



GPU COMPUTING TO EXASCALE AND BEYOND

BILL DALLY

CHIEF SCIENTIST & SVP OF RESEARCH, NVIDIA



GPU Computing

1 The GPU Advantage

2 To ExaScale and Beyond

3 The GPU is the Computer

The GPU Advantage

The GPU Advantage

A Tale of Two Machines

Tianhe-1A

at NSC Tianjin



Tianhe-1A

at NSC Tianjin

- The World's Fastest Supercomputer
- 2.507 Petaflop
- 7168 Tesla M2050 GPUs

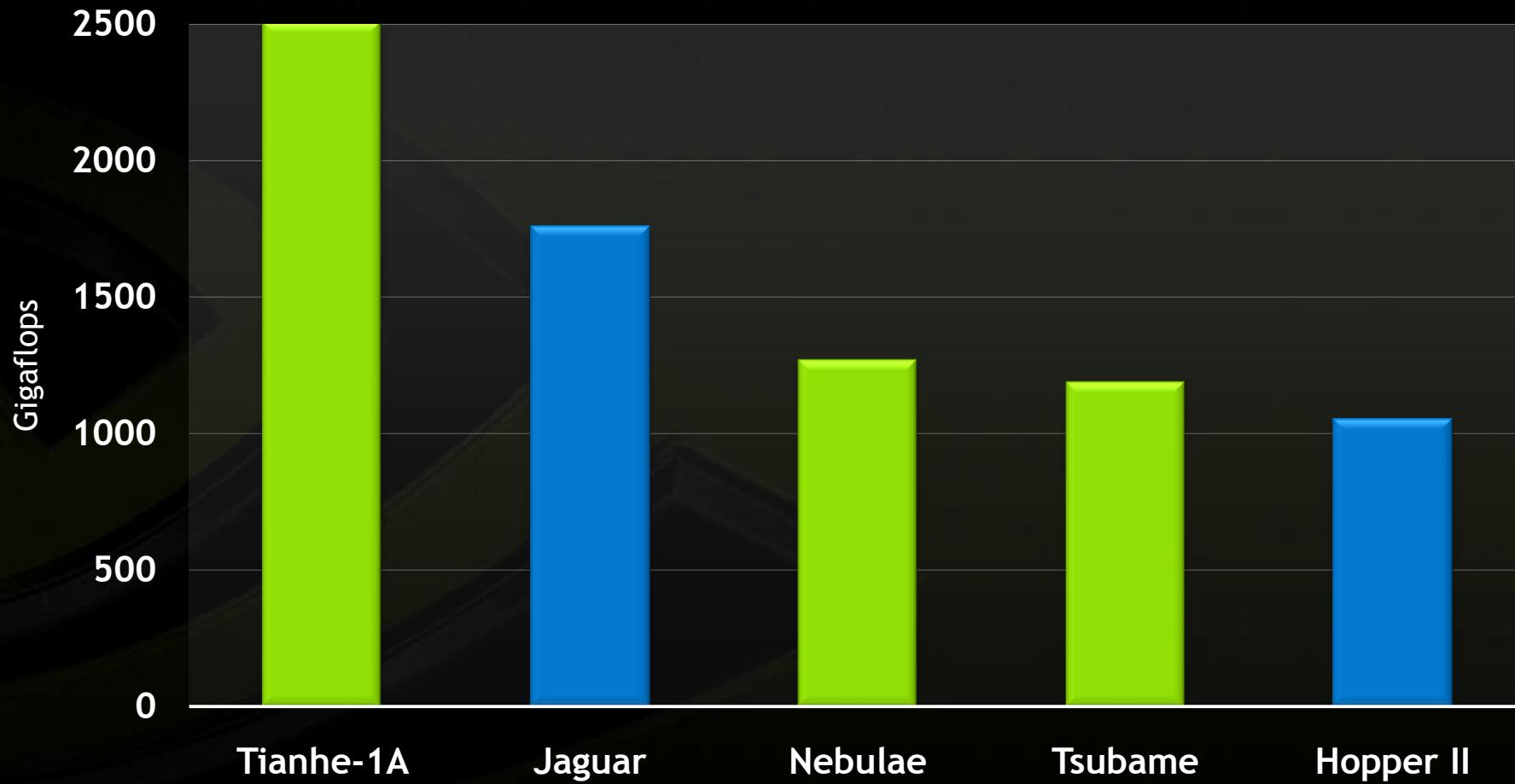


Tesla M2050 GPUs



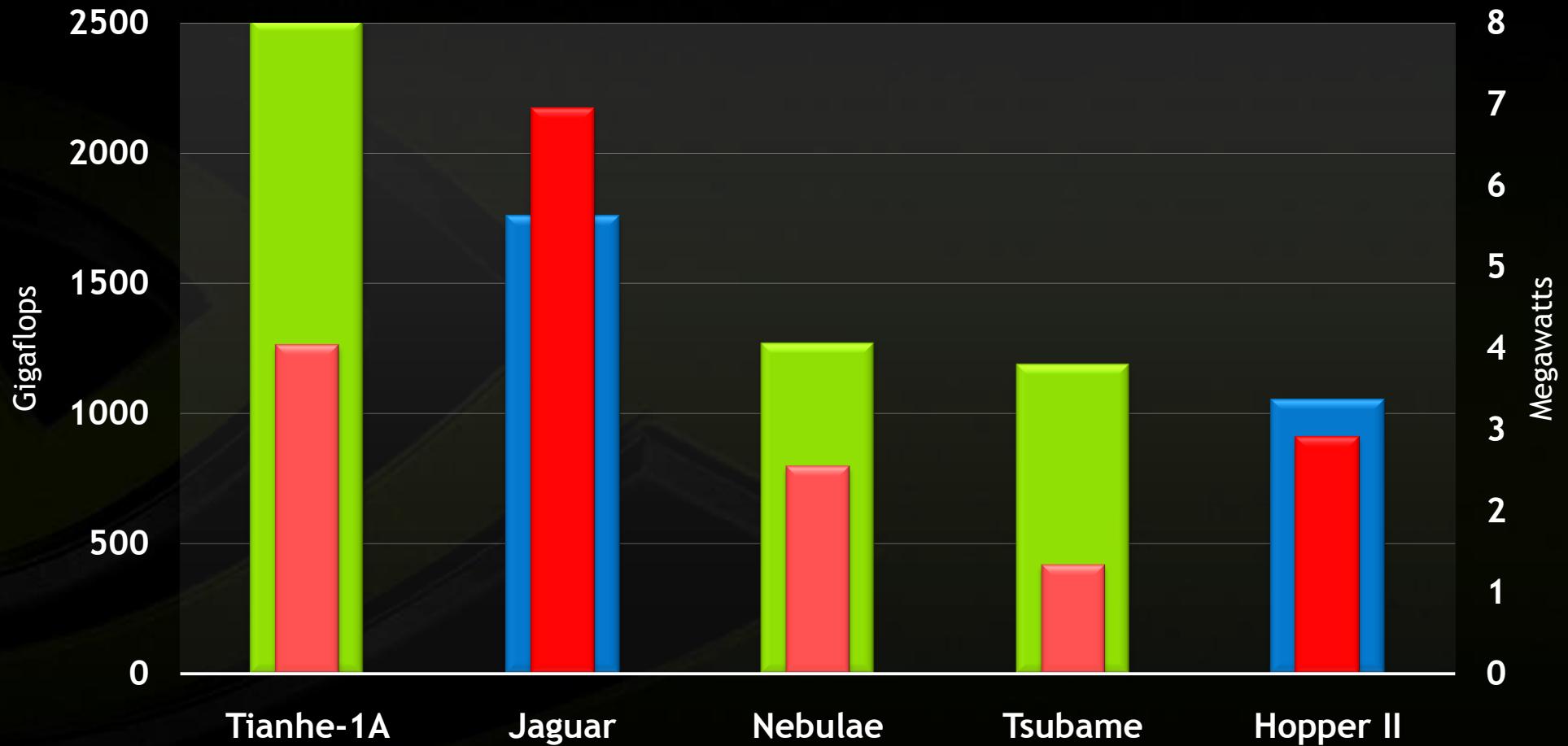


3 of Top5 Supercomputers





Top 5 Performance and Power



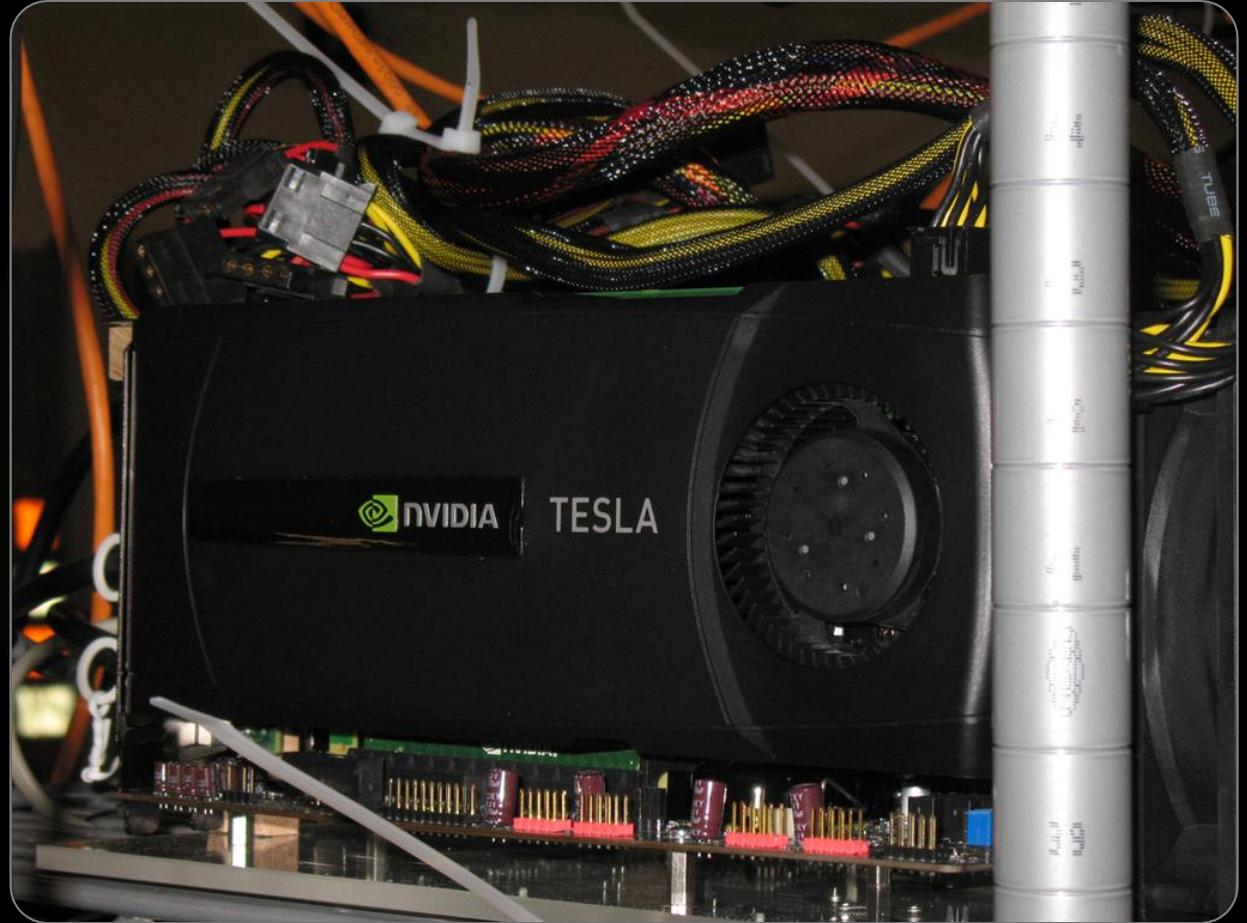
NVIDIA/NCSA

Green 500 Entry



NVIDIA/NCSA

Green 500 Entry



NVIDIA/NCSA Green 500 Entry



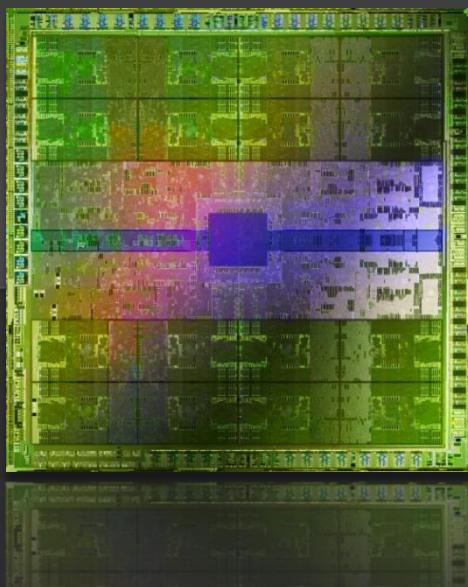
- **128 nodes, each with:**
 - 1x Core i3 530 (2 cores, 2.93 GHz => 23.4 GFLOP peak)
 - 1x Tesla C2050 (14 cores, 1.15 GHz => 515.2 GFLOP peak)
 - 4x QDR Infiniband
 - 4 GB DRAM
- **Theoretical Peak Perf: 68.95 TF**
- **Footprint: ~20 ft² => 3.45 TF/ft²**
- **Cost: \$500K (street price) => 137.9 MF/\$**
- **Linpack: 33.62 TF, 36.0 kW => 934 MF/W**

The GPU Advantage

Efficiency and Programmability

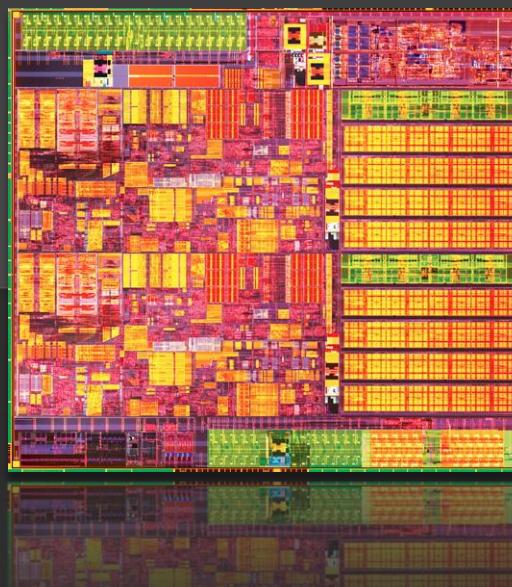
GPU

200pJ/Instruction



CPU

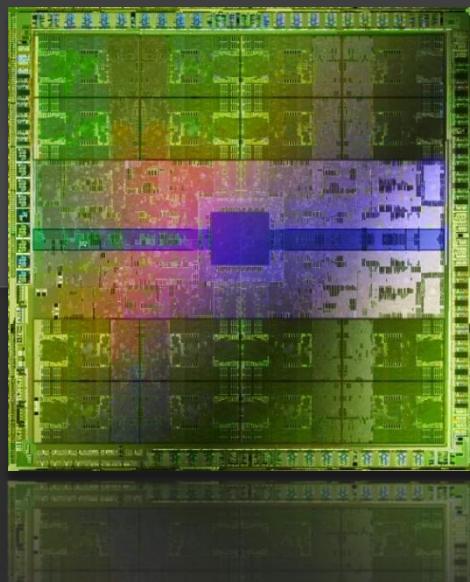
2nJ/Instruction



GPU

200pJ/Instruction

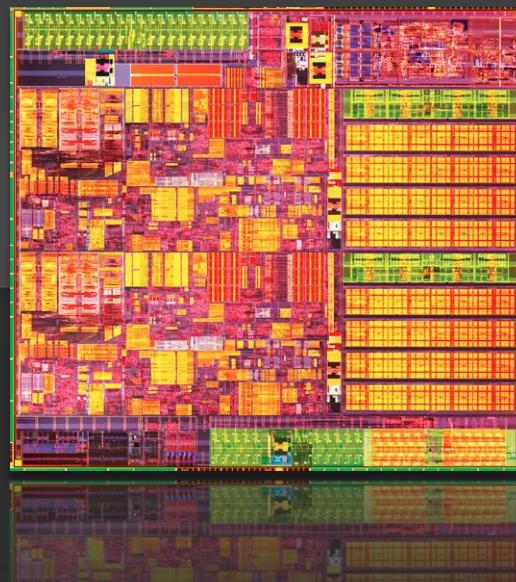
Optimized for Throughput
Explicit Management
of On-chip Memory



CPU

2nJ/Instruction

Optimized for Latency
Caches



CUDA GPU Roadmap



The GPU Advantage

Efficiency and Programmability

The GPU Advantage

CUDA Enables Programmability



CUDA C: C with a Few Keywords

```
void saxpy_serial(int n, float a, float *x, float *y)
{
    for (int i = 0; i < n; ++i)
        y[i] = a*x[i] + y[i];
}
// Invoke serial SAXPY kernel
saxpy_serial(n, 2.0, x, y);
```

