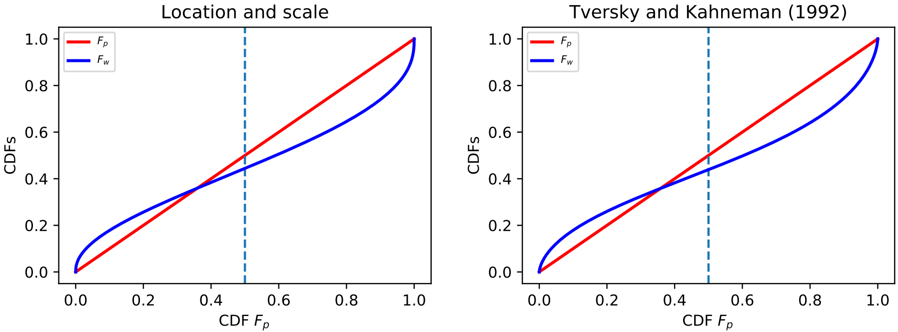
June 13, 2020

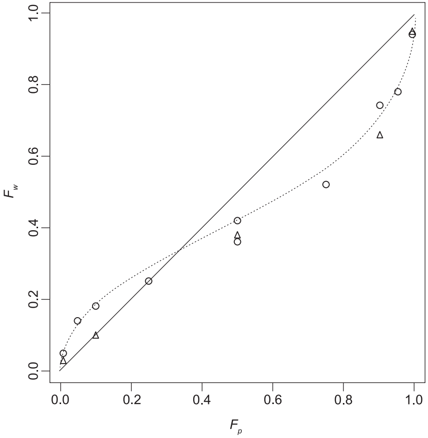
Main results



1. generic inverse-S shape can be explained by difference in uncertainty
2. process of estimation of this uncertainty generates inverse-S shape

▸ PW K&T 1979

Defining Probability Weighting (PW)



(TverskyKahneman1992)

- overestimation of rare events $\rightarrow$ underestimation of common events
- stable empirical pattern: inverse-S shape

Received wisdom:

- PW = maladaptive irrational cognitive bias

In search of a mechanism

$\hookrightarrow$ How does this pattern emerge?

$\hookrightarrow$ Can we derive the functional form (rather than merely fitting some function)?

Set up : A Thought Experiment

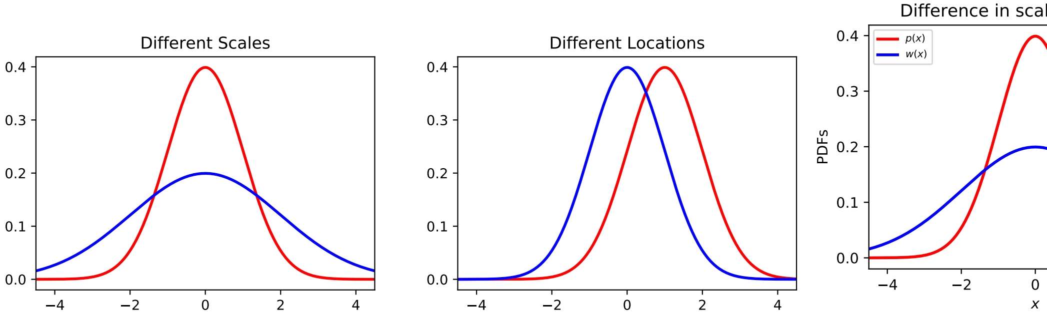
Disinterested Observer (DO)

DO has a model of the random variable X, *e.g.* payout of a gamble
probabilities $p(x)$
CDF $F_p(x)$

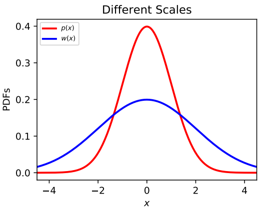
Decision Maker (DM)

DM has a different model of the same random variable X with greater uncertainty
decision weights $w(x)$
CDF $F_w(x)$

