practica2

April 30, 2024

1 Mejora del potencial inicial

Aqui he modificado el potencial utilizado en la practica 1, al igual que lo he generalizado mediante la importacion de un script(anidado al final del jupyter por completitud)

```
[1]: # import astropy.units as u
# import numpy as np
# import gala.potential as gp
# from gala.units import galactic
# import matplotlib.pyplot as plt
from constructor import *
```

```
coldgalpot = create_gal_potential(total_mass=1e11*u.M_sun, r_s=5*u.kpc)
# Valores L*(M) obtenidos de (Cooray,2008)

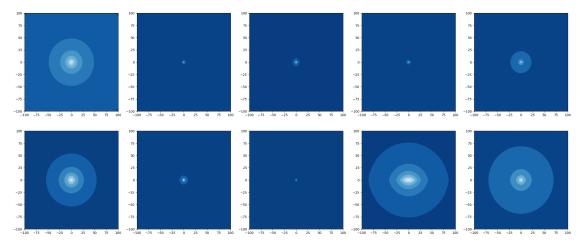
# newgalpot = create_complex_potential(
    total_mass=1e12*u.M_sun,
    r_s=5*u.kpc,
    dm_fraction=0.78,
    disk_total=0.7,
    bulge_total=0.29,
    nucleus_total=0.01,
    bulge_b=1.2,
    disk_a=10,
    disk_b=0.5,
    nucleus_b=0.4
}
```

```
[3]: grid = np.linspace(-100,100,1000)
fig, axes = plt.subplots(2,5,figsize=(30,12))

oldgalpot["halo"].plot_contours((grid,0,grid), ax=axes[0,0])
oldgalpot["bulge"].plot_contours((grid,0,grid), ax=axes[0,1])
oldgalpot["nucleus"].plot_contours((grid,0,grid), ax=axes[0,2])
oldgalpot["disk"].plot_contours((grid,0,grid), ax=axes[0,3])
oldgalpot.plot_contours((grid,0,grid), ax=axes[0,4])

newgalpot["halo"].plot_contours((grid,0,grid), ax=axes[1,0])
```

```
newgalpot["bulge"].plot_contours((grid,0,grid), ax=axes[1,1])
newgalpot["nucleus"].plot_contours((grid,0,grid), ax=axes[1,2])
newgalpot["disk"].plot_contours((grid,0,grid), ax=axes[1,3])
newgalpot.plot_contours((grid,0,grid), ax=axes[1,4])
plt.show()
```

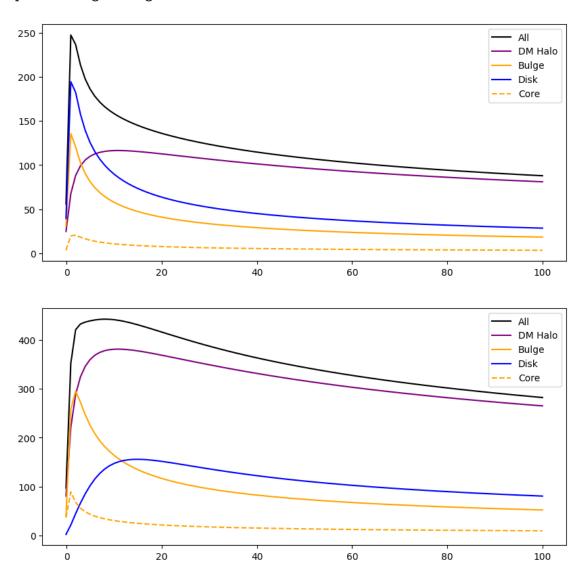


```
[4]: # Curvas de velocidad respectivas ;D
     # Es sencillo ver la curva de rotacion de las componentes y del total
     grid = np.linspace(-0.1,100,100)
     fig, axes = plt.subplots(2,1,figsize=(10,10))
     xyz = np.zeros((3,) + grid.shape)
     xyz[0] = grid
     oldVcirc = {}
     oldVcirc["all"] = oldgalpot.circular_velocity(xyz)
     oldVcirc["halo"] = oldgalpot['halo'].circular_velocity(xyz)
     oldVcirc["bulge"] = oldgalpot['bulge'].circular_velocity(xyz)
     oldVcirc["nucleus"] = oldgalpot['disk'].circular_velocity(xyz)
     oldVcirc["disk"] = oldgalpot['nucleus'].circular_velocity(xyz)
     axes[0].plot(grid,oldVcirc["all"],c='black',label='All')
     axes[0].plot(grid,oldVcirc["halo"],c='purple',label='DM Halo')
     axes[0].plot(grid,oldVcirc["bulge"],c='orange',label='Bulge')
     axes[0].plot(grid,oldVcirc["nucleus"],c='blue',label='Disk')
     axes[0].plot(grid,oldVcirc["disk"],c='orange',linestyle='--',label='Core')
     axes[0].legend()
     newVcirc = {}
     newVcirc["all"] = newgalpot.circular_velocity(xyz)
     newVcirc["halo"] = newgalpot['halo'].circular_velocity(xyz)
```

```
newVcirc["bulge"] = newgalpot['bulge'].circular_velocity(xyz)
newVcirc["nucleus"] = newgalpot['disk'].circular_velocity(xyz)
newVcirc["disk"] = newgalpot['nucleus'].circular_velocity(xyz)

axes[1].plot(grid,newVcirc["all"],c='black',label='All')
axes[1].plot(grid,newVcirc["halo"],c='purple',label='DM Halo')
axes[1].plot(grid,newVcirc["bulge"],c='orange',label='Bulge')
axes[1].plot(grid,newVcirc["nucleus"],c='blue',label='Disk')
axes[1].plot(grid,newVcirc["disk"],c='orange',linestyle='--',label='Core')
axes[1].legend()
```

[4]: <matplotlib.legend.Legend at 0x7f9b73ecd340>



2 Recreacion de orbitas practica 1 en potencial mejorado

Se utilizan las mismas condiciones iniciales que antes, por completitud se utiliza igualmente el potencial de la practica1, llamado oldgalpot

```
[5]: import gala.dynamics as gd
     def orbit_integrate(pot):
         txtsize = 8
         r = [7.5,0,0] * u.kpc
         v = [0, 200, 0] * u.km/u.s
         ics_closed = gd.PhaseSpacePosition(pos=r,vel=v)
         r = [100, -300, 0] * u.kpc
         v = [-70, 260, 0] * u.km/u.s
         ics_hyperbolic = gd.PhaseSpacePosition(pos=r,vel=v)
         fig,axes = plt.subplots(2,4,figsize=(20,10))
         sumpot = gp.CCompositePotential()
         i = 0
         grid_closed = np.linspace(-30,30,1000)
         grid hypebolic = np.linspace(-150,150,1000)
         components_str = ''
         for key in pot.keys():
             sumpot[key] = pot[key]
             sumpot.plot_contours(grid=(grid_closed,grid_closed,0), ax=axes[0,i])
             sumpot.plot_contours(grid=(grid_hypebolic,grid_hypebolic,0),__
      \Rightarrowax=axes[1,i])
             closed_orbit = gp.Hamiltonian(sumpot).integrate_orbit(ics_closed, dt=0.
      \hookrightarrow6, n_steps=1e4)
             closed_orbit.plot(components=['x','y'], axes=[axes[0,i]], color='red')
             hyperbolic_orbit = gp.Hamiltonian(sumpot).
      →integrate_orbit(ics_hyperbolic, dt=1., n_steps=6e3)
             hyperbolic orbit.plot(components=['x','y'], axes=[axes[1,i]],

color='red')
             components_str += key + '|'
             axes[0,i].set_title(f'{components_str}')
             axes[0,i].set_xlim(-30,30)
             axes[0,i].set_ylim(-30,30)
             axes[1,i].set_xlim(-100,100)
             axes[1,i].set_ylim(-100,100)
             # texto con apocentros y datos
             closed_energy = np.round(ics_closed.energy(sumpot).to(u.km**2/u.
      \hookrightarrow s**2)[0],2)
             closed_apocenter = np.round(closed_orbit.apocenter(),2)
             closed_pericenter = np.round(closed_orbit.pericenter(),2)
```

```
closed_eccentricity = np.round(closed_orbit.eccentricity(),2)
      hyperbolic_energy = np.round(ics_hyperbolic.energy(sumpot).to(u.km**2/u.
\Rightarrow s**2)[0],2)
      hyperbolic apocenter = np.round(hyperbolic orbit.apocenter(),2)
      hyperbolic_pericenter = np.round(hyperbolic_orbit.pericenter(),2)
      hyperbolic eccentricity = np.round(hyperbolic orbit.eccentricity(),2)
      axes[0,i].text(0.01,0.95,f'E = \{closed\_energy\}',transform=axes<math>[0,i].
⇔transAxes,size=txtsize,c='white')
      axes[0,i].text(0.01,0.025,f'Apocenter =
→{closed_apocenter}',transform=axes[0,i].transAxes,size=txtsize,c='white')
      axes[0,i].text(0.01,0.075,f'Pericenter =
axes[0,i].text(0.01,0.125,f'Ecentricity =
→{closed_eccentricity}',transform=axes[0,i].transAxes,size=txtsize,c='white')
      axes[1,i].text(0.01,0.95,f'E = \{\text{hyperbolic\_energy}\}', \text{transform=axes}[1,i].

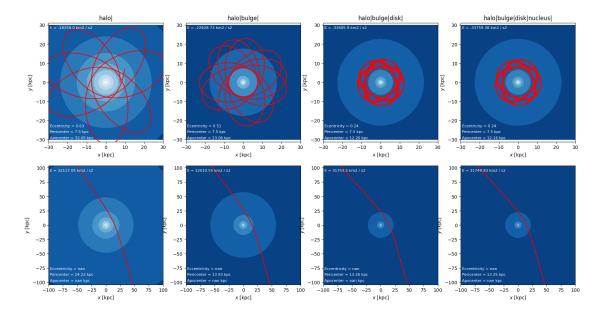
→transAxes,size=txtsize,c='white')
      axes[1,i].text(0.01,0.025,f'Apocenter =_{\sqcup}
→{hyperbolic_apocenter}',transform=axes[1,i].transAxes,size=txtsize,c='white')
      axes[1,i].text(0.01,0.075,f'Pericenter = 11)
⇔transAxes,size=txtsize,c='white')
      axes[1,i].text(0.01,0.125,f'Eccentricity = _{\sqcup}
⇔transAxes,size=txtsize,c='white')
      # Podemos saber si seleccionamos dt corecto si vemos que la energia se_{f L}
\hookrightarrowconserva
      print('-'*84)
      print(components_str)
      print('-'*84)
      print('Std deviation of Energy')
      print(np.std(closed_orbit.energy()),'\n',np.std(hyperbolic_orbit.
⇔energy()))
      print('Std deviation of Ang.Mom')
      # Y que tambien el momentum angular lo hace
      print(np.std(closed_orbit.angular_momentum()[2,:]),'\n',np.

→std(hyperbolic_orbit.angular_momentum()[2,:]))
      i += 1
  return(fig,axes)
```