*Standard
C Code*

```
__global__ void saxpy_parallel(int n, float a, float *x, float *y)
{
    int i = blockIdx.x*blockDim.x + threadIdx.x;
    if (i < n)  y[i] = a*x[i] + y[i];
}
// Invoke parallel SAXPY kernel with 256 threads/block
int nblocks = (n + 255) / 256;
saxpy_parallel<<<nblocks, 256>>>(n, 2.0, x, y);
```

*CUDA
C Code*

Research & Education



Libraries

$$\oint \mathbf{E} \cdot d\mathbf{A} = \frac{q_{enc}}{\epsilon_0}$$
$$\oint \mathbf{B} \cdot d\mathbf{A} = 0$$
$$\oint \mathbf{E} \cdot d\mathbf{s} = -\frac{d\Phi_B}{dt}$$
$$\oint \mathbf{B} \cdot d\mathbf{s} = \mu_0 \epsilon_0 \frac{d\Phi_E}{dt} + \mu_0 i_{enc}$$

Mathematical Packages



Integrated Development Environment Parallel Nsight for MS Visual Studio

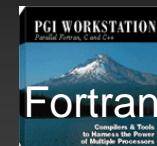


GPU Computing Ecosystem

Languages & API's

CUDA C/C++

Microsoft®
DirectX®11



All Major Platforms



Consultants, Training & Certification



Tools & Partners



GPU Computing Today

By the Numbers:

200 Million

CUDA Capable GPUs

600,000

CUDA Toolkit Downloads

100,000

Active GPU Computing Developers

8,000

Members in Parallel Nsight Developer Program

362

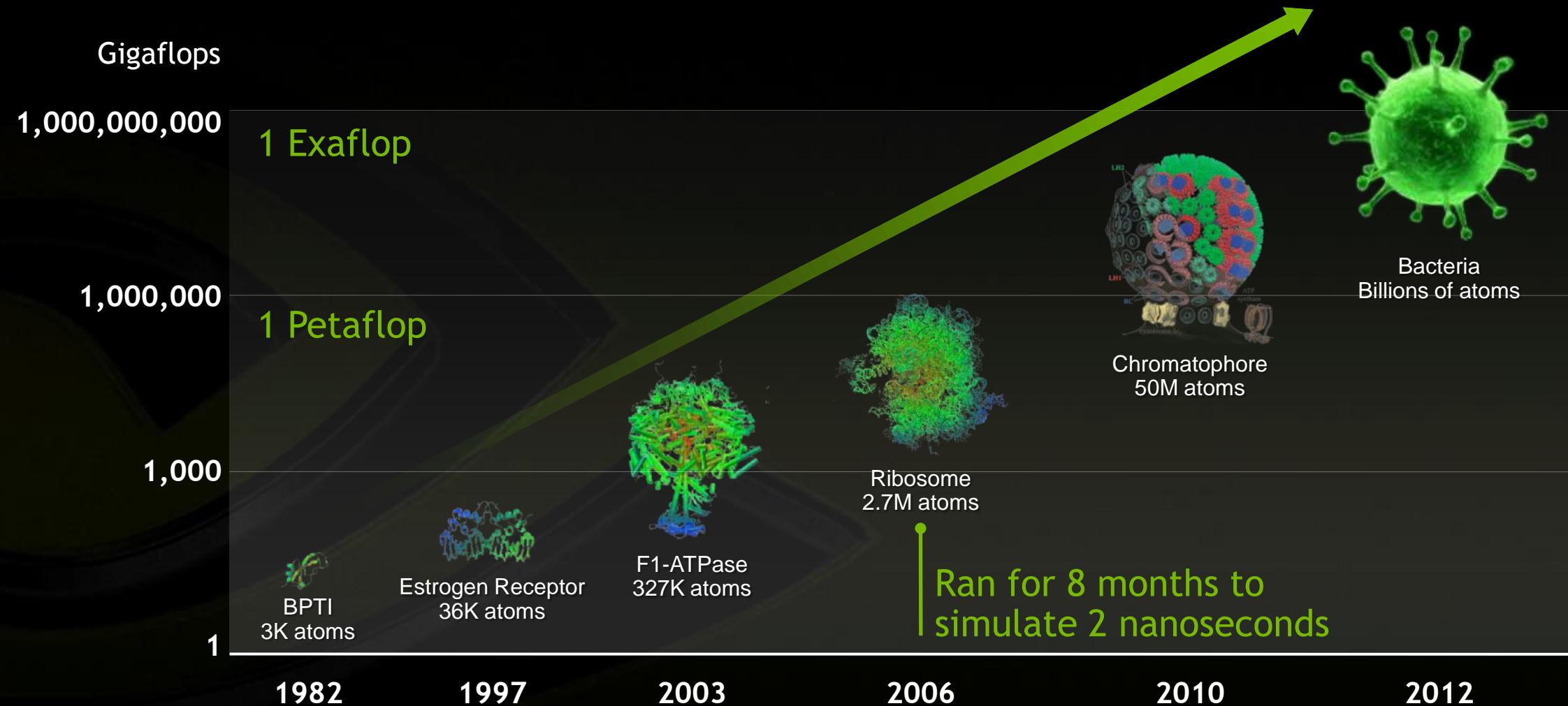
Universities Teaching CUDA Worldwide

11

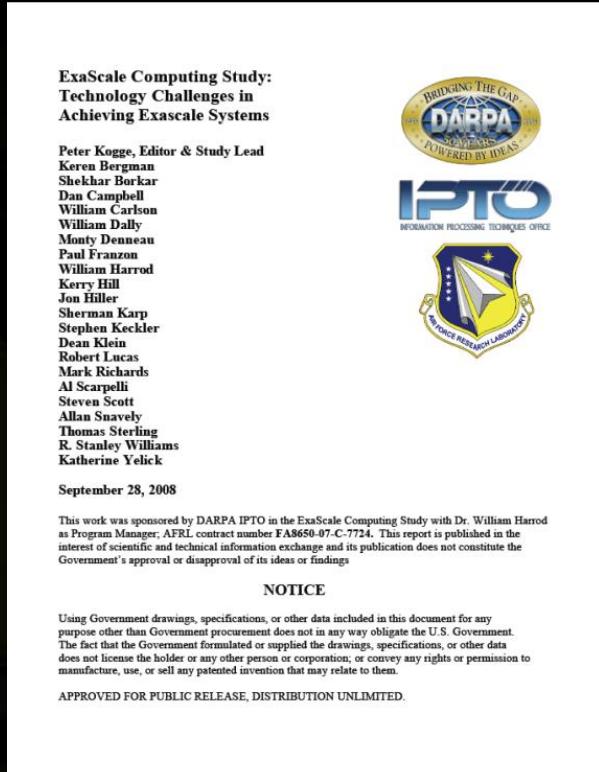
CUDA Centers of Excellence Worldwide

To ExaScale and Beyond

Science Needs 1000x More Computing



DARPA Study Identifies Four Challenges for ExaScale Computing



Report published September 28, 2008:
● Four Major Challenges

- Energy and Power challenge
 - Memory and Storage challenge
 - Concurrency and Locality challenge
 - Resiliency challenge
- Number one issue is power
- Extrapolations of current architectures and technology indicate over 100MW for an Exaflop!
 - Power also constrains what we can put on a chip

