

What are we weighting for?

A mechanistic model for probability weighting

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Main results

Main Results

Probability
Weighting

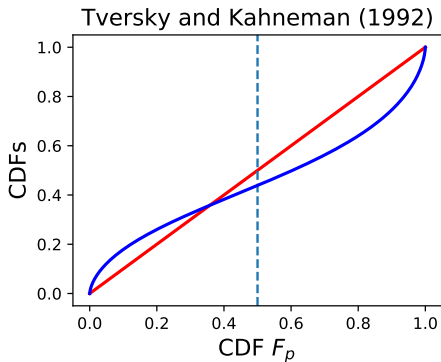
Setup

Functional Form

Ergodicity
Question

Estimation

Conclusion





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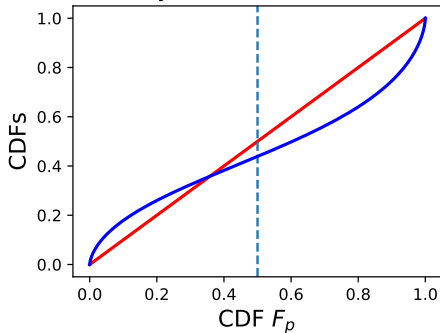
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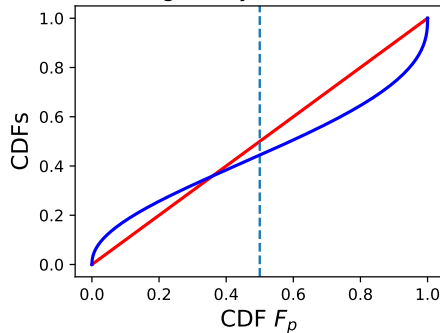
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Tversky and Kahneman (1992)



Ergodicity Economics





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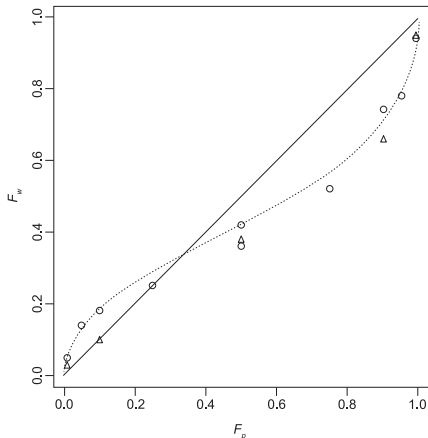
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Definition of Probability Weighting (PW)



(Tversky and Kahneman 1992, p. 310, Fig. 1, relabelled axes)

- empirical pattern: inverse-S shape
- Cumulative Prospect Theory (CPT)

Classical interpretation of PW:

- maladaptive irrational cognitive bias

In search of a mechanism

- ↪ How does this pattern emerge?
- ↪ Can we derive a functional form (rather than fit a function)?

Task: model payout, x , of a gamble as a random variable.

Disinterested Observer (DO)



DO assigns PDF $p(x)$
 \hookrightarrow CDF $F_p(x)$

Decision Maker (DM)



DM assigns different PDF $w(x)$
 \hookrightarrow CDF $F_w(x)$



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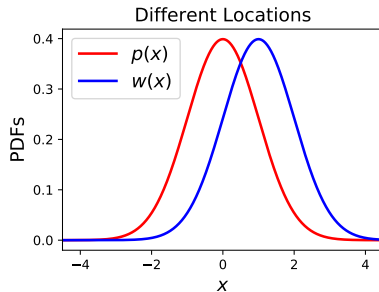
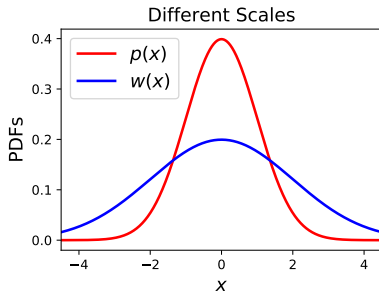
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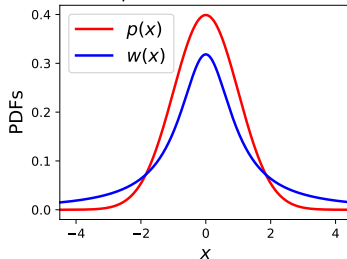
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Scales, Locations, Shapes



Different Shapes: Gaussian and t -distribution





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Thought Experiment: DM assumes greater scale