[6]: orbit_integrate(oldgalpot)

```
/home/mbugueno/anaconda3/envs/galaenv/lib/python3.12/site-
packages/numpy/core/fromnumeric.py:3504: RuntimeWarning: Mean of empty slice.
return _methods._mean(a, axis=axis, dtype=dtype,
/home/mbugueno/anaconda3/envs/galaenv/lib/python3.12/site-
packages/numpy/core/_methods.py:129: RuntimeWarning: invalid value encountered
```

<pre>in scalar divide ret = ret.dtype.type(ret / rcount)</pre>	
halo	
Std deviation of Energy 5.282064624981633e-08 kpc2 / Myr2 5.1652334433290194e-08 kpc2 / Myr2 Std deviation of Ang.Mom 4.0894219647285164e-15 kpc2 / Myr 1.6883644340429877e-13 kpc2 / Myr	
halo bulge	
Std deviation of Energy 7.739724675770838e-08 kpc2 / Myr2 6.368840922873448e-08 kpc2 / Myr2 Std deviation of Ang.Mom 6.6392235314686294e-15 kpc2 / Myr 3.20919034251333e-13 kpc2 / Myr	
halo bulge disk	
Std deviation of Energy 1.306619770051138e-07 kpc2 / Myr2 9.990359975750819e-08 kpc2 / Myr2 Std deviation of Ang.Mom 1.914497966406166e-15 kpc2 / Myr 2.5398320672928374e-13 kpc2 / Myr	
halo bulge disk nucleus	
Std deviation of Energy 1.3077955020815733e-07 kpc2 / Myr2 1.0050217193964668e-07 kpc2 / Myr2 Std deviation of Ang.Mom 2.236970743950807e-15 kpc2 / Myr 2.2504376157291334e-13 kpc2 / Myr	



[7]: orbit_integrate(newgalpot)

halo

Std deviation of Energy

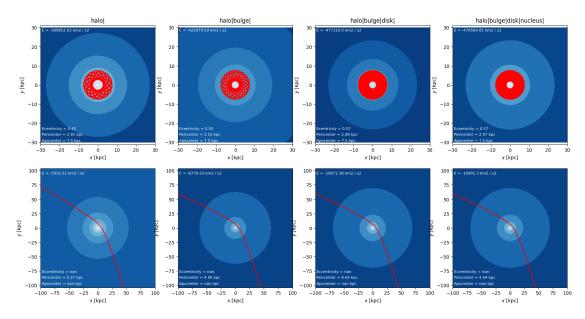
2.836599698070888e-05 kpc2 / Myr2

1.0284121916748385e-05 kpc2 / Myr2

Std deviation of Ang.Mom

4.131331762910151e-15 kpc2 / Myr

```
7.848084455925017e-14 kpc2 / Myr
    halo|bulge|
    Std deviation of Energy
    0.00011468422063876896 kpc2 / Myr2
     1.6276716278089295e-05 kpc2 / Myr2
    Std deviation of Ang.Mom
    6.2872043623462105e-15 kpc2 / Myr
     1.605188472161369e-13 kpc2 / Myr
    halo|bulge|disk|
    Std deviation of Energy
    0.00013196197532522818 kpc2 / Myr2
     2.090979815077077e-05 kpc2 / Myr2
    Std deviation of Ang.Mom
    4.4561205923234054e-15 kpc2 / Myr
     1.5448358318461416e-13 kpc2 / Myr
    halo|bulge|disk|nucleus|
    _____
                          ______
    Std deviation of Energy
    0.00013853432120844276 kpc2 / Myr2
    2.1225038406008355e-05 kpc2 / Myr2
    Std deviation of Ang.Mom
    3.034951910999407e-15 \text{ kpc2} / \text{Myr}
     1.4593351891812216e-13 kpc2 / Myr
[7]: (<Figure size 2000x1000 with 8 Axes>,
     array([[<Axes: title={'center': 'halo|'}, xlabel='$x$ [$\\mathrm{kpc}$]',
    ylabel='$y$ [$\\mathrm{kpc}$]'>,
             <Axes: title={'center': 'halo|bulge|'}, xlabel='$x$ [$\\mathrm{kpc}$]',</pre>
    ylabel='$y$ [$\\mathrm{kpc}$]'>,
             <Axes: title={'center': 'halo|bulge|disk|'}, xlabel='$x$</pre>
    [$\\mathrm{kpc}$]', ylabel='$y$ [$\\mathrm{kpc}$]'>,
             <Axes: title={'center': 'halo|bulge|disk|nucleus|'}, xlabel='$x$</pre>
    [$\\mathrm{kpc}$]', ylabel='$y$ [$\\mathrm{kpc}$]'>],
            [<Axes: xlabel='x [\m [x]', ylabel='x" [x]'>,
             <Axes: xlabel='x [$\\mathrm{kpc}$]', ylabel='y [$\\mathrm{kpc}$]'>,
             <Axes: xlabel='$x$ [$\\mathrm{kpc}$]', ylabel='$y$ [$\\mathrm{kpc}$]'>,
```



3 1) Evolucion temporal de parametros de las orbitas

Aqui son mostrados los parametros con respecto al tiempo de las orbitas de manera secuencial en los potenciales mejorados y antiguos - Energia (E_T) vs t - Momento angular total (L_T) vs t - Componentes del momento angular (L_x, L_y, L_z) vs t - Eccentricidad(e) vs t

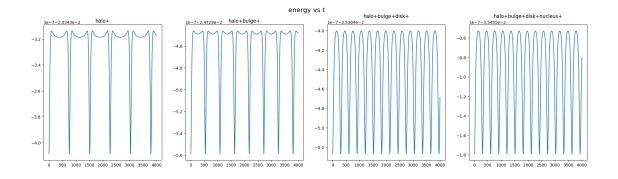
```
[8]: def parametersvstime(pot,parameter,ics_closed):
         fig, axes = plt.subplots(1,4,figsize=(24,6))
         sumpot = gp.CCompositePotential()
         grid_closed = np.linspace(-30,30,1000)
         grid_hypebolic = np.linspace(-150,150,1000)
         components_str = ""
         for key in pot.keys():
             sumpot[key] = pot[key]
             closed_orbit = gp.Hamiltonian(sumpot).integrate_orbit(ics_closed, dt=0.
      \rightarrow 4, n_steps=1e4)
             components_str += key + '+'
             axes[i].set_title(f'{components_str}')
             cparameters = {}
             cparameters["energy"] = closed_orbit.energy()
             cparameters["L_x"] = closed_orbit.angular_momentum()[0,:]
             cparameters["L_y"] = closed_orbit.angular_momentum()[1,:]
```