Available at

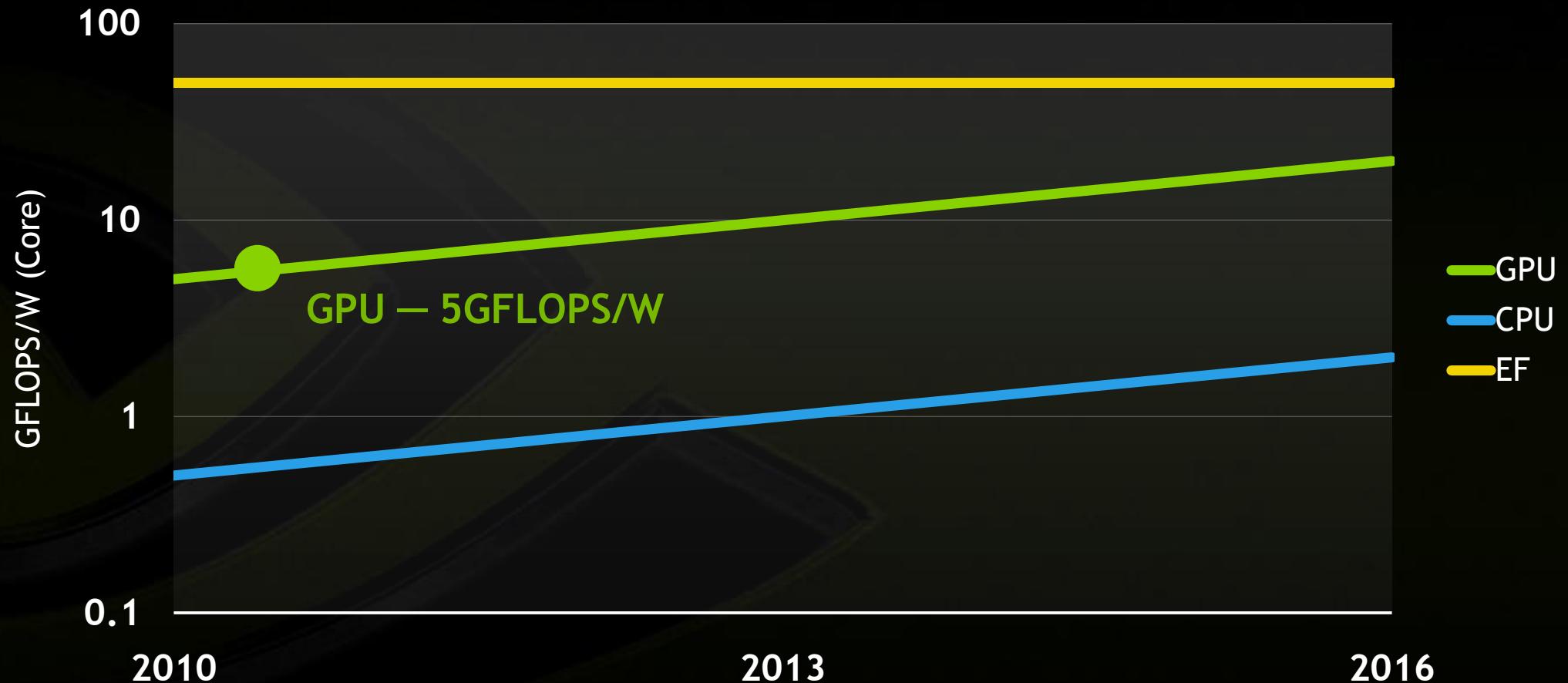
www.darpa.mil/ipto/personnel/docs/ExaScale_Study_Initial.pdf