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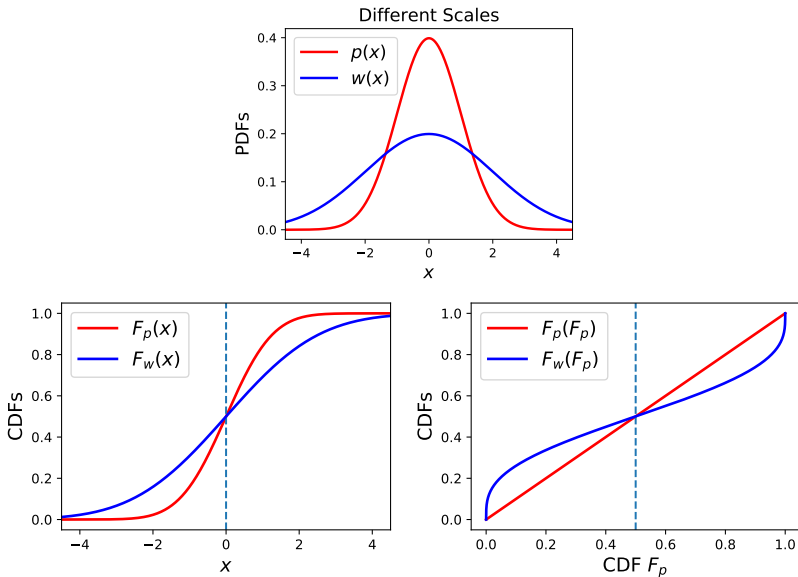
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Functional form of the weighting function

Gaussian case with different scale:

$$w(p) = p^{\frac{1}{\alpha^2}} \underbrace{\frac{(2\pi\sigma^2)^{\frac{1-\alpha^2}{2\alpha^2}}}{\alpha}}_{\text{normalisation factor}}, \quad (1)$$

where

- DO's scale is σ
- DM's scale is $\alpha\sigma$

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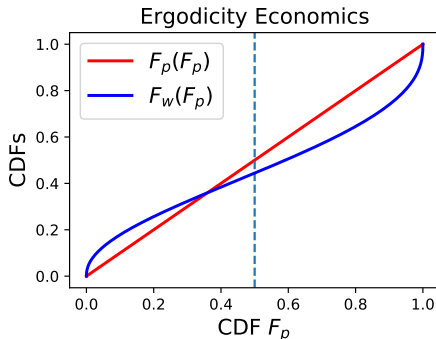
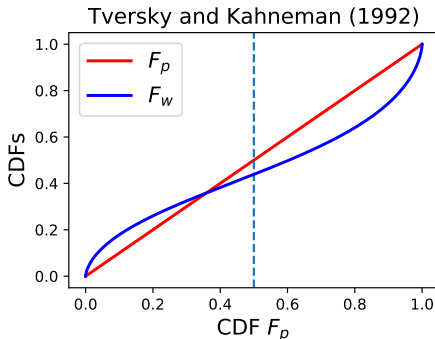
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Interim conclusion



- DM's greater scale gives inverse-S shape (unimodal distributions)
- difference in locations gives asymmetry
- reproduces observations of probability weighting

Job done. Thank you for your attention ;)



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The Ergodicity Question

Typical DO concern

What happens on average to
the **ensemble** of subjects?

\neq

Typical DM concern

What happens to me
on average over time?



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Why DM's greater scale?

- DM has no control over experiment
- experiment may be unclear to DM
- DM may not trust DO
- ...



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Experiencing probabilities

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- probabilities are not observable
 - probabilities encountered as
 - known frequencies in ensemble of experiments (DO)
 - frequencies estimated over time (DM)
- ↪ **estimates have uncertainties – cautious DM accounts for these**



Rare Event

- $p(x) = 0.001$
 - 100 observations
 - $\sim 99.5\%$ get 0 or 1 events
 - $\hat{p}(x) = 0$ or $\hat{p}(x) = 0.01$
- ↪ $\hat{p}(x)$ off by 1000%

Common Event

- $p(x) = 0.5$
 - 100 observations
 - $\sim 99.5\%$ get between 35 and 65 events,
 - $0.35 < \hat{p}(x) < 0.65$
- ↪ $\hat{p}(x)$ off by 30%

↪ small $p(x)$, small count \rightarrow big uncertainty



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DMs don't like surprises

To avoid surprises, DMs **add estimation uncertainty** $\varepsilon [p(x)]$ to every estimated probability, then normalize, s.t.

$$w(x) = \frac{p(x) + \varepsilon [p(x)]}{\int (p(s) + \varepsilon [p(s)]) ds} \quad (2)$$