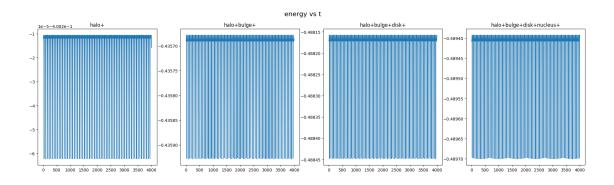
```
cparameters["L_z"] = closed_orbit.angular_momentum()[2,:]
      cparameters["L_T"] = np.sqrt(cparameters["L_x"]**2 +__
if parameter in ["energy","L T"]:
          x = closed_orbit.t
          y = cparameters[parameter]
          axes[i].plot(x,y)
      if parameter in ["e"]:
          apo = closed_orbit.apocenter(func=None,return_times=True)[0][:]
          apo_times = closed_orbit.apocenter(func=None,return_times=True)[1][:
\hookrightarrow
          per = closed orbit.pericenter(func=None,return times=True)[0][:]
          per_times = closed_orbit.
→pericenter(func=None,return_times=True)[1][:]
              cparameters["e"] = (apo-per)/(apo+per)
          except:
              cparameters["e"] = (apo-per[1:])/(apo+per[1:])
          x = apo_times
          y = cparameters[parameter]
          axes[i].plot(x,y)
      if parameter in ["L"]:
          x = closed orbit.t
          for name in ["L_x","L_y","L_z"]:
              y = cparameters[name]
              axes[i].plot(x,y, label=f"{name}")
              axes[i].legend(fontsize=10)
      i += 1
  fig.suptitle(f"{parameter} vs t", size=16)
  return(fig,axes)
```

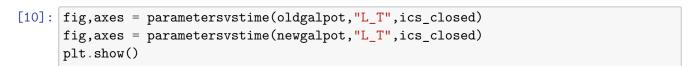
```
[9]: # Orbitas usadas initial
    r = [8,0,0] * u.kpc
    v = [0, 190, 0] * u.km/u.s
    ics_closed = gd.PhaseSpacePosition(pos=r,vel=v)

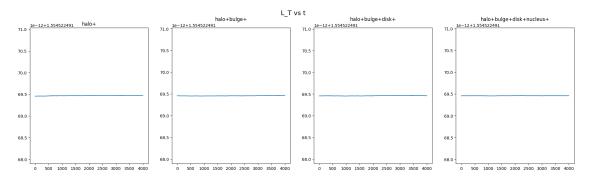
    r = [100,-300,0] * u.kpc
    v = [-70, 260, 0] * u.km/u.s
    ics_hyperbolic = gd.PhaseSpacePosition(pos=r,vel=v)

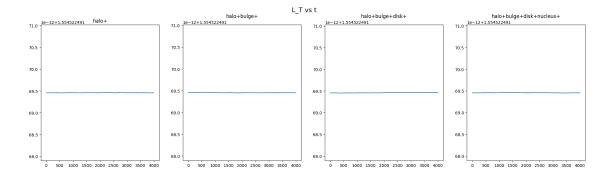
    fig,axes = parametersvstime(oldgalpot,"energy",ics_closed)
    fig,axes = parametersvstime(newgalpot,"energy",ics_closed)
    plt.show()
```



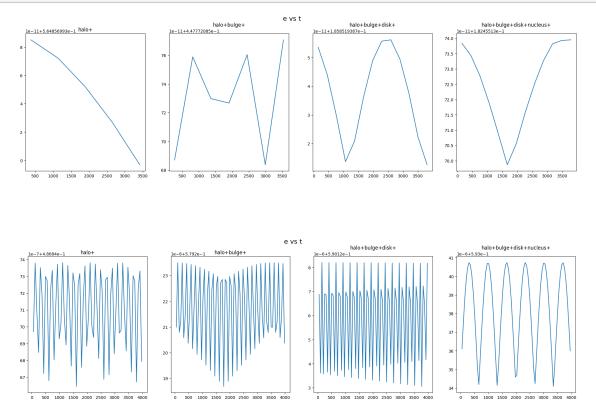




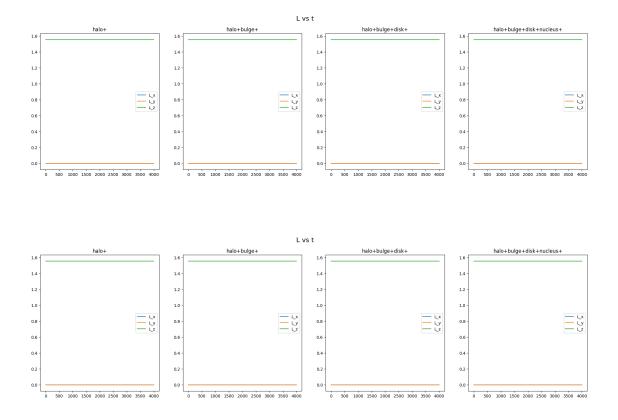




[11]: fig,axes = parametersvstime(oldgalpot, "e",ics_closed)
fig,axes = parametersvstime(newgalpot, "e",ics_closed)
plt.show()



```
[12]: fig,axes = parametersvstime(oldgalpot, "L",ics_closed)
fig,axes = parametersvstime(newgalpot, "L",ics_closed)
plt.show()
```



3.1 1.1) Discusion

EL observar estos valores de manera temporal permite saber que tan buena fue la integracion, ya que para valores demasiado grandes de "dt" la integracion es incorrecta y ocurren situaciones donde ni la energia ni el momento angular se conservan. Sin embargo esto sera solo cierto si el potencial que se esta considerando no cambia con respecto al tiempo, que en el caso particular presentado es asi, todos los potenciales son estaticos temporalmente.

Viendo los casos por orden: La energia vs el tiempo, si bien puede aparentar que esta cambiando, las variaciones no superan un valor de 0.0003, por ende es practicamente constante, aun asi si se desea se puede reducir dt, para mejorar aun mas la precision, sin embargo ya es suficientemente preciso.

El momentum angular total vs el tiempo, se conserva completamente como es esperado, y es practicamente constante en toda la integración.

La excentricidad vs el tiempo, es practicamente constante nuevamente, esto tiene sentido al considerar que la orbita que posee el cuerpo no es particularmente caotica, y se mantiene en forma, solo rotando la orbita en si como un todo.

Luego si vemos las componentes del momento angular tiene sentido que apunte directamente en z, ya que la orbita que dibuja el objeto es bidimensional

4 2) Superficies de poincare de las orbitas

Se realizan los cortes tanto en las orbitas en los potenciales antiguos como nuevos

```
[13]: def poincare_surface(pot, ics,
                            ax=None, xyz=["x","y","v x"],
                            dt=0.1*u.Myr, t final=1000*u.Myr
                           ):
          11 11 11
          Generates a 3d figure of the poincare surface, ax must have a 3d property
          orbit = gp.Hamiltonian(pot).integrate_orbit(ics, dt=dt, n_steps=t_final/dt)
          orbit.plot_3d(components=xyz, color='red', ax=ax)
          return(orbit)
      def multi_poincare(pot,ics,
       \Rightarrow xyz1=["x","y","v_x"], xyz2=["x","z","v_x"], xyz3=["y","z","v_y"],
                         t final=4000*u.Myr
                         ):
          nnn
          Makes 3 poincare 3d surfaces, according to xyz1,xyz2 and xyz3
          fig,axes = plt.subplots(1,3,figsize=(9,3), subplot_kw={'projection': "3d"})
          i = 0
          xyz = [xyz1, xyz2, xyz3]
          for ax in axes:
              poincare_surface(pot,ics,t_final=t_final,xyz=xyz[i], ax=ax)
          return(fig,axes)
      def poincare_slice(pot,ics,
                          hor="x", ver="v_x", cut="y",
                          proj plane=0,
                          dproj=1e-1, ax=None,
                          dt=0.1*u.Myr, t final=1000*u.Myr
                         ):
          11 11 11
          Makes a poincare slice, by limiting the slice around a point according to a_{\sqcup}
       ⇒dproj. that cuts the plane "cut"
          11 11 11
          orbit = gp.Hamiltonian(pot).integrate_orbit(ics, dt=dt, n_steps=t_final/dt)
          orbit_data = {}
          orbit_data["x"] = orbit.pos.x
          orbit_data["y"] = orbit.pos.y
          orbit data["z"] = orbit.pos.z
          orbit_data["v_x"] = orbit.vel.d_x
```

