

What are we weighting for?

A mechanistic model for probability weighting

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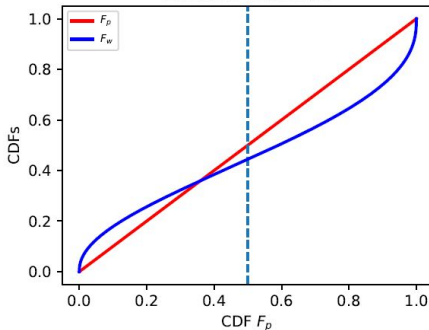




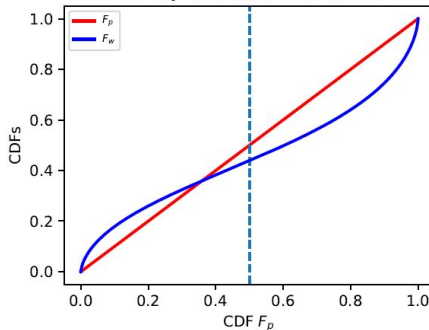
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Main results

Location and scale



Tversky and Kahneman (1992)



- ① generic inverse-S shape can be explained by difference in uncertainty
- ② relative estimation error in $p(x)$ is greater for rarer events

► PW K&T 1979



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Main Result

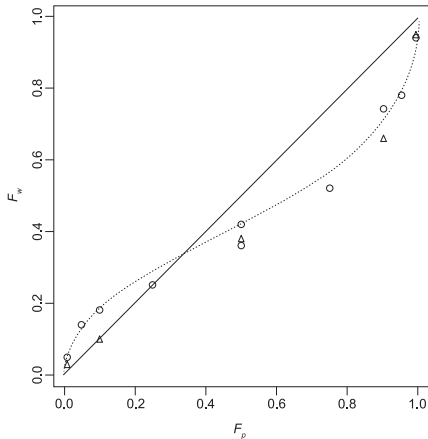
Probability
Weighting

Uncertainty in
PDFs & CDFs

Ergodicity
Question

Estimation

Conclusion



(Tversky and Kahneman 1992, p. 310, Fig. 1, relabelled axes)

Probability Weighting (PW)

- overestimation of rare events → underestimation of common events
- stable empirical pattern: inverse-S shape

Received wisdom:

- PW = maladaptive irrational cognitive bias

In search of a mechanism

- ↪ How does this pattern emerge?
- ↪ Can we derive the functional form (rather than merely fitting some function)?



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Set up : A Thought Experiment

Disinterested Observer (DO)



DO has a **model** of the same
random variable X , e.g. payout
of a gamble

probabilities $p(x)$

CDF $F_p(x)$



Decision Maker (DM)



DM has a **model** of the same
random variable X , e.g. payout of a
gamble

decision weights $w(x)$

CDF $F_w(x)$



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DM's Additional Uncertainty

reasons for DM's extra uncertainty in the random variable X :

- DM has no control over the experiment,
- DM's incomplete comprehension of the experiment/decision problem,
- DM needs to trust the DO
- uncertain outcome is consequential only to the DM,
- ...



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- uncertain outcome is consequential only to the DM,
- ...

Let's take a look at the simplest case of extra uncertainty ...

Numerically, our procedure can be applied to arbitrary distributions:

► Algo

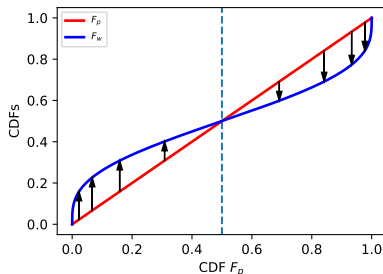
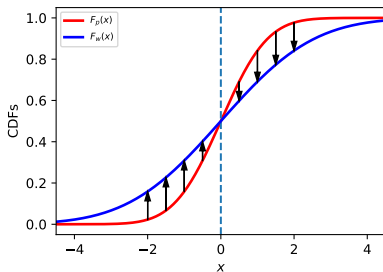
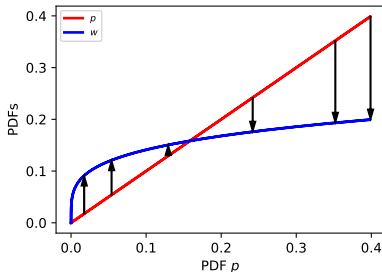
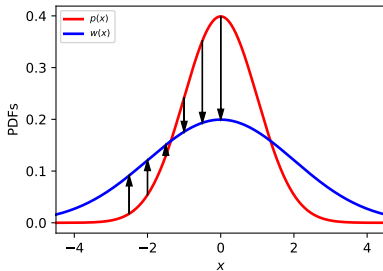
- ① construct a list of values for the CDF assumed by the DO, $F_p(x)$
- ② construct a list of values for the CDF assumed by the DM, $F_w(x)$
- ③ plot $F_w(x)$ vs. $F_p(x)$