Power is THE Problem

Power is THE Problem

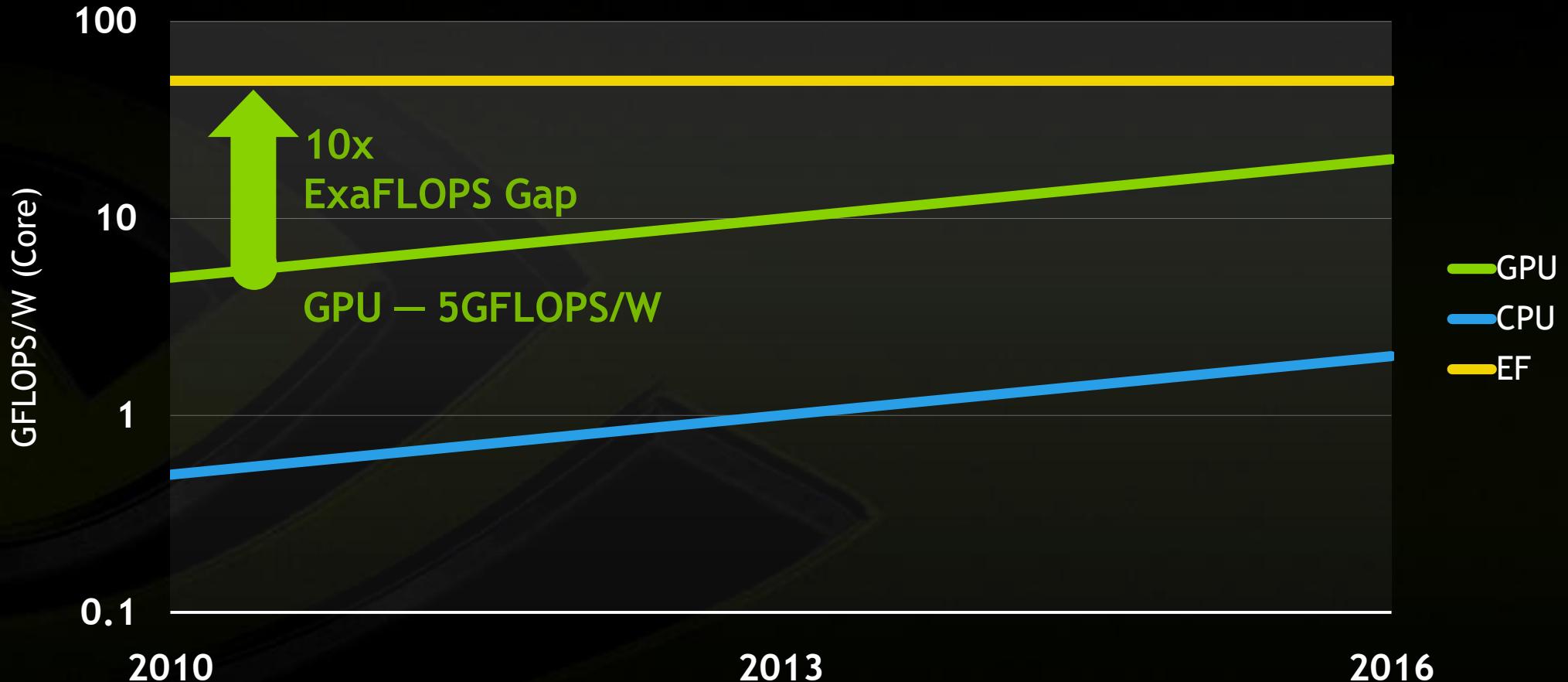
A GPU is the Solution

ExaFLOPS at 20MW = 50GFLOPS/W

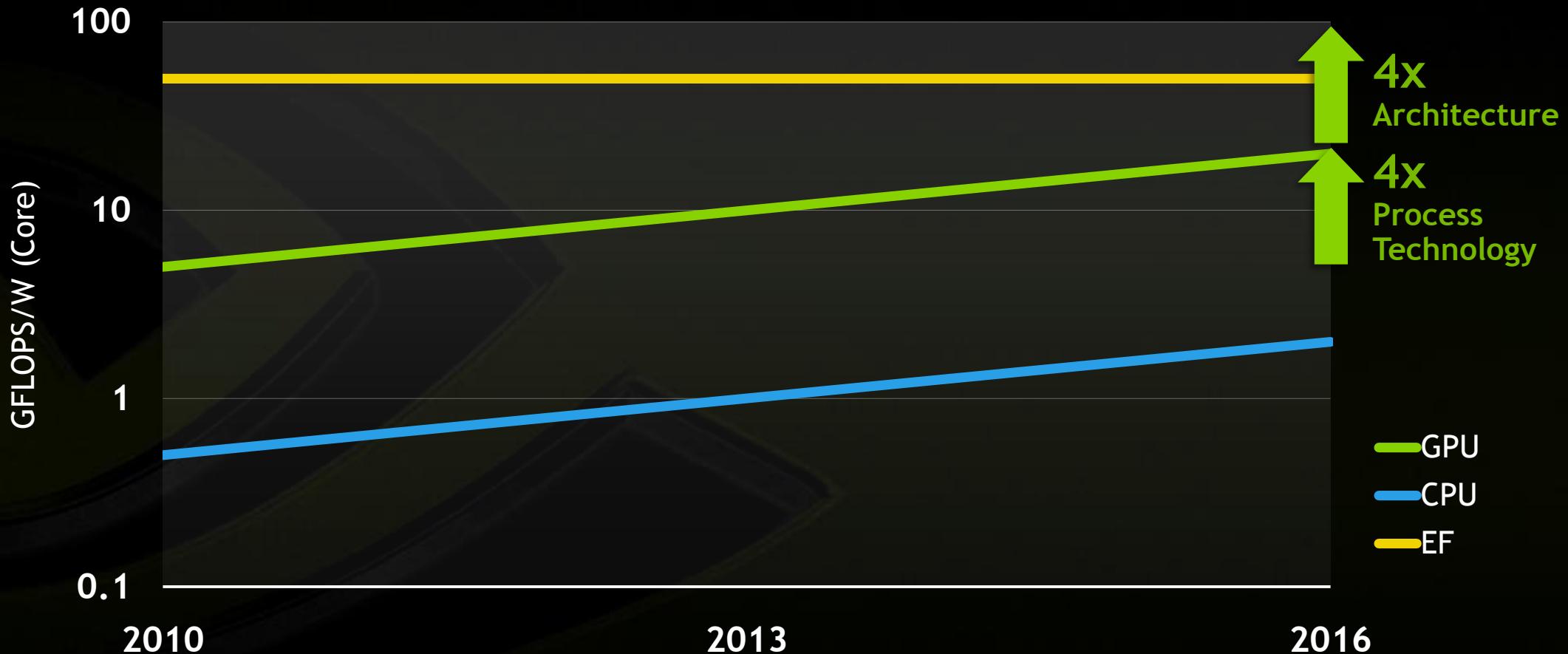


50GFLOPS/W

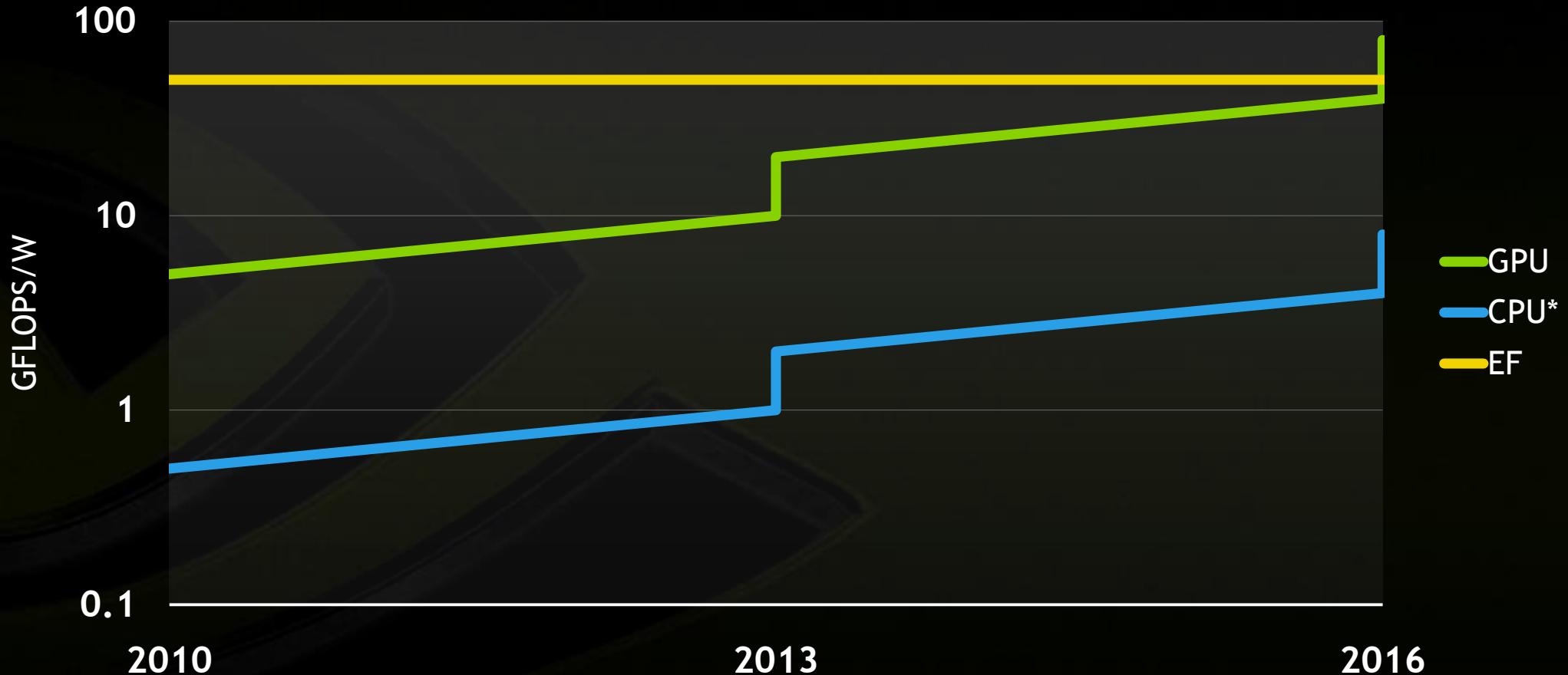
10x Energy Gap for Today's GPU



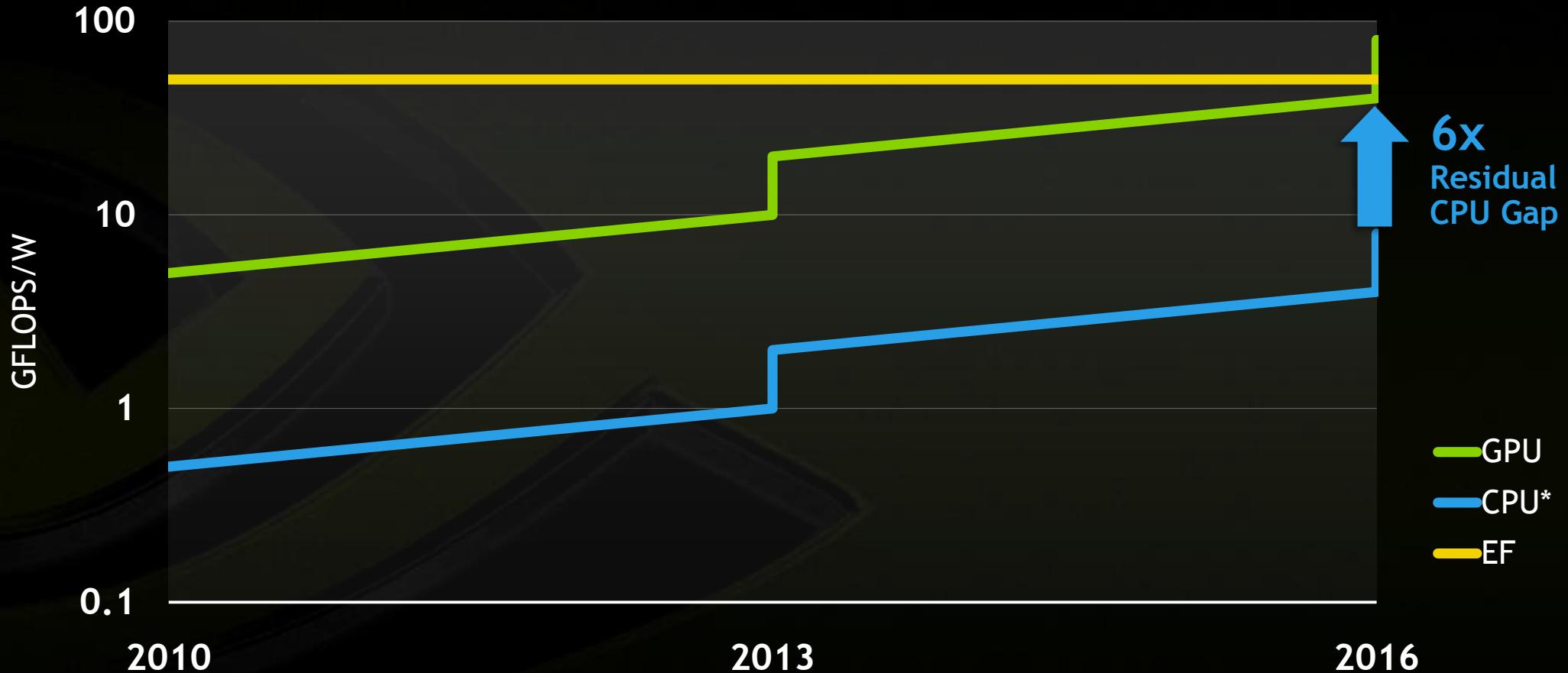
GPUs Close the Gap with Process and Architecture