Types of Different Uncertainties



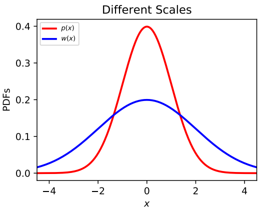
The Simplest Case : Different Scales



Numerical procedure applies to arbitrary distributions:

1. construct a list of values for the CDF assumed by the DO, $F_p(x)$
2. construct a list of values for the CDF assumed by the DM, $F_w(x)$
3. plot $F_w(x)$ *vs.* $F_p(x)$

The Simplest Case : Different Scales



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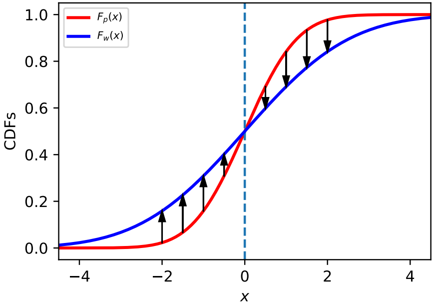
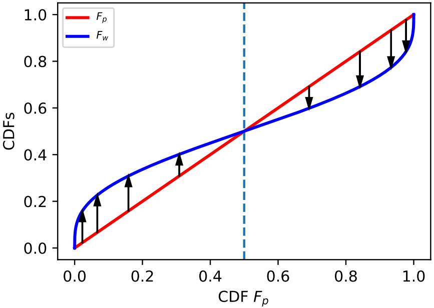
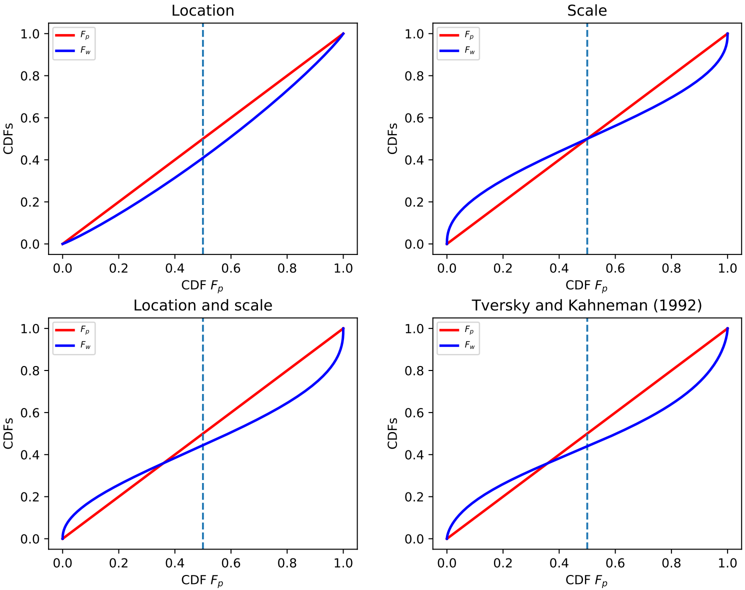




Applying the Procedure to the Uncertainty Types

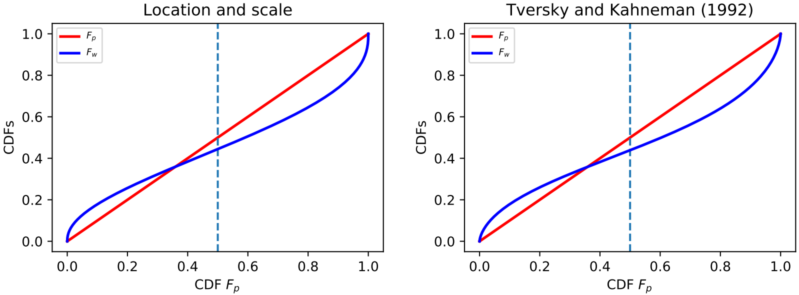


Interim conclusion

- greater scale reproduces inverse-S shape
- differences in location and scale reproduce asymmetric inverse-S shape
- inverse-S shape arises for all unimodal distributions
- Probability Weighting is the effect of a difference in uncertainty

Job done. Thank you for your attention ;)

Functional Forms



Asking the Ergodicity Question

DO's concern		**DM's concern**
What happens on average to the ensemble of subjects?	$\neq$	What happens to me on average over finite time?