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► Algo

Transmission of different uncertainties from PDFs into CDFs



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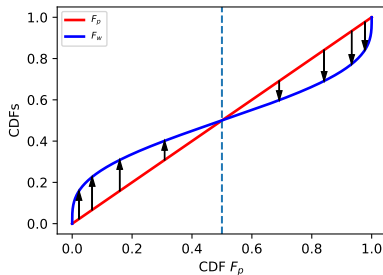
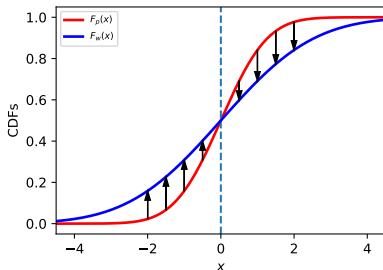
Estimation

Conclusion



Interim conclusion

- greater DM scales reproduces inverse-S shape





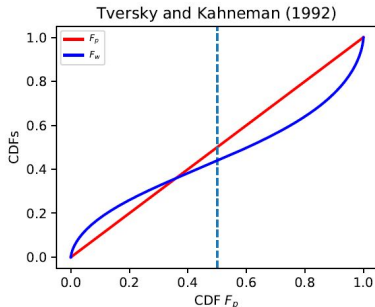
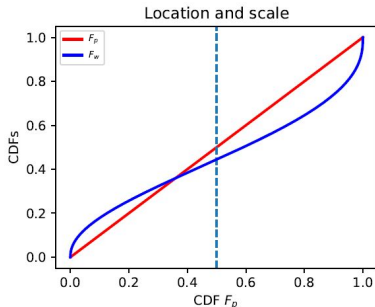
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► Algo

Transmission of different uncertainties from PDFs into CDFs

Interim conclusion

- greater DM scales reproduces inverse-S shape
- differences in location and scale reproduce asymmetric inverse-S shape
- inverse-S shape whenever DM's assumes greater scale for a unimodal distribution





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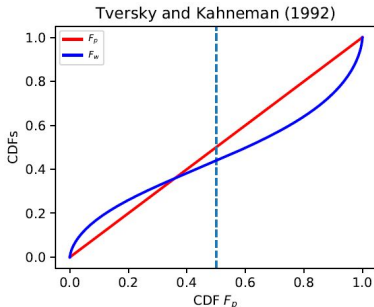
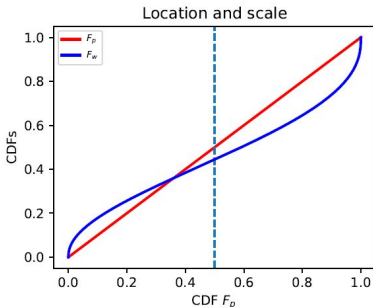
► Algo

Transmission of different uncertainties from PDFs into CDFs

Interim conclusion

- greater DM scales reproduces inverse-S shape
 - differences in location and scale reproduce asymmetric inverse-S shape
 - inverse-S shape whenever DM's assumes greater scale for a unimodal distribution
- *Job done. Thank you for your attention ;)*

► Functional Forms





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Asking the Ergodicity Question

Rule: non-ergodic wealth dynamics (e.g. multiplicative) (see Peters [2019](#))

Exception: ergodic wealth dynamics (e.g. additive)

DO's concern

What happens on average to the **ensemble** of subjects?

≠

DM's concern

What happens to me **on average over time**?