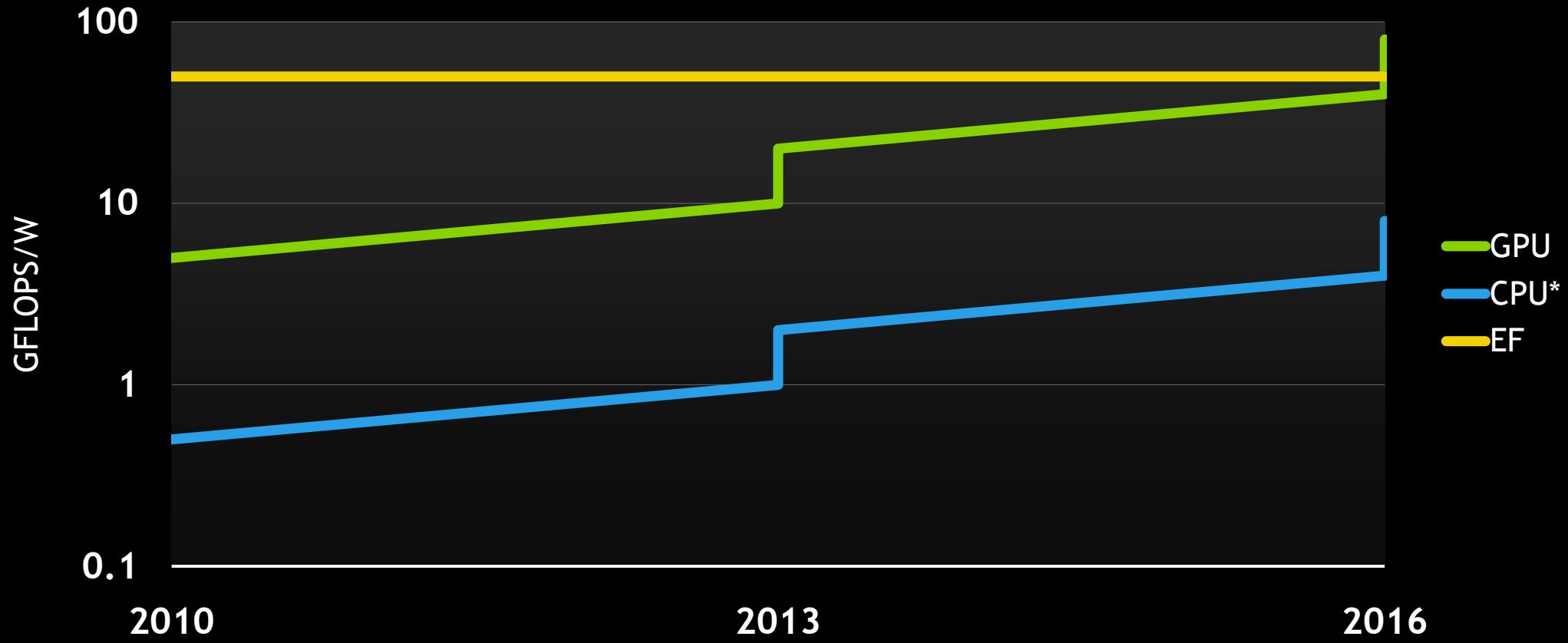


GPUs Close the Gap with Process and Architecture



GPUs Close the Gap With CPUs, a Gap Remains





GPUs Close the Gap
With CPUs, a Gap Remains

Heterogeneous Computing
is Required to get to ExaScale

Echelon

NVIDIA's Extreme-Scale Computing Project

Echelon Team



NVIDIA®



Penn

CRAY



Micron®