Extra Uncertainty is Part of DM's Inference Problem I

DM's adaptive rationality: err on the side of caution:

- DM has no control over the experiment,
- DM's incomplete comprehension of the experiment/decision problem,
- DM needs to trust the DO
- uncertain outcome is consequential only to the DM,
- ...

Extra Uncertainty is Part of DM's Inference Problem II

- "probability" is polysemous (**Gigerenzer1991**; **Gigerenzer2018**; **HertwigGigerenzer1999**)
- probabilities are not observable, but
- DM observes counts of (rare) events along his life trajectory through time

$\hookrightarrow$ **DM's inference problem:** estimate probability $p(x)$ from counts

Main Result
Probability Weighting
Ergodicity Question
Estimation
Conclusion

Nature of Inference for Rare Events

Rare Event

- $p(x) = 0.0001$
- 10000 observations
- $\sim$ 99.5% of such time series will contain 0 or 1 events
- Naïve estimation: $\hat{p}(x) = 0$ or $\hat{p}(x) = 0.0001$

$\hookrightarrow$ either impossible or ten times (over)estimation

Common Event

- $p(x) = 0.1$
- 10000 observations
- $\sim$ 99.5% of time series would contain between 50 and 150 events,

$\hookrightarrow$ much smaller relative error in $\hat{p}(x)$

$\hookrightarrow$ the smaller $p(x)$ the smaller the count of it in a finite time series
$\hookrightarrow$ the bigger the relative estimation error

Relative Estimation Error is Larger for Rarer Events

Asymptotic probability	Most likely count	Standard error in count	Standard error in probability	Relative error in probability
0.1	1000	32	0.003	3%
0.01	100	10	0.001	10%
0.001	10	3	0.0003	30%
0.0001	1	1	0.0001	100%

Table: $T = 10\,000$, assuming Poisson statistics, relative estimation errors $\sim {}^{1}/_{\sqrt{\text{count}}}$

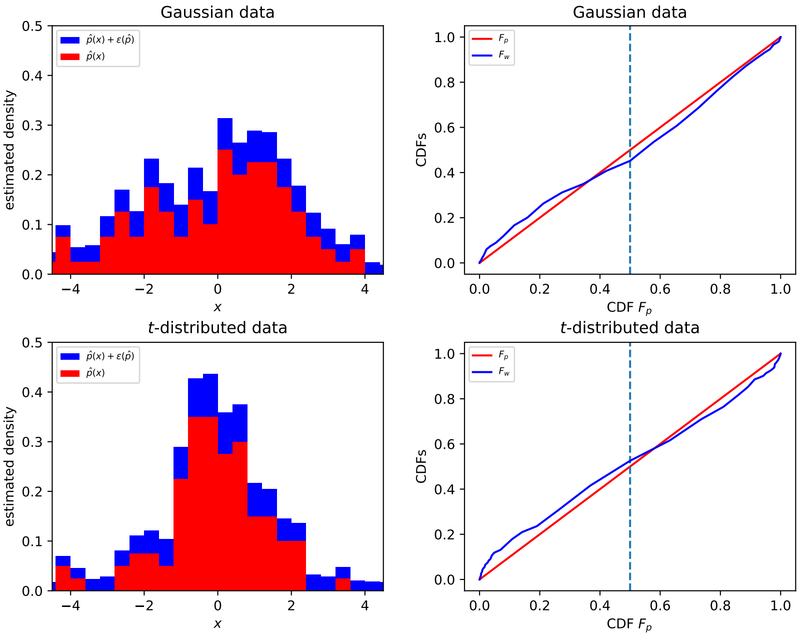
Estimation of the decision weights

Using the count $n(x)$ to form the best estimate and add to it the uncertainty about best estimate