- DM's adaptive/ecological rationality \equiv survival, *i.e.* evolutionary incentive to err on the side of caution
- add more uncertainty to his model

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A Mechanism of Estimating p

- usually the DM does not know $p(x)$
 - probability is not an observable !!!
 - “probability” is polysemous (Gigerenzer [1991](#), [2018](#); Hertwig and Gigerenzer [1999](#))
 - DM has to estimate the (unobservable) model parameter $p(x)$ from an observable count of rare events $n(x)$ over time
- ↪ **(Frequentist) Assumption** $p(x) \equiv$ relative frequency of an event in an infinitely long time series of observation
- very likely to observe no rare events in a finite (small) sample

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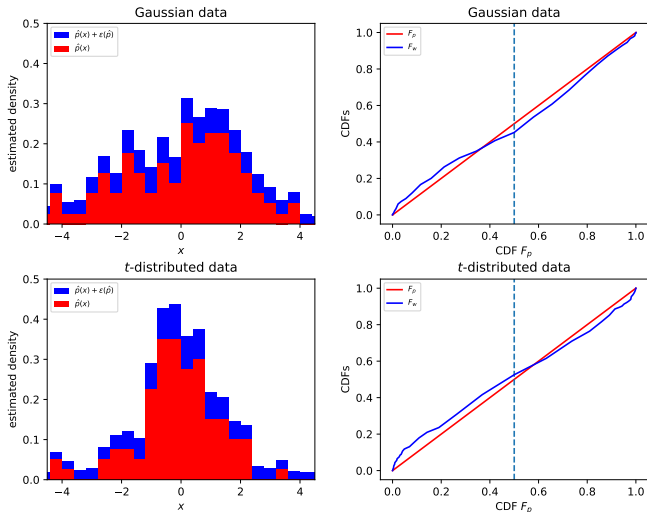
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Simulation of the Estimation



$T = 100$, estimates of $\hat{p}(x)$ in red, estimates with one standard error $\hat{p}(x) + \varepsilon[\hat{p}(x)]$ in blue



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Using the fact that $n(x)$ is a random variable itself, $n(x) \sim \text{Poisson}$, its fluctuations scale like $\sqrt{n(x)}$

Using the count $n(x)$ to infer the asymptotic PDF as

$$p(x) \approx \frac{n(x)}{T\delta x} \pm \frac{\sqrt{n(x)}}{T\delta x} \quad (1)$$

$$\approx \hat{p}(x) \pm \varepsilon [\hat{p}(x)] \quad (2)$$

with the standard error (expressed in terms of the estimate itself)

$$\varepsilon [\hat{p}(x)] \equiv \frac{\sqrt{n(x)}}{T\delta x} = \sqrt{\frac{\hat{p}(x)}{T\delta x}}$$

- standard error $\varepsilon [\hat{p}(x)]$ shrinks as the probability decreases
 - relative error in the estimate is $1/\sqrt{\hat{p}(x) T\delta x}$ grows as the event becomes rarer
 - consistent with our claim, that low probabilities come with larger relative errors
- ↪ Errors in probability estimates behave differently for low probabilities than for high probabilities: absolute errors are smaller for lower probabilities, but relative errors are larger



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Ergodicity Economics explains probability weighting

- we find an inverse-S shape as a neutral indicator of a difference in opinion
- we find that quite generally the relative uncertainties are larger for rare events than for common events, which generates the inverse-S shape

↪ Probability weighting is rational cautious behaviour under uncertainty

- See full paper at bit.ly/lml-pw-r1
- links to play with the code are inside



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Thank you for your attention!

I'm looking forward to the discussion
Comments & questions are very welcome, here or to

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Probability Weighting as an Estimation Issue

“It is important to distinguish [overweighting](#), which refers to a property of decision weights, from the [overestimation](#) that is commonly found in the assessment of the probability of rare events. [...] In many real-life situations, overestimation and overweighting may both operate to increase the impact of rare events.” (Kahneman and Tversky [1979](#), p. 281)

↪ distinguish between

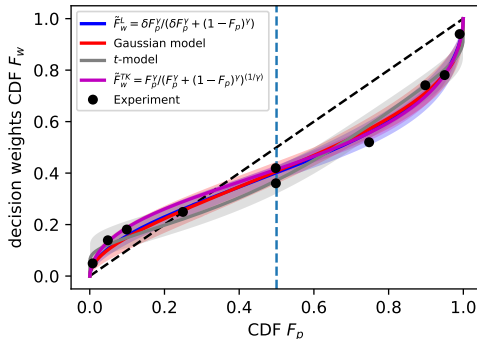
- uncertainty estimation and
- “weighting”

we analyse the former and find very good agreement with the empirical inverse-S pattern

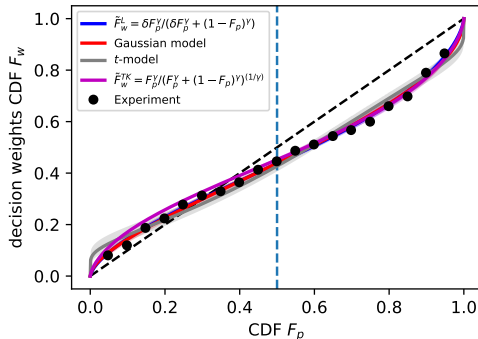
↪ How big is the residual “probability weighting” after accounting for uncertainty estimation?

