0.5365 Acc: 0.7681

Epoch 11/20

Train Loss: 0.4381 Acc: 0.8007 Val Loss: 0.4935 Acc: 0.7681

Epoch 12/20

```
Train Loss: 0.4218 Acc: 0.8069
Val Loss: 0.5401 Acc: 0.6957
Epoch 13/20
-----
Train Loss: 0.4309 Acc: 0.8155
Val Loss: 0.5433 Acc: 0.7826
Epoch 14/20
-----
Train Loss: 0.4130 Acc: 0.8118
Val Loss: 0.5140 Acc: 0.7391
Epoch 15/20
-----
Train Loss: 0.4228 Acc: 0.8044
Val Loss: 0.4774 Acc: 0.7826
Epoch 16/20
-----
Train Loss: 0.4113 Acc: 0.7995
Val Loss: 0.4930 Acc: 0.7681
Epoch 17/20
-----
Train Loss: 0.3990 Acc: 0.8057
Val Loss: 0.4568 Acc: 0.7826
Epoch 18/20
-----
Train Loss: 0.3951 Acc: 0.8192
Val Loss: 0.4685 Acc: 0.7826
Epoch 19/20
Train Loss: 0.3835 Acc: 0.8241
Val Loss: 0.4802 Acc: 0.7971
Epoch 20/20
-----
Train Loss: 0.3774 Acc: 0.8290
Val Loss: 0.4739 Acc: 0.7826
Training complete in 11m 59s
Best val Acc: 0.7971
```

6. Training Visualization

```
In [20]: # Plot training history
    plt.figure(figsize=(12, 5))
    plt.subplot(1, 2, 1)
    plt.plot(train_loss, label='Train Loss')
    plt.plot(val_loss, label='Val Loss')
    plt.title('Loss over epochs')
```

```
plt.legend()

plt.subplot(1, 2, 2)

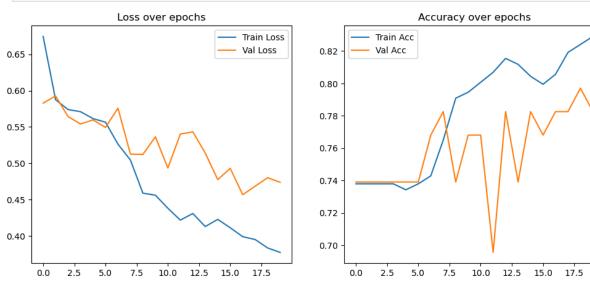
plt.plot([x.cpu().numpy() for x in train_acc], label='Train Acc')

plt.plot([x.cpu().numpy() for x in val_acc], label='Val Acc')

plt.title('Accuracy over epochs')

plt.legend()

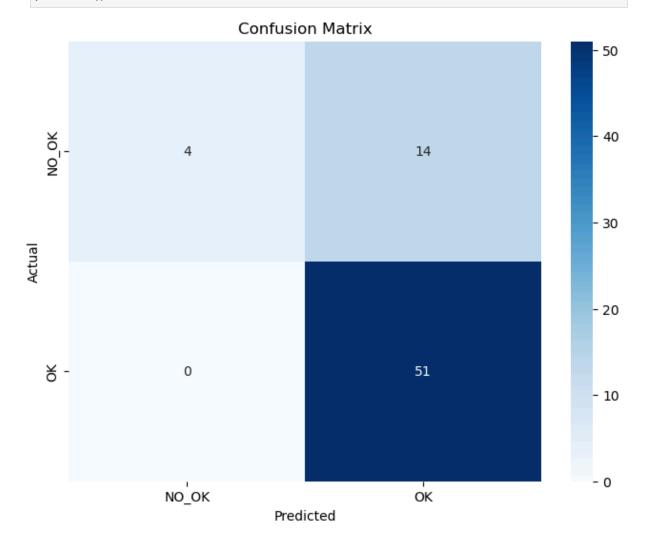
plt.show()
```



7. Model Evaluation

```
In [ ]: # Load best model
    model.load_state_dict(torch.load('../models/best_model_baseline.pt'))
    model.eval()
```

```
Out[]: TextileDefectCNN(
            (features): Sequential(
              (0): Conv2d(3, 32, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
              (1): ReLU()
              (2): MaxPool2d(kernel_size=2, stride=2, padding=0, dilation=1, ceil_mode=Fals
         e)
              (3): Conv2d(32, 64, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
              (4): ReLU()
              (5): MaxPool2d(kernel_size=2, stride=2, padding=0, dilation=1, ceil_mode=Fals
         e)
              (6): Conv2d(64, 128, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
              (7): ReLU()
              (8): MaxPool2d(kernel_size=2, stride=2, padding=0, dilation=1, ceil mode=Fals
         e)
              (9): Conv2d(128, 256, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
              (10): ReLU()
              (11): MaxPool2d(kernel_size=2, stride=2, padding=0, dilation=1, ceil_mode=Fals
         e)
            (classifier): Sequential(
              (0): Flatten(start_dim=1, end_dim=-1)
              (1): Linear(in_features=65536, out_features=512, bias=True)
              (2): ReLU()
              (3): Dropout(p=0.5, inplace=False)
              (4): Linear(in features=512, out features=2, bias=True)
            )
          )
In [22]: # Test evaluation
         all_preds = []
         all_labels = []
         with torch.no_grad():
             for inputs, labels in test_loader:
                 inputs = inputs.to(device)
                 labels = labels.to(device)
                 outputs = model(inputs)
                 _, preds = torch.max(outputs, 1)
                 all_preds.extend(preds.cpu().numpy())
                 all_labels.extend(labels.cpu().numpy())
In [23]: # Classification report
         print(classification_report(all_labels, all_preds, target_names=class_names))
                                   recall f1-score
                      precision
                                                       support
               NO OK
                                     0.22
                                               0.36
                           1.00
                                                            18
                  OK
                           0.78
                                     1.00
                                               0.88
                                                            51
            accuracy
                                               0.80
                                                            69
                           0.89
                                     0.61
                                               0.62
                                                            69
           macro avg
        weighted avg
                           0.84
                                     0.80
                                               0.74
                                                            69
```



8. Save Final Model

```
In [27]: # Save the entire model
torch.save({
    'model_state_dict': model.state_dict(),
    'class_names': class_names,
    'image_size': IMAGE_SIZE
}, '../models/textile_defect_model_baseline.pt')
```

print("Model saved successfully!")

Model saved successfully!