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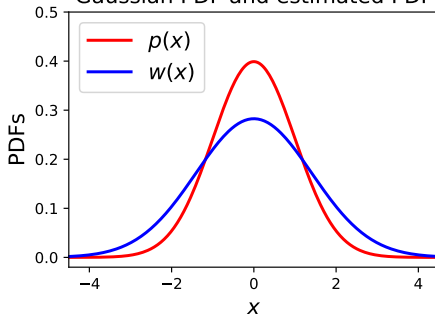
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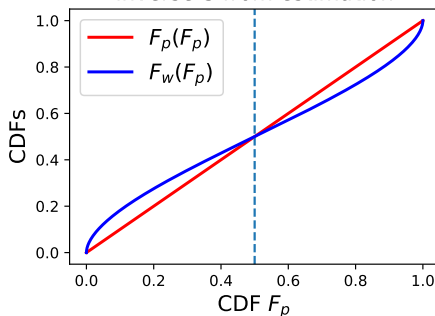
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Gaussian PDF and estimated PDF



inverse-S from estimation





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Classical interpretation of PW

- overestimation of low probability events
- underestimation of high probability events
- ↪ maladaptive irrational cognitive bias

Ergodicity Economics and PW

- inverse-S shape: neutral indicator of different models of the world
- reported observations consistent with DM's extra uncertainty
- may arise from DM estimating probabilities over time
- ↪ Probability weighting is rational cautious behaviour under uncertainty over time

- testable prediction → Let's run an experiment!
- Manuscript at <https://www.researchers.one/article/2020-04-14>
- Interactive code at <https://bit.ly/lml-pw-count-b>



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Probability Weighting as an Estimation Issue

“It is important to distinguish [overweighting](#), which refers to a property of decision weights, from the [overestimation](#) that is commonly found in the assessment of the probability of rare events. [...] In many real-life situations, overestimation and overweighting may both operate to increase the impact of rare events.” (Kahneman and Tversky [1979](#), p. 281)

↪ distinguish between

- uncertainty estimation and
- “weighting”

we analyse the former and find very good agreement with the empirical inverse-S pattern

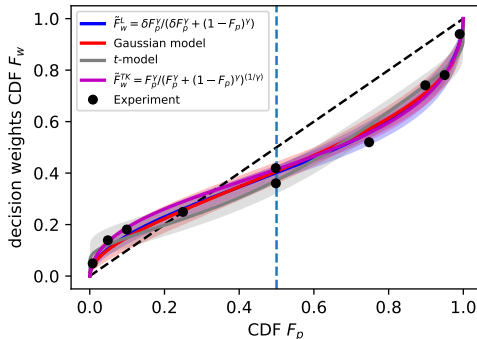
↪ How big is the residual “probability weighting” after accounting for uncertainty estimation?



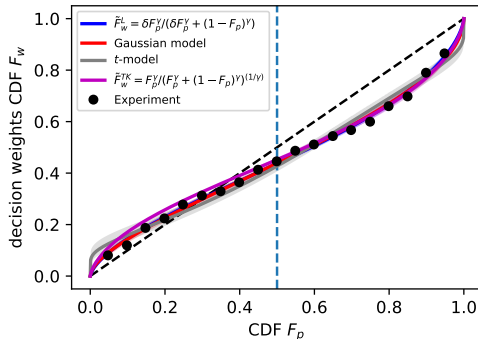
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Estimation Error Explains 99% of Probability Weighting

Tversky & Kahneman (1992)



Tversky & Fox (1995)



- similar fits of Gaussian & t -distributed model

→ How big is the residual “probability weighting” after accounting for estimation errors?



Tversky and Kahneman ([1992](#), $\gamma = 0.68$)

$$\tilde{F}_w^{TK}(F_p; \gamma) = (F_p)^\gamma \frac{1}{\left[(F_p)^\gamma + (1 - F_p)^\gamma\right]^{1/\gamma}} \quad (3)$$

Lattimore, Baker, and Witte ([1992](#))

$$\tilde{F}_w^L(F_p; \delta, \gamma) = \frac{\delta F_p^\gamma}{\delta F_p^\gamma + (1 - F_p)^\gamma} \quad (4)$$

Gaussian case with greater DM scale $\alpha\sigma$

$$w(p) = p^{\frac{1}{\alpha^2}} \frac{(2\pi\sigma^2)^{\frac{1-\alpha^2}{2\alpha^2}}}{\alpha}, \quad (5)$$

which is a power law in p with a pre-factor to ensure normalisation



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