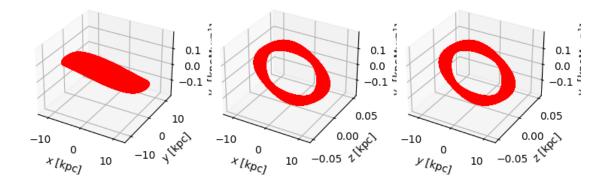
```
orbit_data["v_y"] = orbit.vel.d_y
    orbit_data["v_z"] = orbit.vel.d_z
    x,y = orbit_data[hor],orbit_data[ver]
    z = orbit_data[cut]
    filtre = np.where((z < (proj_plane + dproj) * z.unit) & (z > (proj_plane -u

dproj) * z.unit))
    x,y = x[filtre],y[filtre]
    return(x,y)
def poincare_slice_hw(pot,ics,
                   hor="x", ver="v_x", cut="y",
                   proj_plane=0,
                   dproj=1e-1, ax=None,
                   dt=0.1*u.Myr, t_final=1000*u.Myr
                  ):
    11 11 11
    Makes a poincare slice, by limiting the slice around a point according to a_{\sqcup}
 ⇒dproj. that cuts the plane "cut"
    Limits orbits shown always by positive values of V_{\_}y
    orbit = gp.Hamiltonian(pot).integrate_orbit(ics, dt=dt, n_steps=t_final/dt)
    orbit_data = {}
    orbit_data["x"] = orbit.pos.x
    orbit_data["y"] = orbit.pos.y
    orbit_data["z"] = orbit.pos.z
    orbit_data["v_x"] = orbit.vel.d_x
    orbit data["v y"] = orbit.vel.d y
    orbit_data["v_z"] = orbit.vel.d_z
    x,y = orbit_data[hor],orbit_data[ver]
    z = orbit_data[cut]
    filtre = np.where((z < (proj_plane + dproj) * z.unit) & (z > (proj_plane -__

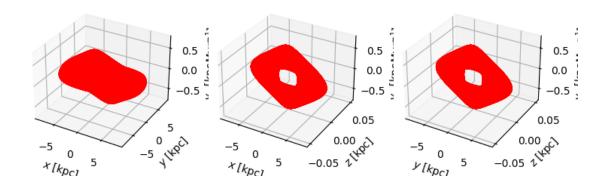
dproj) * z.unit) & (orbit_data["v_y"] > 0))
    x,y = x[filtre],y[filtre]
    return(x,y)
```

4.0.1 Superficies de poincare en potencial completo

```
[14]: fig,axes = multi_poincare(oldgalpot,ics_closed,t_final=1e5*u.Myr)
```



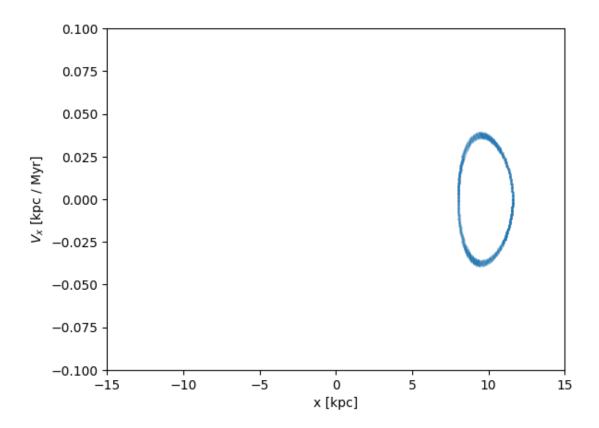
[15]: fig,axes = multi_poincare(newgalpot,ics_closed,t_final=1e4*u.Myr)



4.0.2 Poincare cortes para orbita en el potencial completo

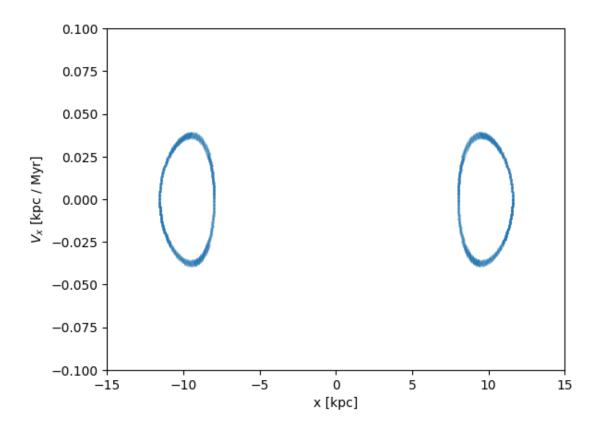
```
[16]: fig,ax = plt.subplots(1,1)
x,y = poincare_slice_hw(oldgalpot,ics_closed,t_final=1e5*u.Myr)
ax.scatter(x,y,s=1e-2)
ax.set_xlabel(f"x [{x.unit}]")
ax.set_ylabel(f"$V_x$ [{y.unit}]")
ax.set_xlim(-15,15)
ax.set_ylim(-0.1,0.1)
```

[16]: (-0.1, 0.1)



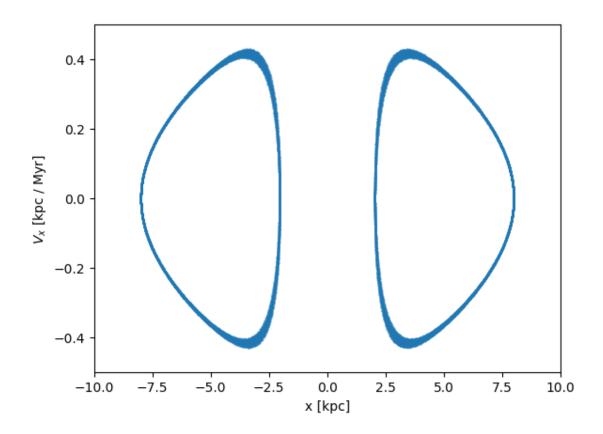
```
[17]: fig,ax = plt.subplots(1,1)
x,y = poincare_slice(oldgalpot,ics_closed,t_final=1e5*u.Myr)
ax.scatter(x,y,s=1e-2)
ax.set_xlabel(f"x [{x.unit}]")
ax.set_ylabel(f"$V_x$ [{y.unit}]")
ax.set_xlim(-15,15)
ax.set_ylim(-0.1,0.1)
```

[17]: (-0.1, 0.1)



```
fig,ax = plt.subplots(1,1)
x,y = poincare_slice(newgalpot,ics_closed,t_final=1e5*u.Myr)
ax.scatter(x,y,s=.1)
ax.set_xlabel(f"x [{x.unit}]")
ax.set_ylabel(f"$V_x$ [{y.unit}]")
ax.set_xlim(-10,10)
ax.set_ylim(-0.5,0.5)
```

[18]: (-0.5, 0.5)