Estimation Error Explains 99% of Probability Weighting

Tversky & Kahneman (1992)



Tversky & Fox (1995)



- similar fits of our Gaussian & t -distributed model

→ How big is the residual “probability weighting” after accounting for estimation errors?



Tversky and Kahneman (1992, $\gamma = 0.68$)

$$\tilde{F}_w^{TK}(F_p; \gamma) = (F_p)^\gamma \frac{1}{\left[(F_p)^\gamma + (1 - F_p)^\gamma\right]^{1/\gamma}} \quad (3)$$

Lattimore, Baker, and Witte (1992)

$$\tilde{F}_w^L(F_p; \delta, \gamma) = \frac{\delta F_p^\gamma}{\delta F_p^\gamma + (1 - F_p)^\gamma} \quad (4)$$

We derive decision weight as a function of probability with $(\alpha\sigma)^2$ as the DM's scale

$$w(p) = p^{\frac{1}{\alpha^2}} \frac{(2\pi\sigma^2)^{\frac{1-\alpha^2}{2\alpha^2}}}{\alpha}, \quad (5)$$

which is a power law in p with a pre-factor to ensure normalisation



Numerically, our procedure can be applied to arbitrary distributions:

- 1 construct a list of values for the CDF assumed by the DO, $F_p(x)$
- 2 construct a list of values for the CDF assumed by the DM, $F_w(x)$
- 3 plot $F_w(x)$ vs. $F_p(x)$

The inverse-S arises whenever a DM assumes a greater scale for a unimodal distribution. To illustrate the generality of the procedure, we carry it out for Student's (power-law tailed) t -distributions (which we refer to as t -distributions), where DO and DM use different shape parameters and different locations



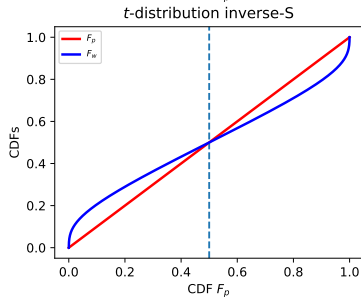
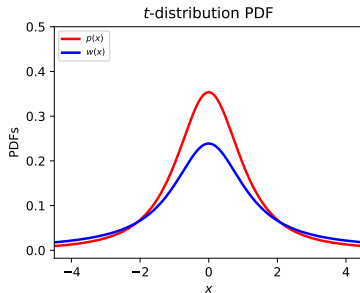
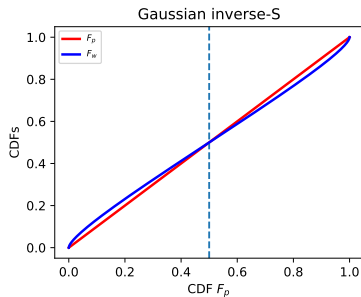
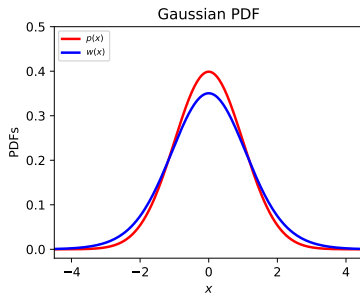
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Effect of Different Scales with Heavy-Tailed t -Distributions

◀ Gaussian





Linking Probability Weighting to Relative Uncertainties

Decision weight w is the normalised sum of the probability $p(x)$ and its uncertainty $\varepsilon [p(x)]$

$$w(x) = \frac{p(x) + \varepsilon [p(x)]}{\int_{-\infty}^{\infty} (p(s) + \varepsilon [p(s)]) ds} . \quad (6)$$

This can be expressed as

$$w(x) = p(x) \left(\frac{1 + \frac{\varepsilon[p(x)]}{p(x)}}{\int_{-\infty}^{\infty} p(s) \left\{ 1 + \frac{\varepsilon[p(s)]}{p(s)} \right\} ds} \right) , \quad (7)$$

where $\frac{\varepsilon[p(x)]}{p(x)}$ is the relative error, which is large (small) for small (large) probabilities
In the long-time limit $w(x) \rightarrow p(x)$



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