What are we weighting for?

A mechanistic model for probability weighting

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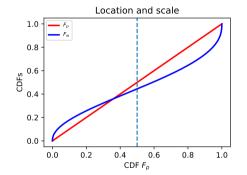


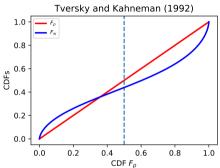
Main Resul

Ergodicity

Estimatio

Conclusion





XXX label on left figure: change to "Ergodicity economics" to mirror K&T?

- inverse-S shape can be explained by difference in uncertainty
- 2 cautious estimation of probabilities generates such differences





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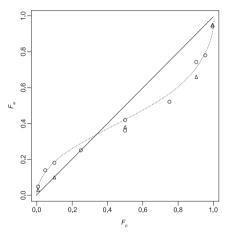
Main Result

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Definition of Probability Weighting (PW)



(Tversky and Kahneman 1992, p. 310, Fig. 1, relabelled axes)

- low probabilities treated as higher;
 high probabilities treated as lower
- stable empirical pattern: inverse-S shape

Received wisdom:

 PW = maladaptive irrational cognitive bias

In search of a mechanism

- \hookrightarrow How does this pattern emerge?





Main Resu

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Task: model payout, x, of a gamble as a random variable.

Disinterested Observer (DO)



DO assigns probabilities p(x)CDF $F_p(x)$

Decision Maker (DM)

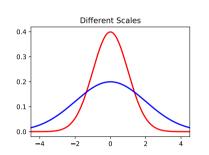


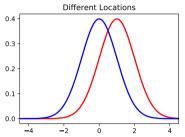
DM assigns different probabilities w(x) (decision weights) CDF $F_w(x)$

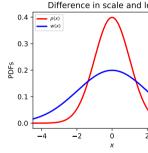


Possible model differences

Locations, Scales, Shapes







XXX produce figure with Gaussian and Student-t with heavy tails to illustrate shape difference

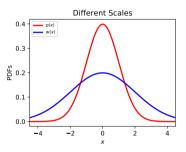


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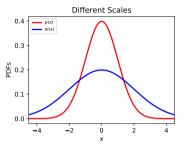
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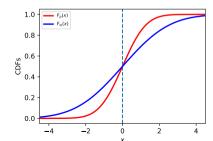
Probability

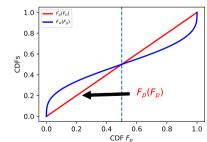
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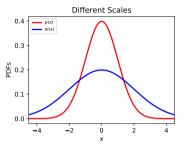


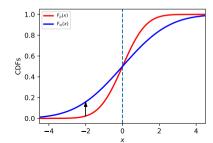


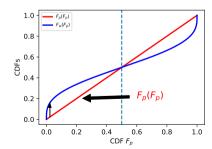
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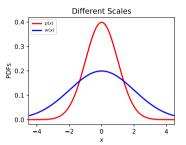
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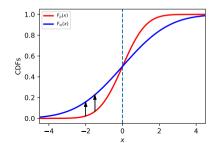
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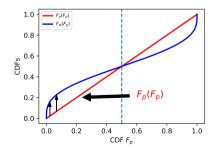
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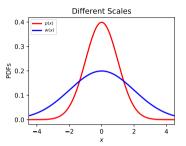
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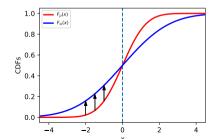
Probability Weighting

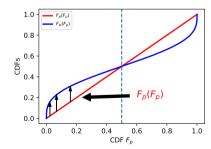
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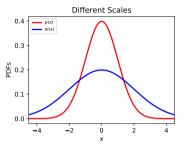
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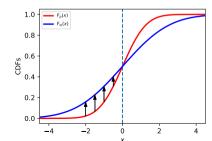
Probability

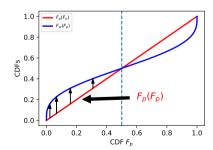
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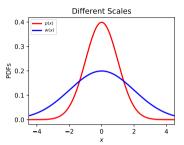


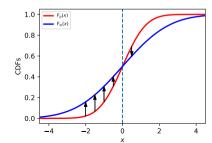


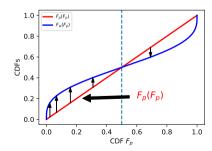
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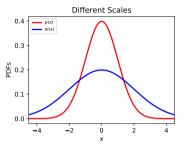