$$w(x) \approx \frac{n(x)}{T\delta x} \pm \frac{\sqrt{n(x)}}{T\delta x} \tag{1}$$
$$w(x) \approx \hat{p}(x) \pm \varepsilon\left[\hat{p}(x)\right] \tag{2}$$

with the standard error expressed in terms of the estimate itself

$$\varepsilon\left[\hat{p}(x)\right] \equiv \frac{\sqrt{n(x)}}{T\delta x} = \sqrt{\frac{\hat{p}(x)}{T\delta x}} \tag{3}$$
$$\lim_{T\to\infty} w(x) \to p(x) \tag{4}$$


Gaussian data
estimated density
$\hat{p}(x) + \varepsilon(\hat{p})$
$\hat{p}(x)$
x
Gaussian data
CDFs
F_p
F_w
CDF F_p
t-distributed data
estimated density
$\hat{p}(x) + \varepsilon(\hat{p})$
$\hat{p}(x)$
x
t-distributed data
CDFs
F_p
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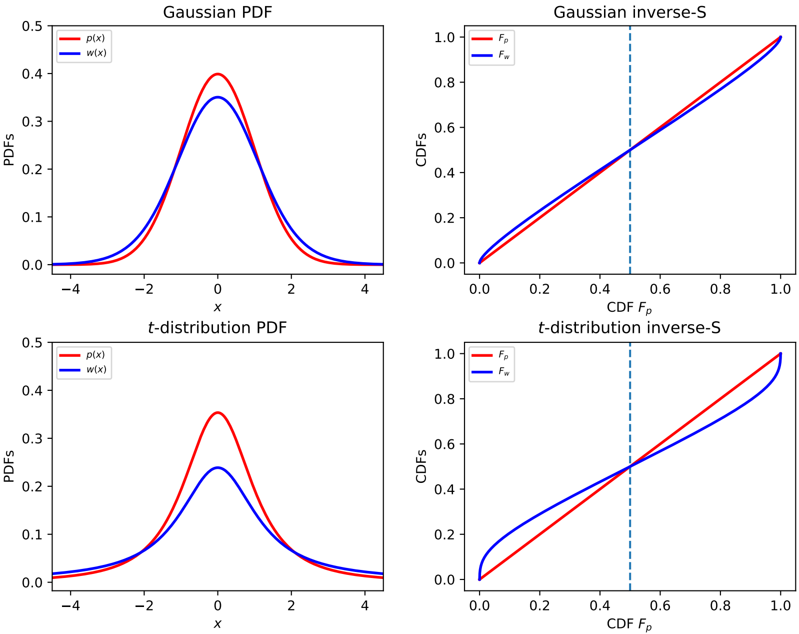
CDF F_p


Gaussian PDF
PDFs
x
$p(x)$
$w(x)$
Gaussian inverse-S
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F_w
t-distribution PDF
PDFs
x
$p(x)$
$w(x)$
t-distribution inverse-S
CDFs
CDF F_p
F_p
F_w

Conclusion

Ergodicity Economics explains probability weighting

- inverse-S shape as a neutral indicator of a difference in opinion
- reported observations are consistent with DM's extra uncertainty
- relative uncertainty arises out of the situation of the DM over time
- reproduce the right type of uncertainty, *i.e.* relative errors are larger for rare events

$\hookrightarrow$ Probability weighting is rational cautious behaviour under uncertainty over time

- See full paper at `bit.ly/lml-pw-r1`
- links to play with the code are inside

Thank you for your attention!

