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1	T	emplate
# i	nclu	de <bits stdc++.h=""></bits>
us	ing	namespace std;
11.0	ing	ll = long long:

```
#define vll vector<ll>
#define vvll vector<vll>
#define pll pair<ll, ll>
#define vpll vector<pll>
#define vvpll vector<vpll>
#define endl '\n'
#define all(xs) xs.begin(), xs.end()
#define found(x, xs) (xs.find(x) != xs.end())
```

2 Algebra

2.1 All divisors

 $O(\sqrt{n})$

```
vll divisors(ll n) {
vll divs;
for (ll i = 1; 1LL * i * i <= n; i++) {
   if (n % i == 0) {
      divs.push_back(i);
      if (i != n / i) {
            divs.push_back(n / i);
      }
      }
    }
}
return divs;
}</pre>
```

2.2 Primality test

 $O(\sqrt{n})$

```
bool isPrime(ll n)
{
    if(n!=2 && n % 2==0)
        return false;

    for(ll d=3; d*d <= n; d+=2)
    {
        if(n % d==0)
            return false;
    }

return n >= 2;
}
```

2.3 Binary exponentiation

 $O(\log n)$

```
1  ll binpow(ll a, ll b) {
2     ll res = 1;
3     while (b > 0) {
4         if (b & 1)
5             res = res * a;
6             a = a * a;
7             b >>= 1;
8     }
9     return res;
10 }
```

2.4 Greatest common divisor

 $O(\log \min(a, b))$

2.4.1 Least common multiple

3 Graphs

3.1 DFS

O(n+m)

```
void dfs(ll at, ll n ,vpll adj[], bool visited[]) {
   if(visited[at])
      return;

visited[at] = true;

vpll neighbours = adj[at];
for(auto nex: neighbours)
```

```
dfs(nex.first, n, adj, visited);
}
```

3.2 BFS

O(n+m)

```
void bfs(ll s, ll n, vll adj[]) {
       bool visited[n] = {0};
2
       visited[s] = true;
3
       queue <11> q;
       q.push(s);
       while (!q.empty())
            vll neighbours = adj[q.front()];
            for(auto nex: neighbours) {
10
                if(!visited[nex]) {
                     visited[nex]=true;
12
                     q.push(nex);
                }
            }
            cout << q.front() << '\n';</pre>
16
            q.pop();
17
       }
18
   }
```

3.2.1 Shortest path on unweighted graph

O(n+m)

```
vll solve(ll s, ll n, vll adj[]) {
       bool visited[n] = {0};
2
       visited[s] = true;
       queue <11> q;
       q.push(s);
6
       vll prev(n, -1);
       while (!q.empty())
            vll neighbours = adj[q.front()];
10
            for(auto nex: neighbours) {
11
                if(!visited[nex]) {
                    visited[nex]=true;
13
                    q.push(nex);
14
                    prev[nex] = q.front();
15
                }
16
17
           }
18
           q.pop();
```

```
}
19
20
       return prev;
21
22
23
   vll reconstructPath(ll s, ll e, vll prev) {
24
        vll path;
25
        for(ll i=e; i!=-1; i=prev[i])
26
            path.push_back(i);
27
28
       reverse(path.begin(), path.end());
30
       if (path [0] == s)
31
            return path;
32
        else {
33
            vll place;
34
            return place;
35
36
37
   }
38
   vll bfs(ll s, ll e, ll n, vll adj[]) {
39
       vll prev = solve(s, n, adj);
40
41
       return reconstructPath(s, e, prev);
42
   }
```

3.3 Flood Fill

```
O(n+m)
```

```
int dir_y[] = {};
   int dir_x[] = {};
   int ff(int i, int j, char c1, char c2) {
       if ((i < 0) || (i >= n)) return 0;
5
       if ((j < 0) || (j >= m)) return 0;
6
       if (grid[i][j] != c1) return 0;
       int ans = 1;
       grid[i][j] = c2;
10
11
       for (int d = 0; d < 8; ++d)</pre>
12
            ans += floodfill(i+dir_y[d], j+dir_x[d], c1, c2);
13
14
       return ans;
15
   }
16
```

3.4 Topological Sort (Directed Acyclic Graph)

3.4.1 DFS Variation

```
O(n+m)
```

```
void dfs(ll at, ll n ,vpll adj[], bool visited[], vll &ts) {
   if(visited[at])
        return;

visited[at] = true;

vpll neighbours = adj[at];
for(auto nex: neighbours)
   dfs(nex.first, n, adj, visited);
ts.push_back(at);
// Only change
```

3.4.2 Kahn's Algorithm

```
priority_queue < 11, v11, greater < 11 >> pq;
   for(11 at=0; at<n; at++)</pre>
                                     // Push all sources of
       connected components in graph
       if(in_degree[at] == 0)
           pq.push(at);
   while(!pq.empty()) {
       11 at = pq.top(); pq.pop();
       vll neighbors = adj[at];
       for(auto nex: neighbors) {
9
            in_degree[nex]--;
           if(in_degree[nex]>0) continue;
11
12
           pq.push(nex);
       }
13
   }
14
```