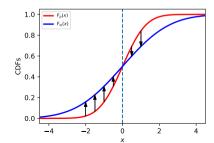


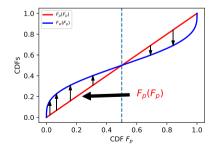
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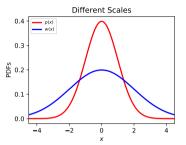


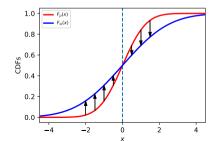


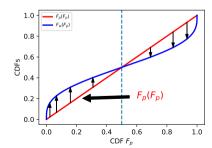
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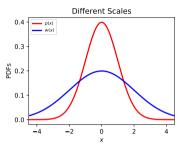


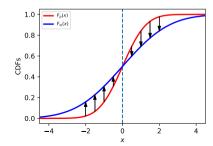


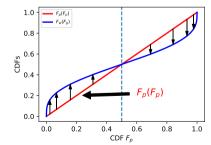
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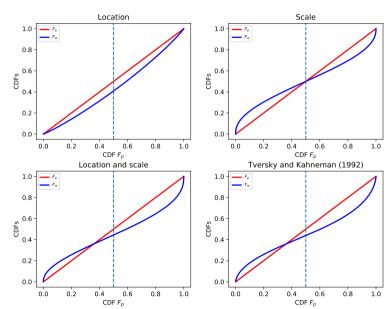


Ergodicity

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Asymmetry from different locations





Ergodicity Question

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Numerically easy for any pair of distributions (models):

- 1 list values of DO's CDF, $F_p(x)$, at set x_i
- 2 list values of DM's CDF, $F_w(x)$, at same x_i
- 3 plot $F_w(x)$ vs. $F_p(x)$

XXX illustrate with corresponding lists and figure



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Main Resu

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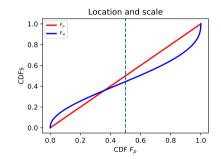
Estimation

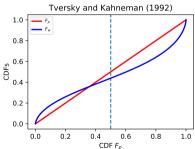
Interim conclusion

- DM's greater scale gives inverse-S shape (unimodal distributions)
- difference in locations gives asymmetry
- reproduces observations of probability weighting

Job done. Thank you for your attention;)

▶ Functional Forms







The Ergodicity Question

Probability

vveighting

Question

Estimatio

Conclusi

Typical DO concern

What happens on average to the ensemble of subjects?



Typical DM concern

What happens to me on average over time?



Why DM's greater scale?

Main Resul

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Estimatio

. . .

- DM has no control over experiment
- experiment may be unclear to DM
- DM may not trust DO
- . .



Experiencing probabilities

- Ergodicity Question
- Estimatio
- . . .

- probabilities are not observable
- probabilities encountered as
 - known frequency in ensemble of experiments (DO)
 - frequencies estimated over time (DM)
- → estimates have uncertainties cautious DM accounts for these

Rare Event

- p(x) = 0.0001
- 10 000 observations
- \sim 99.5% of such time series will contain 0 or 1 events
- Naïve estimation: $\hat{p}(x) = 0$ or $\hat{p}(x) = 0.0001$

Common Event

- p(x) = 0.1
- 10 000 observations
- \sim 99.5% of time series would contain between 50 and 150 events,
- Naïve estimation: $0.05 < \hat{p}(x) < 0.15$
- \hookrightarrow only $\approx 50\%$ error in $\hat{p}(x)$

 \hookrightarrow small p(x), small count \hookrightarrow small count, big uncertainty



Relative estimation error is large for rare events

Asymptotic probability	Most likely count	Standard error in count	Standard error in probability	Relative error in probability
0.1 0.01 0.001 0.0001	1000 100 10	32 10 3	0.003 0.001 0.0003 0.0001	3% 10% 30% 100%

Table: $T=10\,000$, assuming Poisson statistics, relative estimation errors $\sim 1/\sqrt{count}$

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DMs don't like surprises

To avoid surprises, let's say DMs add estimation uncertainty $\varepsilon [p(x)]$ to every estimated probability, then normalize, s.t.

$$w(x) = \frac{p(x) + \varepsilon[p(x)]}{\int (p(s) + \varepsilon[p(s)]) ds}$$

This allows us to derive a functional form, e.g. for the Gaussian case ... (find in manuscript)

...visually similar to function chosen by Kahneman and Tversky.

XXXNot sure we need much more. I'd just have one figure that gives a nice inverse S, for a Gaussian, say, based on estimation error.