THE UNIVERSITY OF
TEXAS
AT AUSTIN™

THE UNIVERSITY OF
TENNESSEE **UT**

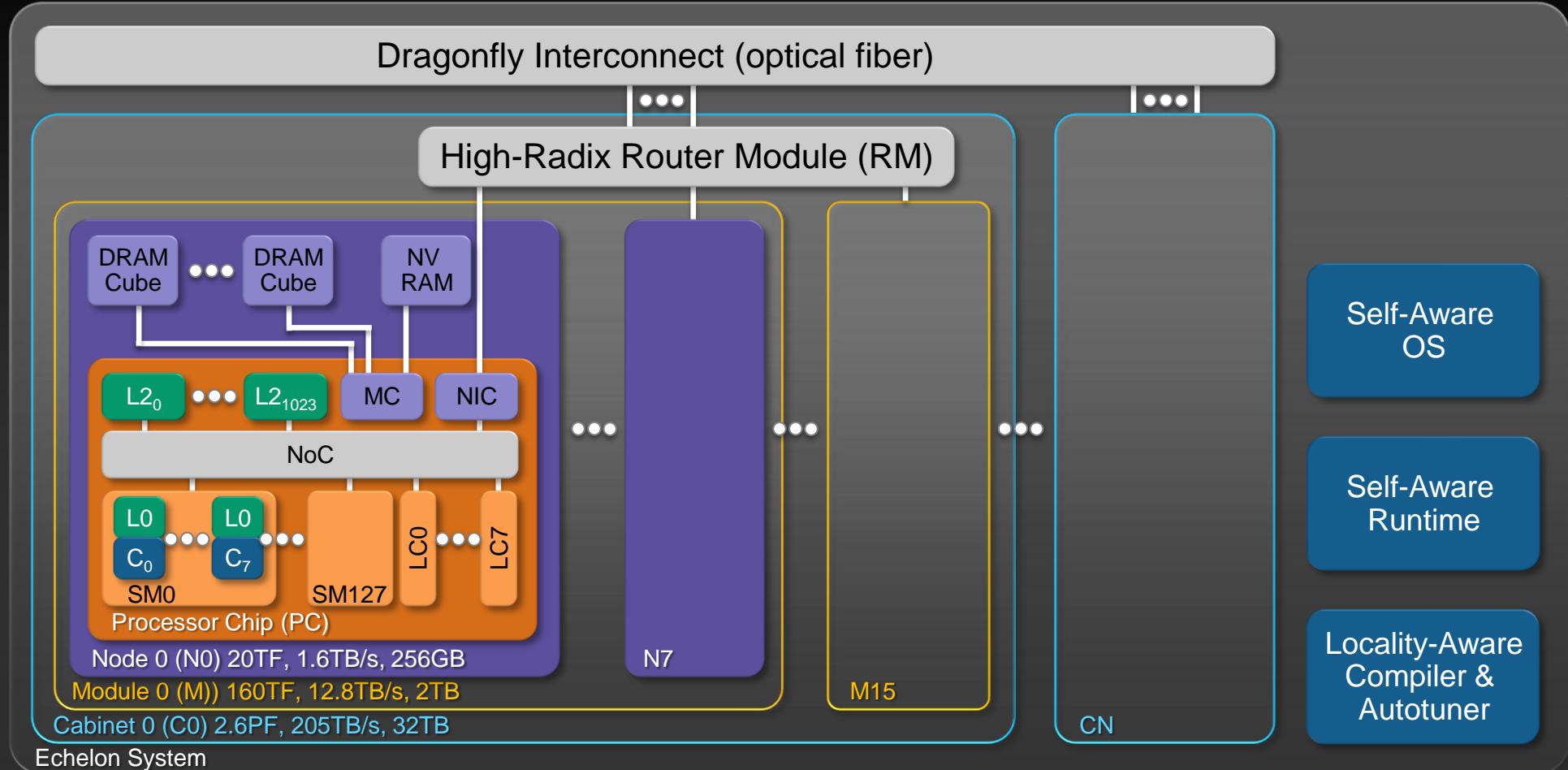
Georgia Institute
of Technology



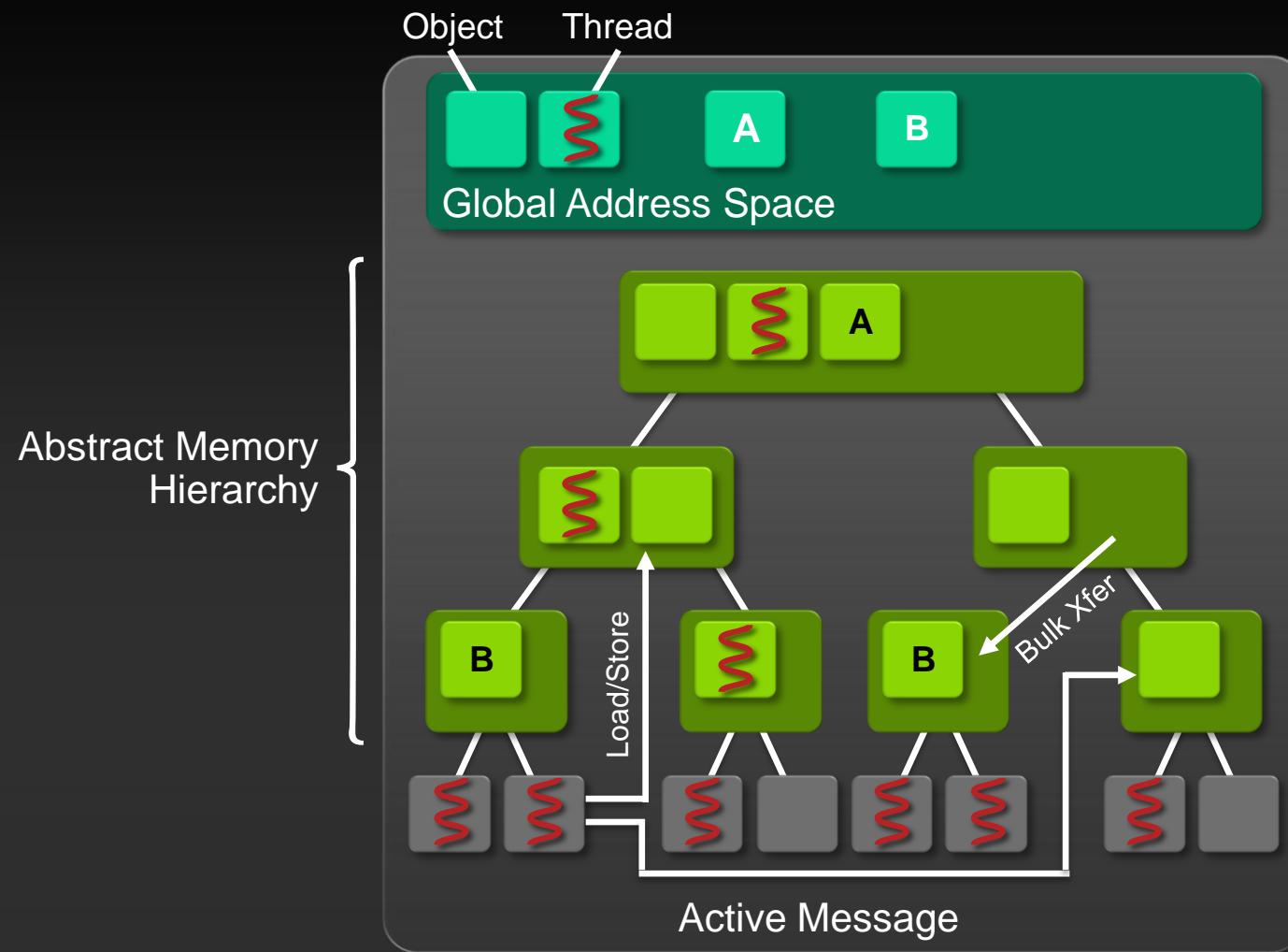
LOCKHEED MARTIN



System Sketch

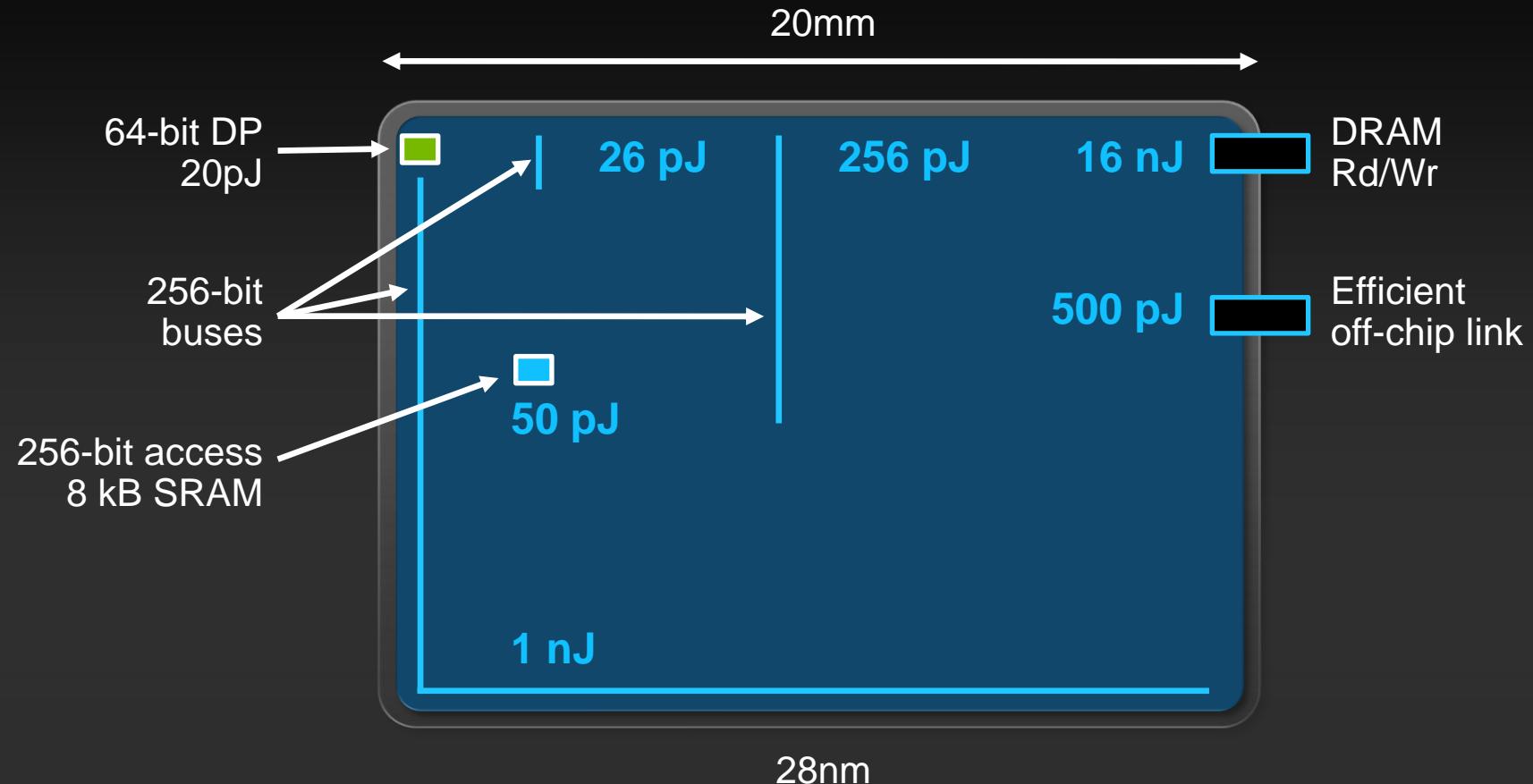


Execution Model



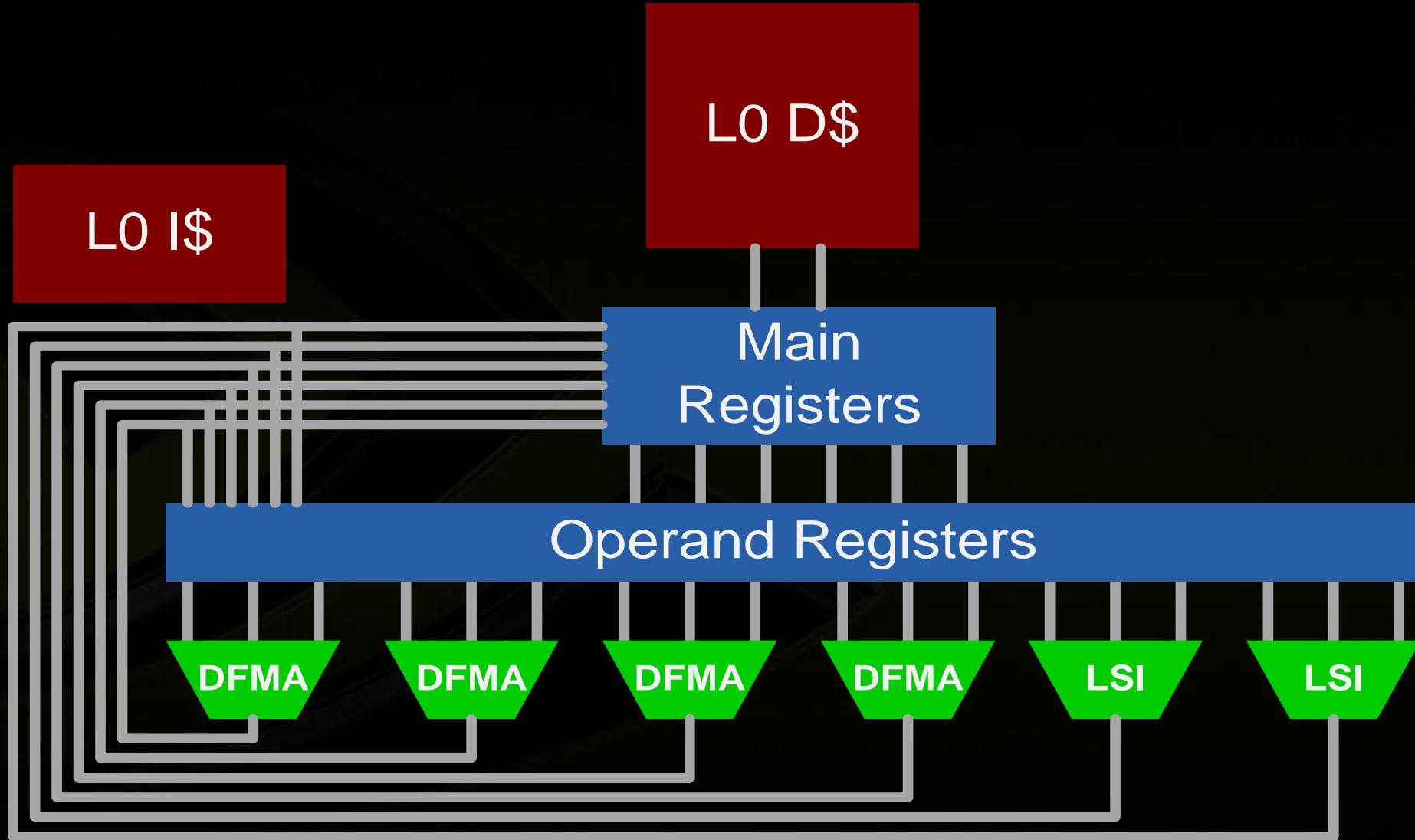
The High Cost of Data Movement