4.0.3 Superficies de poincare en cada potencial progresivo

```
[21]: def multi_poincare_pots(pot,ics,
                         xyz=["x","y","v_x"],
                         t_final=4000*u.Myr
          HHHH
          Makes 3 poincare 3d surfaces, according to xyz1,xyz2 and xyz3
          N = len(pot.keys())
          fig,axes = plt.subplots(1,N,figsize=(2*N,2), subplot_kw={'projection':__

¬"3d"})
          i = 0
          sumpot = gp.CCompositePotential()
          components_str = ''
          for key in pot.keys():
              sumpot[key] = pot[key]
              poincare_surface(sumpot,ics,t_final=t_final,xyz=xyz, ax=axes[i])
              components_str += key + '+'
              axes[i].set_title(f'{components_str}',fontsize=8)
              i+=1
```

```
return(fig,axes)
def poincare_slice_pots(pot, ics,
                         hor="x", ver="v_x", cut="y",
                         proj_plane=0,
                         dproj=1e-1,
                         dt=0.1*u.Myr, t_final=1000*u.Myr
                        ):
    Makes a poincare slice, by limiting the slice around a point according to a_{\sqcup}
 ⇔dproj. that cuts the plane "cut"
    N = len(pot.keys())
    fig,axes = plt.subplots(1,N,figsize=(2*N,2))
    sumpot = gp.CCompositePotential()
    i = 0
    components str = ''
    for key in pot.keys():
        sumpot[key] = pot[key]
        x,y = poincare_slice(sumpot,ics,
 hor=hor, ver=ver, cut=cut, proj_plane=proj_plane, dproj=dproj, ax=axes[i], dt=dt, t_final=t_final=
        axes[i].scatter(x,y,s=1e-2)
        axes[i].set_xlabel(f"{hor} [{x.unit}]")
        axes[i].set_ylabel(f"${ver}$ [{y.unit}]")
        components str += key + '+'
        axes[i].set_title(f'{components_str}',fontsize=8)
        i+=1
    return(fig,axes)
def poincare_slice_pots_hw(pot, ics,
                        hor="x", ver="v_x", cut="y",
                        proj_plane=0,
                         dproj=1e-1,
                        dt=0.1*u.Myr, t_final=1000*u.Myr
                        ):
    n n n
    Makes a poincare slice, by limiting the slice around a point according to a_{\sqcup}
 ⇒dproj. that cuts the plane "cut"
    Limits orbits shown always by positive values of V_y
    11 11 11
    N = len(pot.keys())
    fig,axes = plt.subplots(1,N,figsize=(2*N,2))
    sumpot = gp.CCompositePotential()
    i = 0
    components_str = ''
```

```
for key in pot.keys():
    sumpot[key] = pot[key]
    x,y = poincare_slice_hw(sumpot,ics,

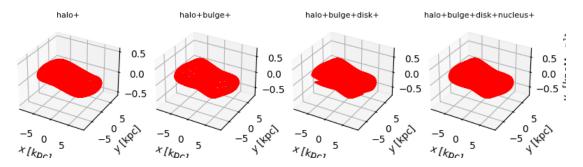
whor=hor,ver=ver,cut=cut,proj_plane=proj_plane,dproj=dproj,ax=axes[i],dt=dt,t_final=t_final
    )
    axes[i].scatter(x,y,s=1e-2)
    axes[i].set_xlabel(f"{hor} [{x.unit}]")
    axes[i].set_ylabel(f"{ver} [{y.unit}]")
    components_str += key + '+'
    axes[i].set_title(f'{components_str}',fontsize=8)
    i+=1
    return(fig,axes)
```

desde aqui solo utilizo el potencial nuevo Se representan las superficies de las orbitas de manera progresiva, se considera solo el caso x vs y vs v_x añadido en el apendice se ven casos extras

```
[22]: r = [8,0,0] * u.kpc
v = [0, 190, 0] * u.km/u.s
ics_closed = gd.PhaseSpacePosition(pos=r,vel=v)

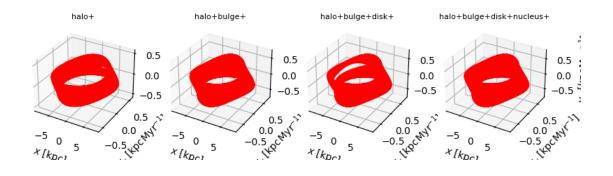
plt.ioff(); fig = plt.figure(); plt.ion()
# whatever plotting you want

fig, axes = multi_poincare_pots(newgalpot, ics_closed, xyz=["x","y","v_x"])
plt.tight_layout()
display(fig)
plt.close()
plt.show()
```

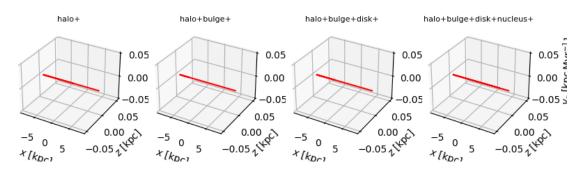


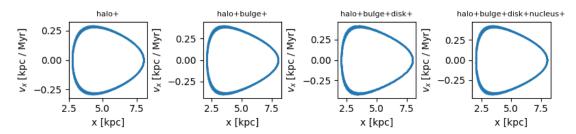
<Figure size 640x480 with 0 Axes>

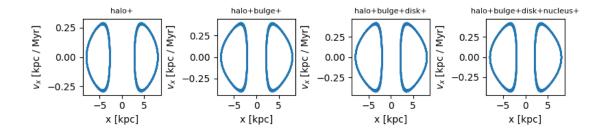
```
[23]: multi_poincare_pots(newgalpot, ics_closed, xyz=["x","v_y","v_x"])
plt.tight_layout()
```



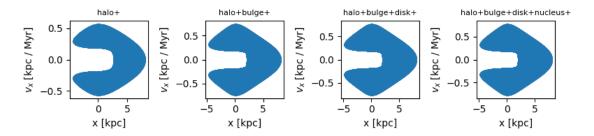
[24]: multi_poincare_pots(newgalpot, ics_closed, xyz=["x","z","v_z"])
plt.tight_layout()

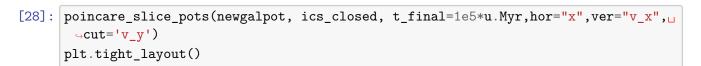


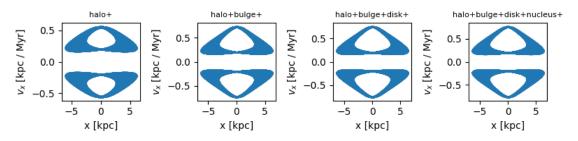


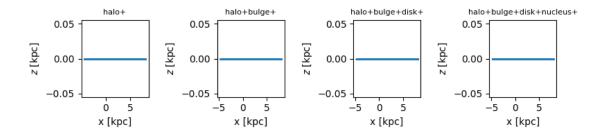


[27]: # FIXED PLOT poincare_slice_pots_hw(newgalpot, ics_closed, t_final=1e5*u. Myr,hor="x",ver="v_x", cut='v_z') plt.tight_layout()









```
[30]: poincare_slice_pots(newgalpot, ics_closed, t_final=1e5*u.Myr,hor="x",ver="z",u
         ⇔cut='v_z')
       plt.tight_layout()
                                             halo+bulge+
                                                                  halo+bulge+disk+
                                                                                      halo+bulge+disk+nucleus+
                 0.05
                                       0.05
                                                              0.05
                                                                                     0.05
                 0.00
                                       0.00
                                                              0.00
                                                                                     0.00
                -0.05
                                      -0.05
                                                             -0.05
                                                                                    -0.05
```

5

4.0.4 Cortes de las superficies de poincare en cada potencial progresivo

_5 O

x [kpc]

4.1 2.1) Discusion

_5 0 5

x [kpc]

Podemos ver claramente que estamos tratando con una orbita regular, ya que los cortes de las superficies de poincare estan limitados a un rmin y un rmax, al igual que al verlo en 3d se ven como torus limitados, en todos los casos.

_5 0 5

x [kpc]

_5 o

x [kpc]

Si fueran orbitas caoticas ocurriria que veriamos en alguno de los cortes de las superficies como la orbita no esta limitada

5 3) Analisis repeticion

Realizando evolucion de parametros temporalmente y superficies de poincare para: - Orbita circular en potencial DM Halo y Miyamoto-Nagai - Orbita anterior levemente perturbada

5.1 Orbita circular

```
[31]: circpot = gp.CCompositePotential()
  circpot["halo"] = newgalpot["halo"]
  circpot["disk"] = newgalpot["disk"]

r = [8,0,0] * u.kpc
```

```
V_circ = circpot.circular_velocity(r)
V_circ = V_circ[0]
V_circ = V_circ.value

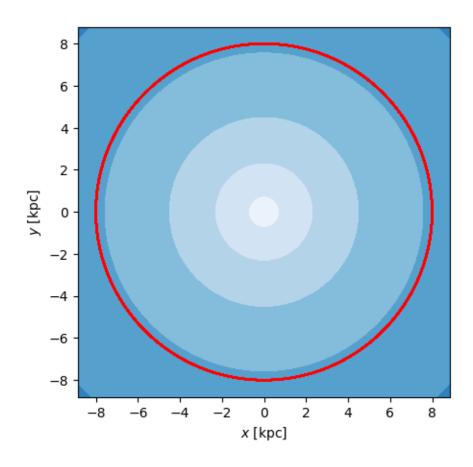
v = [0, V_circ, 0] * u.km/u.s
circular_ics = gd.PhaseSpacePosition(pos=r,vel=v)
```