Main Resul

Ergodicity Question

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Ergodicity Economics and probability weighting

- inverse-S shape appears as neutral indicator of a difference in opinion
- reported observations consistent with DM's extra uncertainty
- may arise from DM estimating probabilities over time
- → Probability weighting is rational cautious behaviour under uncertainty over time
 - Manuscript at https://www.researchers.one/article/2020-04-14
- Interactive code at https://bit.ly/lml-pw-code
 XXX researchers.one link is better: an opportunity to advertise R1 and explain it's
 open for public review.
 - XXX code link goes to wrong place best to link to binder for interactive notebook.



Reference

Thank you for your attention!

I'm looking forward to the discussion Comments & questions are very welcome, here or to

WE NEED YOU!



Submit an open peer review to this paper on bit.ly/lml-pw-r1





Back Up References

BACK UP



Back Up
References

Probability Weighting as an Estimation Issue

"It is important to distinguish overweighting, which refers to a property of decision weights, from the overestimation that is commonly found in the assessment of the probability of rare events. [...] In many real-life situations, overestimation and overweighting may both operate to increase the impact of rare events." (Kahneman and Tversky 1979, p. 281)

- - uncertainty estimation and
 - "weighting"

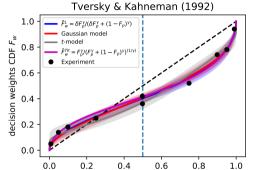
we analyse the former and find very good agreement with the empirical inverse-S pattern

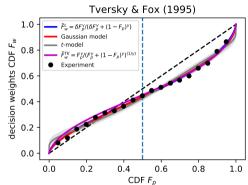
→ How big is the residual "probability weighting" after accounting for uncertainty estimation?





Estimation Error Explains 99% of Probability Weighting





• similar fits of Gaussian & t-distributed model

 $CDF F_{p}$

→ How big is the residual "probability weighting" after accounting for estimation errors?





Functional Forms Gaussian

Tversky and Kahneman (1992, $\gamma = 0.68$)

$$\tilde{F}_{w}^{TK}\left(F_{p};\gamma\right) = \left(F_{p}\right)^{\gamma} \frac{1}{\left[\left(F_{p}\right)^{\gamma} + \left(1 - F_{p}\right)^{\gamma}\right]^{1/\gamma}} \tag{1}$$

Lattimore, Baker, and Witte (1992)

$$\tilde{F}_{w}^{L}\left(F_{p};\delta,\gamma\right) = \frac{\delta F_{p}^{\gamma}}{\delta F_{p}^{\gamma} + \left(1 - F_{p}\right)^{\gamma}}\tag{2}$$

We derive decision weight as a function of probability with $(\alpha\sigma)^2$ as the DM's scale

$$w(p) = p^{\frac{1}{\alpha^2}} \frac{(2\pi\sigma^2)^{\frac{1-\alpha^2}{2\alpha^2}}}{\alpha} , \qquad (3)$$

which is a power law in p with a pre-factor to ensure normalisation

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Linking Probability Weighting to Relative Uncertainties

Decision weight w is the normalised sum of the probability p(x) and its uncertainty $\varepsilon[p(x)]$

$$w(x) = \frac{p(x) + \varepsilon \left[p(x) \right]}{\int_{-\infty}^{\infty} \left(p(s) + \varepsilon \left[p(s) \right] \right) ds} . \tag{4}$$

This can be expressed as

$$w(x) = p(x) \left(\frac{1 + \frac{\varepsilon[p(x)]}{p(x)}}{\int_{-\infty}^{\infty} p(s) \left\{ 1 + \frac{\varepsilon[p(s)]}{p(s)} \right\} ds} \right) , \qquad (5)$$

where $\frac{\varepsilon[p(x)]}{p(x)}$ is the relative error, which is large (small) for small (large) probabilities In the long-time limit $w(x) \to p(x)$

Reference





Back Up References







Lattimore, Pamela K., Joanna R. Baker, and A. Dryden Witte (1992). "Influence of Probability on Risky Choice: A Parametric Examination". *Journal of Economic Behavior and Organization* 17 (3), pp. 377–400. DOI:10.1016/S0167-2681(95)90015-2 (cit. on p. 30).



Tversky, Amos and Daniel Kahneman (1992). "Advances in Prospect Theory: Cumulative Representation of Uncertainty". *Journal of Risk and Uncertainty* 5 (4), pp. 297–323. DOI:10.1007/BF00122574 (cit. on pp. 3, 30).