Fetching operands costs more than computing on them

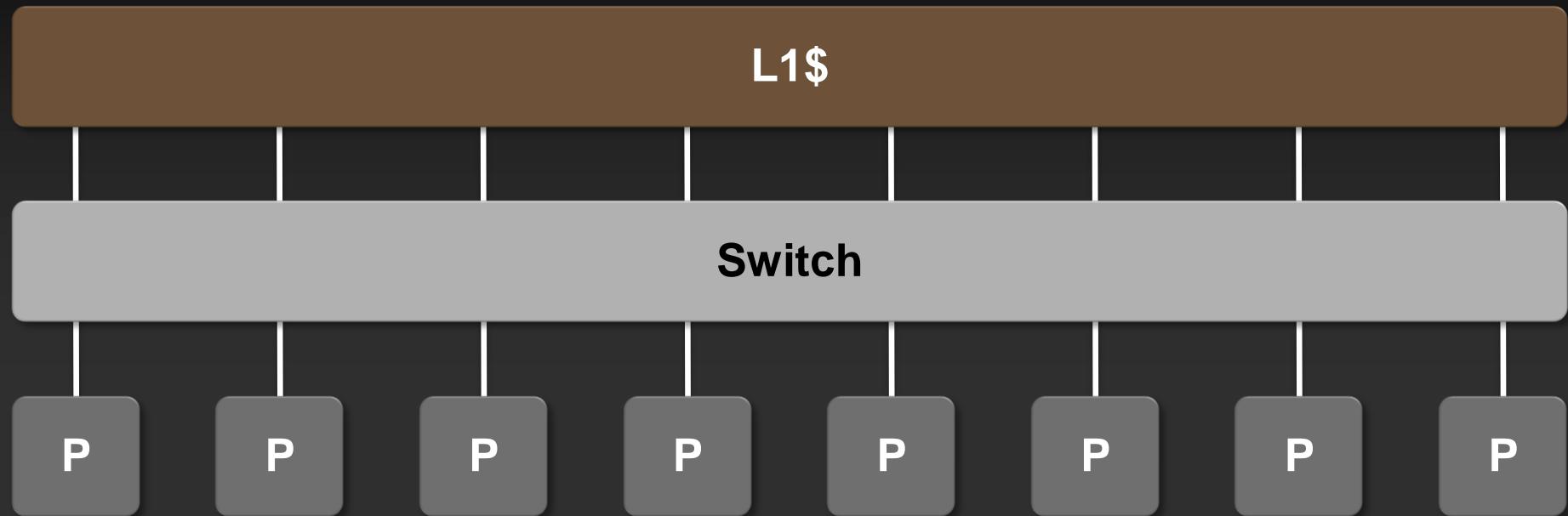


An NVIDIA ExaScale Machine

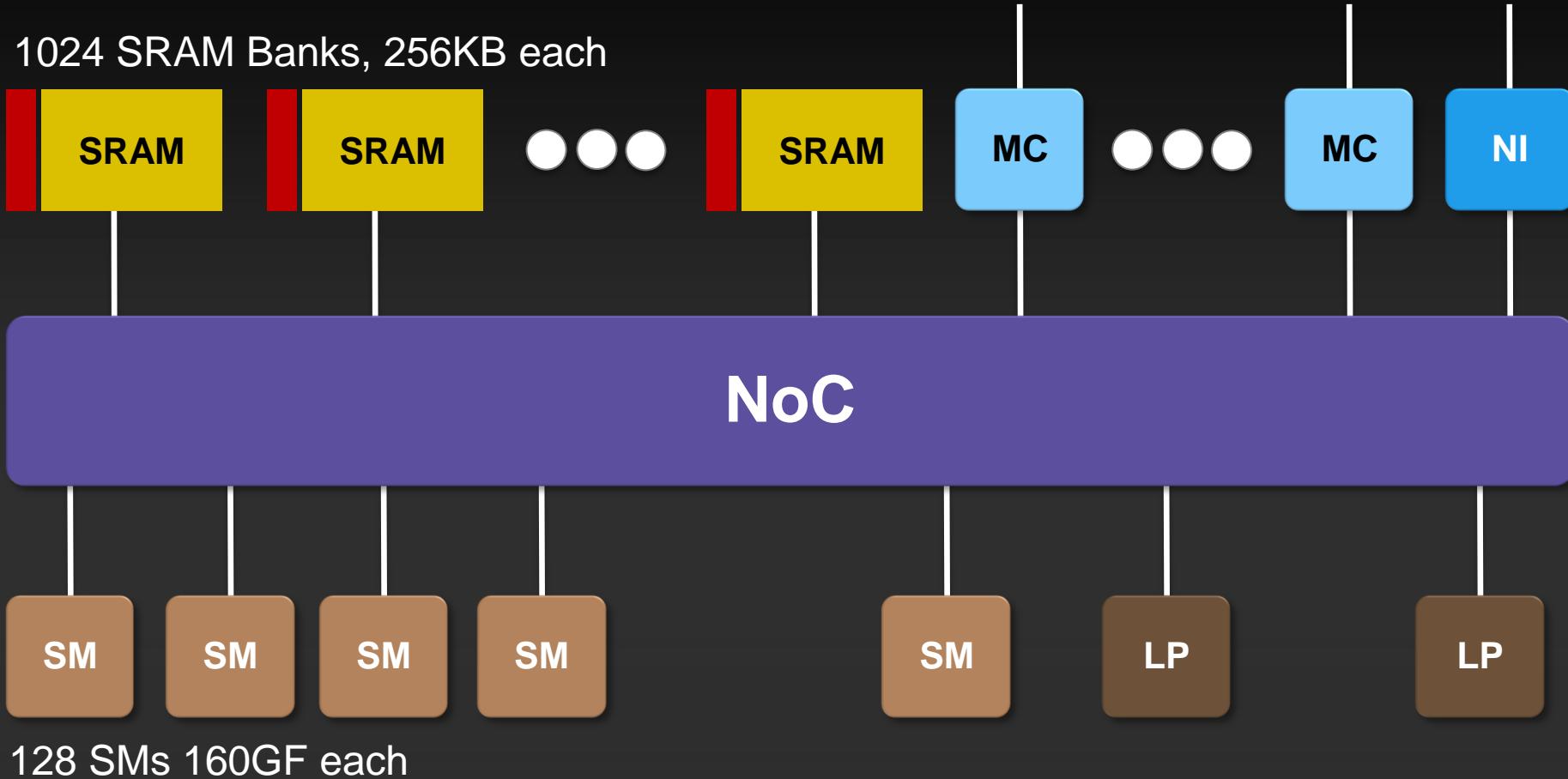
Lane – 4 DFMAs, 20GFLOPS



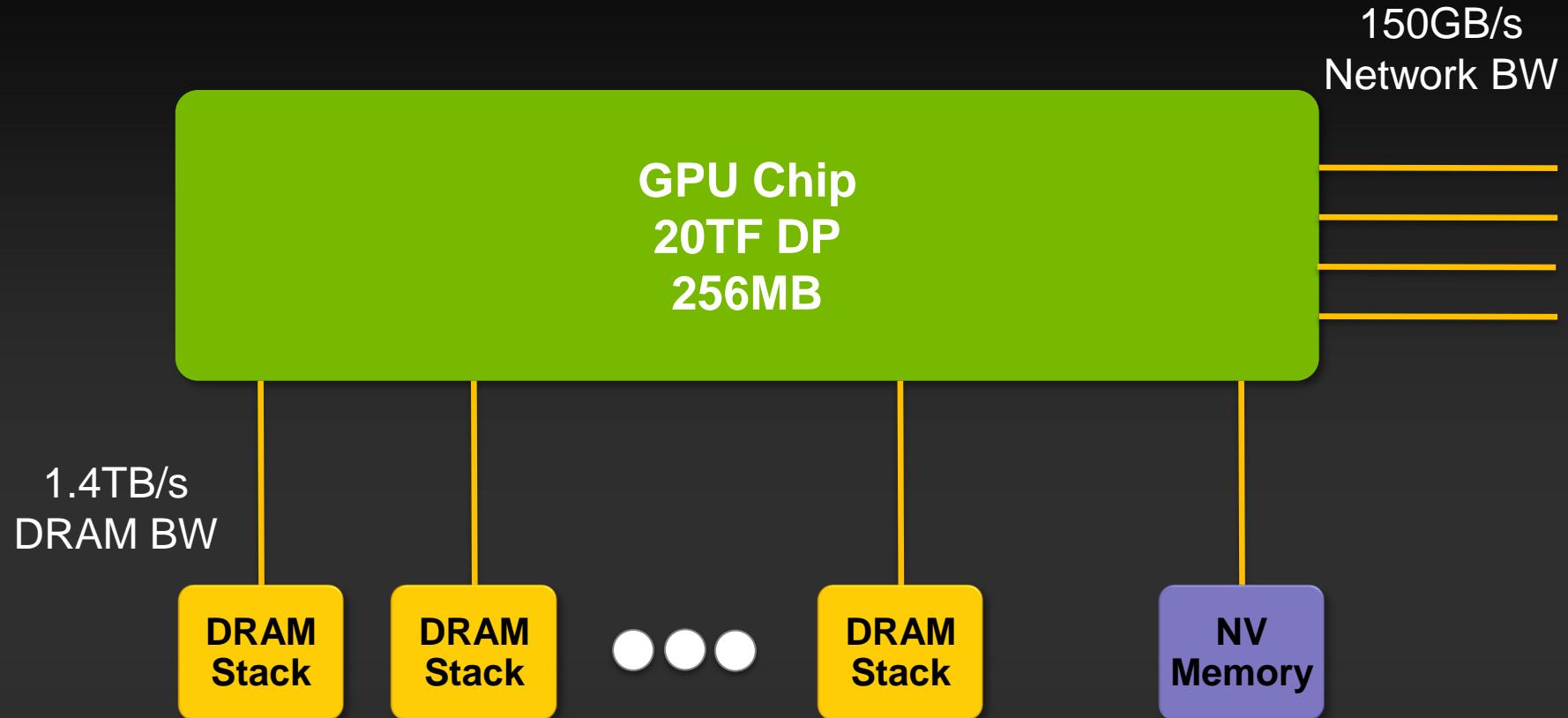
SM – 8 lanes – 160GFLOPS



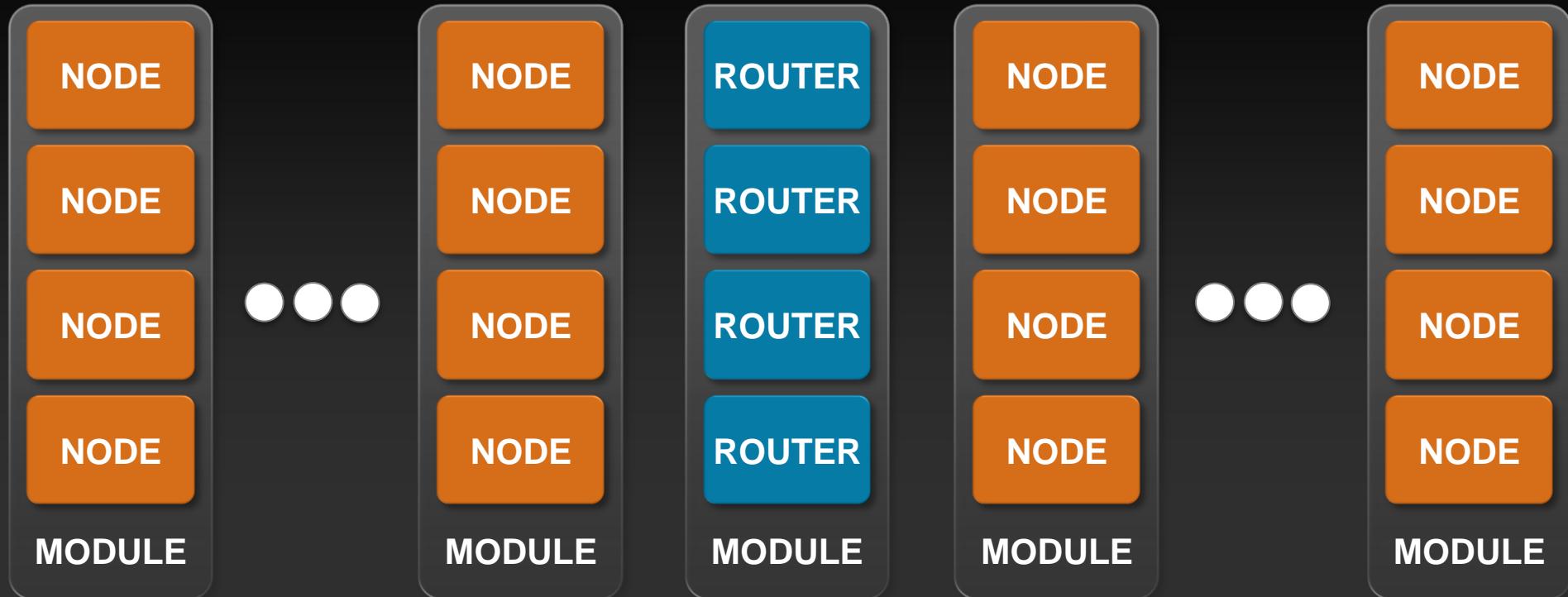
Chip – 128 SMs – 20.48 TFLOPS + 8 Latency Processors