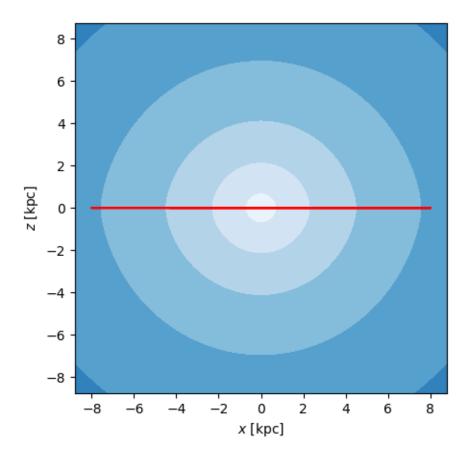
```
orbit = gp.Hamiltonian(circpot).integrate_orbit(circular_ics, dt=0.4, un_steps=1e4)
grid = np.linspace(-30,30,1000)

fig,ax = plt.subplots(1,1,figsize=(5,5))
orbit.plot(components=['x','y'], color='red', axes=ax)
circpot.plot_contours(grid=(grid,grid,0), ax=ax)
plt.show

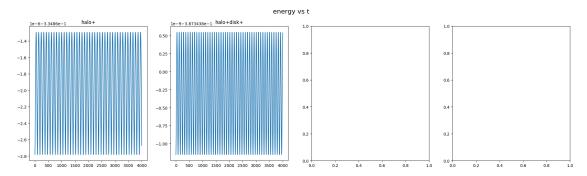
fig,ax = plt.subplots(1,1,figsize=(5,5))
orbit.plot(components=['x','z'], color='red', axes=ax)
circpot.plot_contours(grid=(grid,0,grid), ax=ax)
plt.show
```

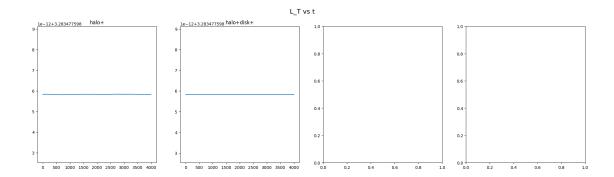
[33]: <function matplotlib.pyplot.show(close=None, block=None)>





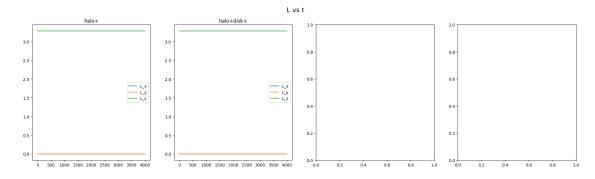






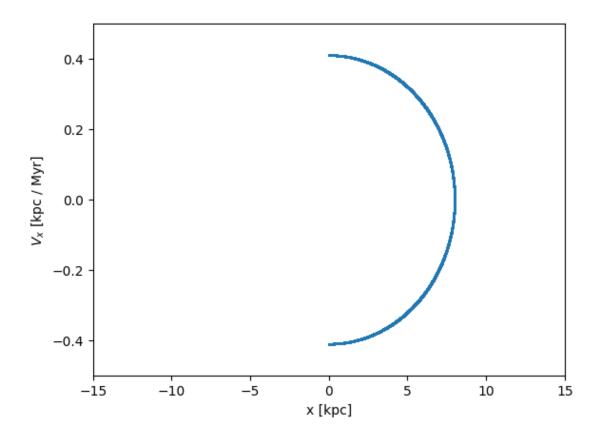
```
[36]: #fig,axes = parametersvstime(circpot,"e",circular_ics)
plt.show()
```

```
[37]: fig,axes = parametersvstime(circpot, "L", circular_ics)
plt.show()
```



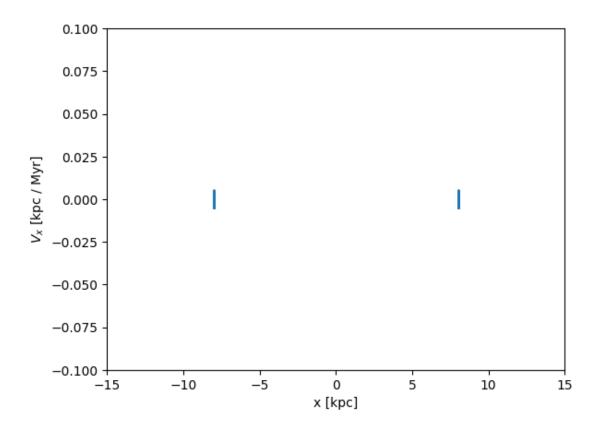
```
[38]: # FIXED PLOT
fig,ax = plt.subplots(1,1)
x,y = poincare_slice_hw(circpot,circular_ics,t_final=1e5*u.Myr,cut='v_z')
ax.scatter(x,y,s=1e-2)
ax.set_xlabel(f"x [{x.unit}]")
ax.set_ylabel(f"$V_x$ [{y.unit}]")
ax.set_ylabel(f"$0.5,0.5)
```

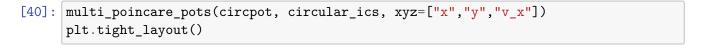
[38]: (-0.5, 0.5)

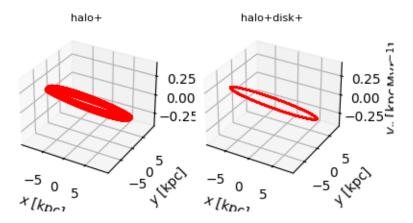


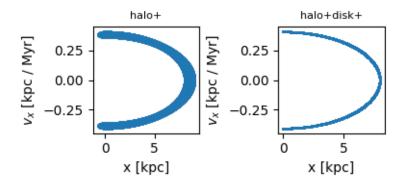
```
[39]: fig,ax = plt.subplots(1,1)
x,y = poincare_slice(circpot,circular_ics,t_final=1e5*u.Myr)
ax.scatter(x,y,s=1e-2)
ax.set_xlabel(f"x [{x.unit}]")
ax.set_ylabel(f"$V_x$ [{y.unit}]")
ax.set_xlim(-15,15)
ax.set_ylim(-0.1,0.1)
```

[39]: (-0.1, 0.1)

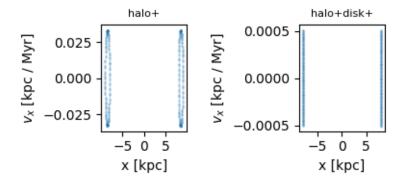




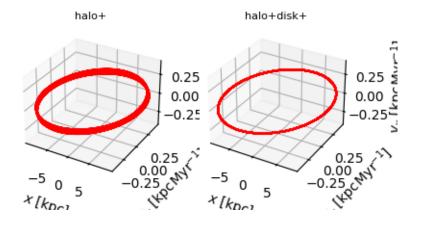




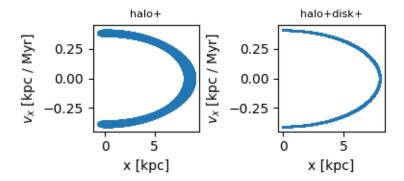
[42]: poincare_slice_pots(circpot, circular_ics, t_final=1e5*u.Myr,hor="x",ver="v_x",u ocut='y', dproj=1e-2)
plt.tight_layout()



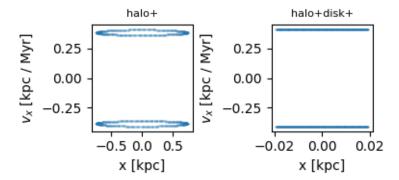
[43]: multi_poincare_pots(circpot, circular_ics, xyz=["x","v_y","v_x"])
plt.tight_layout()



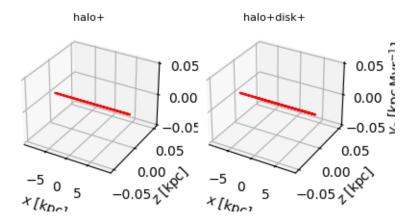
[44]: # FIXED PLOT poincare_slice_pots_hw(circpot, circular_ics, t_final=1e5*u. ∴Myr,hor="x",ver="v_x", cut='v_y', dproj=1e2) plt.tight_layout()

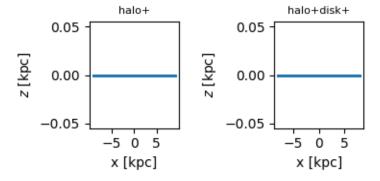


[45]: poincare_slice_pots(circpot, circular_ics, t_final=1e5*u.Myr,hor="x",ver="v_x", u cut='v_y', dproj=1e-3)
plt.tight_layout()

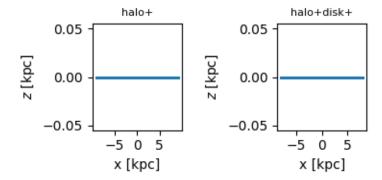


```
[46]: multi_poincare_pots(circpot, circular_ics, xyz=["x","z","v_z"])
plt.tight_layout()
```





[48]: poincare_slice_pots(circpot, circular_ics, t_final=1e5*u.Myr,hor="x",ver="z",u cut='v_z', dproj=1e-3)
plt.tight_layout()