3.5 Bipartite Graph Check (Undirected Graph)

```
O(n+m)
```

```
bool isBipartite(ll s, ll n, vll adj[]) {
    queue < ll > q;
    q.push(s);
    vll color(n, -1); color[s] = 0;
    bool flag = true;
    while (!q.empty())
    {
        vll neighbours = adj[q.front()];
        for(auto nex: neighbours) {
    }
}
```

```
if(color[nex] == -1) {
                     color[nex] = 1-(color[q.front()]);
                     q.push(nex);
12
                }
13
                else if(color[nex] == color[q.front()]) {
                     flag = false;
15
                     break;
16
                }
            }
18
19
            q.pop();
21
       return flag;
22
23
```

3.6 Cycle Check (Directed Graph)

O(n+m)

```
enum { UNVISITED = -1, VISITED = -2,
                                          EXPLORED = -3;
2
   void cycleCheck(ll at, ll n ,vll adj[], int visited[], ll
3
      dfs_parent[]) {
       visited[at] = EXPLORED;
       vll neighbours = adj[at];
6
       for(auto nex: neighbours) {
           if(visited[nex] == UNVISITED) {
               // Tree edges (part of the DFS spanning tree)
               dfs_parent[nex] = at;
               cycleCheck(nex, n, adj, visited);
           else if(visited[nex] == EXPLORED) {
13
               if(nex == dfs_parent[at]) {
14
                   // Trivial cycle
                   // Do something
16
17
               else {
                   // Non trivial cycle - Back Edge ((u, v)
19
                       such that v is the ancestor of node u but
                        is not part of the DFS tree)
                   // Do something
20
           else if(visited[nex] == VISITED) {
24
               // Forward/Cross edge ((u, v) such that v is a
25
                   descendant but not part of the DFS tree)
               // Do something
26
```

3.7 Dijkstra

 $O(n\log n + m\log n)$

```
void dijkstra(ll s, vll & d, vll & p) {
       d.assign(n, LLONG_MAX);
       p.assign(n, -1);
       d[s] = 0;
       priority_queue<pll, vpll, greater<pll>> q;
       q.push({0, s});
       while (!q.empty()) {
           11 v = q.top().second;
           ll d_v = q.top().first;
           q.pop();
11
            if (d_v != d[v])
                continue;
            for (auto edge : adj[v]) {
15
                11 to = edge.first;
16
                11 len = edge.second;
17
18
                if (d[v] + len < d[to]) {</pre>
19
                    d[to] = d[v] + len;
                    p[to] = v;
                    q.push({d[to], to});
22
23
           }
24
       }
25
   }
```

4 Math Formulas

4.1 Sum of an arithmetic progression

$$S_n = \frac{n}{2}(a_1 + a_n)$$

4.2 Permutation with repeated elements

$$P_n = \frac{n!}{n_1! n_2! \dots n_k!}$$

4.3 Check if is geometric progression

$$a_i^2 = a_{i-1} a_{i+1}$$

4.4 Bitwise equations

$$a|b = a \oplus b + a\&b$$

$$a \oplus (a\&b) = (a|b) \oplus b$$

$$(a\&b) \oplus (a|b) = a \oplus b$$

$$a+b = a|b+a\&b$$

$$a+b = a \oplus b + 2(a\&b)$$

$$\begin{aligned} a-b &= (a \oplus (a\&b)) - ((a|b) \oplus a) \\ a-b &= ((a|b) \oplus b) - ((a|b) \oplus a) \\ a-b &= (a \oplus (a\&b)) - (b \oplus (a\&b)) \\ a-b &= ((a|b) \oplus b) - (b \oplus (a\&b)) \end{aligned}$$

4.5 Cube of Binomial

$$(a+b)^3 = a^3 + 3a^2b + 3ab^2 + b^3$$

 $(a-b)^3 = a^3 - 3a^2b + 3ab^2 - b^3$

4.5.1 Sum of Cubes

$$a^3 + b^3 = (a+b)(a^2 - ab + b^2)$$

4.5.2 Difference of Cubes

$$a^3 - b^3 = (a - b)(a^2 + ab + b^2)$$

4.6 Binomial expansion

5 Facts

5.1 XOR

5.1.1 Self-inverse property

To cancel a XOR, you can XOR again the same value because $a \oplus a = 0$, so $(value \oplus a) \oplus a = value$

5.1.2 Identity element

$$a \oplus 0 = a$$

5.1.3 Commutative

 $a\oplus b=b\oplus a$

5.1.4 Associative

$$(a \oplus b) \oplus c = a \oplus (b \oplus c)$$