Node MCM – 20TF + 256GB



Cabinet – 128 Nodes – 2.56PF – 38 kW



32 Modules, 4 Nodes/Module,
Central Router Module(s), Dragonfly Interconnect

System – to ExaScale and Beyond



Dragonfly Interconnect
400 Cabinets is ~1EF and ~15MW



CONCLUSION



GPU Computing is the Future

1

GPU Computing is #1 Today

On Top 500 AND Dominant on Green 500

2

GPU Computing Enables ExaScale

At Reasonable Power

3

The GPU is the Computer

A general purpose computing engine, not just an accelerator

4

The Real Challenge is Software



THANK YOU

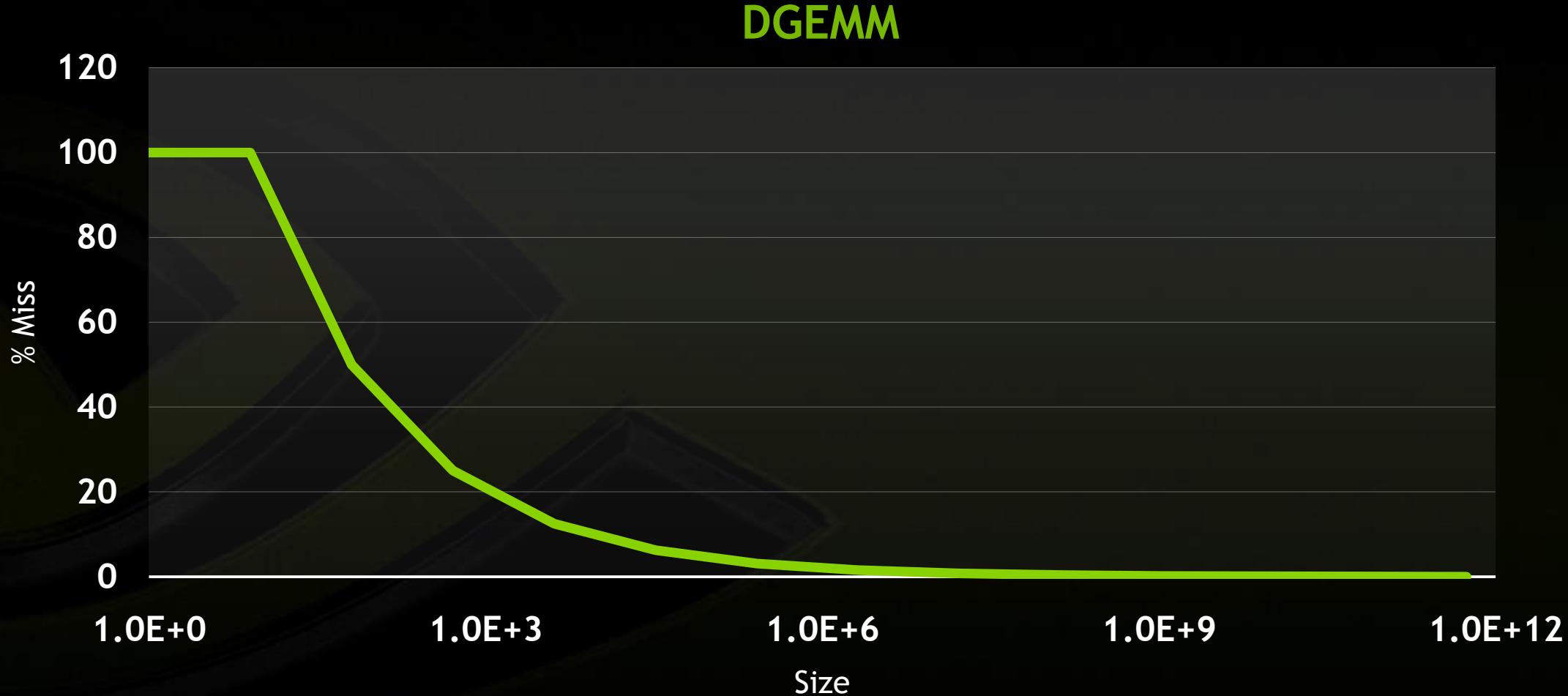




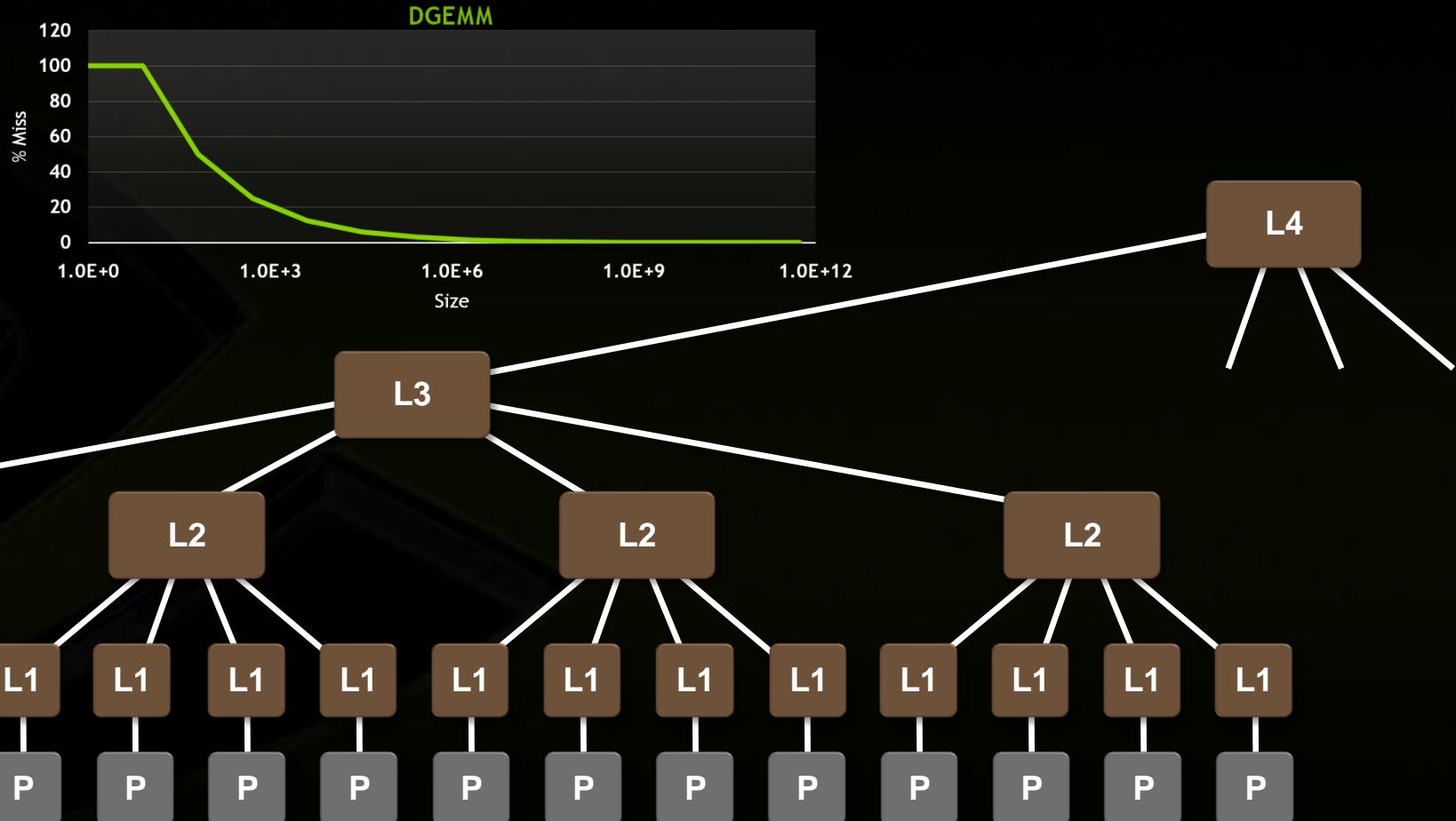
Power is THE Problem

- 1 Data Movement Dominates Power
- 2 Optimize the Storage Hierarchy
- 3 Tailor Memory to the Application

Some Applications Have Hierarchical Re-Use

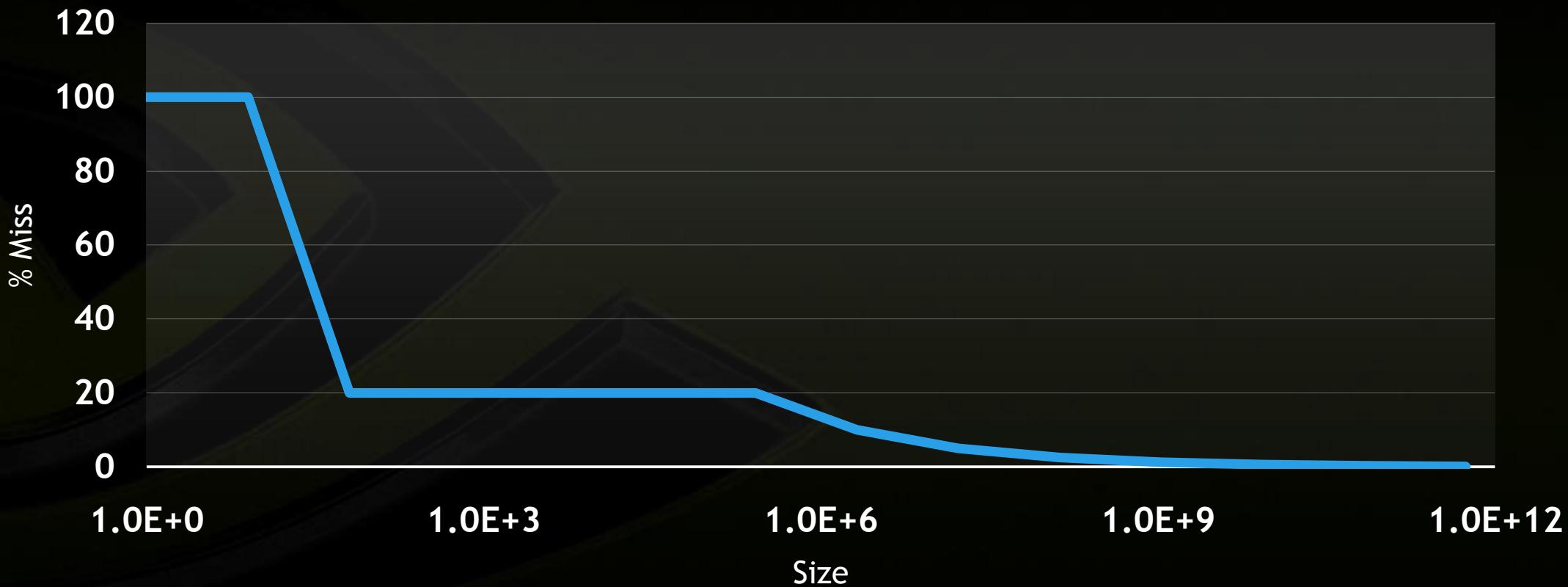


Applications with Hierarchical Reuse Want a Deep Storage Hierarchy

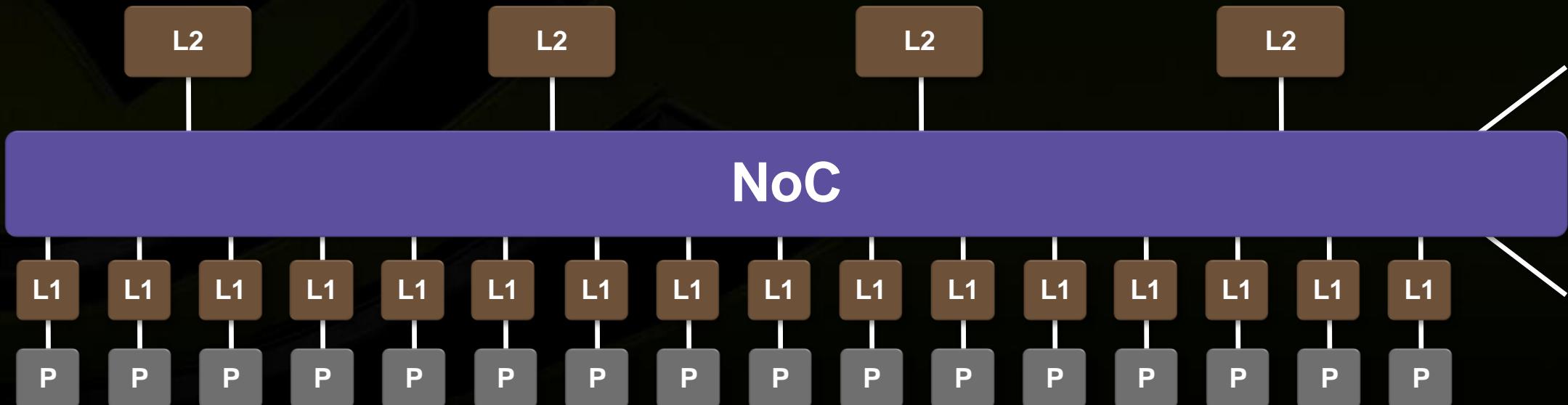
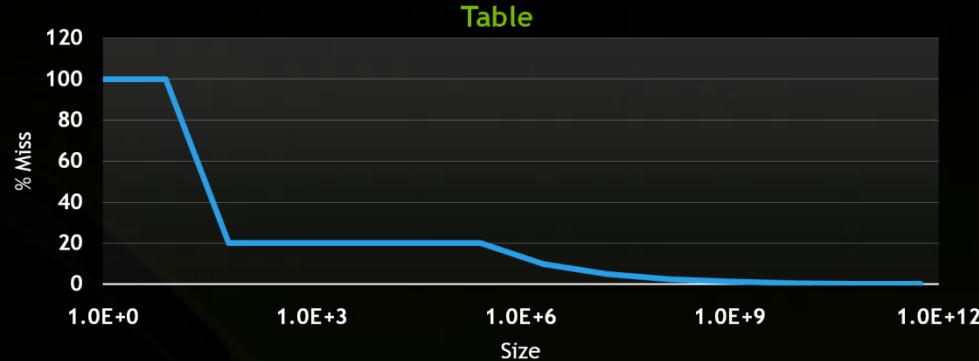


Some Applications Have Plateaus in Their Working Sets

Table

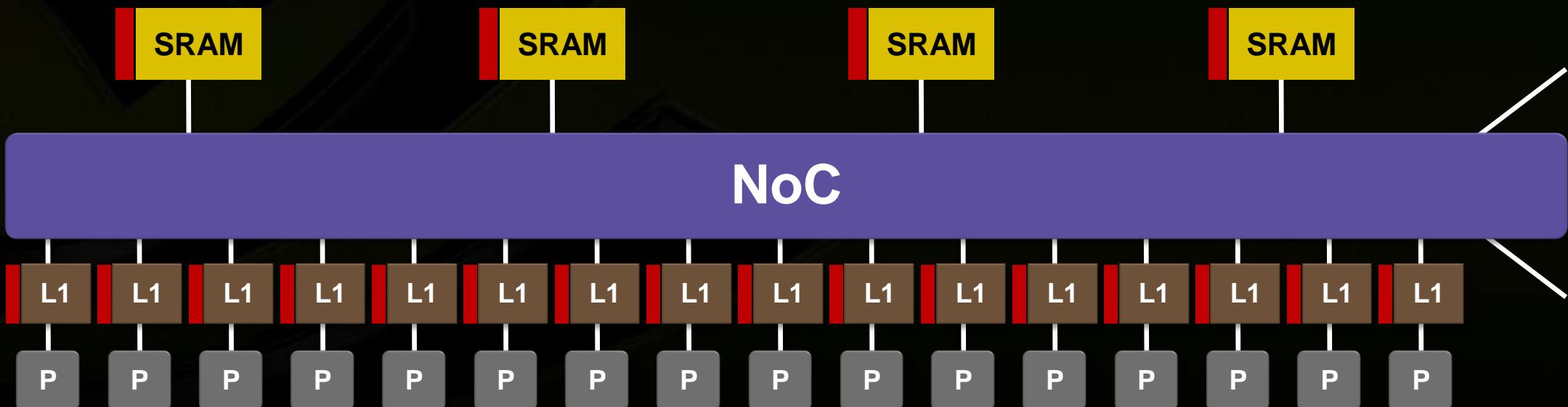


Applications with Plateaus Want a Shallow Storage Hierarchy



Configurable Memory Can Do Both At the Same Time

- Flat hierarchy for large working sets
- Deep hierarchy for reuse
- “Shared” memory for explicit management
- Cache memory for unpredictable sharing



Configurable Memory Reduces Distance and Energy