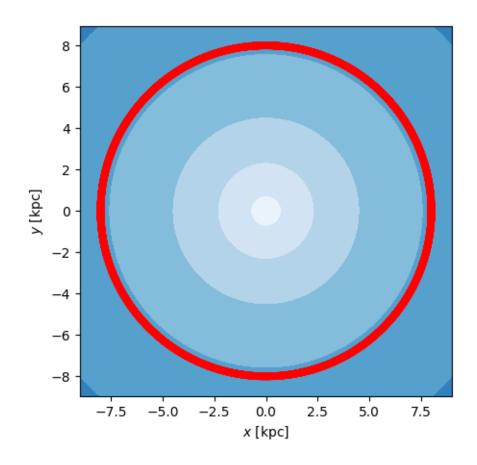


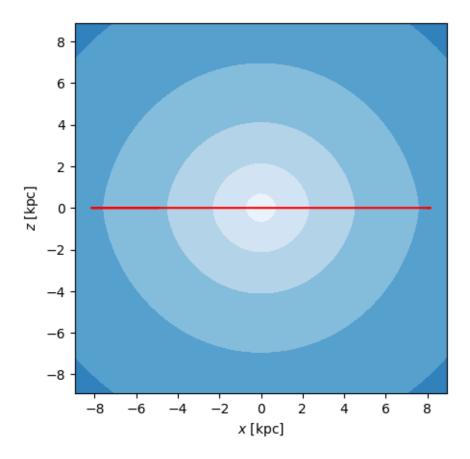
5.2 Orbita perturbada levemente

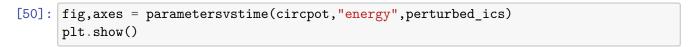
```
[49]: r = [8,0,0] * u.kpc
      V_circ = circpot.circular_velocity(r)
      print(V_circ)
      V_circ = V_circ[0]
      V_circ = V_circ.value
      v = [10, V\_circ, 0] * u.km/u.s
      perturbed_ics = gd.PhaseSpacePosition(pos=r,vel=v)
      perturbed_orbit = gp.Hamiltonian(circpot).integrate_orbit(perturbed_ics, dt=0.
       \rightarrow 4, n_steps=1e4)
      grid = np.linspace(-30,30,1000)
      fig,ax = plt.subplots(1,1,figsize=(5,5))
      perturbed_orbit.plot(components=['x','y'], color='red', axes=ax)
      circpot.plot_contours(grid=(grid,grid,0), ax=ax)
      plt.show
      fig,ax = plt.subplots(1,1,figsize=(5,5))
      perturbed_orbit.plot(components=['x','z'], color='red', axes=ax)
      circpot.plot_contours(grid=(grid,0,grid), ax=ax)
      plt.show
```

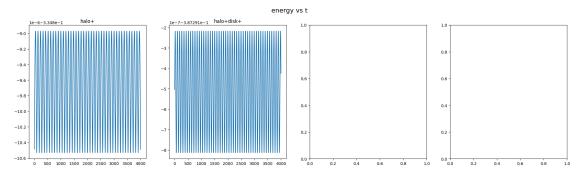
[401.31985689] km / s

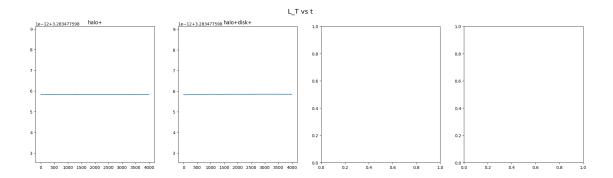
[49]: <function matplotlib.pyplot.show(close=None, block=None)>





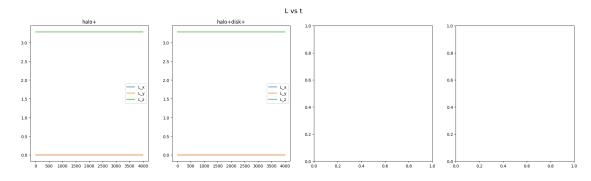






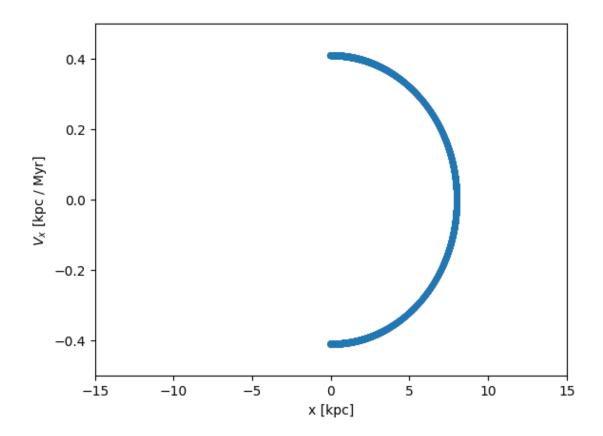
```
[52]: #fig,axes = parametersvstime(circpot,"e",perturbed_ics)
plt.show()
```

[53]: fig,axes = parametersvstime(circpot, "L", perturbed_ics)
plt.show()



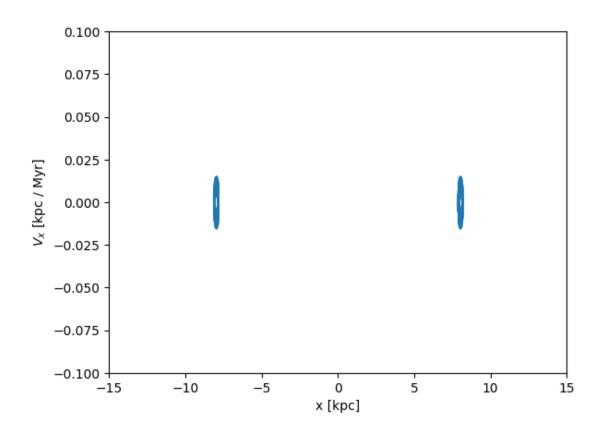
```
[54]: # FIXED PLOT
fig,ax = plt.subplots(1,1)
x,y = poincare_slice_hw(circpot,perturbed_ics,t_final=1e5*u.Myr,dproj=1e2)
ax.scatter(x,y,s=1e-2)
ax.set_xlabel(f"x [{x.unit}]")
ax.set_ylabel(f"$V_x$ [{y.unit}]")
ax.set_xlim(-15,15)
ax.set_ylim(-0.5,0.5)
```

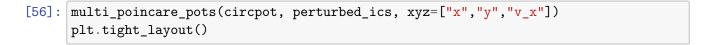
[54]: (-0.5, 0.5)

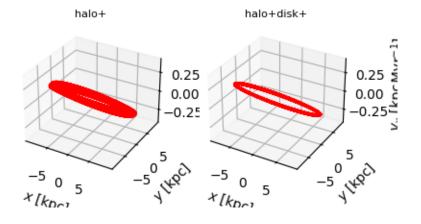


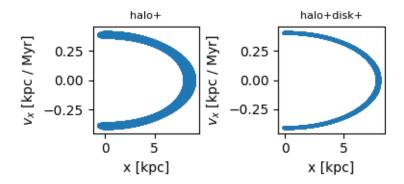
```
[55]: fig,ax = plt.subplots(1,1)
x,y = poincare_slice(circpot,perturbed_ics,t_final=1e5*u.Myr)
ax.scatter(x,y,s=1e-2)
ax.set_xlabel(f"x [{x.unit}]")
ax.set_ylabel(f"$V_x$ [{y.unit}]")
ax.set_xlim(-15,15)
ax.set_ylim(-0.1,0.1)
```

[55]: (-0.1, 0.1)





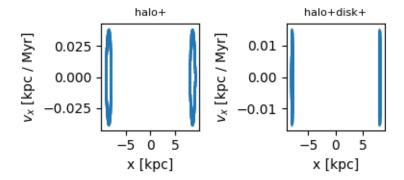




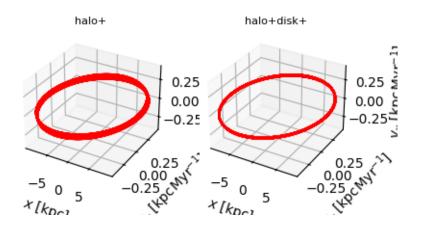
```
[58]: poincare_slice_pots(circpot, perturbed_ics, t_final=1e5*u.

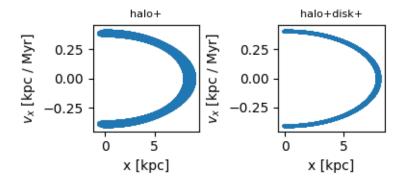
Myr,hor="x",ver="v_x", cut='y', dproj=1e-1)

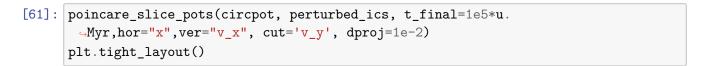
plt.tight_layout()
```