I'm looking forward to the discussion
Comments & questions are very welcome, here or to

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Submit an open peer review to this paper on
bit.ly/lml-pw-r1

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BACK UP

Probability Weighting as an Estimation Issue

"It is important to distinguish overweighting, which refers to a property of decision weights, from the overestimation that is commonly found in the assessment of the probability of rare events. [...] In many real-life situations, overestimation and overweighting may both operate to increase the impact of rare events." (**KahnemanTversky1979**)

$\hookrightarrow$ distinguish between

- uncertainty estimation and
- "weighting"

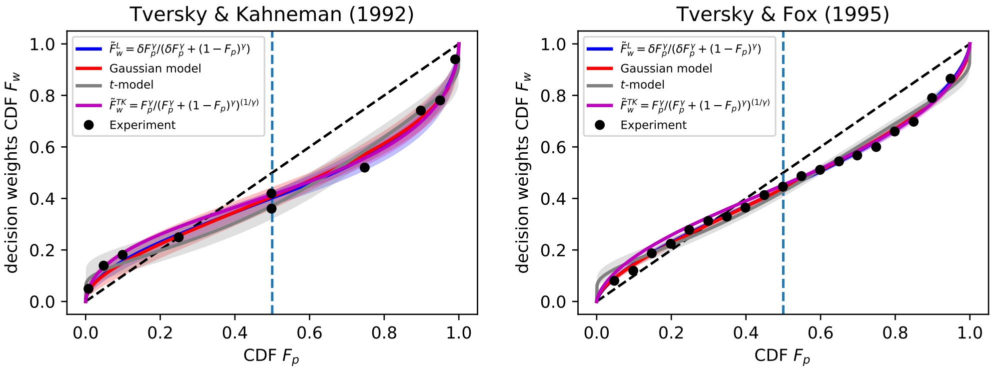
we analyse the former and find very good agreement with the empirical inverse-S pattern

$\hookrightarrow$ How big is the residual "probability weighting" after accounting for uncertainty estimation?

Main Results

Back Up

Estimation Error Explains 99% of Probability Weighting



- similar fits of Gaussian & t-distributed model

$\hookrightarrow$ How big is the residual "probability weighting" after accounting for estimation errors?

◂ Main Results

Functional Forms

Gaussian

TverskyKahneman1992

$$\tilde{F}_w^{TK}\left(F_p;\gamma\right) = \left(F_p\right)^{\gamma} \frac{1}{\left[\left(F_p\right)^{\gamma} + \left(1 - F_p\right)^{\gamma}\right]^{1/\gamma}} \tag{5}$$

LattimoreBakerWitte1992

$$\tilde{F}_w^{L}\left(F_p;\delta,\gamma\right) = \frac{\delta F_p^{\gamma}}{\delta F_p^{\gamma} + \left(1 - F_p\right)^{\gamma}} \tag{6}$$

We derive decision weight as a function of probability with $(\alpha\sigma)^2$ as the DM's scale

$$w(p) = p^{\frac{1}{\alpha^2}} \frac{\left(2\pi\sigma^2\right)^{\frac{1-\alpha^2}{2\alpha^2}}}{\alpha}\ , \tag{7}$$

which is a power law in p with a pre-factor to ensure normalisation

Linking Probability Weighting to Relative Uncertainties

Decision weight w is the normalised sum of the probability $p(x)$ and its uncertainty $\varepsilon\left[p(x)\right]$

$$w(x) = \frac{p(x) + \varepsilon\left[p(x)\right]}{\int_{-\infty}^{\infty}\Big(p(s) + \varepsilon\left[p(s)\right]\Big)\, ds} \, . \tag{8}$$

This can be expressed as

$$w(x) = p(x)\left(\frac{1 + \frac{\varepsilon[p(x)]}{p(x)}}{\int_{-\infty}^{\infty} p(s)\left\{1 + \frac{\varepsilon[p(s)]}{p(s)}\right\} ds}\right) \, , \tag{9}$$

where $\frac{\varepsilon[p(x)]}{p(x)}$ is the relative error, which is large (small) for small (large) probabilities

In the long-time limit $w(x) \to p(x)$

References I