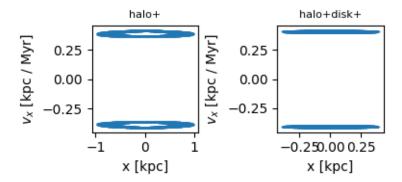


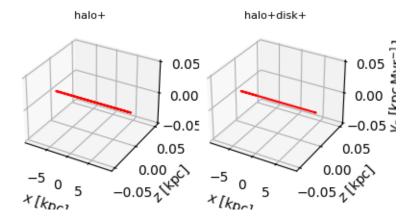
[59]: multi_poincare_pots(circpot, perturbed_ics, xyz=["x","v_y","v_x"])
plt.tight_layout()

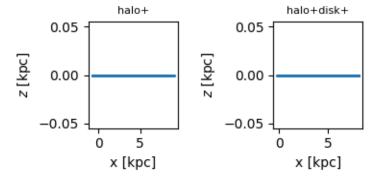








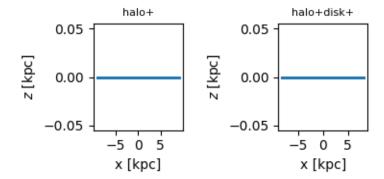




[64]: poincare_slice_pots(circpot, perturbed_ics, t_final=1e5*u.Myr,hor="x",ver="z",

cut='v_z', dproj=1e-2)

plt.tight_layout()



5.3 3.1 Discusion

Como podemos ver en las superficies, cuando se trata de perturbaciones tan leves, los cortes de las superficies no suelen cambiar demasiado, ya que seguimos estando en un punto estable energeticamente hablando.

Es posible realizar perturbaciones mayores las cuales si llegan a desembocar en cambios en los cortes de las superficies(zona bonus)

llegando a llenar densamente un corte en los casos donde las 2 integrales de movimiento restantes no son aislantes. LLegando a tener curvas en los cortes de superficie cuando la segunda integral de movimiento si es aislante Y el caso extremo es donde tenemos un numero finito de puntos cuando tenemos una tercera integral aislante

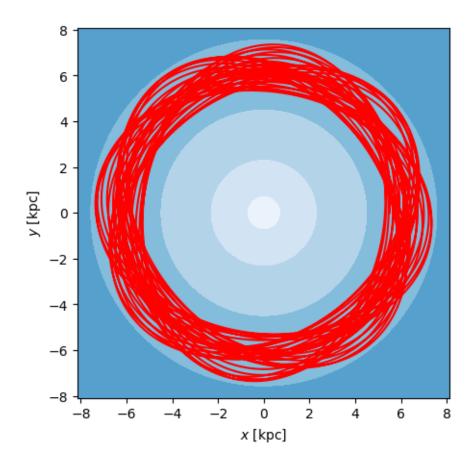
Claramente en todas estas orbitas y potenciales tenemos asegurada una integral aislante, la energia, debido a que nuestros potenciales simulados son constantes en el tiempo

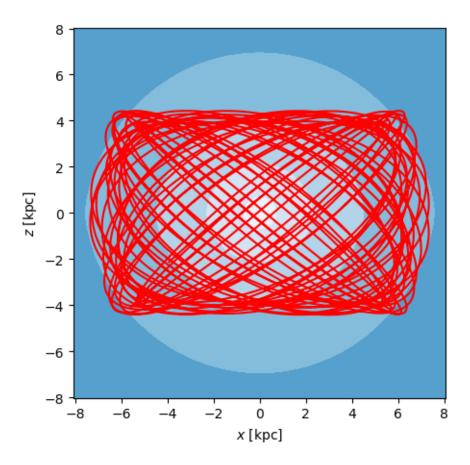
5.4 (BONUS)Orbita locaaa

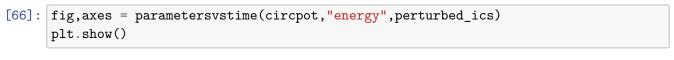
```
[65]: r = [5.5,0,4] * u.kpc
      V_circ = circpot.circular_velocity(r)
      print(V_circ)
      V_circ = V_circ[0]
      V_circ = V_circ.value
      v = [30, V circ, 35] * u.km/u.s
      perturbed_ics = gd.PhaseSpacePosition(pos=r,vel=v)
      perturbed_orbit = gp.Hamiltonian(circpot).integrate_orbit(perturbed_ics, dt=0.
       4, n_steps=1e4)
      grid = np.linspace(-30,30,1000)
      fig,ax = plt.subplots(1,1,figsize=(5,5))
      perturbed_orbit.plot(components=['x','y'], color='red', axes=ax)
      circpot.plot_contours(grid=(grid,grid,0), ax=ax)
      plt.show
      fig,ax = plt.subplots(1,1,figsize=(5,5))
      perturbed_orbit.plot(components=['x','z'], color='red', axes=ax)
      circpot.plot_contours(grid=(grid,0,grid), ax=ax)
      plt.show
```

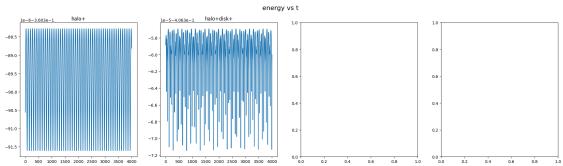
[394.9016256] km / s

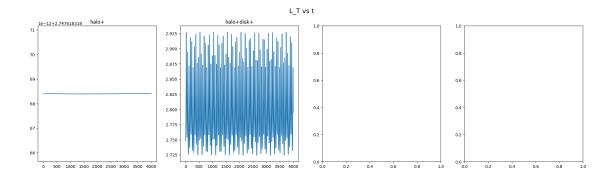
[65]: <function matplotlib.pyplot.show(close=None, block=None)>





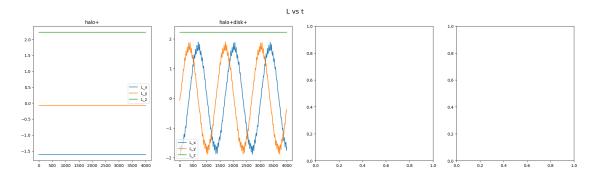




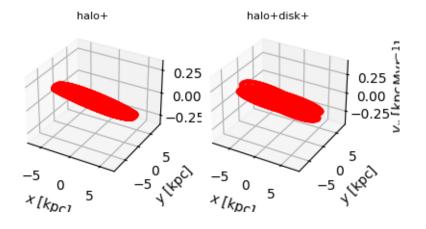


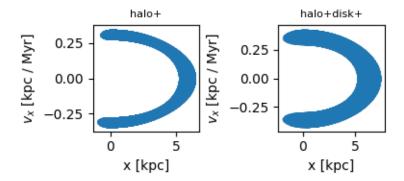
[68]: #fig,axes = parametersvstime(circpot,"e",perturbed_ics)
plt.show()

[69]: fig,axes = parametersvstime(circpot, "L", perturbed_ics)
plt.show()

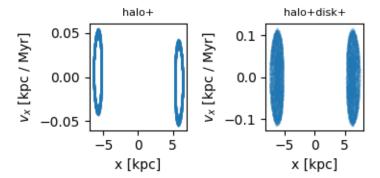


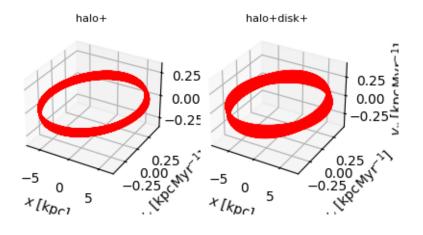
[70]: multi_poincare_pots(circpot, perturbed_ics, xyz=["x","y","v_x"])
plt.tight_layout()

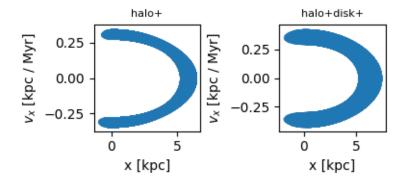




[72]: poincare_slice_pots(circpot, perturbed_ics, t_final=1e5*u. Myr,hor="x",ver="v_x", cut='y', dproj=1e-1) plt.tight_layout()



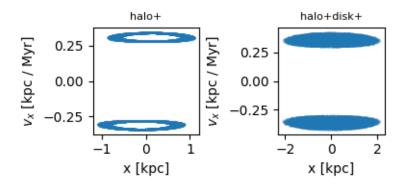




[75]: poincare_slice_pots(circpot, perturbed_ics, t_final=1e5*u.

Myr,hor="x",ver="v_x", cut='v_y', dproj=1e-2)

plt.tight_layout()



[76]: multi_poincare_pots(circpot, perturbed_ics, xyz=["x","z","v_z"]) plt.tight_layout()

